



# **SFT Group Meeting**

Status Update #7

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6th July 2023





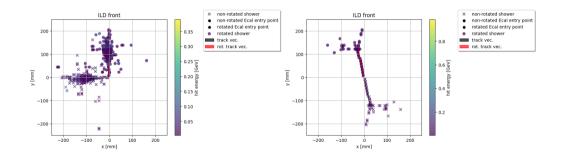
## What am I doing?

- Regression: TOF estimation using ML techniques based on ECal hits
- data: 4D point cloud: (x,y,z,e) N × 4 points, N = # hits
  + timing info let's see how to implement that, positional encoding?
- remark: N will differ for different pfos
- + extract intrinsic features





#### 29 June 06 July: Showery Showers!





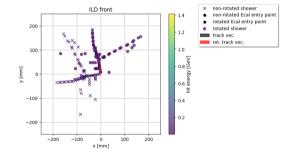


### 29 June 06 July: PFO Selection

- reworked PFO selection: previously:
  - if the shower had hits from other particles != MC truth in it: reject PFO

#### now:

 $\bullet$  if the deposited energy in the shower is <90% from MC truth: reject PFO







#### Further Work + Outlook

Further Work:

- generated a new dataset
- worked on PointNet++ dataloader Outlook:
- implement the RMS90 quality cut (discussed last meeting)
- $\bullet \ \ work \ on \ PointNet++ \ implementation$