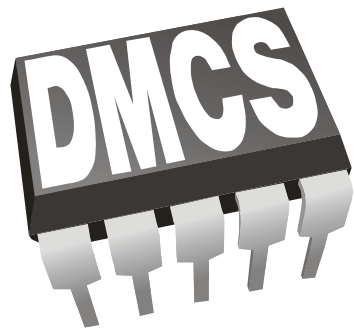




Status of Piezo Controller and Driver

K. Przygoda

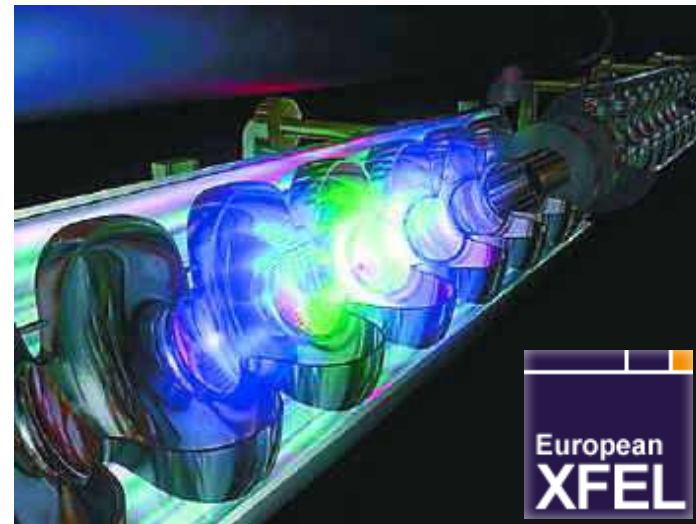
T. Poźniak



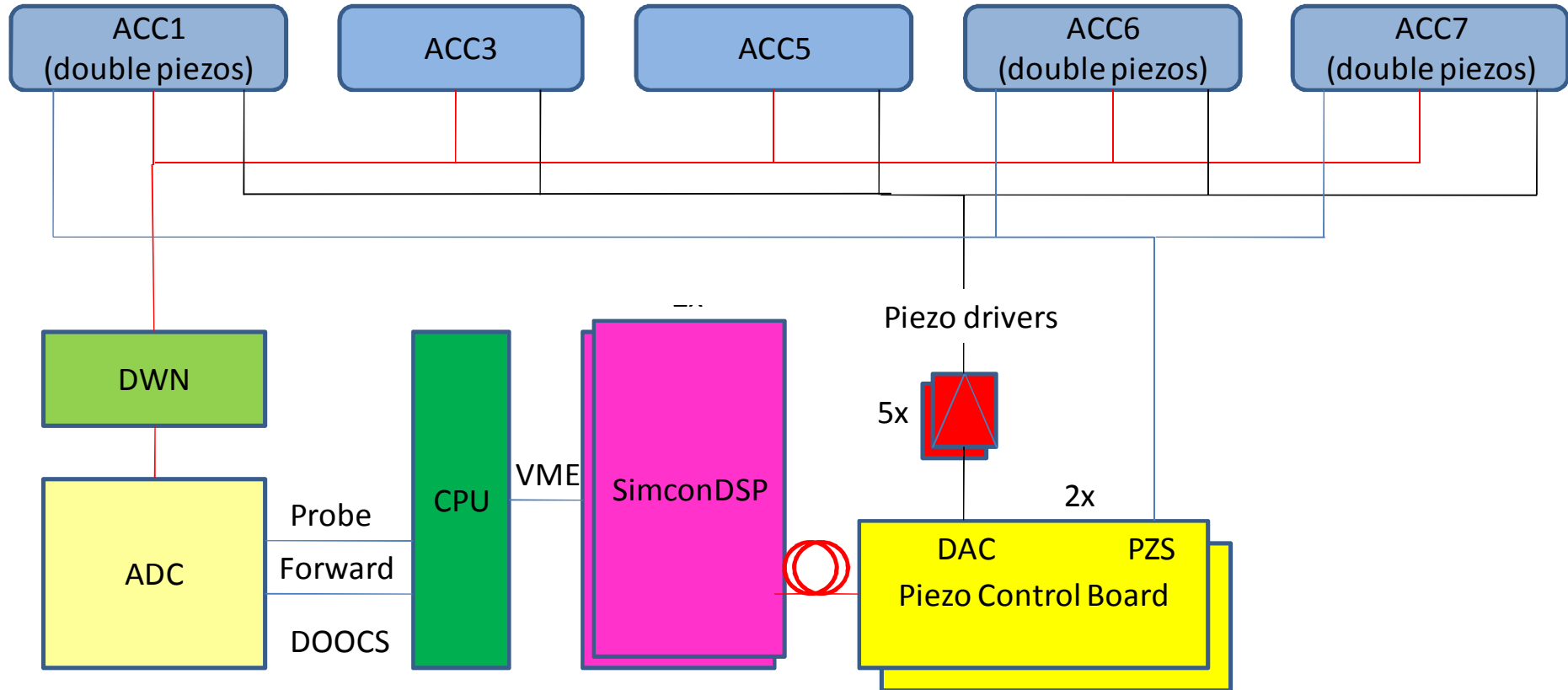
Piezo in XFEL Experiment

Main parameters:

- beam energy up to 20 GeV \rightarrow wavelength, λ_e up to 0.1 nm
- 25 RF stations, each one powered by klystron of 5 \div 10 MW
- 25 RF st. x 4 accelerating modules = 100 accelerating modules
- each accelerating module with 8 SC cavities
- nominal $E_{\text{acc}} \approx 25$ MV/m $\rightarrow \Delta f \approx 250$ Hz $\rightarrow \Delta P_{\text{kly}} \approx +25\%$
- **800 piezos for driving and 800 for sensing**
- RF pulse duration 1.3 ms
- RF pulse repetition rate $f_{\text{RP}} = 10$ Hz

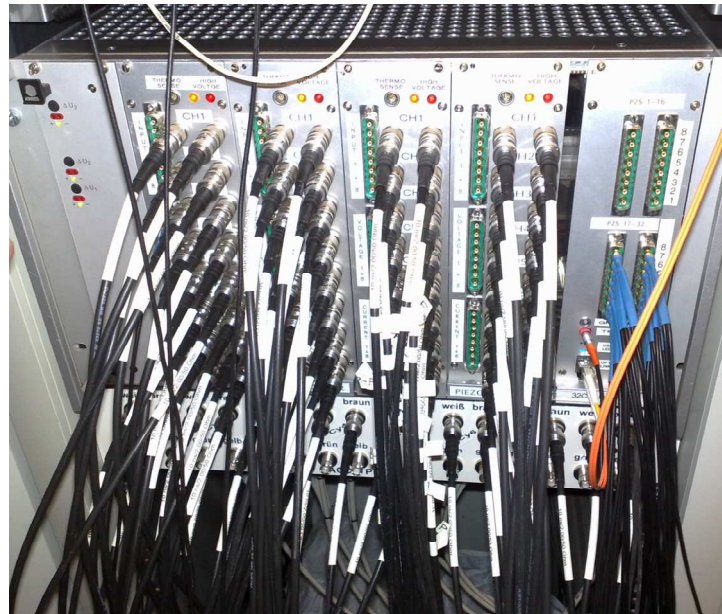
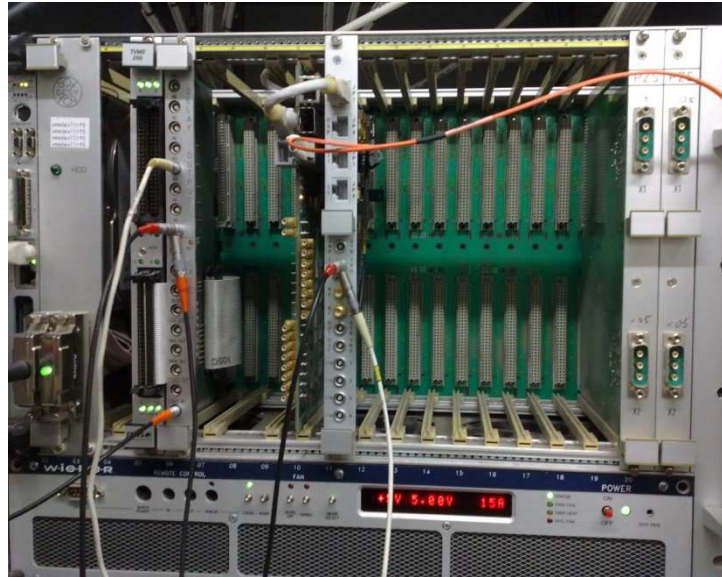


Piezo Tuners Control at FLASH



40 cavities, 5 accelerating modules
(single and double piezo tuners)

System Installation at FLASH



Installed:

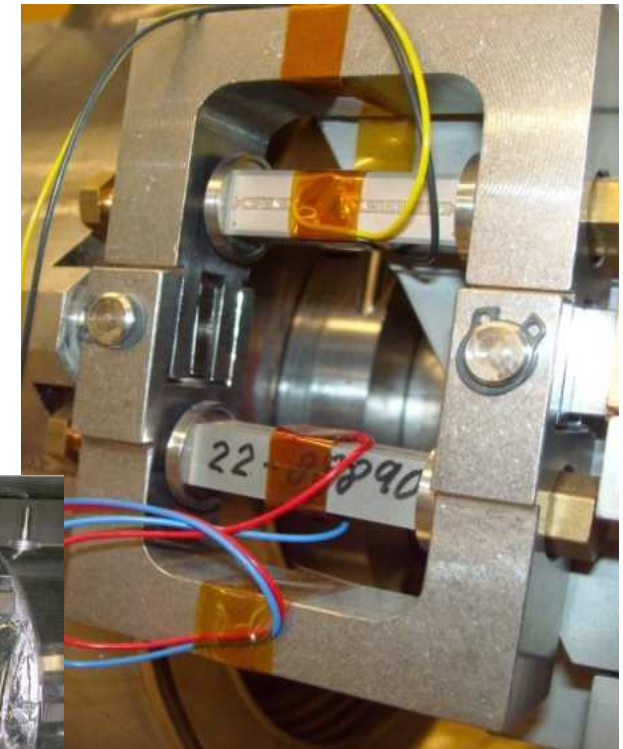
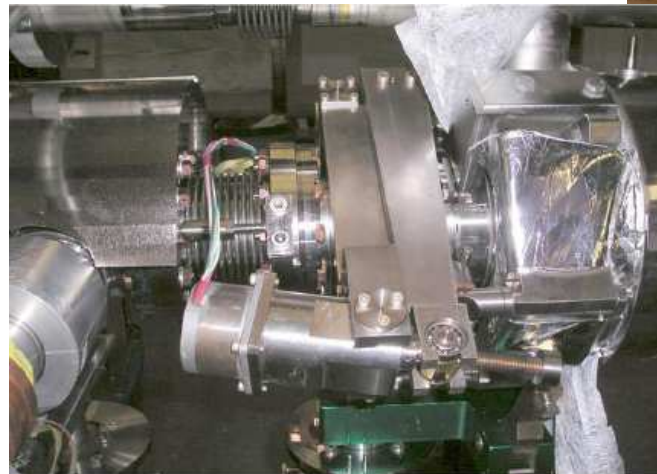
5x PZD units
2x DAC/ADC units
2x Piezo Crates

Spare parts:

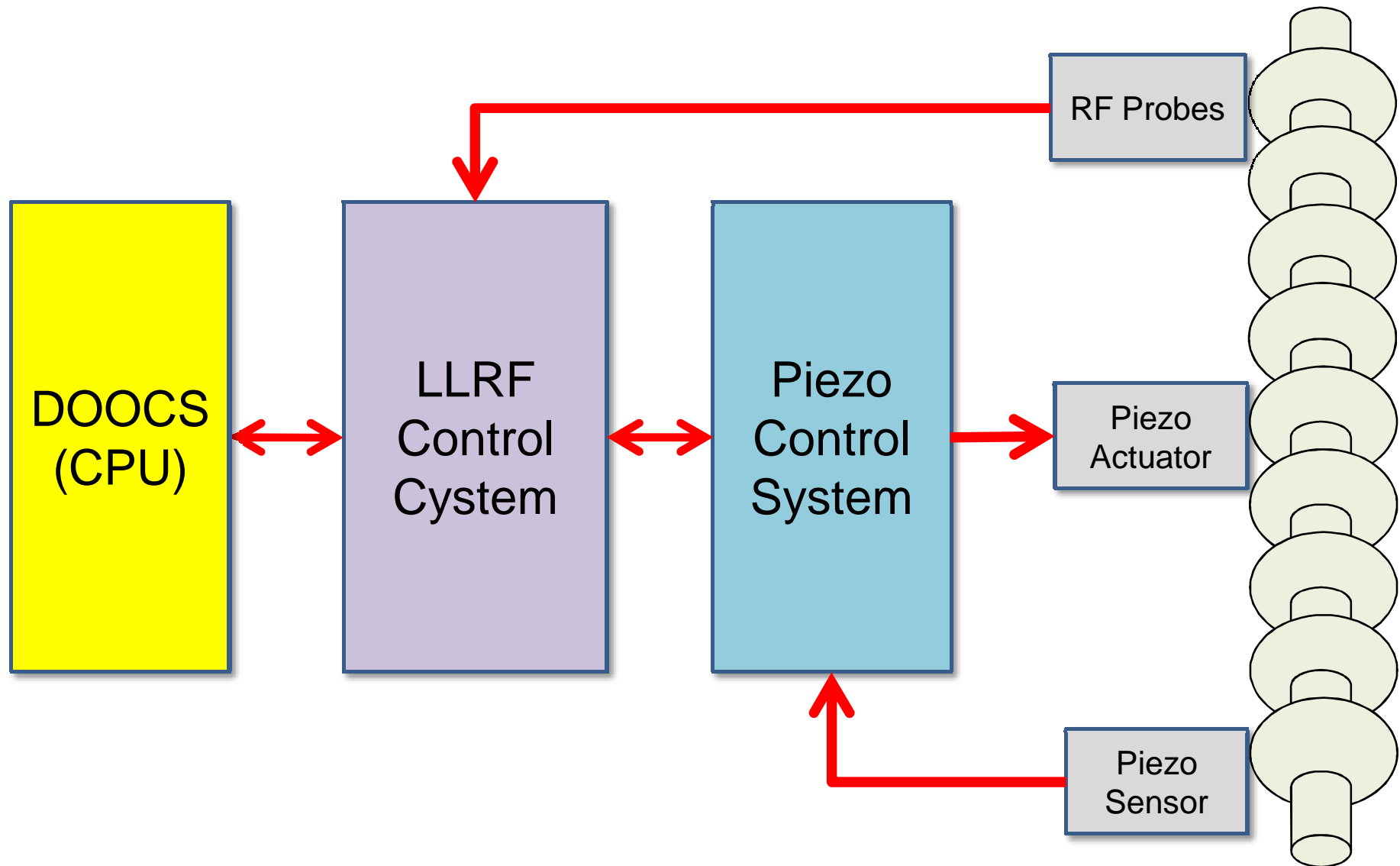
3x PZD units
2x DAC/ADC units
2x Piezo Crates

Piezo Control System Specification

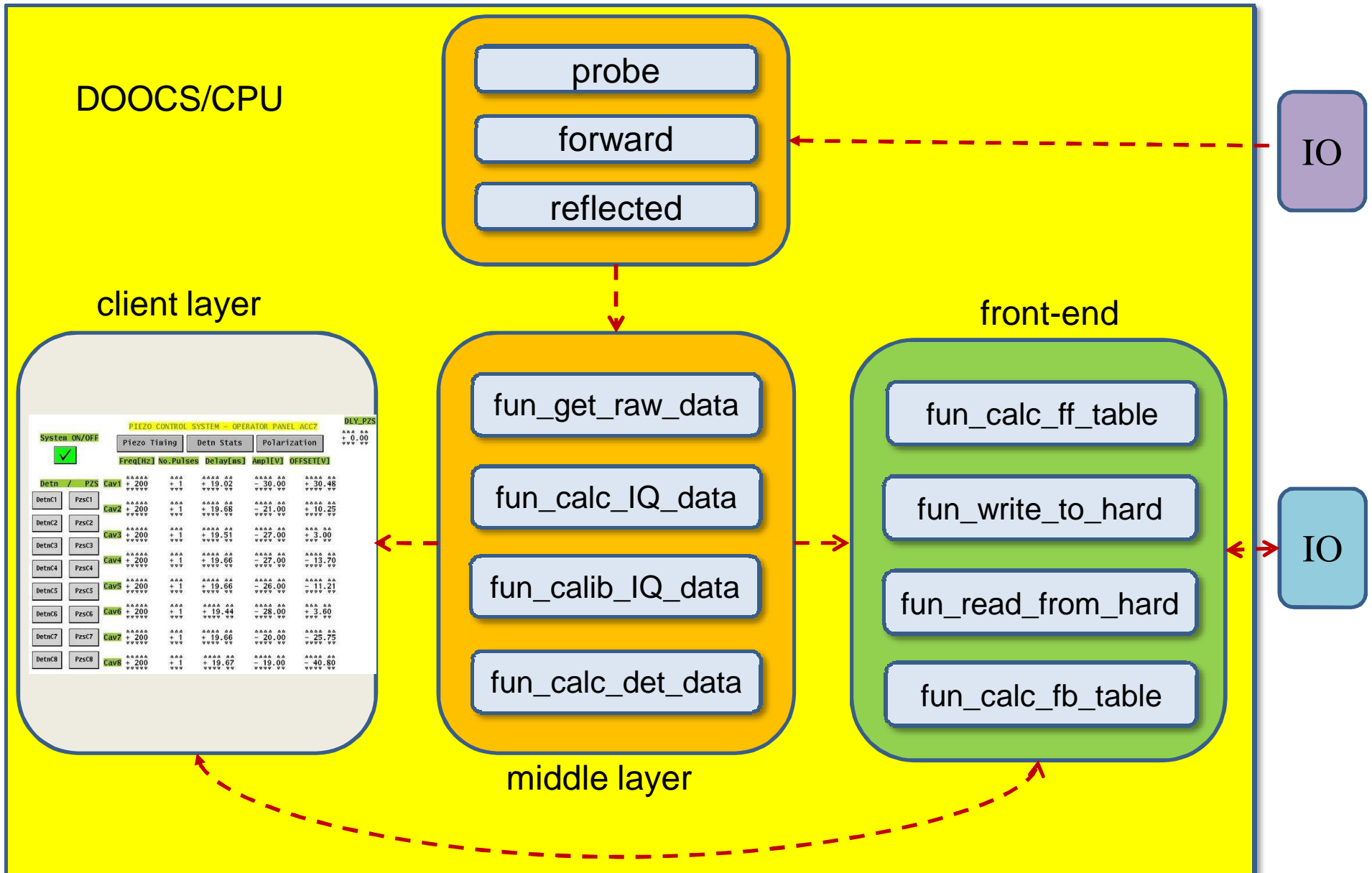
- System should be able to compensate 4 accelerating modules with 8 SC cavities each (*2 boards*)
- Each board will have integrated 16 driving and sensing circuits
- External power supply unit: - 48 V
- Internal power supply unit:
 - Symmetric: ± 96 V
 - Assymetric: -48 V/+144 V
- Operation with uTCA standard:
 - inside standalone box
 - optical link connection



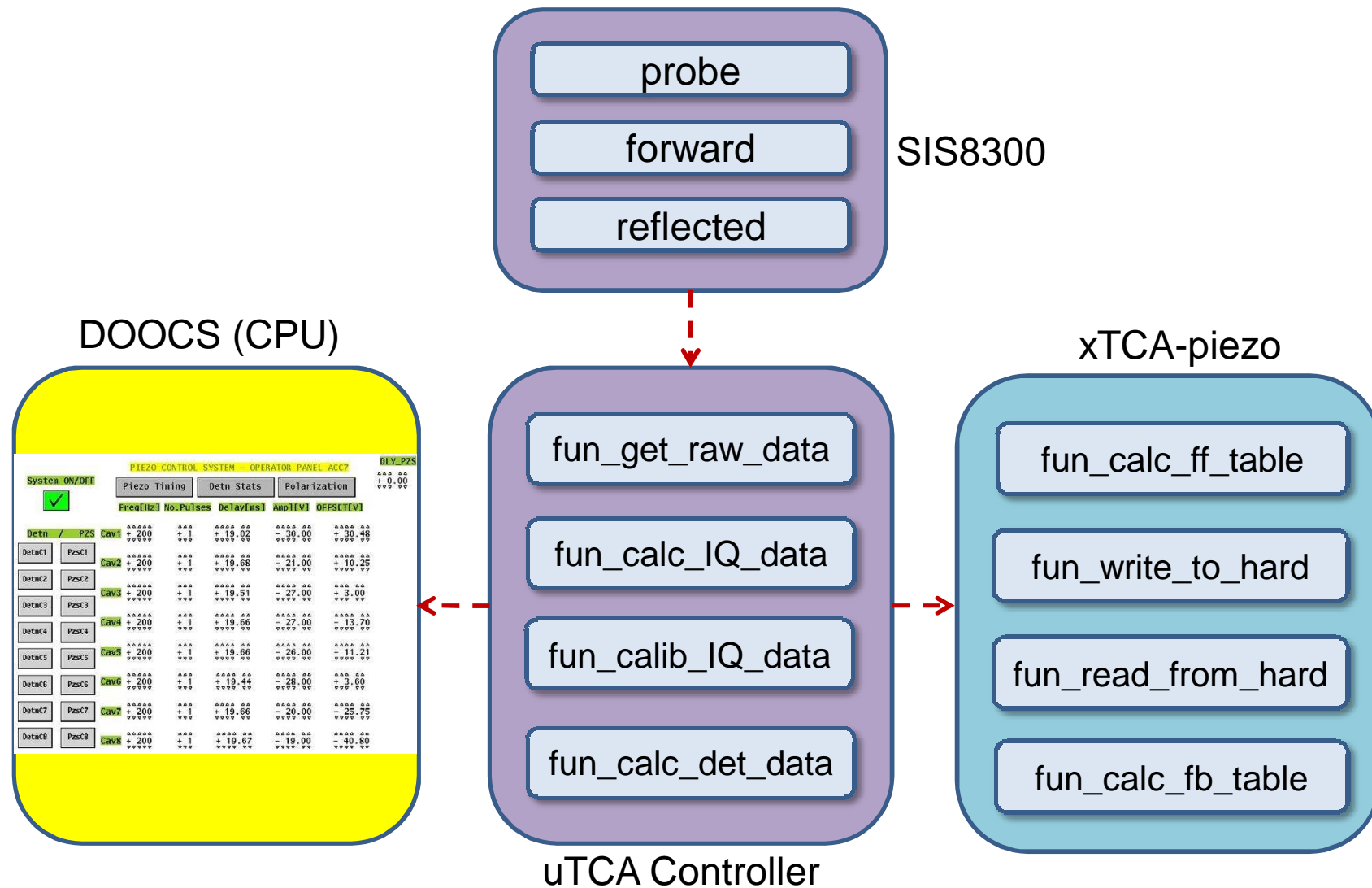
Layout of Piezo Control System



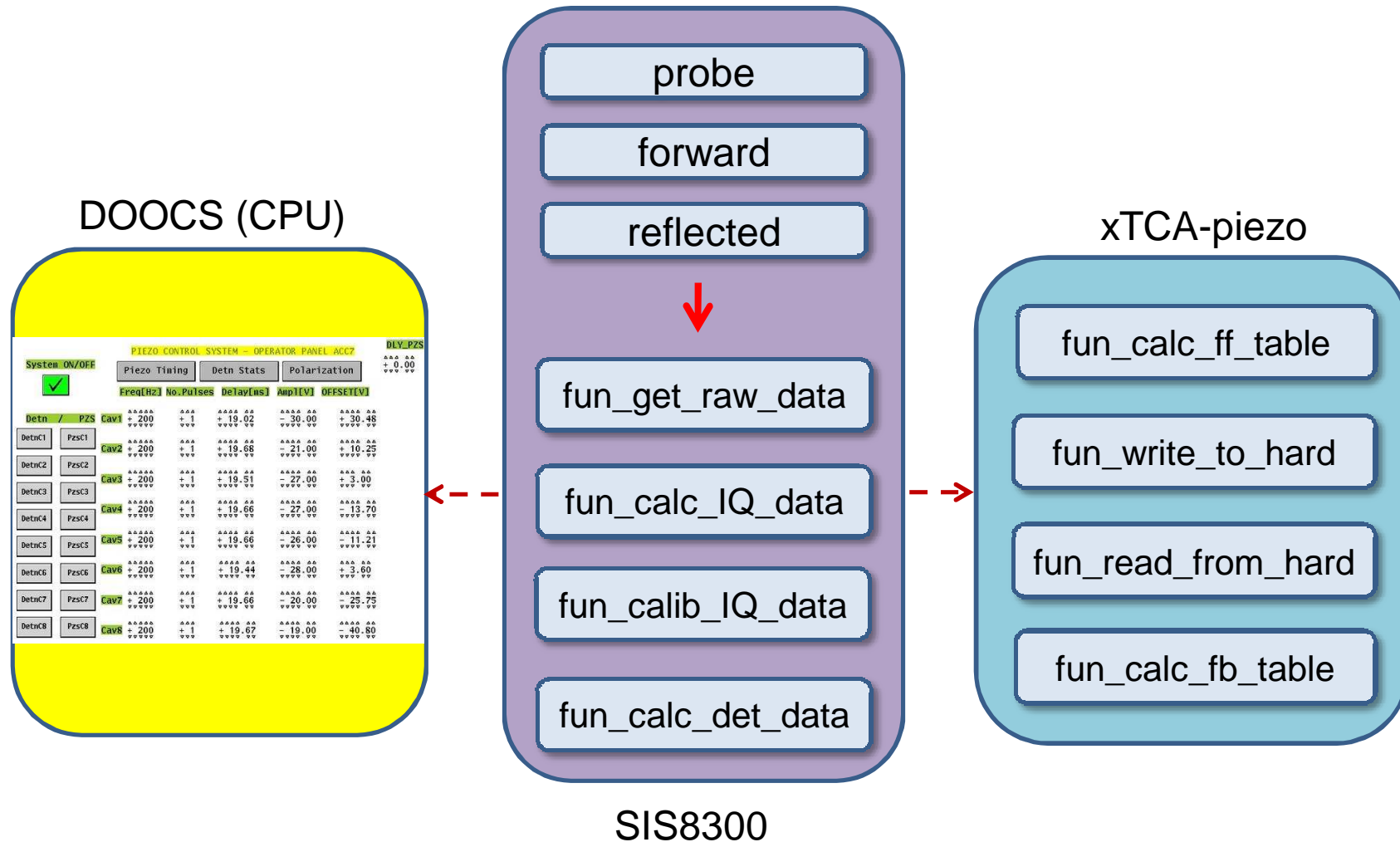
Software Based Control Scheme



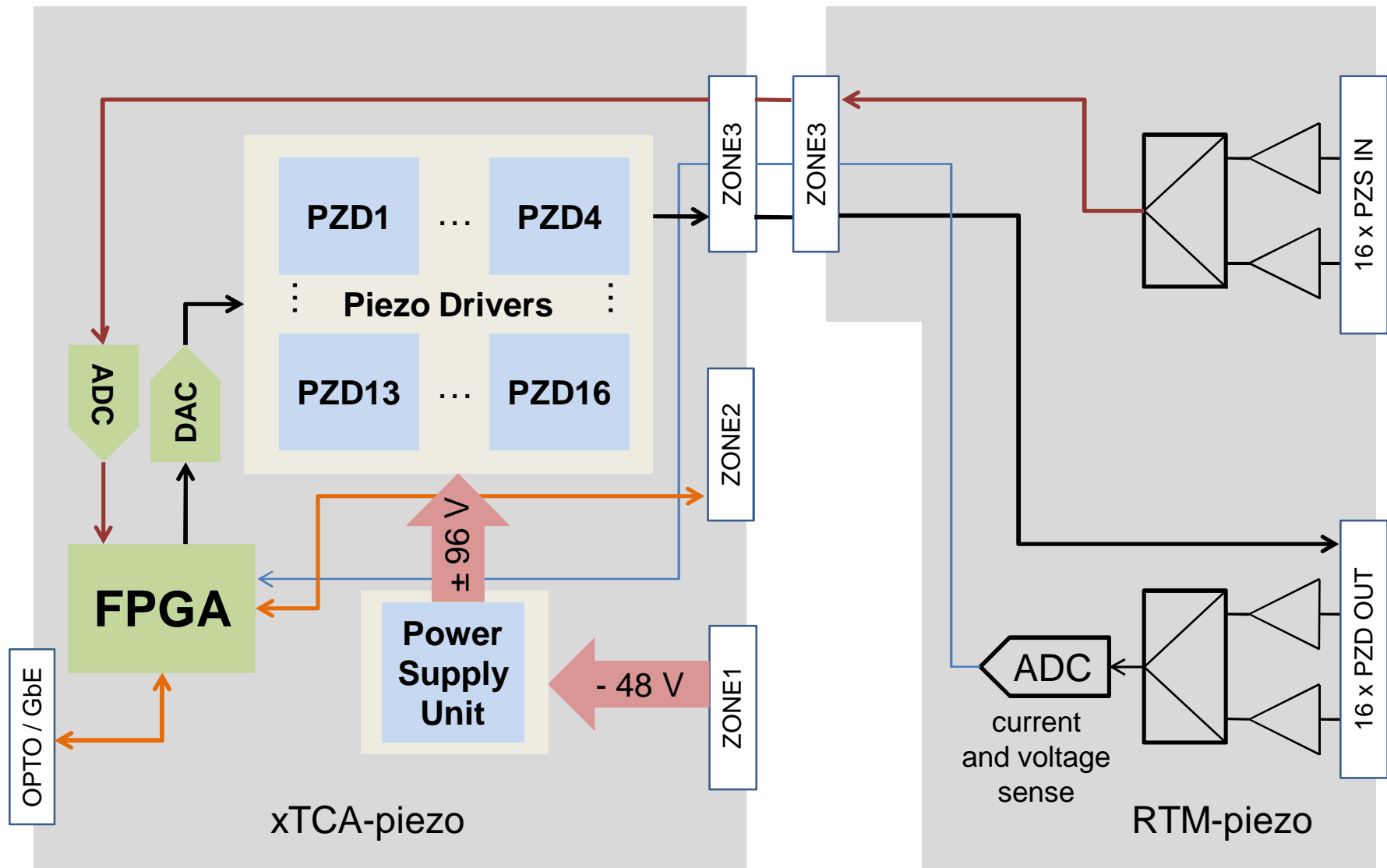
Firmware Based Control Scheme ver.1



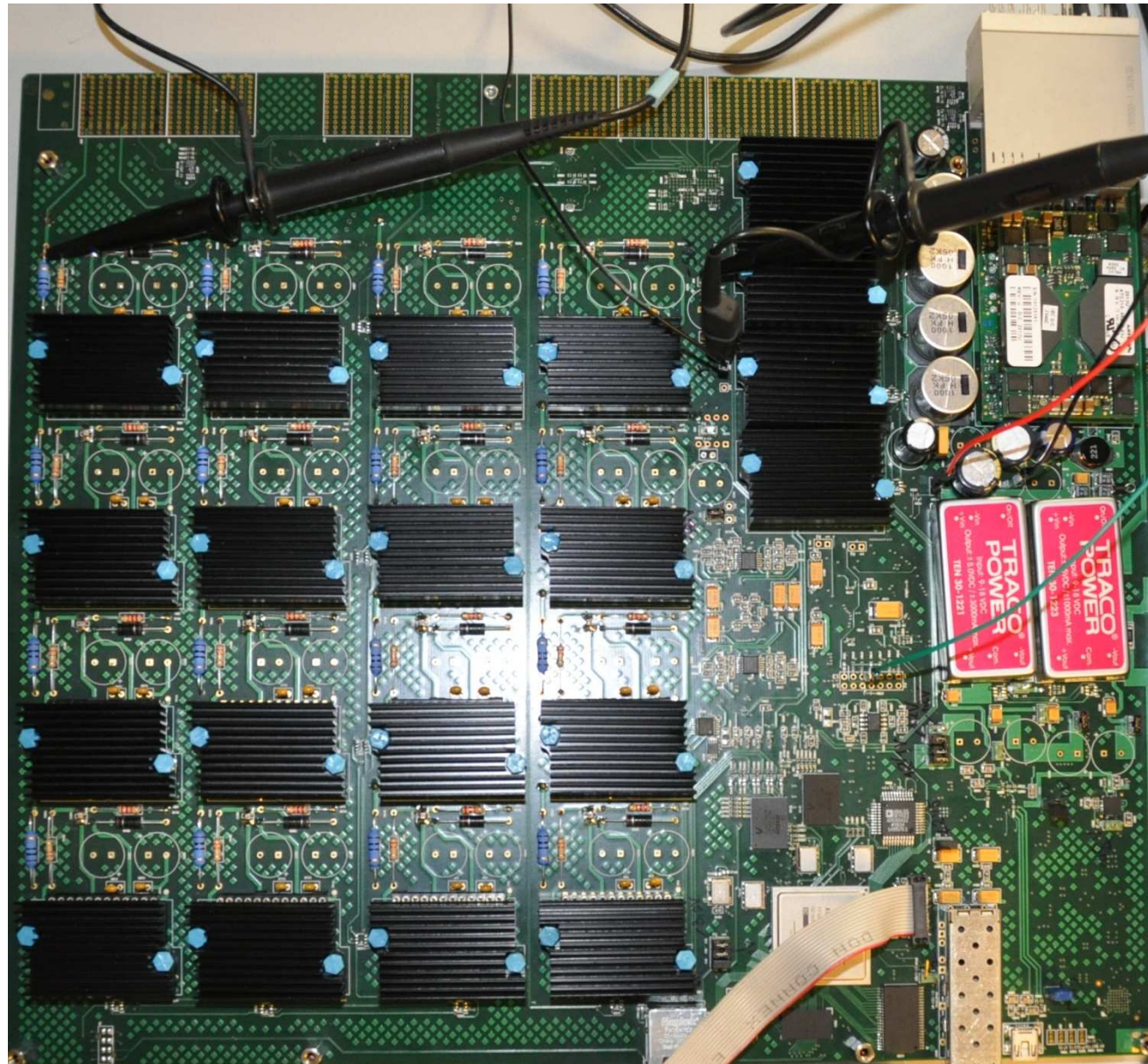
Firmware Based Control Scheme ver.2



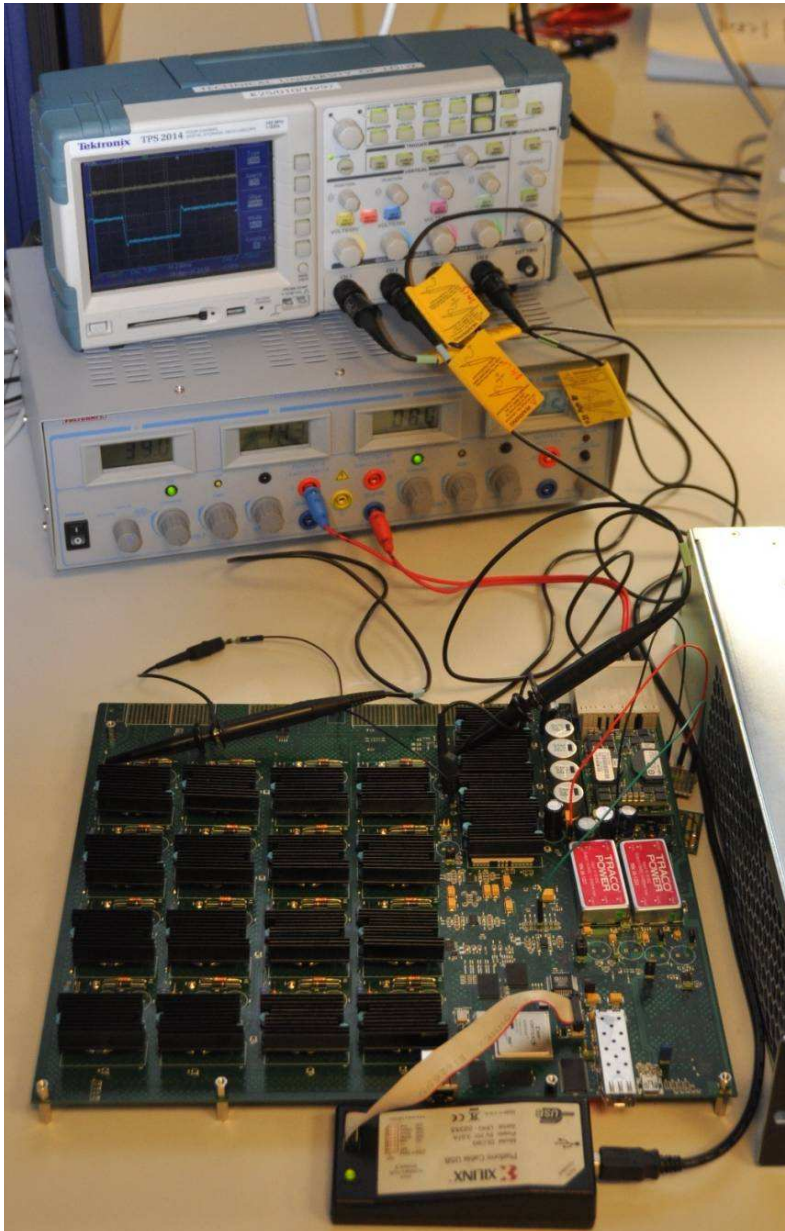
Piezo Controller rev. 1



Piezo Controller rev.1 (PCB 10L)



Laboratory Test Stand



- Power supply units debugged
 - ATC210 (-48 V \Leftrightarrow {12 V/3.3 V})
 - TEN-30 (12 V \Leftrightarrow { \pm 5 V/ \pm 15 V})
 - LTM4600 (12 V \Leftrightarrow {3.3 V/2.5 V/ 1 V})
 - TPS7448 (2.5 V \Leftrightarrow {1.8 V/1.2 V/1 V})
 - BCM (48 V \Leftrightarrow \pm 96 V)
- FPGA unit debugged
 - MGT(RocketIO \Leftrightarrow opto)
 - SPI Interface (with DAC)
 - Parallel Interface (with ADC)
- Driving circuits debugged
 - 16-ch DAC
 - 16 x PB51
- Sensing circuit debugged
 - ADC

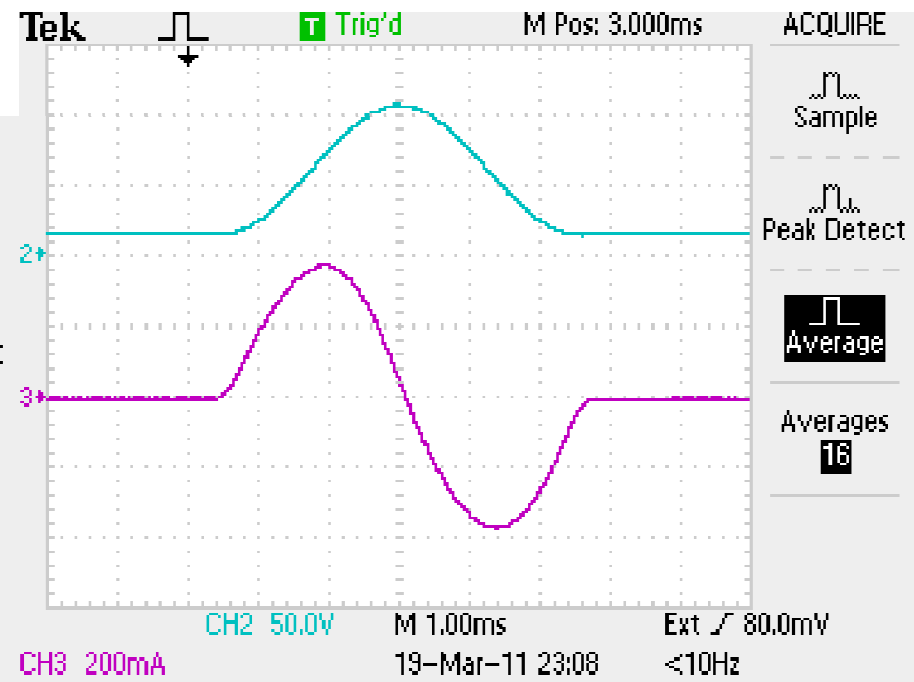
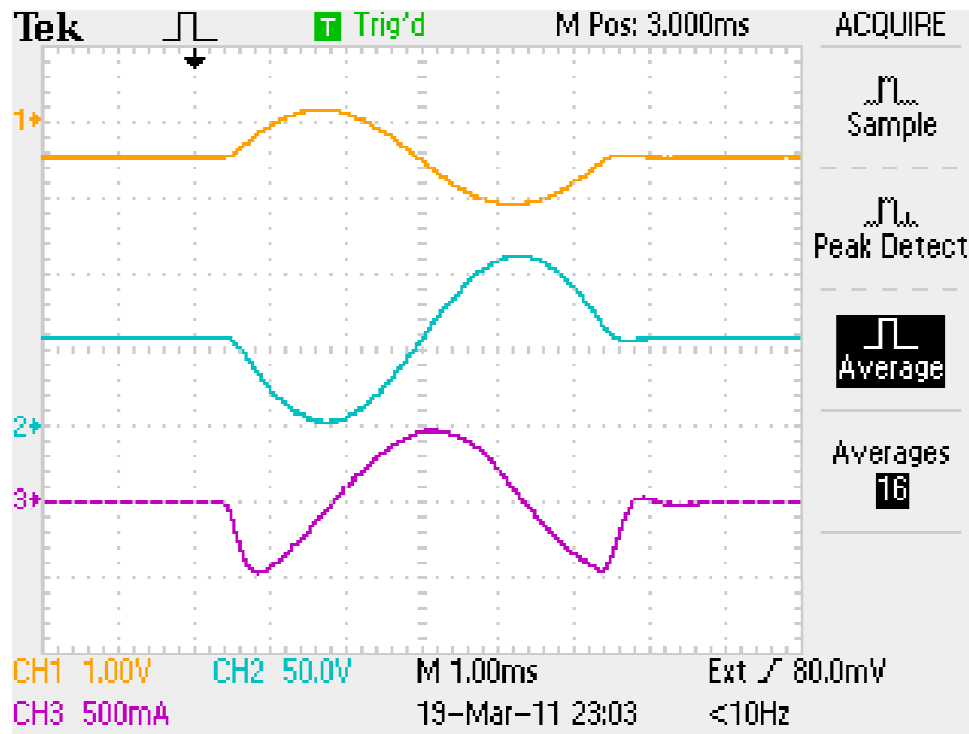
System Costs rev.1 (single RF station)

- PB51 – 2x16x150EUR (4.8 kE)
- ATC210 – 2x250EUR
- BCM – 8x50EUR
- XV5FVX30 – 2x300EUR
- BOX – 2x200 EUR
- PCB (10L) – xTCA - 2x800EUR (with doc)
- PCB (4L) – RTM – 2x375EUR (with doc)

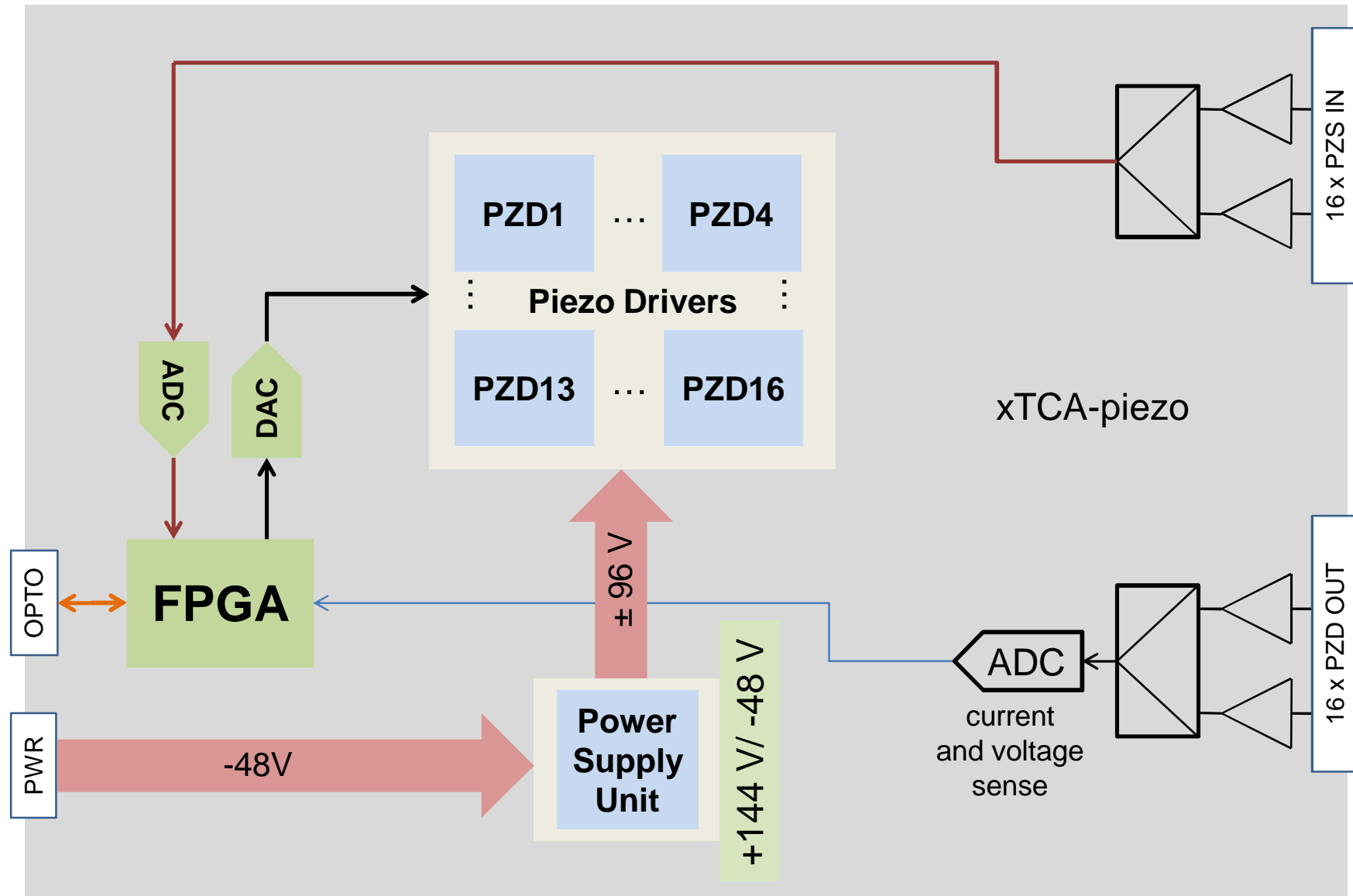
Total cost – ~9kE (should be 2kE!!!)

Conclusions to rev. 2

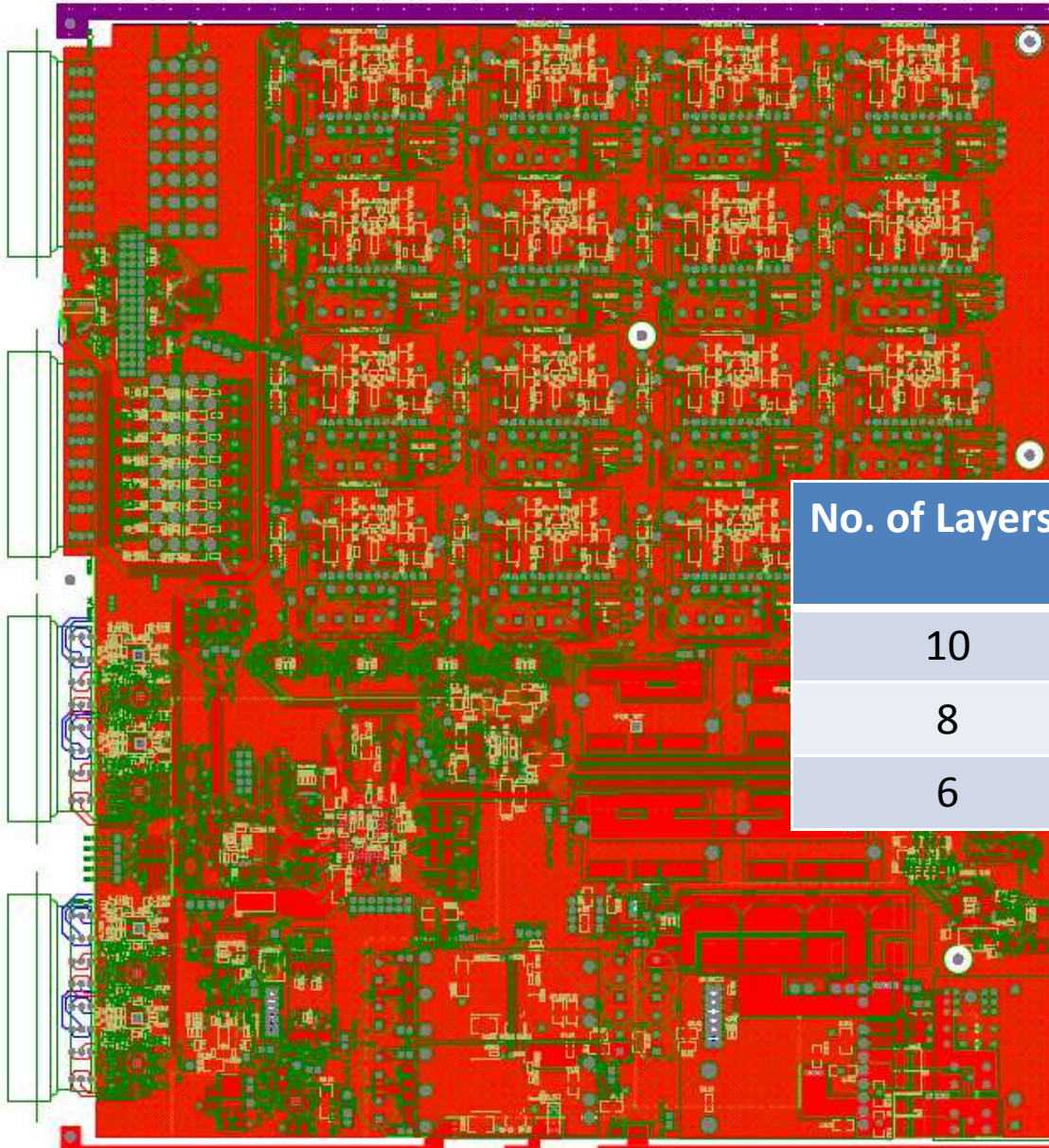
- Change radiators direction
- Unipolar/bipolar Power Supply Unit
- Unipolar drive -20 V / 120 V
- Avoid sharp current transitions
- Reduce the costs



Piezo Controller rev. 2



Piezo Controller rev.2 (PCB)



No. of Layers	Unit cost [EUR]	60 units cost [EUR]
10	240	14400
8	148	8880
6	195	11700

System Costs rev.2 (single RF station)

- PB51 – 2x16x150EUR (4.8 kE)
- ATC210 – 2x250EUR
- BCM – 8x50EUR
- XC6SLX25T – 2x40EUR
- BOX – 2x200 EUR
- PCB (8L) – xTCA - 2x300EUR (with doc)

Total cost – ~6.4kE (should be 2kE!!!)

Thank You for Your Attention

