

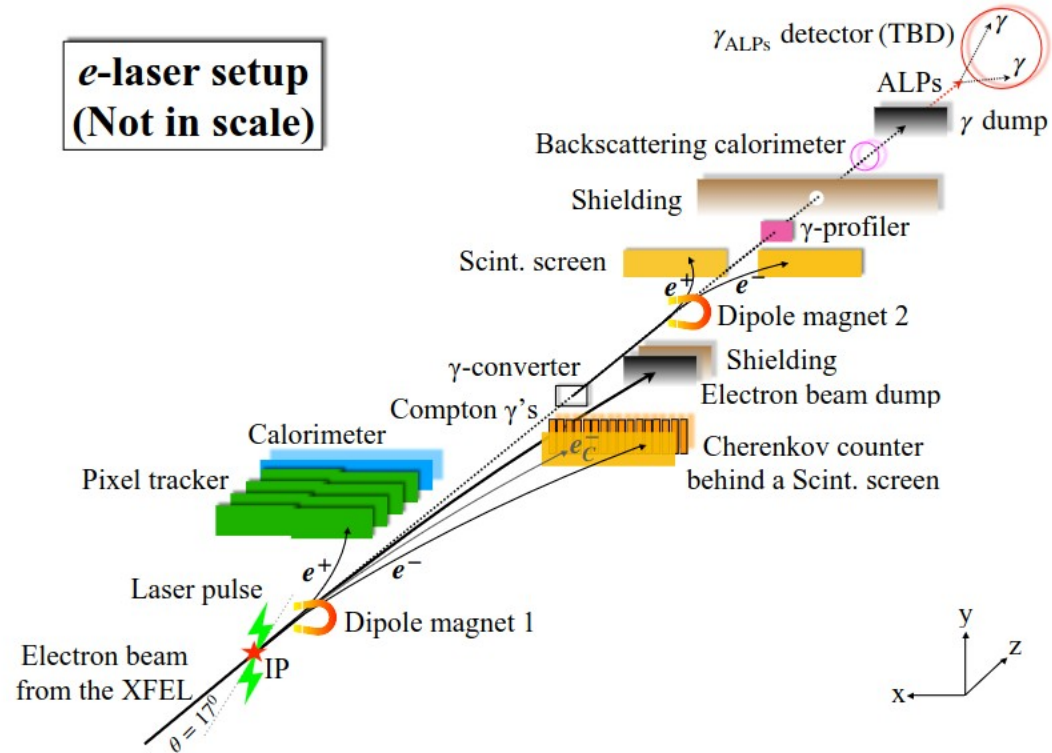
Tracking in the LUXE experiment

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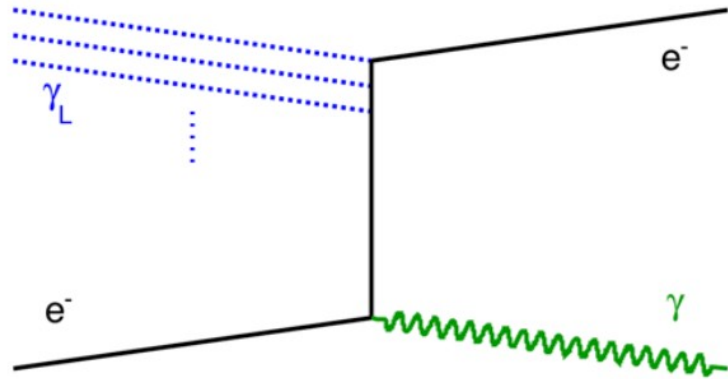
The Laser Und XFEL Experiment (LUXE)

LUXE main goals:

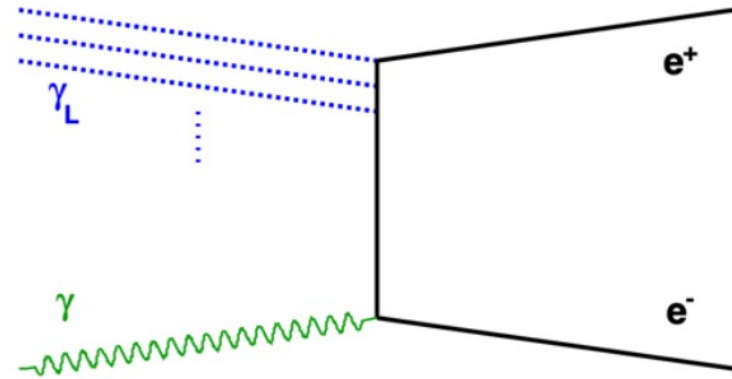
- Precision measurements in the **non-perturbative** regime of **QED**
- Search for **new particles** beyond the SM



The Laser Und XFEL Experiment (LUXE)



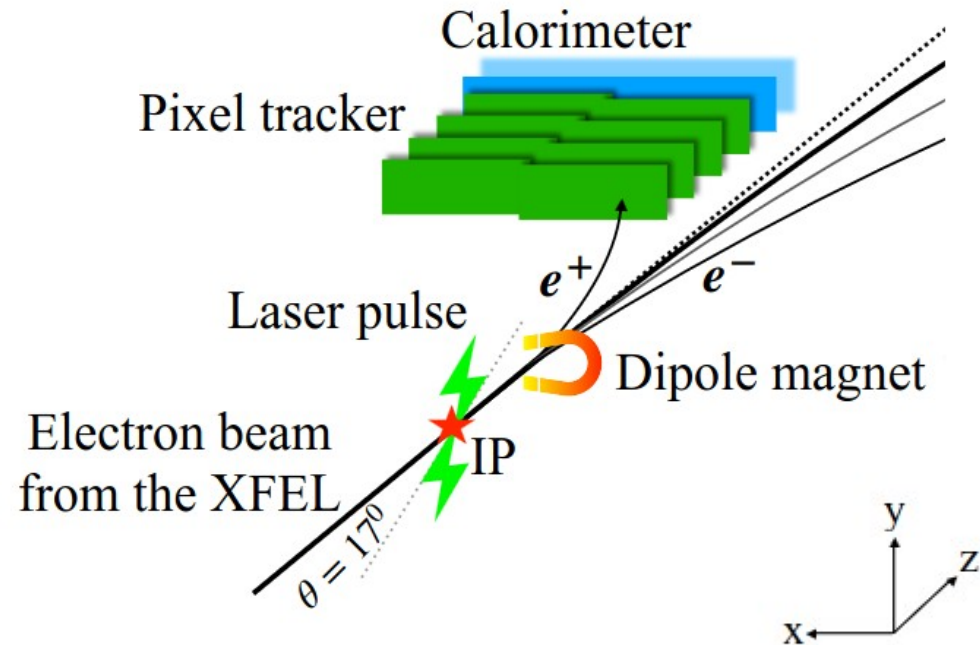
Non-linear Compton scattering



Breit-Wheeler process

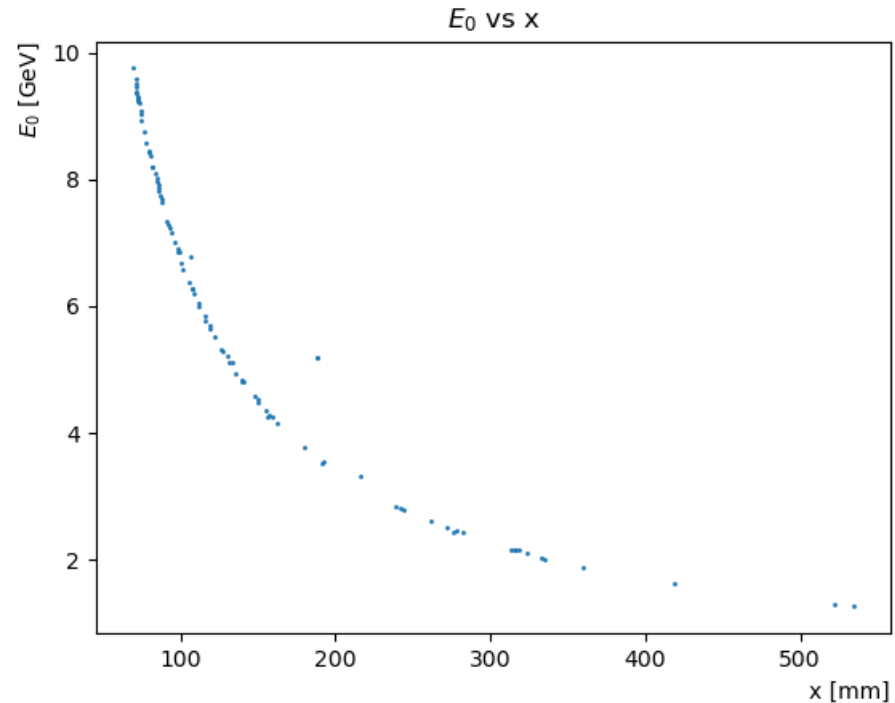
Tracking

- 4 Layers, 100 mm apart
- Each layer – 2 sensors slightly overlapping
- Hits position is currently given in **global** coordinates: (x, y, z)
- No magnetic field in the tracker
→ Trajectories are straight lines (up to scattering)



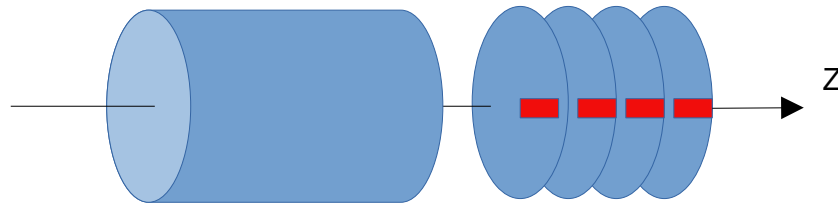
Correlation between E_0 and x

- More energetic positrons are expected to reach the tracker closer to the beam axis.
- Outliers in this case are a result of positrons emitting a photon, thus losing energy, but still registered as primary particles with their initial energy



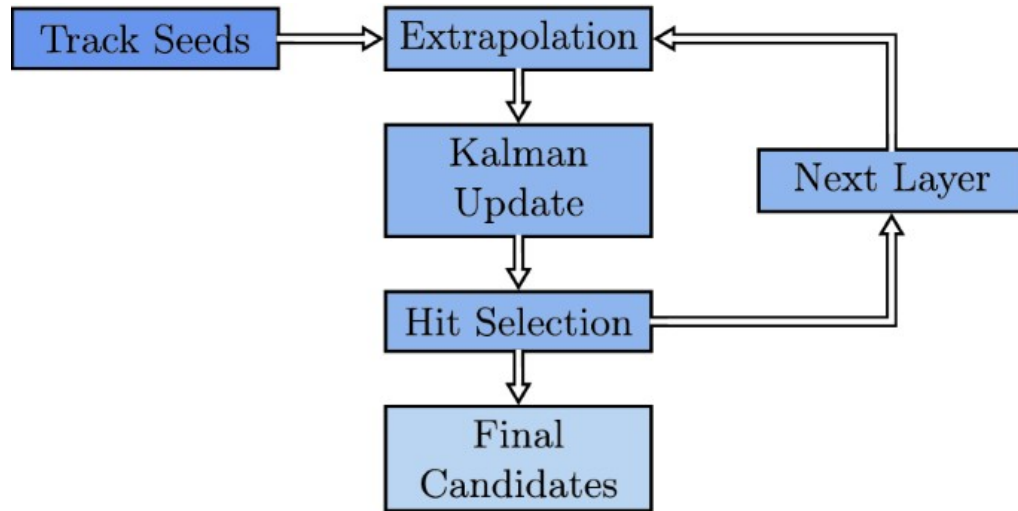
A common tracking software (ACTS)

- Experiment-independent toolkit for track reconstruction in HEP
- Assumes a barrel-shaped detector with end-cap disks
- The 4 layers are mapped to a rectangle in 4 end-cap disks:



Combinatorial Kalman Filter (CKF)

- Performs the track finding and track fitting altogether.
- If more than one hit is found, the procedure splits for both possibilities



Images from: <https://acts.readthedocs.io/en/latest/tracking.html> , and: https://link.springer.com/chapter/10.1007/978-3-030-24997-7_6

Kalman Filter

- Performs track fitting only, thus, requires track candidates
- At each step – adds the next hit and updates the fit
- The code is written based on the CKF for LUXE
- ACTS requires a propagator, updater, and a smoother
- Currently – assume a single particle and consider all hits as a track candidate
- Next step – get multiple track candidates and loop over them

Quadratic unconstrained binary optimization (QUBO)

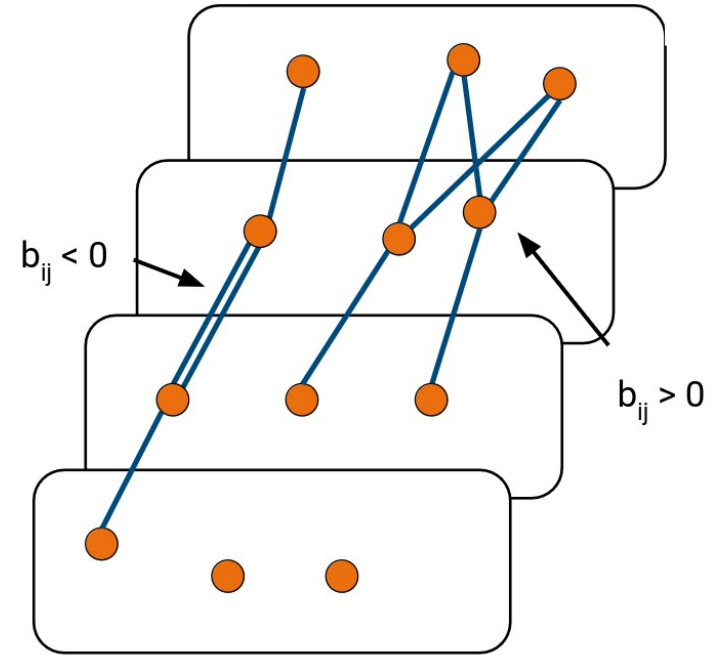
- Current focus is for KF input is the output of the QUBO
- Should be applicable for other track finding methods (gmn etc.)
- The objective function to minimize:

$$O = \sum_i^N \sum_{j < i} b_{ij} T_i T_j + \sum_{i=1}^N a_i T_i,$$

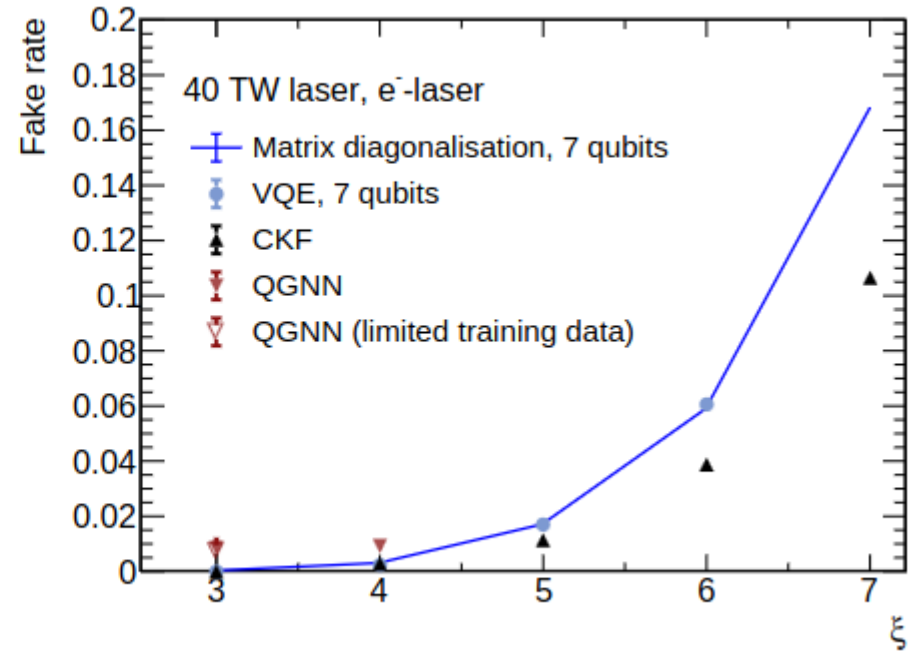
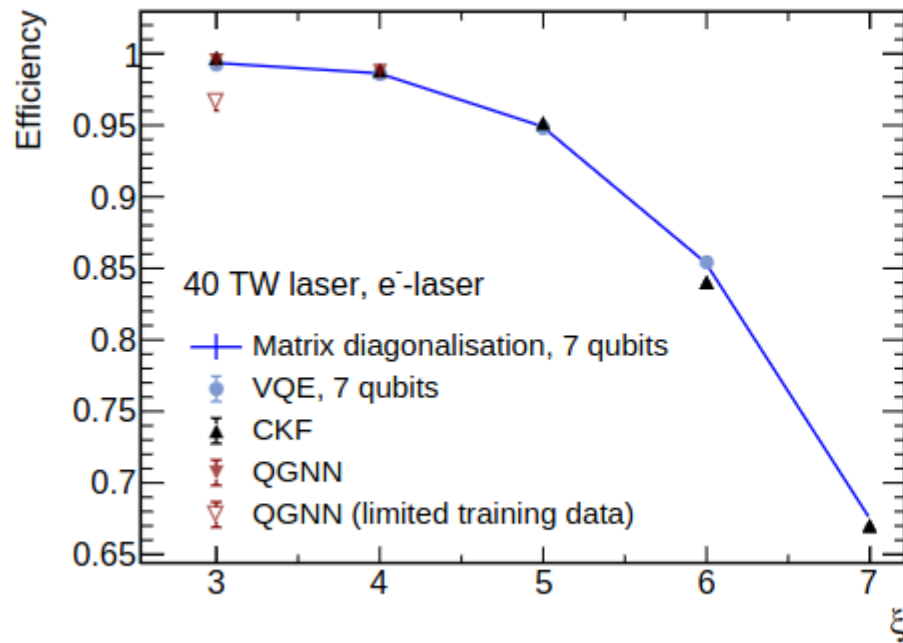
T_i – triplets of consecutive hits, assume binary values.

b_{ij} – compatibility of triplets

a_i – quality of the triplet



CKF efficiency and fake rate

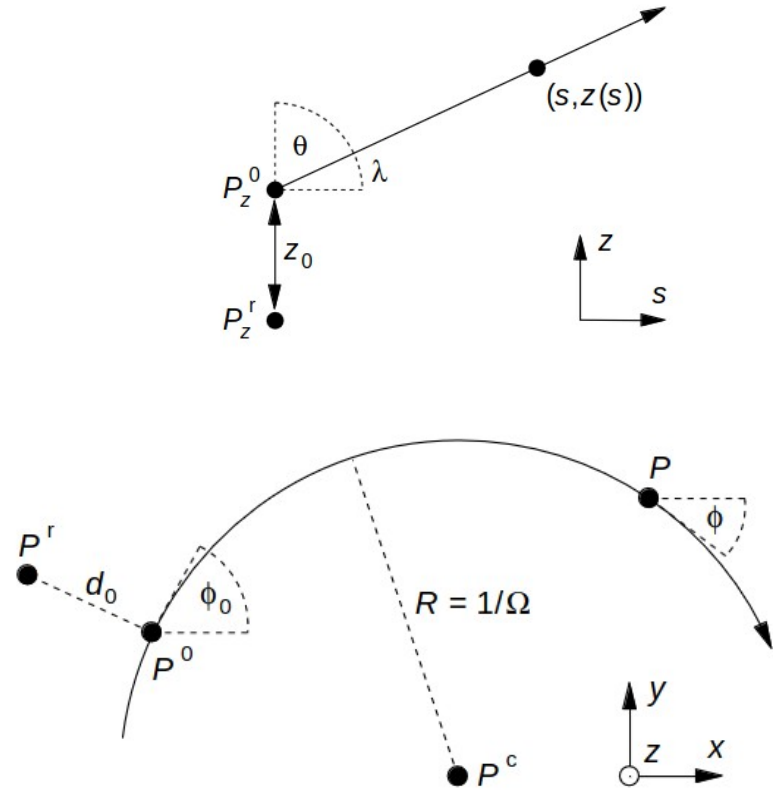
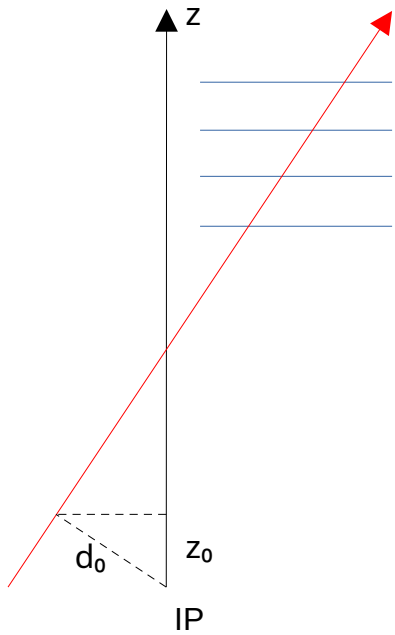


CKF includes the track fitting. For QUBO, the track candidates were fitted to straight lines with the least-square method. Current aim is to fit using the Kalman filter and compare the results.

Image taken from: <https://arxiv.org/pdf/2304.01690.pdf>

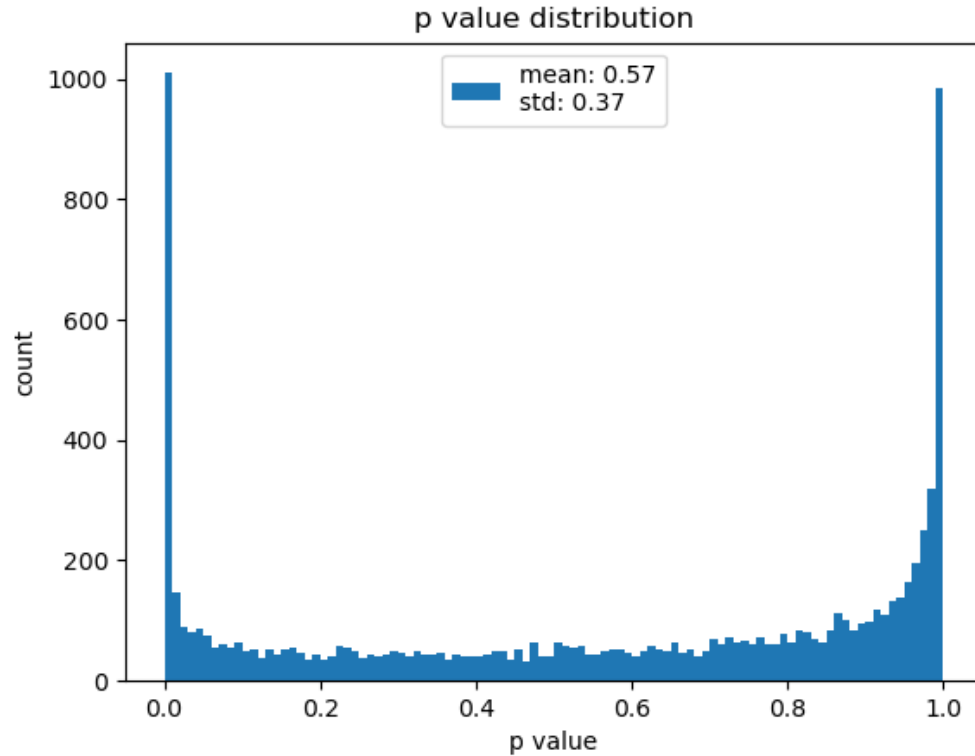
Track Parameters

The track is given by 5 parameters: $(d_0, z_0, \Omega, \phi_0, \tan(\tilde{\lambda}))$



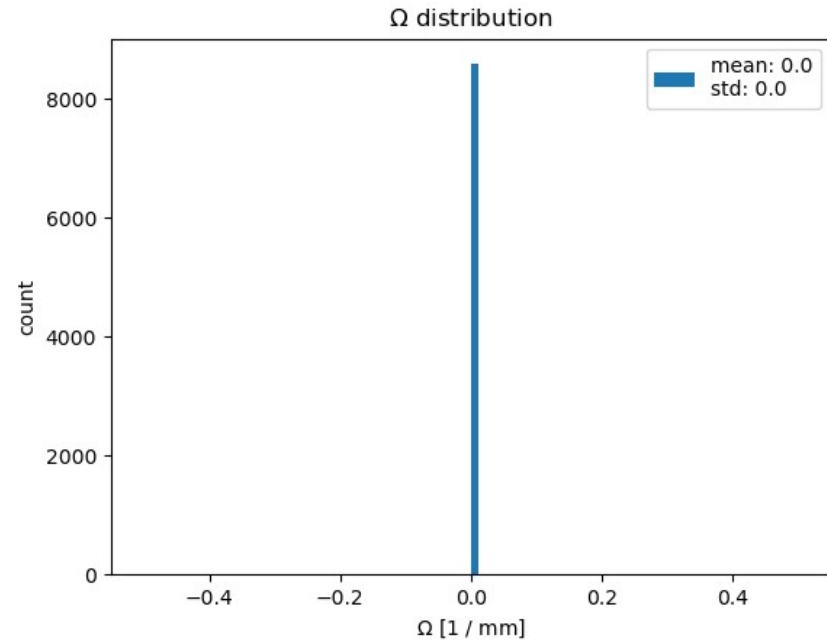
P value

- Number of events: 10000
- Reconstructed tracks: 8583

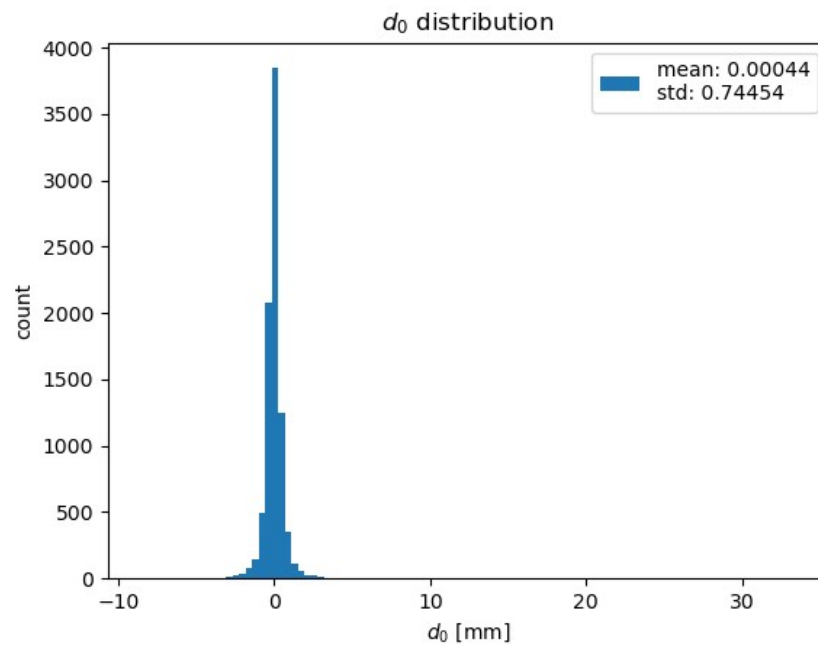
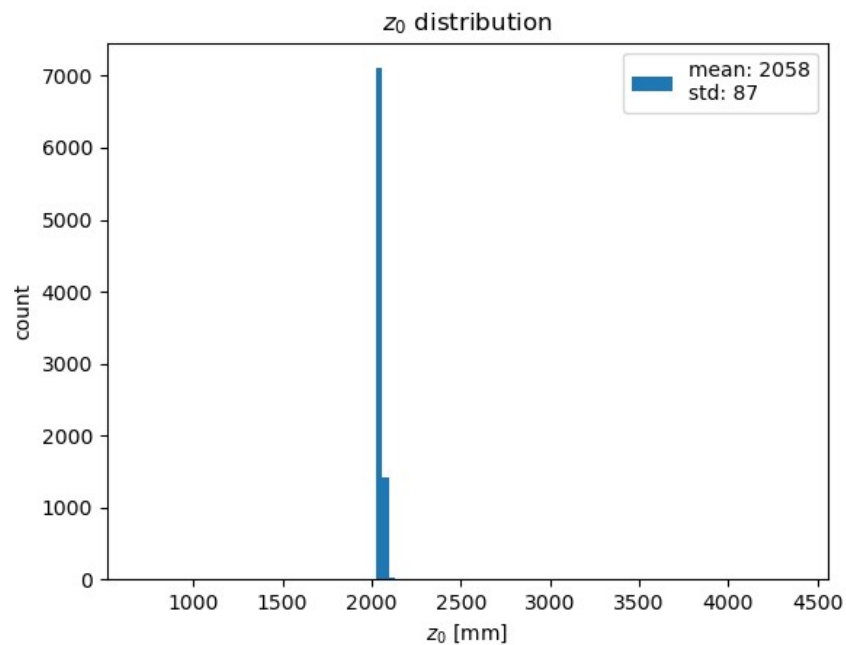


Track Parameters Distributions

- Ω might be pre-fixed to 0 (under investigation).



Track Parameters Distributions



Track Parameters Distributions

