

*LUXE Technical Meeting, 5th October 2023*

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# Laser polarisation effects on positron

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# Introduction

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- ❖ Comparing samples from ptarmigan v0.8.1 (CP) to v0.11 (LP).
- ❖ Linear laser polarisation along x.
- ❖ High-power laser systems are normally linearly polarised, and the peak electric field at focus is reduced by a factor of  $\sqrt{2}$  if converted to circular polarisation.
- ❖ Circular polarisation assumed in earlier studies as predictions are easier to produce.

# Comparison

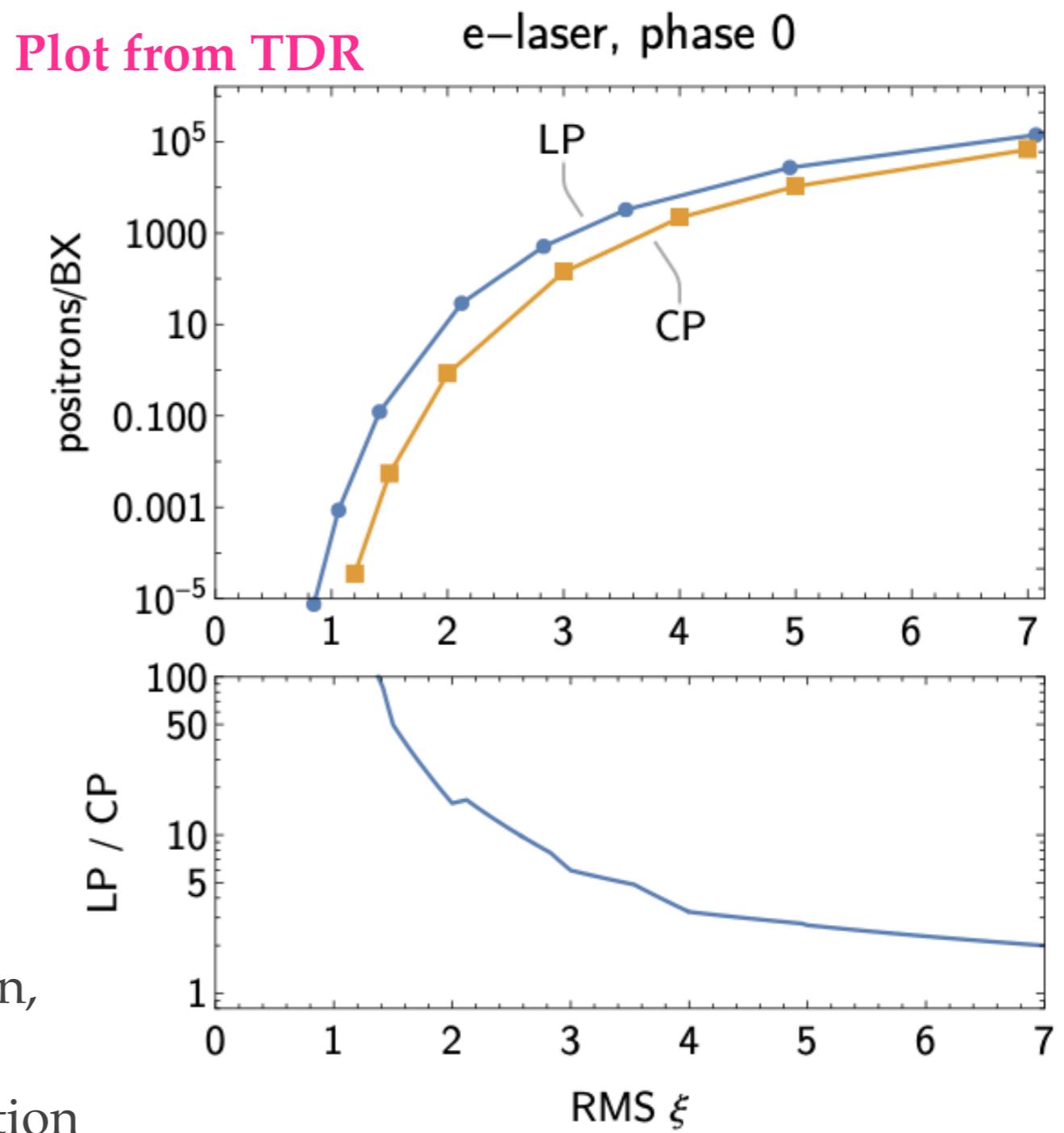
- ❖ E-laser phase-0 highest  $\xi$  chosen, averaged over 10 BX.
- ❖ dt\_multiplier affects how close weights of positrons are to 1 (the smaller the better, but more CPU intensive).

Ptarmigan versions	v0.8.1	v0.11
Nominal $\xi$	7	7
Polarisation	Circular	Linear
dt_multiplier	0.5	0.2
Waist	$3.38\mu\text{m}$	$\sqrt{2} \times 3.38\mu\text{m}$
Average $\xi$	3.25	2.46
# positrons (raw)	40601	27025
# positrons (weighted)	67043	27374
		108325
		140982

# Positron rate

- ❖ For a given laser waist, the positron rate is larger for linear polarisation than for circular polarisation.

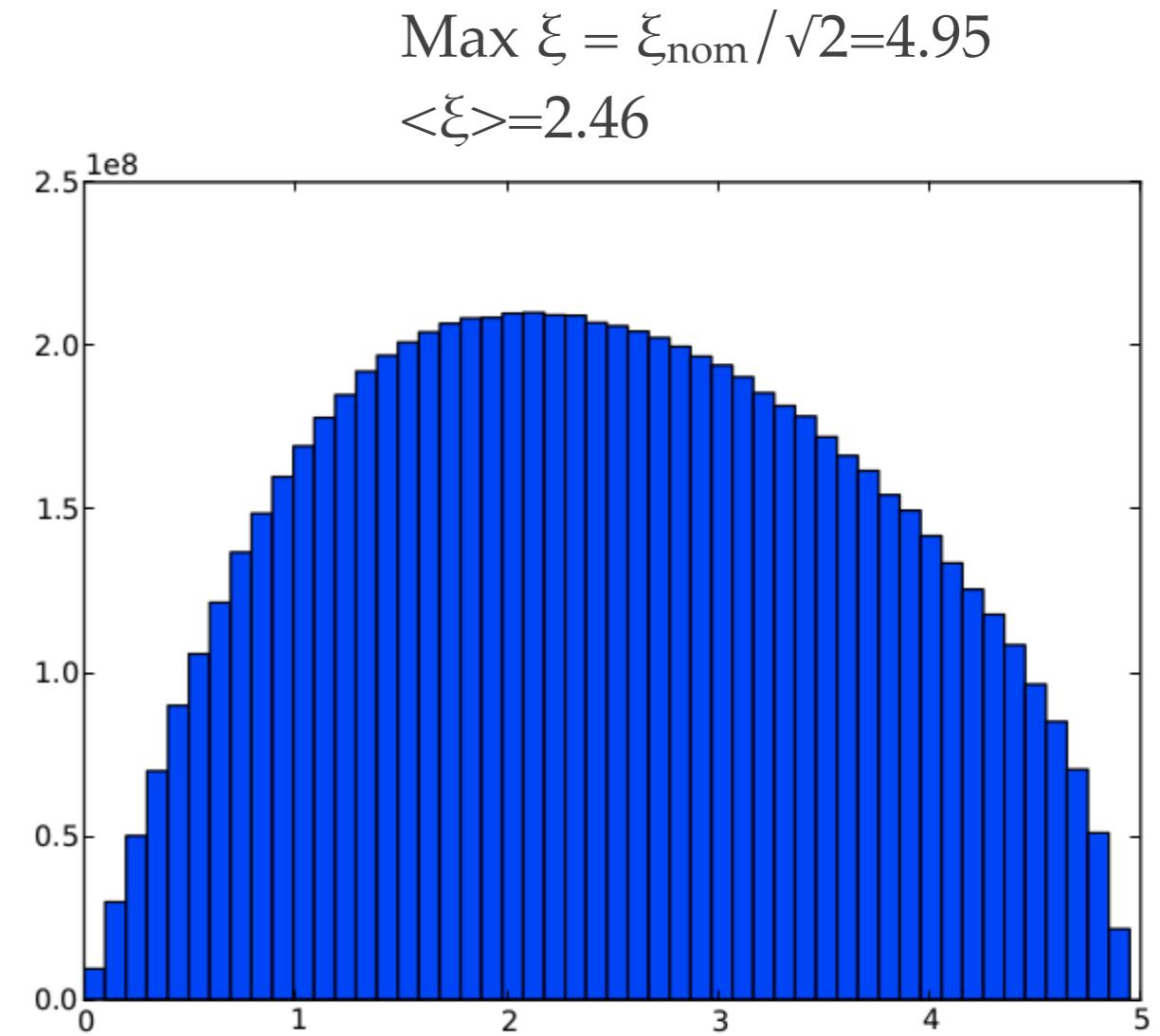
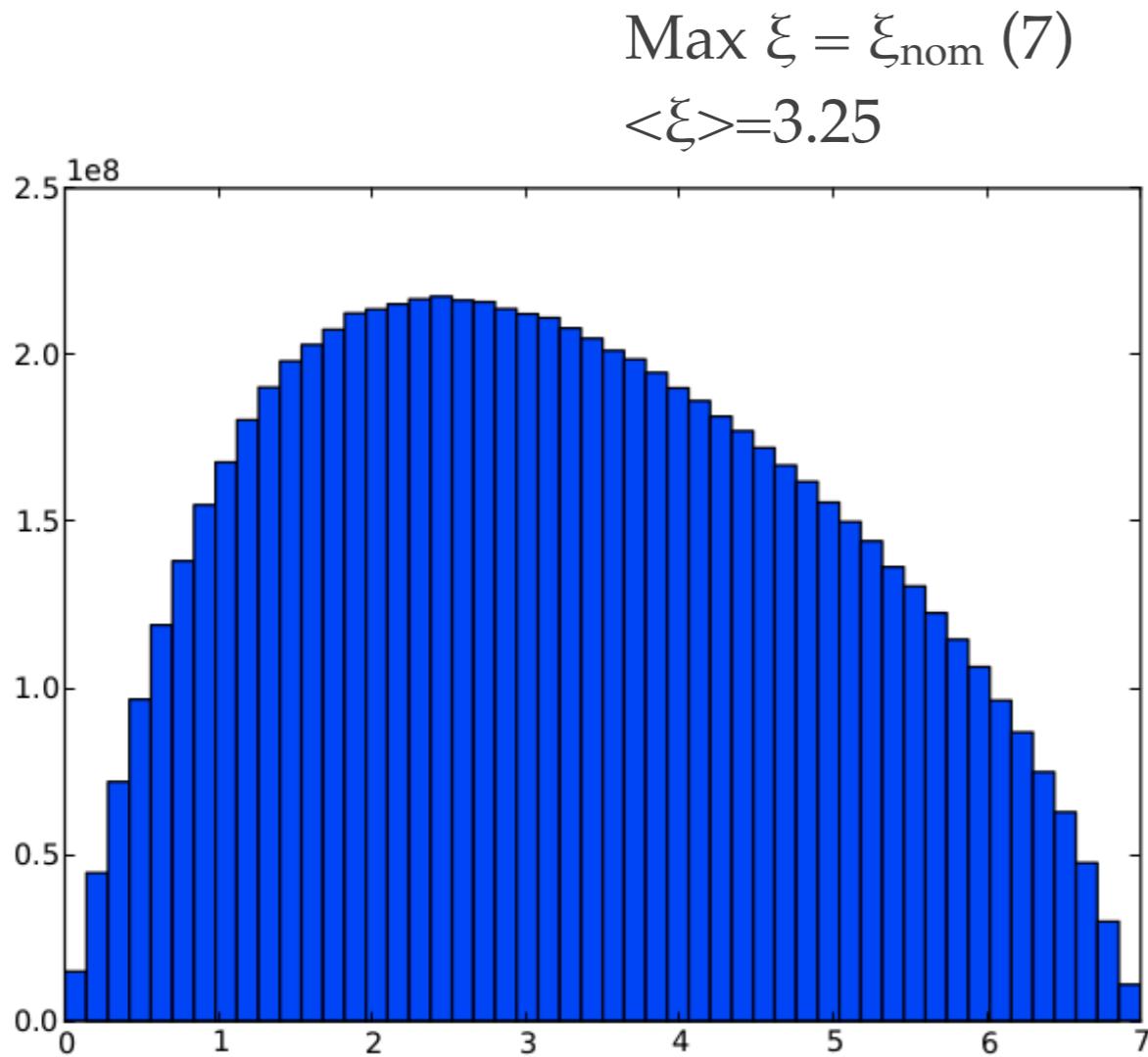
$$\xi_{RMS} = \frac{eE_{RMS}}{m\omega} \text{ for circular polarisation,}$$
$$\xi_{RMS} = \sqrt{2} \frac{eE_{RMS}}{m\omega} \text{ for linear polarisation}$$





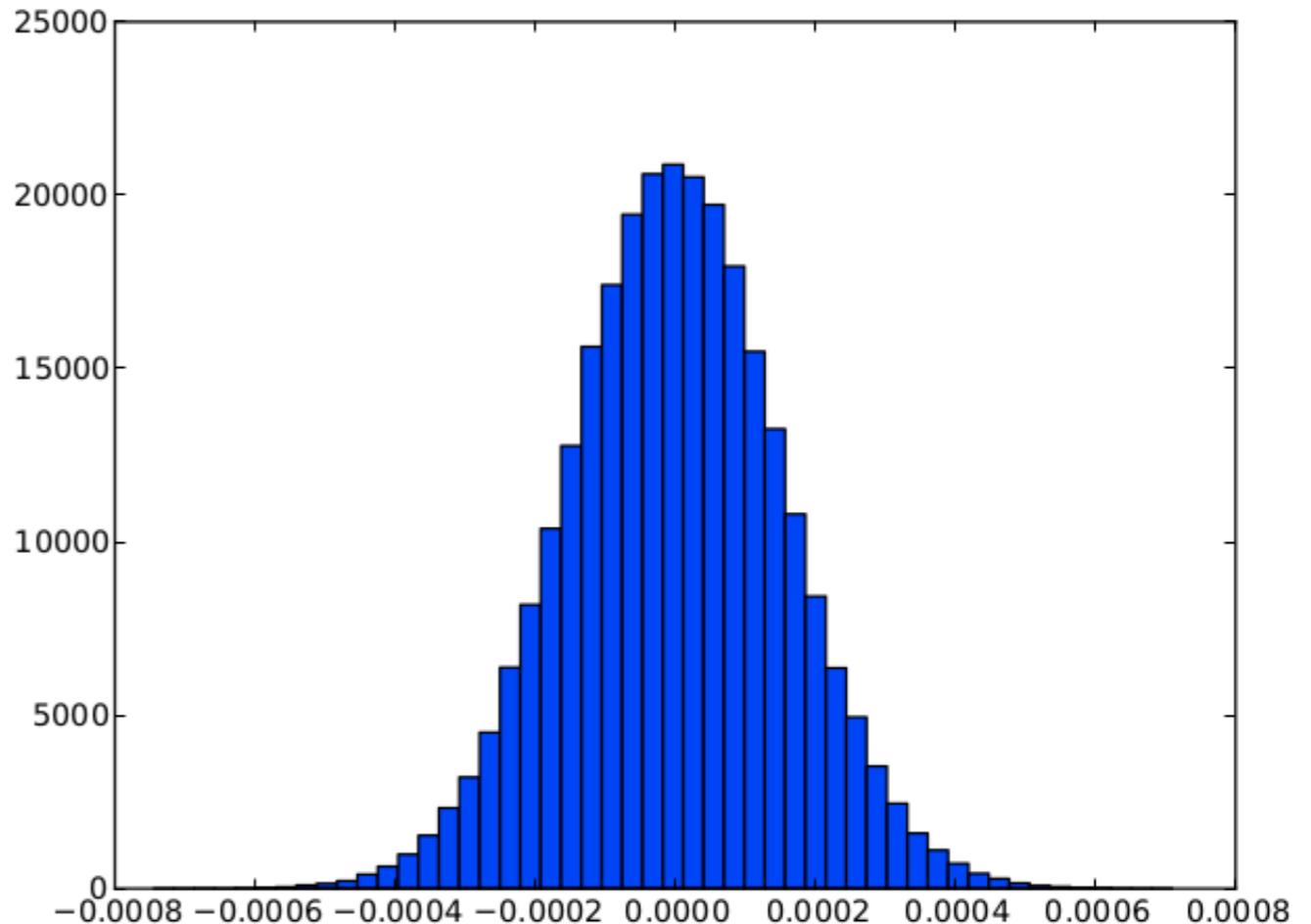
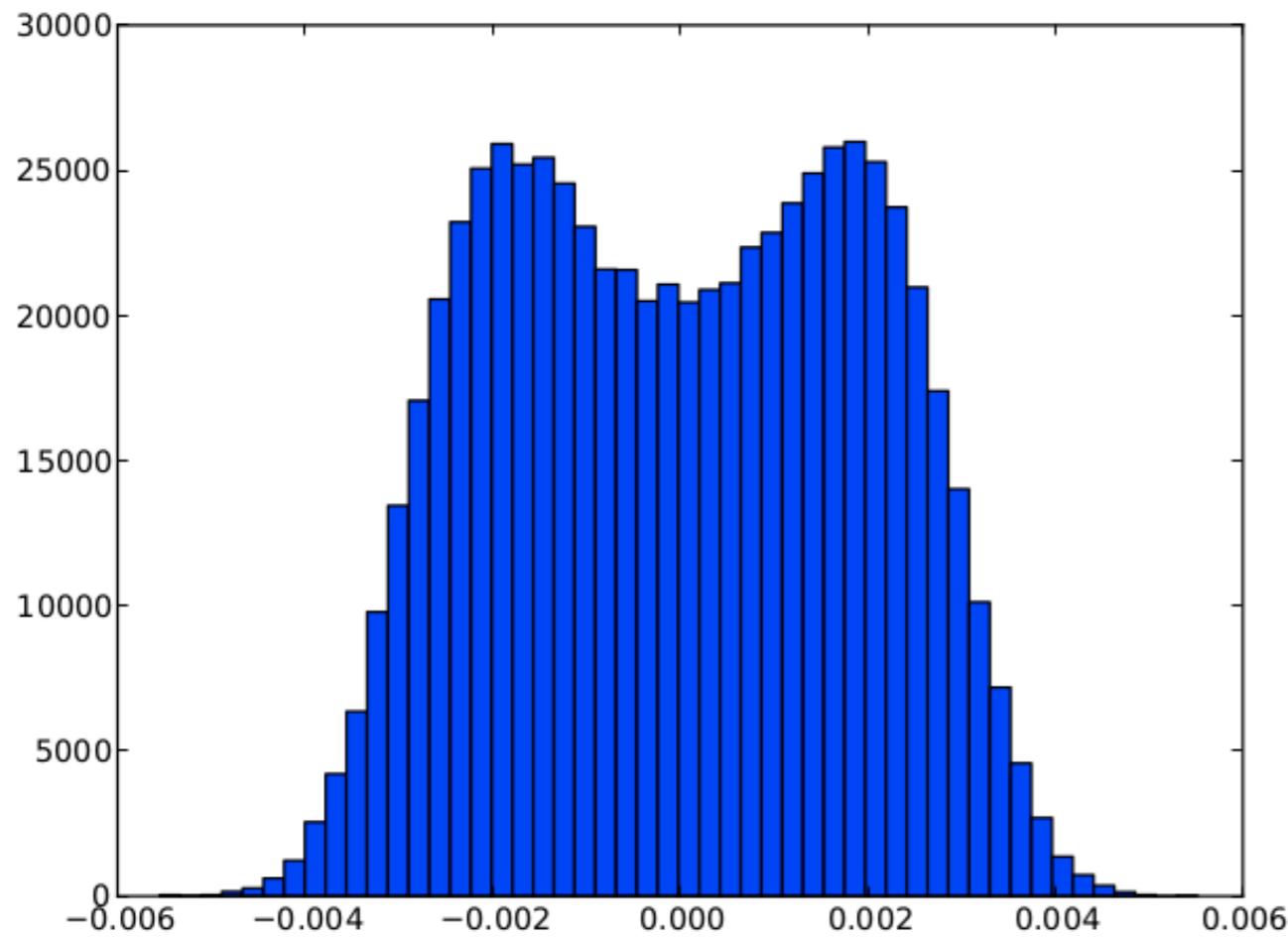
I compare both with  $\xi_{\text{nom}}=7$  here, but one should normally compare same max  $\xi$ .

- ❖ Left: ptarmigan v0.8.1 (CP,  $\xi_{\text{nom}}=7$ ). Right: ptarmigan v0.11 (LP,  $\xi_{\text{nom}}=7$ ).
- ❖ Summed over 10 BX



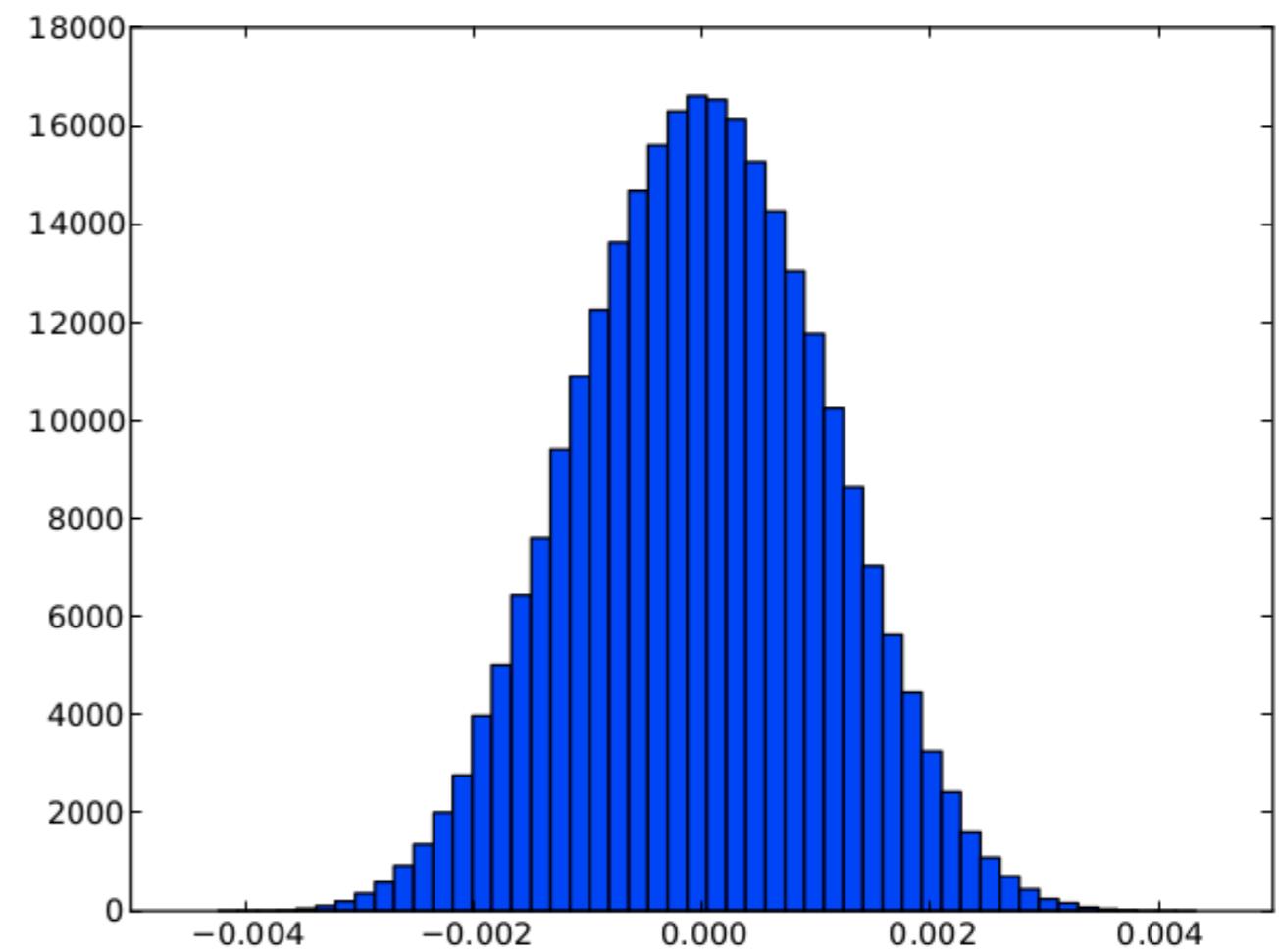
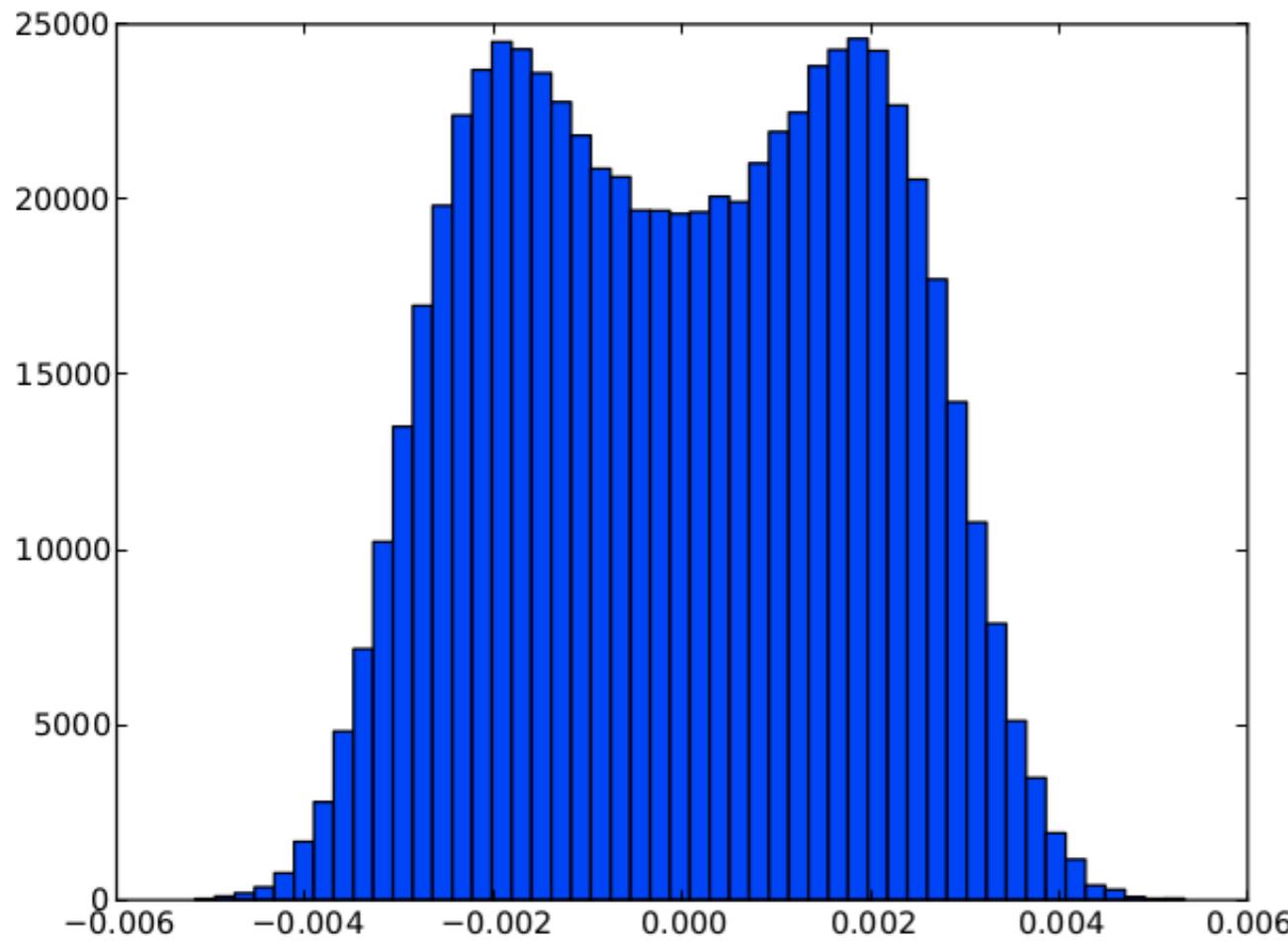
# Momentum in y

- ❖ Left: ptarmigan v0.8.1 (CP,  $\xi_{\text{nom}}=7$ ). Right: ptarmigan v0.11 (LP,  $\xi_{\text{nom}}=7$ )
- ❖ Note the scale in x-axis, momentum spread is 10x larger on the left.



# Momentum in x

- ❖ The spread in x is of the same scale but shows the same single vs double peak structure.



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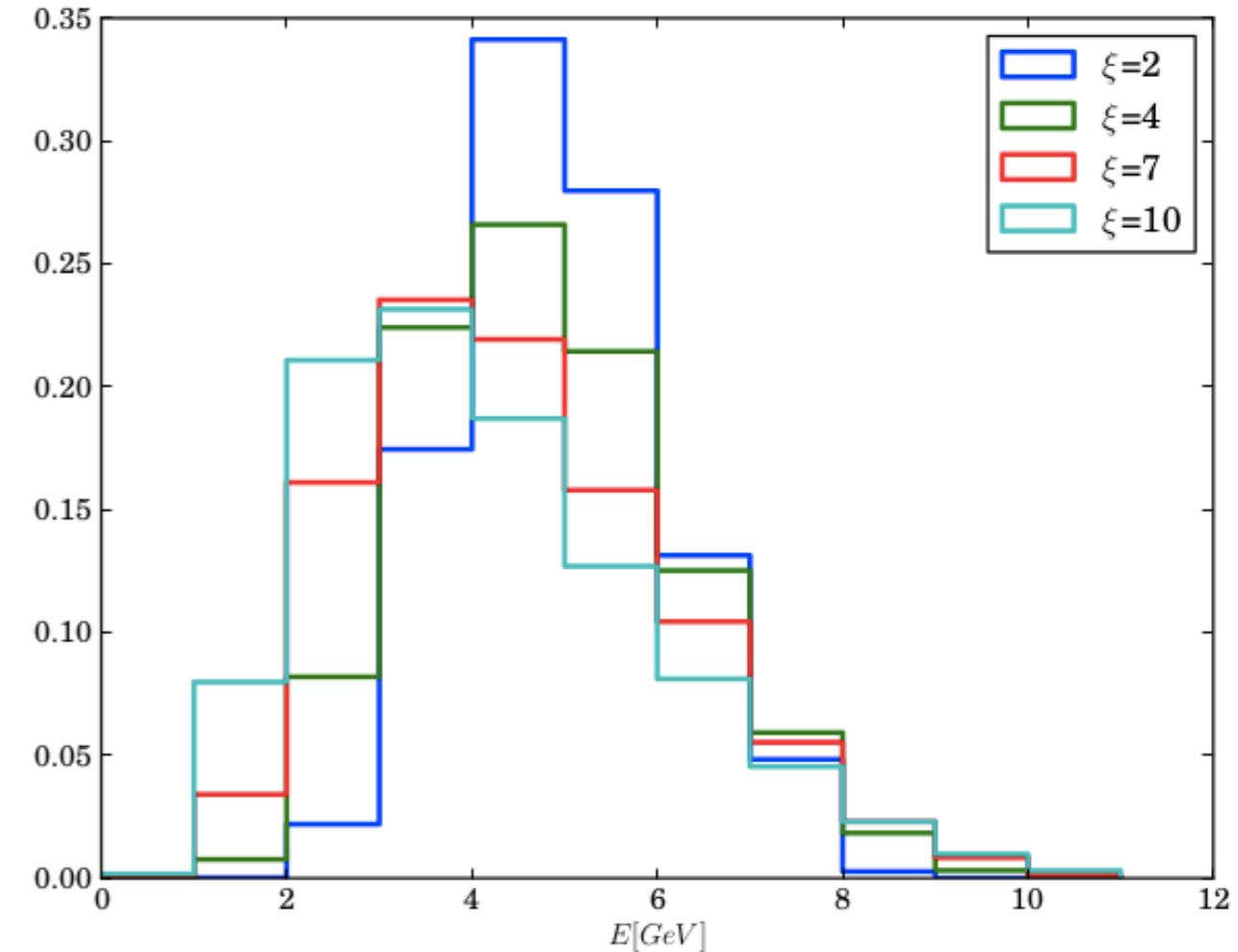
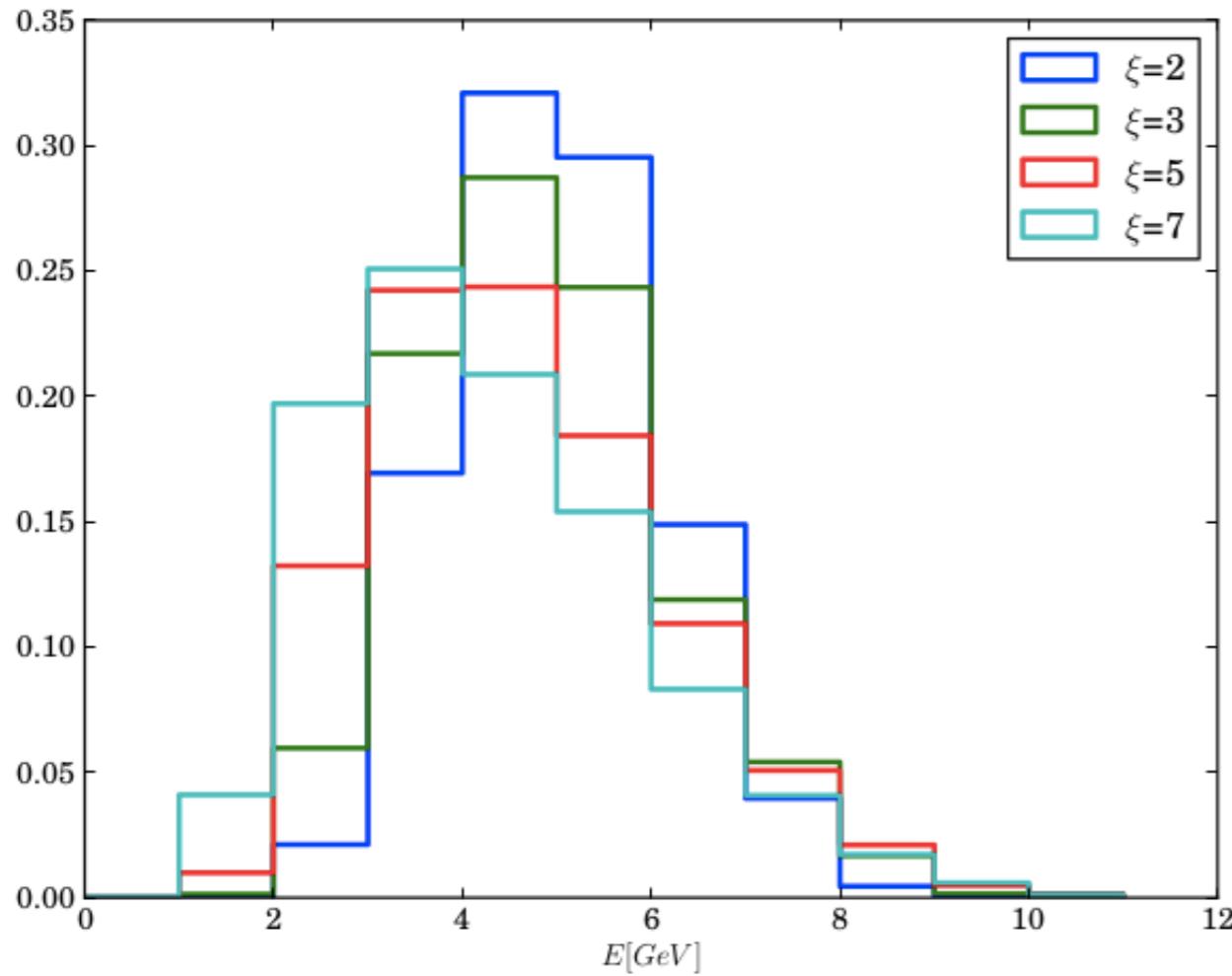
# $\xi$ dependence

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- ❖ For circular polarisation,  $p_x \sim p_y$  and shows double peak structure.
- ❖ For linear polarisation,  $p_y$  much narrower than  $p_x$ .
- ❖ Now look at dependence on  $\xi$ .
- ❖ Use samples with weight biasing for statistics. Only 1 BX per  $\xi$ .
- ❖ Plots normalised to unity.

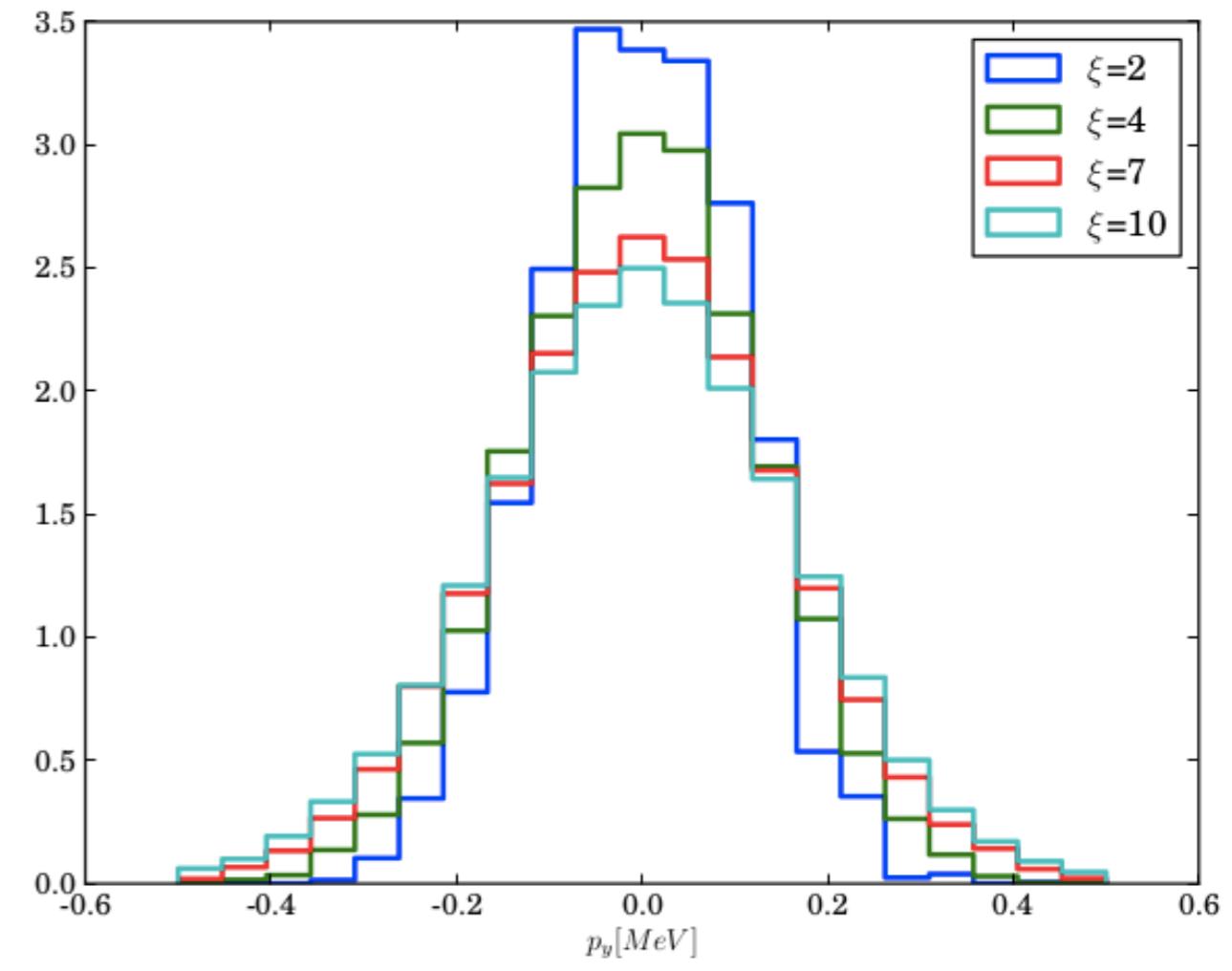
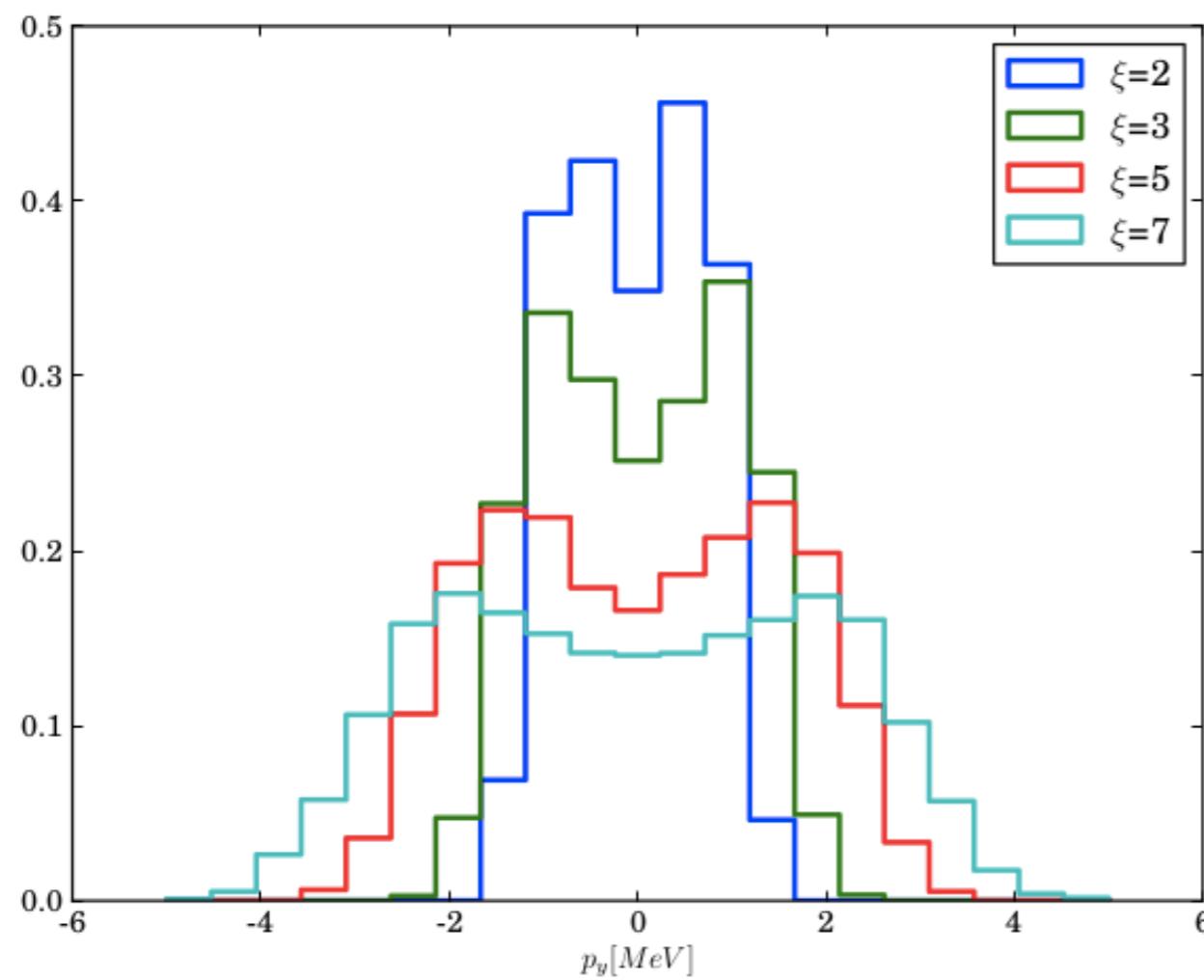
# E dependence on $\xi$

- ❖ Left: ptarmigan v0.8.1 (CP). Right: ptarmigan v0.11 (LP)
- ❖ Positron energy tends to be lower and broader as  $\xi$  increases.



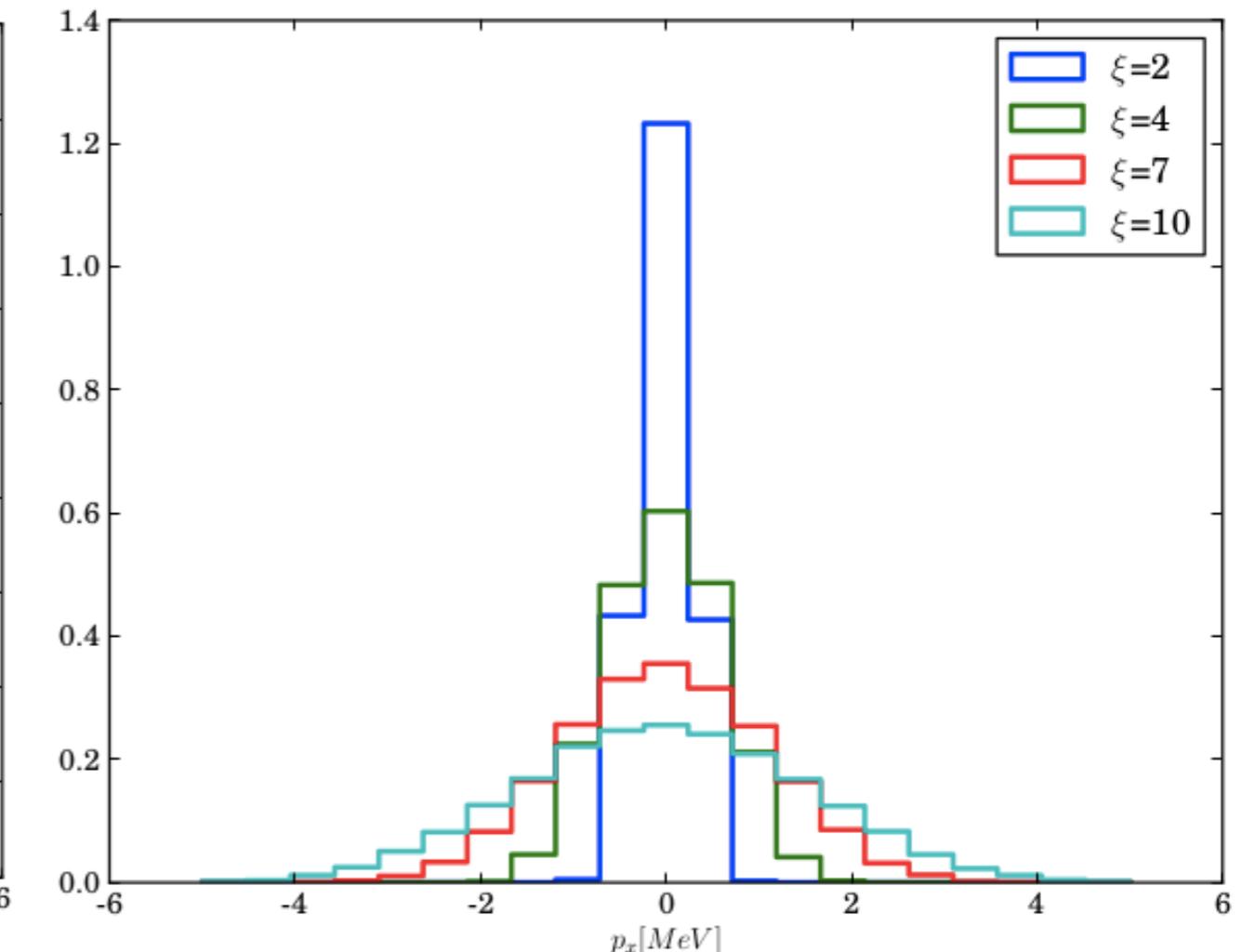
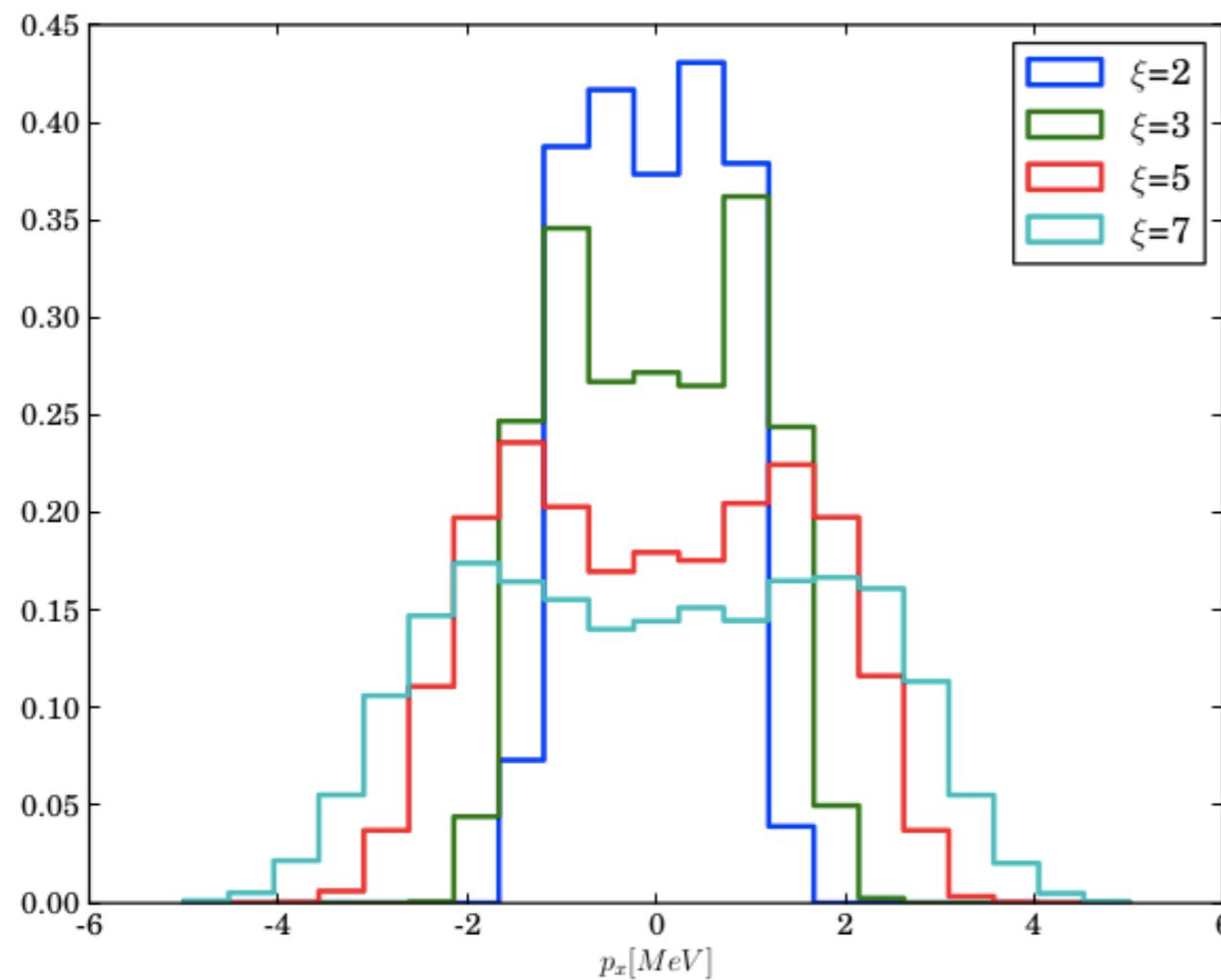
# $p_y$ dependence on $\xi$

- ❖ Left: ptarmigan v0.8.1 (CP). Right: ptarmigan v0.11 (LP)
- ❖ Broadens with  $\xi$ .



# $p_x$ dependence on $\xi$

- ❖ Left: ptarmigan v0.8.1 (CP). Right: ptarmigan v0.11 (LP)
- ❖ More pronounced broadening in  $x$  than in  $y$  for linear polarisation (polarisation along  $x$ ).



# Resolved polarisation

- ❖ Photon polarisation not resolved. See T. Blackburn's talk at e.g. collaboration meeting.
  - ❖ B-polarised (polarised perpendicular to laser E field) photons more likely to create  $e^+e^-$  pairs, but radiated photons are mostly E-polarised.
  - ❖ ~15-20% correction to the rate for LP, mostly unchanged for CP.
- ❖ To verify, run with latest ptarmigan version (1.3.3) and ask specifically for photon polarisation to be resolved.
- ❖ No obvious change in dispersion.

Phase-0	# positrons (weighted) from 1 BX	
	Not resolved	Resolved
$\xi=7$ CP	68692 (v0.8.1)	69204 (v1.3.3)
$\xi=10$ LP	141600 (v0.11)	129289 (v1.3.3)

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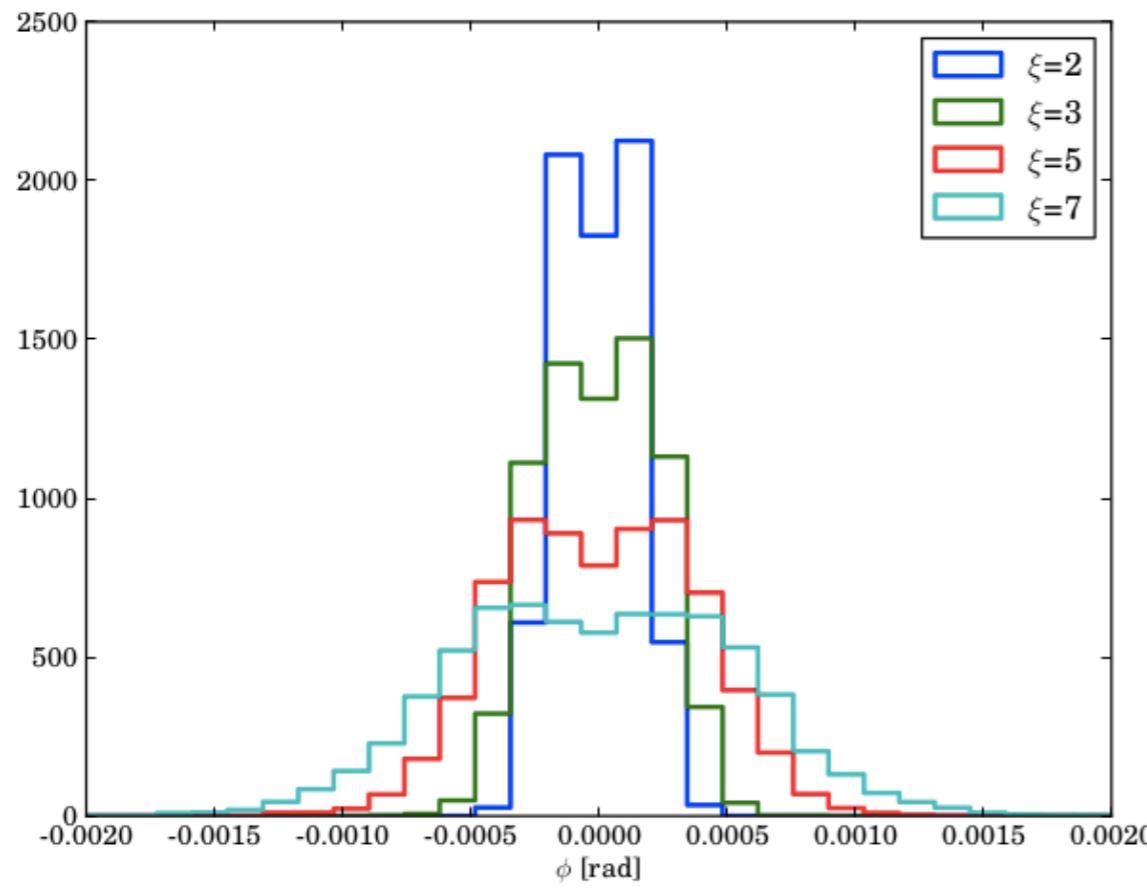
# Tracking

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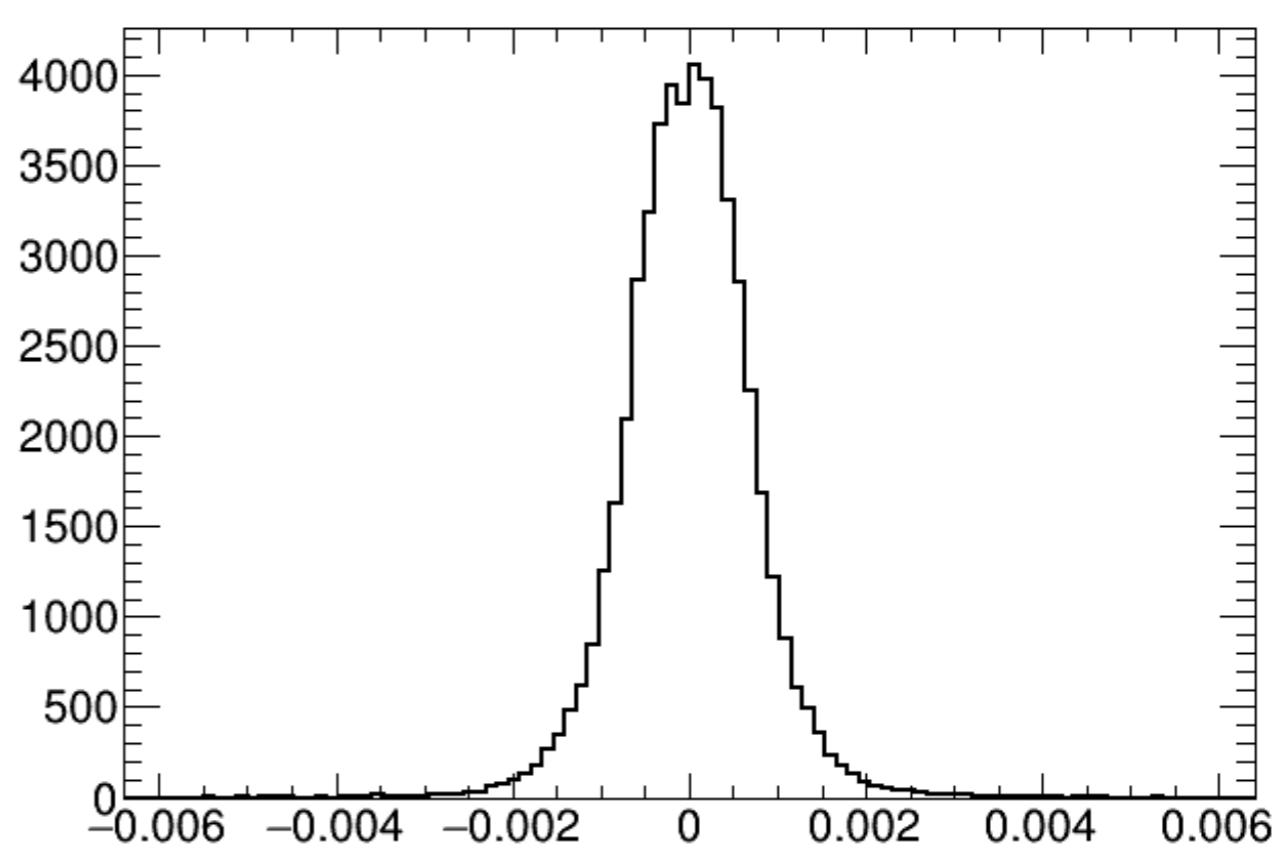
- ❖ What does this mean for tracking?
- ❖ Can we measure  $\xi$ ?
- ❖ For linear polarisation, the high  $\xi$  reach in phase-0 results in double the number of positrons than studied so far tracking.
  - ❖ However, the lack of dispersion in  $y$  means we can expect significantly higher than double the peak occupancy!
  - ❖ Tracking would be very challenging!

# Track $\phi$ (CP)

- ❖  $\phi$  is a measure of  $p_y$ .  $\phi$  measured from track fitting is quite smeared.
- ❖ However, width still shows a dependence on  $\xi$ .
  - ❖ Gaussian width =  $0.065 \pm 0.002$  ( $\xi=7$ ),  $0.046 \pm 0.004$  ( $\xi=5$ ),  $0.038 \pm 0.006$  ( $\xi=4$ ). Statistical uncertainty only.



True  $\phi$  at IP



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Measured  $\phi$  for  $\xi=7$

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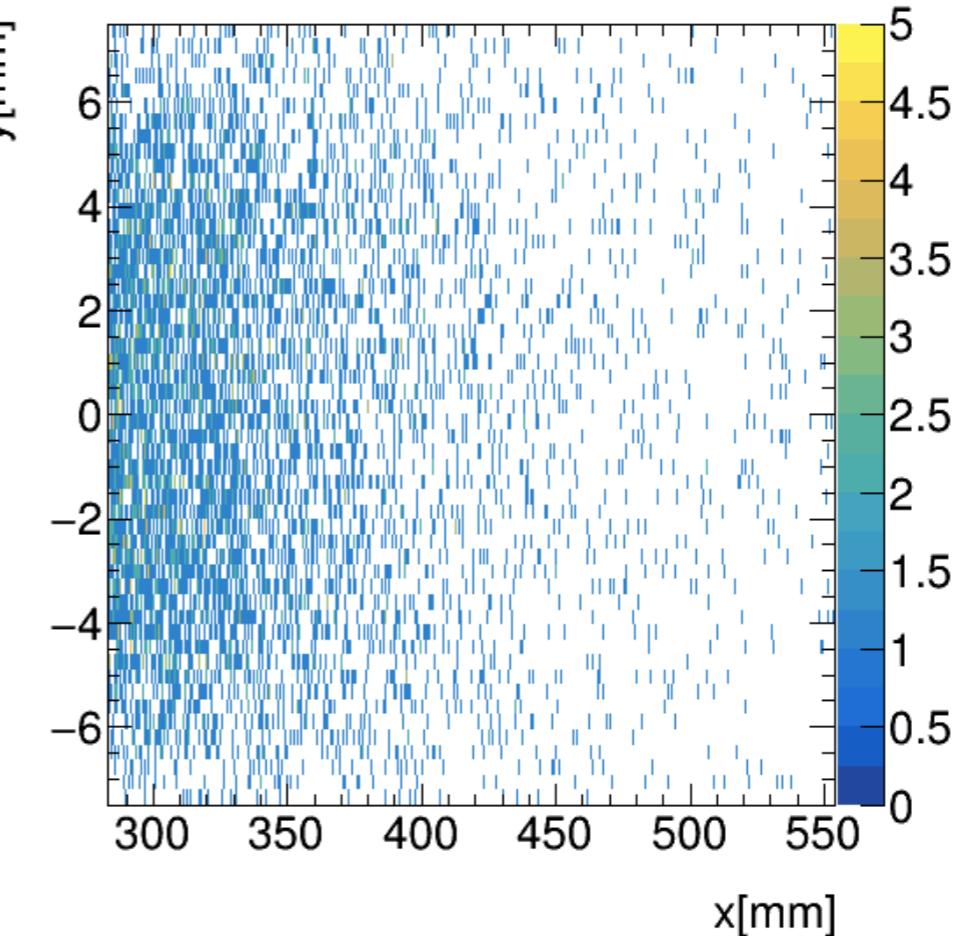
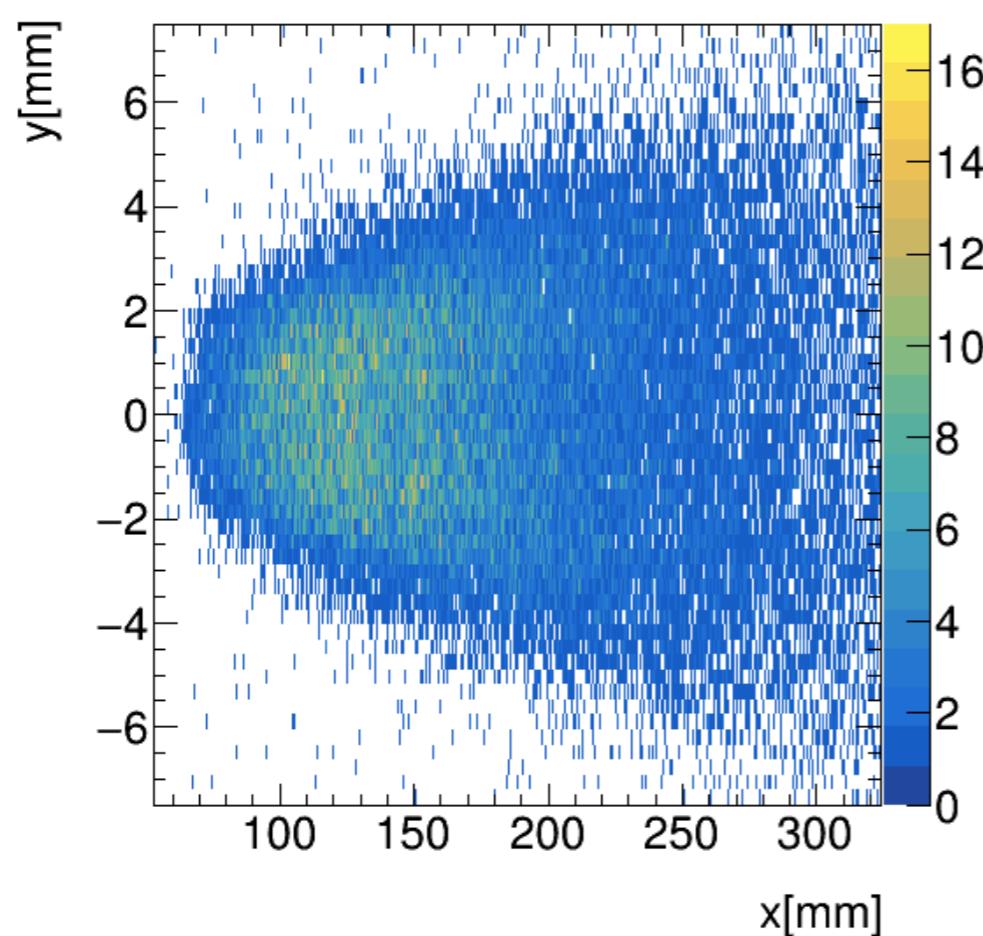
# Occupancy

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- ❖ For best estimate of occupancies, need:
  - ❖ Positron weight=1
  - ❖ Run full digitisation to get detector response, since a particle usually results in  $\geq 2$  pixel hits.
- ❖ This is not available, so I extrapolate to get an estimate..
- ❖ Compare high  $\xi$  reach in phase-0 for circular ( $\xi_{\text{nom}}=7$ ) vs linear ( $\xi_{\text{nom}}=10$ ) polarisation.
- ❖ Run tracker simulation using DDsim. Divide detector into roughly 10x10 pixels and count the number of particles to get occupancy map.
- ❖ Note: slightly different samples shown than before, use only 1 BX.

# Occupancy

- ❖ ptarmigan v0.8.1 (CP,  $\xi_{\text{nom}}=7$ ) custom weight=1 sample. # positrons (raw)= 67442.



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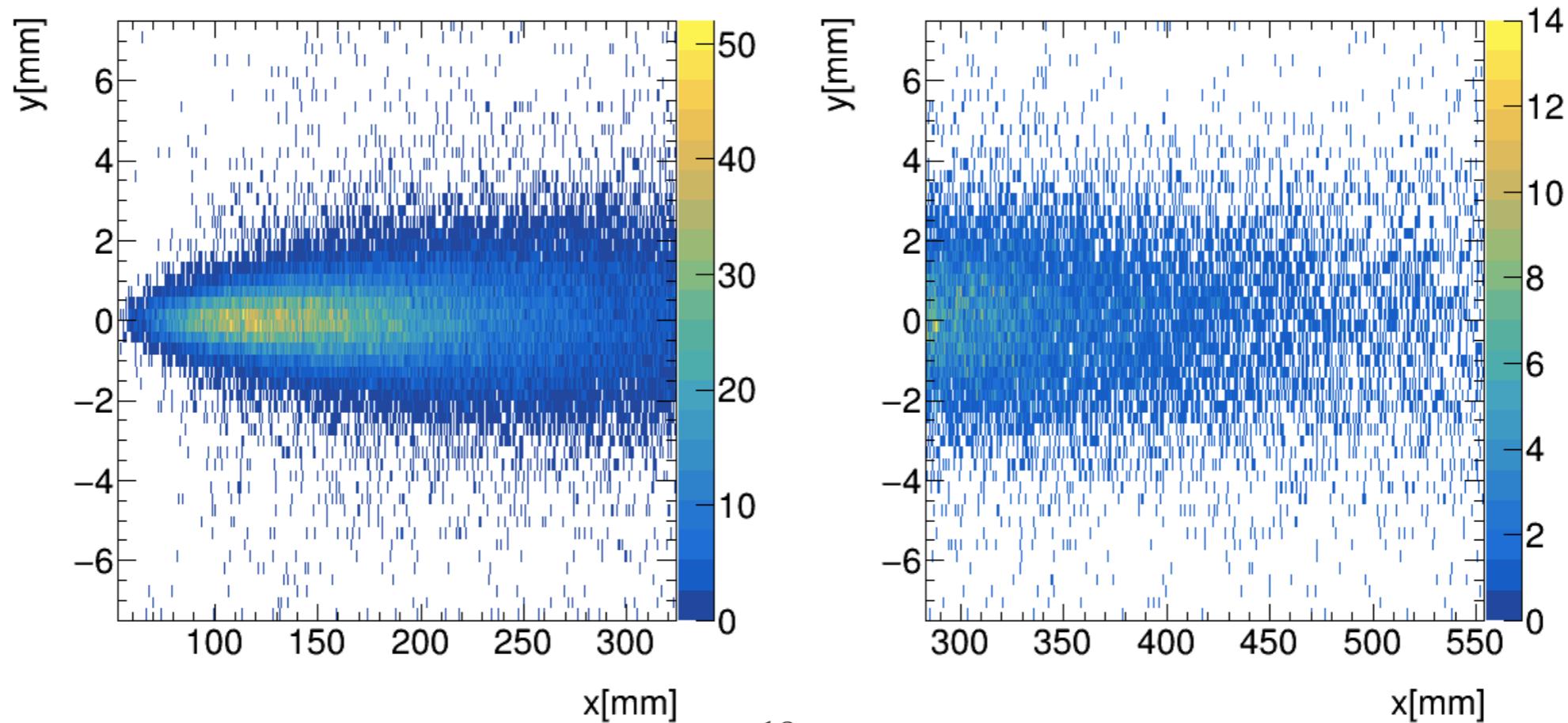
# Occupancy

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- ❖ Assuming  $\geq 2$  pixel hits per particle (2.6 pixels to be exact, from the average found in digitised samples):
  - ❖ Peak occupancy  $\sim 45\%$
  - ❖ 90% quantile on the inner stave  $\sim 13\%$  occupancy (i.e. 10% of all pixels in the inner stave have occupancy of  $\sim 13\%$ ).
- ❖ 56% of pixels in the inner stave are not hit.

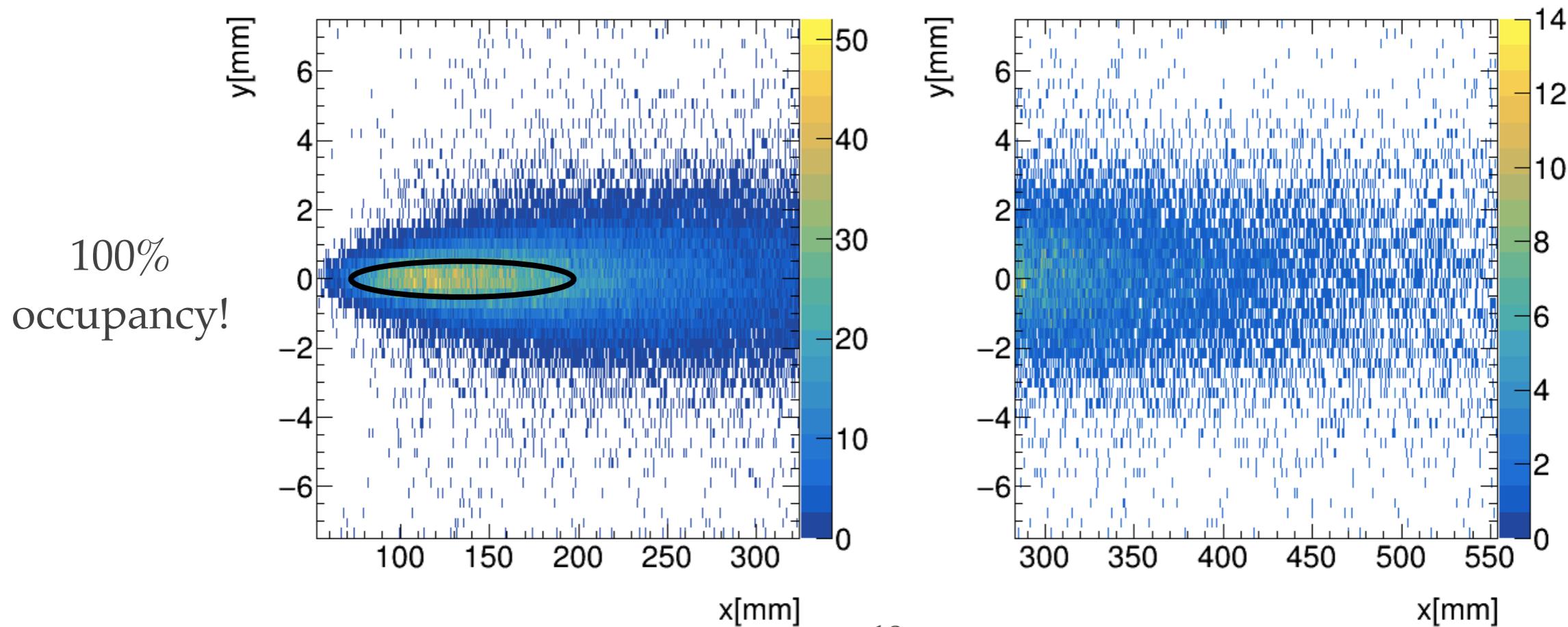
# Occupancy

- ❖ ptarmigan v0.11 (LP,  $\xi_{\text{nom}}=10$ ) average weight=1.3 sample. # positrons (raw)=108759.
- ❖ Assuming  $\geq 2$  pixel hits per particle and fixed weight -> peak occupancy 100%, 90% quantile on the inner stave ~23% occupancy (less dramatic increase because large parts of the detector are unused, 70% of inner stave).



# Occupancy

- ❖ ptarmigan v0.11 (LP,  $\xi_{\text{nom}}=10$ ) average weight=1.3 sample. # positrons (raw)=108759.
- ❖ Assuming  $\geq 2$  pixel hits per particle and fixed weight -> peak occupancy 100%, 90% quantile on the inner stave ~23% occupancy (less dramatic increase because large parts of the detector are unused, 70% of inner stave).



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# Summary

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- ❖ Polarisation has a strong effect on the particle yields as well as their properties.
- ❖ The dispersion carries information about  $\xi$ .
- ❖ With linear polarisation (along x), tracking is impossible for part of the detector at highest  $\xi$  already in phase-0.
- ❖ What if the polarisation is along y direction?