

TB 2022

Automatic Alignment Method

29 / 11 / 23

Kirill Smagloy

- Michal's method – Hough Transform
- The method in this presentation(Itamar's method) – Scan and search max hits in pad

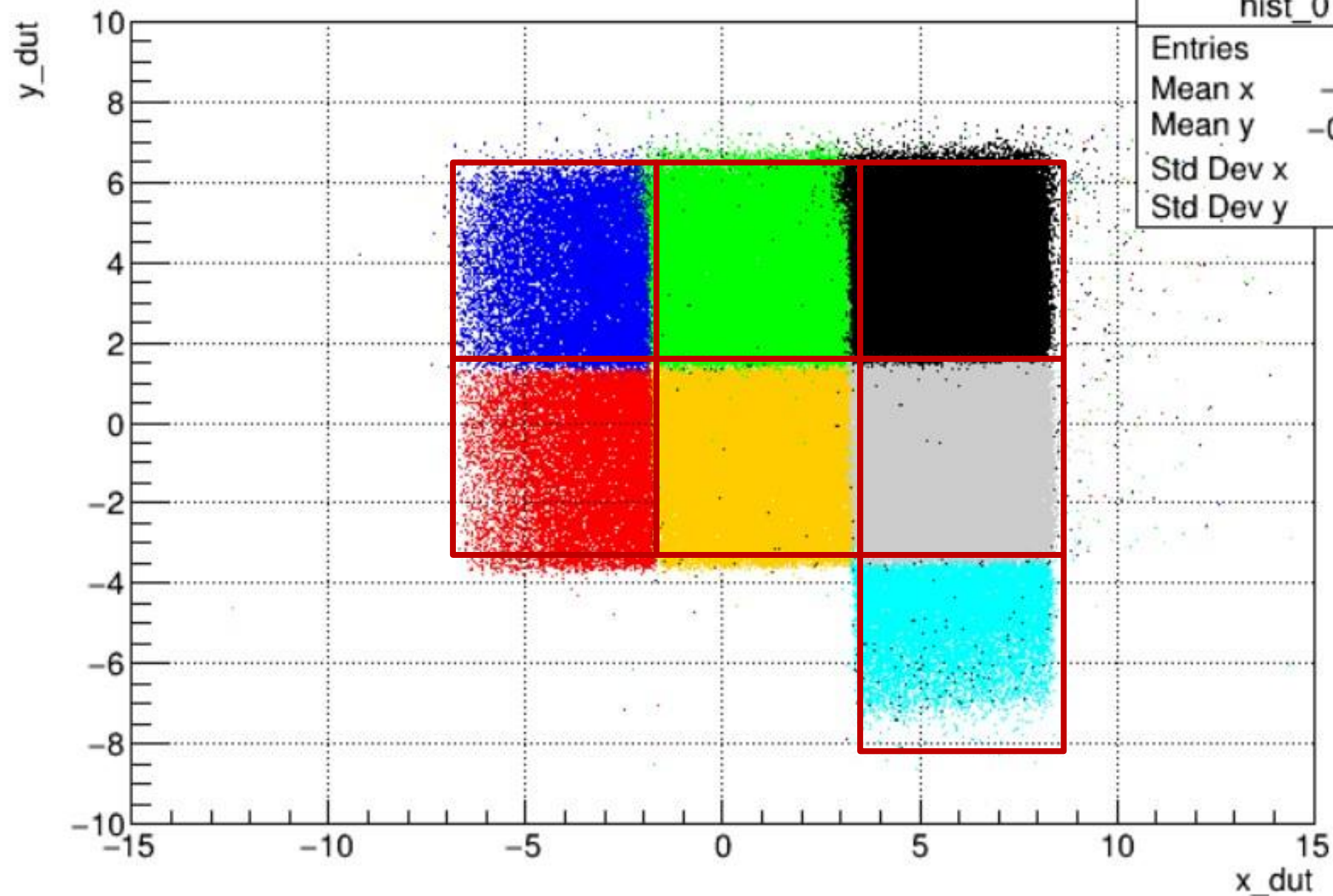
Alignment Program

- Currently the program works with the runs on the sensors –
ANTON 1, YAN 1, Calice 75, Calice 74
- The program recognizes the pad length, and the noisy/dead pads of each sensor
- For the GaAs sensors, inverts the x_{dut} coordinate before aligning

The Method

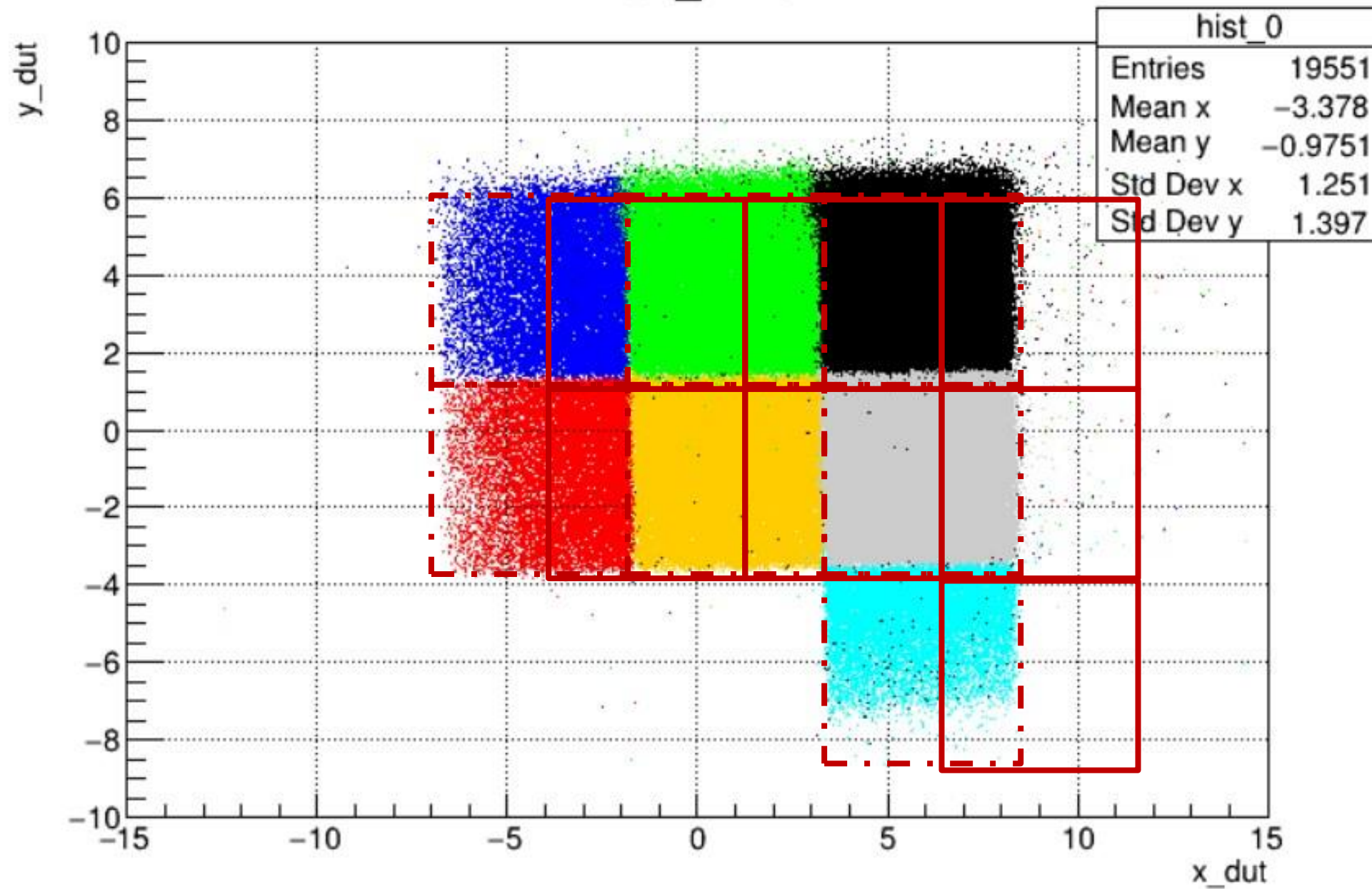
Run_4475

| hist_0 | |
|-----------|---------|
| Entries | 19551 |
| Mean x | -3.378 |
| Mean y | -0.9751 |
| Std Dev x | 1.251 |
| Std Dev y | 1.397 |

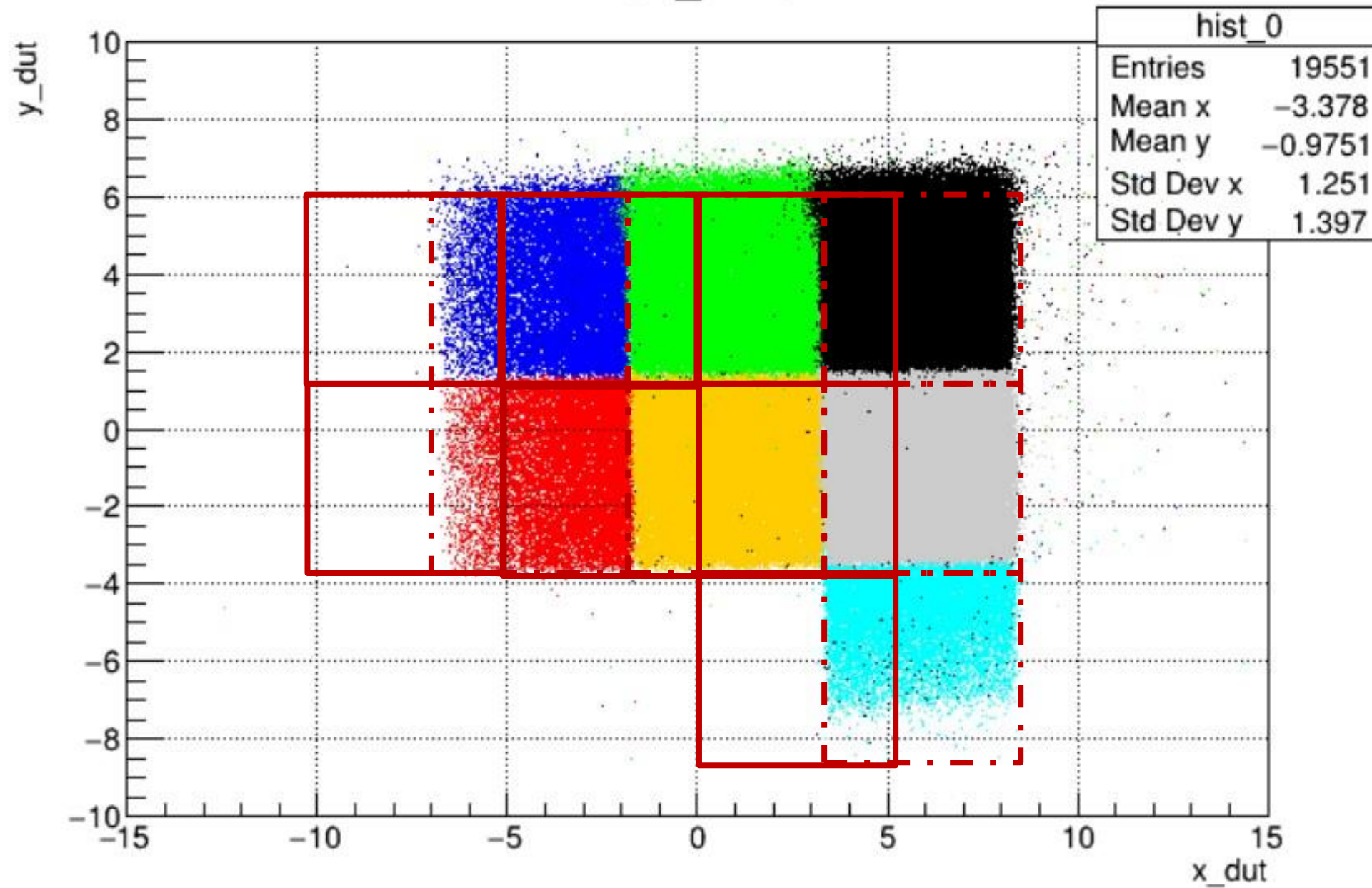


***Each color represents a different pad**

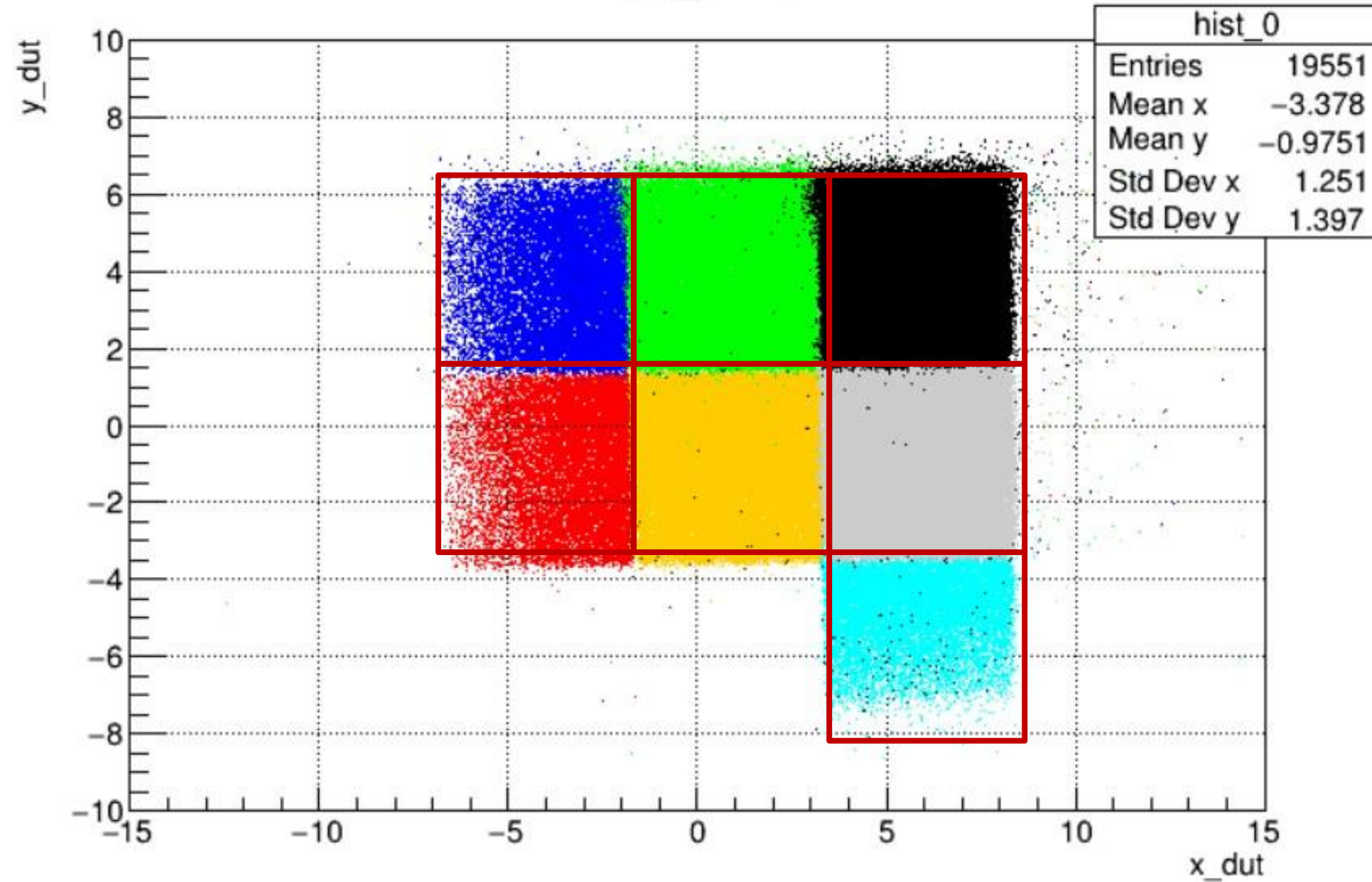
Run_4475



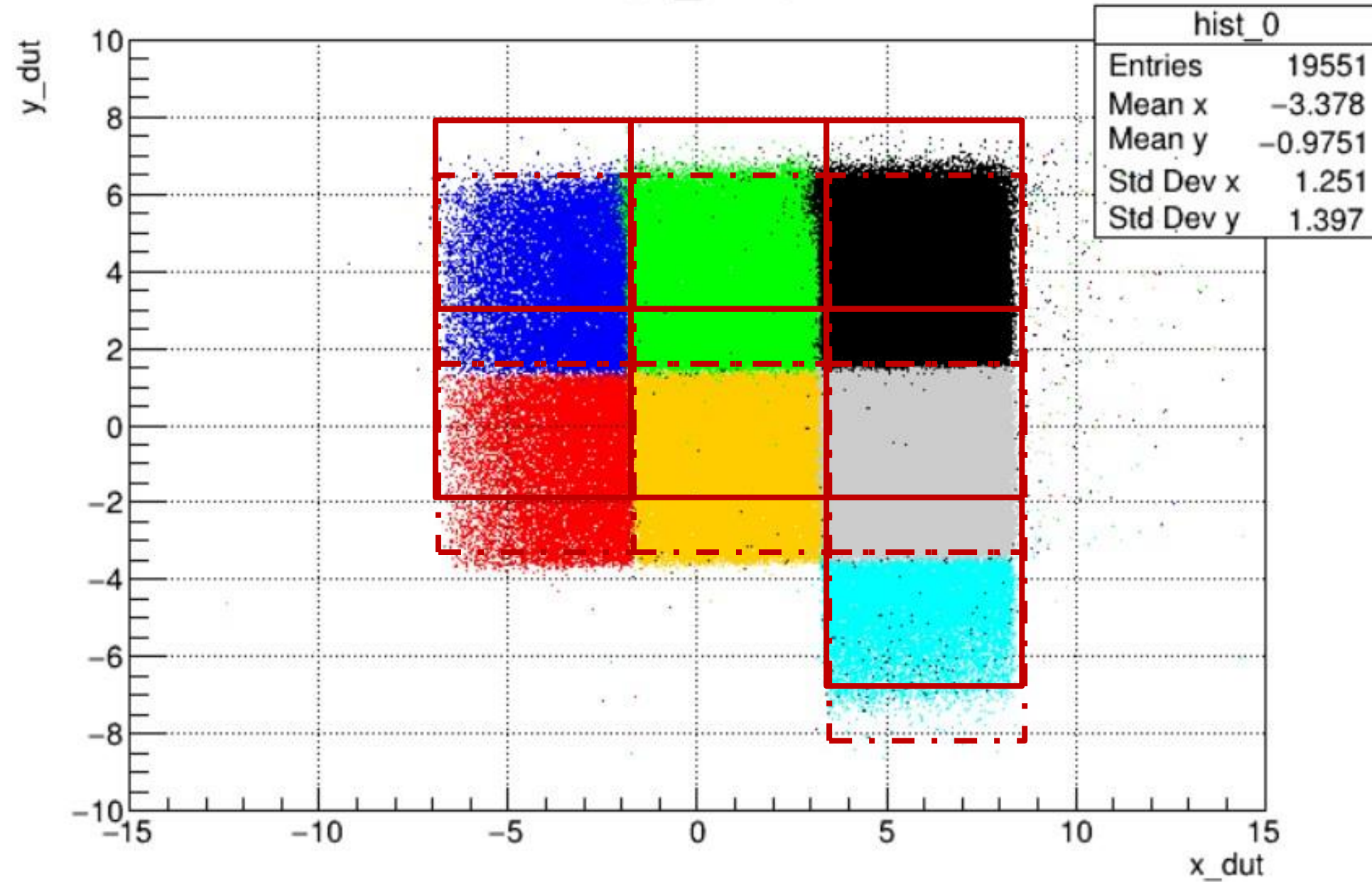
Run_4475



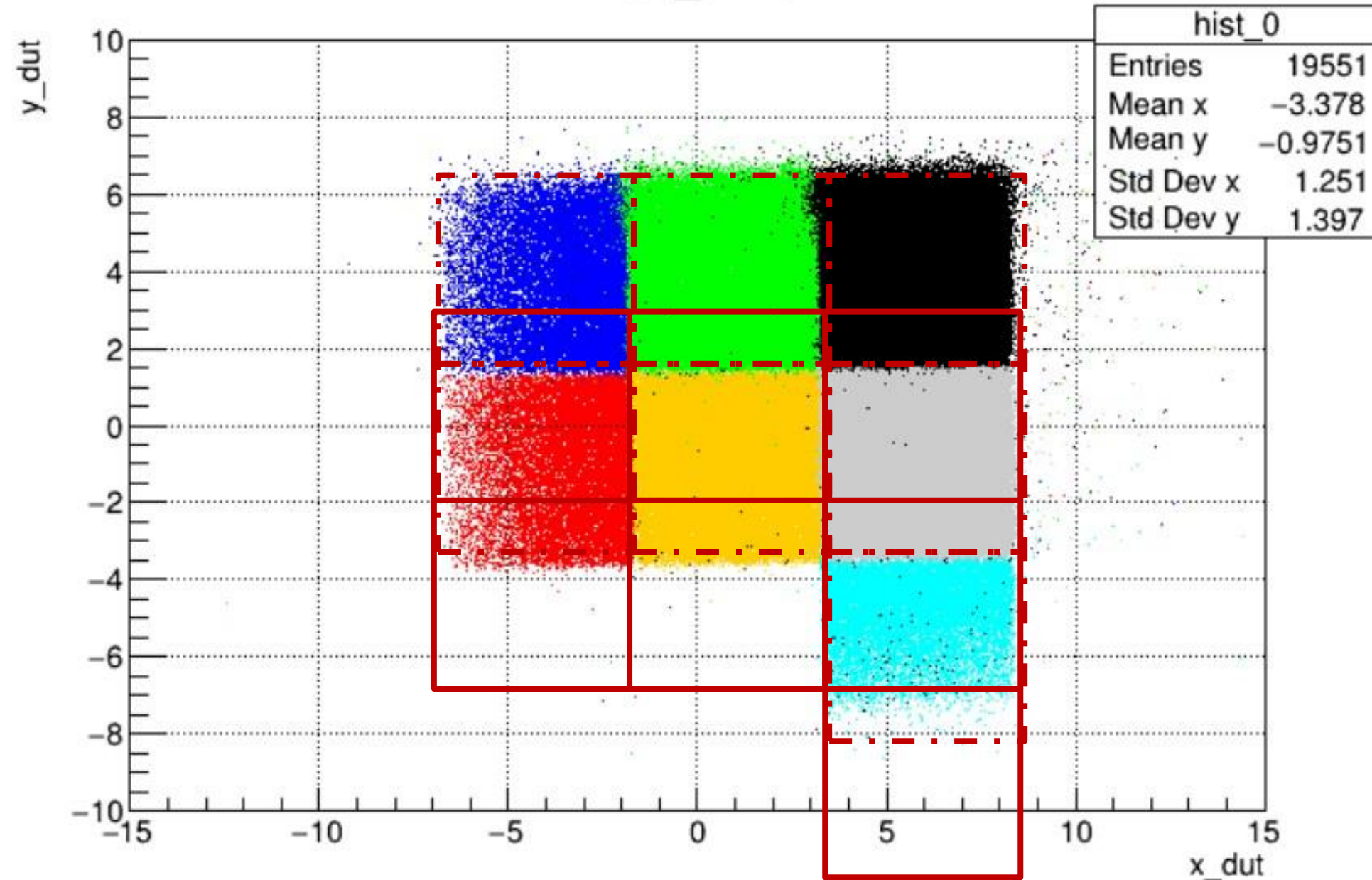
Run_4475



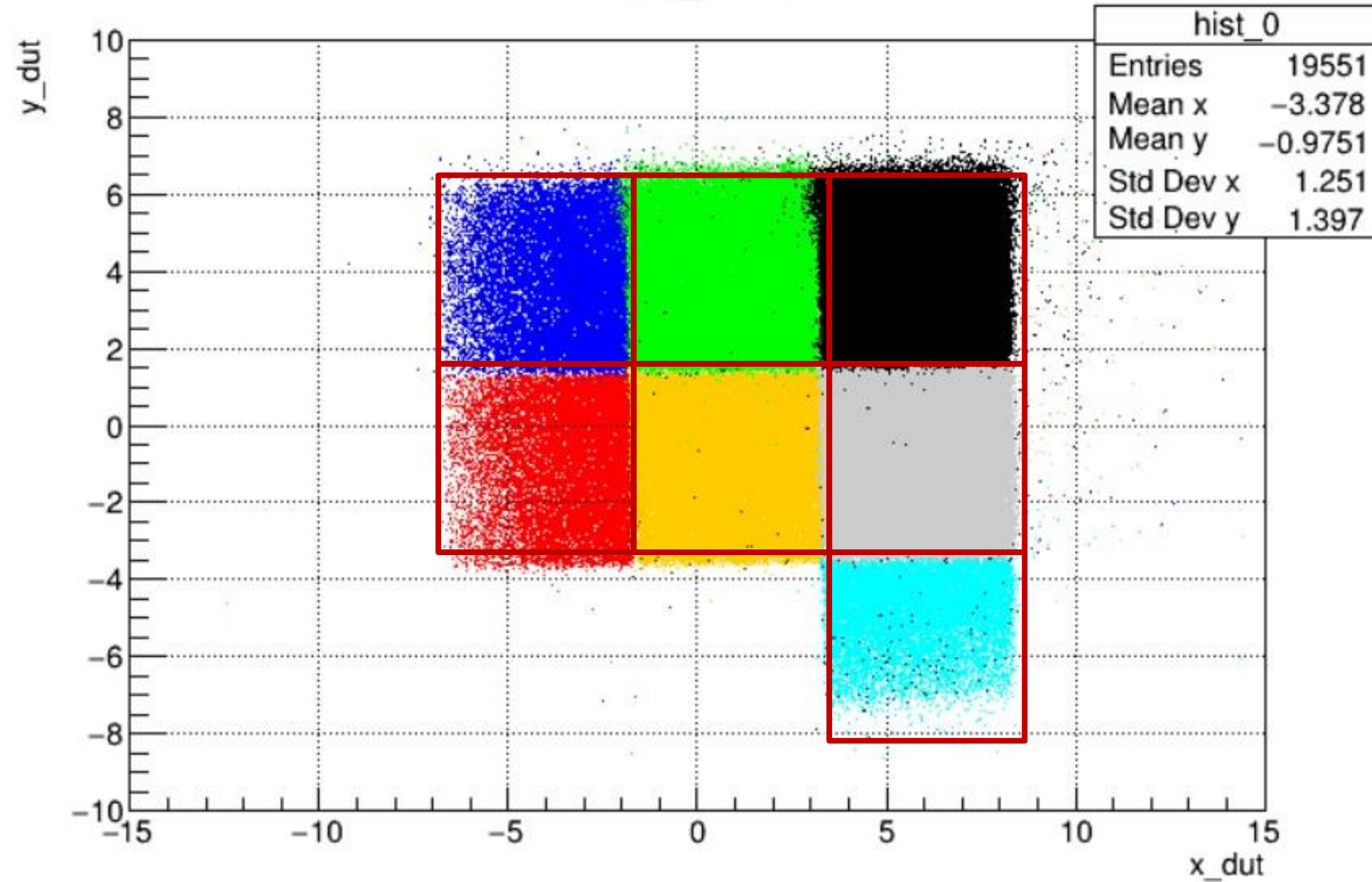
Run_4475



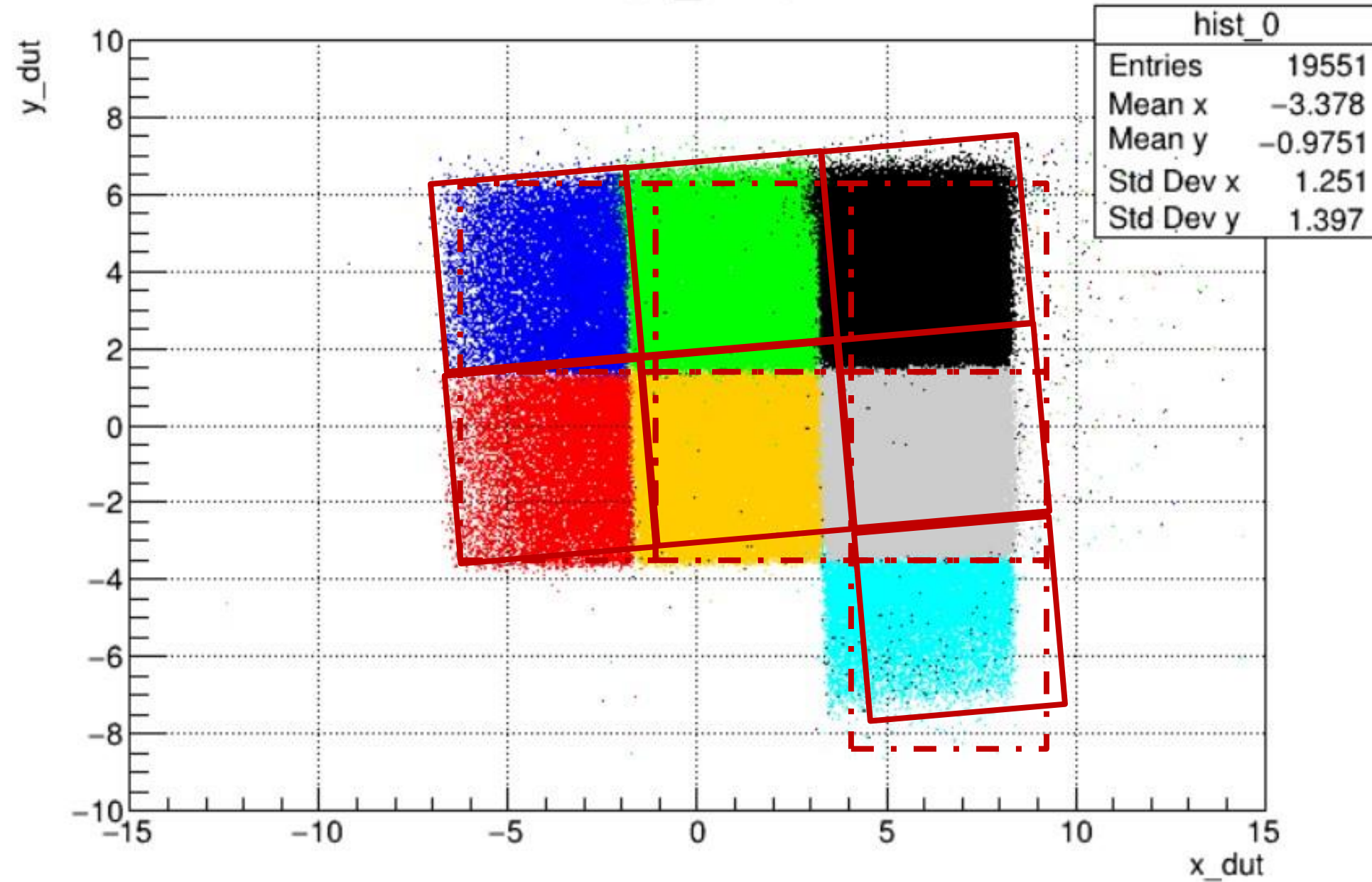
Run_4475



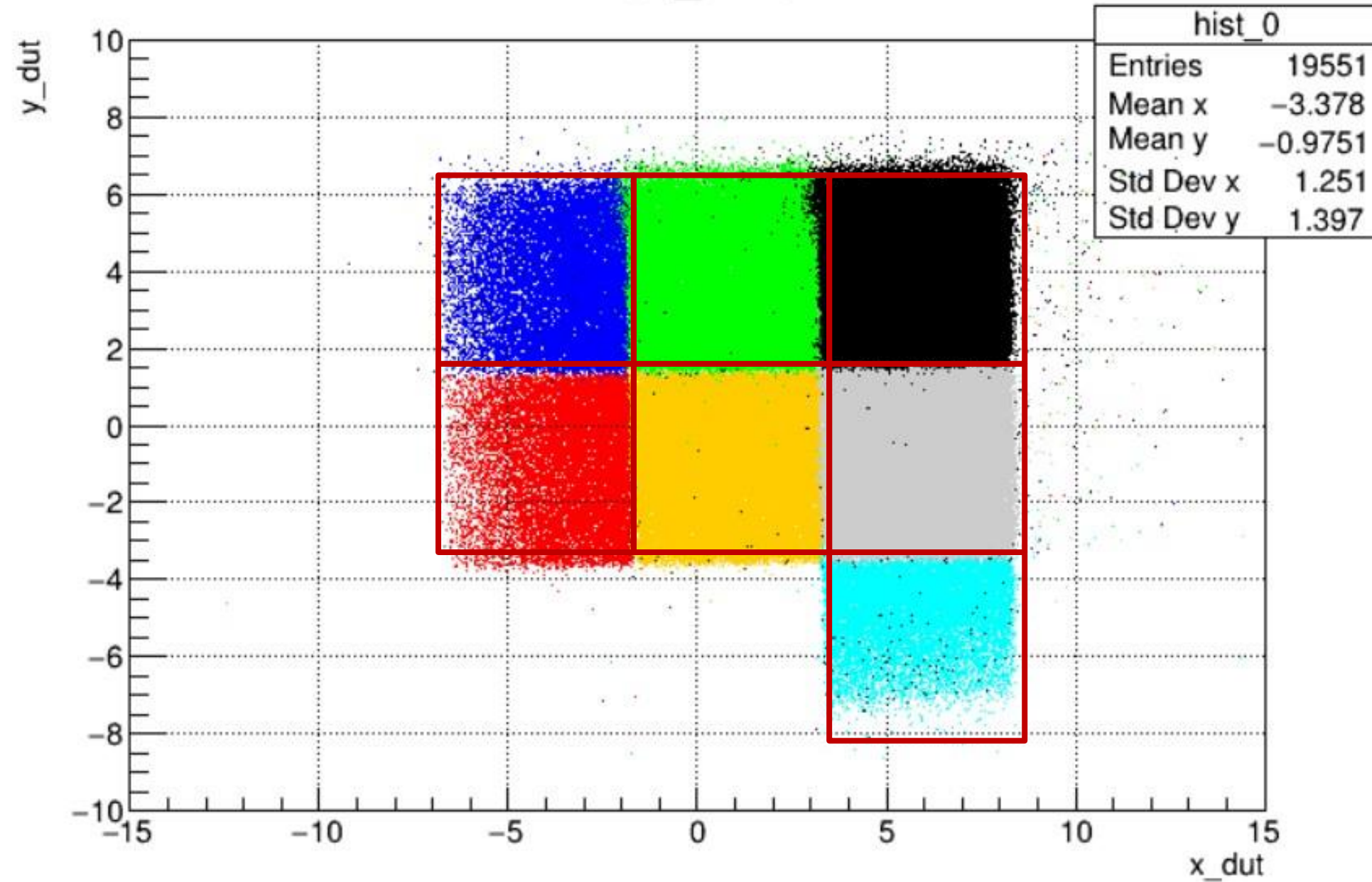
Run_4475



Run_4475



Run_4475



The Alignment Process

The alignment process consists of four major steps:

- First Step – Finding the “leading” pads(Above 4.5% of the total entries)
- Second Step – Shift-aligning one corner pad, to avoid rotation effects
- Third Step – Rotating all the pads together
- Fourth Step – Final shift-alignment of the rotated pads

Run 4475 – ANTON 1 sensor

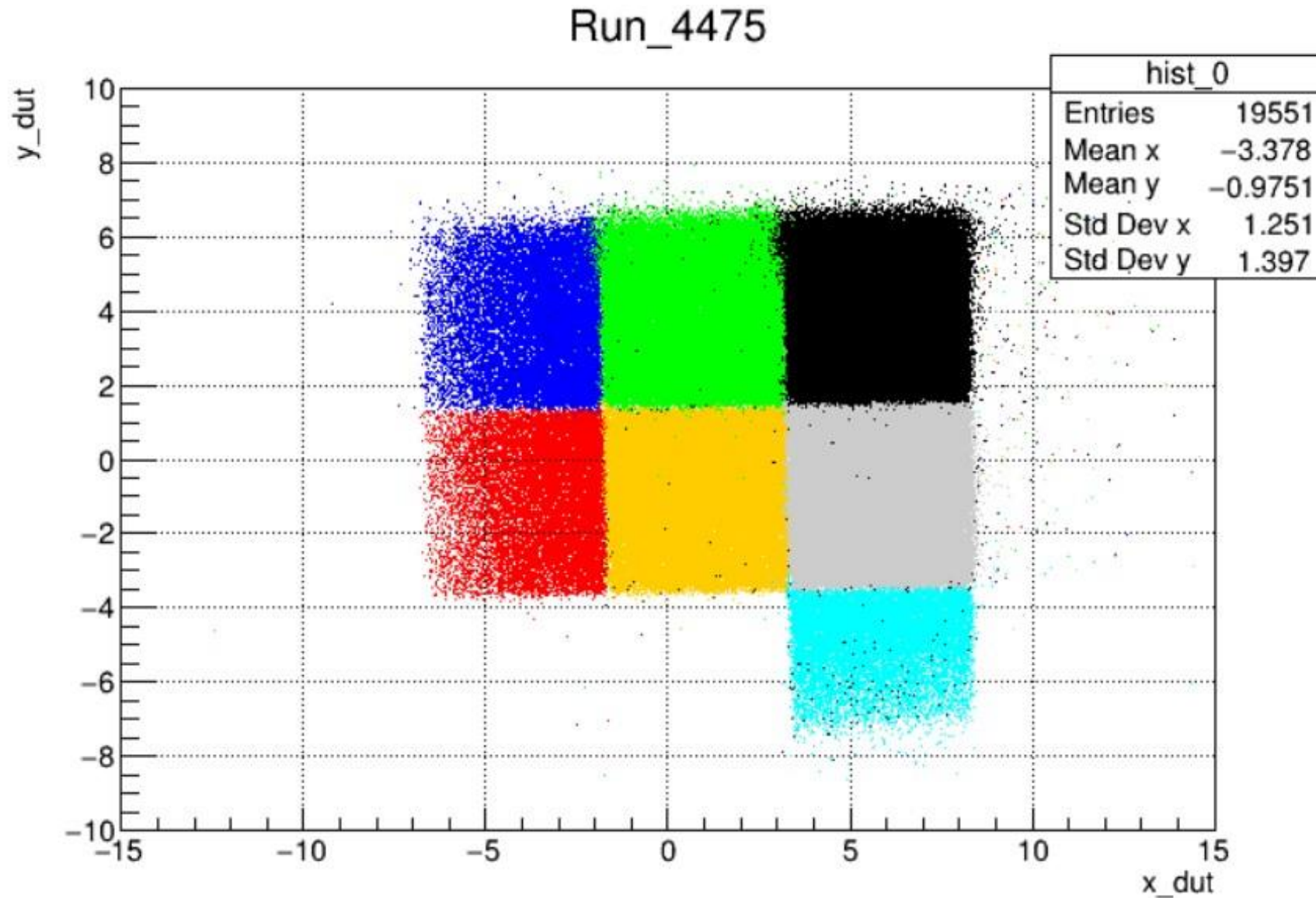
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Run 4475 – Step 1

*Each color represents a different pad

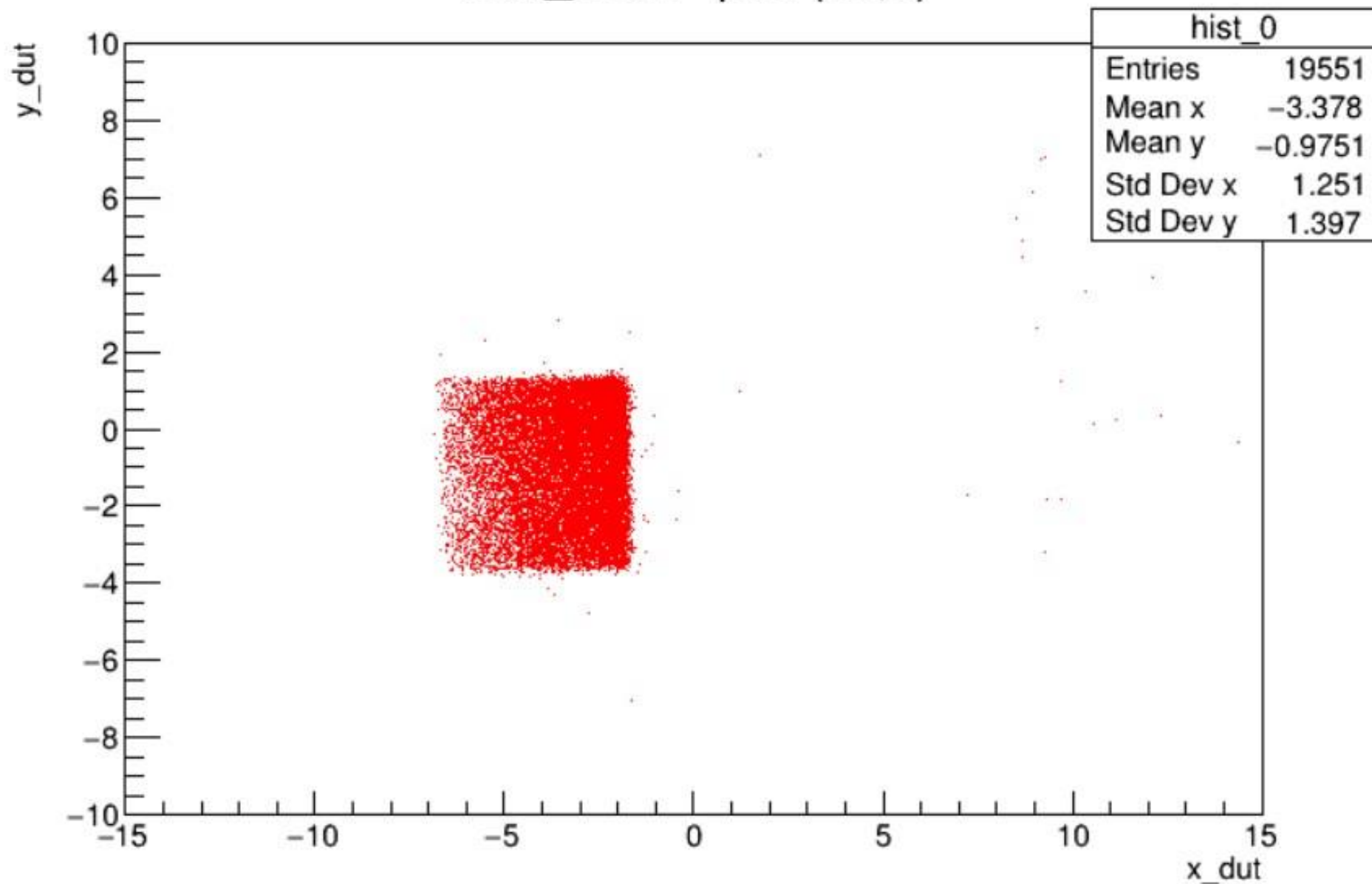


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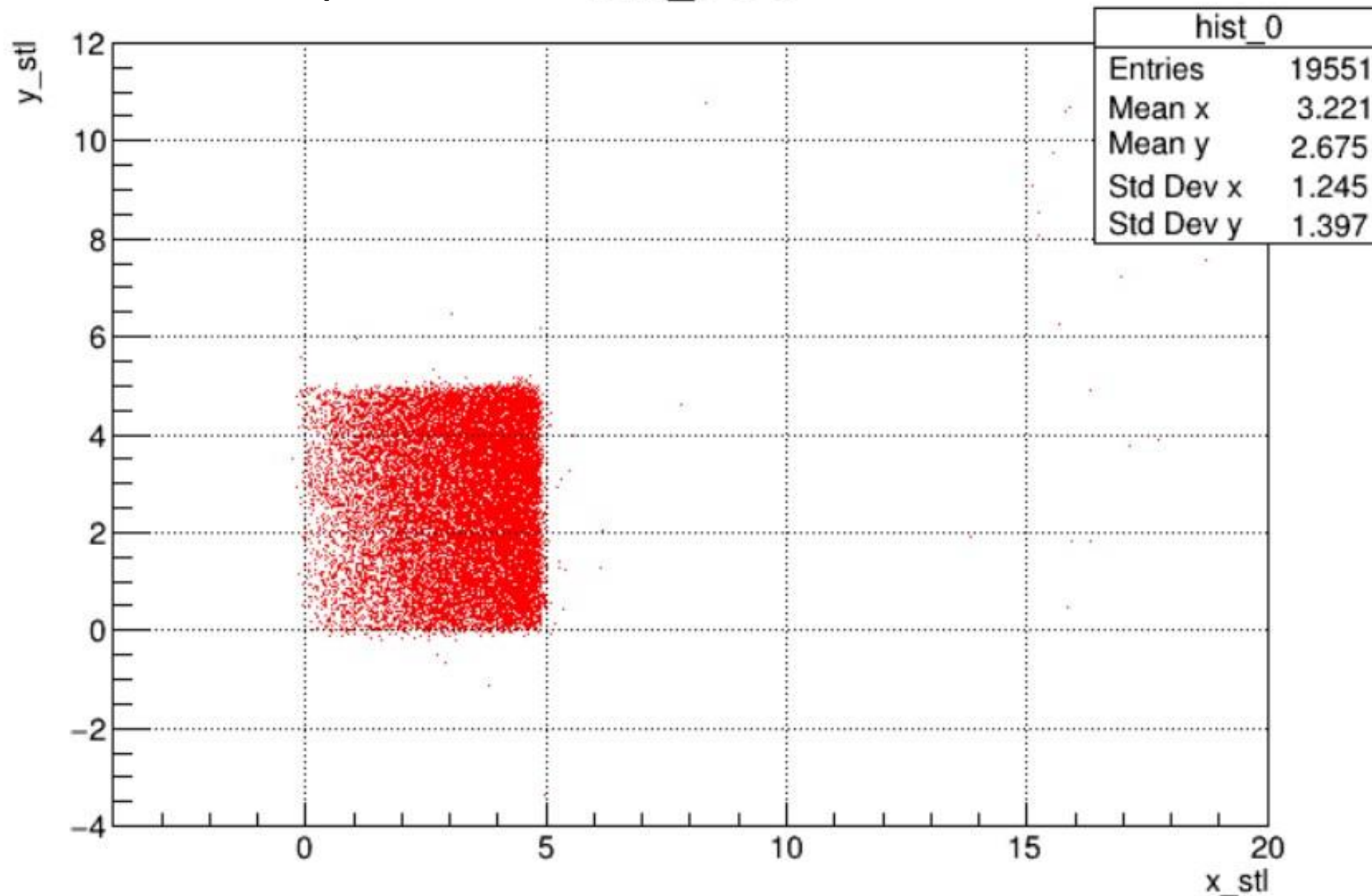
Run 4475 – Step 2

Run_4475 - pad (12,3)



Run 4475 – Step 2

Run_4475

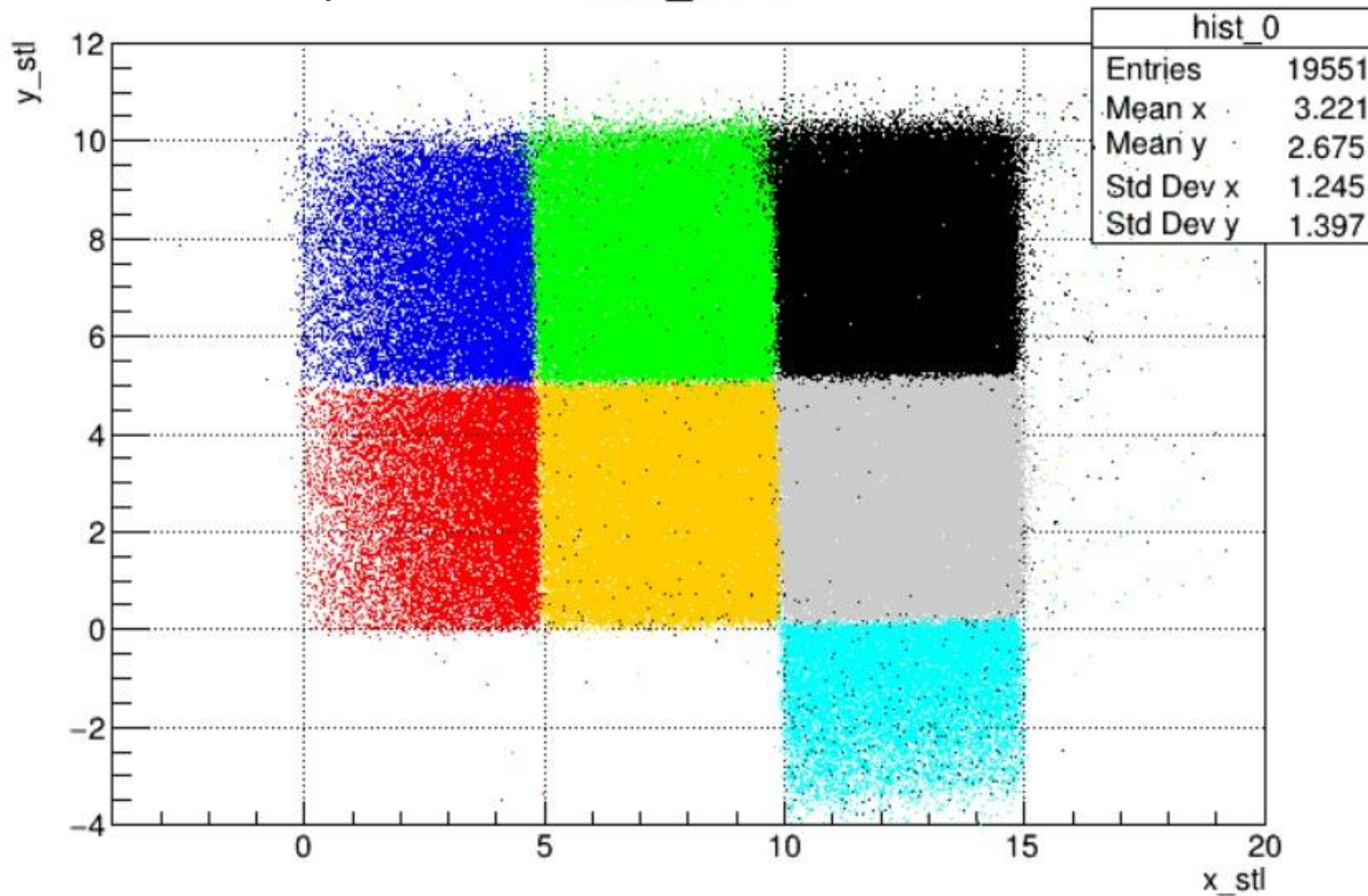


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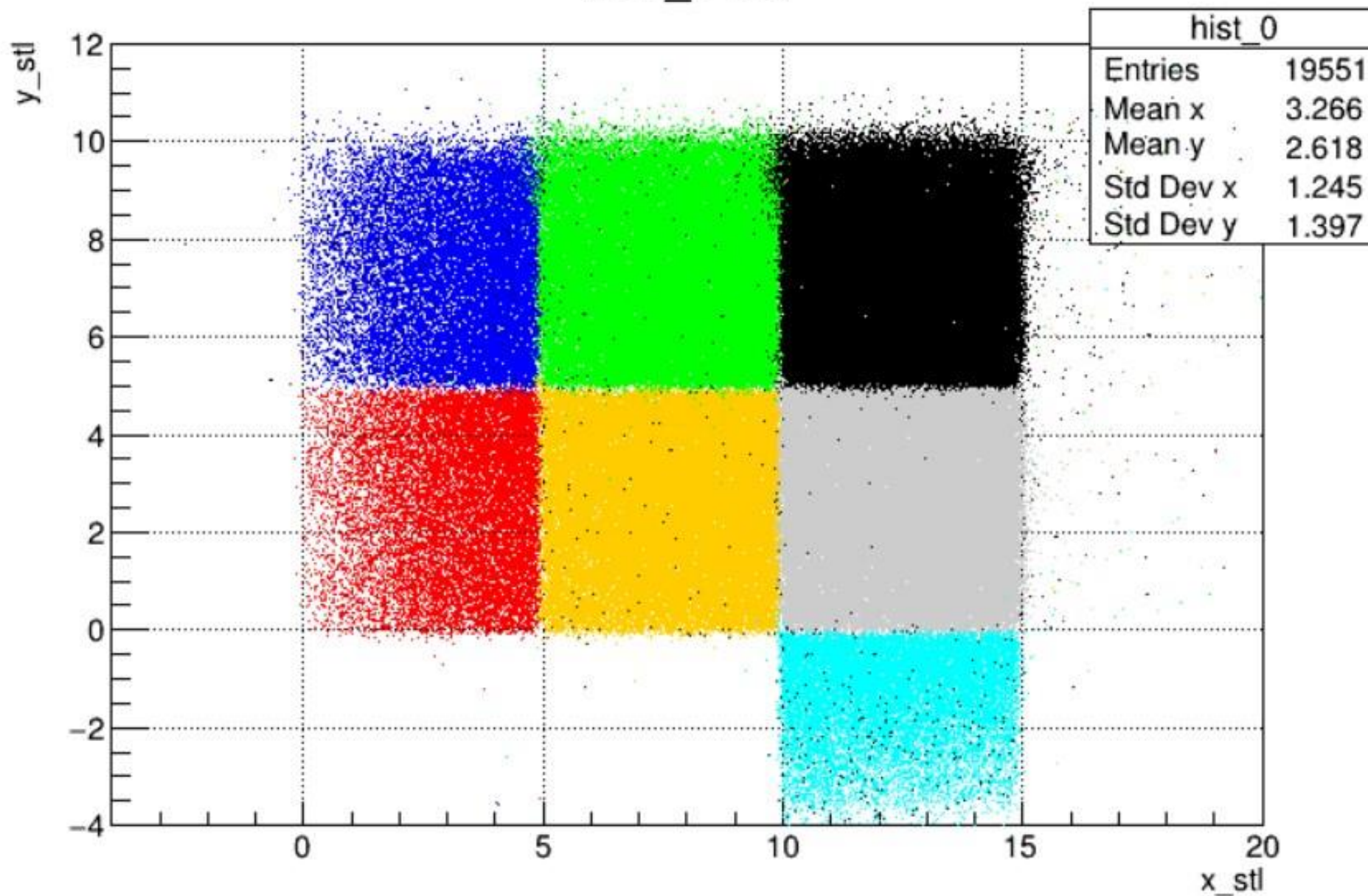
Run 4475 – Step 3

Run_4475



Run 4475 – Step 3

Run_4475

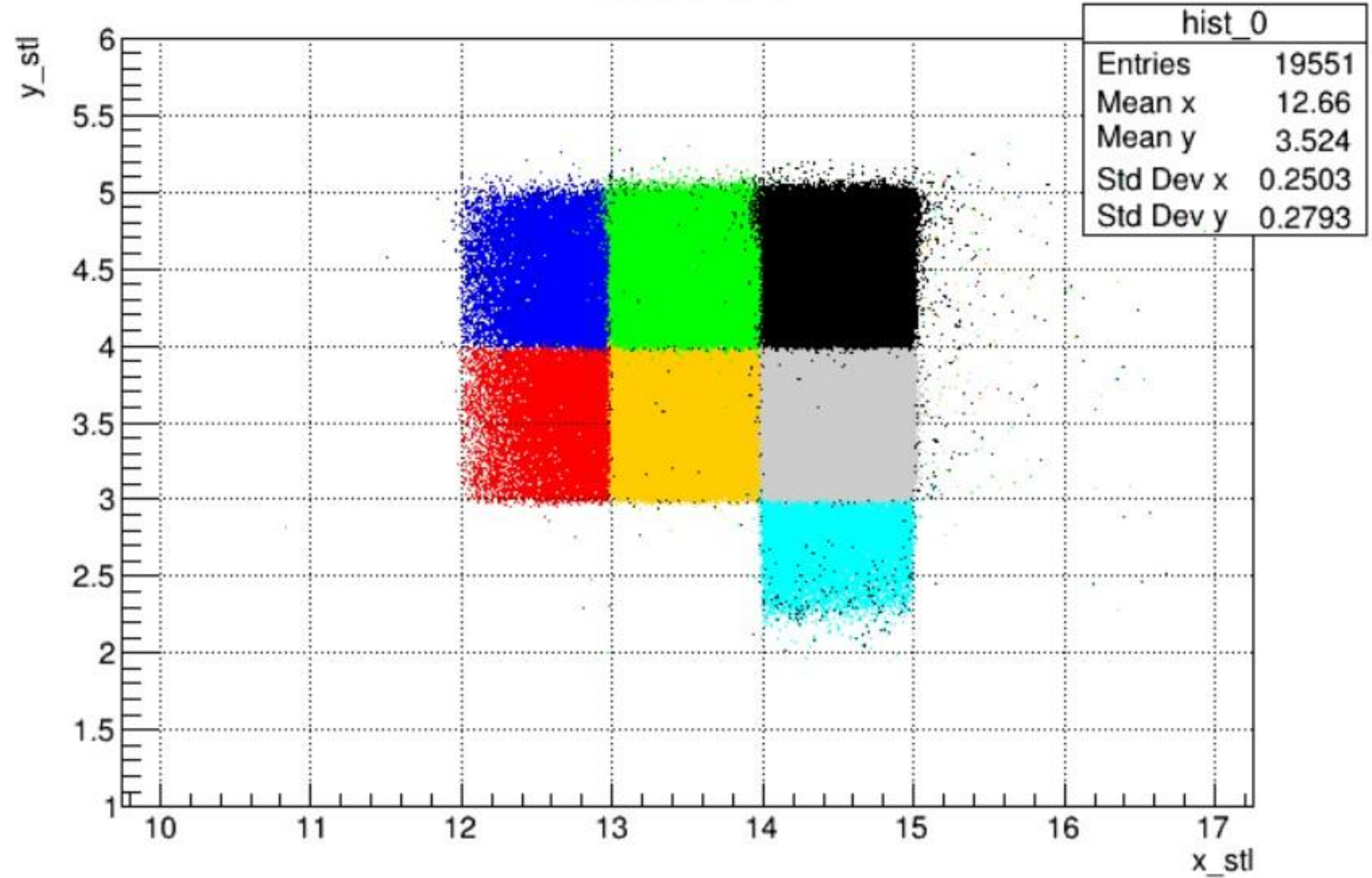


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Run 4475 – Step 4

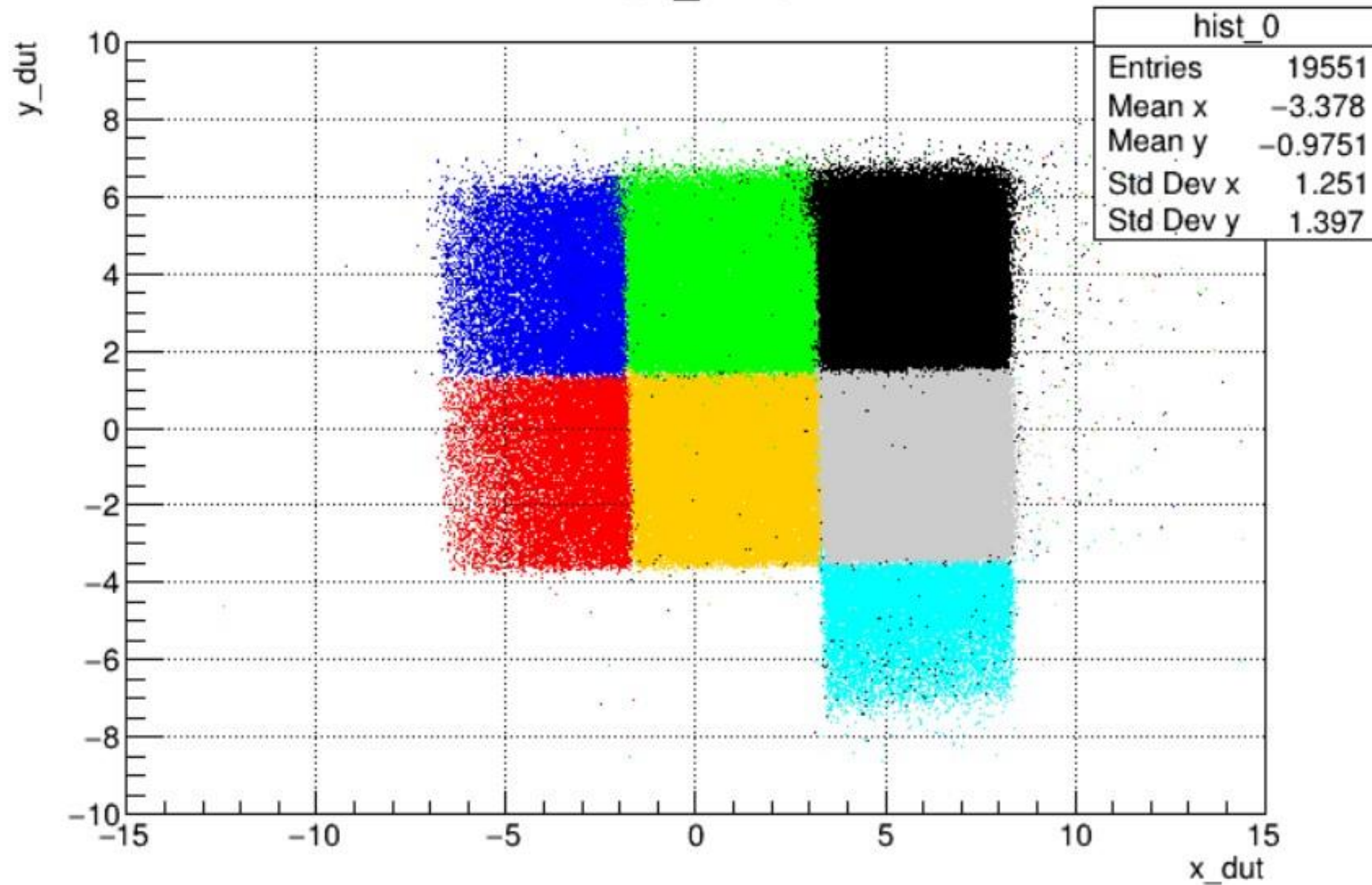
Run_4475



To Summarize

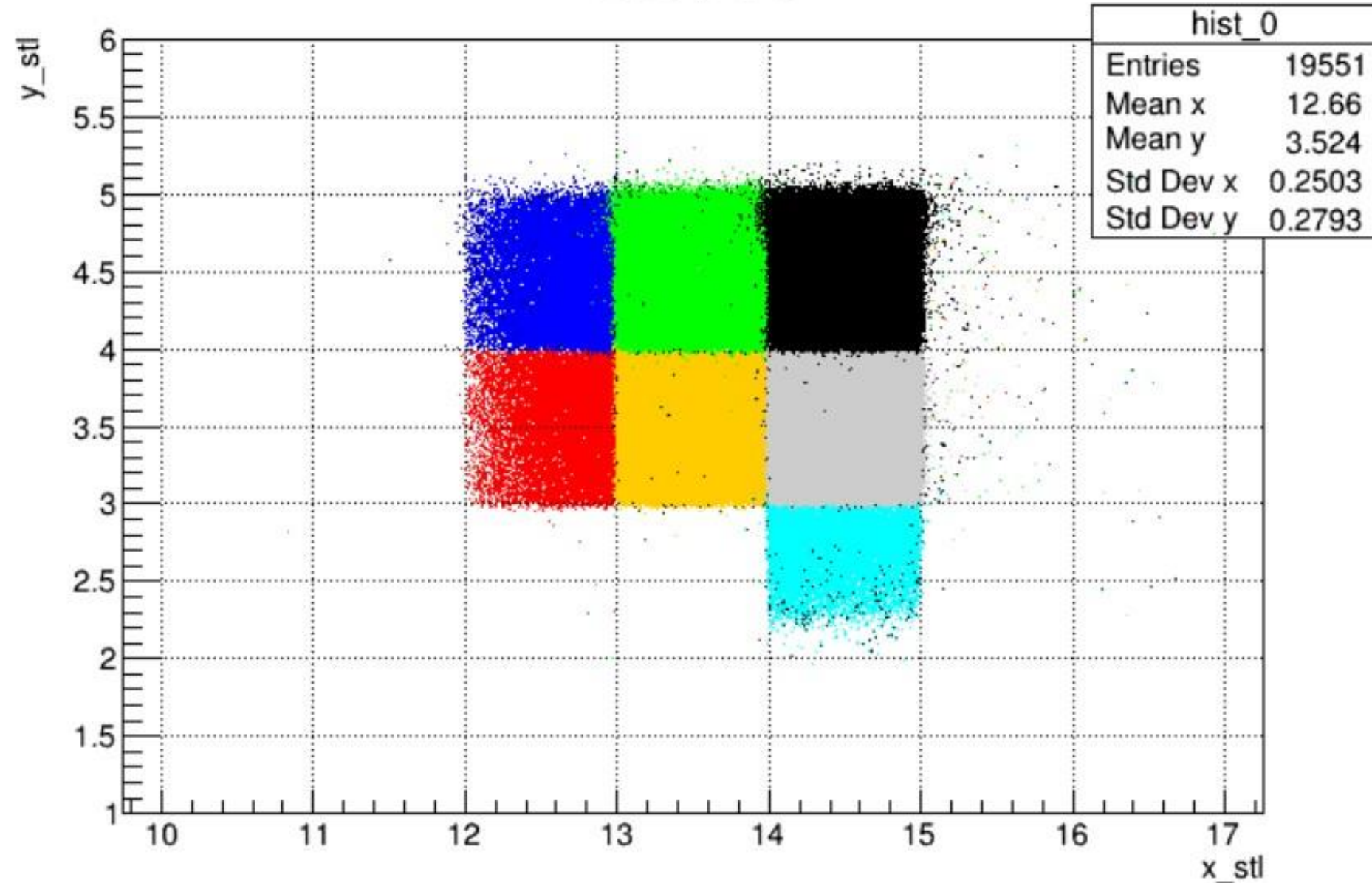
Run 4475 – Initial

Run_4475



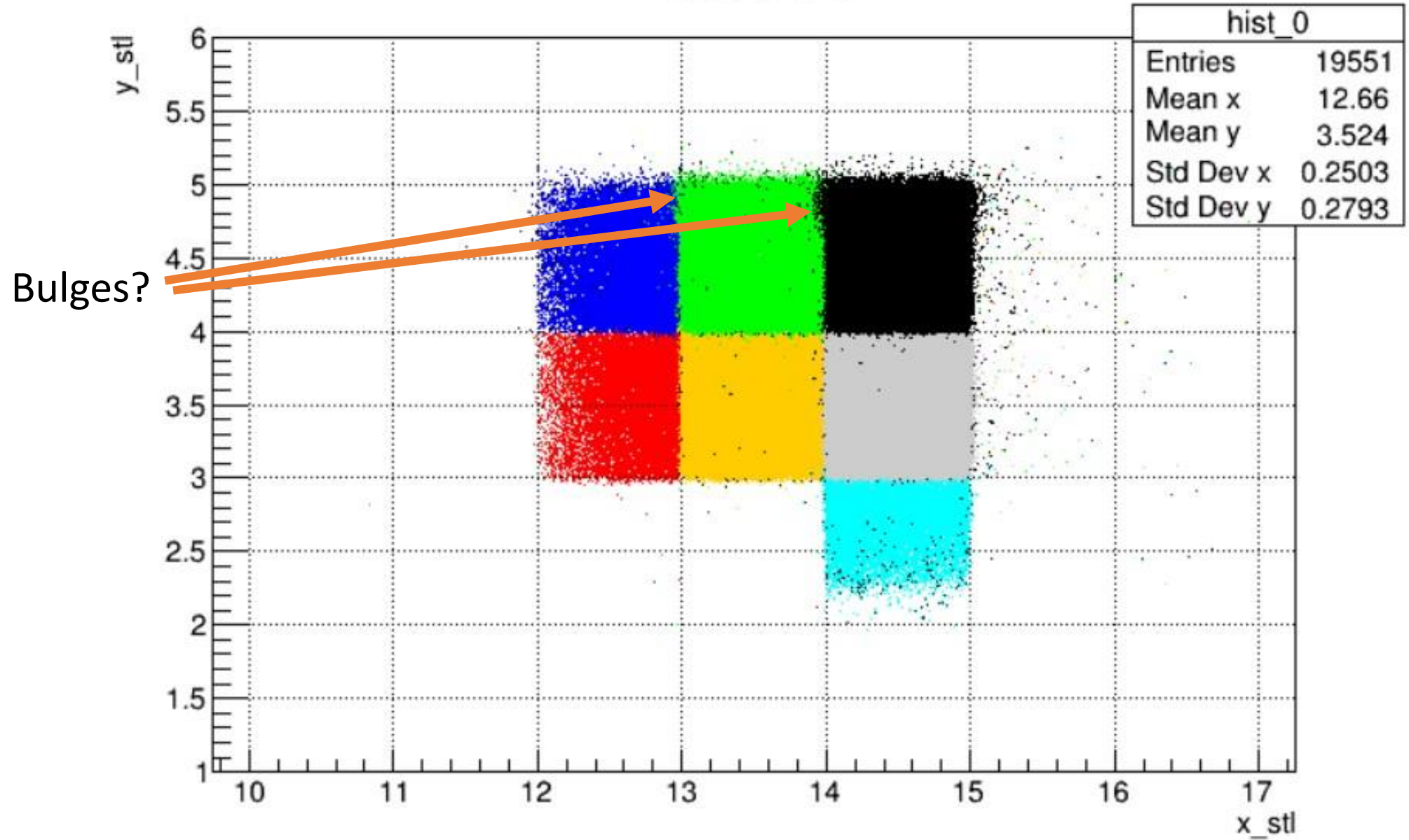
Run 4475 – Aligned

Run_4475



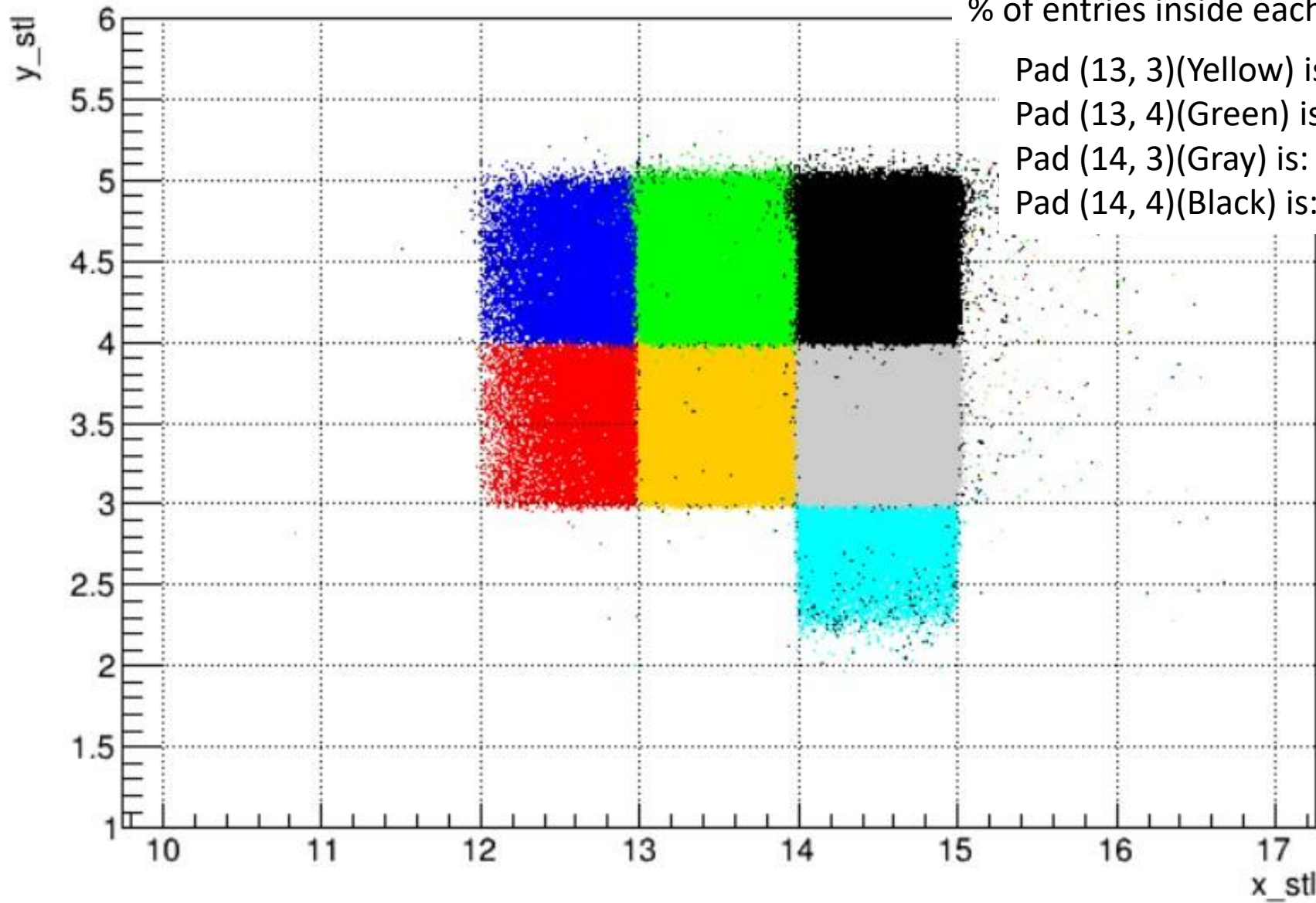
Run 4475 – Aligned

Run_4475



Run 4475 – Aligned

Run_4475



% of entries inside each of the four main pads:

Pad (13, 3)(Yellow) is: 99.02% out of 57483

Pad (13, 4)(Green) is: 97.61% out of 65299

Pad (14, 3)(Gray) is: 98.71% out of 80836

Pad (14, 4)(Black) is: 97.79% out of 87499

Comparing Results – Run 4475

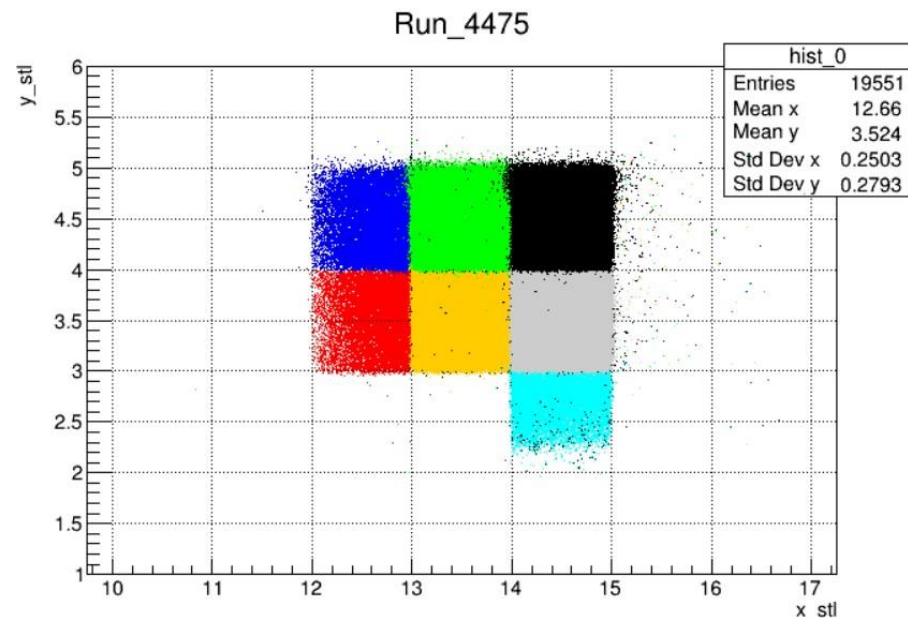
Kirill's, Michal's alignment:

Pad (13, 3)(Yellow) is: 99.02%, 99.09%

Pad (13, 4)(Green) is: 97.61% , 97.60%

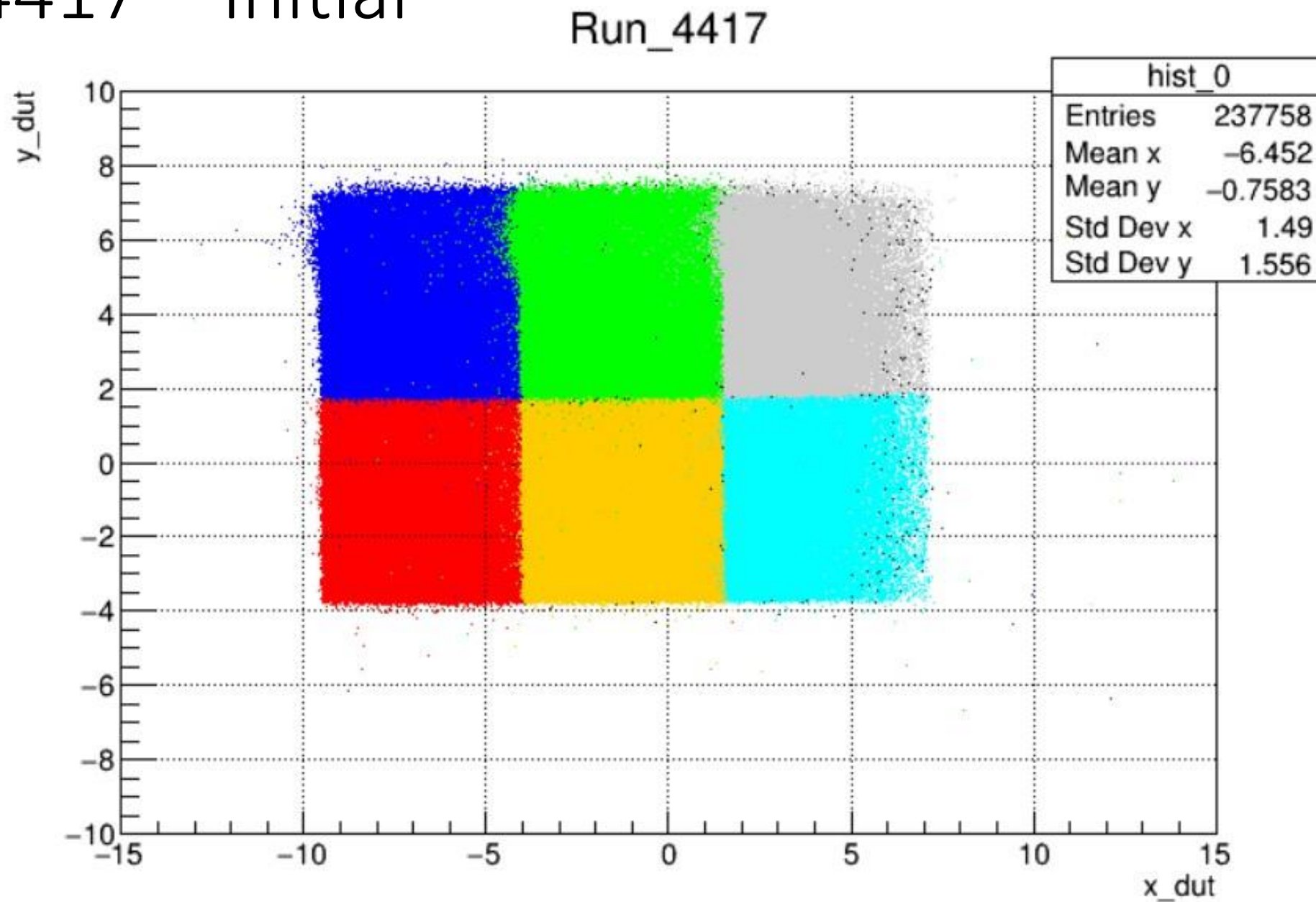
Pad (14, 3)(Gray) is: 98.71% , 98.66%

Pad (14, 4)(Black) is: 97.79%, 97.74%



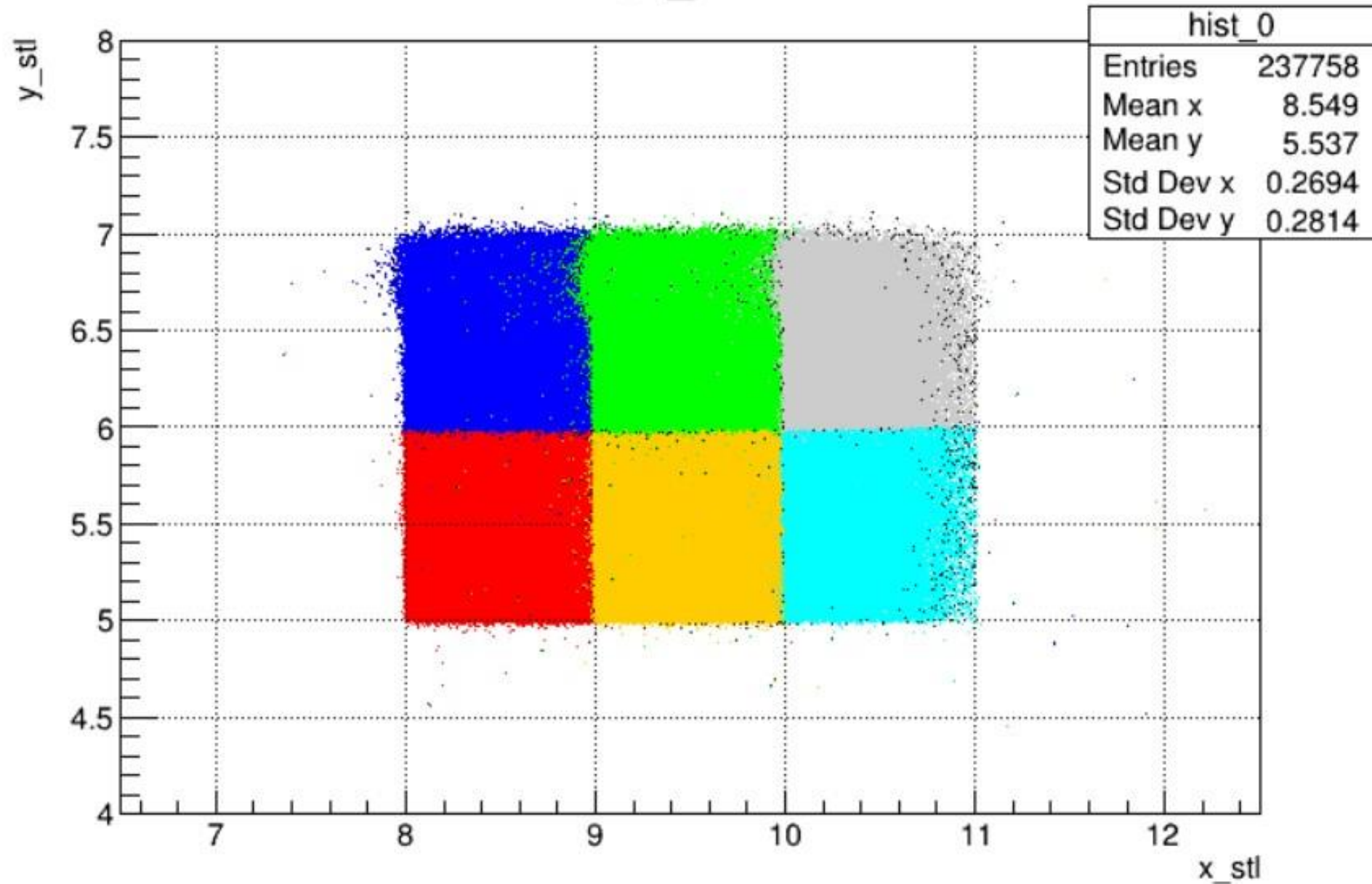
Run 4417 – Calice 75 sensor

Run 4417 – Initial



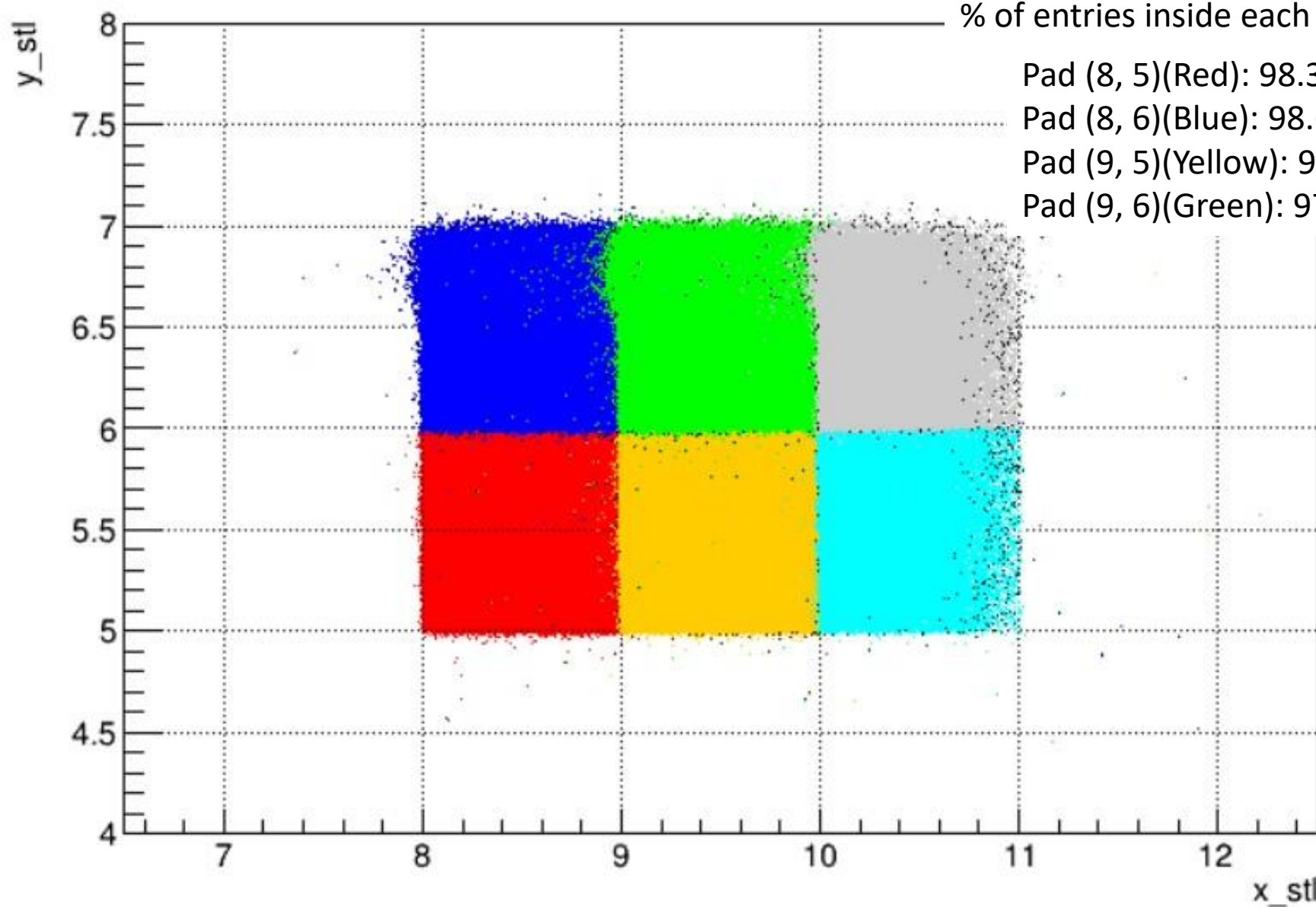
Run 4417 – Aligned

Run_4417



Run 4417 – Aligned

Run_4417



% of entries inside each of the four main pads:

Pad (8, 5)(Red): 98.34% out of 237758

Pad (8, 6)(Blue): 98.6% out of 231559

Pad (9, 5)(Yellow): 98.45% out of 197998

Pad (9, 6)(Green): 97.91% out of 203907

Comparing Results – Run 4417

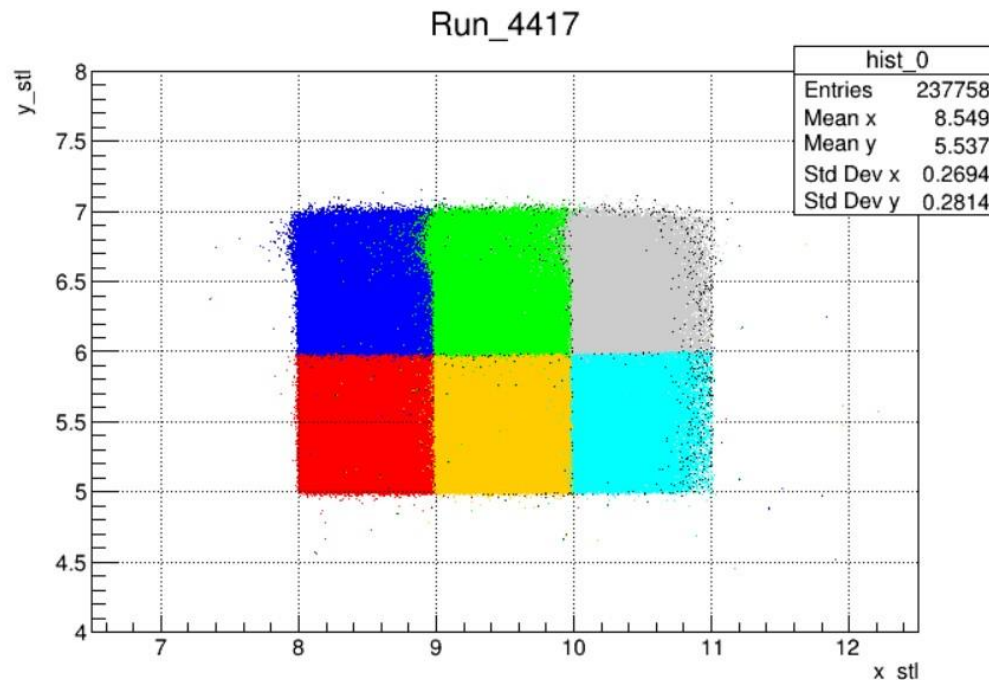
Kirill's, Michal's alignment:

Pad (8, 5)(Red): 98.34%, 98.62%

Pad (8, 6)(Blue): 98.60%, 98.65%

Pad (9, 5)(Yellow): 98.45%, 97.55%

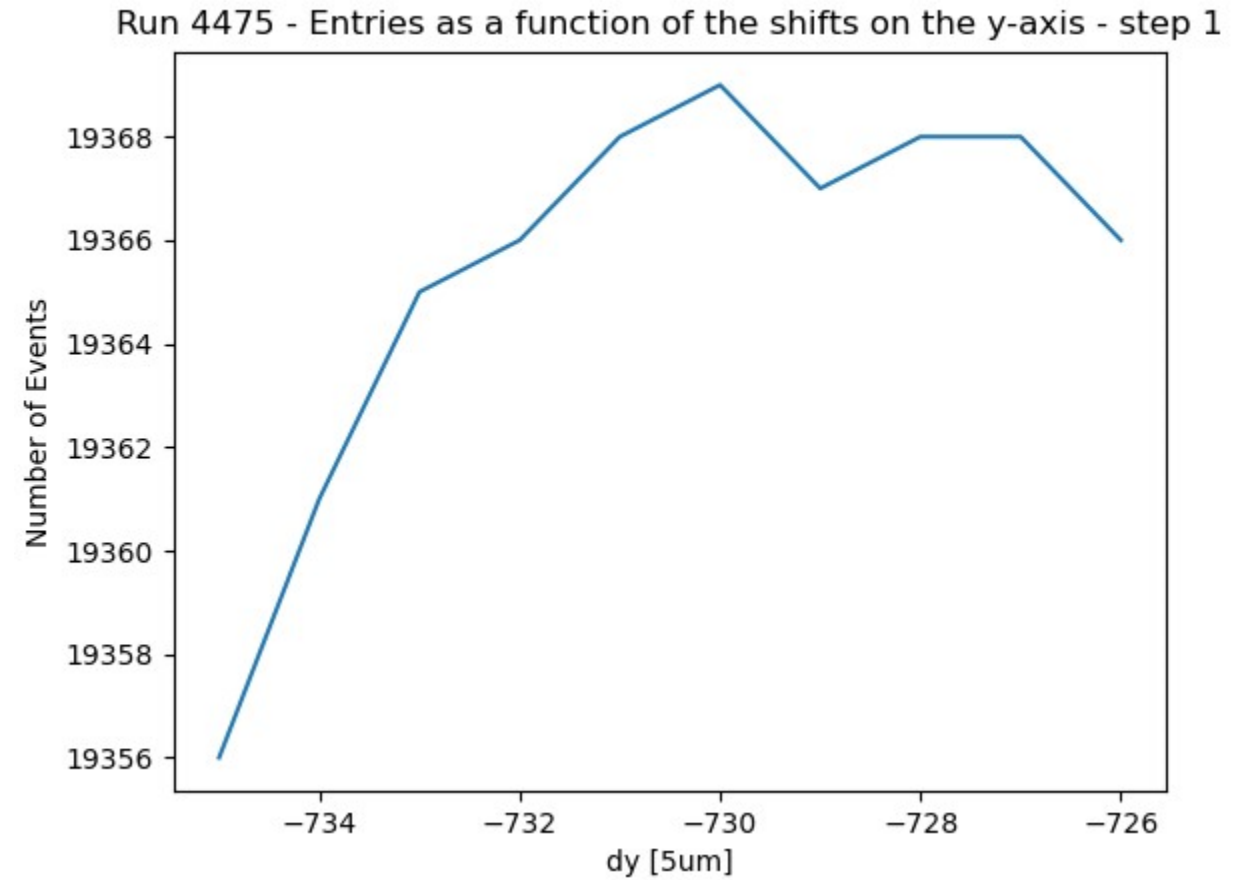
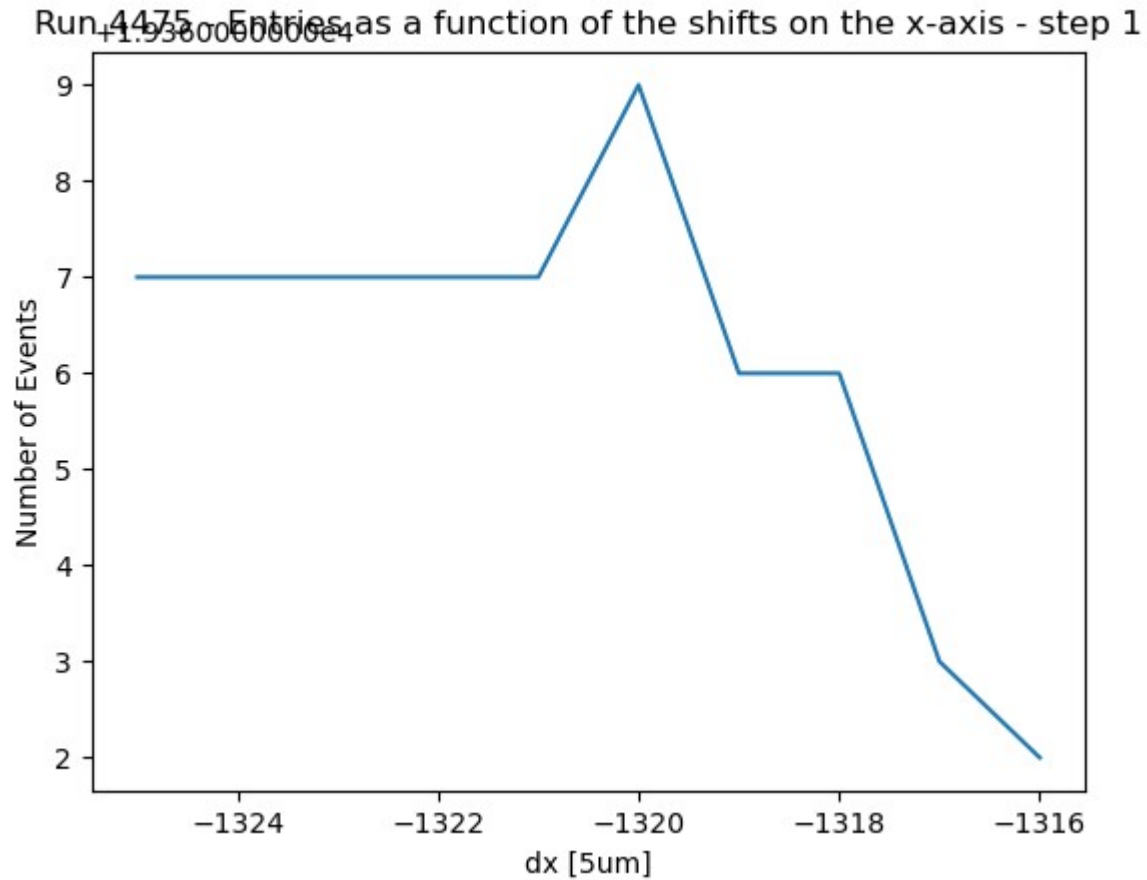
Pad (9, 6)(Green): 97.91%, 98.40%



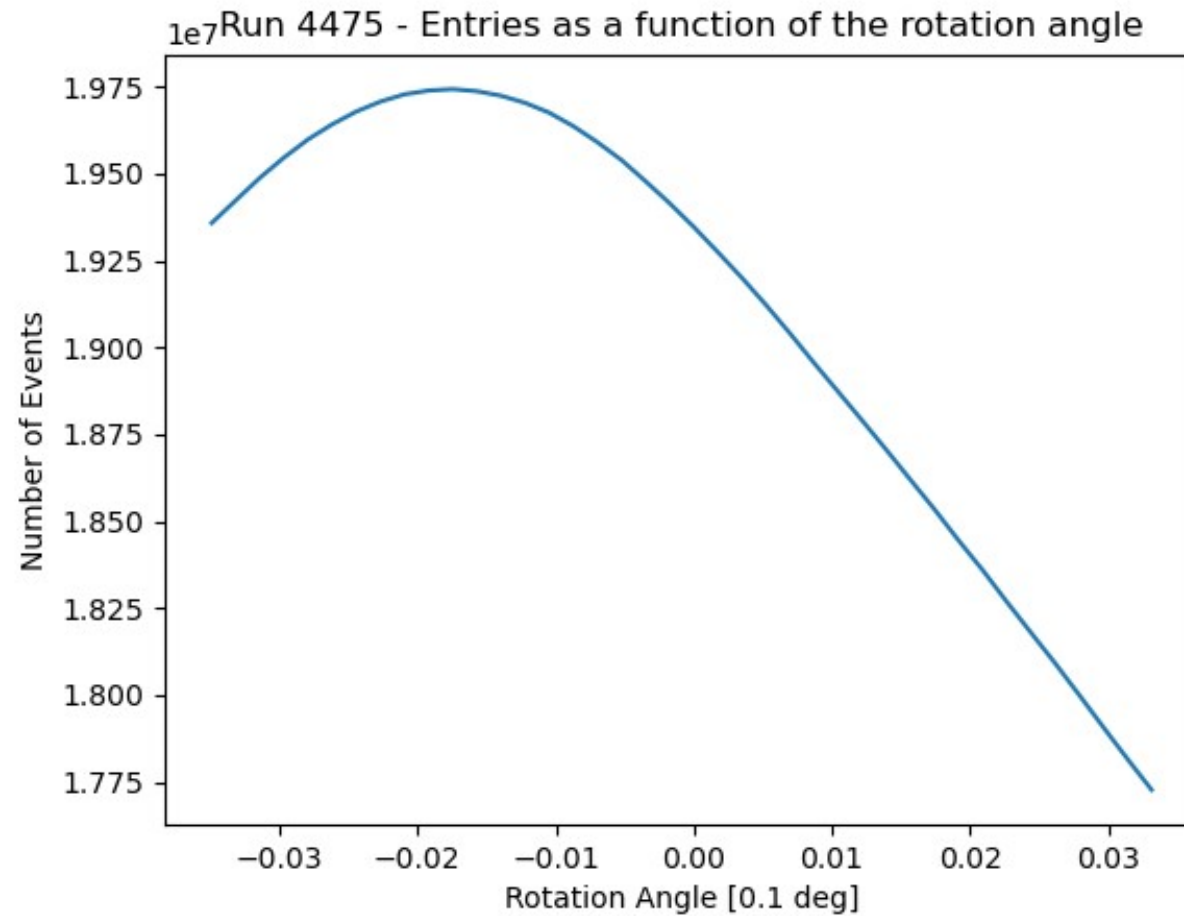
Additional Plots

- The program plots the numbers of entries as a function of each shift for us to make sure that there was a unique maximum

Step 2 – Axis shifts for one pad

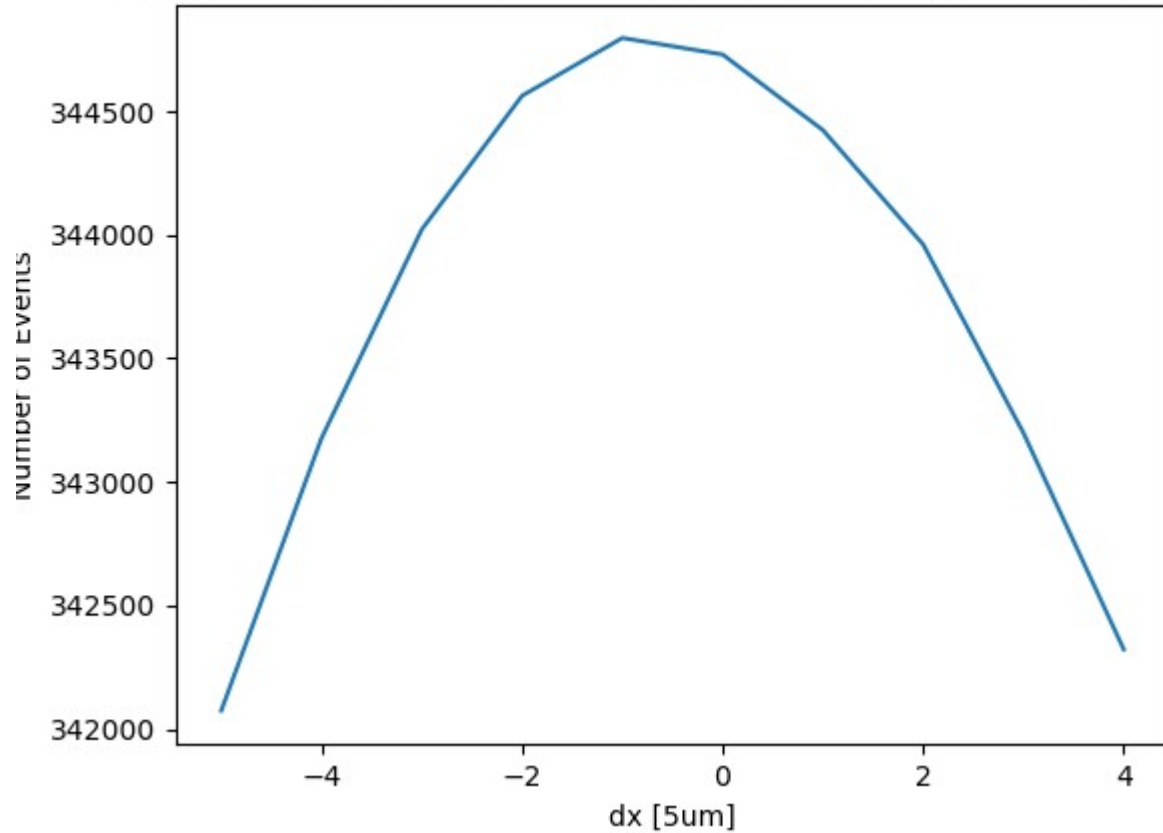


Step 3 – Rotation Shifts

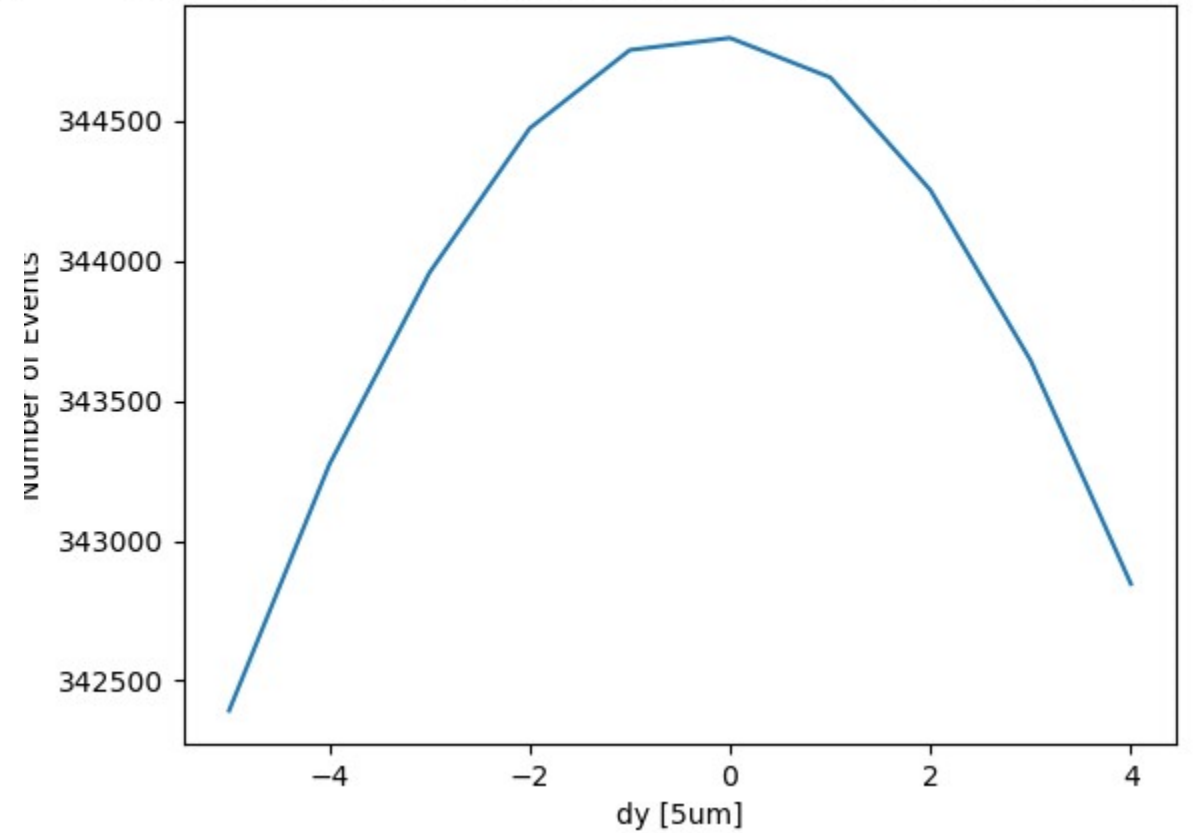


Step 4 – Axis shifts for all pads

Run 4475 - Entries as a function of the shifts on the x-axis - step 2



Run 4475 - Entries as a function of the shifts on the y-axis - step 2



Problems

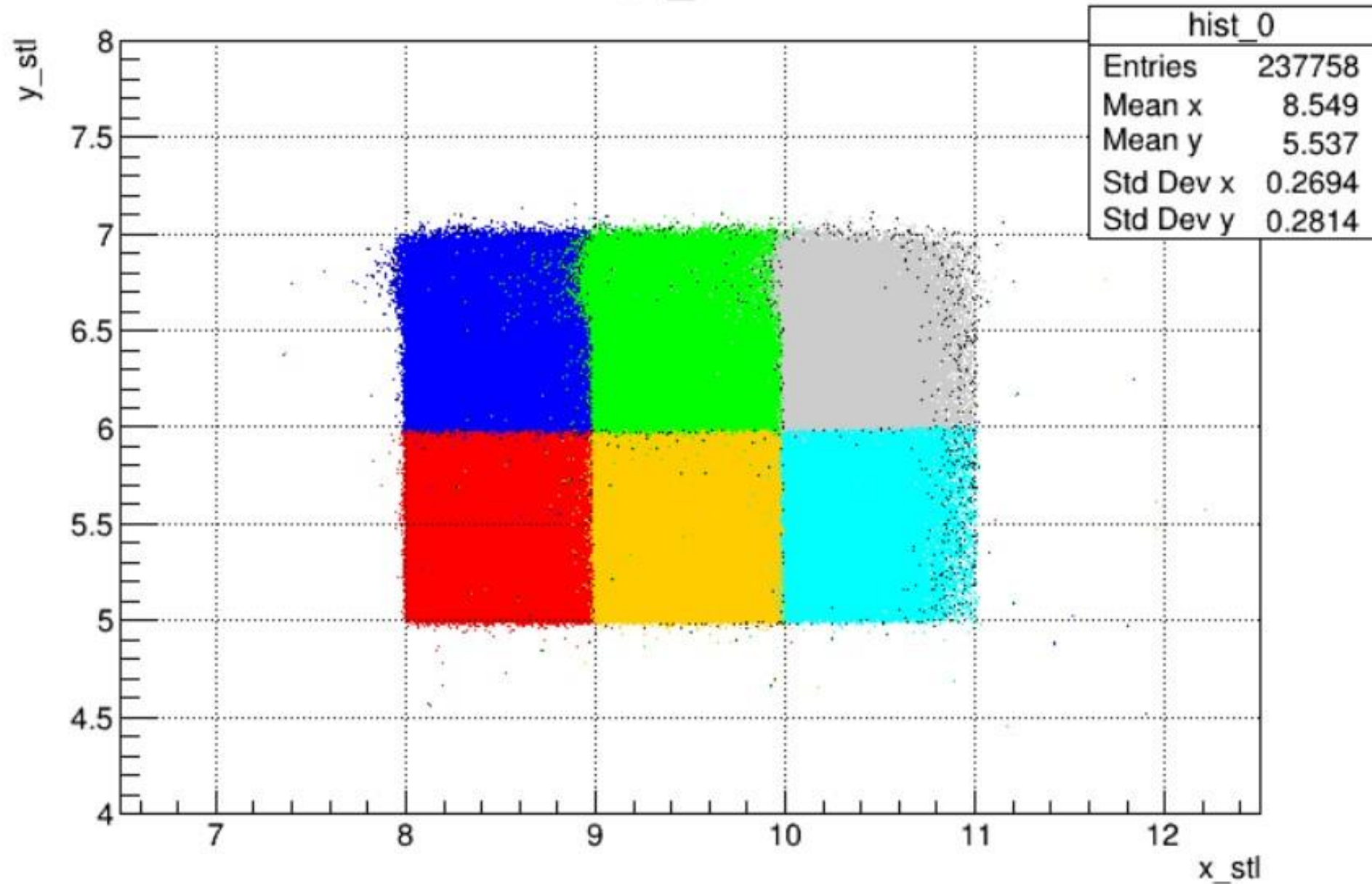
- The program takes about 5.5-7.5 minutes to align completely for each individual run
- “Bulges” on the upper row of each run

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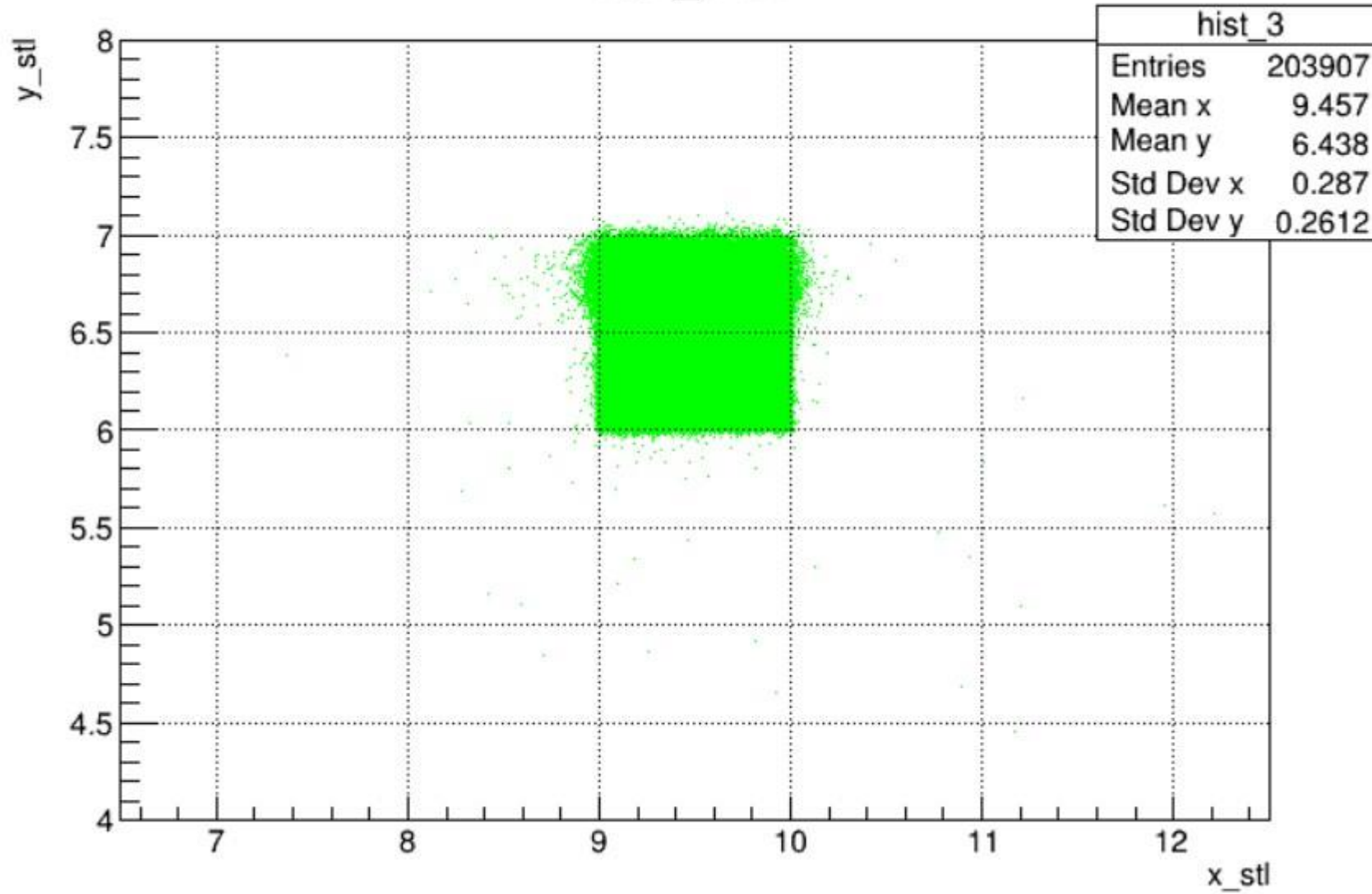
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- “Bulges” on the upper row of each run

Run 4417 – Aligned

Run_4417

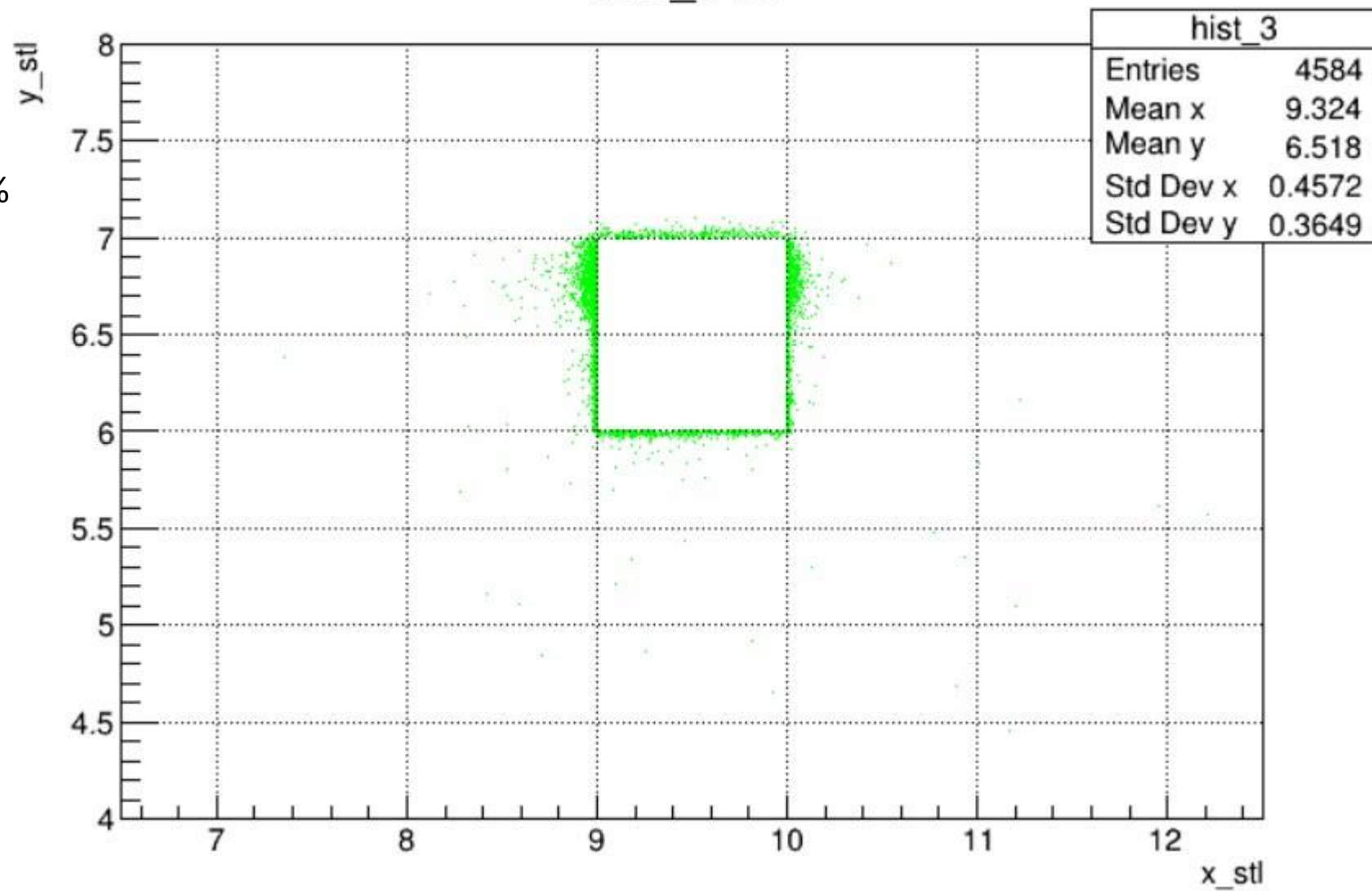


Run_4417



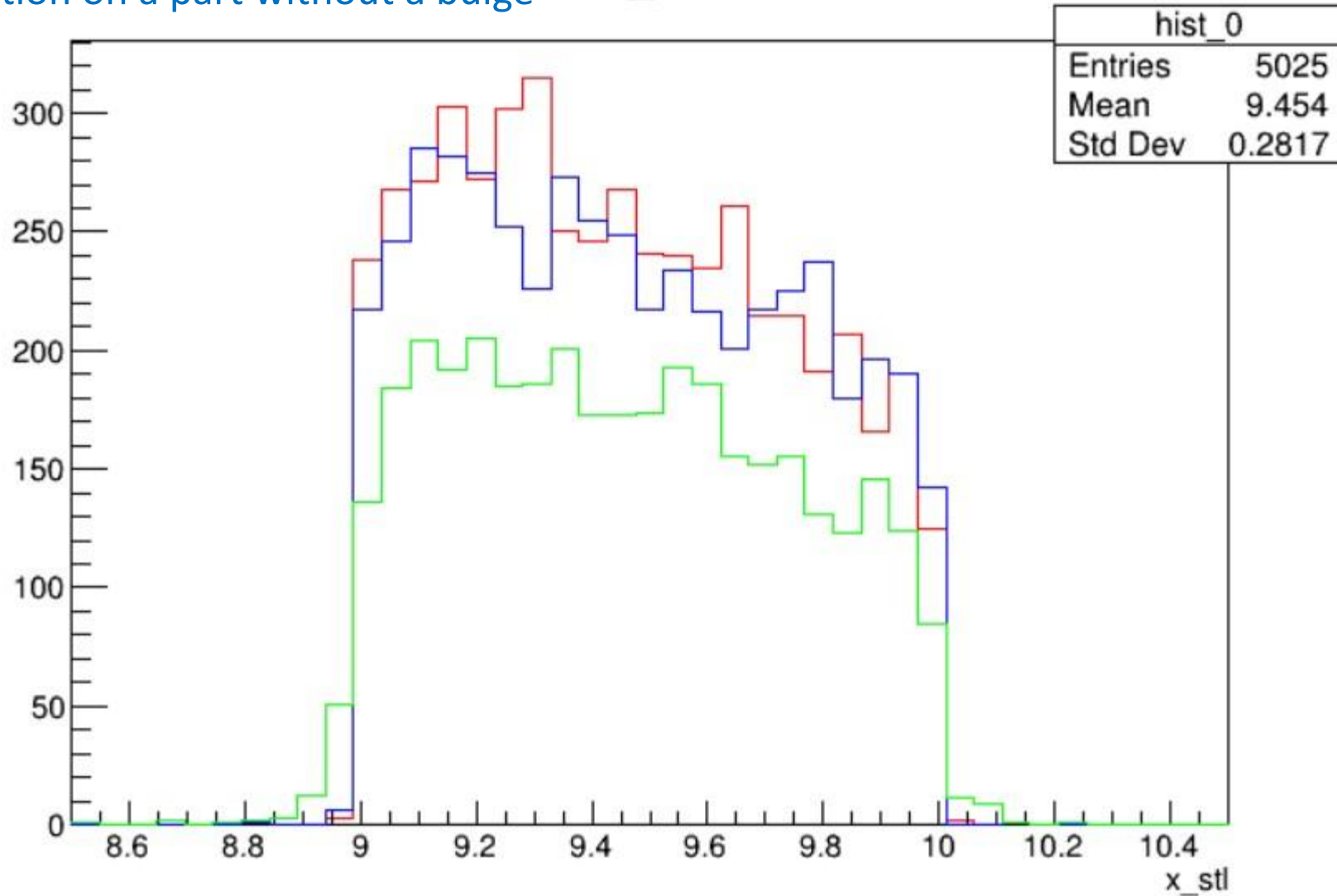
Run_4417

% of entries outside: 2.09%



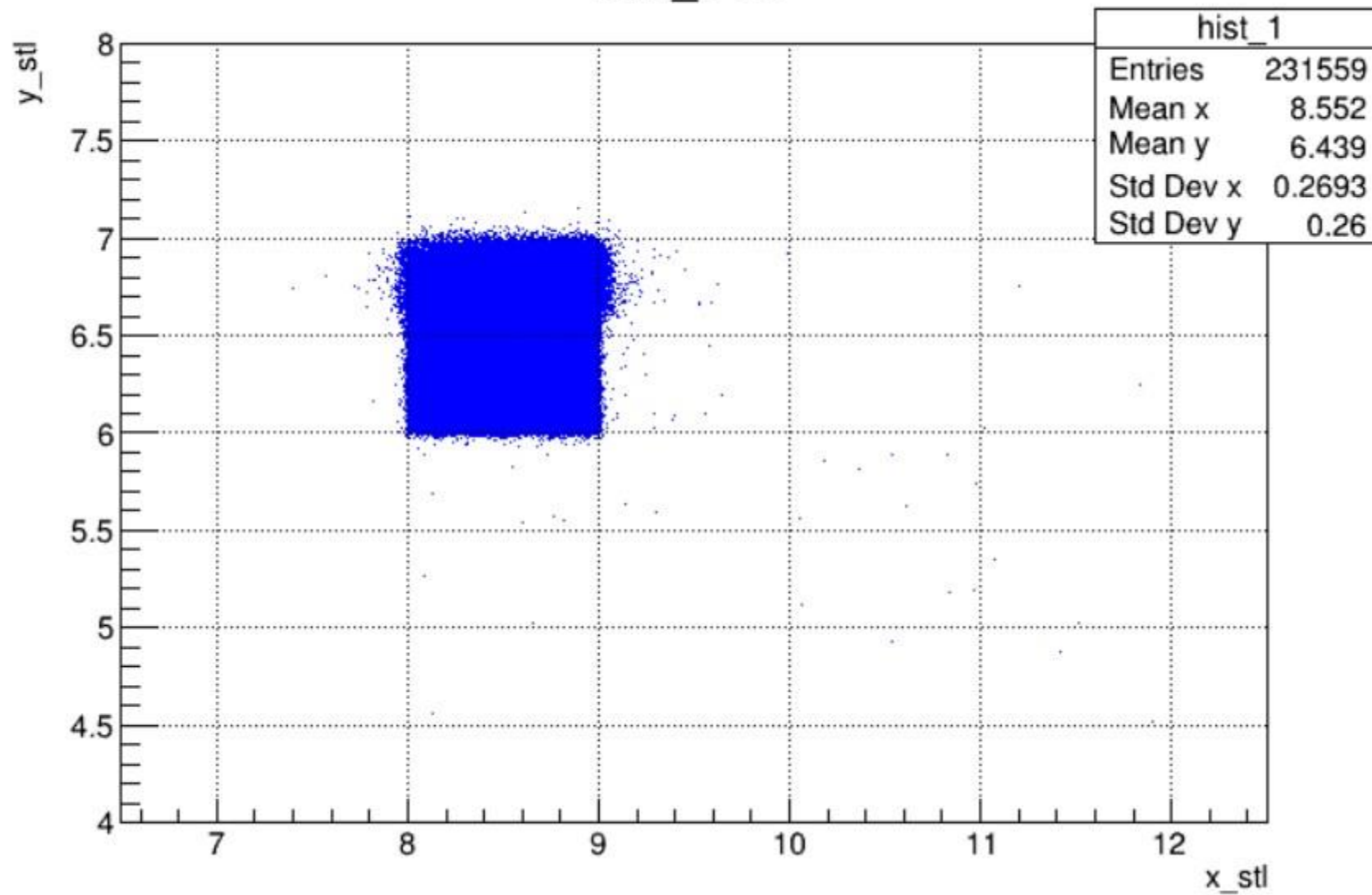
Run 4417 - Pad (9,6) (Green):

- Green Plot – Projection on the bulge
- Red Plot – Projection on the middle of the pad
- Blue Plot – Projection on a part without a bulge

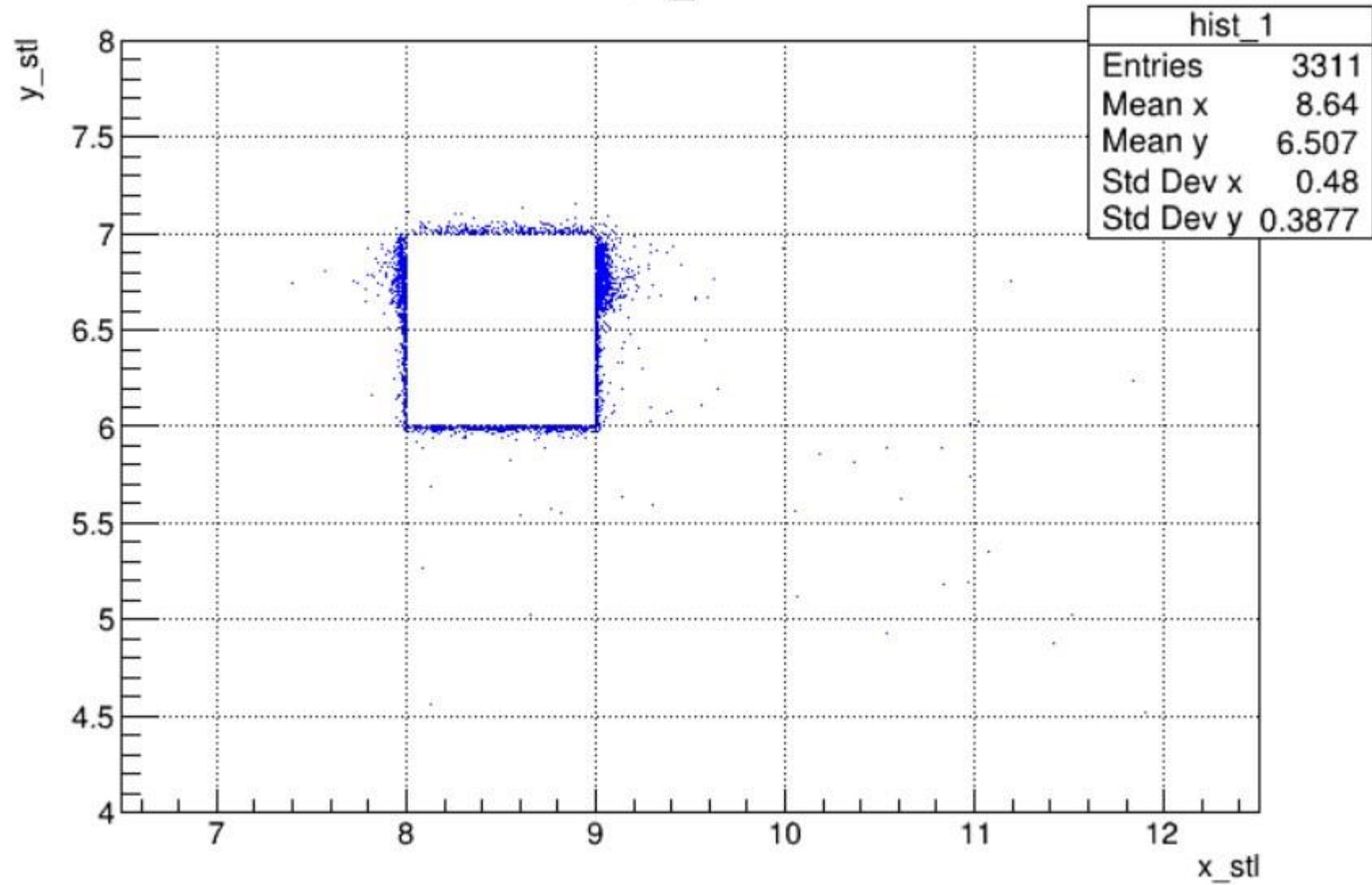


- The bulges are notable visually, but the percentage is relatively low
- The bulges always occur on the upper row, independent of sensor and run number(before the alignment as well)
- We suspect that they come from a property of the telescope, and will use them to determine it's resolution

Run_4417



Run_4417



% of entries outside: 1.40%

Questions?

Thank You For Listening😊