# Present and Future Operation Tools and Algorithms at ALS

#### **Thorsten Hellert**

**ALS Accelerator Physics Group** 



#### **ALS Will Stick with EPICS**

#### • EPICS 7:

- Flat naming -> adding structures to PV names
- Phoebus Tools:
  - Control Room Displays
  - Alarm handler



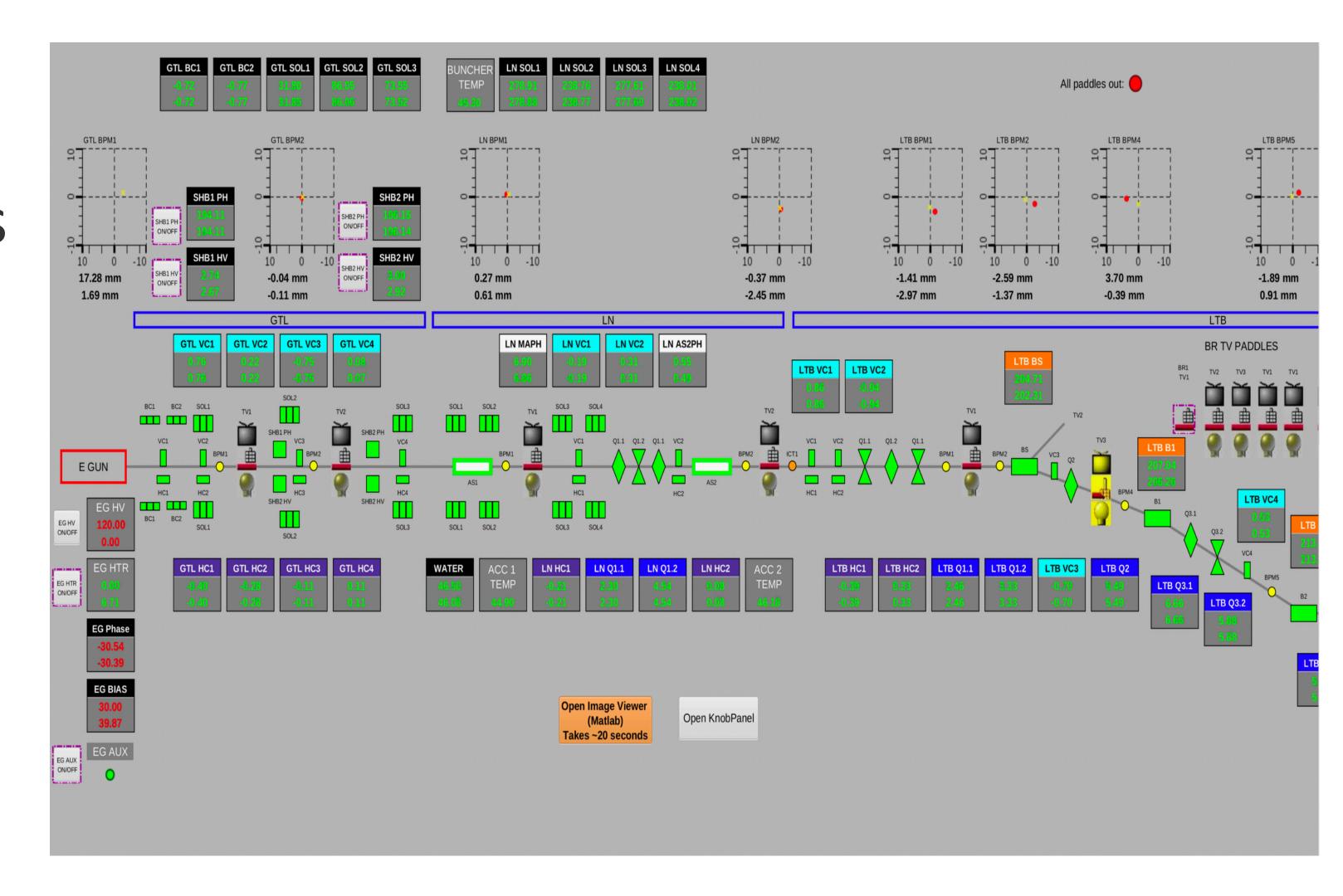




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#### **ALS Will Stick with EPICS**

#### • EPICS 7:

- Flat naming -> adding structures to PV names
- Phoebus Tools:
  - Control Room Displays
  - Alarm handler
- Archiver Appliance:
  - Python / Matlab
  - Grafana (new)

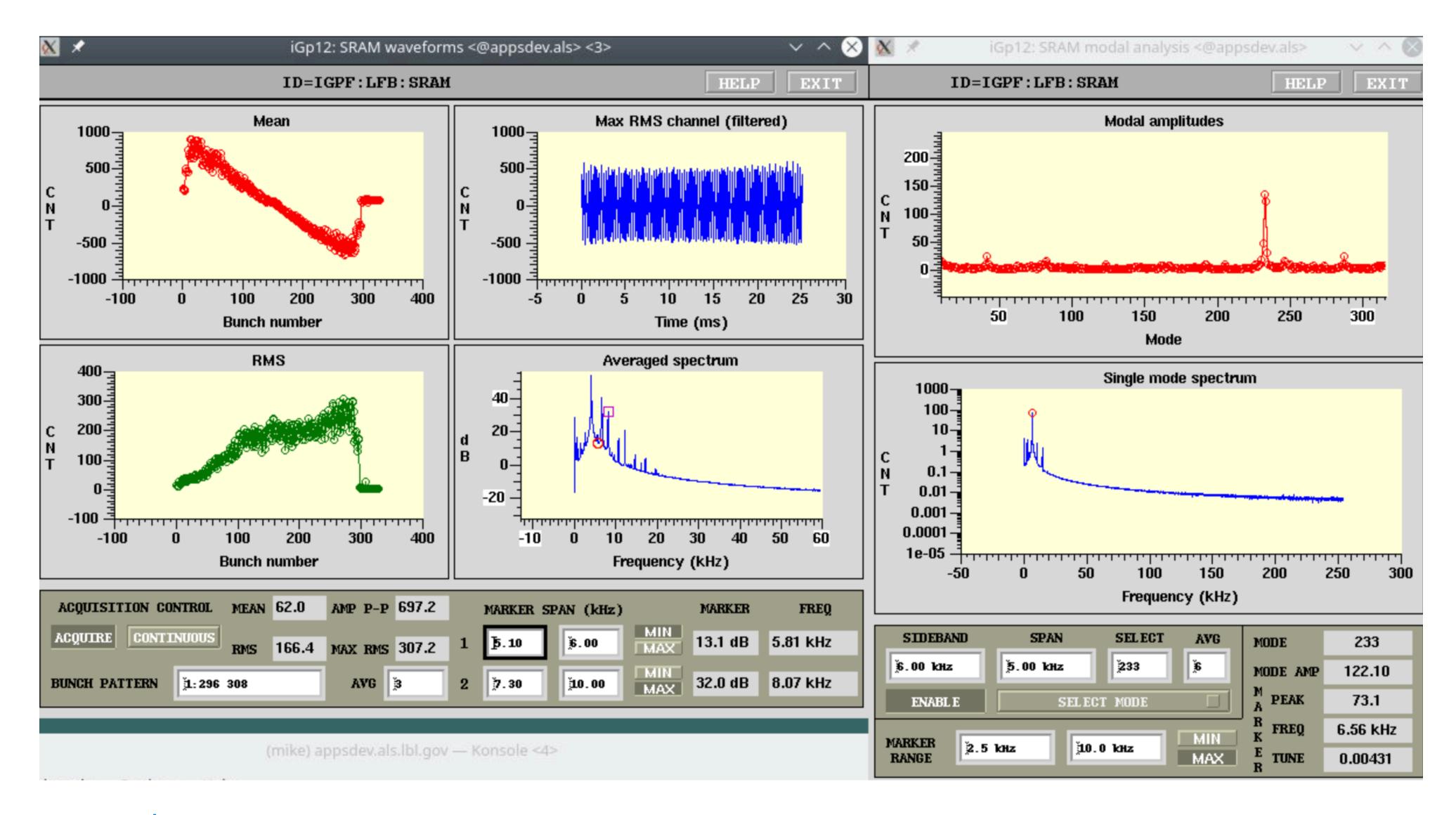


https://grafana.com/





#### LFB & TFB: Dimtel



# ALS is Very Matlab Focused

#### **Naming Convention**

Family = Group descriptor (text string)
Field = Subgroup descriptor (text string)
DeviceList = [Sector Element-in-Sector]

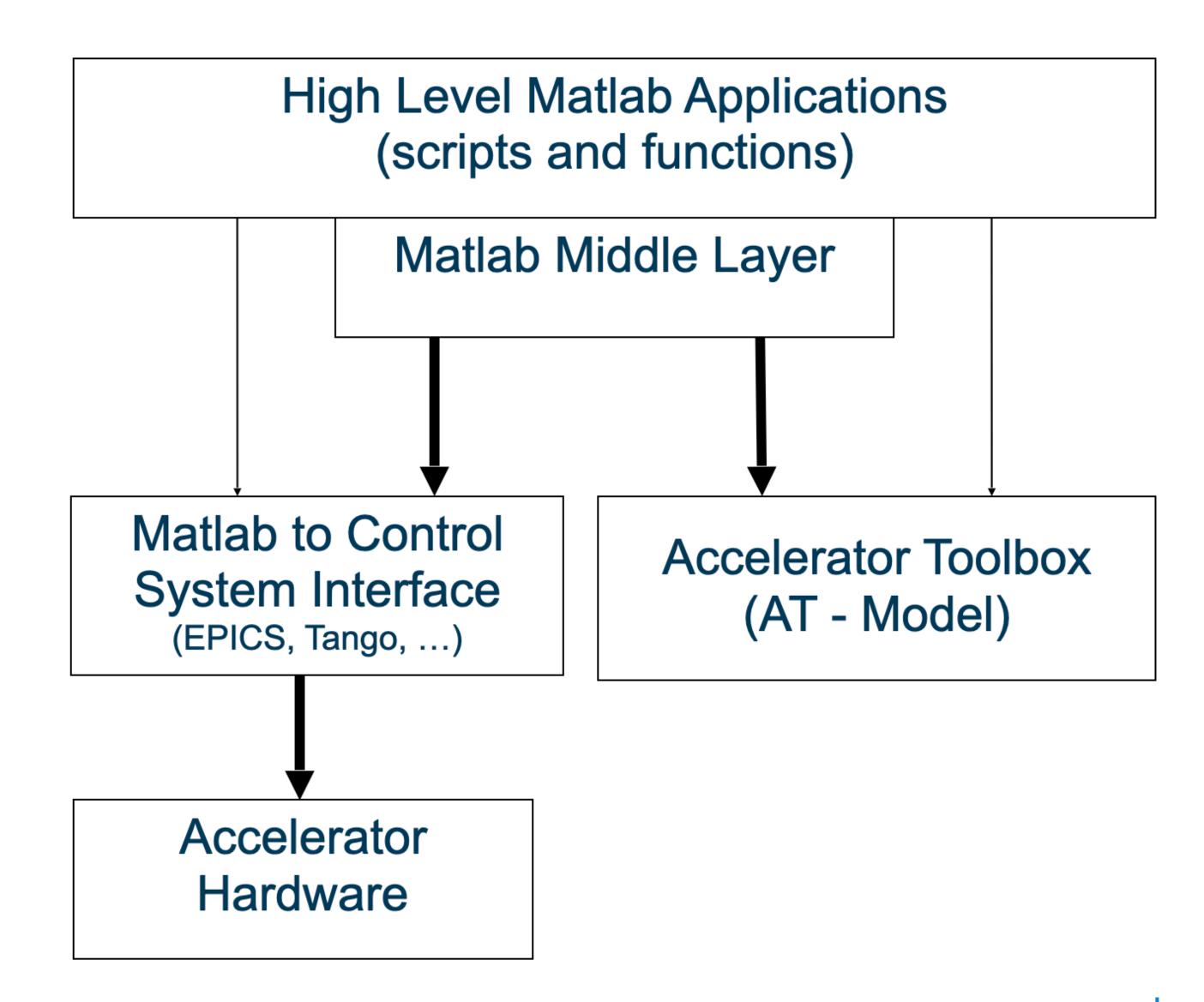
#### **Basic Functions**

```
getpv(Family, Field, DeviceList);
setpv(Family, Field, Value, DeviceList);
steppv(Family, Field, Value, DeviceList);
```

These functions can branch between the model and online.

#### **Examples:**

```
x = getpv('BPMx', 'Monitor', [3 4;5 2]);
h = getpv('HCM', 'Setpoint', [2 1;12 4]);
setpv('QF', 'Setpoint', 81);
```







#### Name Server: EPICS Channel Finder

At the ALS, the channel finder service tags channels using the same "Accelerator, Family, Field, Device" scheme as in the MML.

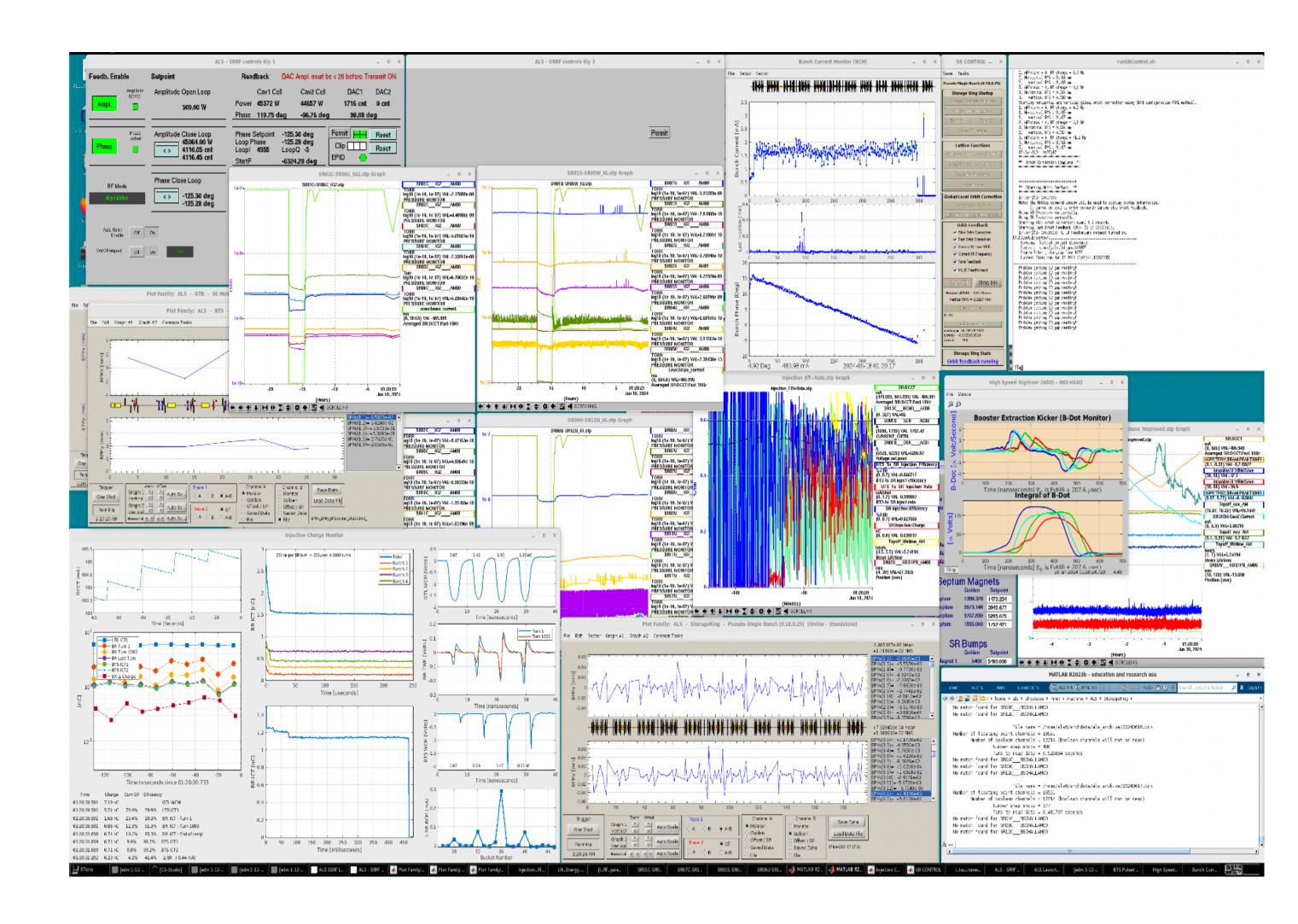
Controls Main × Ops Laun			aunche	cher × ALS Launcher ×		< Linac >	K MOD1	× MOD2 ×	miniDCCT ×	EPBI ×	Channel Ta	ble × Chann	iel Table ×
Query:	* Acc=	SR Fam	ily=QF	Field=Se	tpoint Sect	or=* Devi	ce=*						
name 🔺			Acc	Family	Field	Sector	Device	Position	Golden		archive	recordType	iocName
SR01C_	_QF1	_AC02	SR	QF	Setpoint	1	1	3.378696	96.908063344168553		Fast	ao	ffbsec01
SR01C_	_QF2	_AC03	SR	QF	Setpoint	1	2	12.677306	96.548511743507575		Fast	ao	ffbsec01
SR02C_	_QF1	_AC02	SR	QF	Setpoint	2	1	19.778696	95.67546942	0609659	Fast	ao	ffbsec02
SR02C_	_QF2	_AC03	SR	QF	Setpoint	2	2	29.077306	96.25629257	026965	Fast	ao	ffbsec02
SR03C_	_QF1	_AC02	SR	QF	Setpoint	3	1	36.178696	96.25499375	5862387	Fast	ao	ffbsec03
SR03C_	_QF2	_AC03	SR	QF	Setpoint	3	2	45.477306	94.96899315	4771908	Fast	ao	ffbsec03
SR04C_	_QF1	_AC02	SR	QF	Setpoint	4	1	52.578696	97.36266856	0344588	Fast	ao	ffbsec04
SR04C_	_QF2	_AC03	SR	QF	Setpoint	4	2	61.879111	96.99748131	0809263	Fast	ao	ffbsec04
SR05C_	_QF1	_AC02	SR	QF	Setpoint	5	1	68.980501	95.70388698	7555819	Fast	ao	ffbsec05
SR05C_	_QF2	_AC03	SR	QF	Setpoint	5	2	78.279111	95.28859316	9344963	Fast	ao	ffbsec05
SR06C_	_QF1	_AC02	SR	QF	Setpoint	6	1	85.380501	96.44757318	0643431	Fast	ao	ffbsec06
SR06C_	_QF2	_AC03	SR	QF	Setpoint	6	2	94.679111	96.50602041	01957	Fast	ao	ffbsec06
SR07C_	_QF1	_AC02	SR	QF	Setpoint	7	1	101.780501	95.74434734	4953354	Fast	ao	ffbsec07
SR07C_	_QF2	_AC03	SR	QF	Setpoint	7	2	111.079111	96.56681685	0643619	Fast	ao	ffbsec07
SR08C_	_QF1	_AC02	SR	QF	Setpoint	8	1	118.180501	96.15799988	63688	Fast	ao	ffbsec08
SR08C_	_QF2	_AC03	SR	QF	Setpoint	8	2	127.480916	97.18719441	846909	Fast	ao	ffbsec08
SR09C_	_QF1	_AC02	SR	QF	Setpoint	9	1	134.582305	95.34805839	70734	Fast	ao	ffbsec09
SR09C_	_QF2	_AC03	SR	QF	Setpoint	9	2	143.880916	96.18249707	0246868	Fast	ao	ffbsec09
SR10C_	_QF1	_AC02	SR	QF	Setpoint	10	1	150.982306	96.26678358	2685619	Fast	ao	ffbsec10
SR10C_	_QF2	_AC03	SR	QF	Setpoint	10	2	160.280916	95.86179780	5405516	Fast	ao	ffbsec10
SR11C_	_QF2	_AC03	SR	QF	Setpoint	11	2	176.680916	95.54326854	0128	Fast	ao	ffbsec11
SR11C:QF1:Setpoint		oint	SR	QF	Setpoint	11	1	167.382306	95.77525481	1217167	Fast	ao	genesys
SR12C_	_QF1	_AC02	SR	QF	Setpoint	12	1	183.782306	96.48420006	3890142	Fast	ao	ffbsec12
SR12C_	_QF2	_AC03	SR	QF	Setpoint	12	2	193.082721	106.2144888	5069287	Fast	ao	ffbsec12



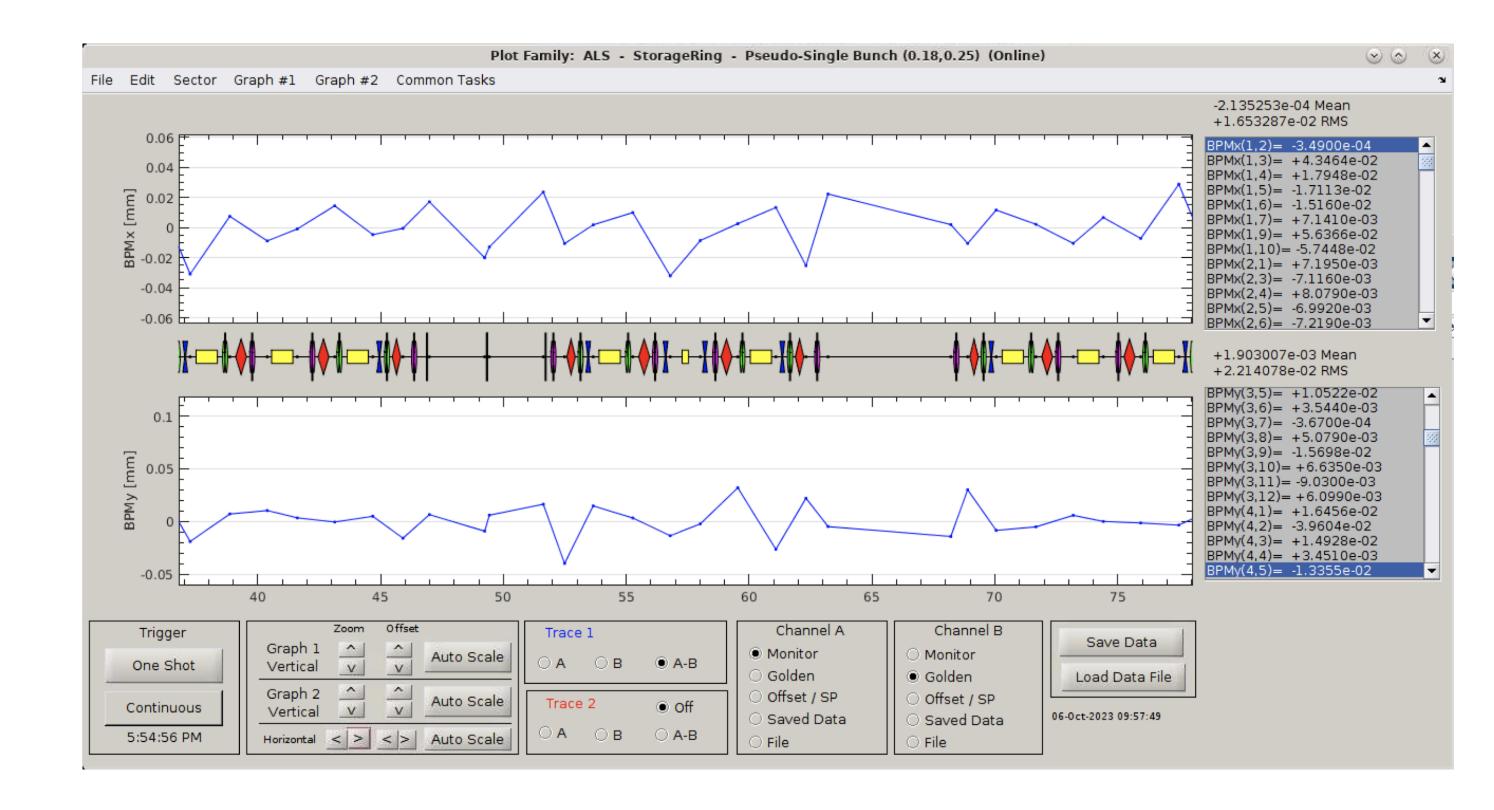


# Current High Level Applications in Matlab

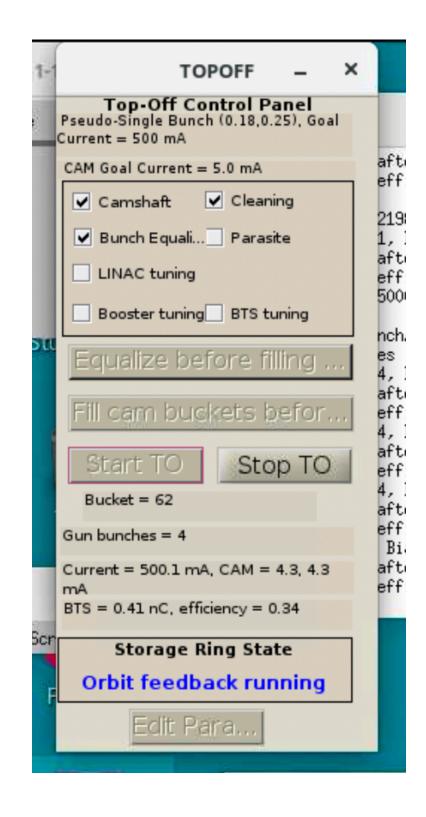
Display (plotfamily, mmlviewer)

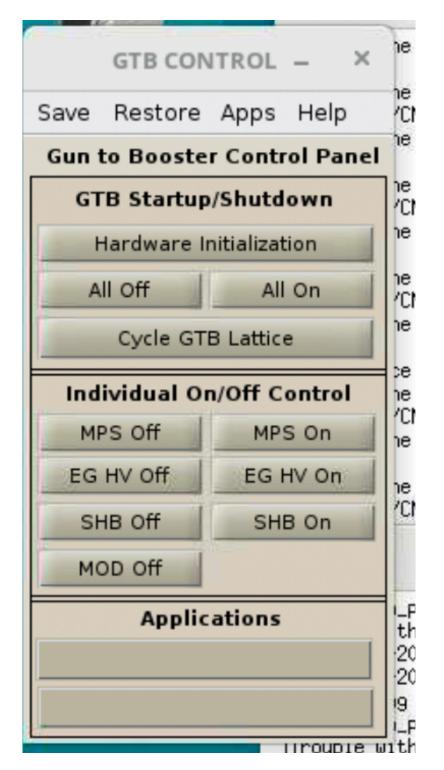


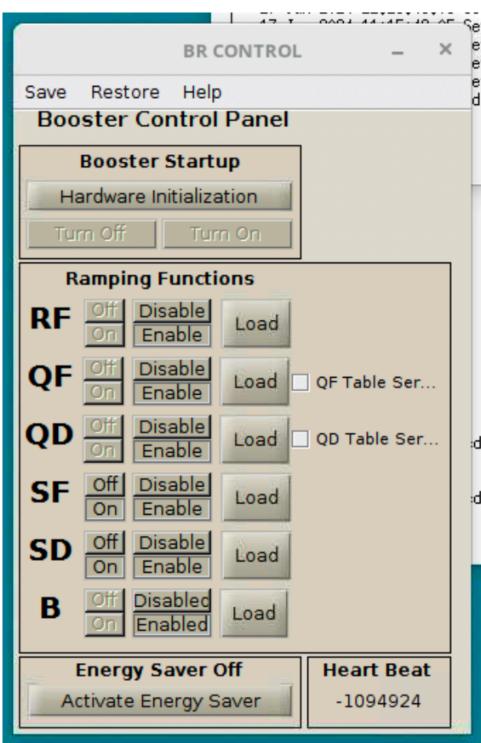
Display (plotfamily, mmlviewer)



- Display (plotfamily, mmlviewer)
- Main Control Panels

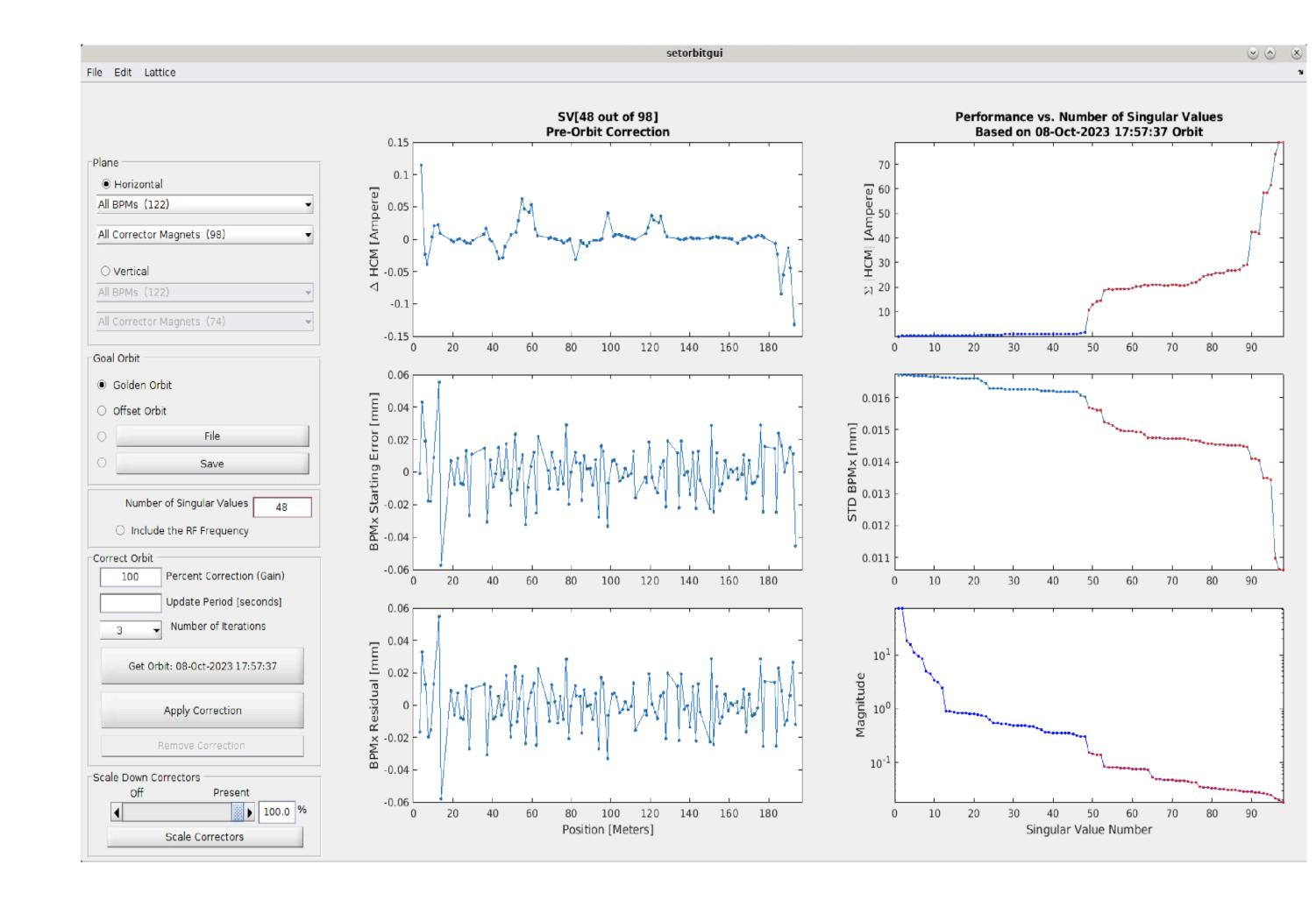




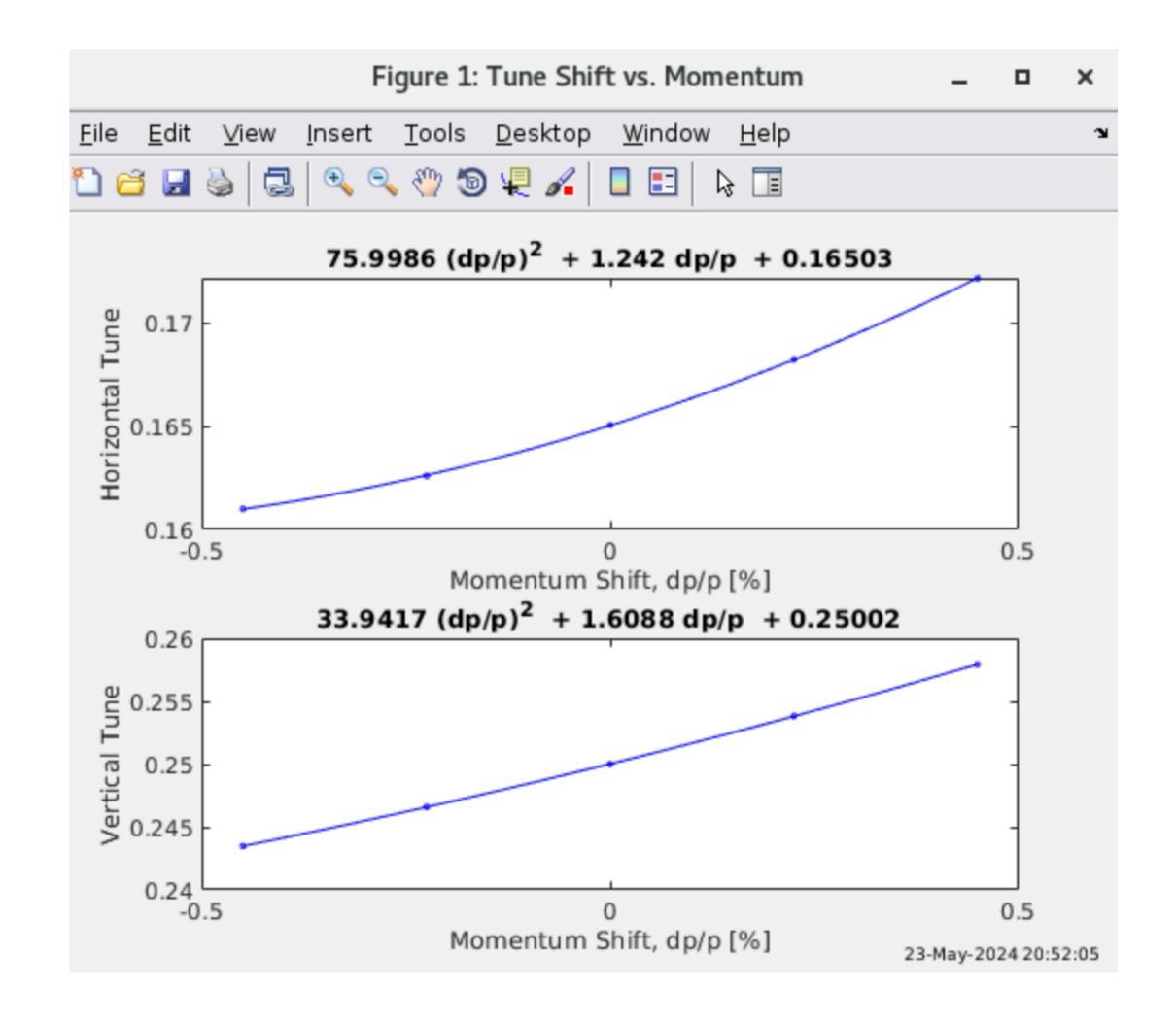




- Display (plotfamily, mmlviewer)
- Main Control Panels
- Orbit correction and slow orbit feedback



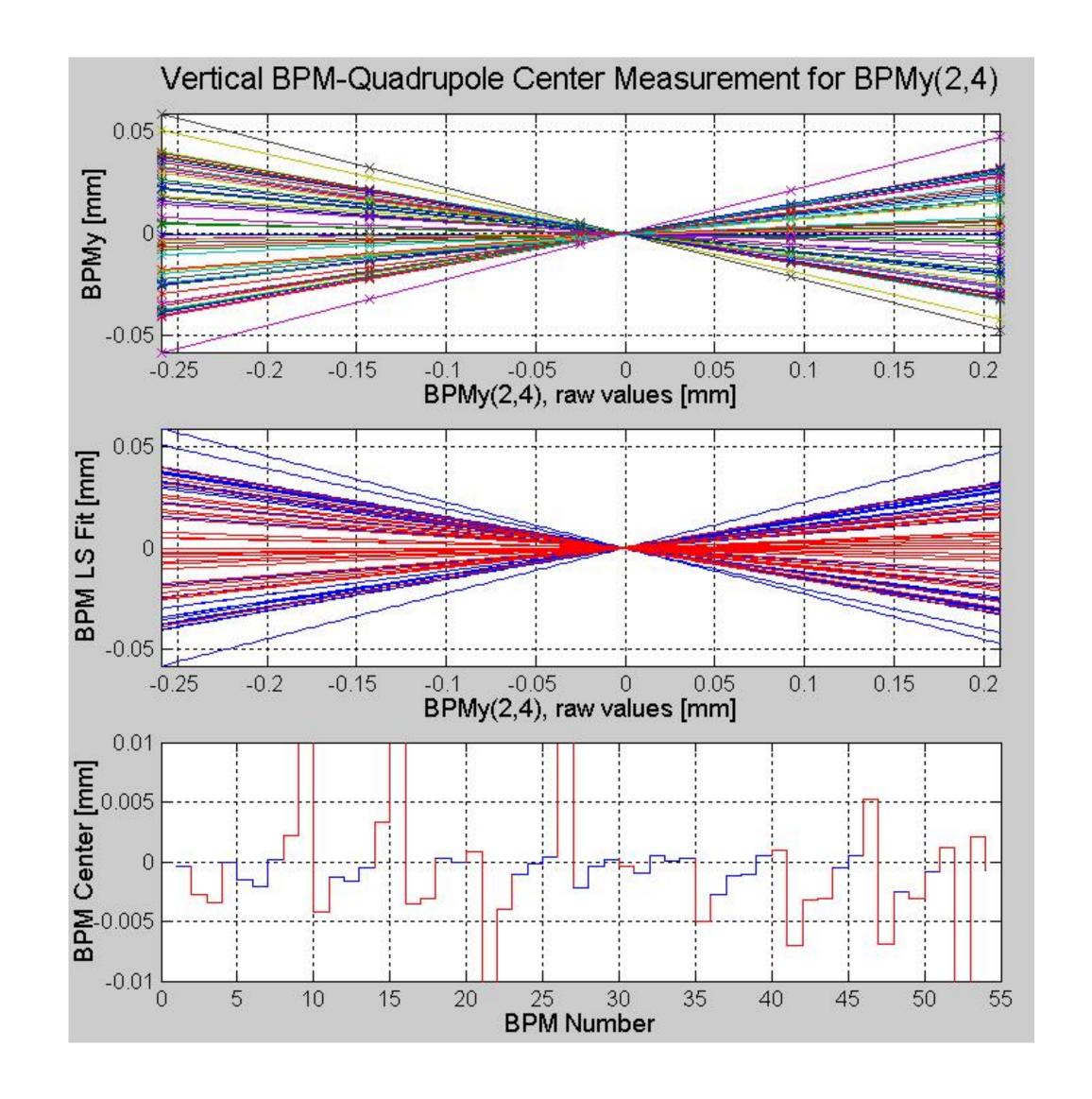
- Display (plotfamily, mmlviewer)
- Main Control Panels
- Orbit correction and slow orbit feedback
- Chromaticity Correction



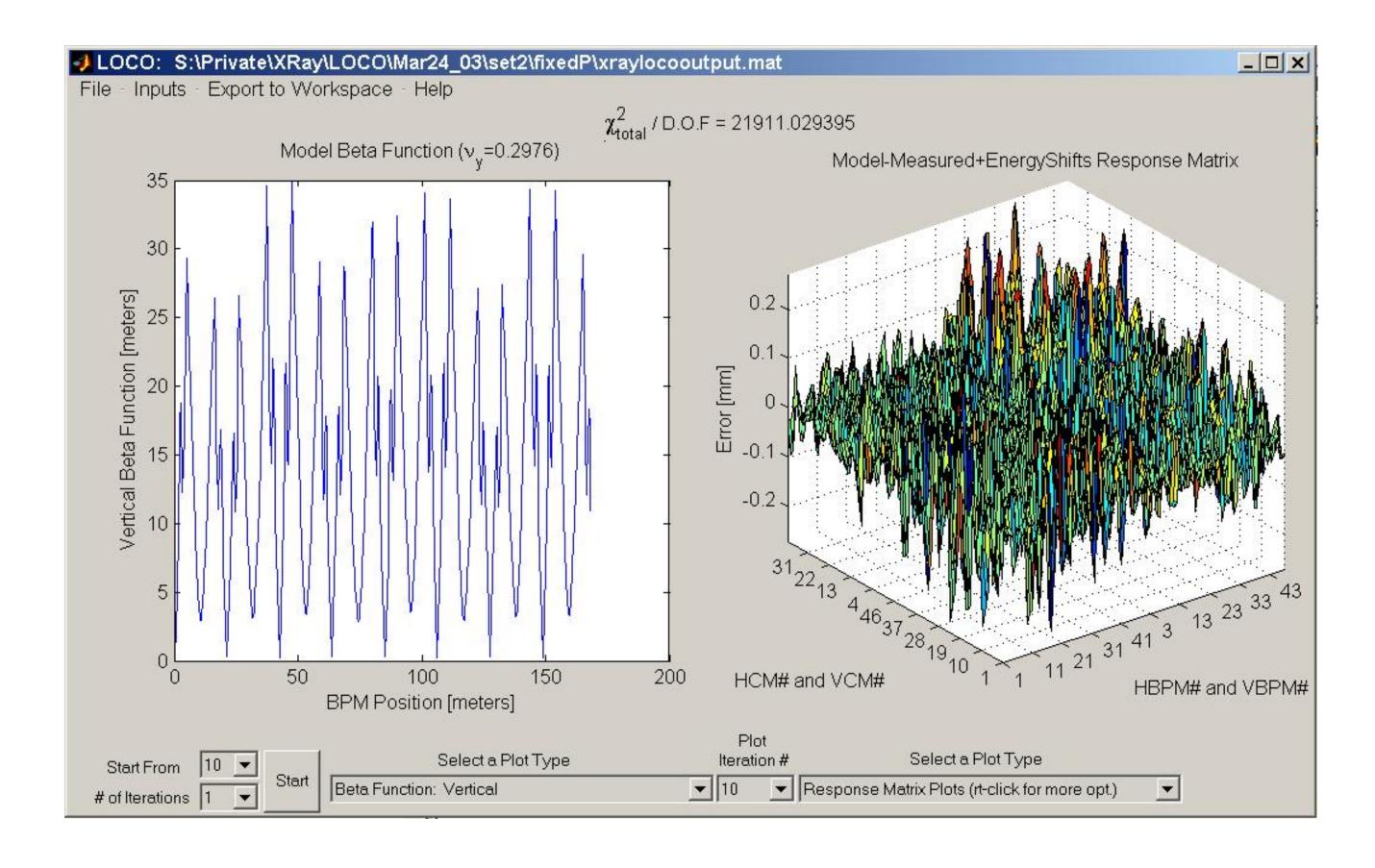


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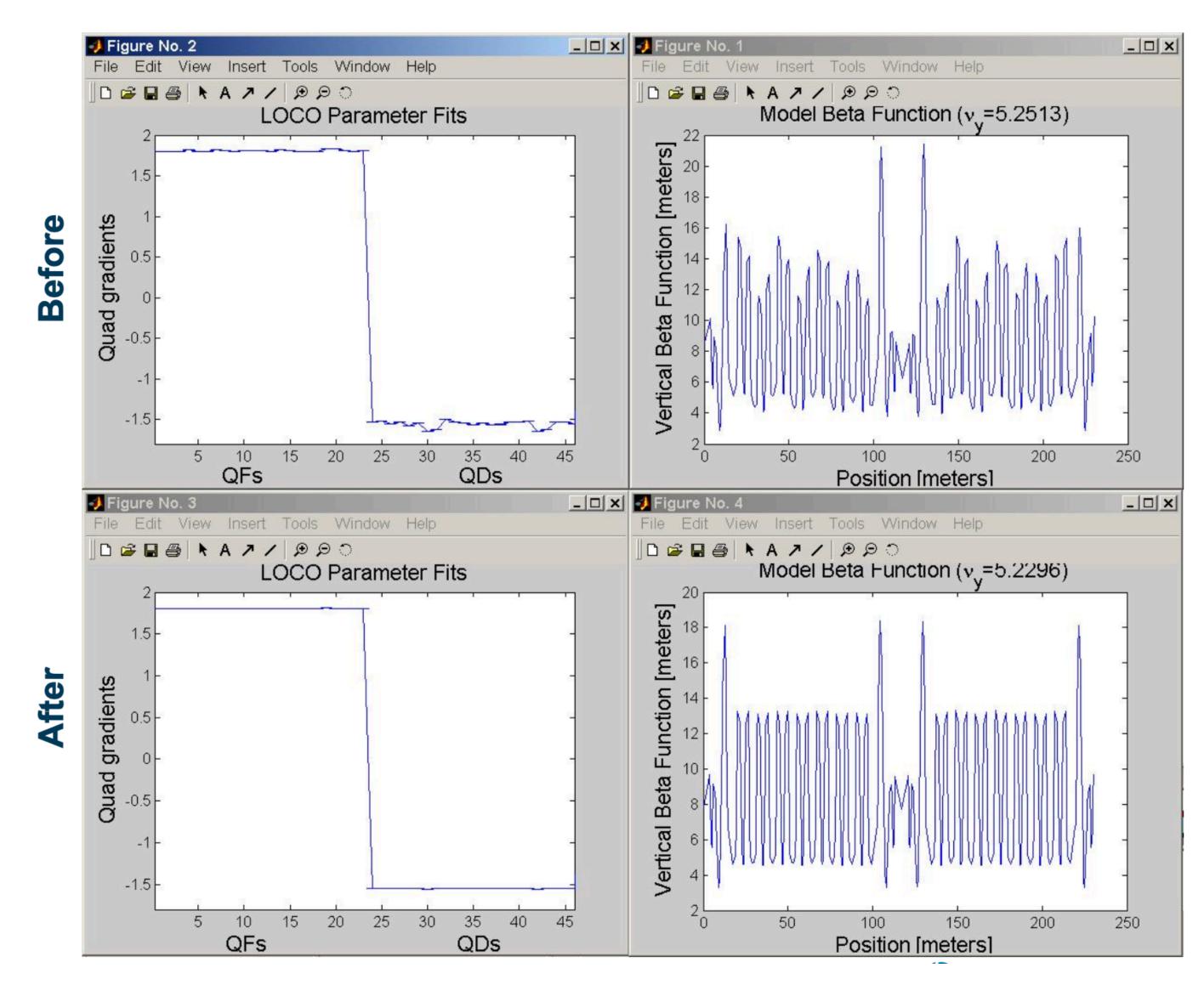
- Display (plotfamily, mmlviewer)
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- Orbit correction and slow orbit feedback
- Chromaticity Correction
- Beam Based Alignment



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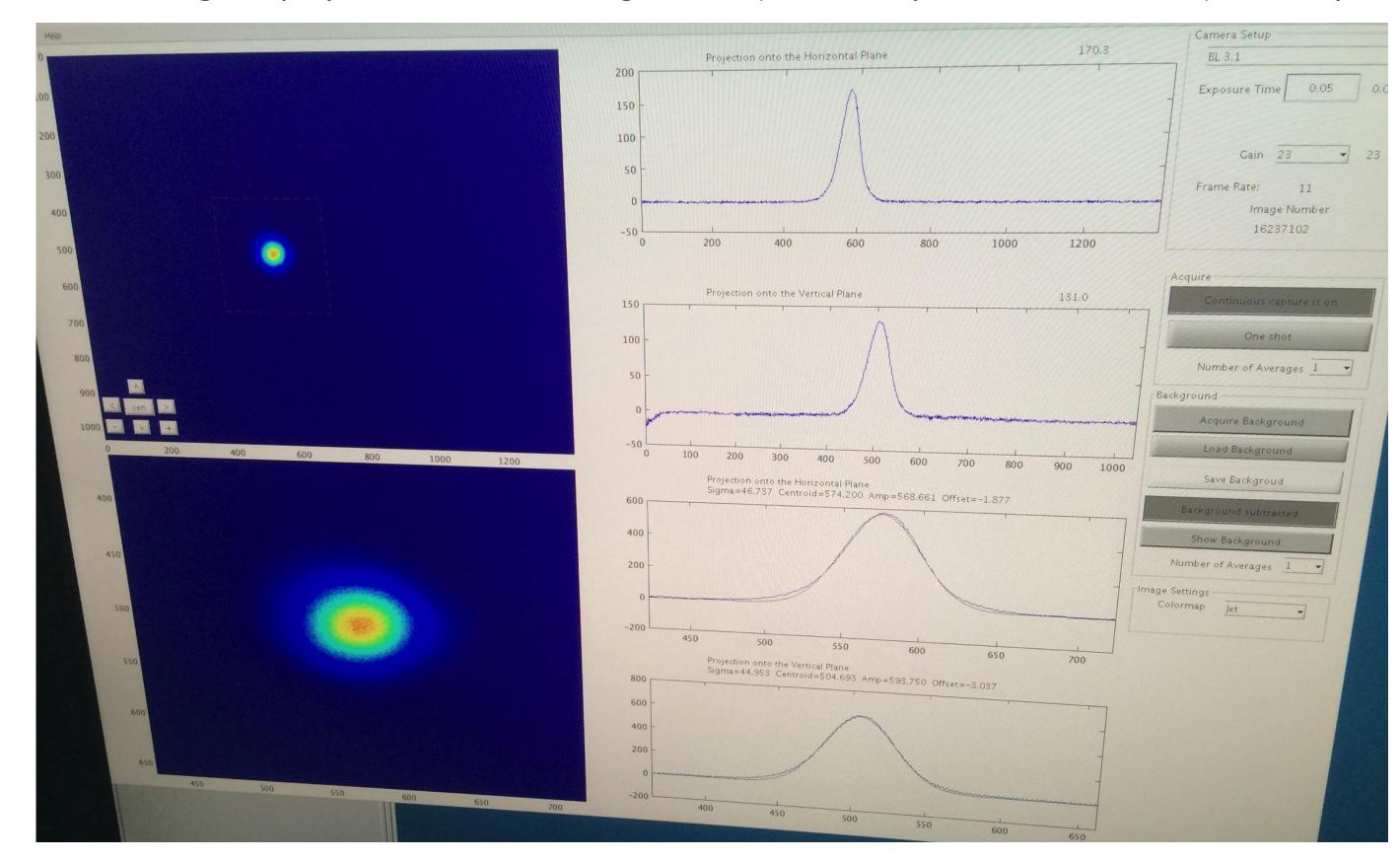




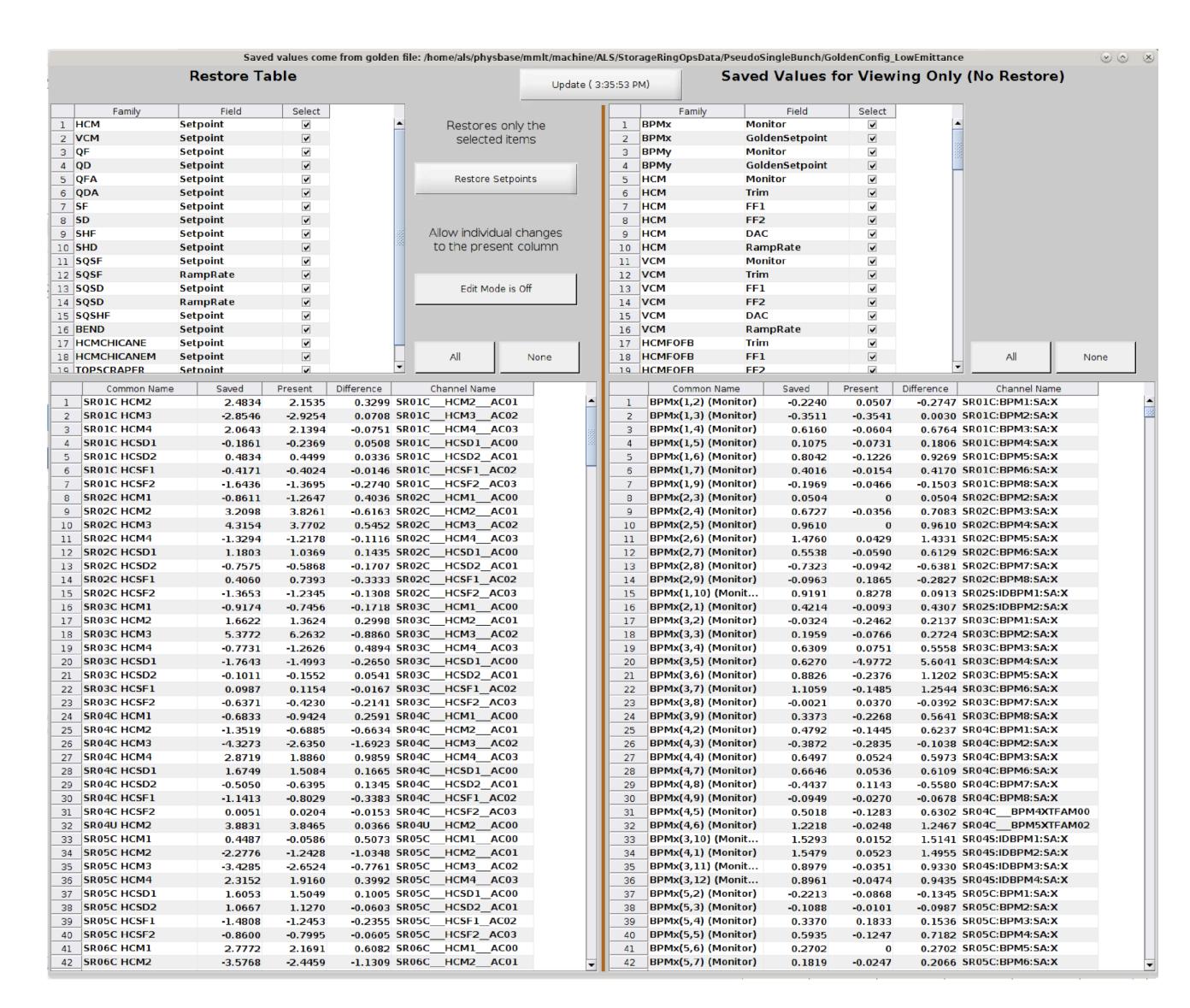


- Display (plotfamily, mmlviewer)
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- CCD cameras analysis

Cameras / image displays have all been using Matlab (now slowly moved to Phoebus) for analysis

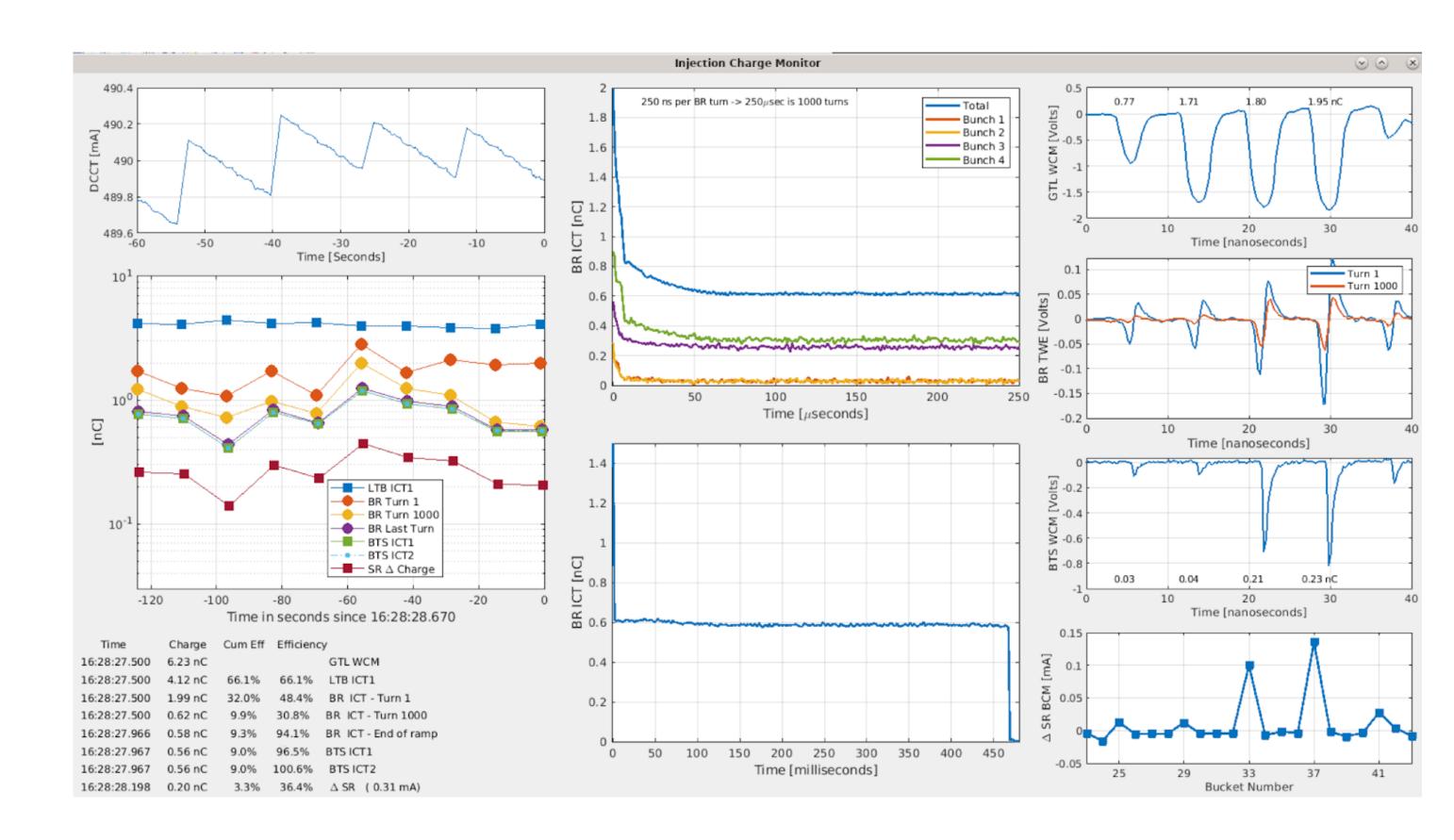


- Display (plotfamily, mmlviewer)
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- Chromaticity Correction
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- CCD cameras
- Save/ restore / configuration control

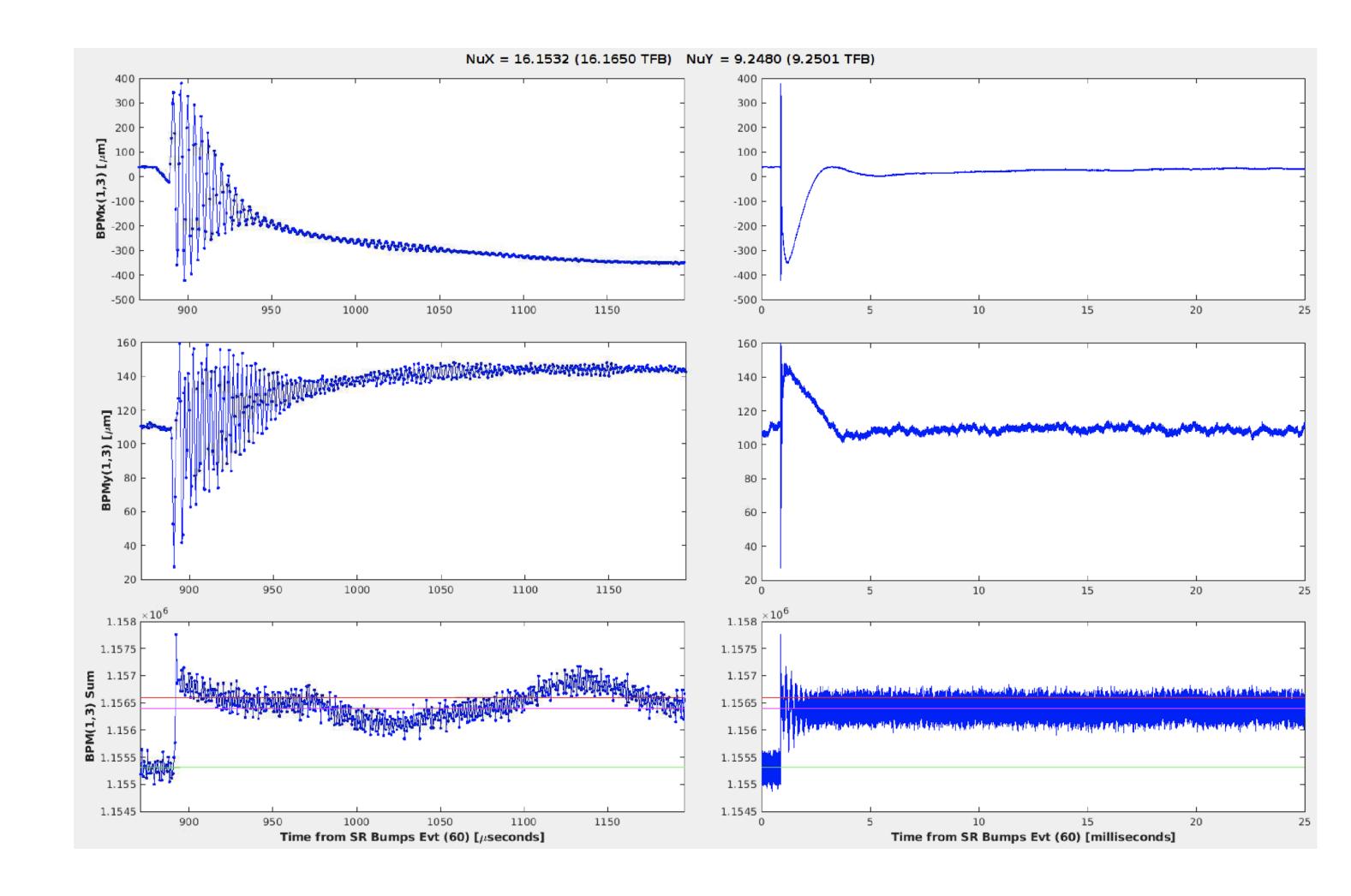




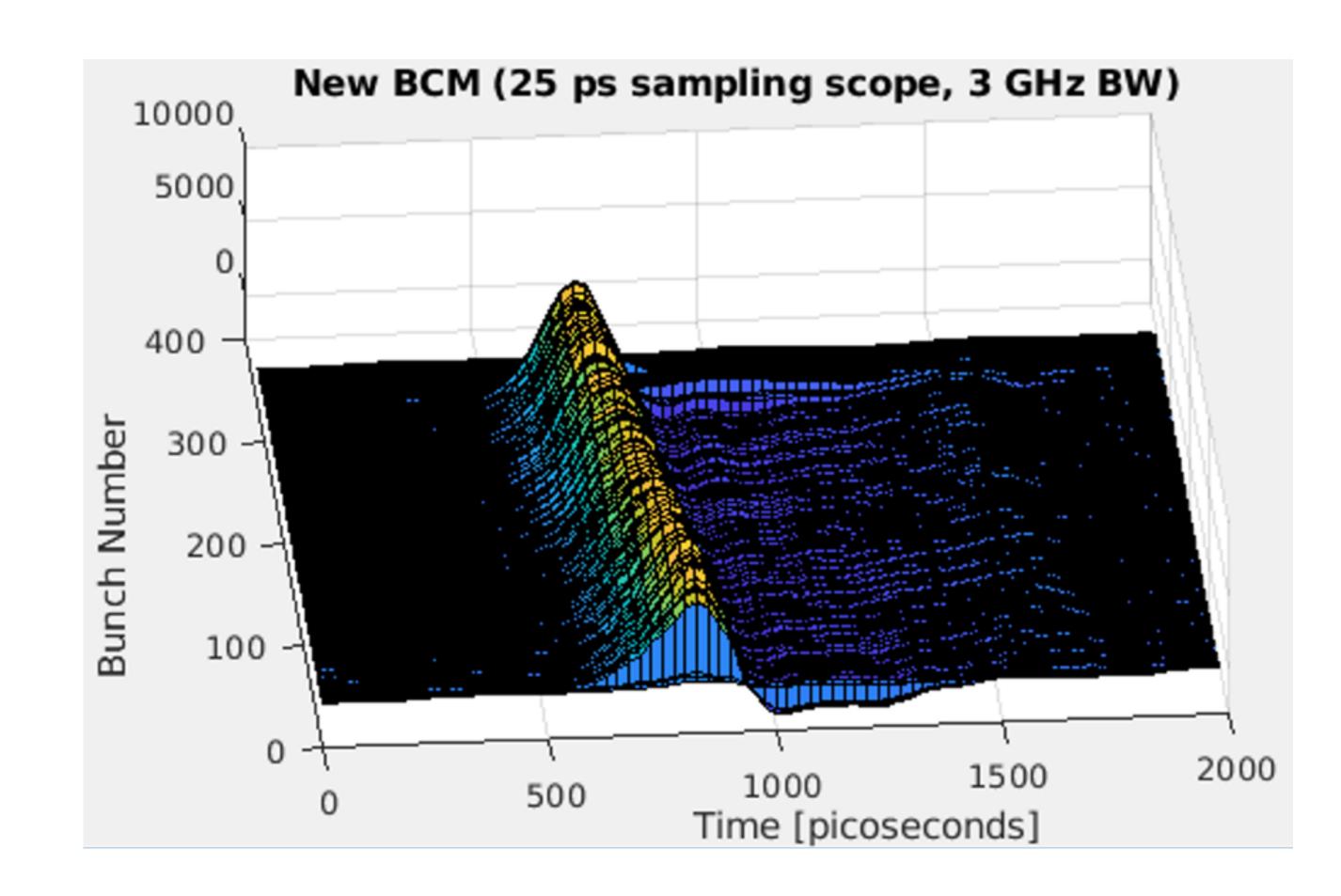
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- Save/ restore / configuration control
- Injection Monitoring



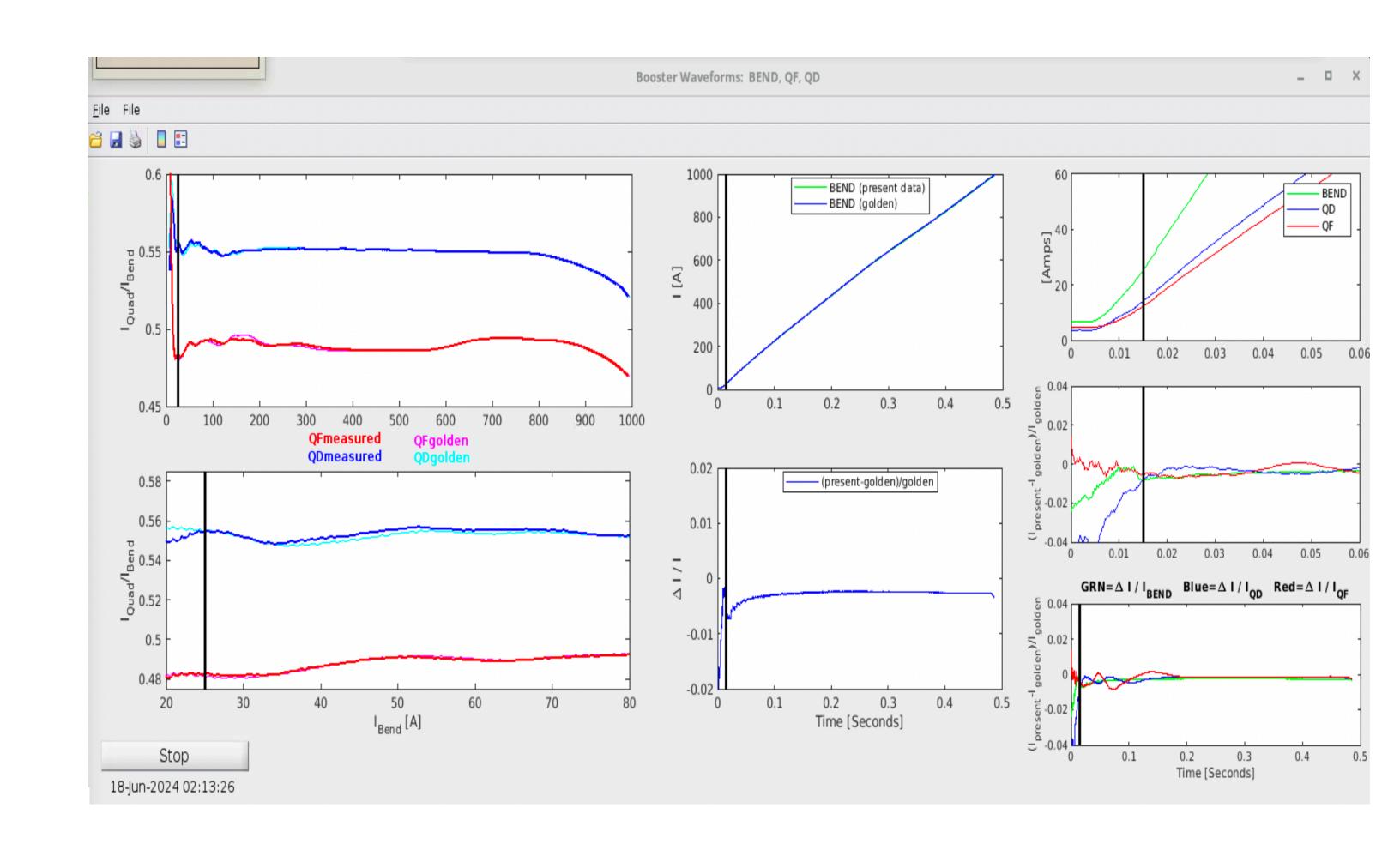
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- Bunch Current and Phase



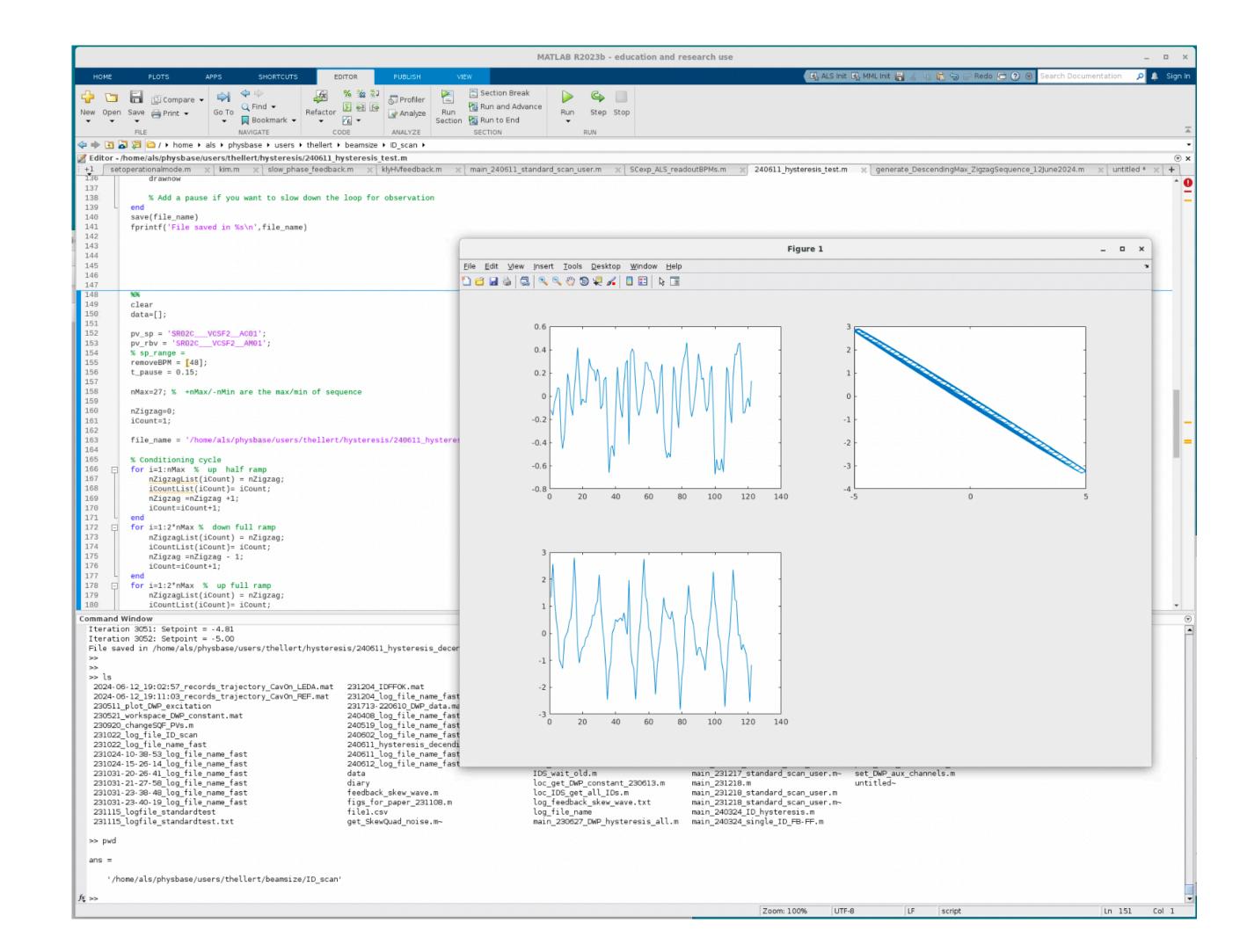
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- Hysteresis / Standardization of Magnets
- Primary Scripting Language for Physics Shifts



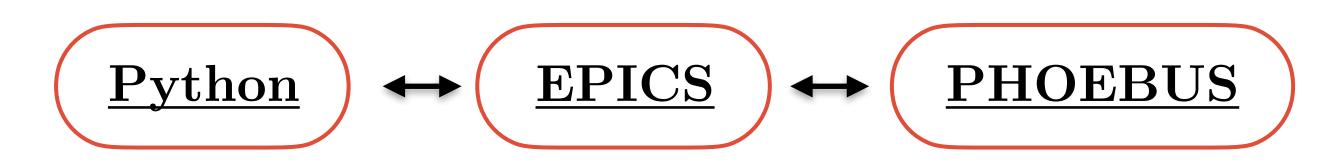




# Future Applications

# Machine Learning Projects are Implemented in Python

- Machine learning applications will become more important in the future
  - Implemented in python
  - Currently without any middle layer

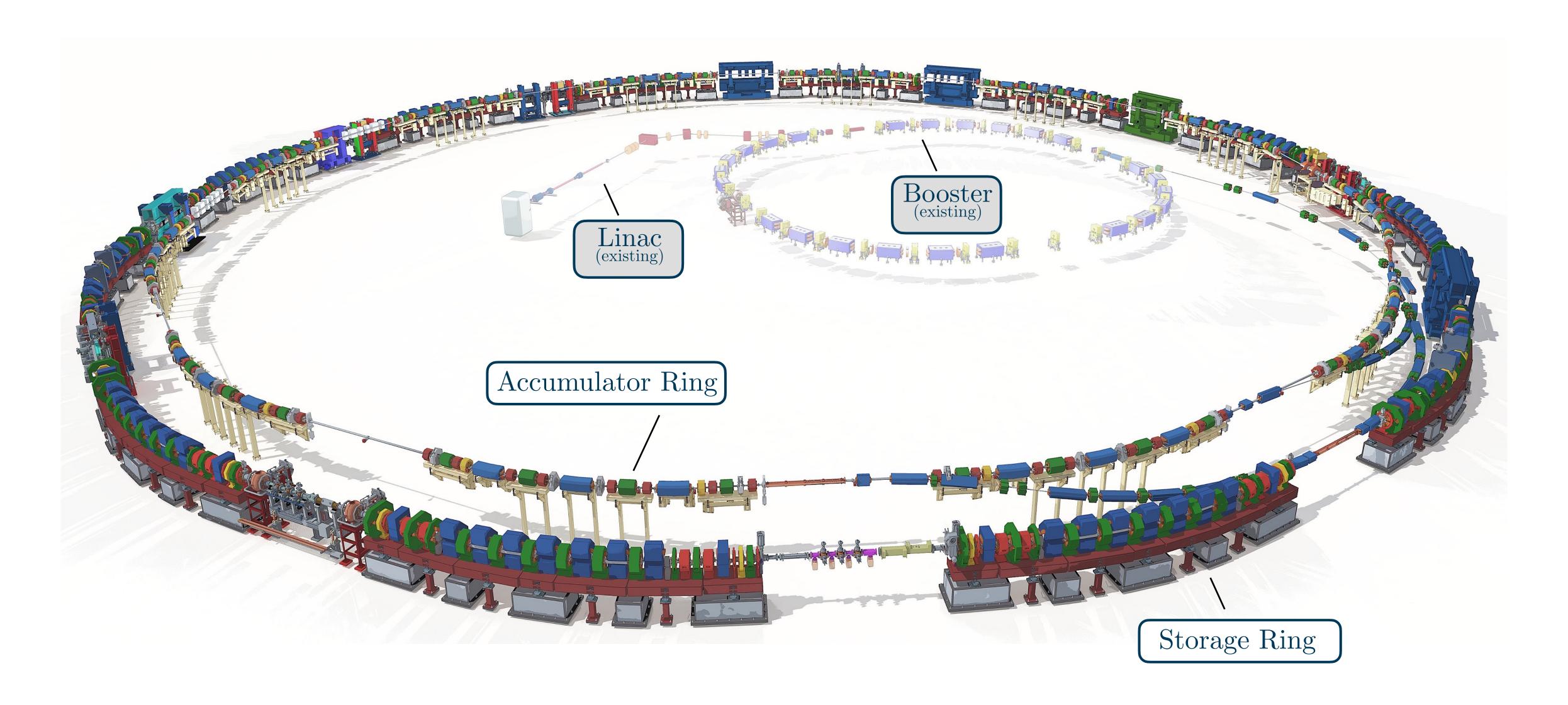






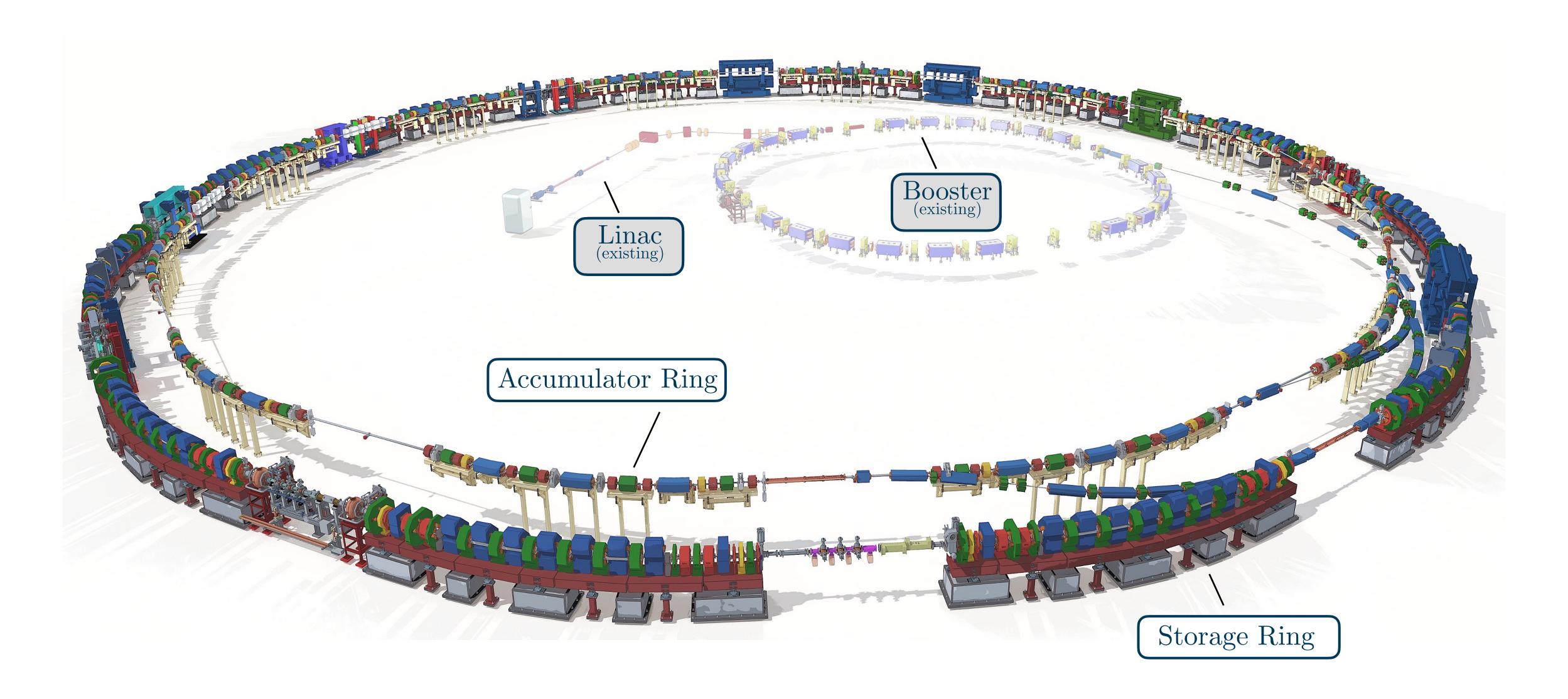


# Overview of the ALS-U Accelerator Facility



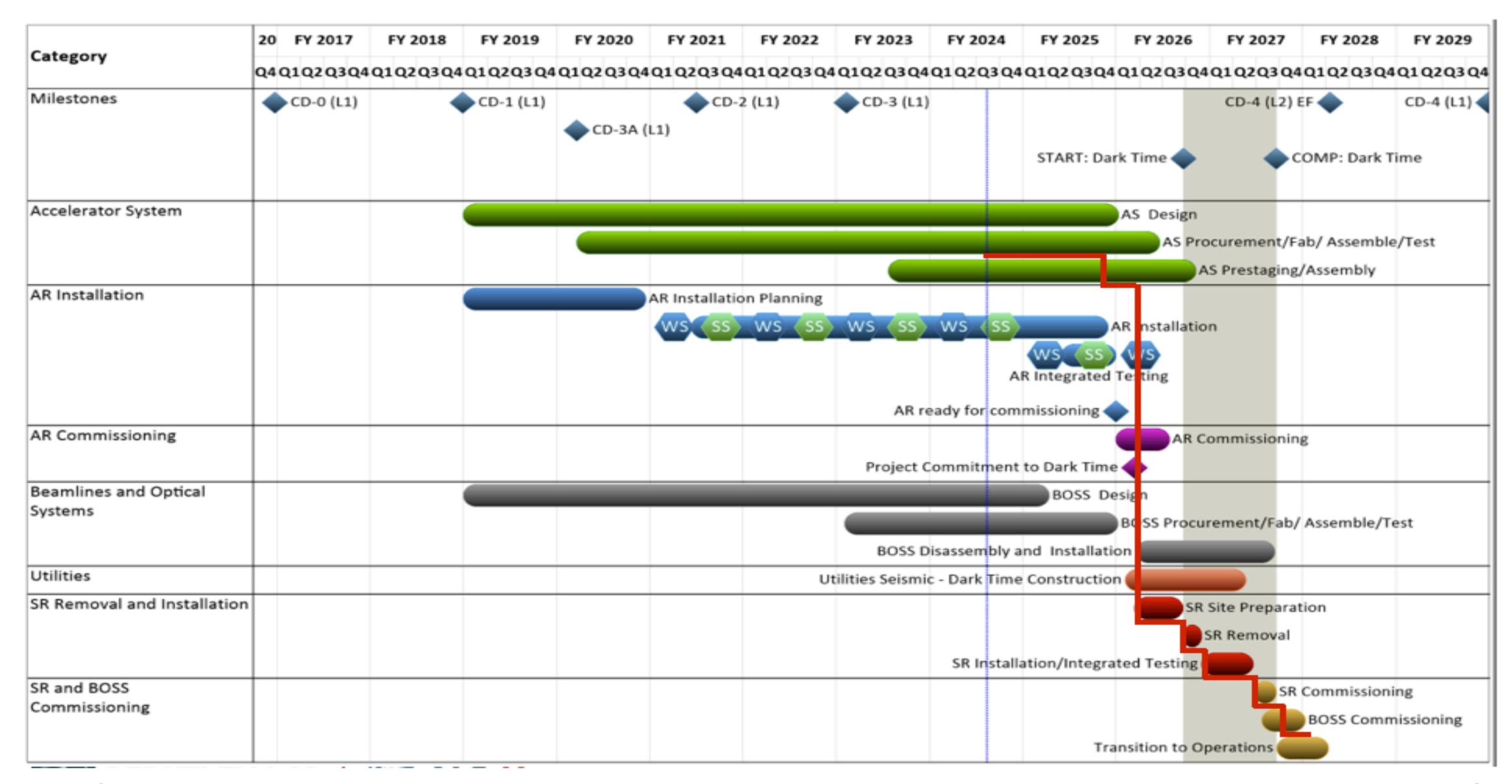
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# Overview of the ALS-U Accelerator Facility



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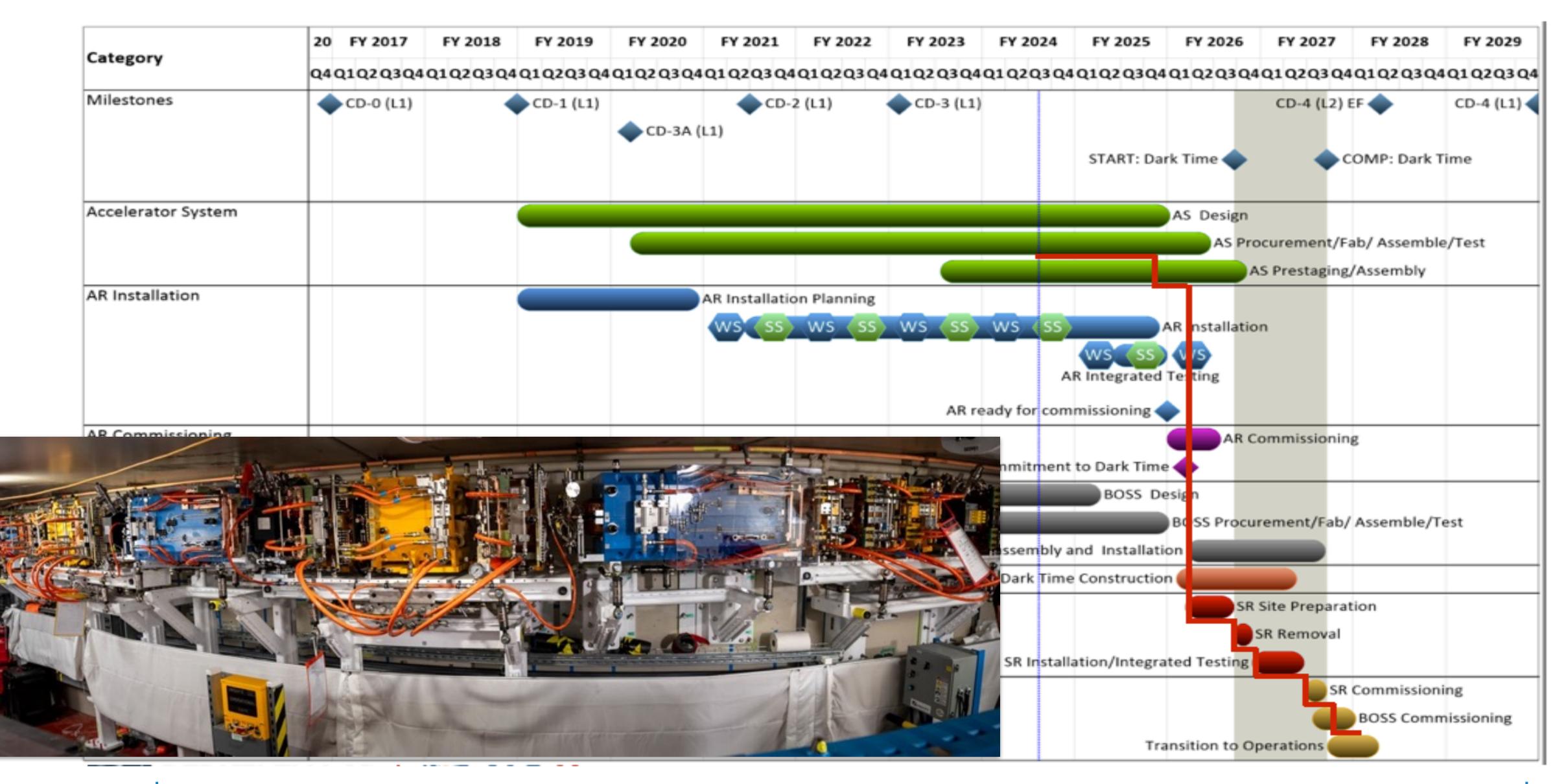
#### **ALS-U Schedule**





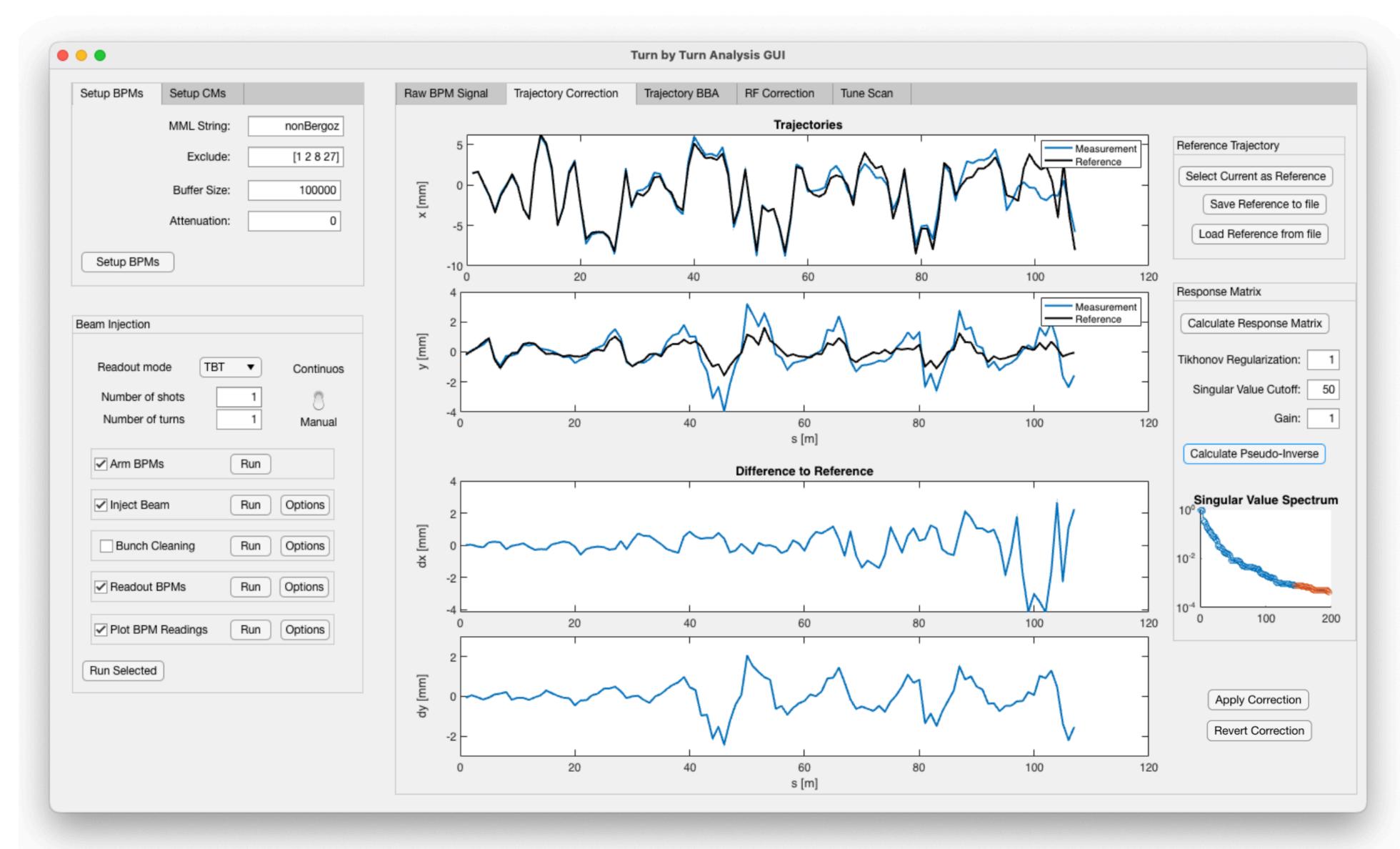


#### **ALS-U Schedule**





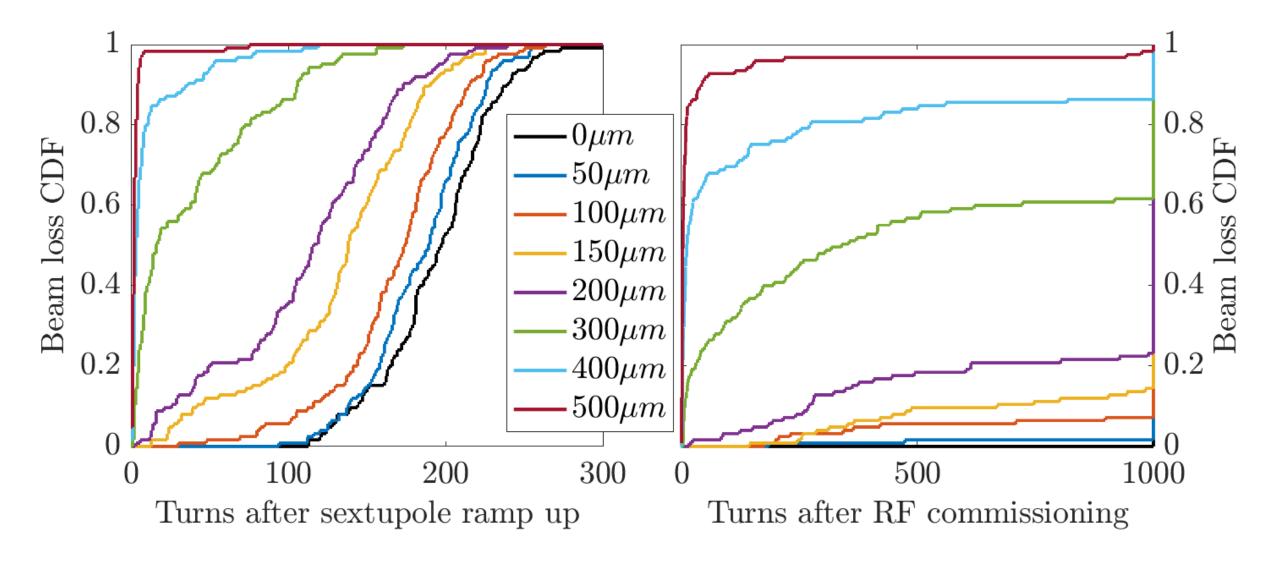
# **Turn-by-Turn Trajectory Correction / Beam Threading**

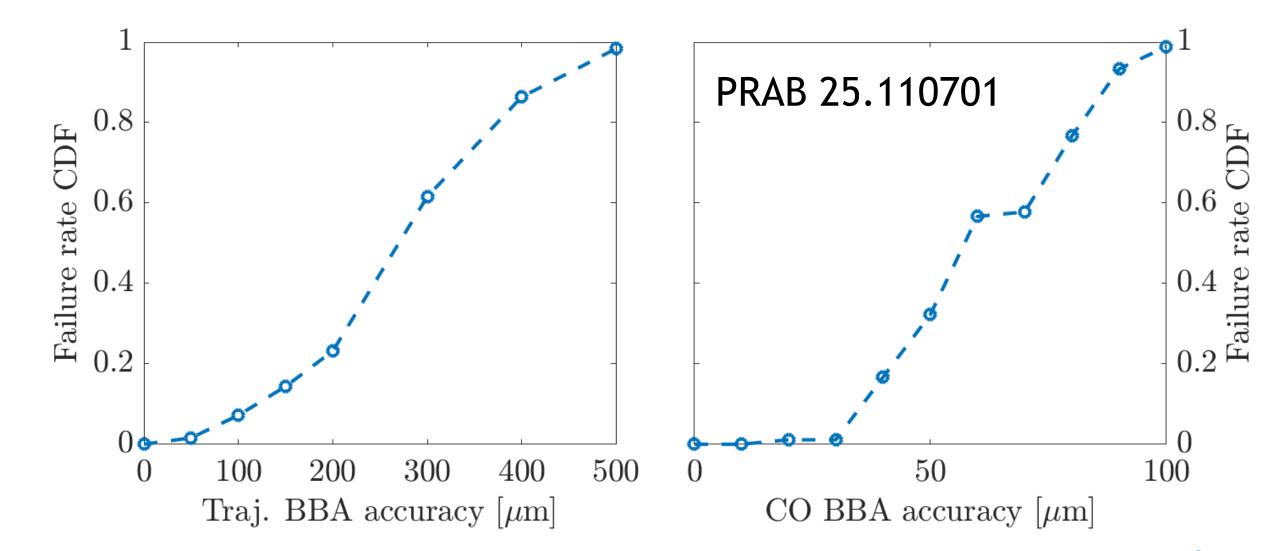


# Turn-by-Turn Beam Based Alignment

#### • Turn-by-Turn BBA Required for ALS-U

- Commissioning simulations for ALS-U Storage
   Ring show that without ~100um rms BPM offsets
   reliable beam capture can not be expected
- Initial BPM offsets to be expected at ~500um rms
- Turn by turn BBA routine mandatory for successful beam capture at ALS-U SR









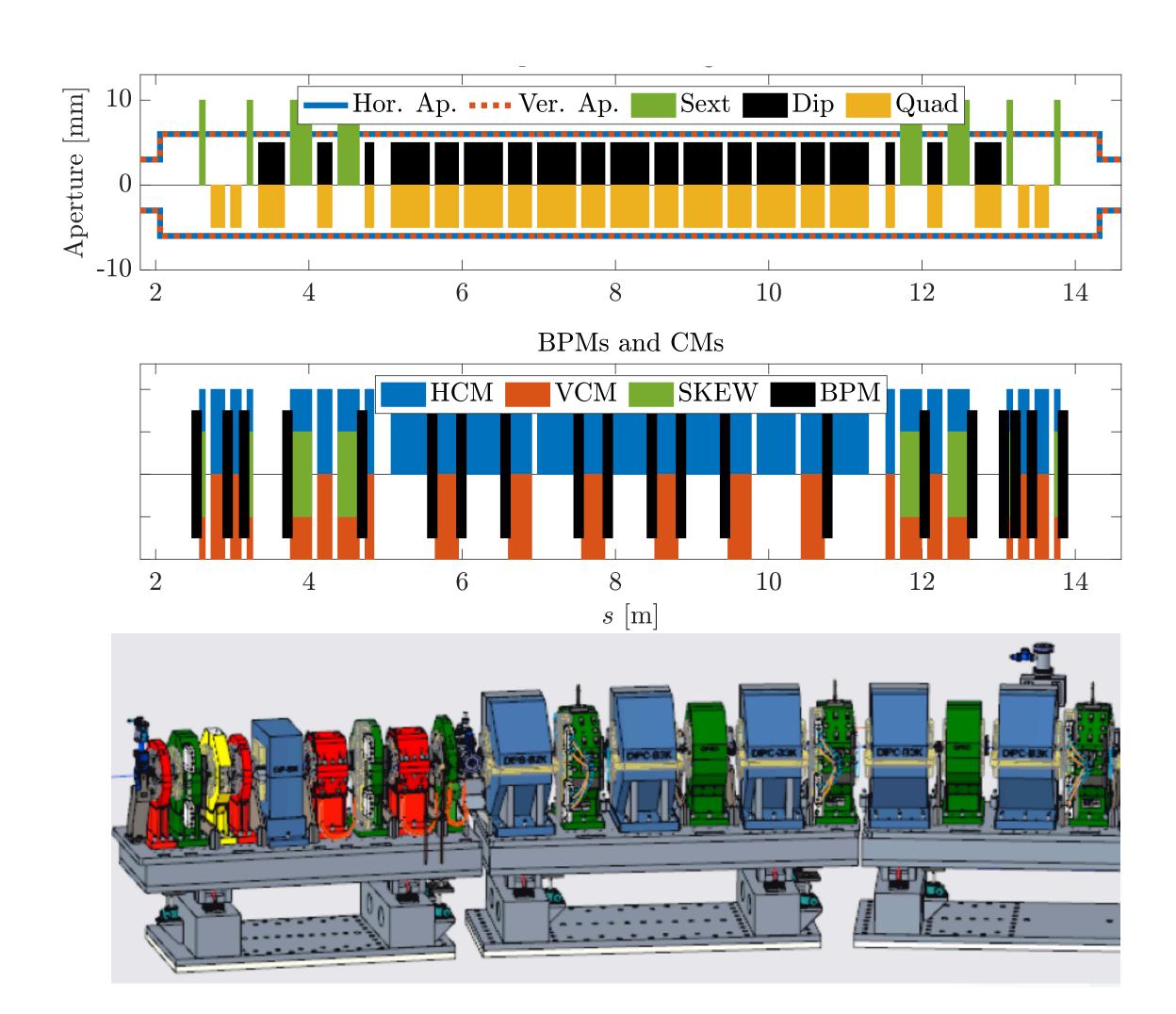
# Beam Dynamics Challenges

#### Tight space constraints

- Most correctors are embedded in combined function magnets
- Dipole field compensation critical for BBA

#### Little Margin for Errors

- Commissioning simulations show that the lifetime goal of 30min is met with little margin (including IDs)
- Hysteresis might become critical to compensate





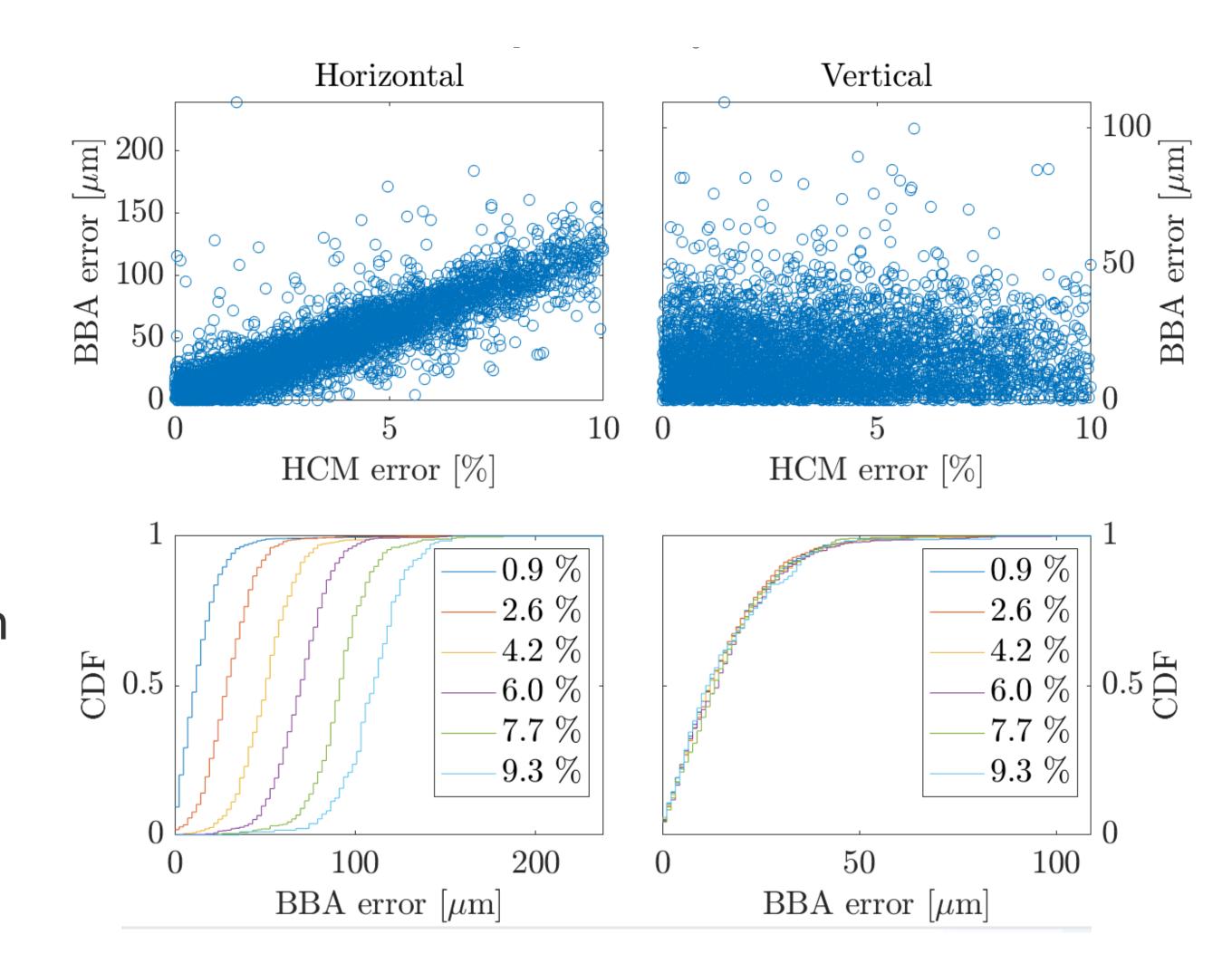
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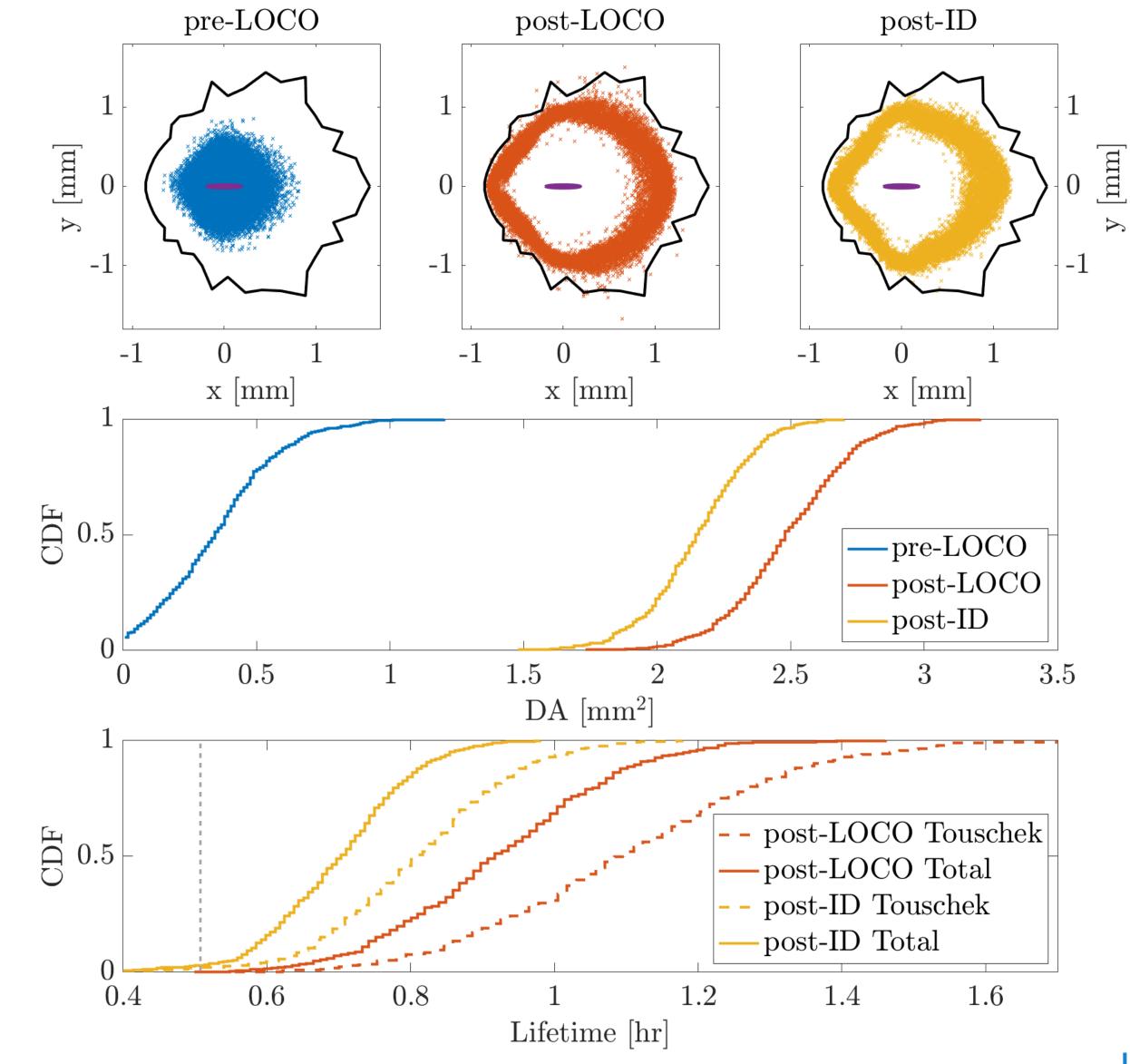
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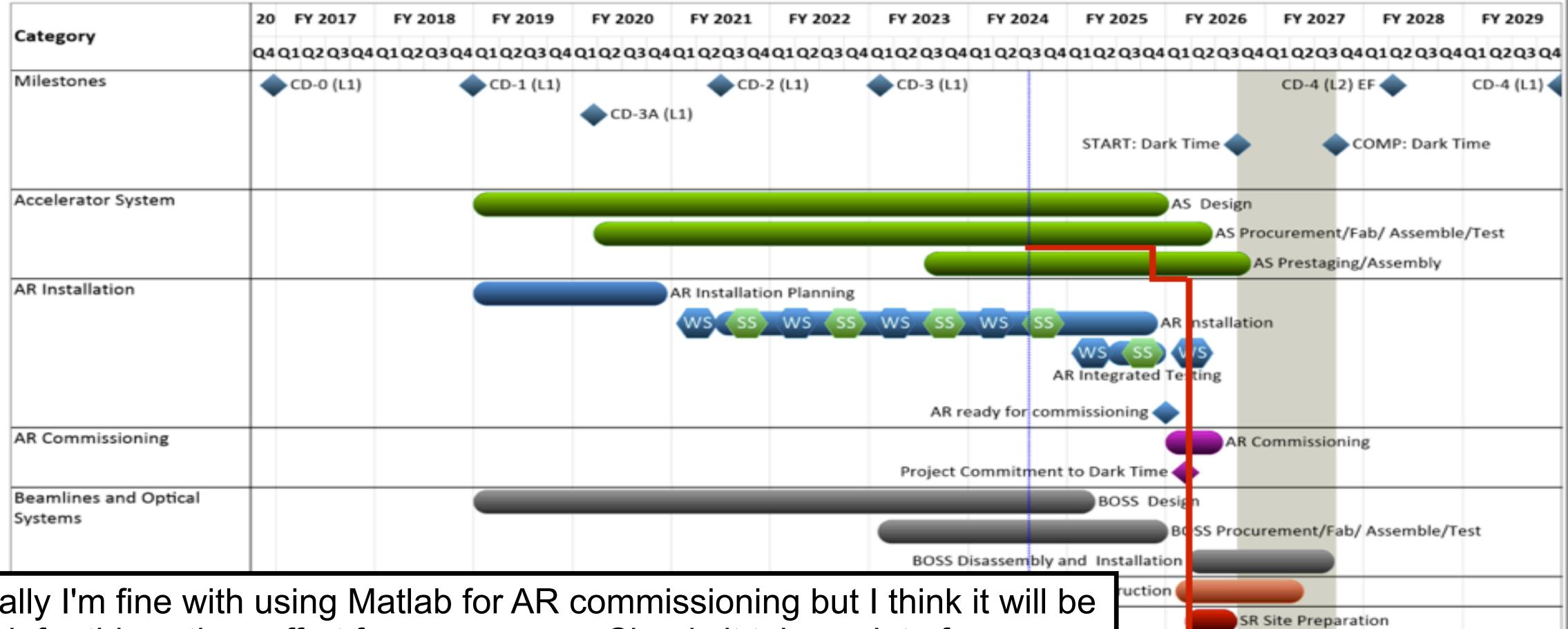
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#### Outlook



"Personally I'm fine with using Matlab for AR commissioning but I think it will be a setback for this python effort for many years. Clearly it takes a lot of debugging to roll out a new middlelayer and physics functions. Commissioning is a perfect time to do that debugging (after debugging on a simulator). The matlab mml was debugged on CLS and Spear3 commissioning."





ntegrated Testing

**Transition to Operations** 

SR Removal

SR Commissioning

**BOSS Commissioning**