

### TB22 ANALYSIS

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## **OVERVIEW**

- Telescope resolution
- Hough Transform (HT) uncertainty
- Calorimetry prelim



## **TELESCOPE RESOLUTION**

A second attempt

### GAAS HITS OUTSIDE PAD RECAP

Events of single track & single pad hit. Pad-based color assignment.





### **TELESCOPE RESOLUTION**

Idea – use hits on the traces to get the telescope resolution.

- Choose events with (x, y) position far above the assigned pad.
- Plot a histogram of their x value given by the telescope.
- The standard deviation is the telescope resolution (neglecting the trace width).

The result is  $\sim$ 50 microns.



х<sub>т</sub> [mm]



## HT UNCERTAINTY

Update & Summary

## HT – FIND LINE EQUATION



## STATISTICAL UNCERTAINTY

### Get line parameters distribution Fit Gaussian $\rightarrow$ get mpv



Subdivide data to get distribution of mpv  $\rightarrow$  std of the mpv distribution is the algorithm's uncertainty



- Generated random points from a uniform distribution on a horizontal line.
- Smeared points with  $\sigma$  values of 10, 20, ..., 100 microns.
- Ran the alignment algorithm on the smeared dataset and got the uncertainty.

• In addition, checked the effect of changing the parameters of the algorithm, and statistics.

Values are nicely distributed around 0



The uncertainty for a given smearing  $\sigma$  slightly varies, but it is always at the level of a few microns and hence negligible.



Data smearing  $\sigma$  [ $\mu$ m]

Higher statistics give smaller uncertainties, but are still at the order of a few microns



## HT UNCERTAINTY - CONCLUSION

- Statistics is the main variable affecting the algorithm's uncertainty
- The algorithm's uncertainty is at the level of a few microns
- The alignment's uncertainty is dominated by the telescope resolution



### CALORIMETRY

Preliminary

### DEBUG DATA ON

Calorimetry files:

- $\sim 1/_2$  million events
- $\sim$  300,000 empty events
- $\sim$  150,000 events with data



### NUMBER OF PADS HIT



number of W plates

### NUMBER OF PADS HIT

Based on a Molière radius of about 9mm, if the particle hit in the center of a pad, we expect to see about 25 pads hit.

Other hit positions will give a lower number.

Plot to the right shows the number of events with more than 25 pads hit, per layer.



CALICE



number of pads hit - limited

- Events with up to 25 pads
- Full sized plots, layer-by-layer, are available at the end of the presentation

GaAs



number of pads hit - limited

- Events with up to 25 pads
- Full sized plots, layer-by-layer, are available at the end of the presentation

#### CALICE - number of hits - log scale



#### GaAs - number of hits - log scale



Pads below the beam center are hit more often than those above

 $\rightarrow$  Traces ?

- 10<sup>3</sup>

### **AVERAGE ADC COUNT**



number of W plates

#### CALICE - average ADC count



#### GaAs - average ADC count



### SUMMARY

- Traces-based telescope resolution calculation 50  $\mu m$
- Alignment precision is dominated by the telescope resolution
- Calorimetry:
  - Traces seem to cause additional pads hit with lower ADC count.
  - Total ADC count in GaAs is on average higher than CALICE to be further investigated

### THANK YOU!



A pixelated flower in reference to the previous slides

## BACKUP

### TRACES BASED EFFECTS



## ALIGNMENT GOAL

Translate global position given by the telescope to a local position on the sensor.

Local coordinate system agreed – units of pad length

• e.g. (7.25, 2.5) is located as such pad (7, 2):



# ALIGNMENT METHODS

### <u>Max hits in pad</u>

Set a grid and find the position that gives the highest number of hits in the correct pad. Input data – events of a single electron & a single hit.

### <u>Hough Transform</u>

Used as a line recognition algorithm to find the edges of the pads.

Input data – single electron events that hit in between pads (to get a good "image" of the edges).

### MAX HITS



## HOUGH TRANSFORM

- Shape detecting framework
- Used a slight variation of the original

### FIND RELEVANT AREA

The data is noisy, and we are only interested in a single line.

We don't want to consider all points, so we first find an estimation for the edge position.

Revisited – seems to miss some fine-tuning.



### Image and parameter space









GaAs

































GaAs













GaAs

















































CALICE





















