

Fine-tuning of MAPS Simulations with Hexagonal Pixel Designs

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Motivation



TANGERINE (Towards Next Generation Silicon Detectors) project aims the development of 65 nm CMOS MAPS (Monolithic Active Pixel Sensor) for future lepton collider and test beam telescopes.

(by simulations and prototype chip tests)

	(HL-) LHC (ATLAS/CMS)	Future Lepton Colliders
Material budget	10% X ₀	< 1% X ₀
Single-point resolution	~ 15 µm	≤ 3 µm
Time resolution	25 ns	~ ps – ns
Granularity	50 μm x 50 μm	≤ 25 µm x 25 µm

S. Spannagel, 93rd PRC

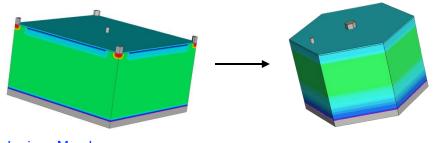
Hexagonal pixels

- ☐ Fewer number of neighboring pixels
- Reduced electric field effects from corners
- □ Reduced path between the corner and the electrode in the same area of pixels

TANGERINE requirements

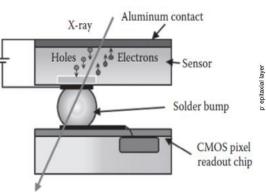
Parameter	Value
Single-point resolution	$< 3 \ \mu \mathrm{m}$
Time resolution	1 - 10 ns
Granularity	$<25~\mu\mathrm{m}\times25~\mu\mathrm{m}$
Particle rate	$1 \mathrm{\ MHz}$
Material budget	$< 0.05\% X_0$

For studying the possibility of using hexagonal pixels, we use the detailed simulations.

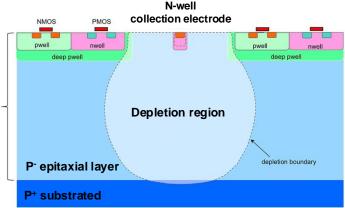


Monolithic Active Pixel Sensor (MAPS)

Conventional hybrid pixel detector



MAPS Standard



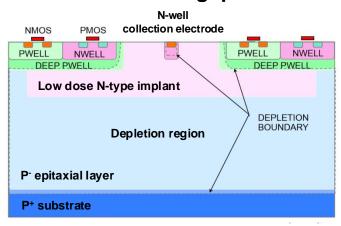
https://doi.org/10.1109/NSSMIC.2017.8533085

https://doi.org/10.1016/j.nima.2017.07.046

- P-type epitaxial layer (epi-layer) with lower doping concentration than p-type Si substrate
- → high-resistivity, depletion region*
- □ Small n-well collection electrode
- Employing commercial CMOS circuitry for readout electronics (NMOS, PMOS)
- → low material budget, compactness
- ☐ N-gap: low dose n-type implantation
- → larger depletion region, higher efficiency

- P-type substrate
- Reverse bias voltage
- Not fully depleted

MAPS N-gap



https://doi.org/10.3390/instruments6040051

* Depletion region (backup #25)

Let's think about the PN junction.

We can assume that there're **no mobile charge carriers** in the middle of the n-side and p-side.

Any electron or hole entering this area will be swept out by the electric field.

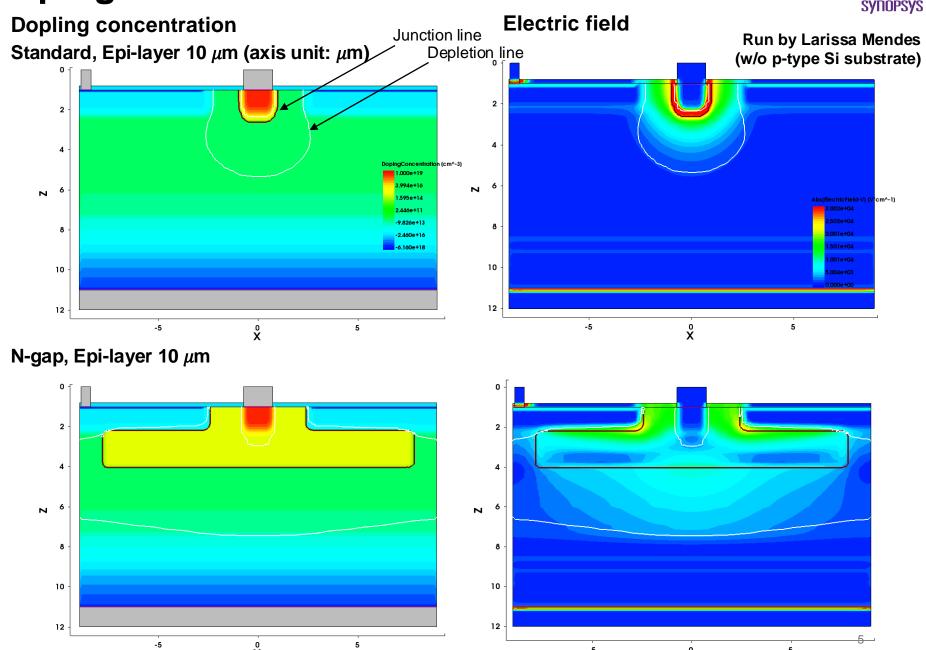
→ In this area, charges **move by drift not by diffusion.**

It attracts charges fast and strongly. When the reverse bias is applied to the PN diode, depletion region gets wider.

4

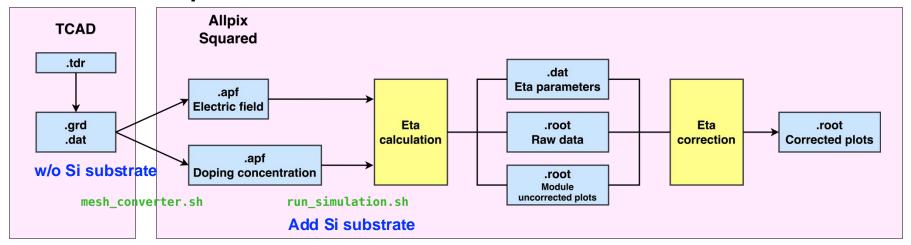
Doping Concentration and Electric Field

SYNOPSYS



Simulation

Data flow in Allpix²



Sentaurus TCAD

- SProcess: fabrication process simulation
- o **SDevice**: simulates numerically the electrical behaviour of a single semiconductor device
- SDE: 2D and 3D device structure editor, geometric operations

SYNOPSYS

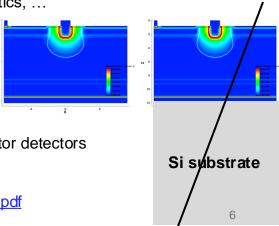
→ Doping concentration, electric field, mobility, electrical characteristics, ... https://www.synopsys.com/manufacturing/tcad.html



Monte Carlo simulations for semiconductor tracker and vertex detectors [2]

- Simulation of charge deposition and transport in semiconductor detectors
- o **Digitization** to hits in the frontend electronics
- Using Geant4 and ROOT

https://project-allpix-squared.web.cern.ch/usermanual/allpix-manual.pdf



Figures of Merit

: a quantity to characterize the performance of the MAPS

1. Cluster size

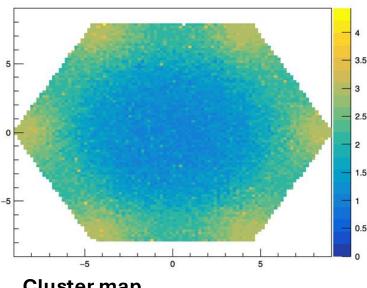
- Number of pixels in each reconstructed cluster (> 1)
- ☐ Shows the degree of charge sharing
- → Larger cluster size means higher charge sharing
- Mean cluster sizes across the full pixels are in the graphs.

2. Efficiency

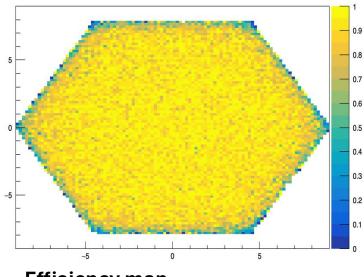
- □ How many particles generate signals compared to the number of the incident particles.
- \Box 0 ~ 1 (or 0 ~ 100 %)
- Mean efficiency across the full pixel are in the graphs.

3. Spatial resolution

☐ Difference between reconstructed cluster position and real particle position (residual)

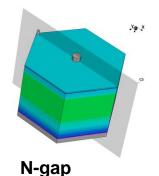






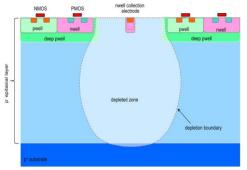
Efficiency map

Simulation Setup



Standard

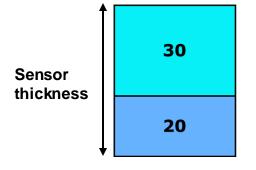


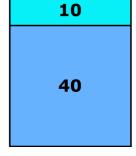


https://doi.org/10.1016/j.nima.2017.07 .046

NWELL COLLECTION ELECTRODE NWELL PWELL LOW DOSE N-TYPE IMPLANT DEPLETION BOUNDARY DEPLETED ZONE P" EPITAXIAL LAYER

https://doi.org/10.3390/instruments60 40051





Unit: um **Epi-layer** P-type Si substrate

Simulation type

Electrostatic

Incident particle

5 GeV electron beam

Geometry

Hexagonal

Events

100,000

Voltage supply

Collection electrode 1.2 V Backside electrode -1.2 V

Contact electrode -1.2 V

Pitch

10.00 μ m 18.00 μ m $25.00 \, \mu m$

Layout and epi-layer

Standard, Epi 30 μ m Standard. Epi $10 \, \mu \text{m}$ N-gap, Epi 30 μ m

N-gap,

Epi 10 μ m

1. Pitch and layout comparison

at 10 μ m epi-layer

2. Epi-layer and layout comparison at 18.00 μ m pitch

+ Integration time comparison

25 ns

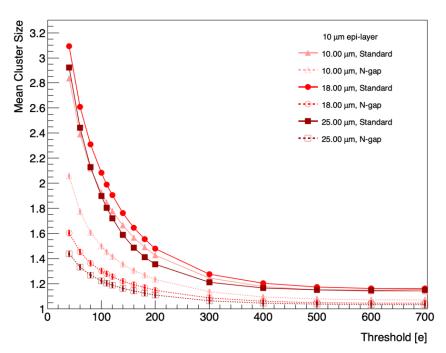
40 ns

 $5 \mu s$

Pixel size and Layout Comparison

(10 μ m epi-layer)

Cluster Size



25.00 μ m pitch has smaller cluster size for both layouts.

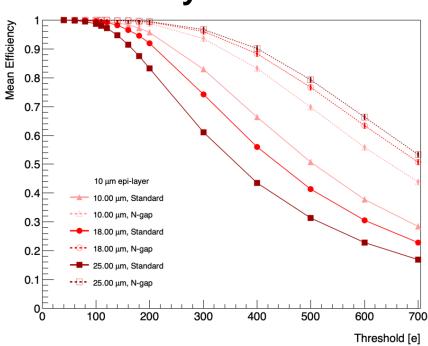
N-gap

- N-gap has smaller cluster size (less charge sharing) as expected
- o Cluster sizes are inversely proportional to the pitch.

Standard

o Cluster sizes are not proportional to the pitch.

Efficiency



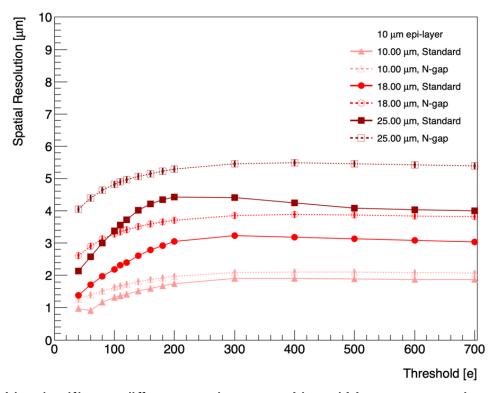
The highest efficiency in 25.00 μ m N-gap

- N-gap has higher efficiency than Standard as expected.
- N-gap efficiency is proportional to pitch size.
- Standard efficiency is inversely proportional to pitch size.

** More details are in the slide #20 (backup)

Residual in X: Spatial Resolution

(10 μ m epi, multiple pitch sizes)

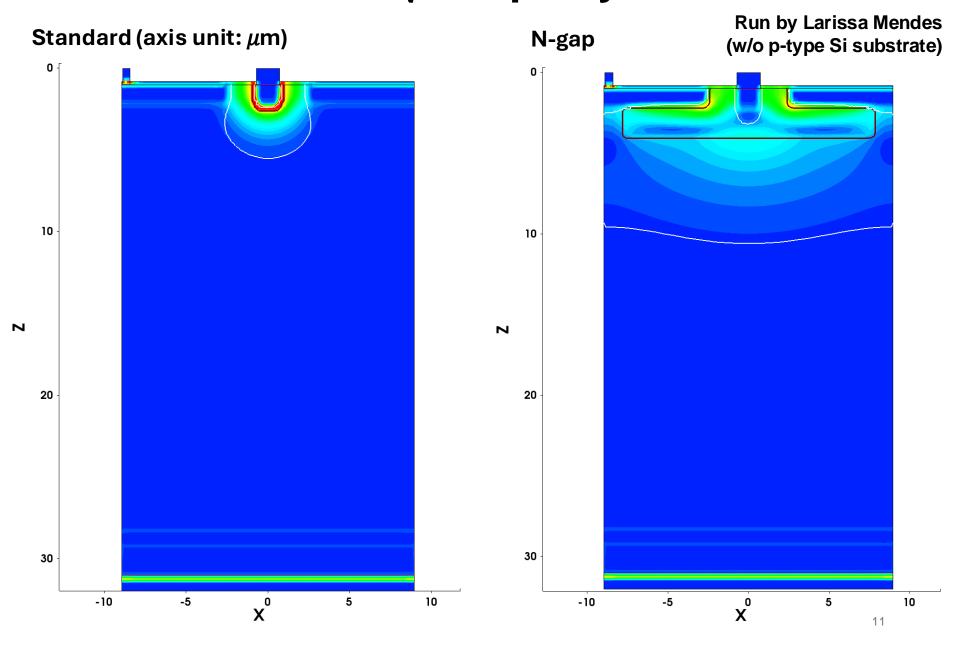


No significant differences between X and Y as expected.

- Standard has higher spatial resolution than N-gap as expected.
- If we use the smaller pitch we can overcome the layout differences as expected.

N-gap is more stable under 200e threshold.

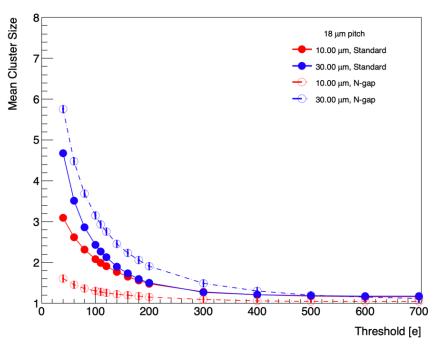
Electric Field in 30 μ m Epi-layer



Epitaxial Layer and Layout Comparison

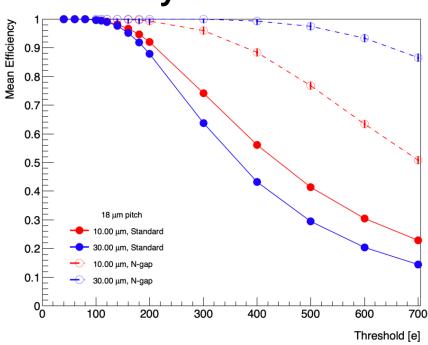
(18 μ m pitch, 25 ns integration time)

Cluster Size



 \circ 10 μ m has smaller cluster size than 30 μ m.

Efficiency

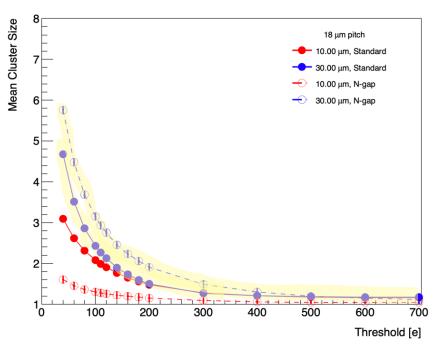


- \circ The highest efficiency in 30 μ m N-gap
- o N-gap has higher efficiency than Standard.

Out of Expectation

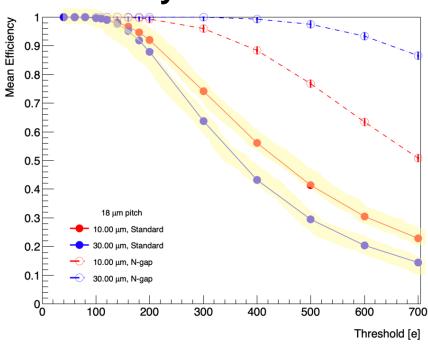
(18 μ m pitch, 25 ns integration time)

Cluster Size



- \circ 10 μ m has smaller cluster size than 30 μ m.
- \circ In 30 μ m, N-gap has bigger cluster size than Standard.

Efficiency



- \circ The highest efficiency in 30 μ m N-gap
- o N-gap has higher efficiency than Standard.
- \circ In Standard, 10 μ m is more efficient than the 30 μ m.

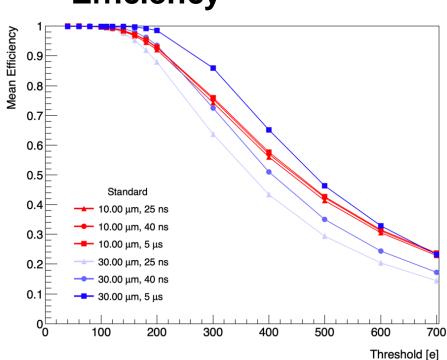
Integration Time Comparison

: 25 ns, 40 ns, 5 μ s in both epi-layer (standard, 18 μ m pitch)

Cluster Size

Mean Cluster Size Standard 12 10.00 μm, 25 ns 10.00 μm, 40 ns 0.00 μm, 5 μs 30.00 μm, 25 ns 30.00 μm, 40 ns --- 30.00 μm, 5 μs 300 400 500 600 700 100 200 Threshold [e]

Efficiency

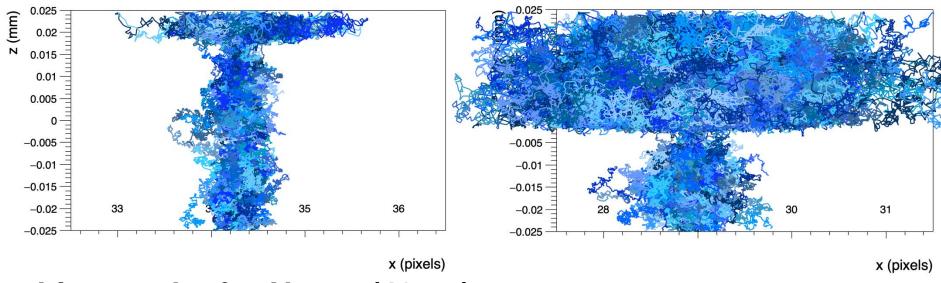


(No significant change in 10 μ m epi-layer.)

- \circ In 30 μ m, cluster size and efficiency increases with the integration time.
- \circ 30 μ m exceeds 10 μ m in efficiency at 5 μ s.

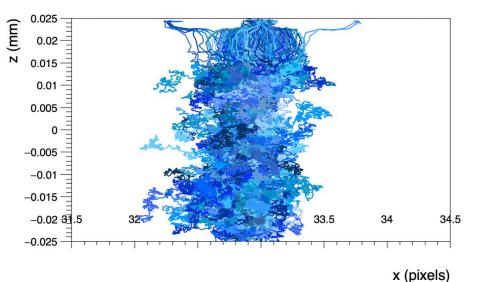
Linegraphs for Standard (40 ns)

10 μ m epi-layer 30 μ m epi-layer

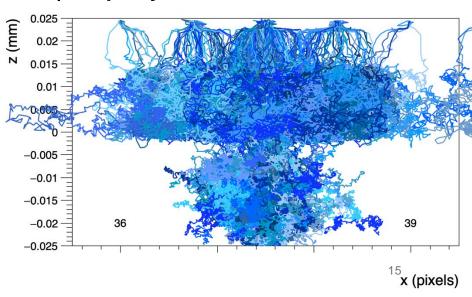


Linegraphs for N-gap (40 ns)

10 μ m epi-layer



30 μ m epi-layer

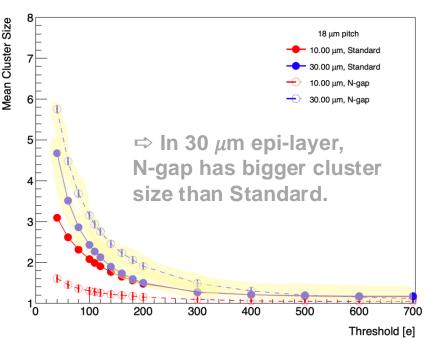


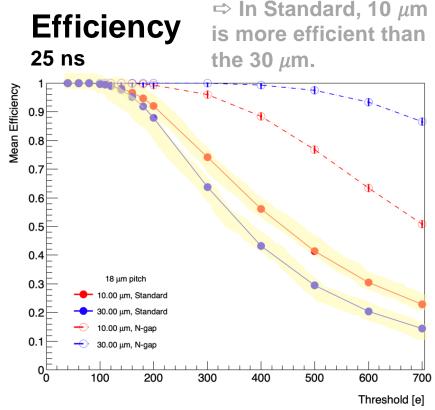
threshold: 60e

Now We Can Understand ...

(10 and 30 μ m epi-layer, 18 μ m pitch)

Cluster Size 25 ns





Explanation of 30 μ m: It makes wide diffusion

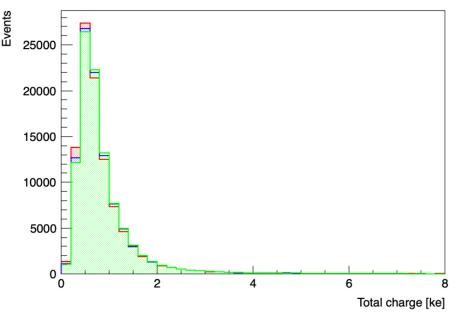
- In Standard, many charge carriers can be recombined before reaching the depletion region of the far pixel. That's why we lose efficiency rapidly as the thresholds increase.
- But in N-gap, it has larger depletion region. Thus, although they move widely by diffusion, carriers can easily reach the depletion region in far pixels and generate signals.
- \Box We can also explain why only the 30 μ m epi-layer is influenced by the integration time.

Total Charge Per Event

(25 ns, 40 ns, 5 μ s for standard in both epi-layer)

* Fit function: Landau distribution

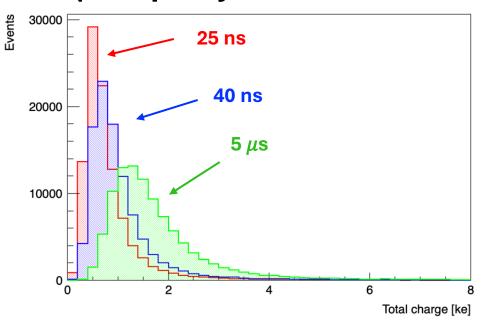
10 μ m epi-layer



Most probable value

10 μm		30 μm		
25 ns	5.00e-1	25 ns	4.96e-1	
40 ns	5.10e-1	40 ns	6.45e-1	
5 μs	5.15e-1	5 μs	1.16	

30 μ m epi-layer



In 30 μ m, charges diffuse for a long time going far pixels, and they couldn't be collected in the integration time.

This also supports our explaination!

Conclusion

- 1. In 10 μ m epi-layer, N-gap has smaller cluster size and higher efficiency. However, it shows worse spatial resolution compared to the Standard. (It's because larger cluster size makes reconstruction position more precise)
- 2. 30 μ m epi-layer shows unexpected behaviors in cluster size and efficiency.
- \circ In 30 μ m, N-gap has bigger cluster size than Standard.
- \circ In Standard, 10 μ m is more efficient than the 30 μ m.
- To investigate, we changed integration time and checked the charge and linegraphs. Only in the 30 μ m, cluster size and efficiency increases with the integration time.
- \rightarrow It's because 30 μ m epi-layer makes carriers diffuse widely and the Standard cannot collect them due to its small depletion region.

Backup

More Details

10 um epi-layer (slide #9, 10)

Efficiency proportionality

- □ N-gap: bigger pitch offers larger space for charge collection (depletion region)
- ☐ Standard: bigger pitch makes larger space out of depletion region. It worsens the efficiency.

This also can explain why the cluster sizes change easily with the pitch in N-gap compared to Standard.

** Comments from Håkan

Cluster size changes with pitches

As the pitch increases, there will be smaller room for charge sharing.

When efficiency gets lower, we also lose cluster size.

TCAD

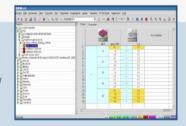
Finite element simulation

Sentaurus TCAD SYNOPSYS®
Silicon to Software

Technology Computer-Aided Design

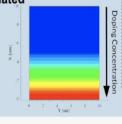
Sentaurus Workbench (SWB)

Can run large numbers of simulations conveniently



Sentaurus Process SPROCESS

Fabrication steps in semiconductor manufacturing can be simulated



Sentaurus Structure Editor SDE



Description of the geometry and doping using an editor

- Define geometry (Shape,material)
- Define doping profile (parametric description)

Sentaurus Device SDEVICE



Device Simulation to define thermal and electrical properties and extract:

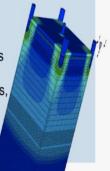
- Electric Field
- Capacitance
- Transient Behavior

Sentaurus Visual SVISUAL

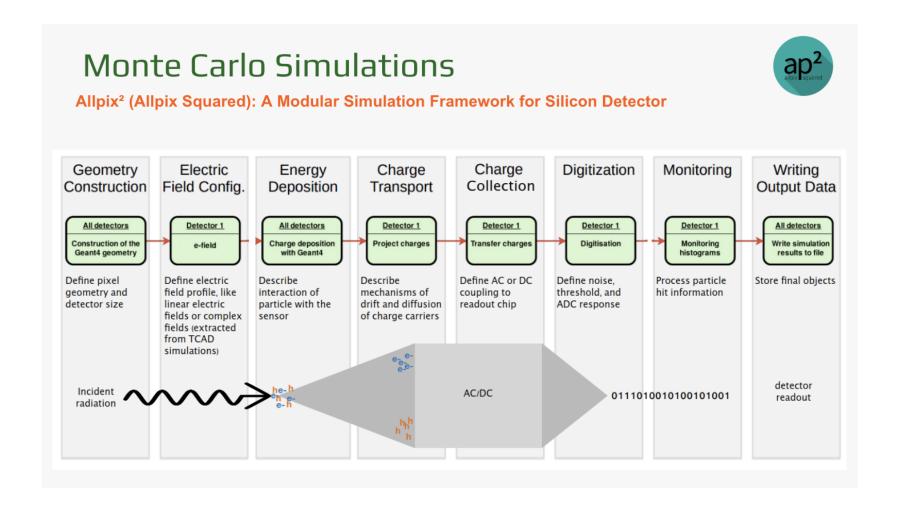


Post-Processing

 Plot and extract Profiles (Efield, Doping Concentration. I-V curves, C-V curves, etc.)



Allpix²



Larissa Mendes 22

Spatial Resolution

- \square RMS of 3σ (99.7 %) residual distribution
- Residual: difference between reconstructed cluster position and real particle position

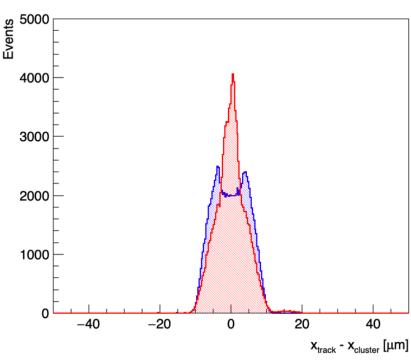
In Allpix² simulation,

□ Reconstructed cluster position: chargeweighted mean of a cluster

$$x = \frac{\sum_{i} x_i q_i}{\sum_{i} q_i}$$

- □ Real particle position: randomly drawn position from a Gaussian distribution
- □ Bigger cluster size leads to the smaller spatial resolution because it makes more precise reconstructed position

 \Box We use an η -correction



Residual distribution

: Before (blue) and after (red) η -correction

Deep P-well

In real, NMOS, PMOS → p-well → deep p-well structure.

(In TCAD simulation, we use it without CMOS.)

P-well is bigger than deep p-well for more space for charge collection.

Epitaxial Layer

Epitaxy (prefix *epi*- means "on top of") refers to a type of crystal growth or material deposition in which new <u>crystalline</u> layers are formed with one or more well-defined orientations with respect to the crystalline seed layer.

TCAD Files

*.grd: grid file. Structure of mesh.

*.dat: contain variables such as e-field potential and carrier concentrations at every mesh point in the device.

Depletion Region

With the reverse bias voltage (ref. G. Lutz, Semiconductor Radiation Detectors)

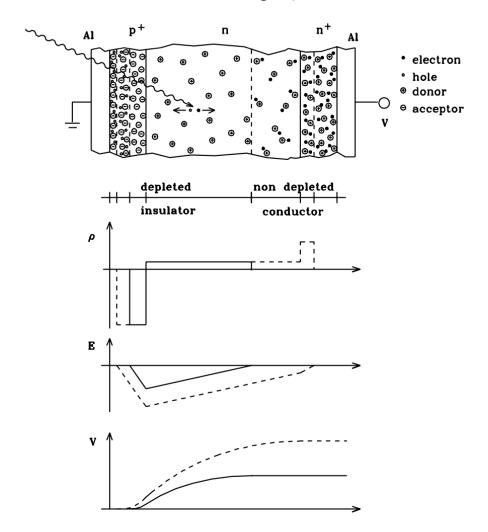


Fig. 5.2. A p-n diode junction detector: charge density, electric field and potential for partial (continuous line) and full (dashed line) depletion