# Flows of geometric structures

Shubham Dwivedi Universität Hamburg

QU Days February 20, 2025 What do we mean by a geometric structure?

#### What do we mean by a geometric structure?

Let  $(M^n, g)$  be an *n*-dimensional smooth Riemannian manifold  $\rightsquigarrow$  for all  $p \in M$ , we have an *n*-dimensional real vector space  $T_pM$  equipped with a positive-definite inner product  $g_p$ , and these "vary smoothly" with  $p \in M$ .

#### What do we mean by a geometric structure?

Let  $(M^n, g)$  be an *n*-dimensional smooth Riemannian manifold  $\rightsquigarrow$  for all  $p \in M$ , we have an *n*-dimensional real vector space  $T_pM$  equipped with a positive-definite inner product  $g_p$ , and these "vary smoothly" with  $p \in M$ .

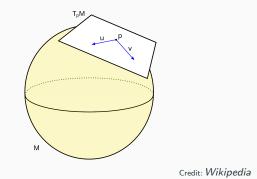


Figure 1: Tangent space at a point in  $\mathbb{S}^2$ 

What other "natural structures" can we put on Riemannian manifolds?

i.e., we would like to attach such a "natural structure" to each tangent space  $T_pM$ , for all  $p \in M$ , in a "smoothly varying" way.

What other "natural structures" can we put on Riemannian manifolds?

i.e., we would like to attach such a "natural structure" to each tangent space  $T_pM$ , for all  $p \in M$ , in a "smoothly varying" way. Some examples:

1) Orientation on a vector space (manifold)

What other "natural structures" can we put on Riemannian manifolds?

i.e., we would like to attach such a "natural structure" to each tangent space  $T_pM$ , for all  $p \in M$ , in a "smoothly varying" way. Some examples:

1) Orientation on a vector space (manifold)  $\rightsquigarrow 0 \neq \mu \in \Gamma(\Lambda^n(T^*M))$ , SO(n)  $\leq$  O(n) preserves  $\mu$ .

What other "natural structures" can we put on Riemannian manifolds?

i.e., we would like to attach such a "natural structure" to each tangent space  $T_pM$ , for all  $p \in M$ , in a "smoothly varying" way. Some examples:

1) Orientation on a vector space (manifold)  $\rightsquigarrow 0 \neq \mu \in \Gamma(\Lambda^n(T^*M))$ , SO(n)  $\leq$  O(n) preserves  $\mu$ .

2) Hermitian structure on a vector space (manifold)

What other "natural structures" can we put on Riemannian manifolds?

i.e., we would like to attach such a "natural structure" to each tangent space  $T_pM$ , for all  $p \in M$ , in a "smoothly varying" way. Some examples:

1) Orientation on a vector space (manifold)  $\rightsquigarrow 0 \neq \mu \in \Gamma(\Lambda^n(T^*M))$ , SO(n)  $\leq$  O(n) preserves  $\mu$ .

2) Hermitian structure on a vector space (manifold)  $n = 2m, \rightsquigarrow J \in \Gamma(End(TM)), J^2 = -Id, J$  compatible with g,  $U(m) = SO(2m) \cap GL(m, \mathbb{C})$  preserves J.

In 1955, Berger classified all possible holonomy groups.

#### In 1955, Berger classified all possible holonomy groups.

Dimension	Holonomy group	Remarks
n	SO(n)	Generic Riemannian manifold
2m	U(m)	Kähler
2m	SU(m)	Calabi-Yau
4q	Sp(q)	Hyper-Kähler
4q	$\operatorname{Sp}(q) \cdot \operatorname{Sp}(1)$	Quaternionic-Kähler
7	G <sub>2</sub>	G <sub>2</sub> -holonomy
8	Spin(7)	Spin(7)-holonomy

#### In 1955, Berger classified all possible holonomy groups.

Dimension	Holonomy group	Remarks
n	SO(n)	Generic Riemannian manifold
2m	U(m)	Kähler → C
2m	SU(m)	Calabi-Yau → C
4q	Sp(q)	Hyper-Kähler $\rightsquigarrow \mathbb{H}$
4q	$\operatorname{Sp}(q) \cdot \operatorname{Sp}(1)$	Quaternionic-Kähler $\rightsquigarrow \mathbb{H}$
7	G <sub>2</sub>	$G_2$ -holonomy $\rightsquigarrow \mathbb{O}$
8	Spin(7)	$\operatorname{Spin}(7)$ -holonomy $\rightsquigarrow \mathbb{O}$

Examples:

- Riemannian metric g: "Best" could mean Ricci-flat: Ric(g) = 0.
- Immersion  $i: L \to (M, g)$ : "Best" could mean minimal: H(i) = 0.

The notion of "best" is usually described by the object u satisfying some geometric nonlinear PDE (often elliptic) of the form P(u) = 0. Usually, the PDE is (tried to be) modeled on the heat equation.

Examples:

- Riemannian metric g: "Best" could mean Ricci-flat: Ric(g) = 0.
- Immersion  $i: L \to (M, g)$ : "Best" could mean minimal: H(i) = 0.

The notion of "best" is usually described by the object u satisfying some geometric nonlinear PDE (often elliptic) of the form P(u) = 0. Usually, the PDE is (tried to be) modeled on the heat equation.

If we start with some  $u_0$  that doesn't satisfy our "best" condition, we can try to evolve it in time as u(t) in some geometric fashion, to hopefully improve it to be "closer to best". This is a geometric flow:

$$\frac{\partial}{\partial t}u(t)=P(u(t)), \qquad u(0)=u_0.$$

Examples:

- Riemannian metric g: "Best" could mean Ricci-flat: Ric(g) = 0.
- Immersion  $i: L \to (M, g)$ : "Best" could mean minimal: H(i) = 0.

The notion of "best" is usually described by the object u satisfying some geometric nonlinear PDE (often elliptic) of the form P(u) = 0. Usually, the PDE is (tried to be) modeled on the heat equation.

If we start with some  $u_0$  that doesn't satisfy our "best" condition, we can try to evolve it in time as u(t) in some geometric fashion, to hopefully improve it to be "closer to best". This is a geometric flow:

$$\frac{\partial}{\partial t}u(t)=P(u(t)), \qquad u(0)=u_0.$$

Ricci Flow:  $\frac{\partial}{\partial t}g(t) = -2\operatorname{Ric}(g(t)),$ Mean Curvature Flow:  $\frac{\partial}{\partial t}i(t) = -H(i(t)).$  Given a geometric flow  $\partial_t u(t) = P(u(t))$  with  $u(0) = u_0$ , we ask:

**Q** 1. Does it have short time existence and uniqueness? That is, does there exist an  $\varepsilon > 0$  and a unique solution on  $[0, \varepsilon)$ ?

Given a geometric flow  $\partial_t u(t) = P(u(t))$  with  $u(0) = u_0$ , we ask:

**Q** 1. Does it have short time existence and uniqueness? That is, does there exist an  $\varepsilon > 0$  and a unique solution on  $[0, \varepsilon)$ ?

**Q** 2. Does it have long time existence? That is, can we take  $\varepsilon = \infty$ ? Usually not. Geometric flows develop singularities in finite-time. Something bad happens at the "singular time"  $\tau$ . Given a geometric flow  $\partial_t u(t) = P(u(t))$  with  $u(0) = u_0$ , we ask:

**Q** 1. Does it have short time existence and uniqueness? That is, does there exist an  $\varepsilon > 0$  and a unique solution on  $[0, \varepsilon)$ ?

**Q** 2. Does it have long time existence? That is, can we take  $\varepsilon = \infty$ ? Usually not. Geometric flows develop singularities in finite-time. Something bad happens at the "singular time"  $\tau$ .

**Q** 3. If it has LTE, does it converge? That is, does  $\lim_{t\to\infty} u(t)$  exist? Some flows exhibit stability: If we start "close enough" to a fixed point, then we have LTE/convergence to the fixed point modulo diffeomorhisms.

Ricci flow of a family of metrics g(t),  $\partial_t g(t) = -2 \operatorname{Ric}(g(t)) \rightsquigarrow \operatorname{most}$  successful and well-studied.

# **Ricci flow of metrics**

Ricci flow of a family of metrics g(t),  $\partial_t g(t) = -2 \operatorname{Ric}(g(t)) \rightsquigarrow \operatorname{most}$  successful and well-studied.

Introduced by Richard Hamilton in 1982 as a way to tackle the Poincaré conjecture



Figure 2: Hamilton

# **Ricci flow of metrics**

Ricci flow of a family of metrics g(t),  $\partial_t g(t) = -2 \operatorname{Ric}(g(t)) \rightsquigarrow \operatorname{most}$  successful and well-studied.

Introduced by Richard Hamilton in 1982 as a way to tackle the Poincaré conjecture



Figure 2: Hamilton

# Poincaré conjecture (1903)

Every three-dimensional topological manifold which is closed, connected, and has trivial fundamental group is homeomorphic to the three-dimensional sphere.



Figure 3: Shrinking  $\mathbb{S}^2$  under Ricci flow



Figure 3: Shrinking  $\mathbb{S}^2$  under Ricci flow



Figure 4: Static flat  $\mathbb{T}^2$  under Ricci flow



Figure 3: Shrinking  $\mathbb{S}^2$  under Ricci flow



#### Figure 4: Static flat $\mathbb{T}^2$ under Ricci flow



Figure 5: Expanding  $\mathbb{T}^2 \# \mathbb{T}^2$  under Ricci flow

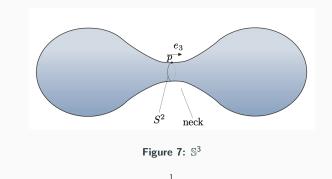


Figure 6: Product  $\mathbb{S}^2\times\mathbb{R}$  under Ricci flow

<sup>&</sup>lt;sup>1</sup>credit: Prof. Peter Topping



Figure 6: Product  $\mathbb{S}^2\times\mathbb{R}$  under Ricci flow



<sup>1</sup>credit: Prof. Peter Topping

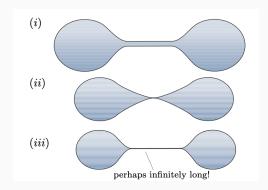


Figure 8: Neck pinch

credit:Prof.PeterTopping

• Short time existence and uniqueness of solutions - deep work of Hamilton, 1982 and later by DeTurck, 1984.

• Short time existence and uniqueness of solutions - deep work of Hamilton, 1982 and later by DeTurck, 1984.

long time existence and/or singularities - vary case by case by pretty well understood in dimensions 2, 3.

• Short time existence and uniqueness of solutions - deep work of Hamilton, 1982 and later by DeTurck, 1984.

long time existence and/or singularities - vary case by case by pretty well understood in dimensions 2, 3.

Convergence and if yes, to what?- very complex.

• Short time existence and uniqueness of solutions - deep work of Hamilton, 1982 and later by DeTurck, 1984.

long time existence and/or singularities - vary case by case by pretty well understood in dimensions 2, 3.

Convergence and if yes, to what?- very complex.

#### Theorem (Perelman, 2003)

The Poincaré conjecture is true and the Ricci flow (with surgery!) on <u>any</u> connected, compact, simply connected 3-manifold converges to the round sphere  $\mathbb{S}^3$ .

# Definition

A Spin(7)-structure on an 8-manifold is a special 4-form  $\Phi$  which induces a Riemannian metric, orientation and also gives a spin structure.

# Definition

A Spin(7)-structure on an 8-manifold is a special 4-form  $\Phi$  which induces a Riemannian metric, orientation and also gives a spin structure.

#### Definition

Let  $(M^8, \Phi)$  be a manifold with a Spin(7)-structure  $\Phi$  and let  $\nabla$  be the Levi-Civita connection of  $g_{\Phi}$ . We call  $(M, \Phi)$  a Spin(7)-manifold if  $\nabla \Phi = 0$ . This is a nonlinear equation on  $\Phi$ .  $\nabla \Phi$  is interpreted as the torsion T of the Spin(7)-structure

Spin(7)-manifolds, i.e., those having torsion-free Spin(7)-structure  $\Phi$  are always Ricci-flat and have special holonomy contained in the Lie group Spin(7) $\subset$  SO(8). Also admit parallel spinors  $\rightsquigarrow$  important in physics.

It is the negative gradient flow of the functional  $\Phi \mapsto \frac{1}{2} \int_{M} |\nabla \Phi|^2_{g_{\Phi}} \operatorname{vol}_{\Phi}$ .

It is the negative gradient flow of the functional  $\Phi \mapsto \frac{1}{2} \int_{M} |\nabla \Phi|^2_{g_{\Phi}} \operatorname{vol}_{\Phi}$ .

#### Theorem (D., '24)

The flow of Spin(7)-structures mentioned above has short-time existence and uniqueness of solutions on any compact  $(M^8, \Phi_0)$ .

It is the negative gradient flow of the functional  $\Phi \mapsto \frac{1}{2} \int_{M} |\nabla \Phi|^2_{g_{\Phi}} \operatorname{vol}_{\Phi}$ .

```
Theorem (D., '24)
```

The flow of Spin(7)-structures mentioned above has short-time existence and uniqueness of solutions on any compact  $(M^8, \Phi_0)$ .

Thus, we answer Q 1. in the affirmative and the study of other problems related to the flow is work in progress.

# Thank you for your attention.