



# Synchronisation and Beam Stabilisation – Midterm Plans –

Mini Workshop – UKFEL/EuXFEL & DESY Collab.

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on behalf of group for accelerator beam controls

5<sup>th</sup> of December 2024

# Optical Synchronisation & Beam-based Stabilisation

@European XFEL

Status

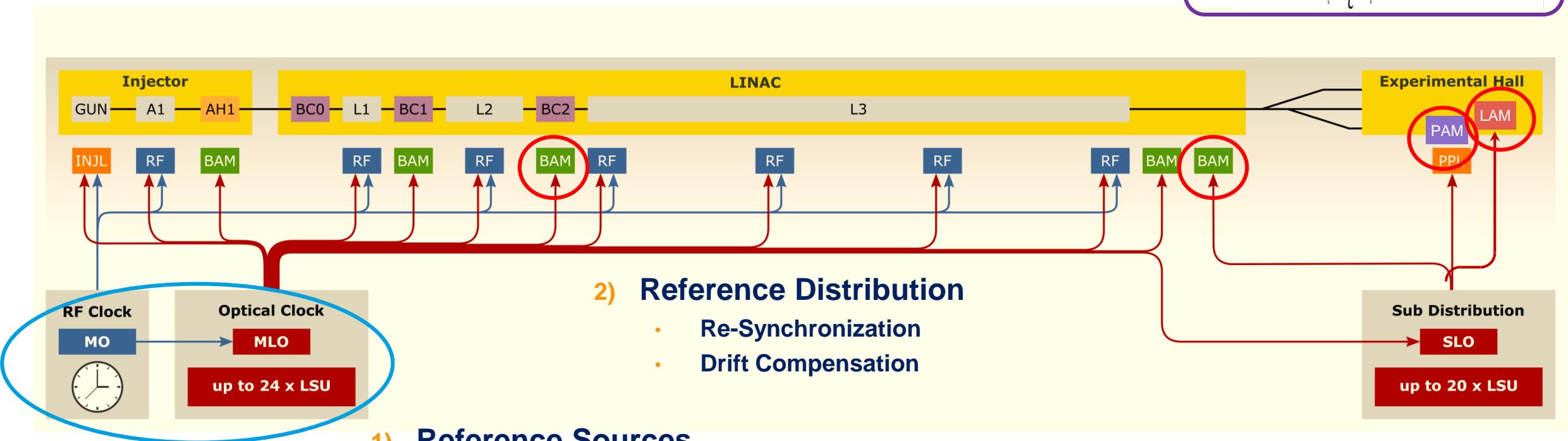
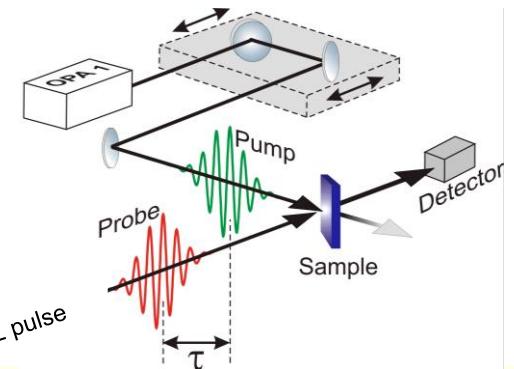
# Hybrid Synchronisation System

RF Backbone + Optical Long-haul Links for Highest Performance.

## Sources of timing jitter

- Short range 1 us...1ms PS, EMI, Material Properties, ...
- Mid range 1ms...10s Acoustic, Fans, Seismic, Air/Water flow,
- Long range 10s ... days Temperature, Rel. Humidity, Air Pressure, ...

Time-resolved,  
Pump-probe Experiments



## 1) Reference Sources

- Main RF Oscillator (MO)
- Main Laser Oscillator (MLO)

- 3) Arrival-time Detection
- 4) Beam-based Feedbacks

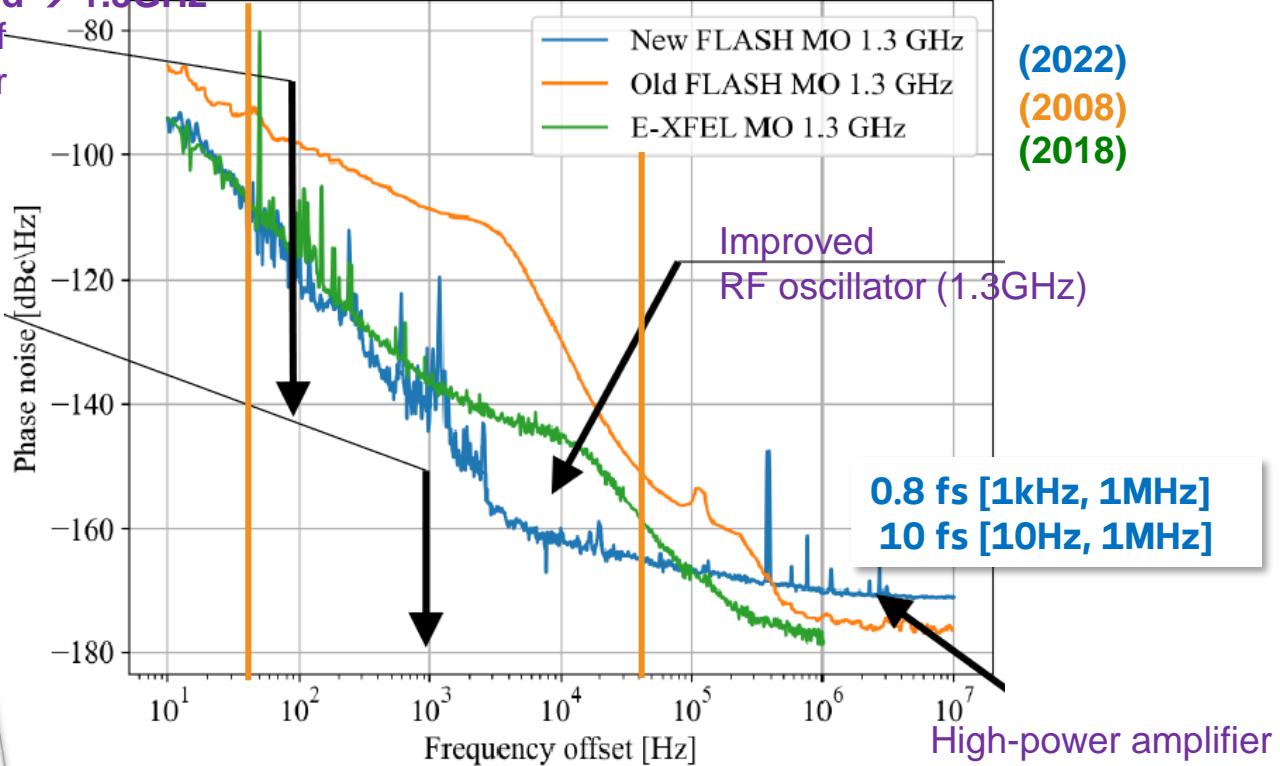
# Reference Sources

## Ultra-Low Absolute Phase Noise.

**MO** RF Oscillator,  
9MHz, GPS disciplined → 1.3GHz

Choice of  
quartz clock oscillator

Vibration  
damping



MLO is commercially available  
<https://kvg-gmbh.de>

Cooperation in between DESY and WUT

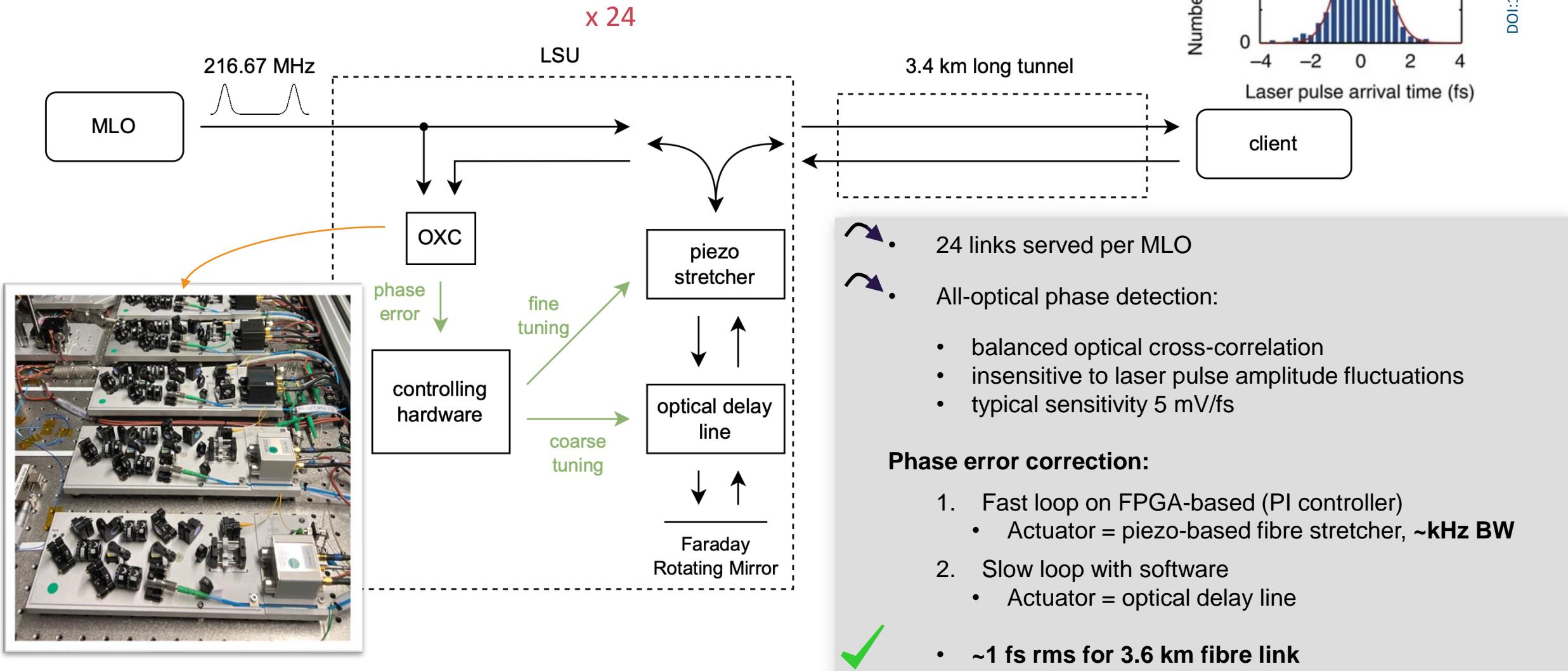
**MLO** Laser Oscillator,  
216 MHz (= 1.3GHz/6)



- Commercial laser oscillator;
- 1550 nm , soliton-like pulses,
- Ultra-low phase noise,
- 24/7 operation,
- 2x MLO for redundancy with fast switching

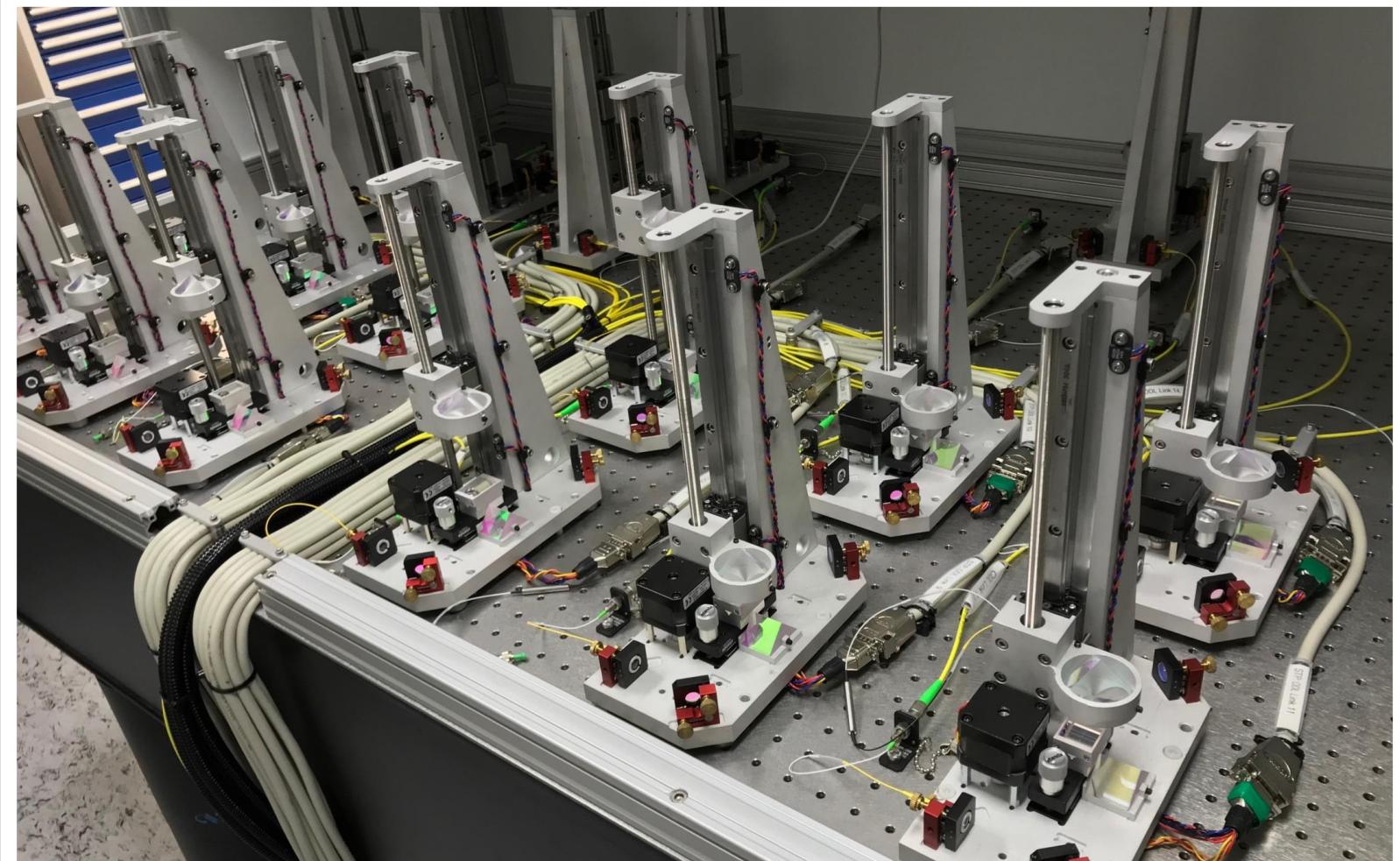
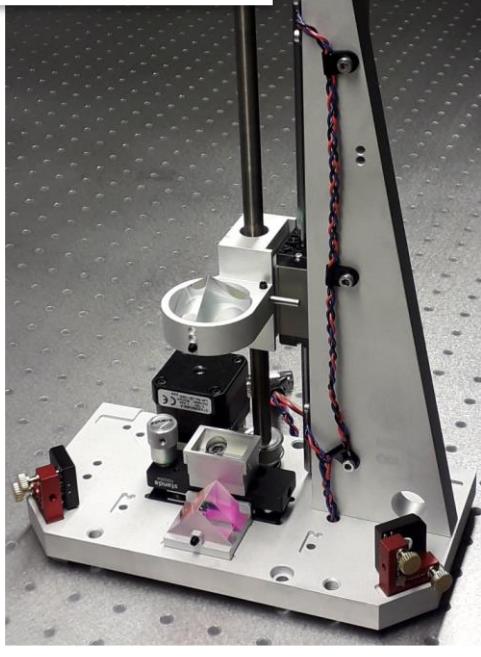
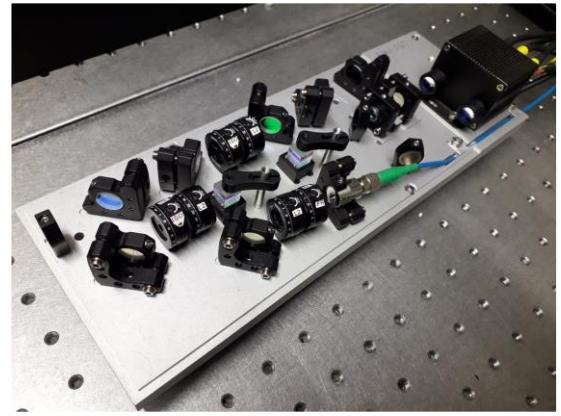
# Pulsed Optical Reference Distribution

## Round-Trip Time Stabilised Fiber Links.



# Link Stabilization Units – Optical Building Blocks

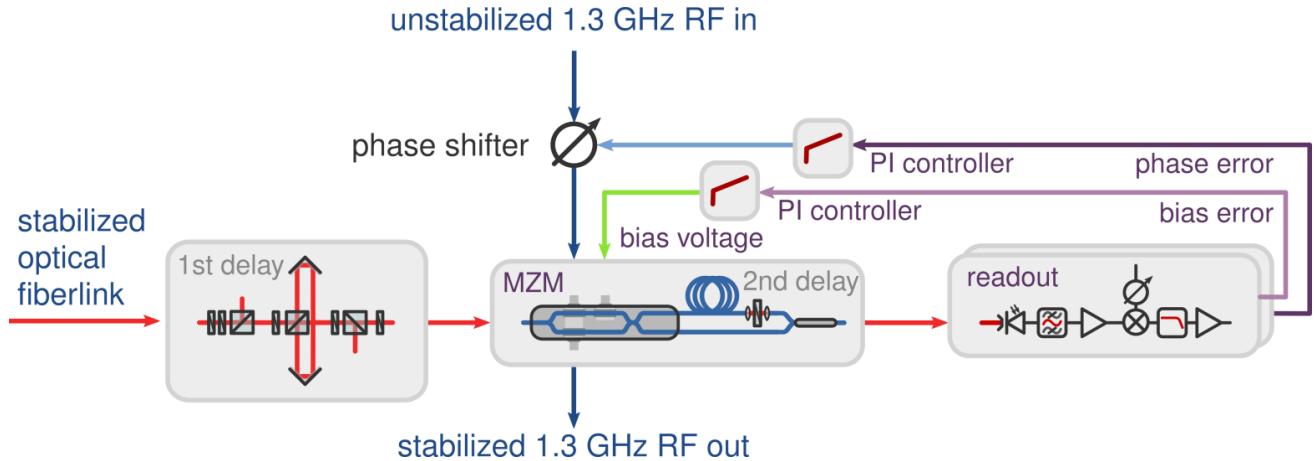
Measurement and Compensation of Fiber Link Transit Time Variations



Courtesy: J. Mueller

# MZM-based, Balanced Laser to RF Phase Detector

## Tightly Phase-locking RF and Optical Oscillators.



### REFM-OPT Design:

- MZM-based laser-to-RF phase detector,
- 19" module,
- Fully engineered,
- Automated controls.

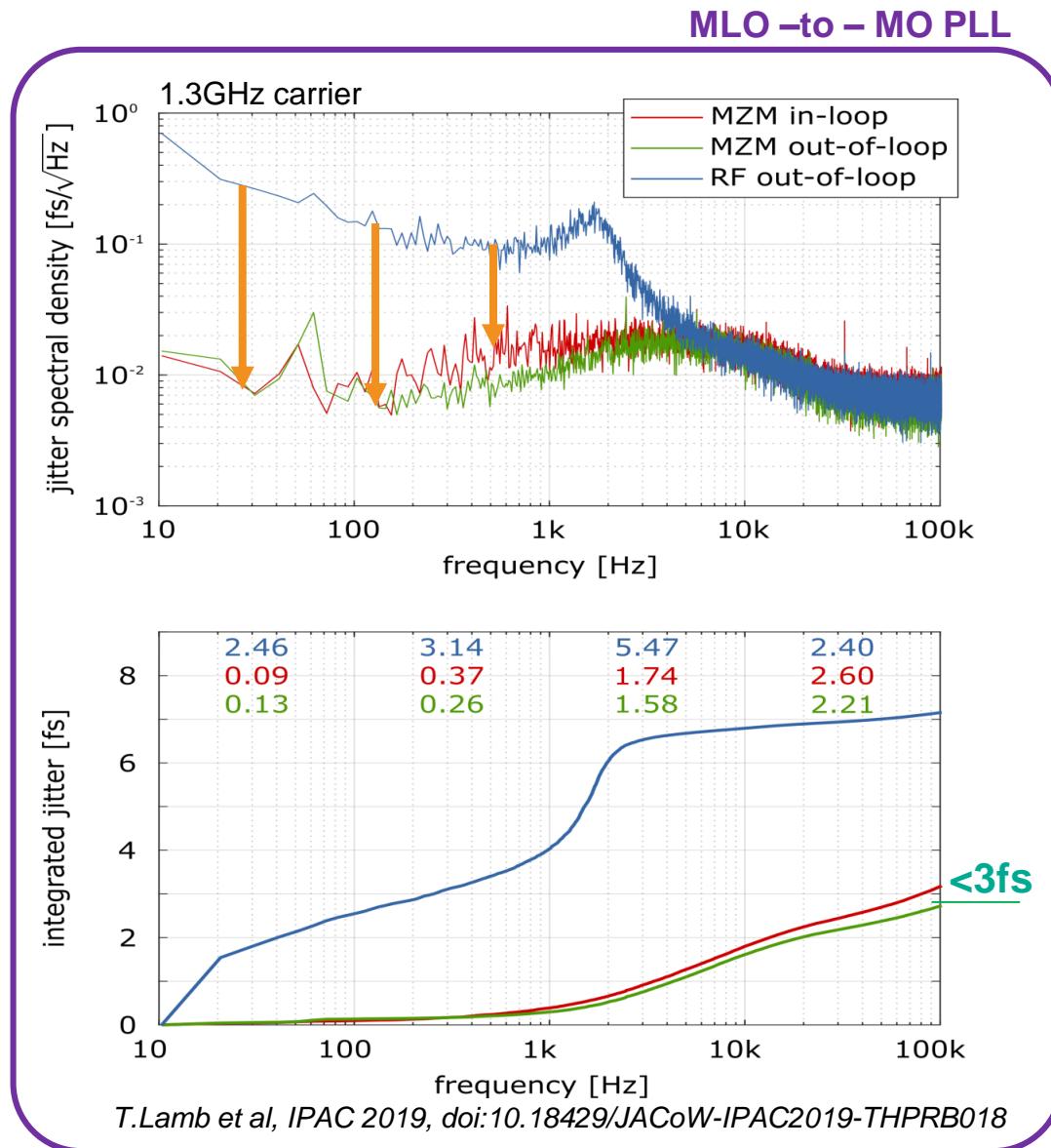


### Typical performance of PLL:

Low-noise : ~3 fs rms  
Ultra-low-drift : < 2 fs pk-to-pk over 1 week

### Applications

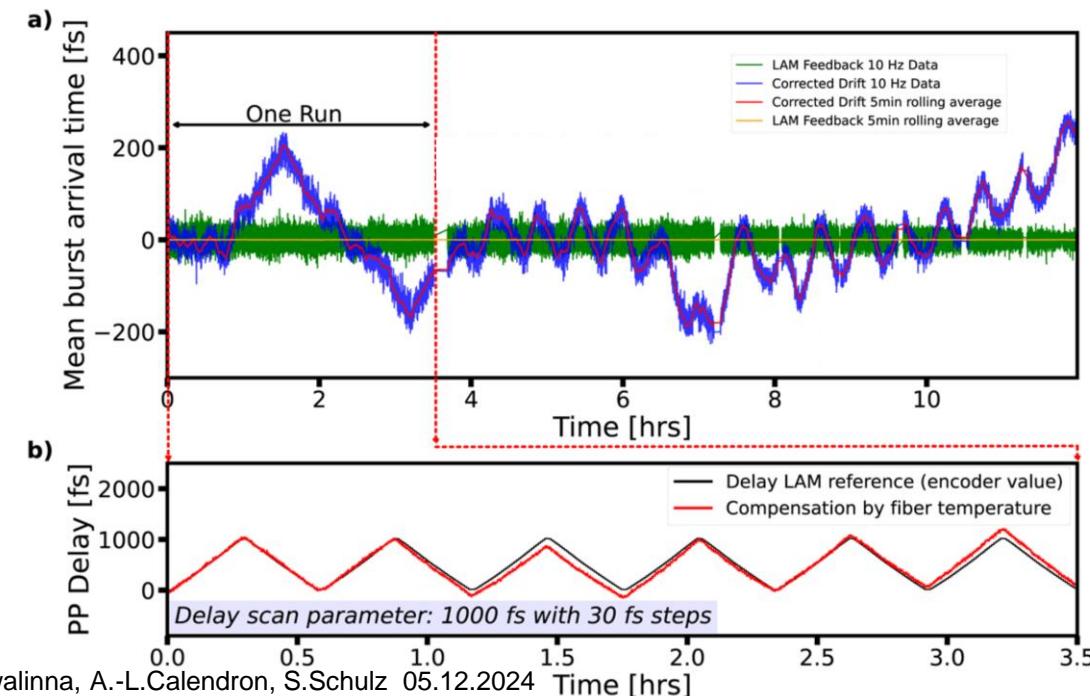
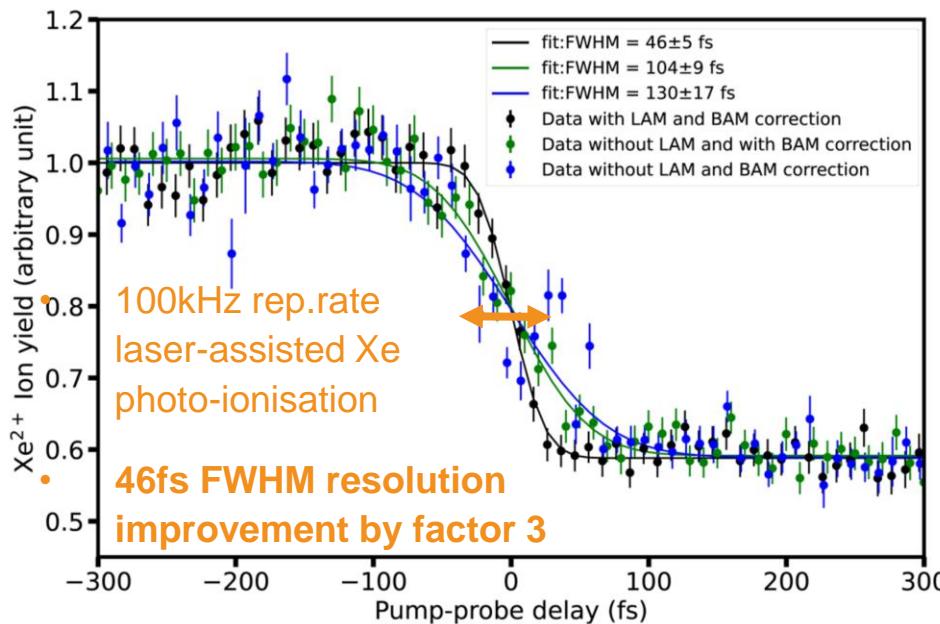
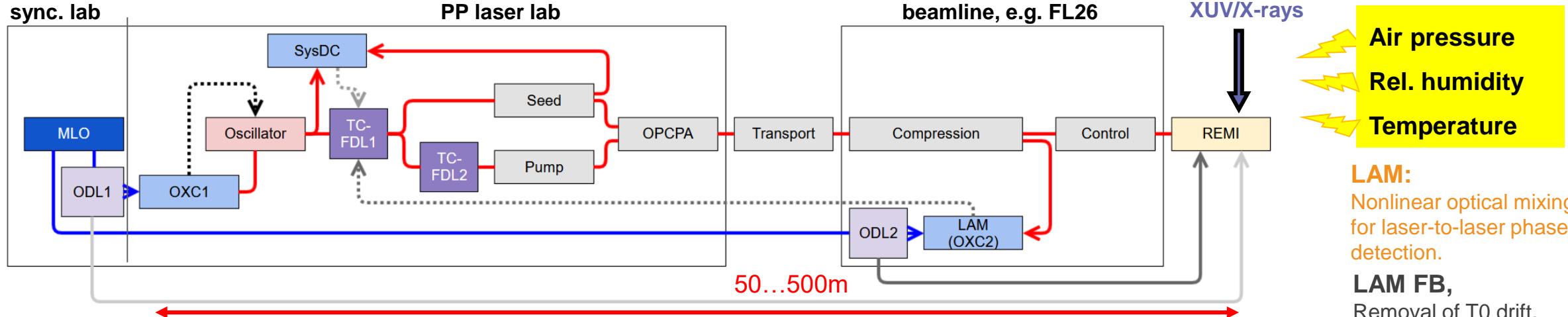
- **MLO to MO locking**
- **RF resynchronization**
  - at location of RF modules
  - locking bw <1kHz
- Removal of phase drifts from RF distribution



T.Lamb et al, IPAC 2019, doi:10.18429/JACoW-IPAC2019-THPRB018

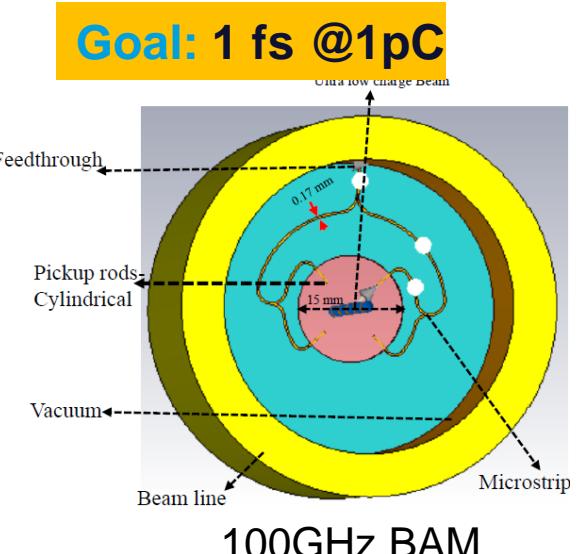
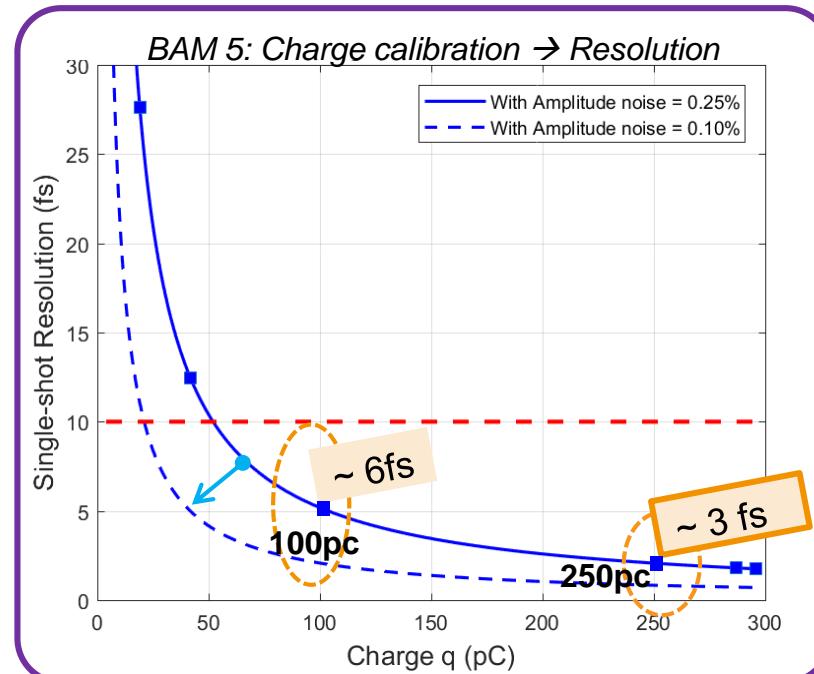
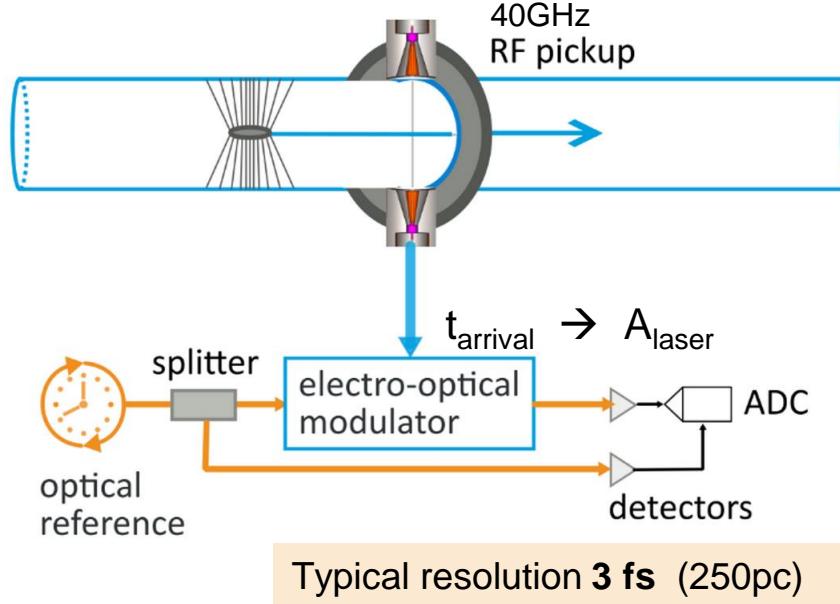
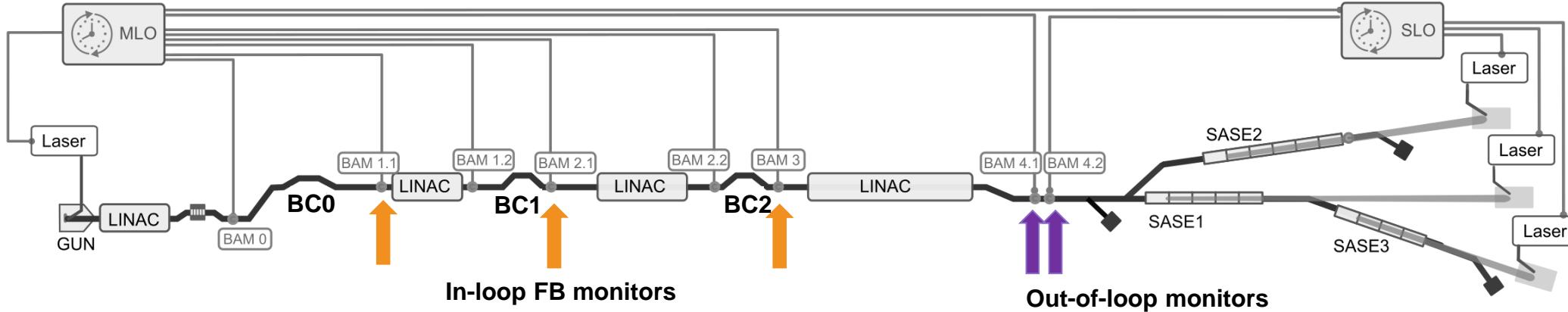
# Laser Pulse Arrival Time Monitors

Drift correction with fs, single-shot Laser-to-Laser phase detector.



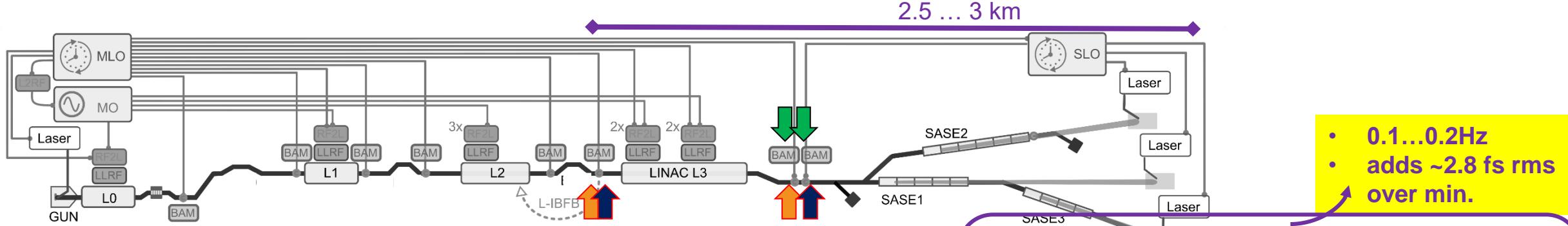
# Electro-optical Bunch-Arrival-time Monitors

Few femtoseconds single-shot resolution.



# Observation : Seismic and Micro-Seismic Effects (< 1Hz)

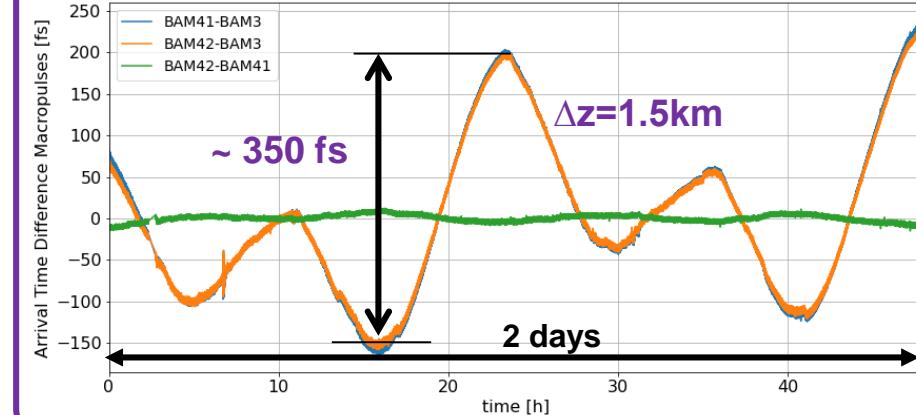
EuXFEL Facility is Periodically Stretched and Compressed from Earth and Ocean Tides.



Differential Arrival-times

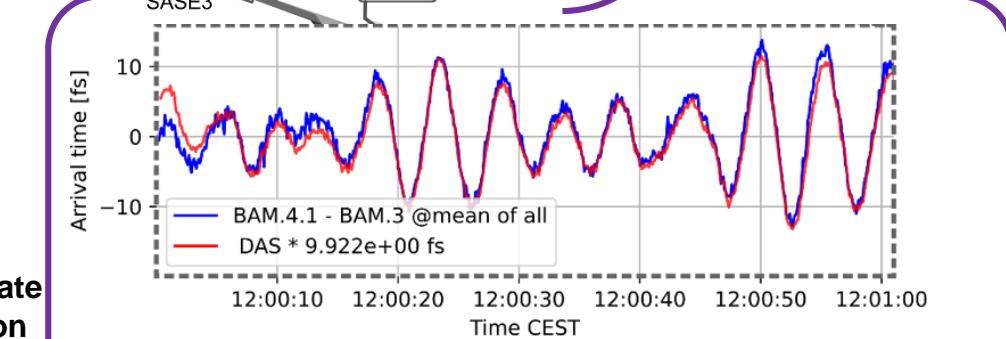
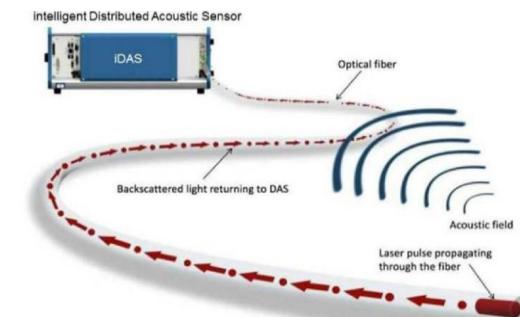
Tidal waves of Earth & Ocean ~12h period

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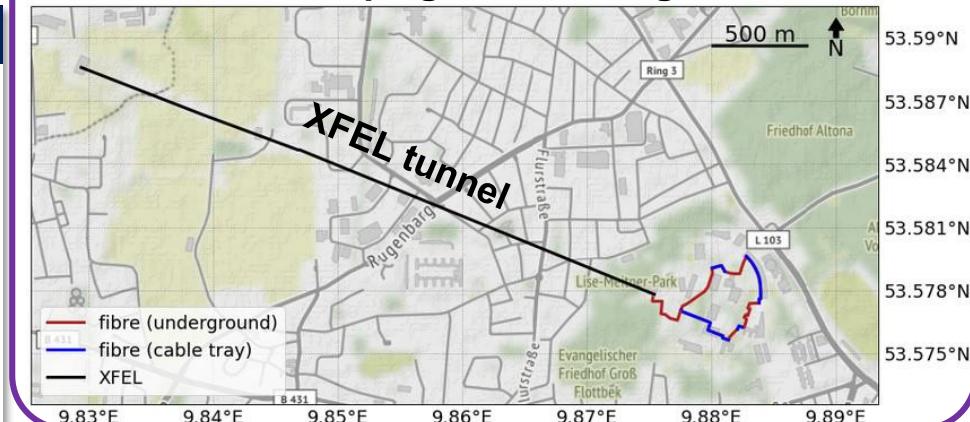


- Drift FEL vs. PP Laser
- Requires feed-forward

iDAS



Measurement campaign 12.6 m length



# **Further Developments**

## **Midterm Plans & On-going Projects**

# Developments

## Overview

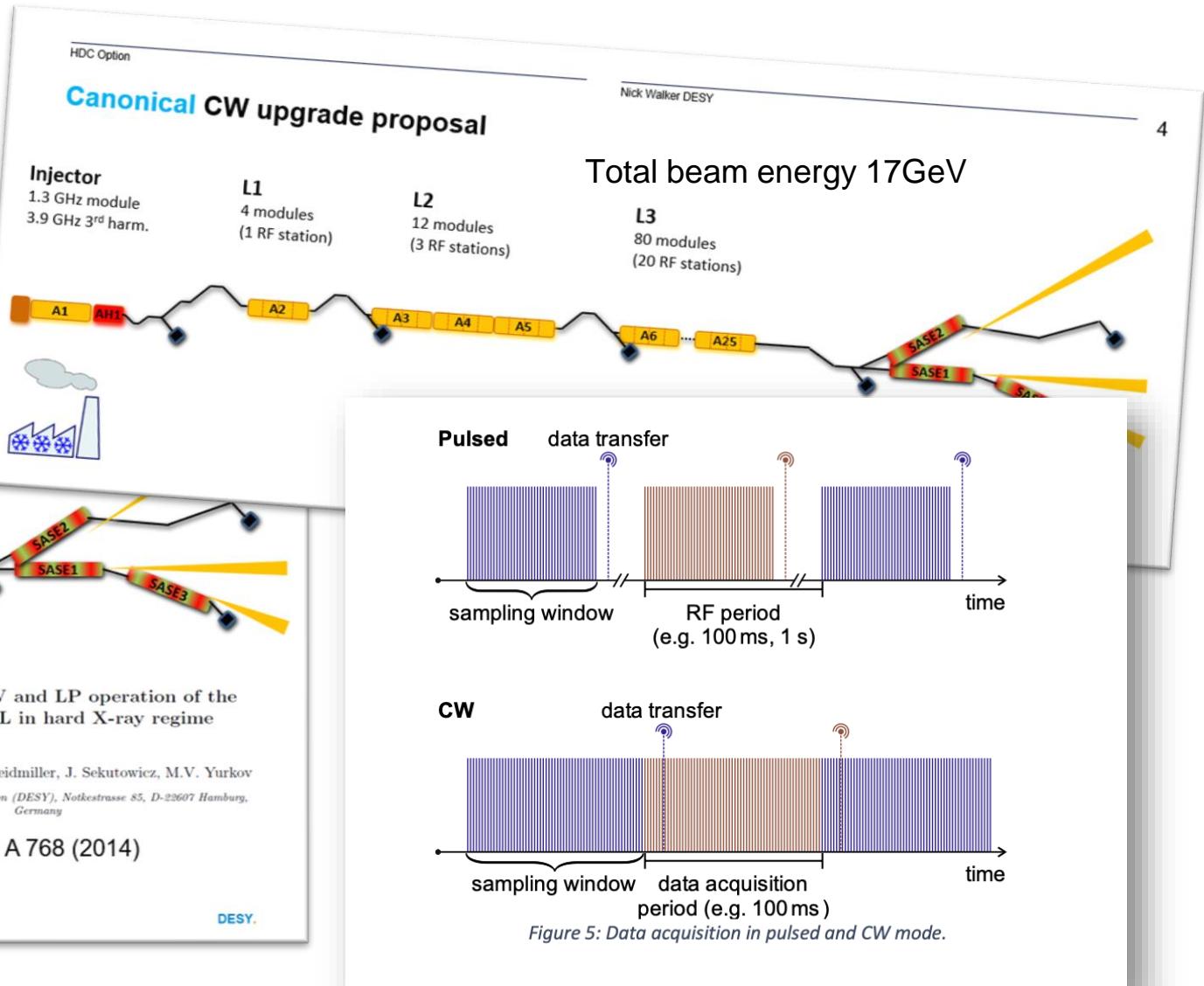
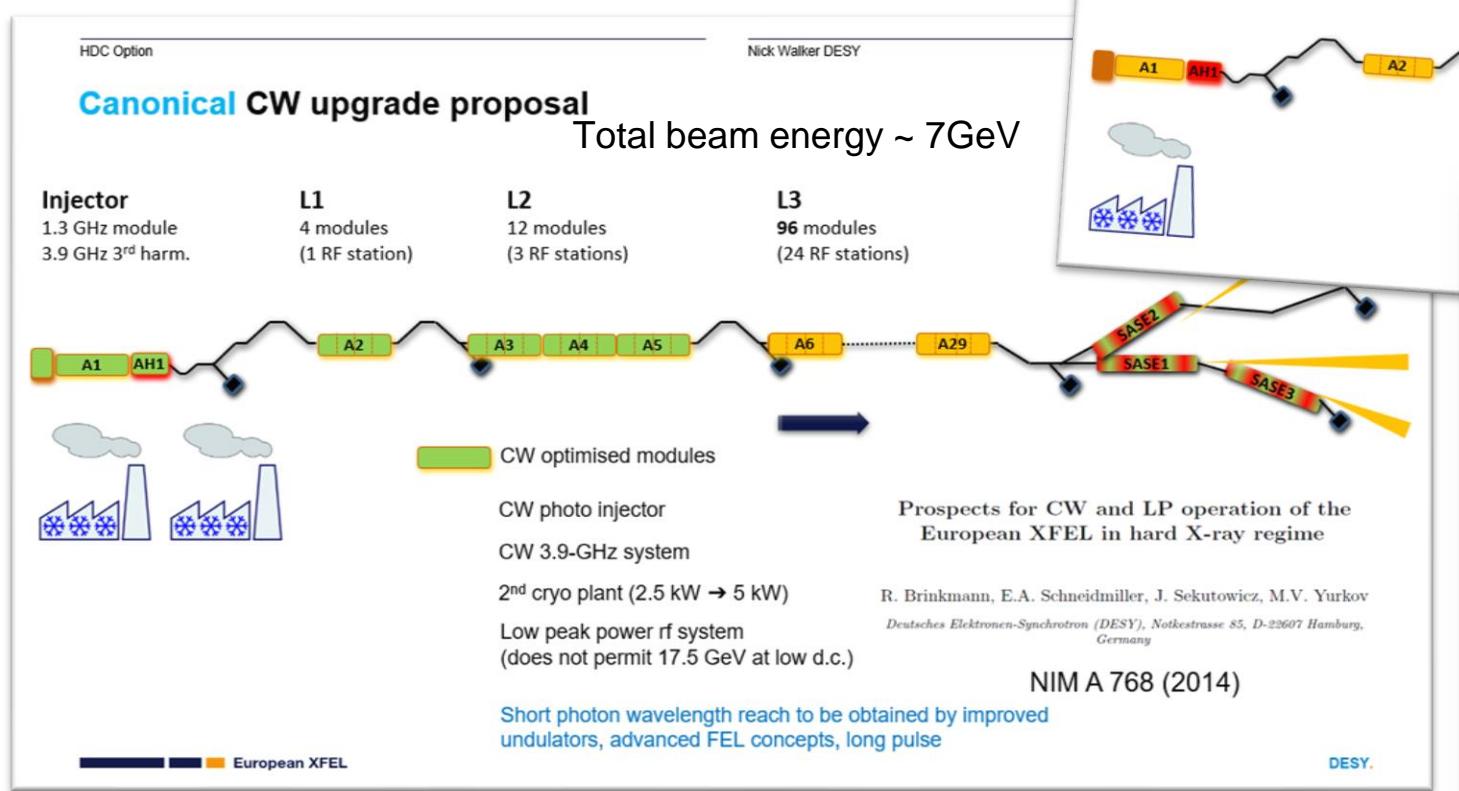
- 1. Beam Diagnostics**
  - A. Bunch arrival-time monitors with <1fs resolution**
  - B. Bunch compression monitors,**
- 2. Beam-based Feedbacks**
  - A. New feedback concept for cw operation mode**  
+ Modelling of noise sources and impact on beam
  - B. Data-driven / model-predictive approach → compensation of sub-Hz disturbance**
- 3. Synchronization System**
  - A. Laser pulse arrival-time monitors & feedback**
  - B. Data-driven improvements of algorithms, configurations and fault diagnosis**
- 4. Proposed : Photon Arrival time Monitor @1550nm**

# Change of Operation Mode @EuXFEL

Also means, change of bunch repetition rates.

Macro-pulsed : bursts @1..10Hz  
high beam rep.rate >1MHz

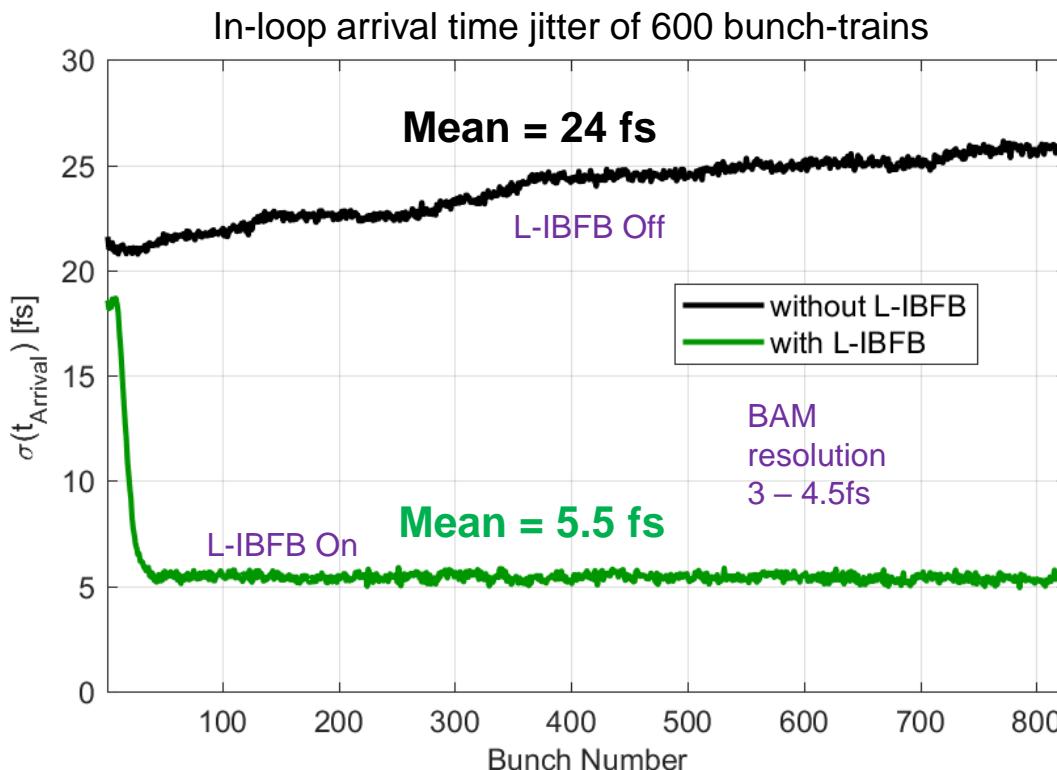
Pure cw: slow beam rep.rate <<1MHz



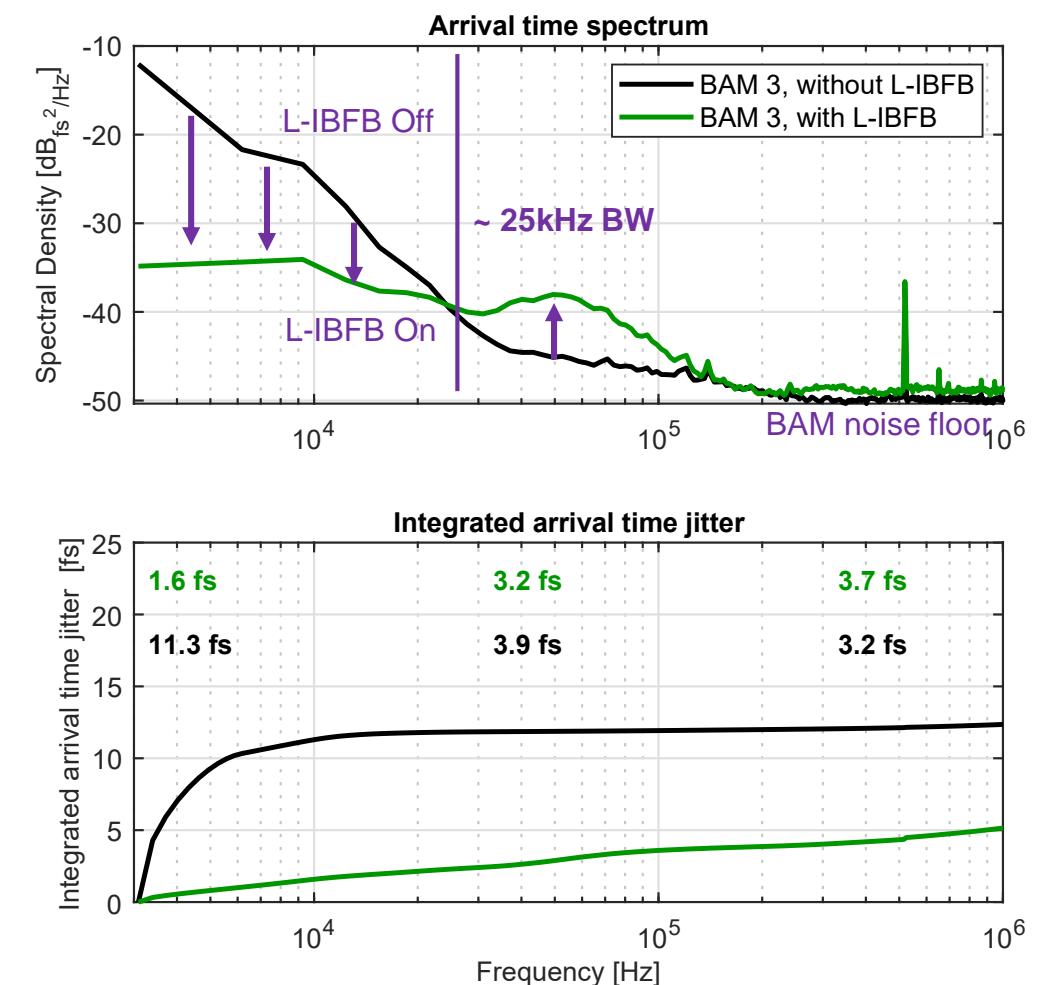
# Intra-Burst Arrival-time Stabilization

State-of-the-art, Suppression of RF field fluctuations within 25kHz BW.

- Energy corrections  $\sim 10^{-6}$  (e.g.  **$\pm 5\text{MeV} @ 2.4\text{GeV}$** ),
- Adaptation time  $\sim 10\text{-}15 \mu\text{s}$ ,
- Operation stable over days,
- Limited regulation range  $\rightarrow$  offset correction by slow feedbacks.



Facility	Best	Daily
EuXFEL	3.3 fs	$\sim 4\ldots 5\text{ fs}$
FLASH	4.7 fs	$\sim 6\text{ fs}$



# Implications from Change to CW Mode @EuXFEL

Beam-based Feedback Control to be Optimized for cw Operation.

**Macro-pulsed** : bursts @1..10Hz  
high beam rep.rate >1MHz 

**Pure cw:** slow beam rep.rate <<1MHz 

- Feedback implemented right now
  1. Slow drift compensation
  2. Adaptive to remove repetitive errors across burst
  3. Fast, intra-burst feedback
    - Acts in time domain. Measures bunch and corrects 2-5us later
    - Controller bandwidth up to 25kHz
    - Requires high sampling rate of bunches (>250kHz rep.rate)  
• → not applicable at <<250kHz bunch rep.rate.

- Requires different concept.

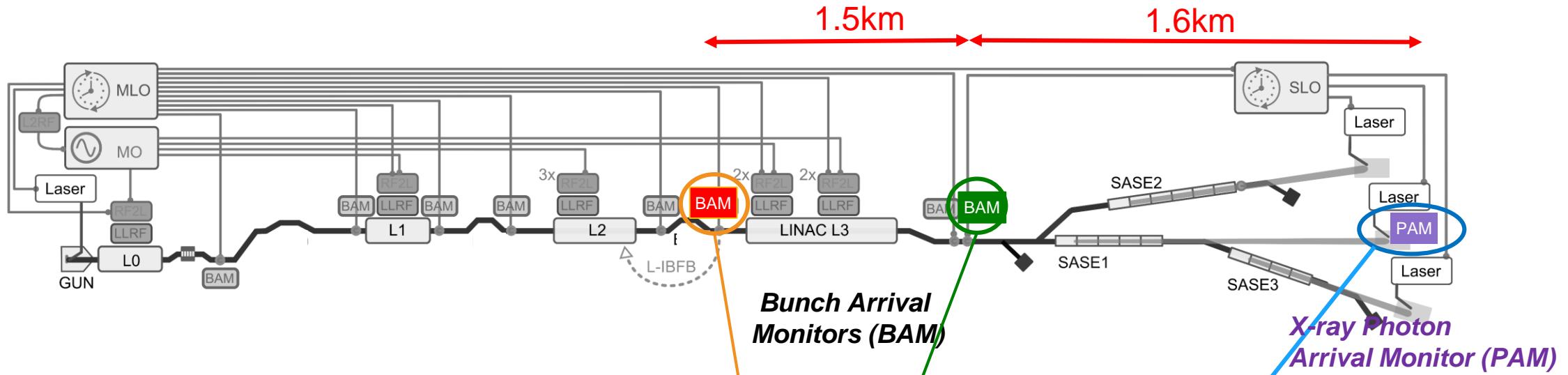
Steps:

1. estimate RF performance → expected noise spectra
2. Model impact on beam stability; main contributions <100Hz?
3. Global controller / FFT (take advantage of continuous measurement)

Needs possibility for tests with beam

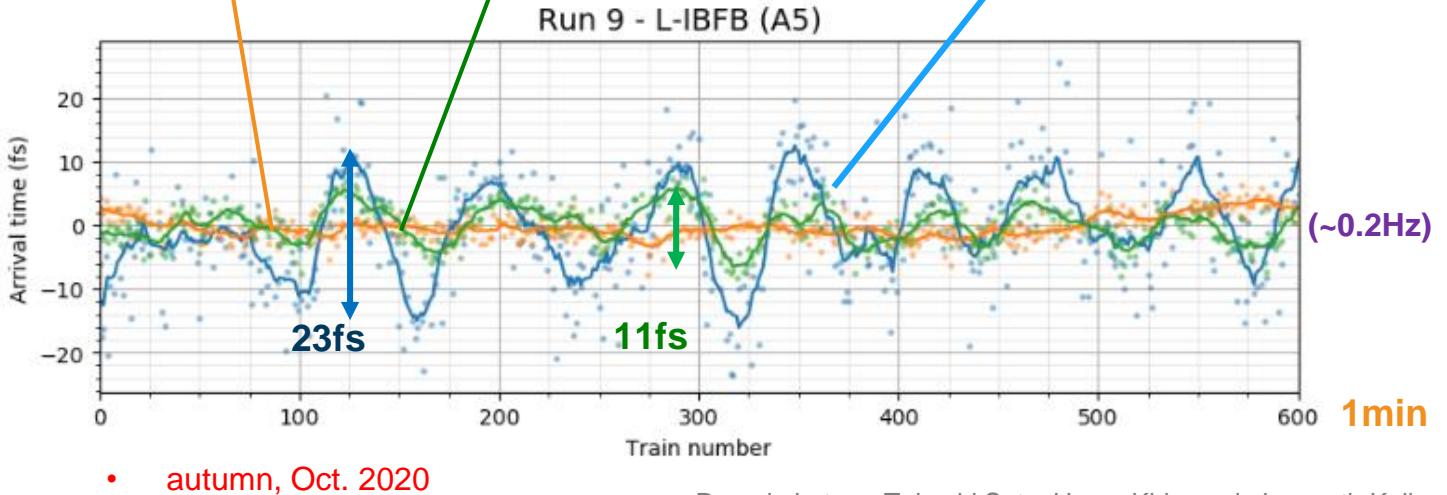
# Ocean Waves Appearing in Beam-based Measurements

Relative Arrival-time change requires compensation for high-precision pump-probe experiments.



Observed arrival-time fluctuation :

- Include additional arrival time monitors
- Model + prediction
- Apply compensation
- Critical for <10fs FWHM overall stability

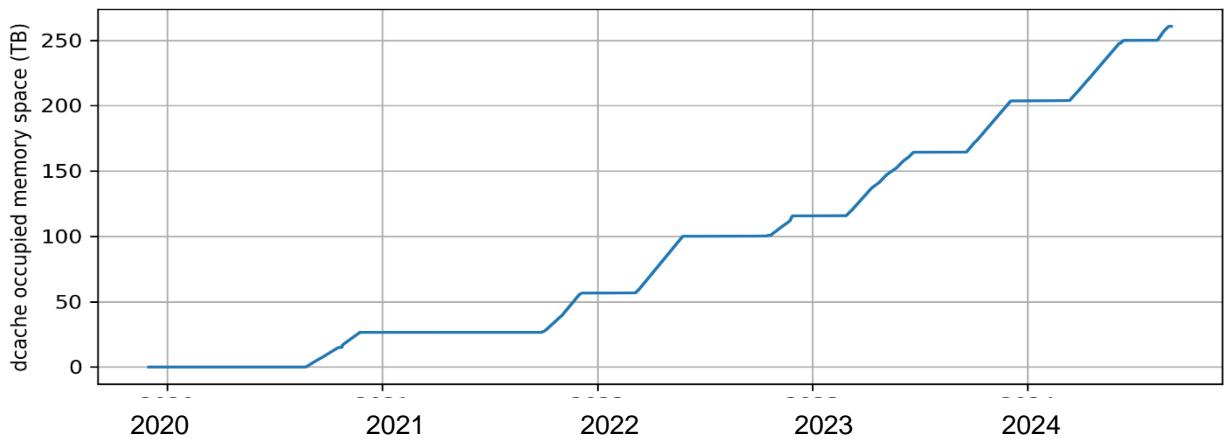
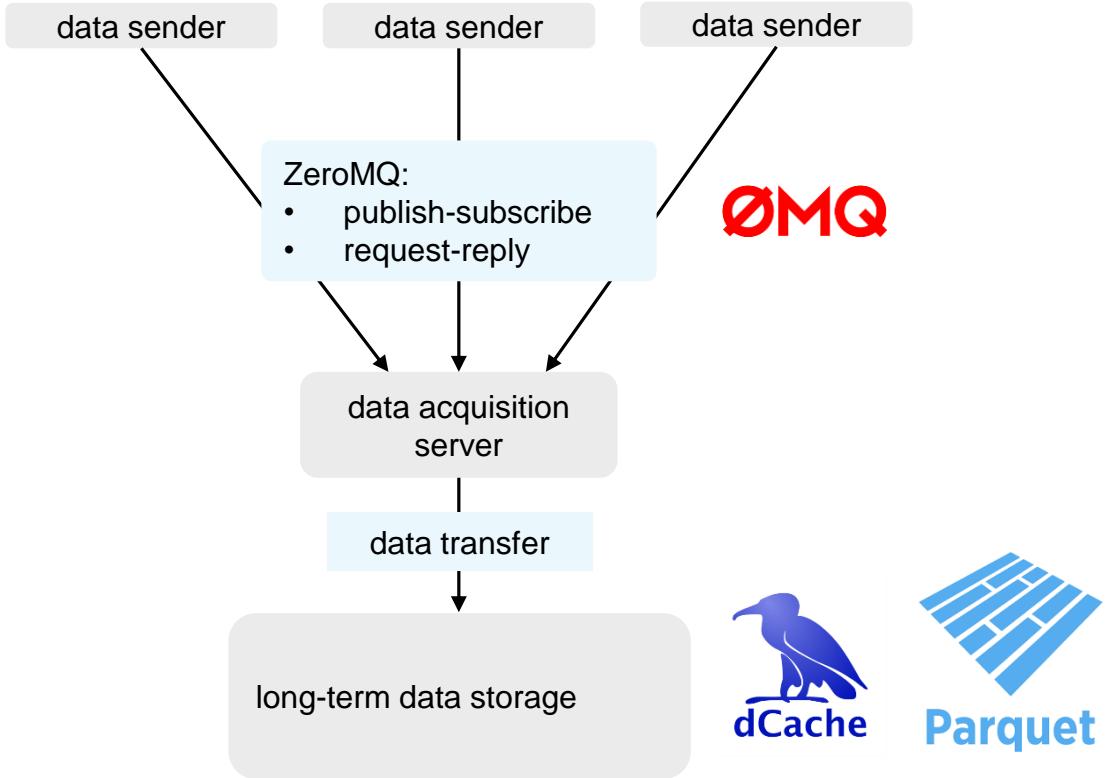


# Data Acquisition and Storage

## Dedicated DAQ System for the Laser-Based Synchronisation System

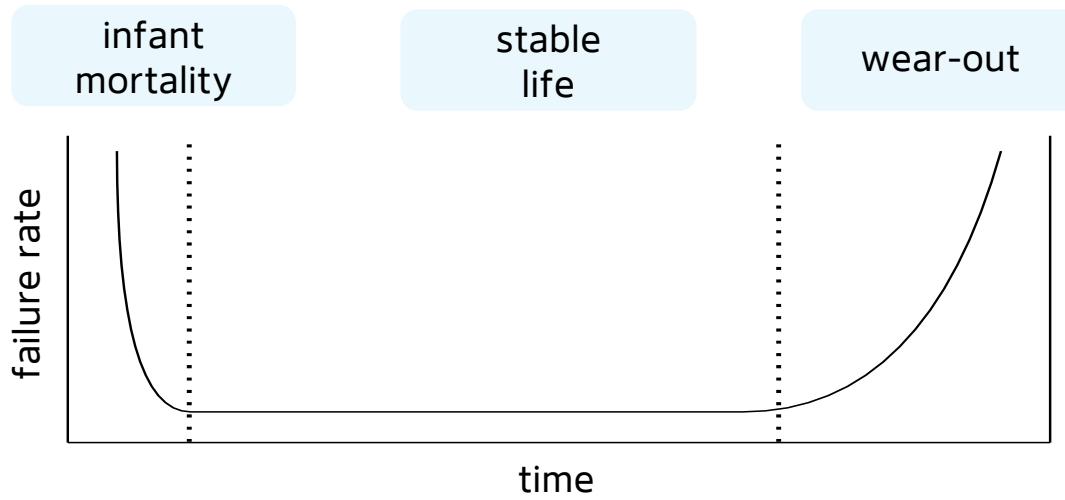
- deep integration into the control system
- foundation of ML applications

- data sources ~47k control system channels
  - controller I/O of all feedback systems
  - configuration
  - environment ( $T$ , relative humidity, air pressure)
- dCache volume ~250 TB since 2021
  - 10 Hz acquisition rate
  - daily 10-second long snapshots of “fast” data
  - → 5-day ring buffer of full fast data set of select subsystems, e.g. MLO



# Data-Driven Condition Monitoring

## The Bathtub Curve – Failure Rates Over the Lifetime of a System



### Typical Life-time of a System

#### a) infant mortality phase

- manufacturing defects, installation issues

#### b) stable life phase

- low and stable failure rate, random/unexpected failures due to sudden, not age-related events

#### c) wear-out phase

- aging effects, components wearing out

### Goals

#### Enhance reliability

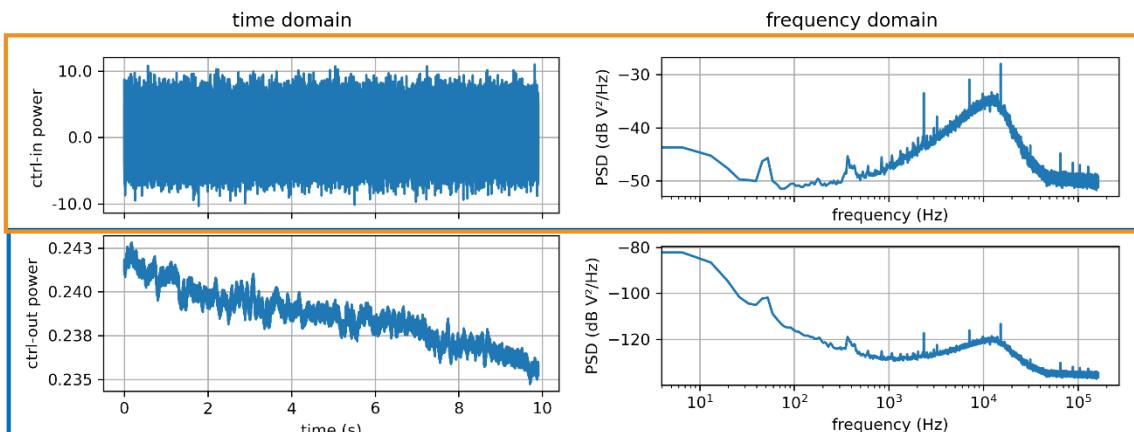
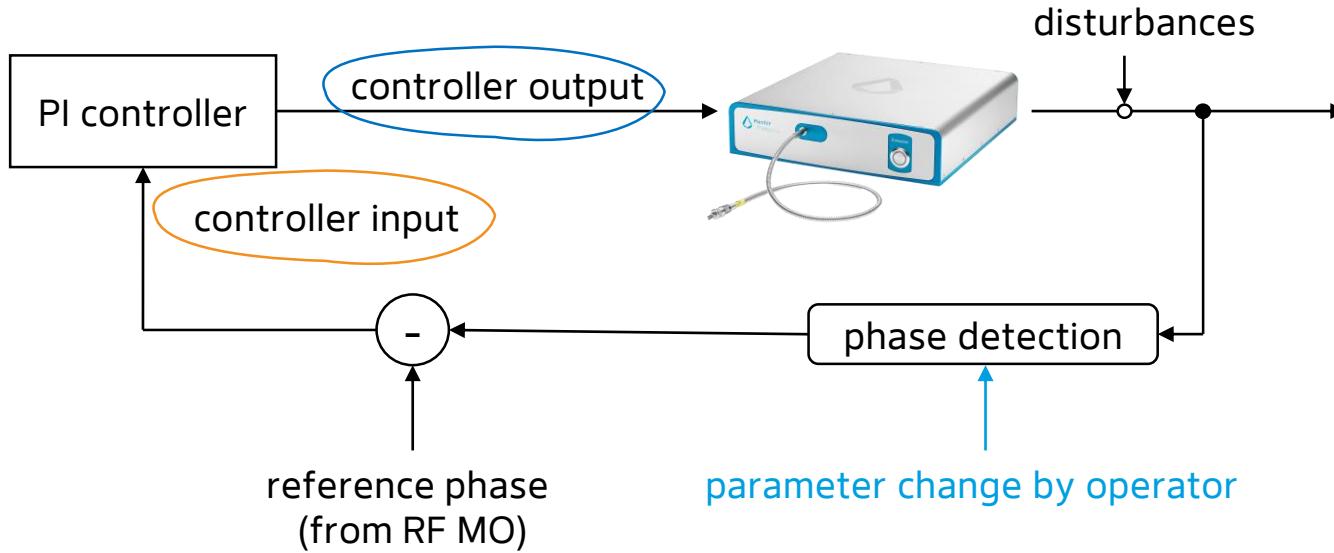
- early fault detection,
- consistent performance,
- extended lifespan

#### Ensure availability

- minimisation of unplanned downtime,
- avoidance of unnecessary maintenance activities

# Project : Fault Analysis & Classification of States

## Example: Main Laser Oscillator PLL Signal



CNN  
autoencoder  
(trained)

- difference w.r.t. *ground truth*
- ground truth / healthy state
  - defined by operator
- problem: external influence
  - metadata capturing
- **work in progress**

class	certainty
healthy	health score
fault class 1	class 1 score
fault class 2	class 2 score
fault class 3	class 3 score
...	...

# Developments & Status

## Potential for Cooperation

- On-going; 1<sup>st</sup> demonstrator done.  
Now technical realization & improvement.  
→ Will benefit from more tests at different facilities
- In preparation; detector development.  
Funding proposals submitted.
- On-going. Based on extensive previous work.  
→ One of our focuses in next 2-3y
- Work in progress.  
First demonstration done,  
for a tidal-wave drift mitigation.
- Work in progress. → large overlap and benefit from  
cooperation.
- Work in progress.
- Feasibility study needed.  
Might be of mutual interest.
1. **Beam Diagnostics**
    - A. **Bunch arrival-time monitors with <1fs resolution**
    - B. Bunch compression monitors,
  2. **Beam-based Feedbacks**
    - A. **New feedback concept for cw operation mode**  
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**Thanks for your attention**