

# ESO - Requirements Management (RM) in Astronomical Instrumentation

From science needs to technical specifications

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# **Key Objectives**





# **ESO Telescopes & Astronomical Instruments**





# **ESO Telescopes & Astronomical Instruments**











# **ESO Project Phases:**

### **Pre-Phase A:**

- + Identification of the science drivers and key performance metrics.
- + Preliminary feasibility studies to assess technical challenges.
- + Initial risk identification and resource estimation.



### **Phase A: Feasibility Report**

- + Detailed feasibility studies addressing technical, operational, and cost aspects.
- + Conceptual design work that outlines the main subsystems and overall architecture.
- Develop final mission concept, and the system-level requirements (Tec. Spec.)
- + Early trade-off studies to compare different design approaches.
- Preliminary risk assessment and mitigation strategies.

### Phase B: PDR

- + Development of detailed preliminary designs and simulations.
- + Establishment of an error and performance budget (for instance, for the AO system, optics, and detectors).
- + Integration of trade-off studies with respect to cost, risk, and technical performance. Also prototyping.
- + Formal reviews with stakeholders to validate that the design can meet the science requirements.

### **Phase C: FDR**

- + Finalization of engineering drawings, specifications, and detailed models.
- + Intensive design reviews and verification of requirements compliance.
- + Detailed planning for manufacturing, assembly, integration, and testing.
- Preparation of calibration and operational plans.





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# What are requirements?• Definitions, examplesImage: DefinitionESO requirements process• Flow downImage: Definition• Flow down• Flow downImage: Definition• Flowdown and allocation• Flowdown and allocationImage: Definition• Flowdown and allocation• Validation and verificationImage: Definition• Validation and verification• Writing good requirements



**Overview** 



# **Requirements Definition**

Requirements describe the necessary functions and features of the system that needs to be designed, created and used. They can be related to:

- Performance (resolution, magnification, contrast,...)
- Functionalities (take visible images, take IR spectroscopy, collect sample in another planet,...)

### **Requirement Conditions**

- Schedule (by when do we need it, be reasonable)
- Cost (budget definition)
- Survival environment (high radiation, earthquakes, extreme temperatures,..)
- Lifetime (10 years, 30 years,...), very linked to cost definition.
- Others (size, weight, ...)

### Understand the goal of your requirement.

- Does something similar already exist?
- Can be improved?
- Do we understand the physics behind?



# Why Requirements Management Matters?







# **Requirements Hierarchy**

Image generated by ChatGPT



# **The Requirements Pyramid**

**1. Science Needs:** High-level goals (e.g., detect exoplanets).

**2. Top-Level Requirements:** Translate science needs (e.g., AO correction shall be provided leading to ensquared energy of at least 15% within a 50x50 mas square aperture).

- 3. Derived Requirements: Break down into subsystems (e.g., wavefront error delivered by the AO shall be < 100 nm.). (Level 1 Req. Specification, L1S @ESO)
- 4. Technical Specifications: Component-level details (e.g.,
  - coating reflectivity > 95%).

# **Science Needs and Their Translation**

**Example:** 

**Science Need:** Detect faint galaxies in the infrared



Top-Level Requirement: Sensitivity must reach 25 AB magnitude in the Ks band.



**Derived Requirement:** Telescope throughput > 60% in the Ks band.



Technical Specification: Mirror coatings with reflectivity > 95% at 2.2 μm.



### +ES+ 0 +

# **Flow-Down Process**





# **Decompose Science Need**







# **Case Study: Infrared Astronomical Instrument**





Infrared image of 30 Doradus (Tarantula Nebula) HAWK-I + VISTA

### **Derived Requirement:**

On-axis wavefront error < 100 nm at 3.3 um

### Flow-Down:

- Telescope and Atmosphere (seeing conditions, turbulence effects)
- AO System (wavefront sensor, deformable mirrors, control algorithms)
- Instrument Optical Design (alignment errors, optical surface quality)
- Mechanical and Thermal Stability



### +ES+ 0 +

# **Case Study: Study Methane on extrasolar planets**



Artist's impression Credit: ESO

### Science Need:

"Detect methane in the atmosphere of an extrasolar planet"

### **Top Level Requirements – Science Performance**

- + Wavelength Coverage: near- to mid-infrared range (2.8 3.5 μm)
- Spectral Resolution: (**R** =  $\lambda/\Delta\lambda$ ) of at least 100,000 at 3.3 μm.
- Sensitivity: 5o detection of a methane feature in an exoplanet atmosphere with a host star of magnitude K = 12 in 10 hours of integration.
- Contrast and High Dynamic Range Capability: planet-star contrast ratio better than 10<sup>5</sup>:1 at angular separations of 0.1–0.5 arcseconds.

### **Top Level Requirements - Optical and Spectroscopic Requirements**

- Throughput: total system efficiency (including telescope, instrument optics, and detector quantum efficiency) shall be ≥ 20% at 3.3 µm.
- Field of View (FoV) and Spatial Sampling: FoV of at least 1 arcsecond to account for adaptive optics (AO) corrections.
- + Pixel scale should match the diffraction limit of a 40m telescope at 3.3 μm (~0.02 arcsec/pixel).

# **Case Study: Study Methane on extrasolar planets**





Artist's impression Credit: ESO

### Science Need:

"Detect methane in the atmosphere of an extrasolar planet"

### **Top Level Requirements – Detector and Readout Requirements**

- Detector Type and Noise Performance: high-QE (≥80%) HgCdTe infrared detector array, optimized for 3-5 μm.
- **★** Readout noise: shall be **<10 e<sup>-</sup> RMS per frame** to allow stacking of exposures.
- **→** Dark current < 0.01 e<sup>-</sup>/s/pixel at an operating temperature of ≤40 K.
- A cryogenic cooling system (e.g., closed-cycle cooler or liquid helium) shall maintain stability within ±0.1 K.

### **Top Level Requirements - Observing Mode Requirements**

- + High-Resolution Spectroscopy Mode.
- + Cross-Correlation Spectroscopy Support.
- + Polarimetry (Optional), for distinguishing between reflected starlight and thermal planetary emission.





# WFE Allocations (example)

Error Source	Budget (nm RMS)	Notes
Atmospheric Turbulence (after AO correction)	60 nm	Residual error after AO compensation
Deformable Mirror Fitting Error	30 nm	Limited by actuator density and response time
Wavefront Sensor Noise	20 nm	Photon noise, detector readout noise, centroiding error
Optical Surface Errors (instrument optics)	20 nm	Mirrors, lenses, coatings, optical misalignments
Static Aberrations (telescope optics)	15 nm	Primary/secondary mirror polishing, alignment errors
Vibrations and Thermal Drifts	10 nm	Mechanical jitter, instrument flexure
Total	~100 nm RMS	Ensures diffraction-limited imaging



# **MAVIS** example

### Top Level Requirements (TLR-14):

The AO module shall perform atmospheric turbulence correction making use of multiple natural-guide-stars (NGSes) and laser-guide-stars (LGS). The NGSes shall be sensed such that the WFS cameras do not obstruct the science FoV and a maximum instrumental throughput is provided.

Under stable, standard atmospheric conditions (TLR-10), **and at a zenith distance of 30°,** the average Strehl ratio (SR) for a V-band filter (performance in other, redder filters is based on the assumption of constant WFE) over the full science FoV of the camera achieved in the raw data product of the instrument over a 15 min duration observation shall be  $\geq$ 10% (goal 15%) when using three m<sub>J</sub> $\approx$ 8 TT-stars (class G2) on a favourable asterism of diameter  $\leq$ 40".

### **Derived Requirements – AO**

☆ The AO module shall deliver unvignetted AO-corrected field of at least (30±1)x(30±1) arcseconds
☆ The AO module, possibly with reduced performance scaling as expected with conditions and to be agreed with ESO, shall operate in the best 80% (corresponding to <1 arcsecond seeing) of seeing conditions (goal: 95%, i.e. <1.5 arcsecond seeing) and good coherence time (corresponding to >2.5 ms; MASS-DIMM value).
☆ The AO module shall support at least one NGS being an extended object up to 3 arcsecond FWHM
☆ A minimum of 11% ensquared energy within a 50x50 mas2 square aperture.
☆ AO performance for bright NGS: The average Strehl ratio (SR) over the full AO-corrected FoV shall be ≥8%

 $\mathcal{R}$  AO performance for bright NGS: The average **Strent ratio** (SR) over the full AO-corrected FoV shall be 289 (goal:>12%) for three NGS with mJ $\approx$ 8 and an asterism diameter  $\leq$ 40 arcsec.

The variation of Strehl ratio as in [#425] or FWHM as in [#426], respectively, over the full AO-corrected FoV shall be less than 10% PTV of the average, for all filters with central wavelength larger than 500nm



# Example of a spec with a missing detail

### **R-MAVIS-SCI-6 Imaging Sensitivity** MAVIS, in a one hour total exposure time, shall be able to image an isolated point source of mV=29 with a SNR≥5. **Driving Science Case Requirement Rationale** Other Relevant Chapters Chapters Need to maximise volume probed, which is proportional to 2.5 Morphology of the first galaxies photometric depth; push to low mass systems beyond Hubble Ultra Deep Field (<29.5mag) Detect RGB of ancient stellar populations within 10Mpc 3.2 Resolved stellar populations in ETG 2.4, 3.3, 3.4, 4.2, 4.3, requires limiting AB magnitude of V=29-30 envelopes 5.2, 5.3, 5.4 Detecting down to 0.1Msun stars in the L/SMC for IMF 4.4 Stars clusters in the Local Universe studies requires V>29 ABmag Detecting lensed young massive clusters forming at z>7 4.7 The origin of the first star clusters at requires limiting magnitudes of V>29 high-z





# **Example of a spec with a missing detail**

<b>R-MAVIS-SCI-6 Imaging Sensitivity</b> $MAVIS$ , in a one hour total exposure time, shall be able to image an isolated point source of $mV=29$ with a $SNR\geq 5$ .				
2.5 Morphology of the first galaxies	Morphology of the first galaxiesNeed to maximise volume probed, which is proportional to photometric depth; push to low mass systems beyond Hubble Ultra Deep Field (<29.5mag)Resolved stellar populations in ETG relopesDetect RGB of ancient stellar populations within 10Mpc requires limiting AB magnitude of V=29-30			
3.2 Resolved stellar populations in ETG envelopes				
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4.7 The origin of the first star clusters at high-z	origin of the first star clusters at Detecting lensed young massive clusters forming at z>7 requires limiting magnitudes of V>29			

What is missing??

The definition of the window to measure the SNR  $\geq$  5 on pixels.





# **ESO Tools for Requirements Management**

# <u>Capturing, tracking, and managing requirements</u>

• IBM Engineering Requirements Management **DOORS** (Dynamic Object-Oriented Requirements System)

# Model-Based Systems Engineering (MBSE) and Requirements Modeling Tools

Mainly done by the consortia:

- MORFEO Cameo
- ANDES MagicDraw
- METIS Polariom

### Test and Validation-Focused Tools

### - DOORS

General Project and Documentation Management Tools:

• Accruent, PDM

Issue and Change Management Tools:

• Jira (Atlassian) – Widely used in agile requirement tracking and issue management.

Traceability and Compliance Tools:

Simulation and Analysis Tools (Used for Requirement Validation in Astronomy):

- Zemax OpticStudio Used to validate optical requirements for telescopes.
- MATLAB & Simulink Simulations for verifying requirements in system design.
- ANSYS, Nastran Structural, thermal, and optical simulations for requirement compliance, FEA Analysis.





### Observatory TLR Level 0 Science Construction Instrument N TLR Proposal Level 1 Reqs Spec Level 1 System SYSTEM DOCUMENTS TECHNICAL BUDGETS SCAO, Stroke, Vibration, ... Optical System Spec, Wavefront Control Spec, Env.Cond., Thermal Regs, Oper. + Maint. Plan, . E-ELT STANDARDS Definitions + Acronyms, Stand. Coordinate Syst., SUB-SYSTEM REQUIREMENTS SPECIFICATIONS DMS M1 M2 Instrument N Level 2+ Common Regs on ICDs Technical EELT Instruments M5 M3 M4 Specification Common Instrument N ICD Instruments ICD LCS CCS PFS Color-Coding: Science LGS Infrastructure Engineering Hardie et al, 2022

# **ESO Requirements Document Tree**

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# **Challenges and Best Practices**



# Challenges

- + Conflicting stakeholder priorities
- + Managing evolving requirements
- + Ensuring traceability

## **Best Practices**

- + Engage stakeholders early
- + Use iterative validation
- Prioritize requirements to balance cost and performance









# Verification and Validation (V&V)

### **Key Concepts:**

### •Verification: "Did we build it right?"

• Testing against specifications.

# •Validation: "Did we build the right thing?"

• Ensuring it meets scientific goals.

At ESO, the verification and validation methods are defined in the Technical Requirement Specification as:

- Verification by Desing (D): using approved records or evidence (design documents and reports, technical descriptions, engineering drawings) that unambiguously show that the requirement is met.
- Verification by Analysis (A): performing theoretical or empirical evaluation using techniques such as systematic and statistical design analysis, modeling and computational simulation.
- Verification by Inspection (I): visual determination of physical characteristics (such as constructional features, hardware conformance to document drawing or workmanship requirements, physical conditions, software source code conformance with coding standards).
- Verification by Test (T): measuring product performance and functions under representative conditions, or under conditions that can be clearly traced to operational ones. It includes the analysis of data derived from the test.



# **Summary & Conclusions**



Requirements management bridges science and engineering





Tools and best practices are critical for success



Use a structured hierarchy and flowdown approach



# **Bibliography**

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