

Cavity Geometry & Figures of Merit

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Idea

- The coupling coefficients as we use them are not ‘scale’ independent
⇒ Suggests false statements like $P_{sig} \propto U_0$
- The GW → Vibration → EM interaction only happens in/near the wall and should not depend on the fields in the entire volume
- Find ‘figures of merit’ that quantify the effect of the geometry on GW sensitivity
- Use figures of merit to find best possible sensitivities that a MAGO-type cavity can reach taking all dependencies (more carefully) into account

Note: the following is just a reformulation, not a correction. But I think it helps to identify how a better detector design should look like. So far, quantities like U_0 were not well separated from the coupling coefficients

Equations of Motion

$$\begin{aligned} \sqrt{U_1} \left(\ddot{b}_1 + \frac{\omega_1}{Q_1} \dot{b}_1 + \omega_1^2 b_1 \right) &= \frac{1}{2} \omega_1^2 \frac{q_m b_0}{\mu_0 \sqrt{U_1}} \int_A d\mathbf{A} \cdot \boldsymbol{\xi}_m (\mathbf{B}_0 \cdot \mathbf{B}_1 - \mathbf{E}_0 \cdot \mathbf{E}_1) , \\ \ddot{q}_m + \frac{\omega_m}{Q_m} \dot{q}_m + \omega_m^2 q_m &= -\frac{1}{2} \ddot{h}_{ij} \underbrace{\int_{V_{\text{wall}}} \frac{dV}{V_{\text{wall}}} \xi^i x^j}_{\text{GW-Vibration Coupling}} , \end{aligned}$$

Vibration-EM Coupling

$$\Rightarrow P_{sig} \propto \omega_1 Q_{cpl} V_{cav} B_0^2 (C\Gamma)^2 h^2$$

$$\Gamma_m^{ij} = \frac{1}{V_{\text{cav}}^{1/3} M} \int_{V_{\text{cav}}} d^3x \rho(\vec{x}) \underline{x^i} \cdot \xi_m^j(\vec{x})$$

Previously we defined:

$$C_{01}^m = \frac{V_{\text{cav}}^{1/3}}{2\sqrt{U_1 U_0}} \int_{\partial V_{\text{cav}}} \underline{d\vec{S}} \cdot \vec{\xi}_m(\vec{x}) \left(\frac{1}{\mu_0} \underline{\vec{B}_1^*} \cdot \vec{B}_0 - \epsilon_0 \underline{\vec{E}_1^*} \cdot \vec{E}_0 \right)$$

GW-Vibration Coupling

old:

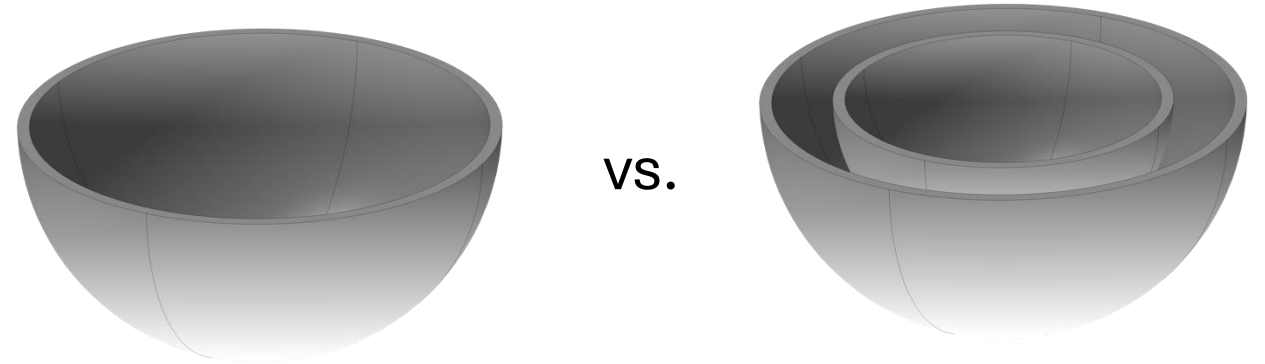
$$\Gamma_m^{ij} = \frac{1}{V_{\text{cav}}^{1/3} M} \int_{V_{\text{cav}}} d^3x \rho(\vec{x}) x^i \cdot \xi_m^j(\vec{x})$$

E.g. concentric geometries -> GW coupling should be similar

new:

$$\Gamma_m^{ij} = \frac{\int_{V_{\text{wall}}} dV \rho \xi^i x^j}{\underbrace{\sqrt{\int_{V_{\text{wall}}} dV \rho |\mathbf{x}|^2}}_{\text{Effective Radius of the Cavity } R_{\text{eff}}}}$$

Effective Radius of the Cavity R_{eff}



Old Definition: $\propto V^{-\frac{1}{3}}$ (can even diverge for $R_i \rightarrow R_o$)

New Definition: **Approx. same coupling**

- $V^{-\frac{1}{3}}$ cancels would cancel in the C_{01} definition, but the sensitivity often scales with Γ alone
- In new definition $q_{\text{vib}} \propto R_{\text{eff}} \Gamma^{ij} h_{ij}$

Vibration-EM Coupling

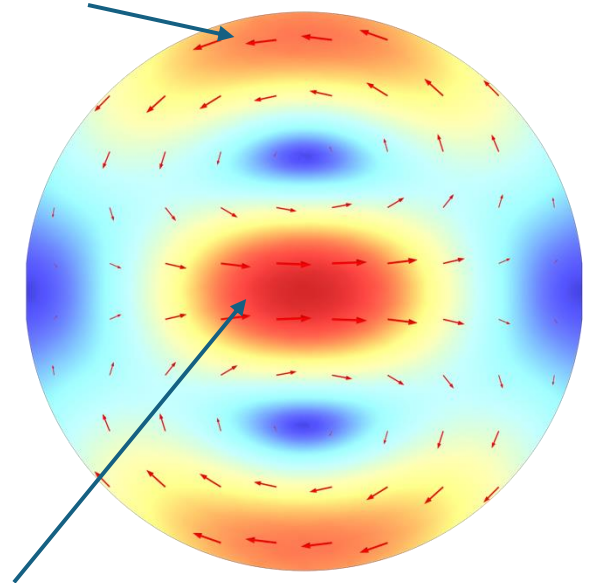
old:

$$C_{01}^m = \frac{V_{\text{cav}}^{1/3}}{2\sqrt{U_1 U_0}} \int_{\partial V_{\text{cav}}} d\vec{S} \cdot \vec{\xi}_m(\vec{x}) \left(\frac{1}{\mu_0} \vec{B}_1^* \cdot \vec{B}_0 - \epsilon_0 \vec{E}_1^* \cdot \vec{E}_0 \right)$$

new:

$$C_{01}^m := \frac{\frac{1}{A} \int_A d\mathbf{A} \cdot \boldsymbol{\xi}_m (\mathbf{B}_0 \cdot \mathbf{B}_1 - \mathbf{E}_0 \cdot \mathbf{E}_1) / 2}{\underbrace{\|\mathbf{B}_0\|_S \|\mathbf{B}_1\|_S}_{\text{Surface averaged fields}}}$$

Increases Coupling



Does nothing to the coupling

$\Rightarrow P_{sig} \propto U_0$ is false.

\Rightarrow Actually: $P_{sig} \propto \|\mathbf{B}_0\|_S^2$

\Rightarrow Again, concentric geometries do better

Rewritten Signal Power

With the new coefficients, the signal PSD becomes:

$$S_{\text{sig}}(\omega) = \frac{1}{2} \frac{\beta}{(1 + \beta)^2} Q_{\text{int}} \omega_1 \frac{(R_{\text{eff}} A_S)^2 B_c^2}{V} \frac{\|\mathbf{B}_0\|_S^2}{\mu_0 \max_{\mathbf{x} \in S} |\mathbf{B}_0(\mathbf{x})|^2} \frac{\|\mathbf{B}_1\|_S^2}{\|\mathbf{B}_1\|_V^2} S_{C_{01}^m \Gamma_m^{ij} h_{ij}}(\omega - \omega_0)$$

Critical field of Niobium

Large extend of cavity & surface good. Large volume bad → All needs to be excited

The $\frac{\|\mathbf{B}_1\|_S^2}{\|\mathbf{B}_1\|_V^2}$ term suggests that high fields away from wall are bad for sensitivity.

However, $Q_{\text{int}} = \frac{\omega_1}{R_S} \frac{V}{A_S} \frac{\|\mathbf{B}_1\|_V^2}{\|\mathbf{B}_1\|_S^2}$ i.e. what's good for Vib-EM coupling is bad for quality factor.

On the other hand, Q_{int} only matters if we don't overcouple

Figures of Merit of Cavity Geometry

Optimal signal power:

Critical coupling: $\mathcal{F}_{\text{crit}}^{ij} := \omega_1 R_{\text{eff}} \sqrt{A_S} \frac{\|\mathbf{B}_0\|_S}{\max_{\mathbf{x} \in S} |\mathbf{B}_0(\mathbf{x})|} |C_{01}^m| \Gamma_m^{ij},$

Overcoupling: $\mathcal{F}_{\text{over}}^{ij} := \sqrt{\omega_1} \frac{R_{\text{eff}} A_S}{\sqrt{V}} \frac{\|\mathbf{B}_0\|_S}{\max_{\mathbf{x} \in S} |\mathbf{B}_0(\mathbf{x})|} \frac{\|\mathbf{B}_1\|_S}{\|\mathbf{B}_1\|_V} |C_{01}^m| \Gamma_m^{ij},$

Usually $\omega_1 \propto 1/\sqrt{A_S}$

Optimal sensitivity:

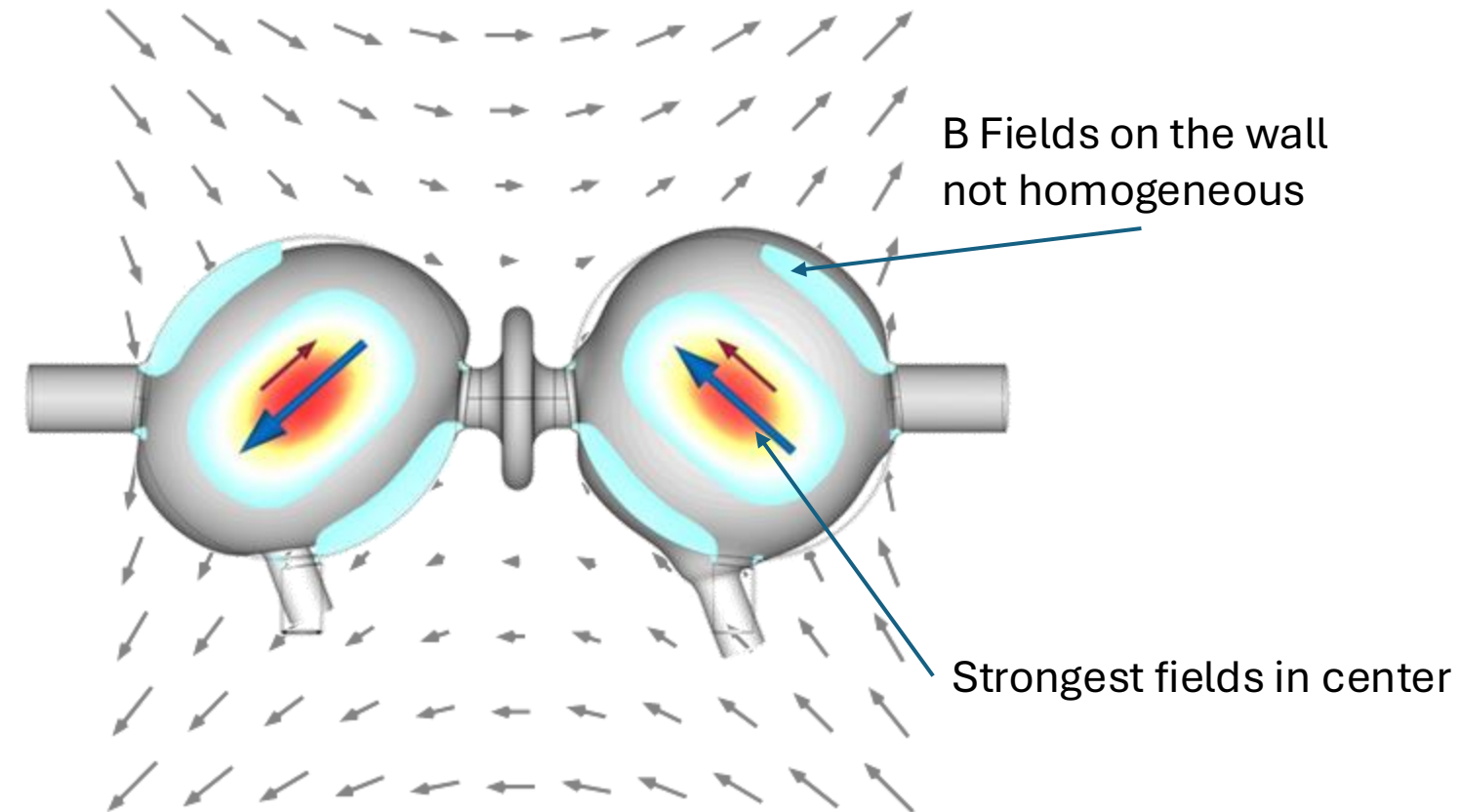
Thermal noise in cavity: $\mathcal{F}_{\text{crit}}^{ij}$

SQL readout noise: $\mathcal{F}_{\text{r}}^{ij} = \mathcal{F}^{ij} / \sqrt{\omega_1}.$

Thermal or mechanical vibrations: $\mathcal{F}_{\text{th. } m}^{ij} = R_{\text{eff}} \Gamma_m^{ij}.$

The remaining parameters **surface resistance** R_s , **mass** M , **critical field** B_c , **temperature** T don't need to be part of an optimization process and don't (directly) depend on the geometry.

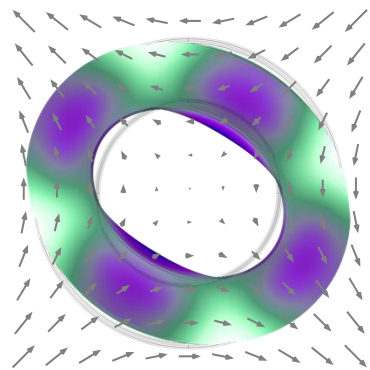
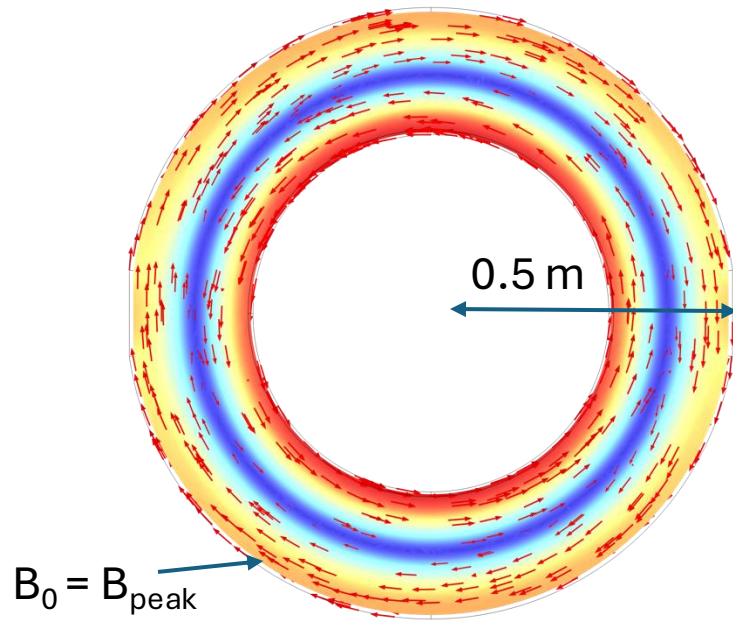
Example for a geometry



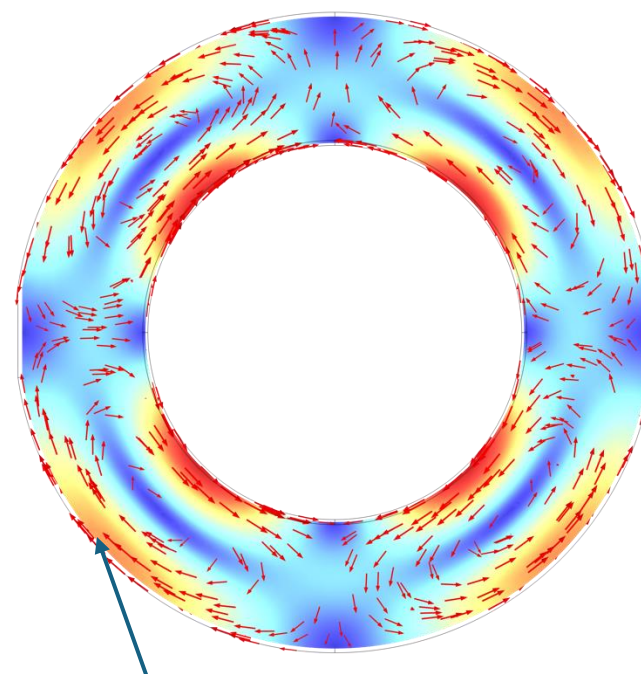
Γ coupling to GW ok, but not perfect
 C_{01} is comparatively high!

$$\begin{aligned} R_{eff} &= 0.17 \text{ m} \\ A_S &= 0.26 \text{ m}^2 \\ \Gamma_{\max} &= 0.3 \\ C_{01} &= 0.15 \\ \frac{\|B_0\|_S}{\max_{x \in S} |B_0(x)|} &= 0.6 \\ \frac{\|B_1\|_S}{\|B_1\|_V} &\ll 1 \end{aligned}$$

Concentric Cylinder



Γ coupling to GW as good as it gets



Surface Average greater than volume average

ω_0, ω_1 don't depend on R_{eff}

Disadvantage: Modes only for \gg MHz GWs possible

$$R_{eff} = 0.4 \text{ m}$$

$$A_S = 2 \text{ m}^2$$

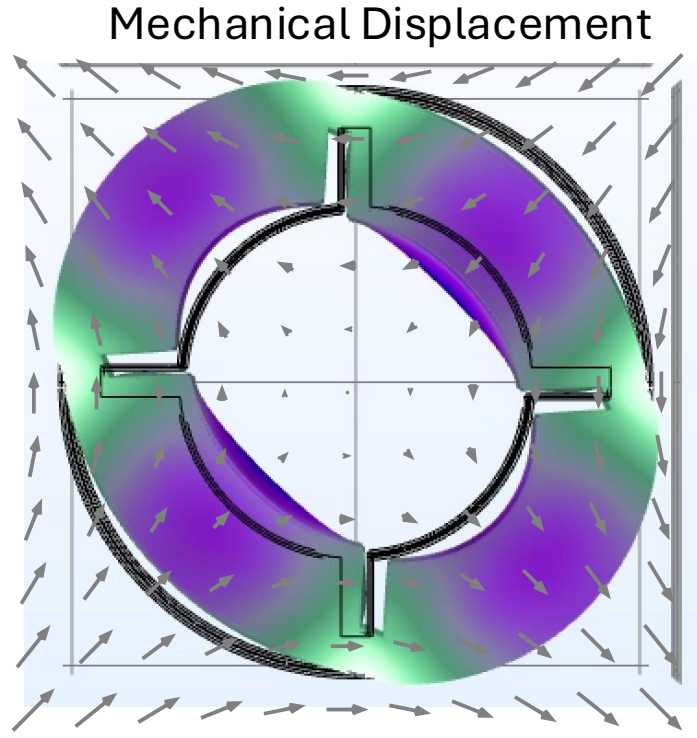
$$\Gamma_{\max} = 0.74$$

$$C_{01} = 0.1$$

$$\frac{\|B_0\|_S}{\max_{x \in S} |B_0(x)|} = 0.73$$

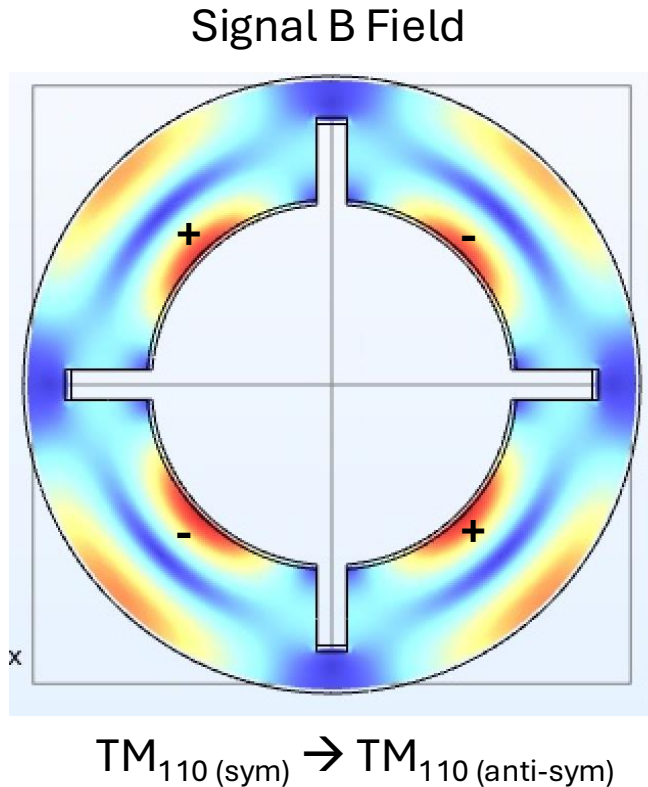
$$\frac{\|B_1\|_S}{\|B_1\|_V} = 1.12$$

Sectioned Concentric Cylinder



Γ coupling to GW as good as it gets

- Could also have more than 4 sections. Not all need to be coupled
- Increased sensitivity due to more cavities & improved directional sensitivity
- In most noise limited cases no loss of sensitivity due to smaller surface area



Similar performance as previous
but frequency spacing arbitrarily small

$$R_{eff} = 0.4 \text{ m}$$

$$A_S = 2 \text{ m}^2$$

$$\Gamma_{\max} = 0.8$$

$$C_{01} = 0.11$$

$$\frac{\|B_0\|_S}{\max_{x \in S} |B_0(x)|} = 0.5$$

$$\frac{\|B_1\|_S}{\|B_1\|_V} = 1.1$$

Conclusion

- Rewriting the signal power helps identifying how an ideal cavity should look like
- Examples of concentric geometries support this interpretation
- Figures of merit help setting upper bounds on how well the detection concept could possibly function → in progress
- A similar analysis can be done for heterodyne Gertsenshtein interactions → in progress with Lars