

Accuracy and uncertainty control for ML-Amplitudes

Nina Elmer

KISS Annual meeting
12.03.2025

arXiv: 2412.12069

with L. Favaro, M. Haußmann, R. Winterhalder and T. Plehn

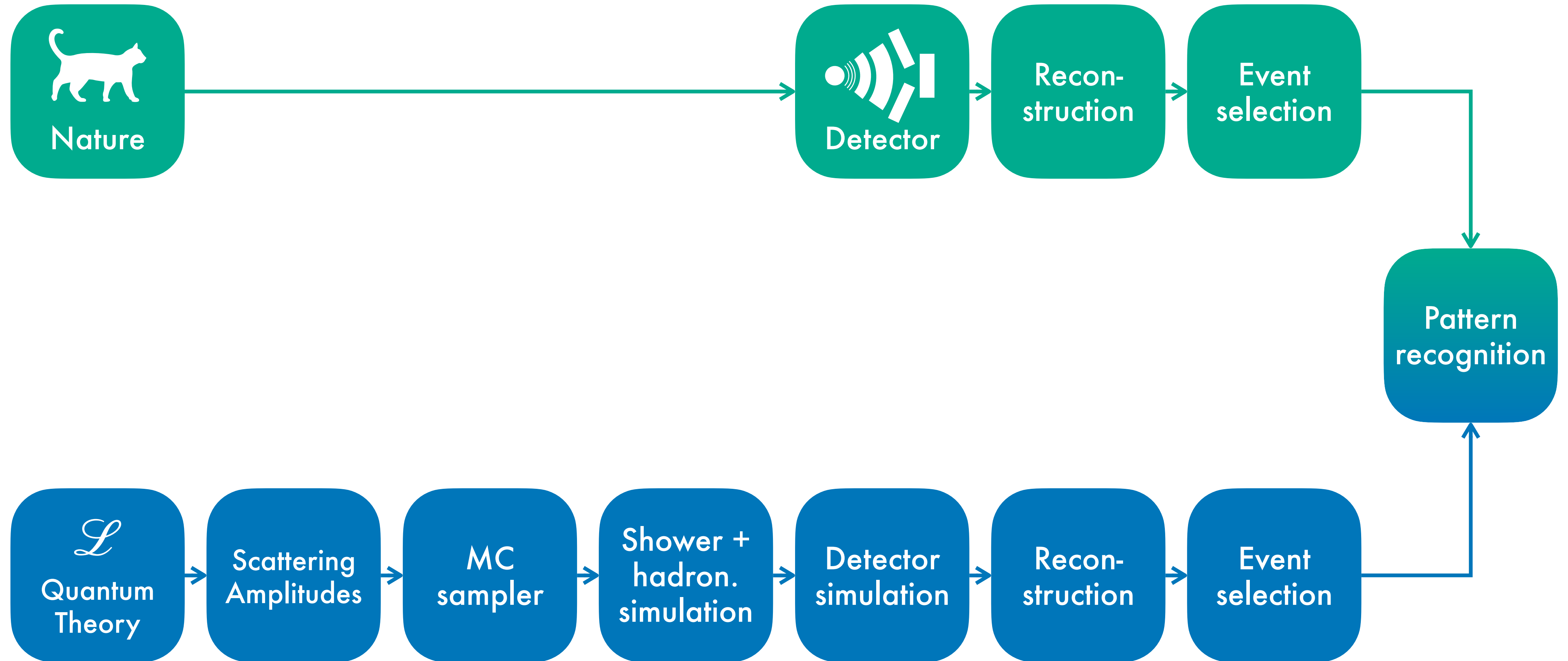


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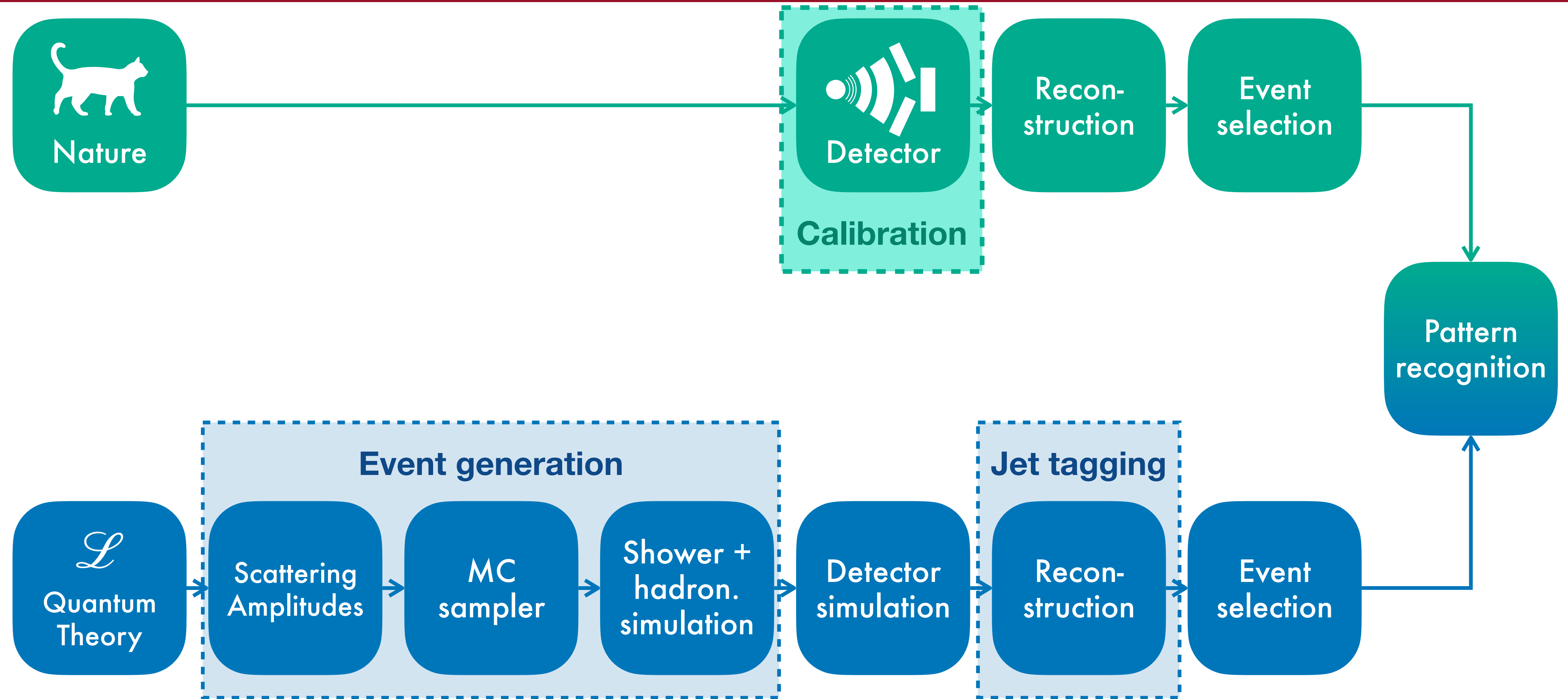
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for Precision Tests of
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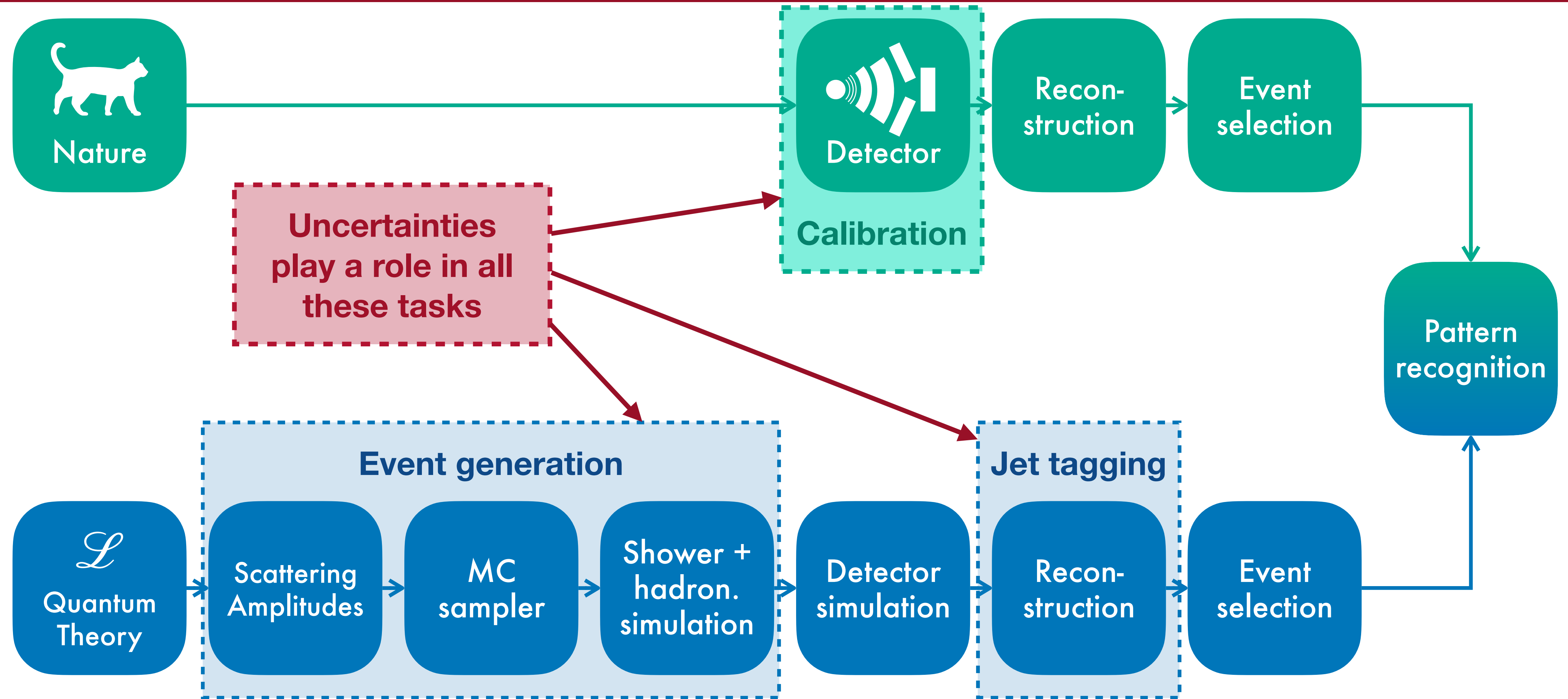
LHC physics and machine learning



LHC physics and machine learning



LHC physics and machine learning



Motivation

- **Reliable interpolation** of two-loop amplitudes [[2412.09534](#)]
- Scaling up to $Z + 5j$ [[2411.00446](#)]
- Amplitude surrogates part of MadGraph and MadNIS (besides generative integration)
→ Theo's talk

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 1. **Faster precision** simulations
 2. **Control** through calibrated uncertainties

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- Can they be controlled?
- Two types of uncertainties:
 - **Systematic**: Plateaus for perfect training (epistemic uncertainty)
 - **Statistical**: Vanishes for perfect training (aleatoric uncertainty)

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- Fit set of Amplitudes $A(x)$ with training data: $\{x, A(x)\}$

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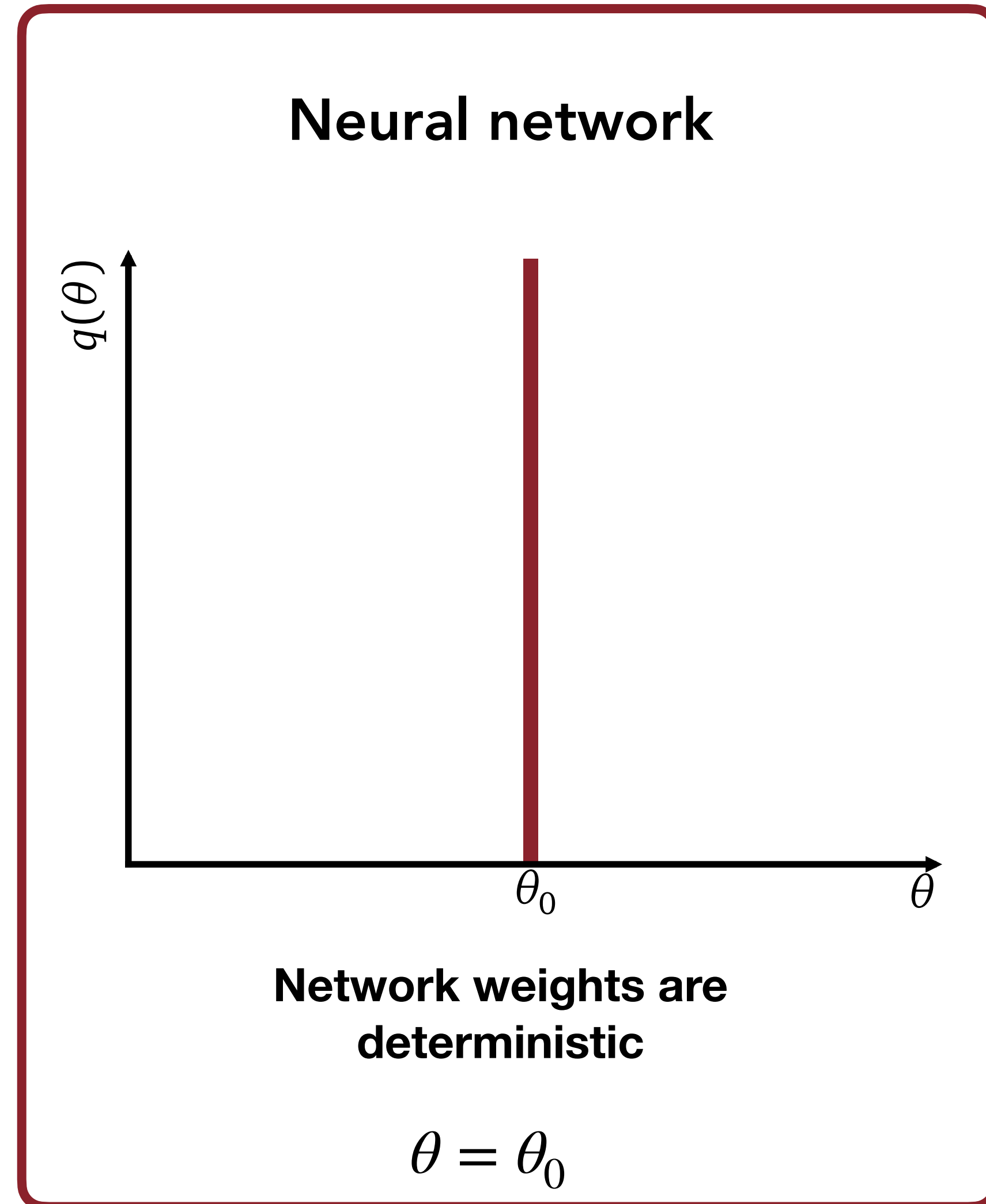
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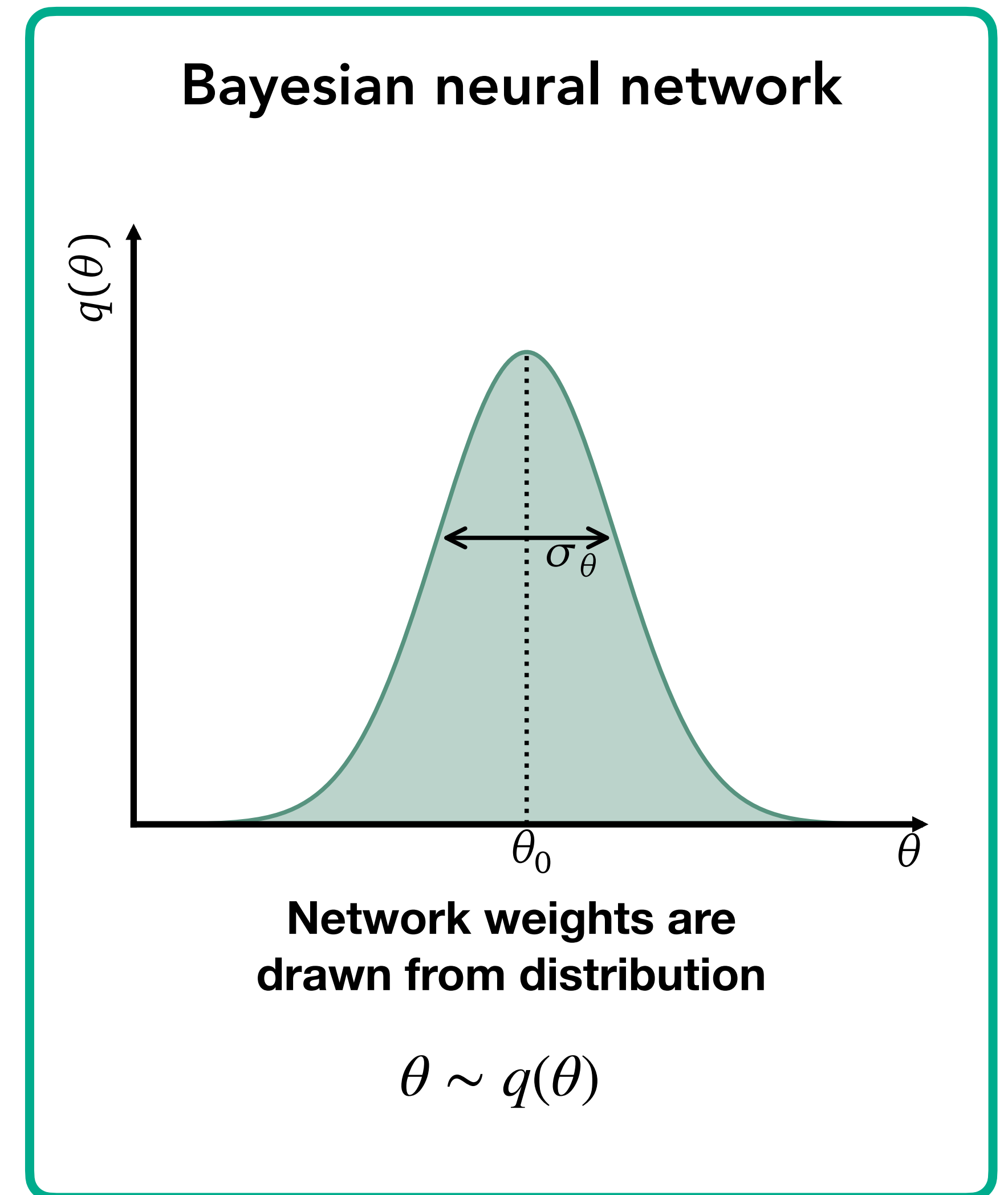
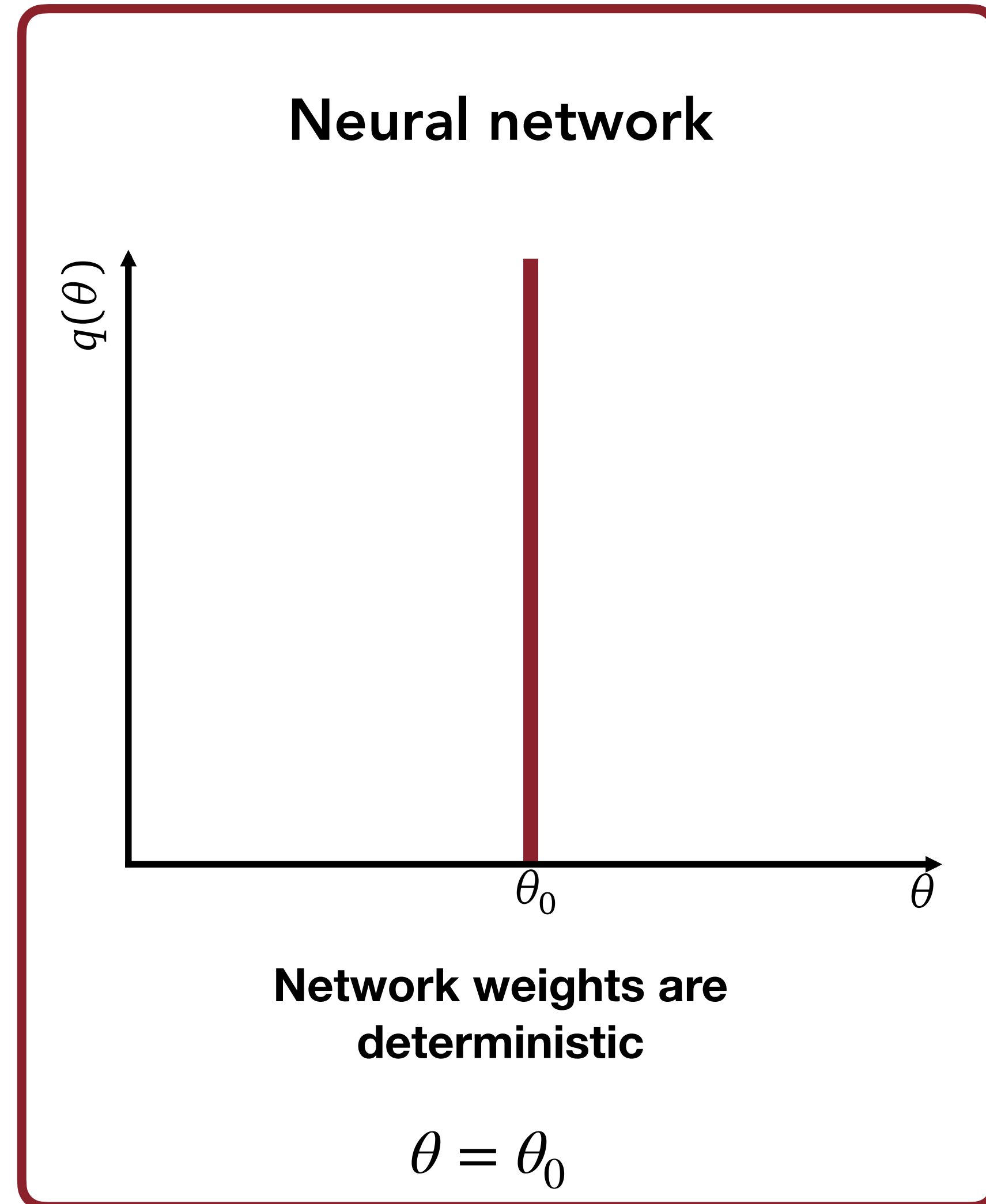
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Bayesian neural networks (BNNs)



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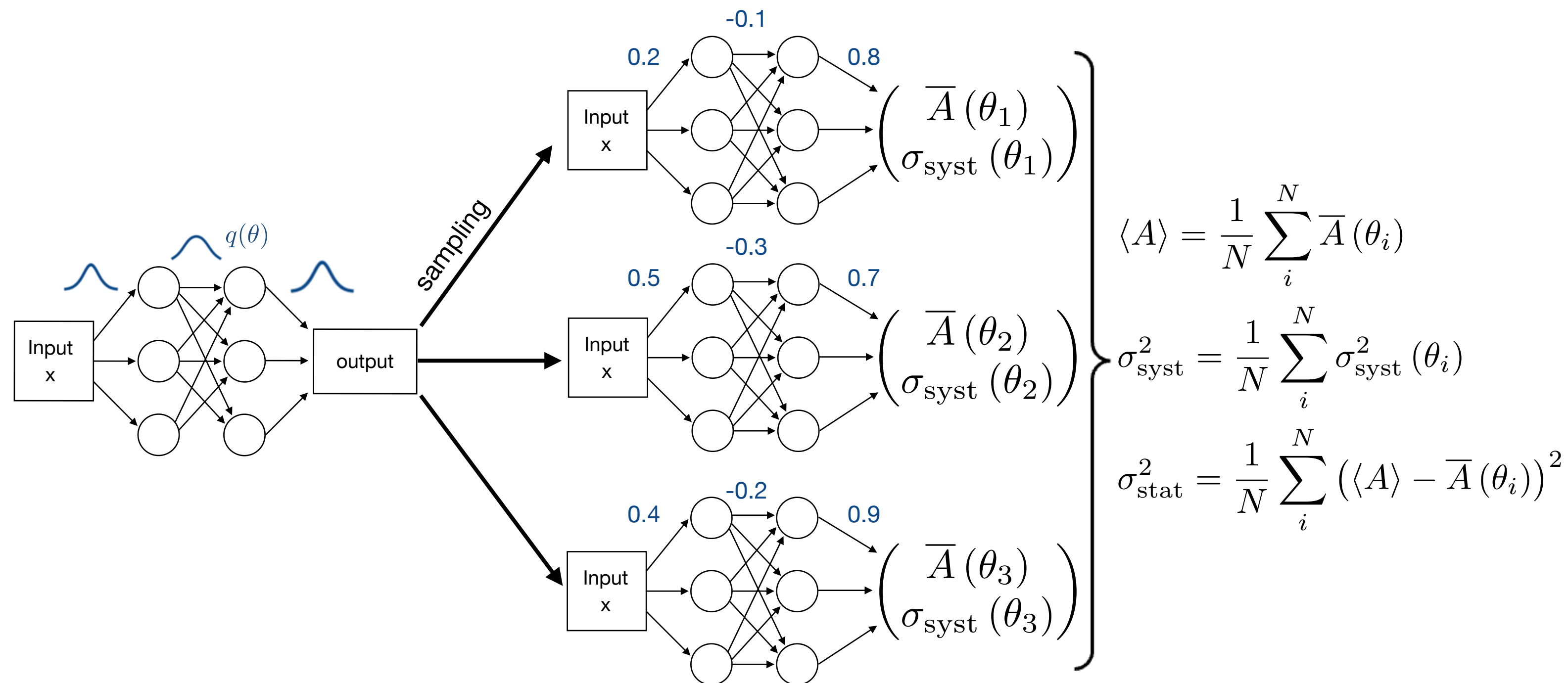


Bayesian neural networks (BNNs)

BNN

Ensemble of networks

Output



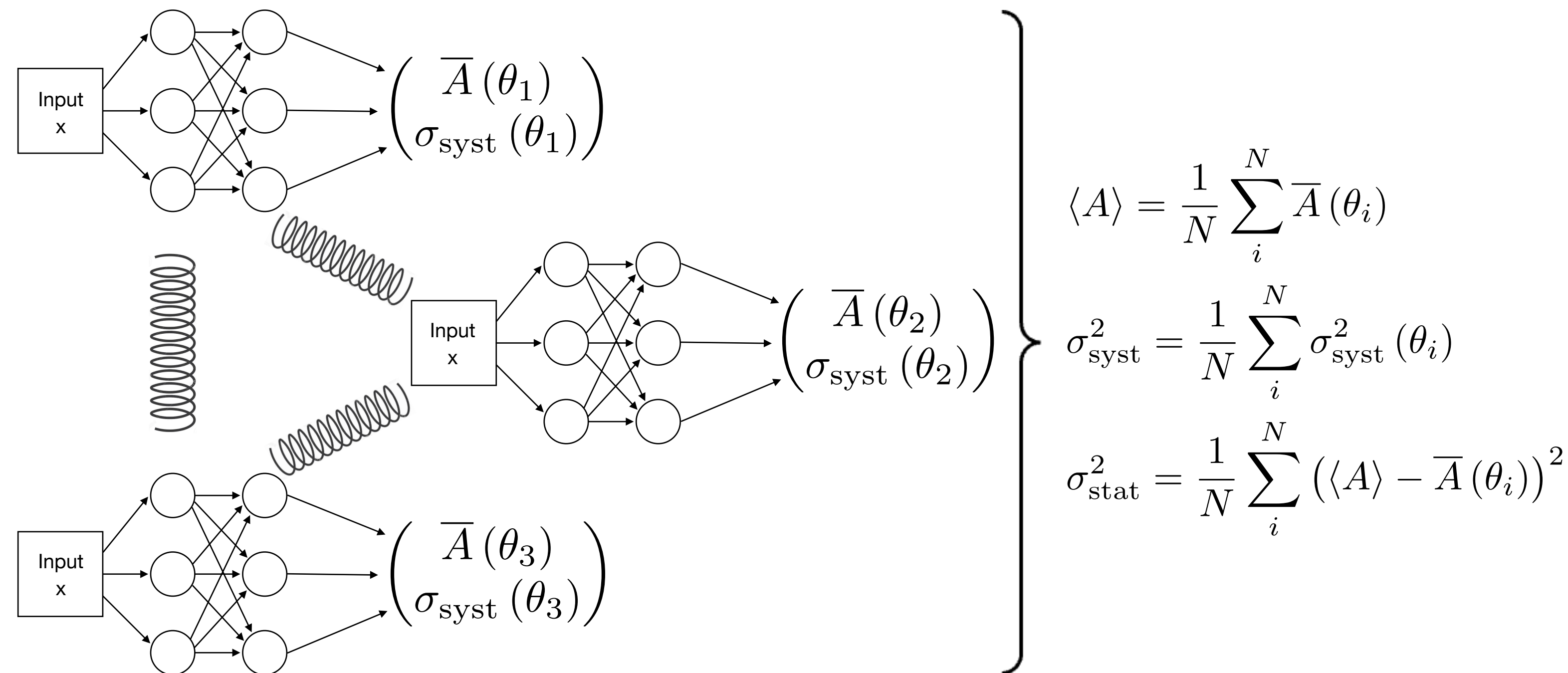
$$\mathcal{L}_{\text{BNN}} = \sum_x \left[\text{KL}[q(\theta), p(\theta)] - \langle \log p(D_{\text{train}} | \theta) \rangle_{\theta \sim q(\theta)} \right]$$

- Parameters: **Network weights** $q(\theta)$
- $q(\theta)$: Params of a Gaussian
- Ensemble: **Sample** $q(\theta)$

Repulsive ensembles (REs)

Ensemble of networks

Output



$$\langle A \rangle = \frac{1}{N} \sum_i^N \bar{A}(\theta_i)$$

$$\sigma_{\text{syst}}^2 = \frac{1}{N} \sum_i^N \sigma_{\text{syst}}^2(\theta_i)$$

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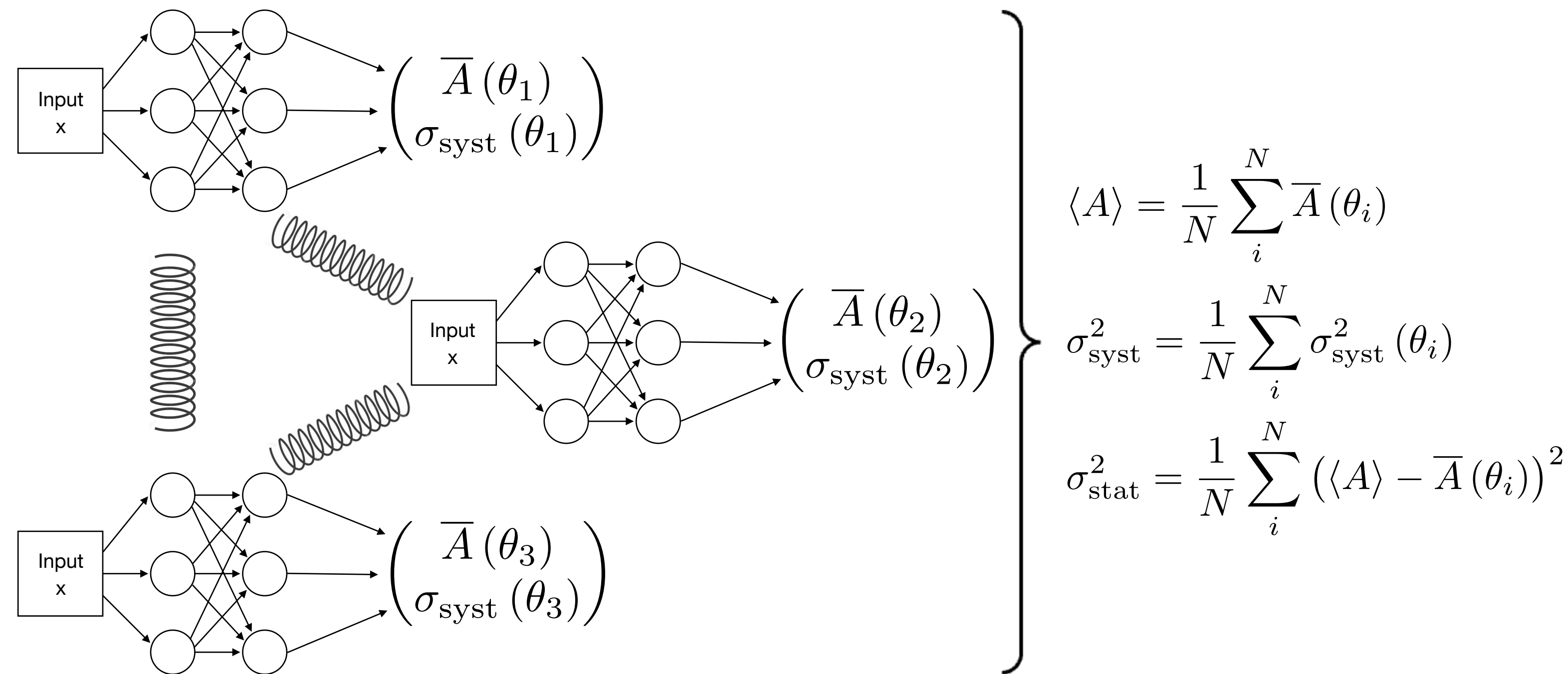
- Repulsive term:
Cover **full posterior** distribution
- Members **trained simultaneously**

$$\mathcal{L}_{\text{RE}} = \sum_{i=1}^n \left[-\frac{1}{B} \sum_{b=1}^B \log p(x_b | \theta_i) + \frac{\beta}{N} \frac{\sum_{j=1}^n k(A_{\theta_i}(x), \overline{A_{\theta_j}(x)})}{\sum_{j=1}^n k(\overline{A_{\theta_i}(x)}, \overline{A_{\theta_j}(x)})} + \frac{\theta_i^2}{2N\sigma^2} \right]$$

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Learning Amplitudes

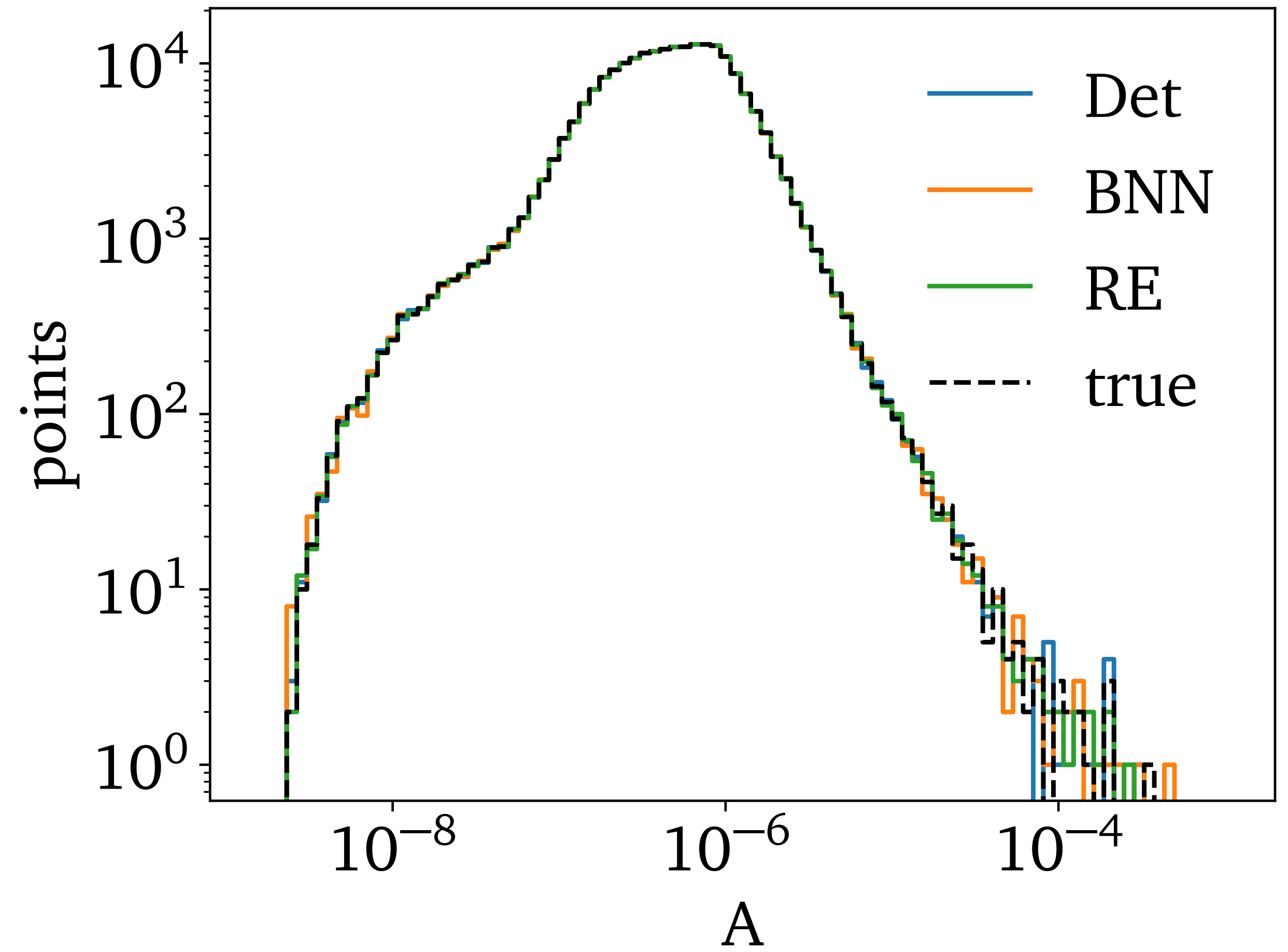
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 - $|\eta_j| < 5$
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Adding Gaussian noise

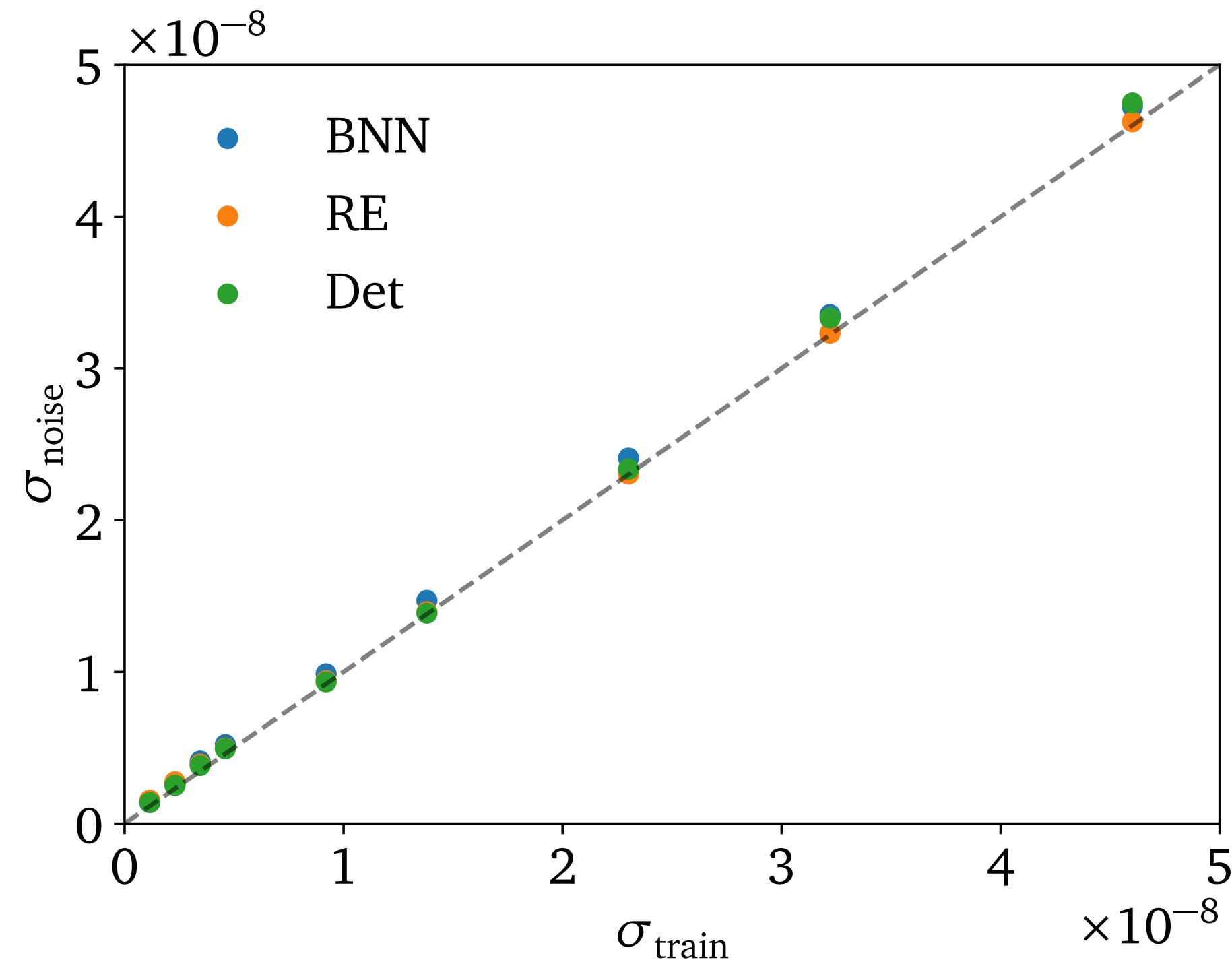
$$\sigma_{\text{tot}}^2 = \sigma_{\text{syst},0}^2 + \sigma_{\text{noise}}^2 + \sigma_{\text{stat}}^2$$

$$\sigma_{\text{train}} = f_{\text{smear}} A_{\text{true}}$$

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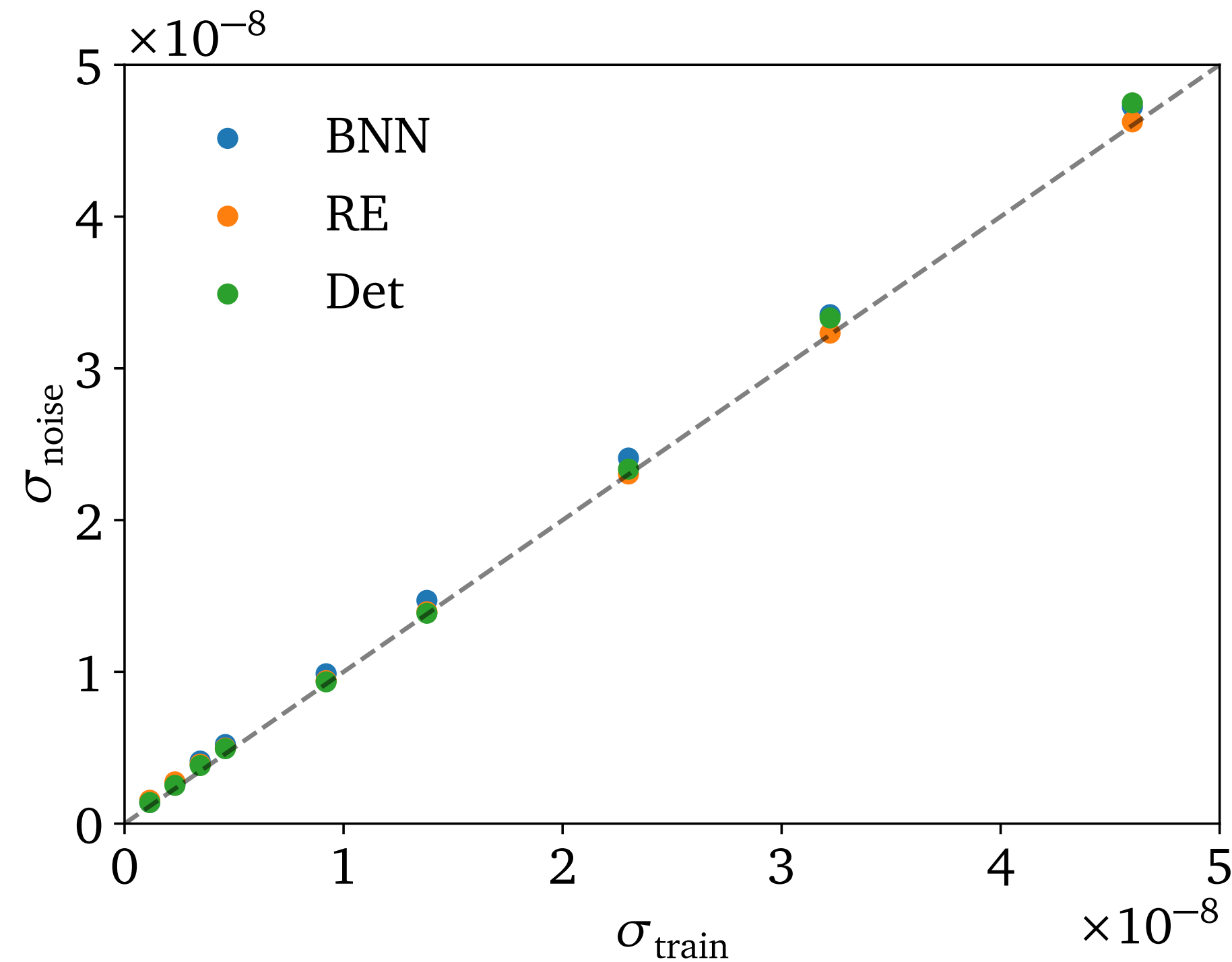
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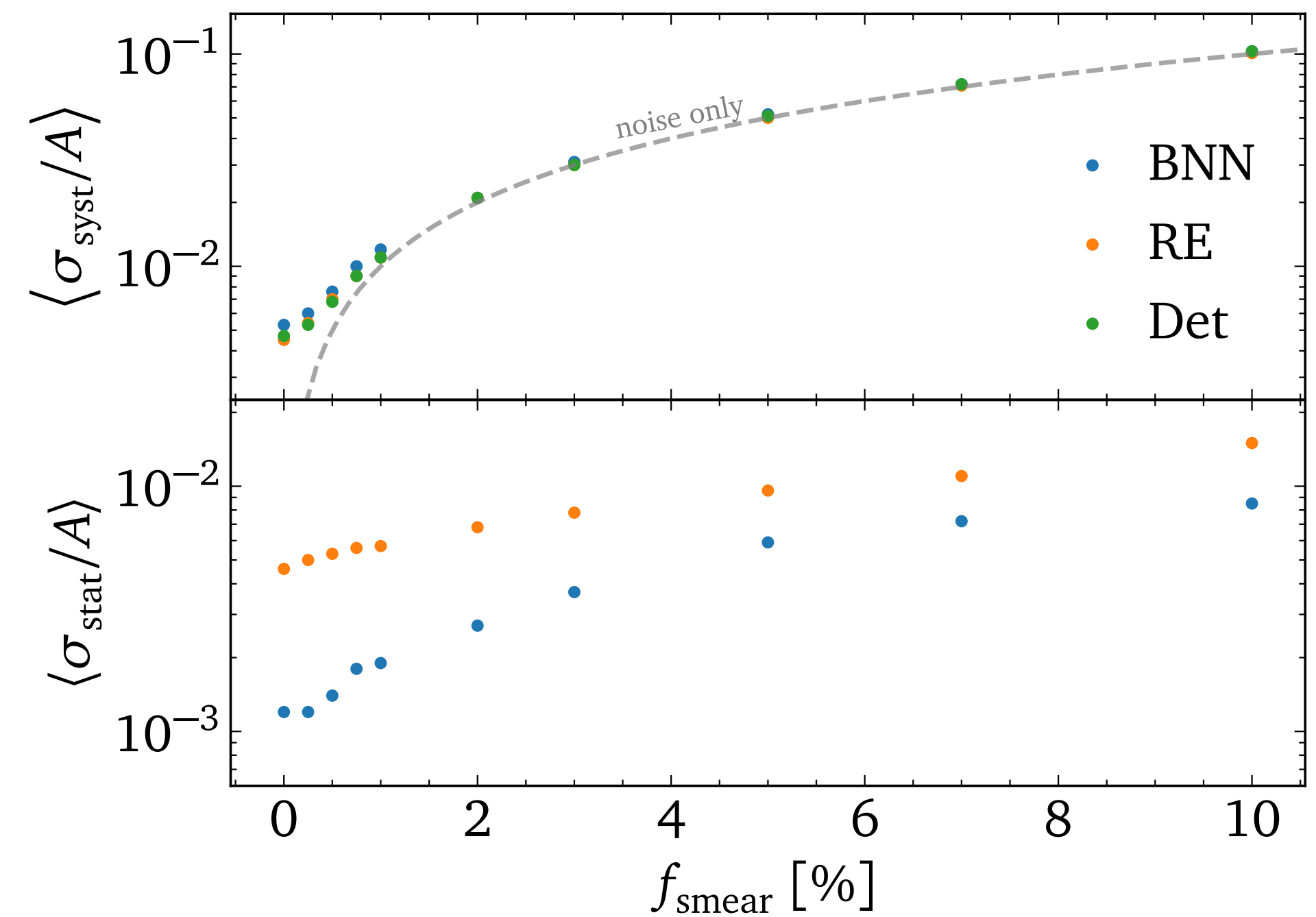


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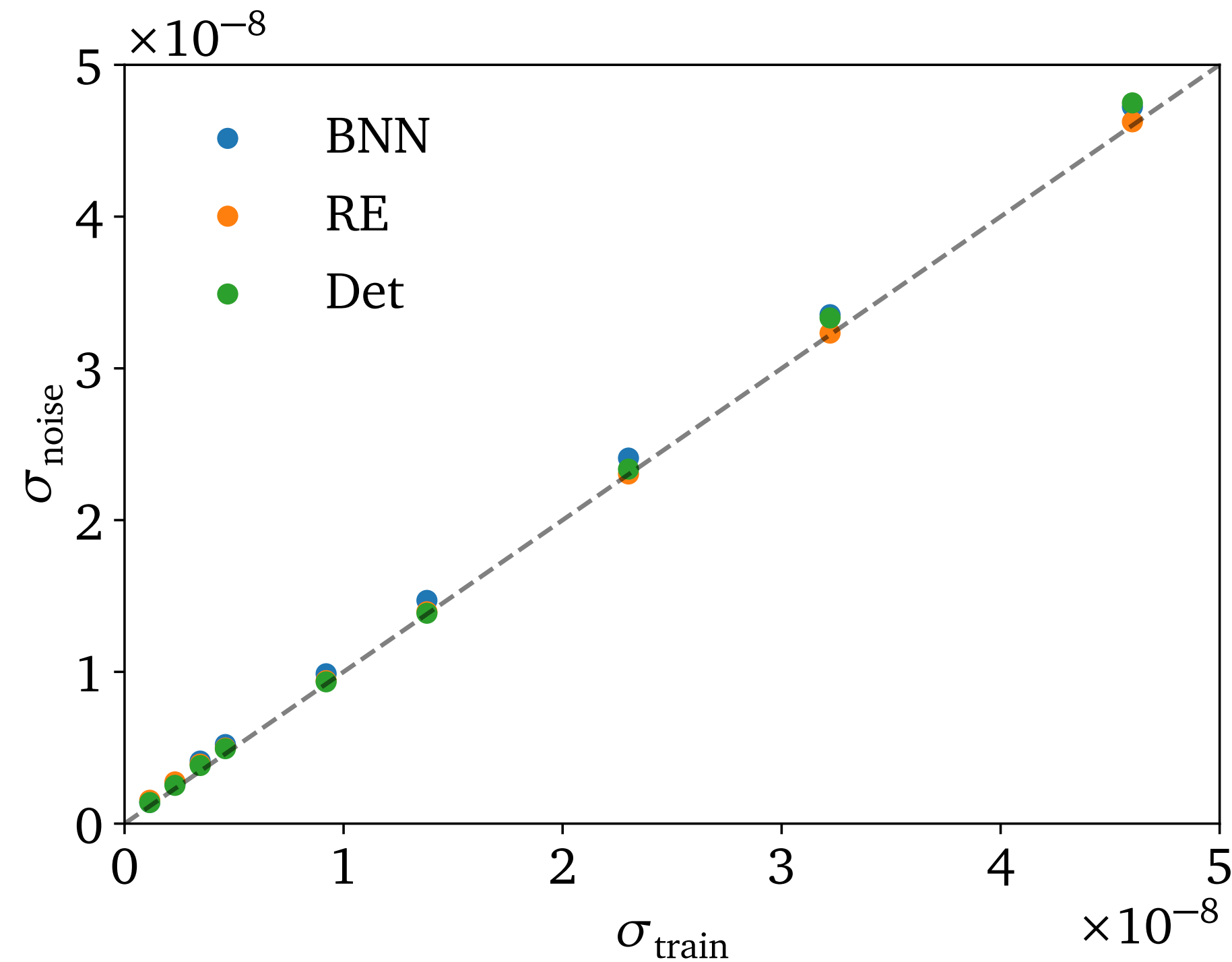


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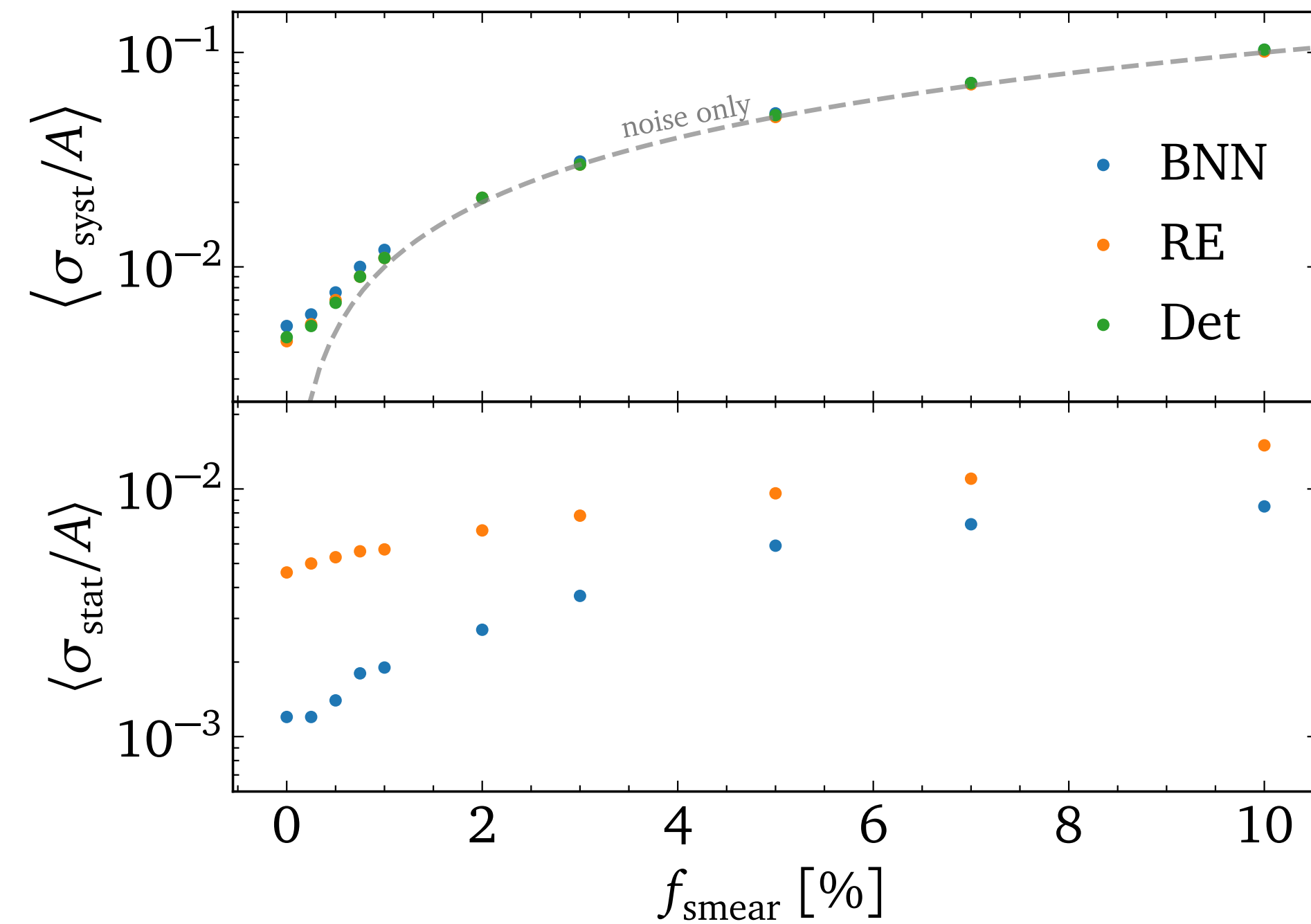


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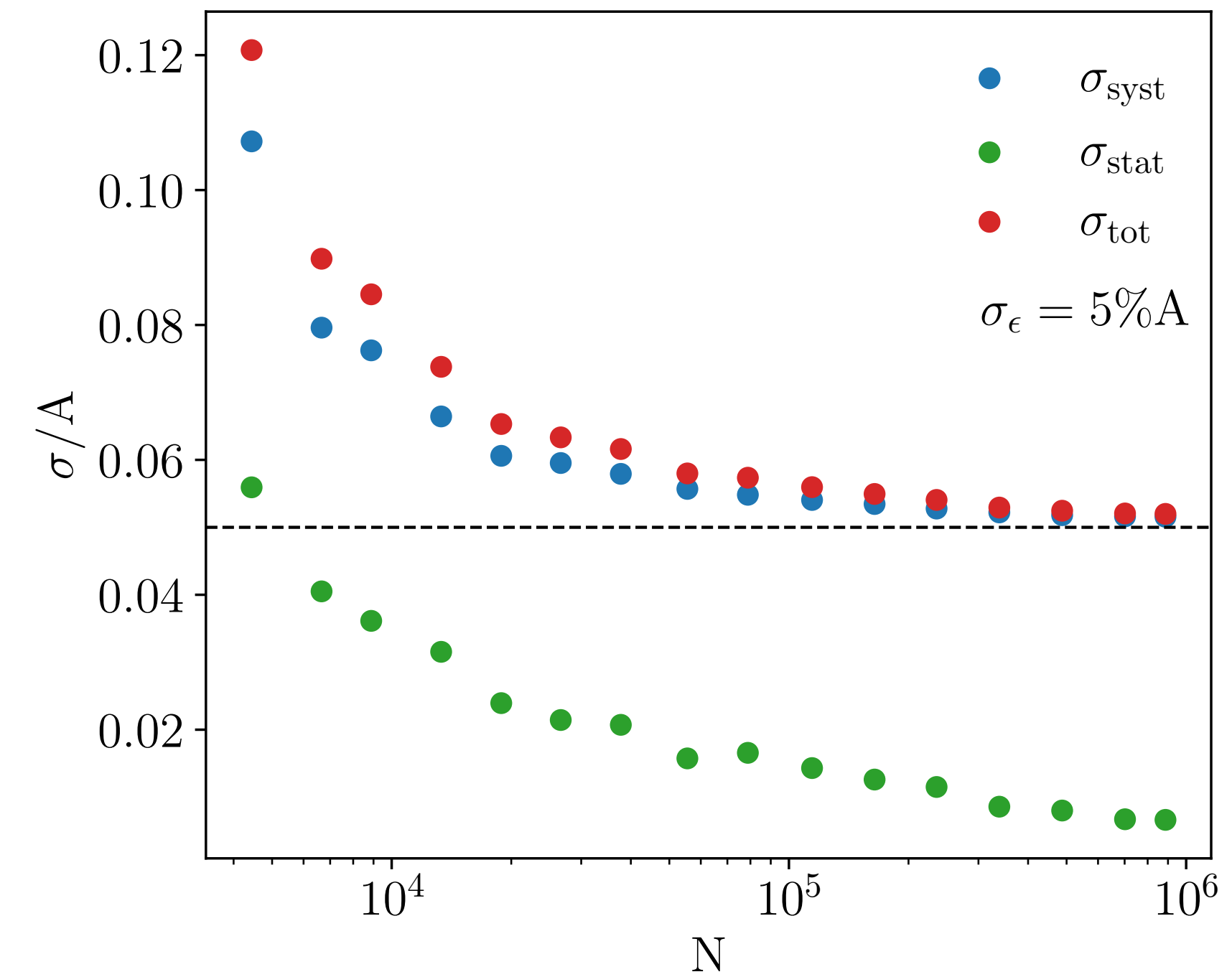
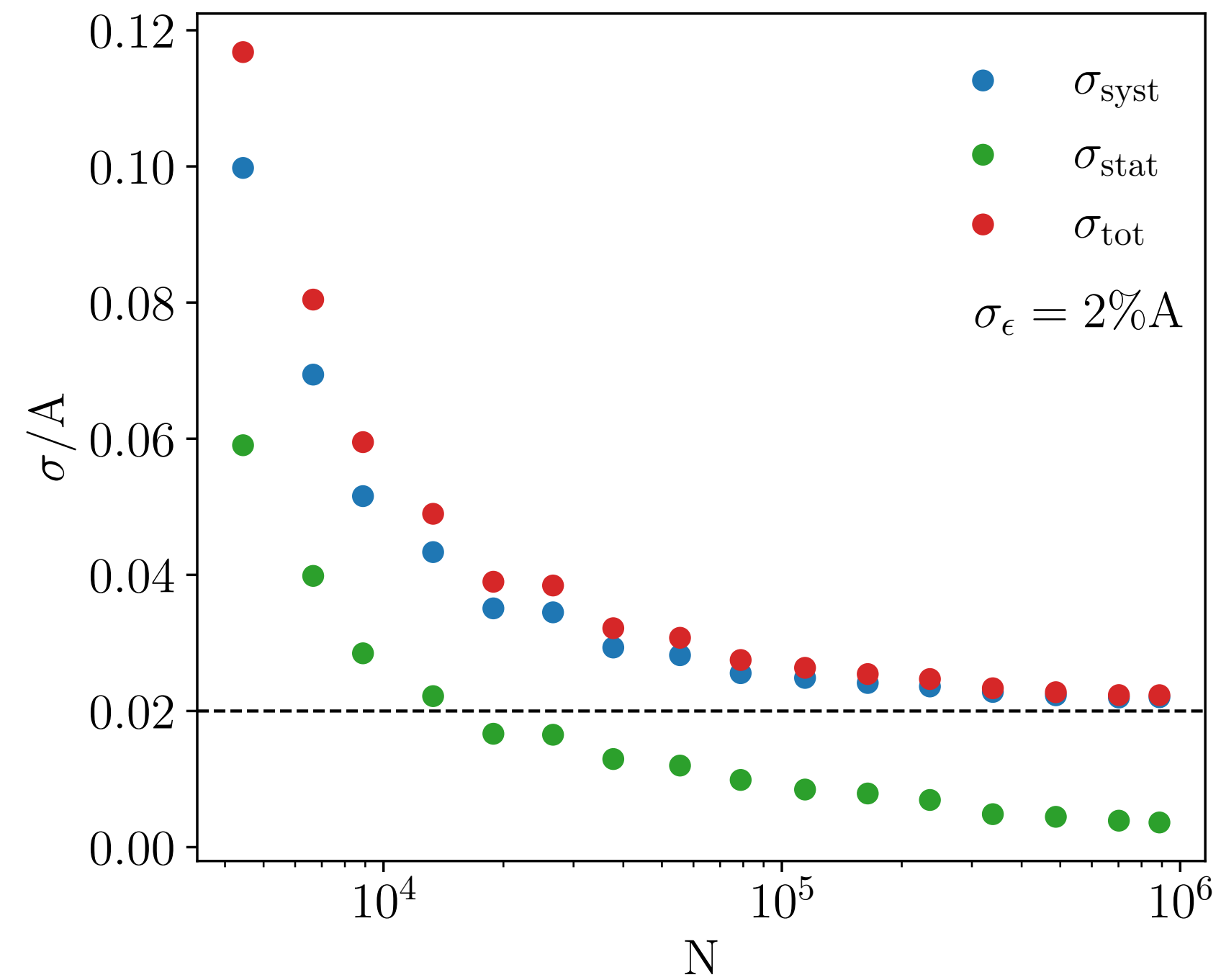
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➡ Networks learn noise as **systematic** uncertainty

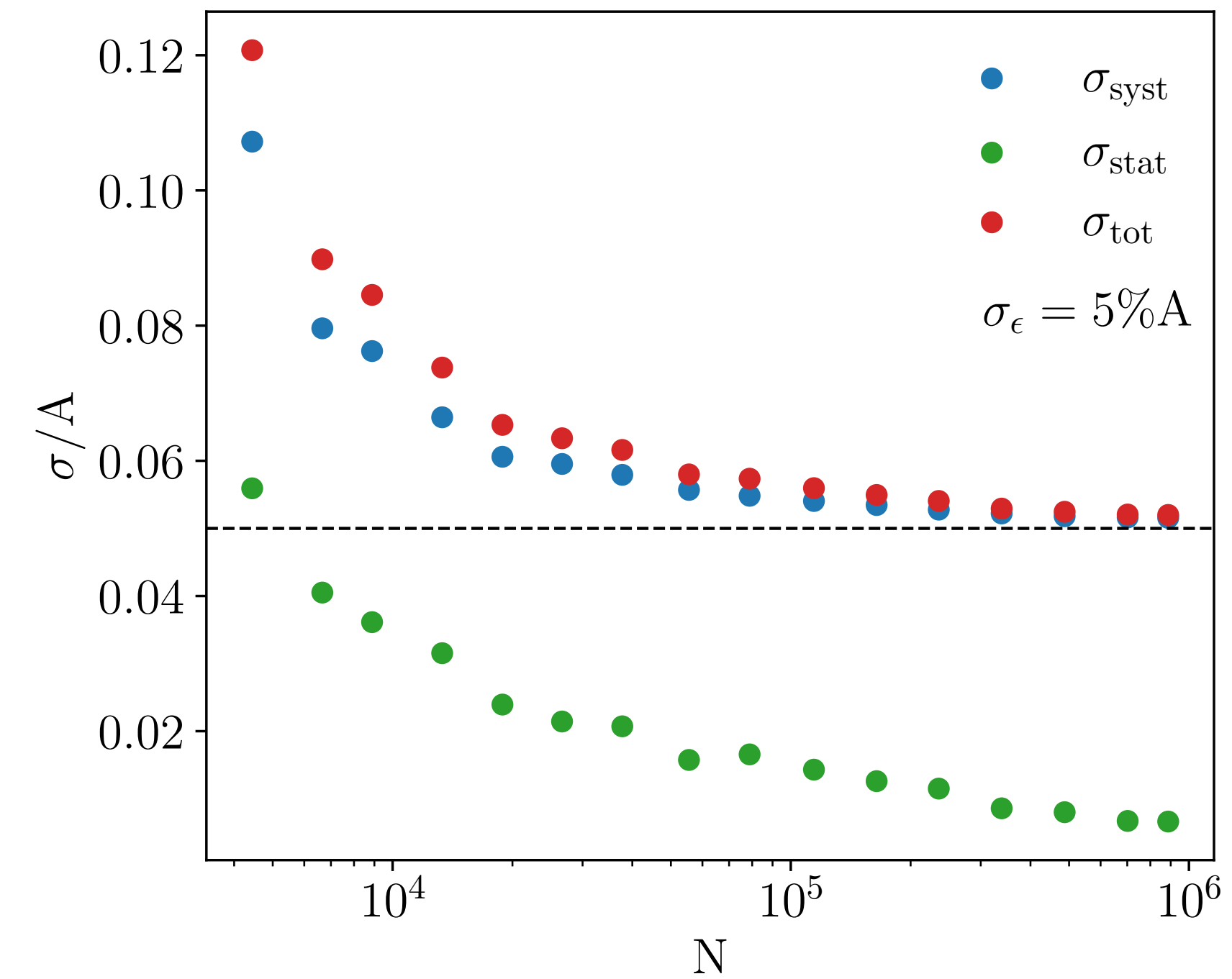
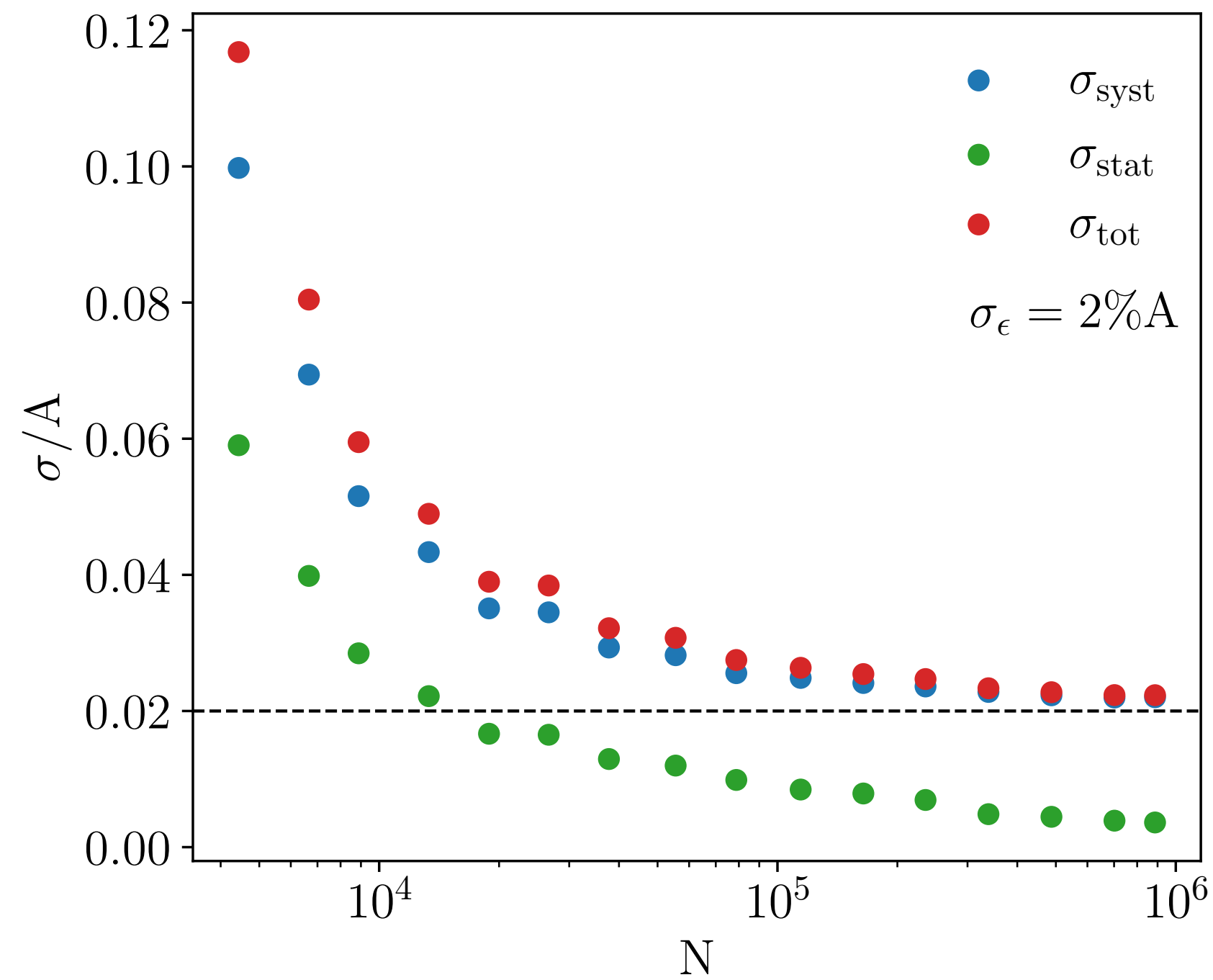
➡ **Intrinsic uncertainty** of 0.4%

Uncertainty behavior



BNN only

Uncertainty behavior



BNN only

1. Statistical uncertainty **independent** of noise
2. Systematic uncertainty **plateaus** on noise level

Calibration of results

Relative deviation

Pull distribution

Calibration of results

Relative deviation



$$\Delta(x) = \frac{A_{\text{NN}}(x) - A_{\text{true}}(x)}{A_{\text{true}}(x)}$$

Pull distribution

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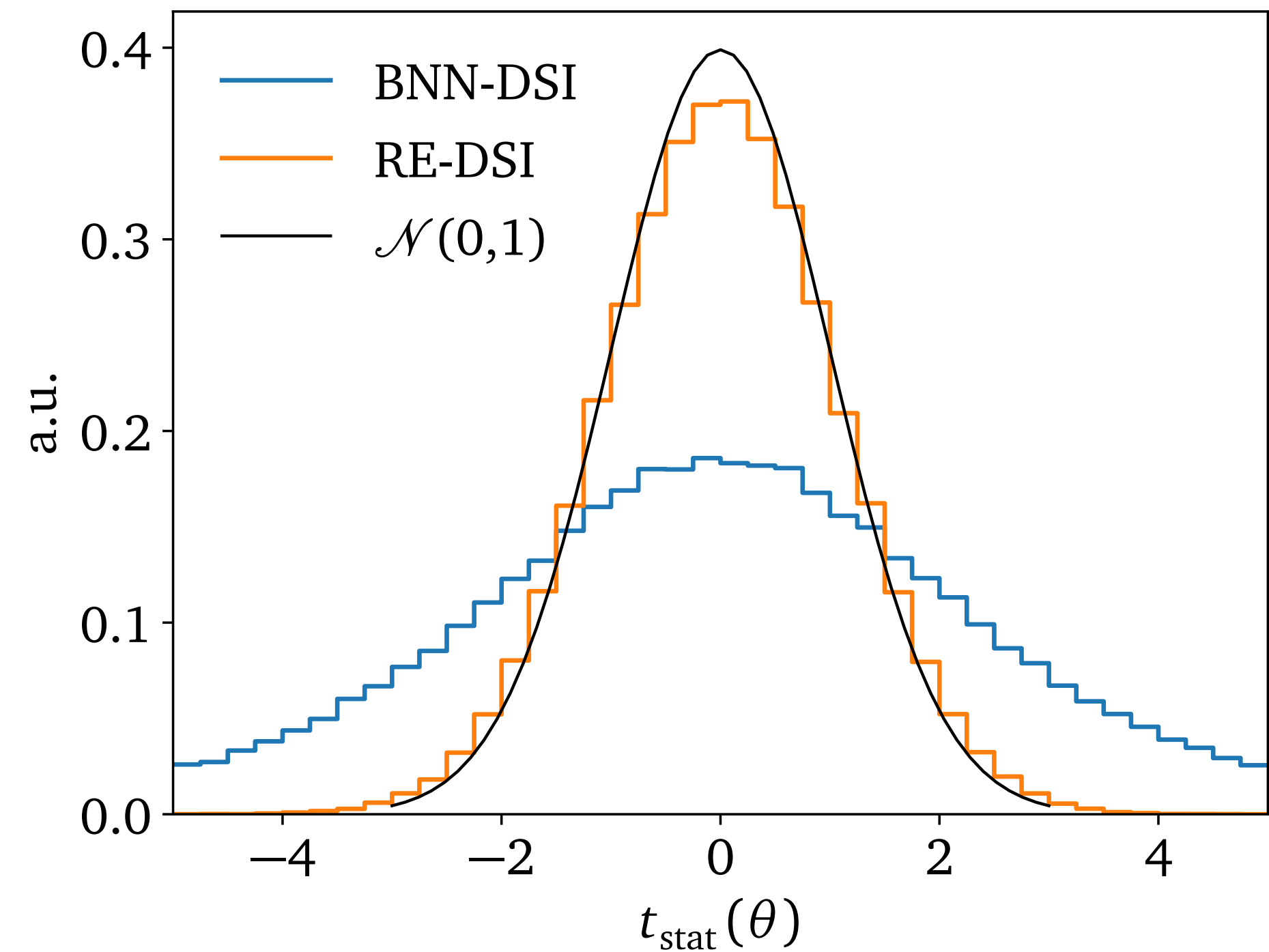
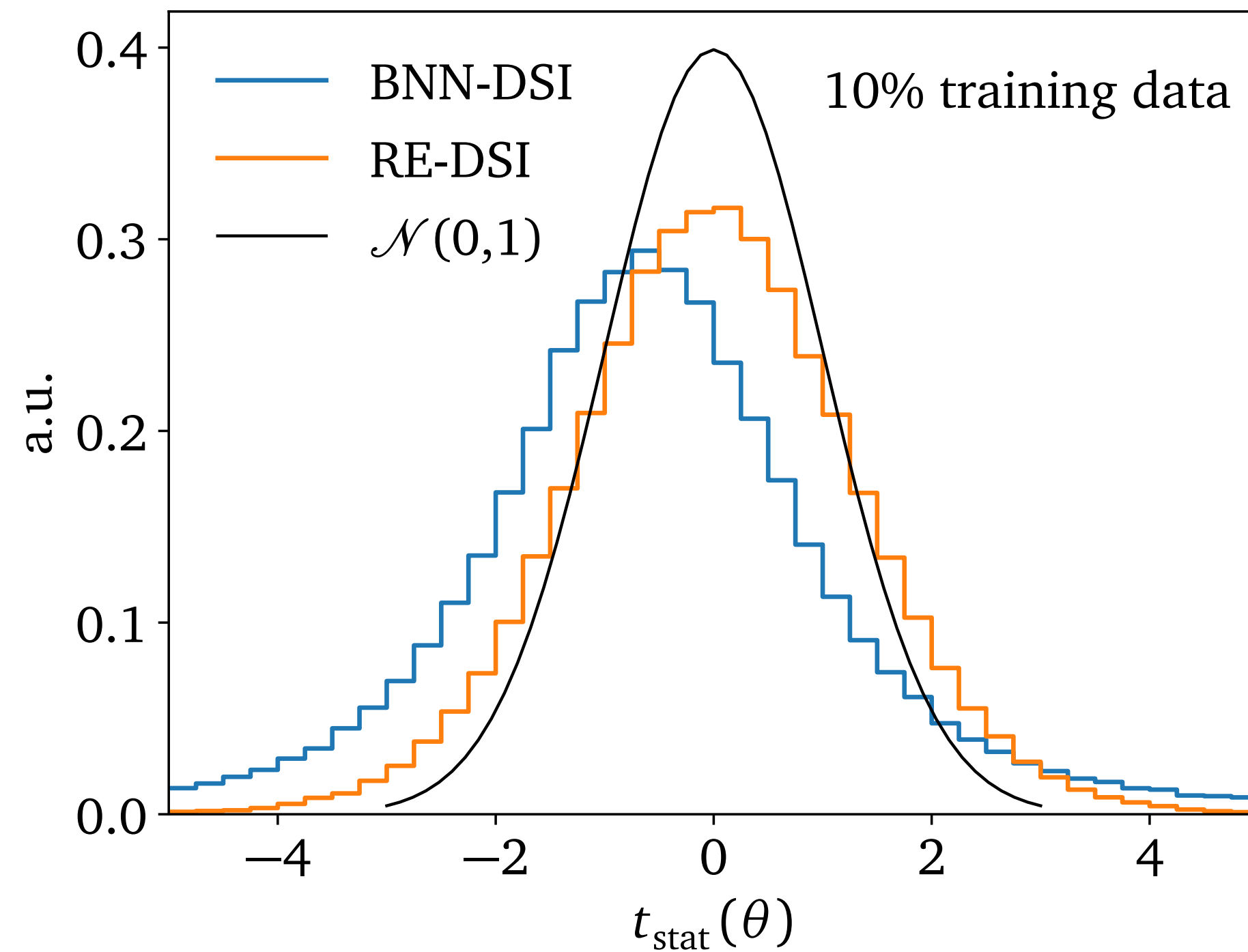
Correctly learned:
follow **Gaussian**

Reducing the training size

- Systematic uncertainty dominant over statistical
- Training on 700000 phase space points: $\sigma_{\text{tot}}(x) \approx \sigma_{\text{syst}}(x) \gg \sigma_{\text{stat}}(x)$
- Reducing training data to 100000 phase space points

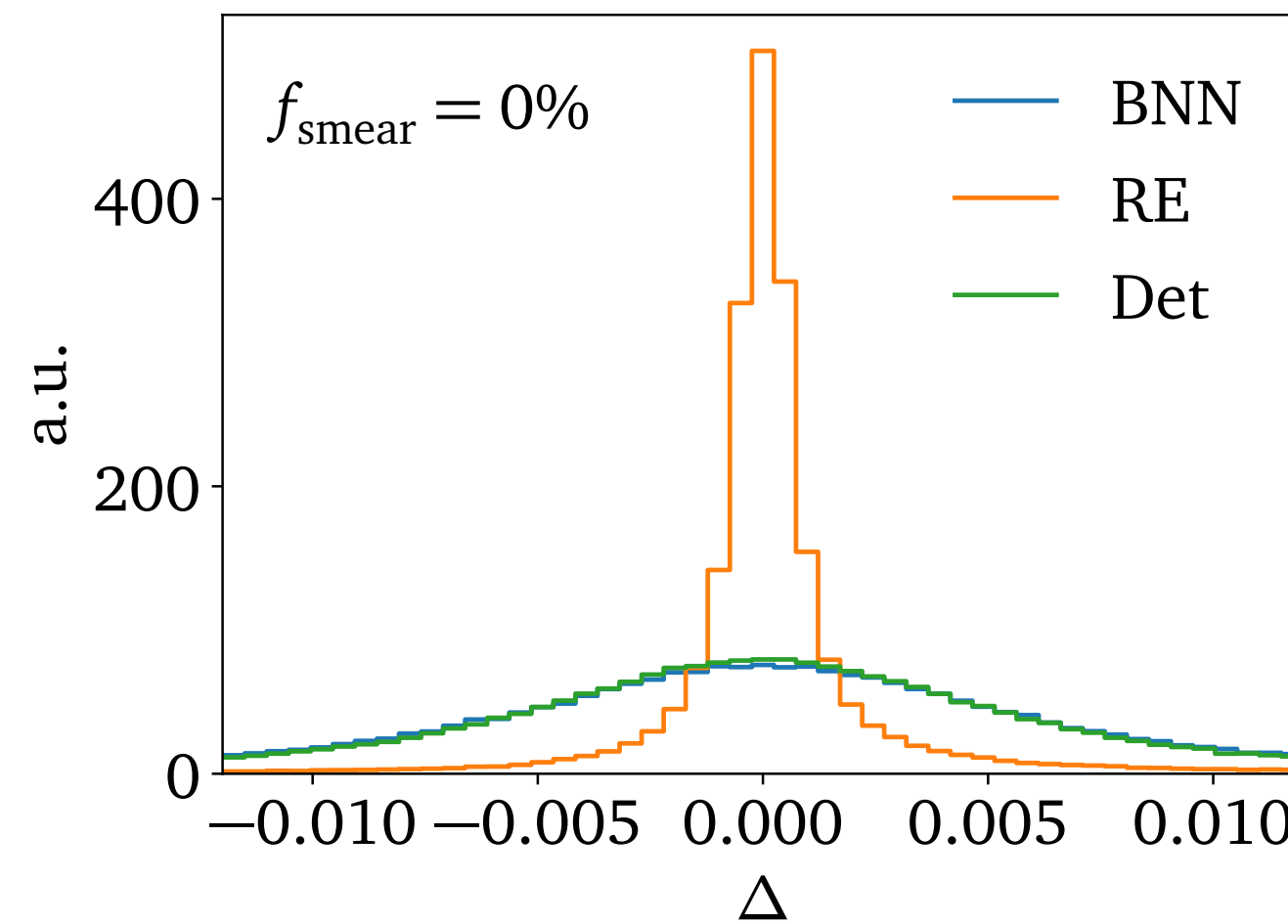
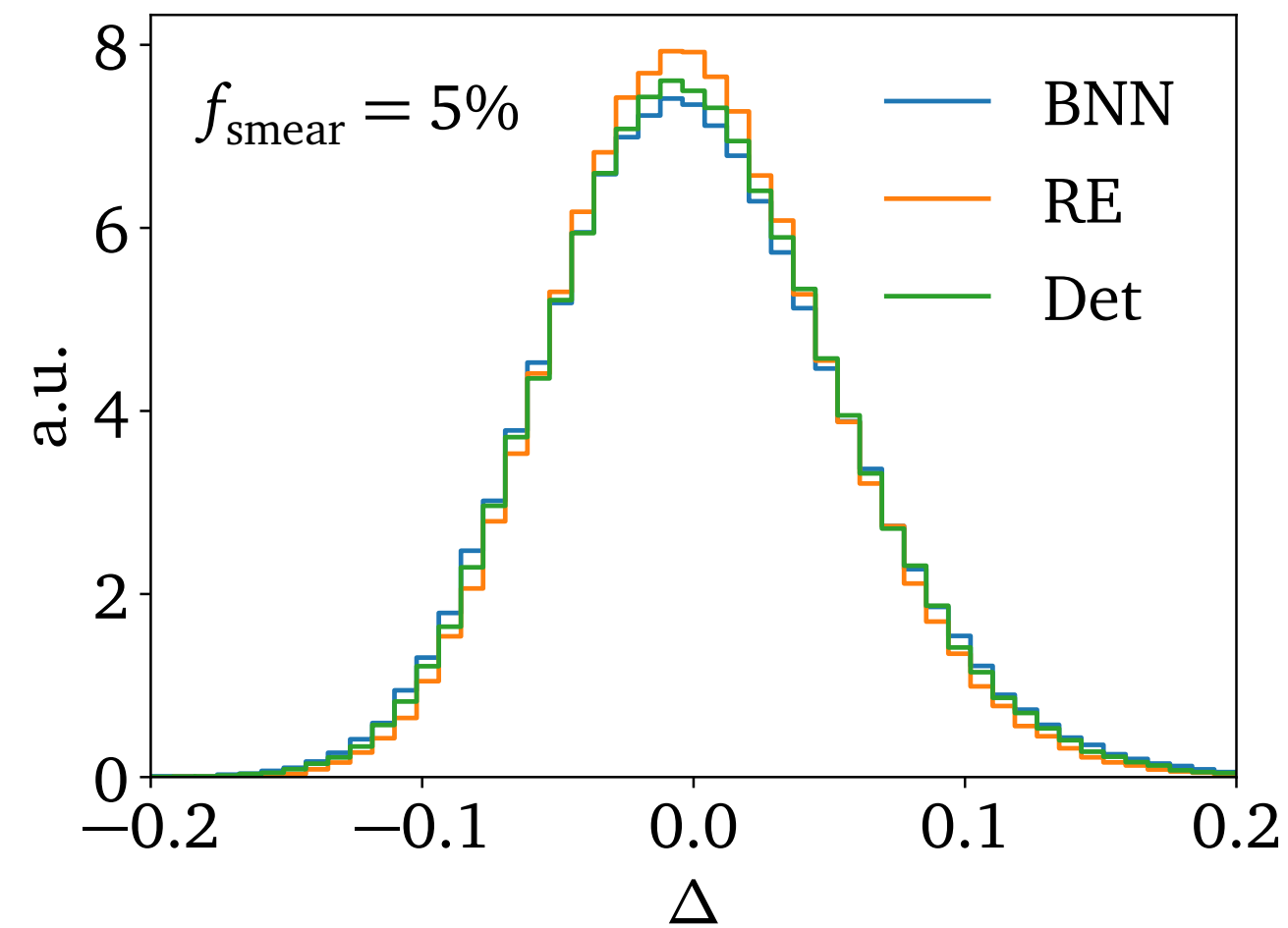
	70%	10%
$\langle \sigma_{\text{syst, BNN-DSI}} / A \rangle$	$8.7 \cdot 10^{-5}$	$2.5 \cdot 10^{-4}$
$\langle \sigma_{\text{stat, BNN-DSI}} / A \rangle$	$3.6 \cdot 10^{-5}$	$1.5 \cdot 10^{-4}$
$\langle \sigma_{\text{syst, RE-DSI}} / A \rangle$	$5.1 \cdot 10^{-5}$	$2.9 \cdot 10^{-4}$
$\langle \sigma_{\text{stat, RE-DSI}} / A \rangle$	$4.8 \cdot 10^{-5}$	$2.2 \cdot 10^{-4}$

Statistical pull



➡ Repulsive ensemble: Advantage for **statistical** uncertainty

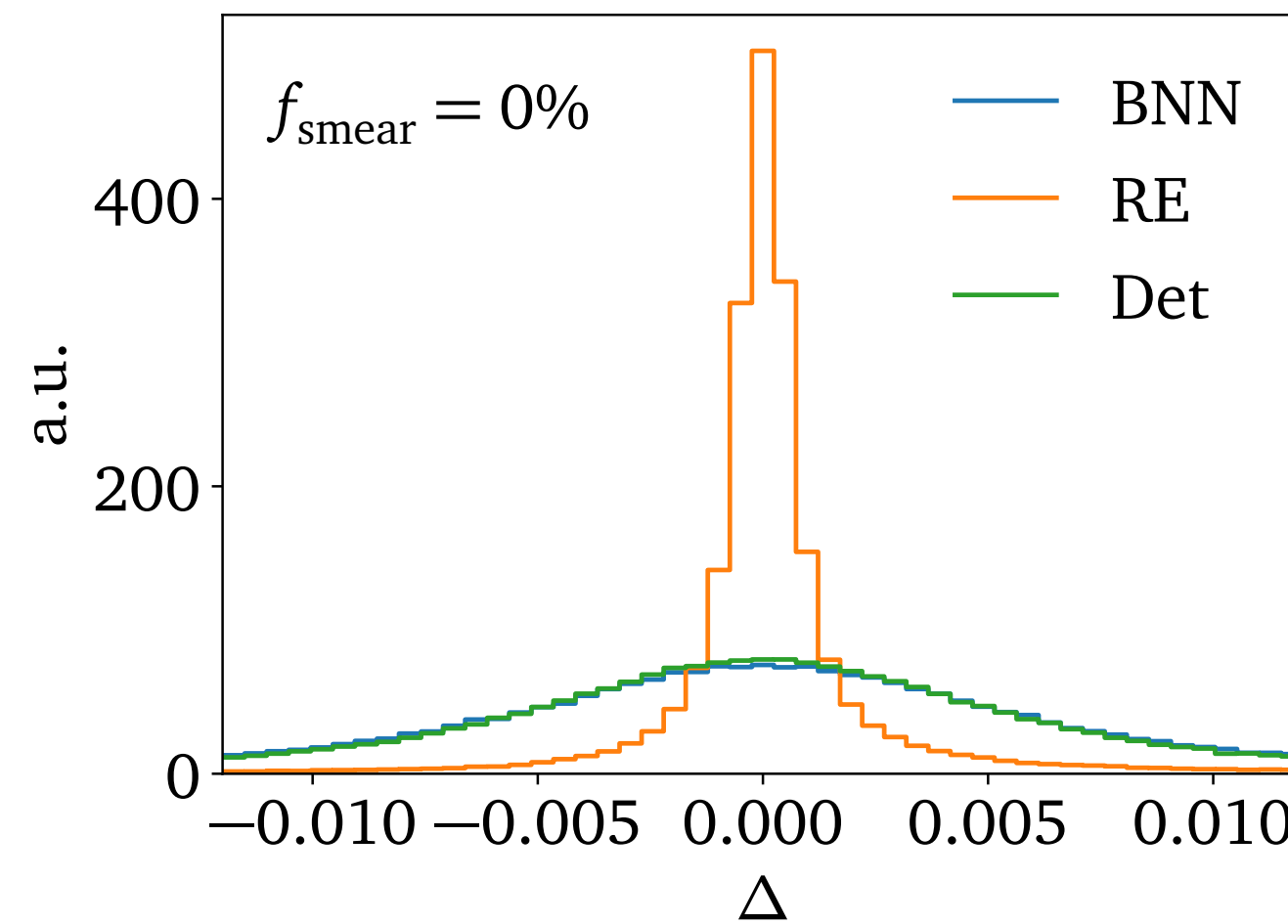
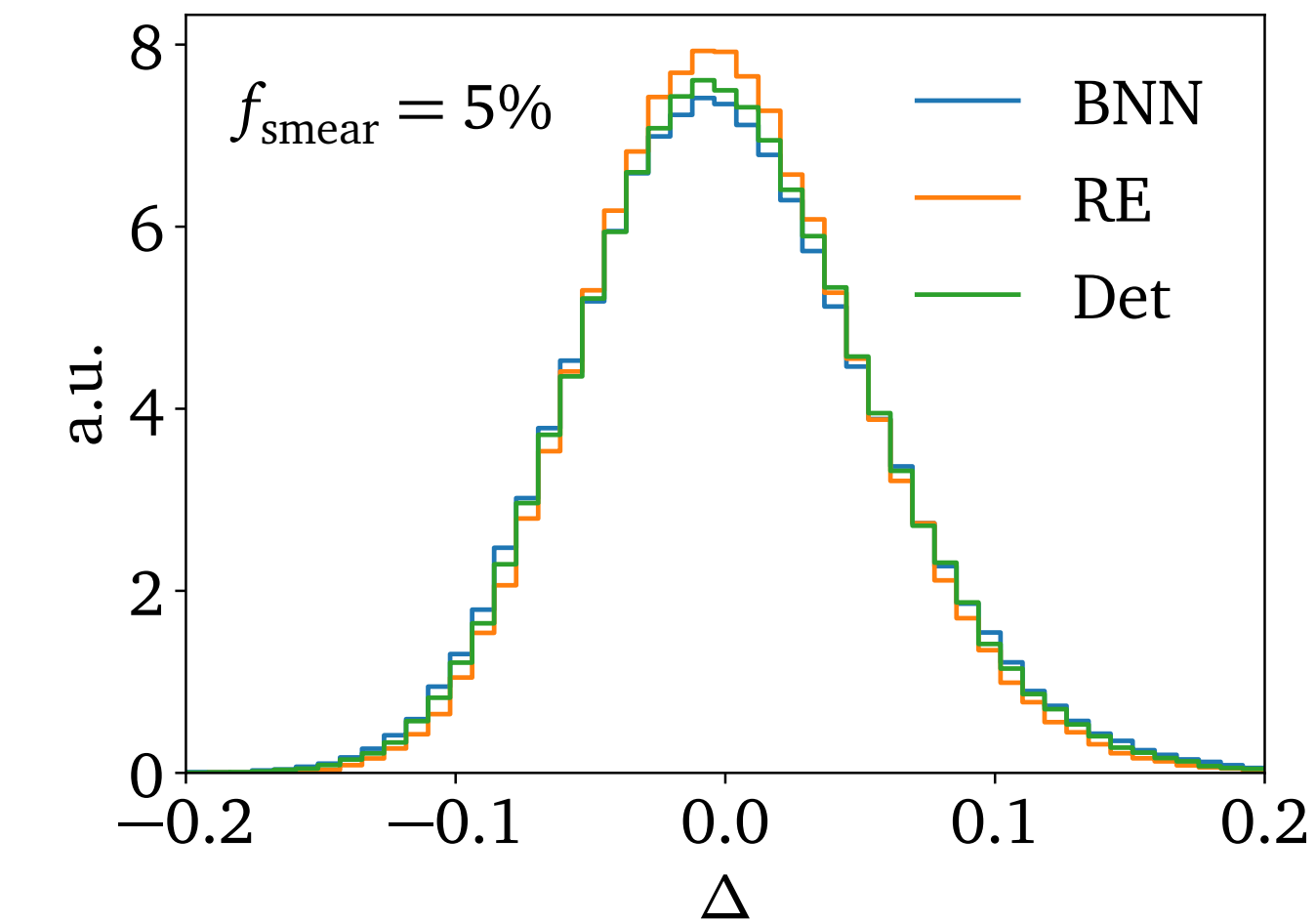
Systematic pull and accuracy



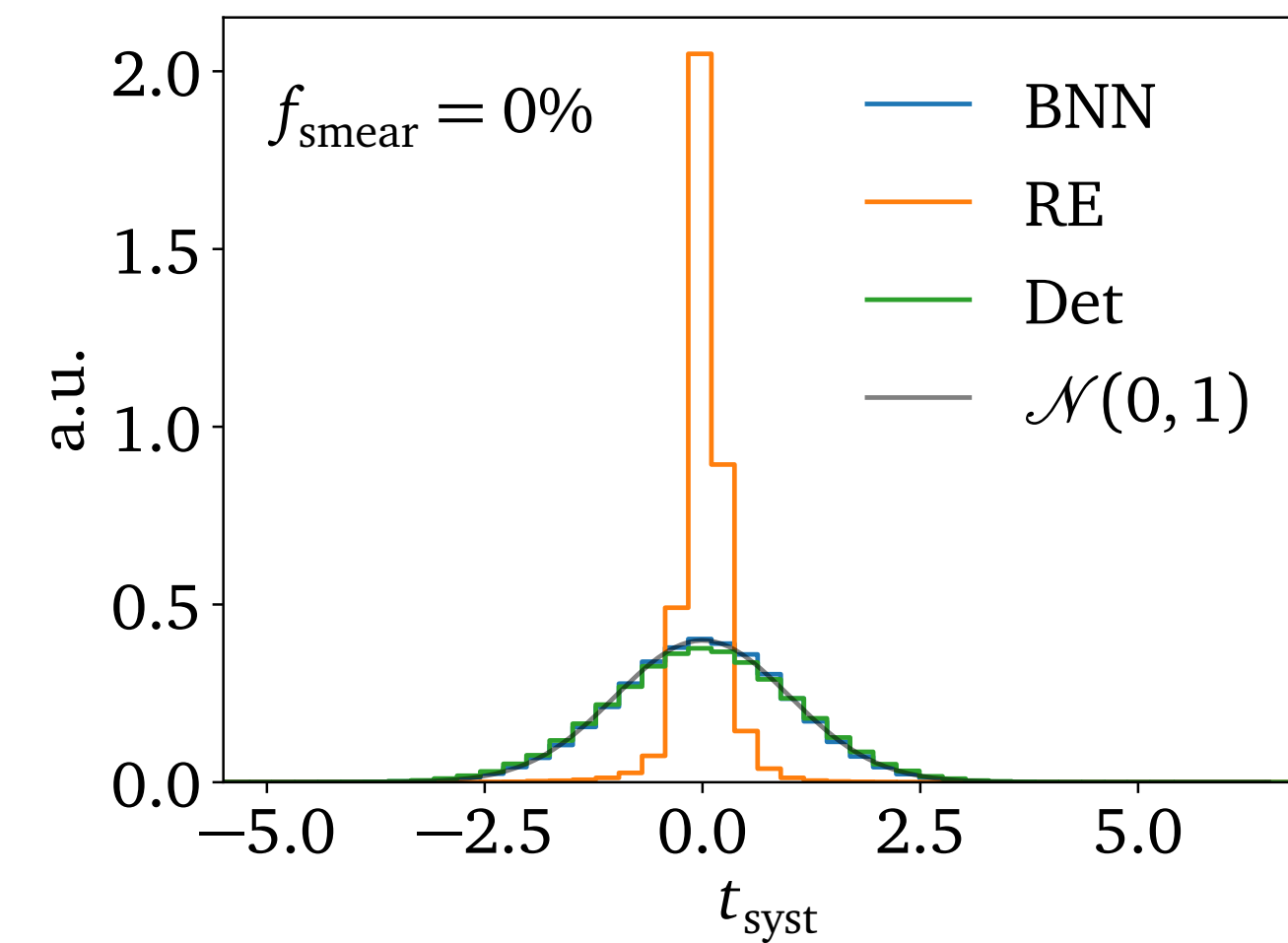
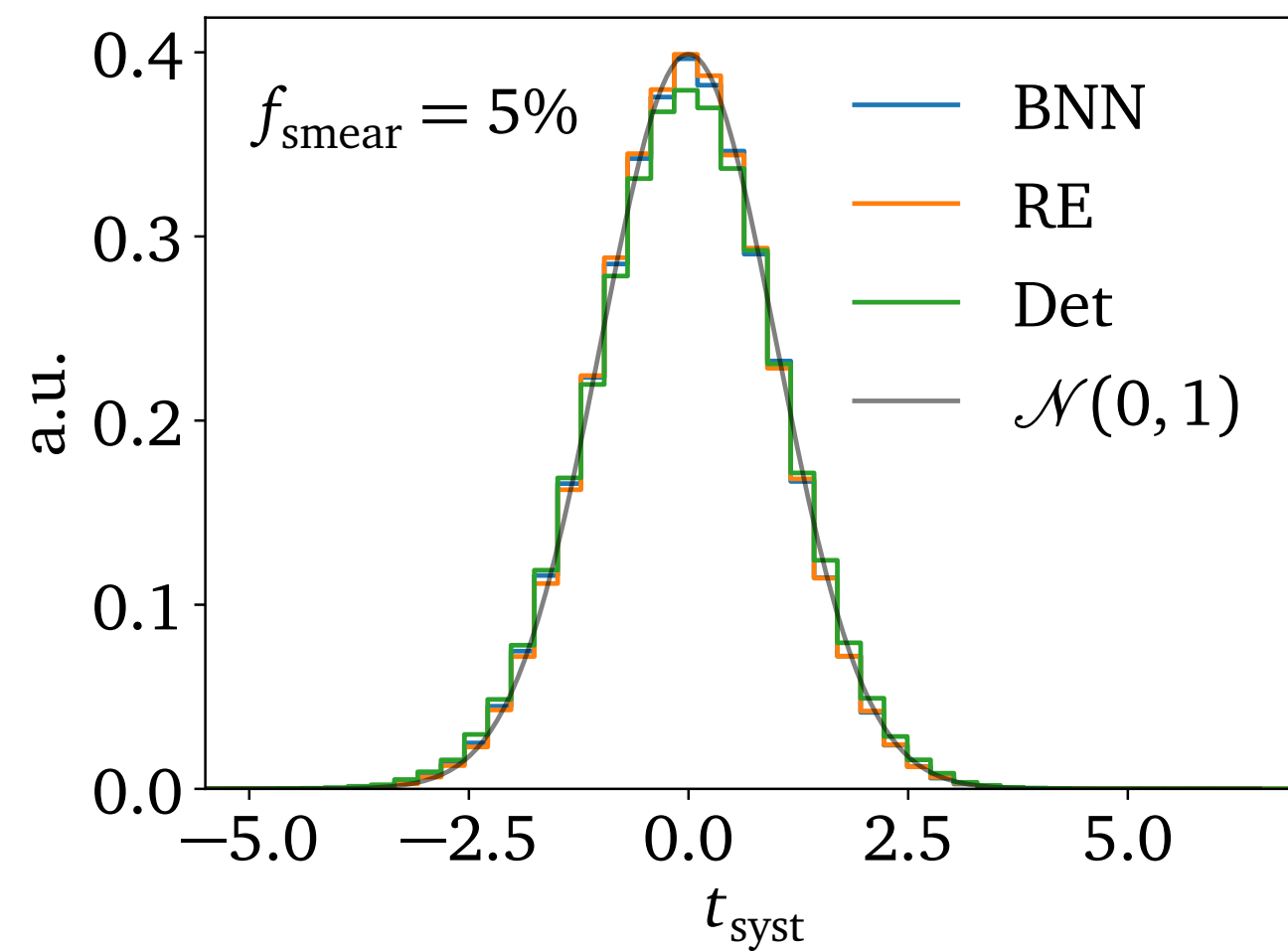
➡ Calibrated results

➡ BNN: Advantage for learning **systematics**

Systematic pull and accuracy



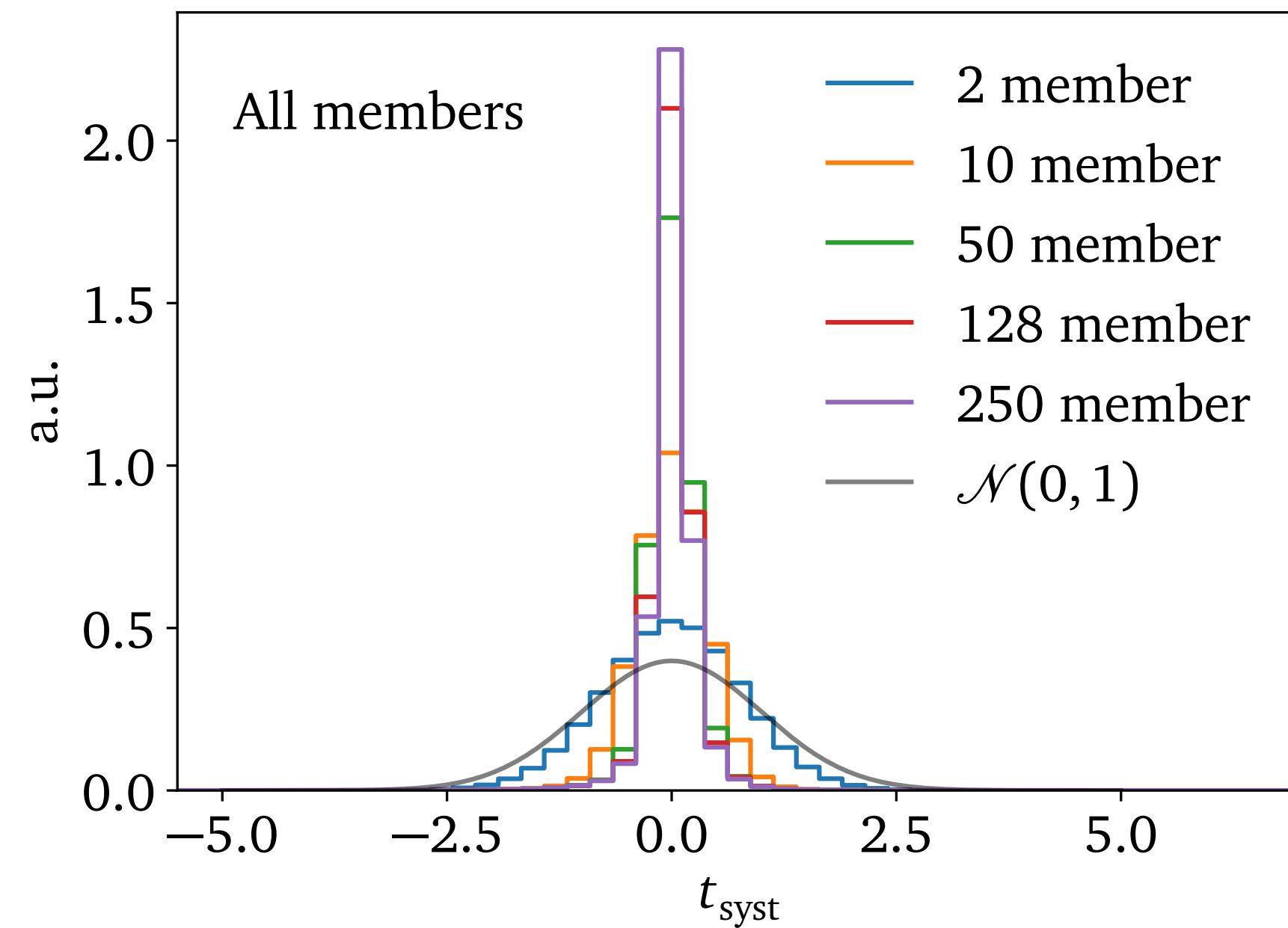
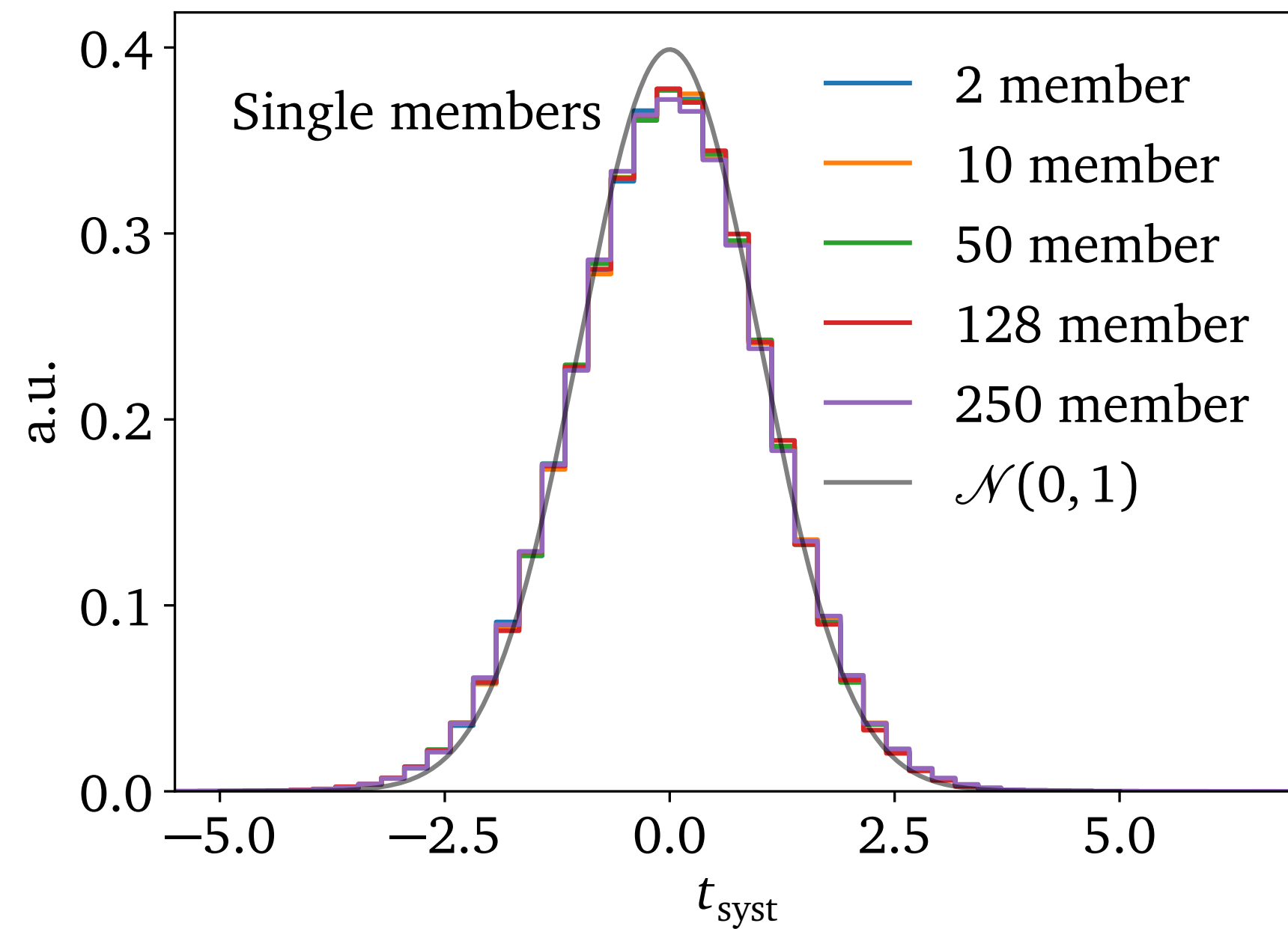
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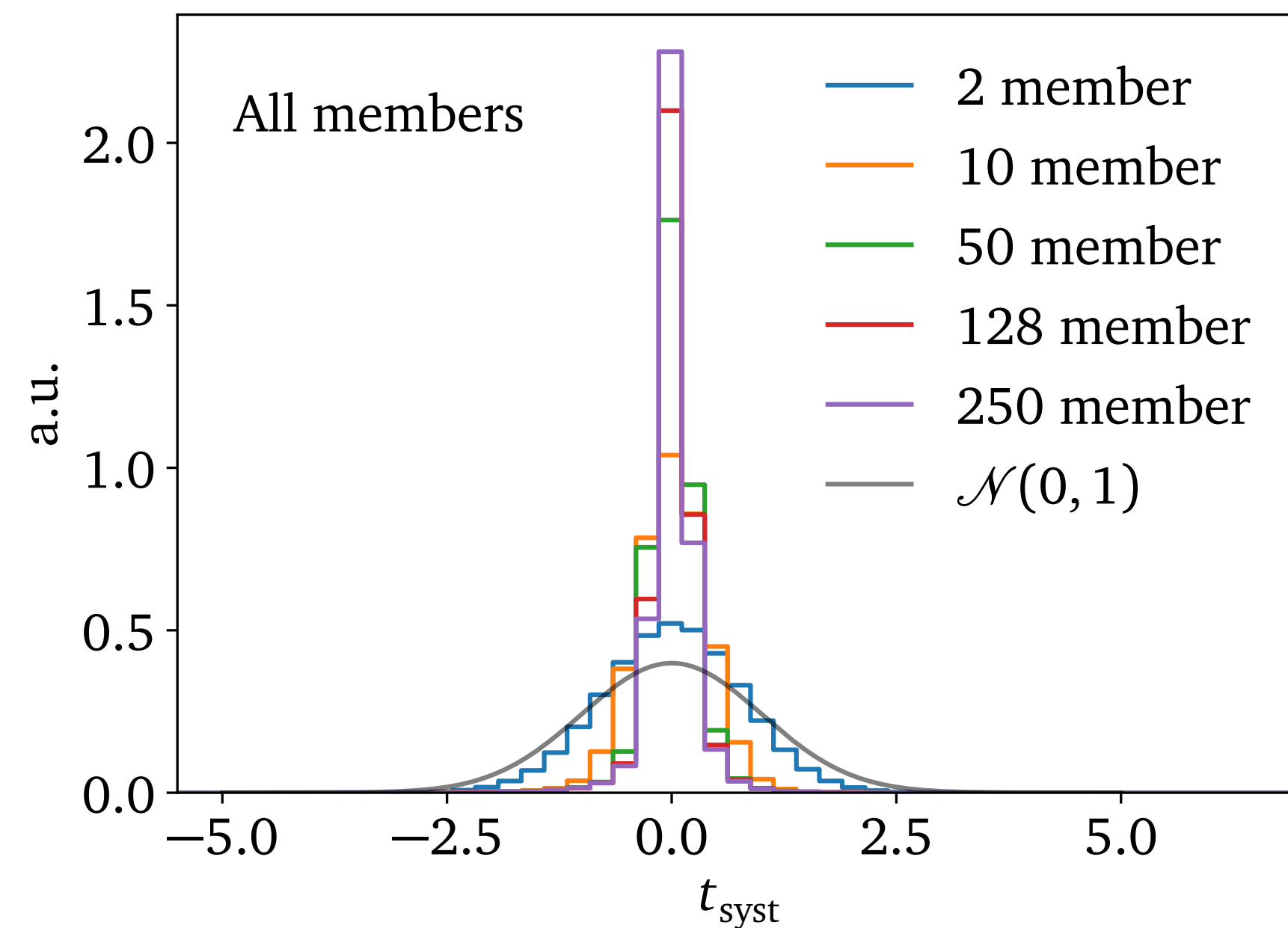
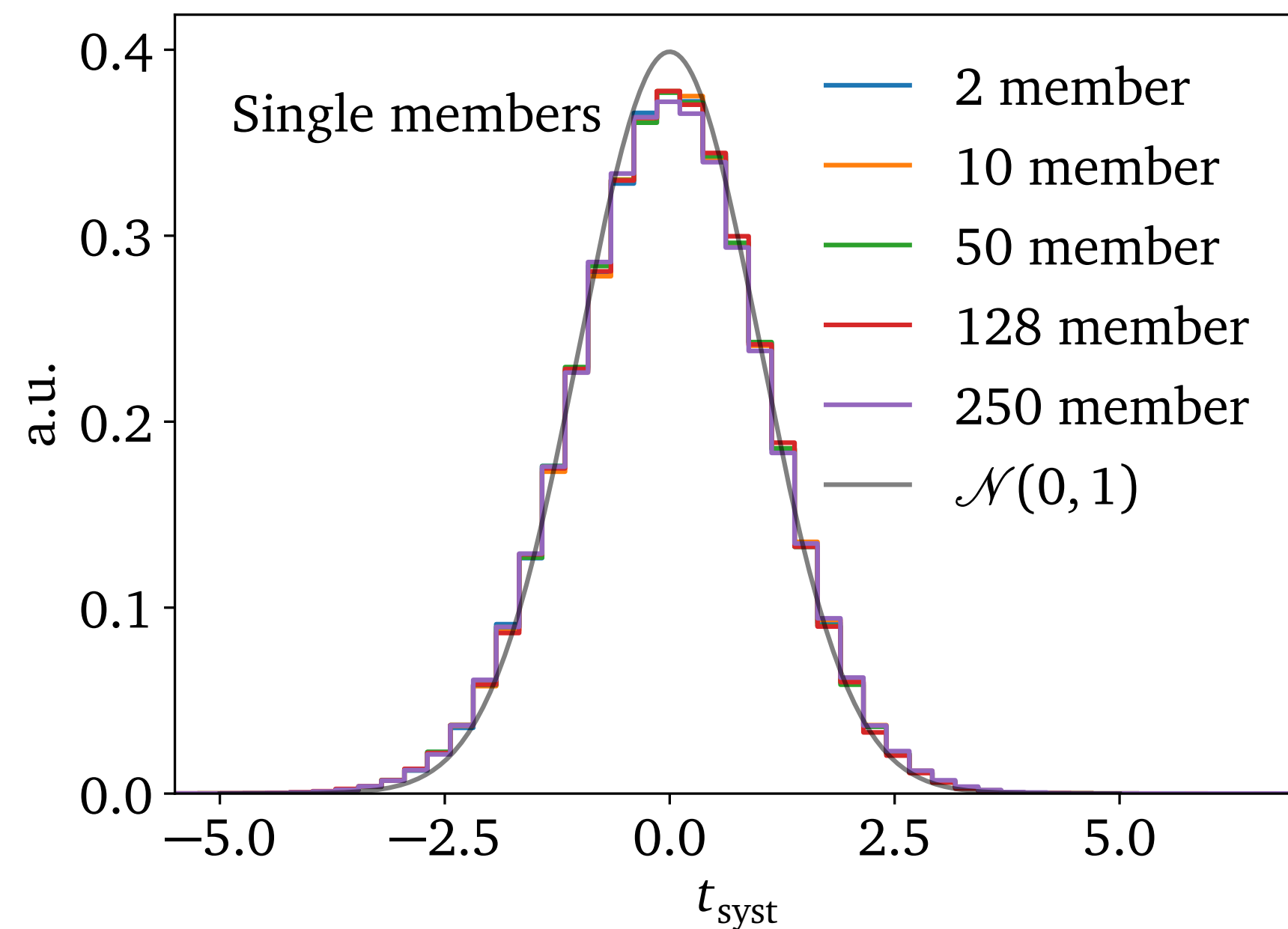
Systematic pull for REs

- Learned $\sigma_{syst}(x)$ too conservative



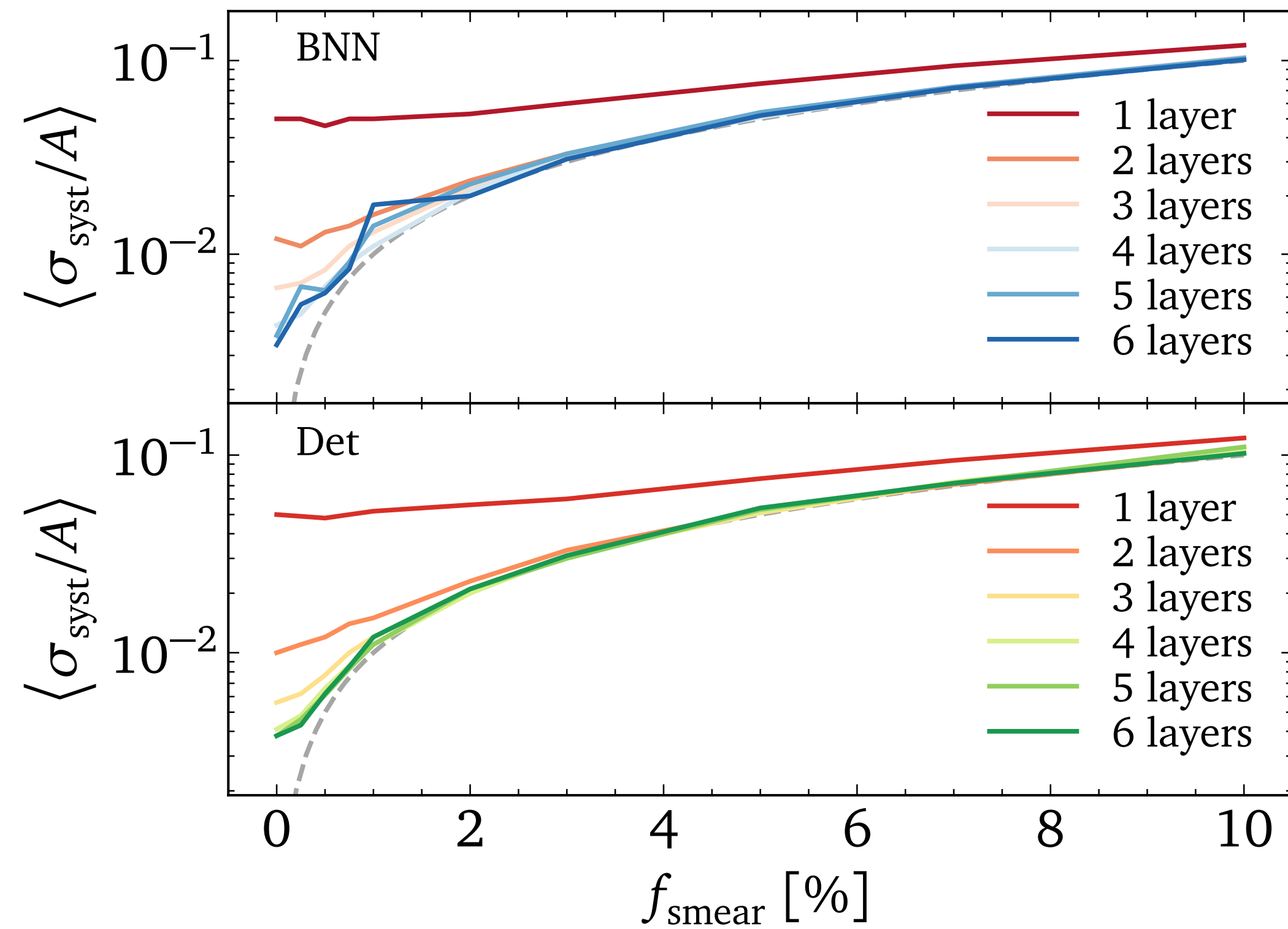
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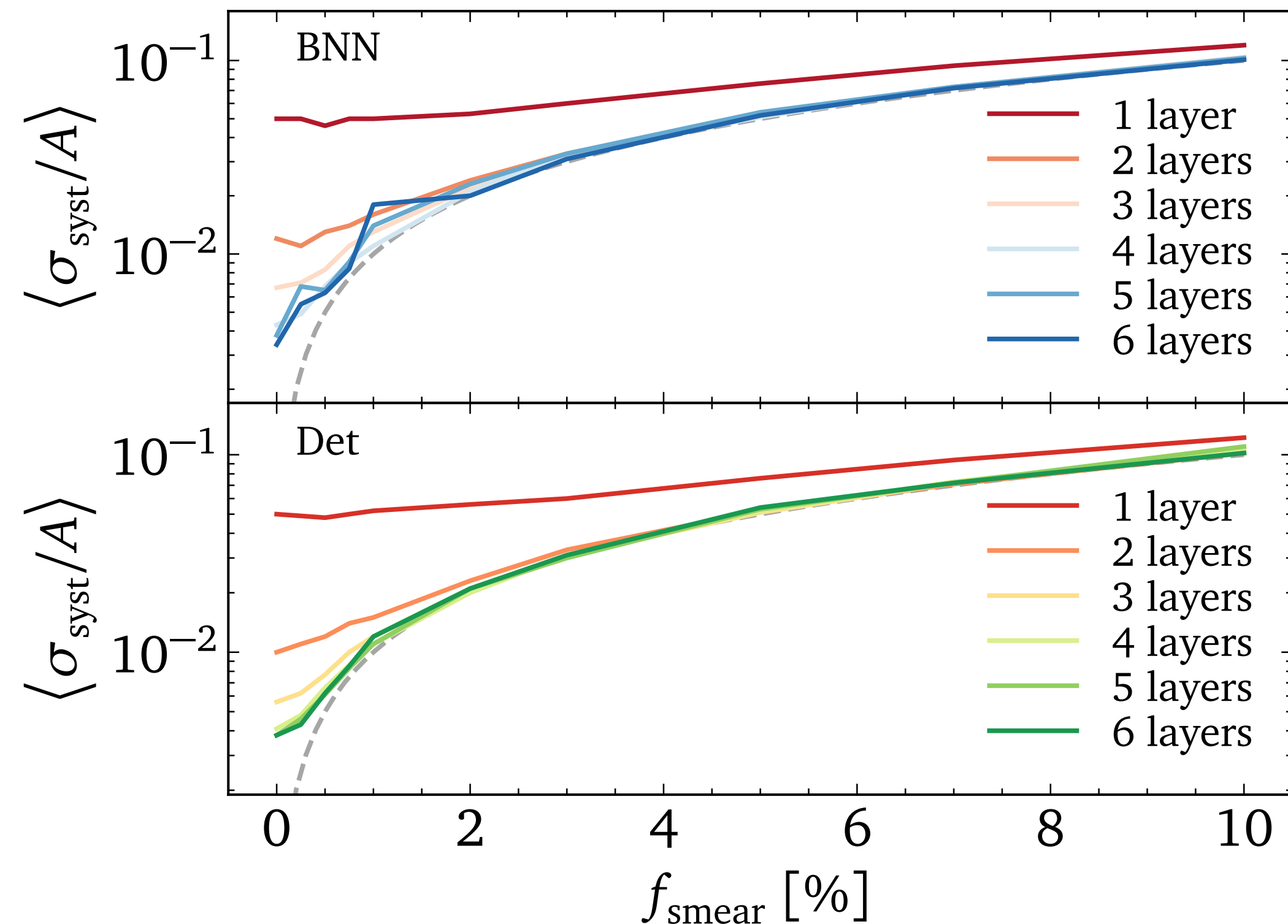
➡ Prediction benefits from ensemble nature but not σ_{syst}

Improve network expressivity



- Source of intrinsic uncertainty?
- BNN: Only last layer Bayesian

Improve network expressivity



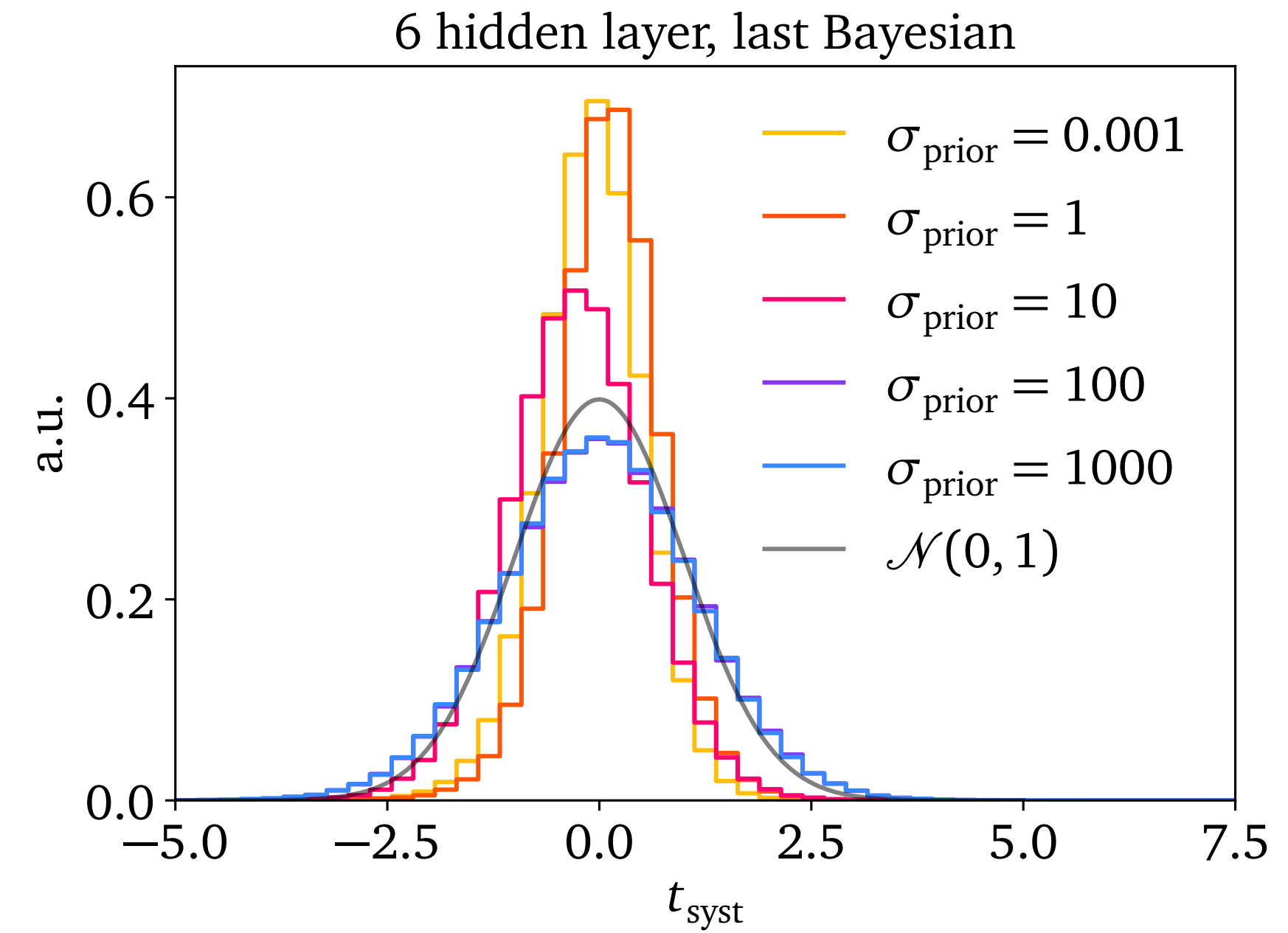
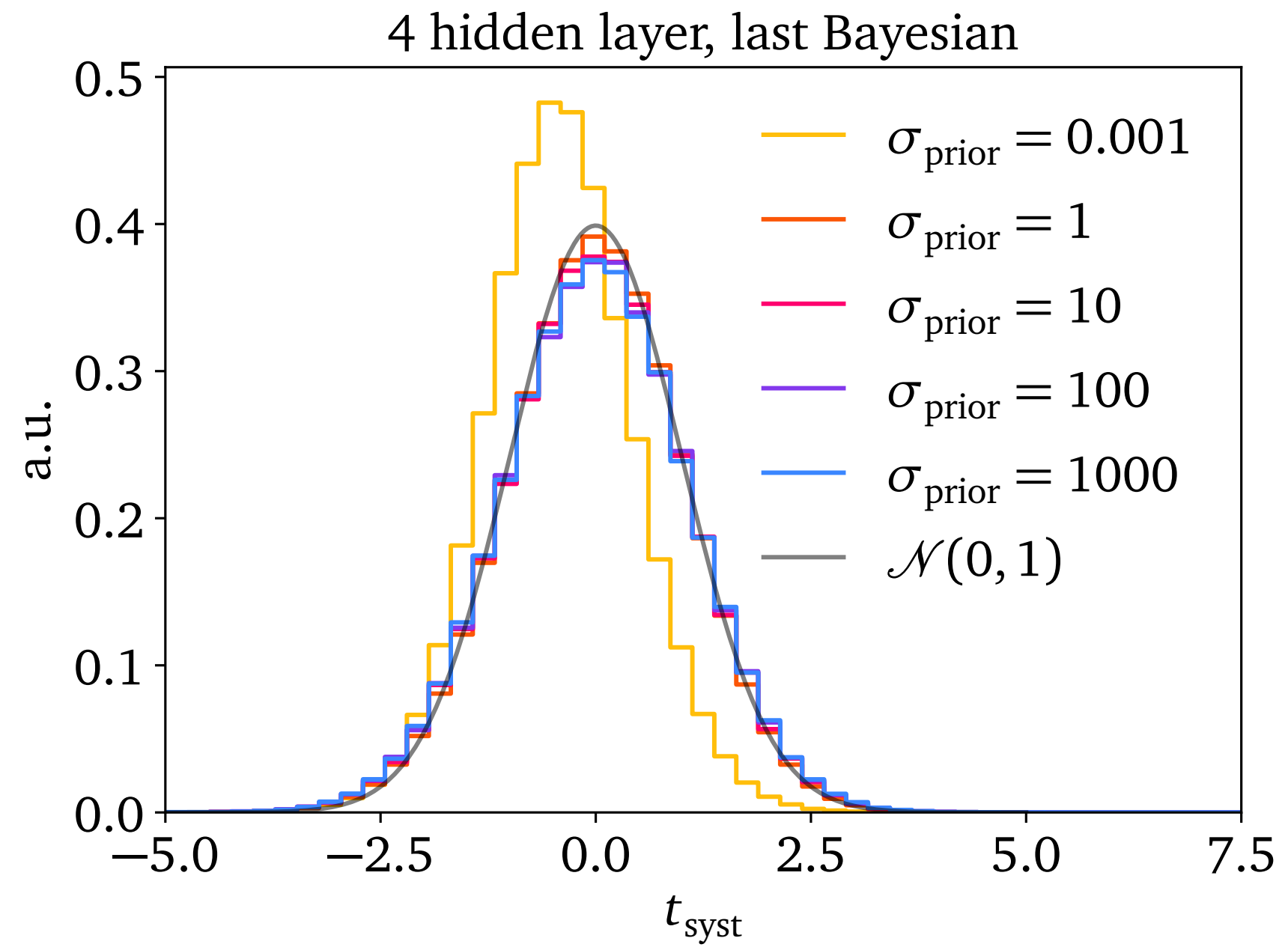
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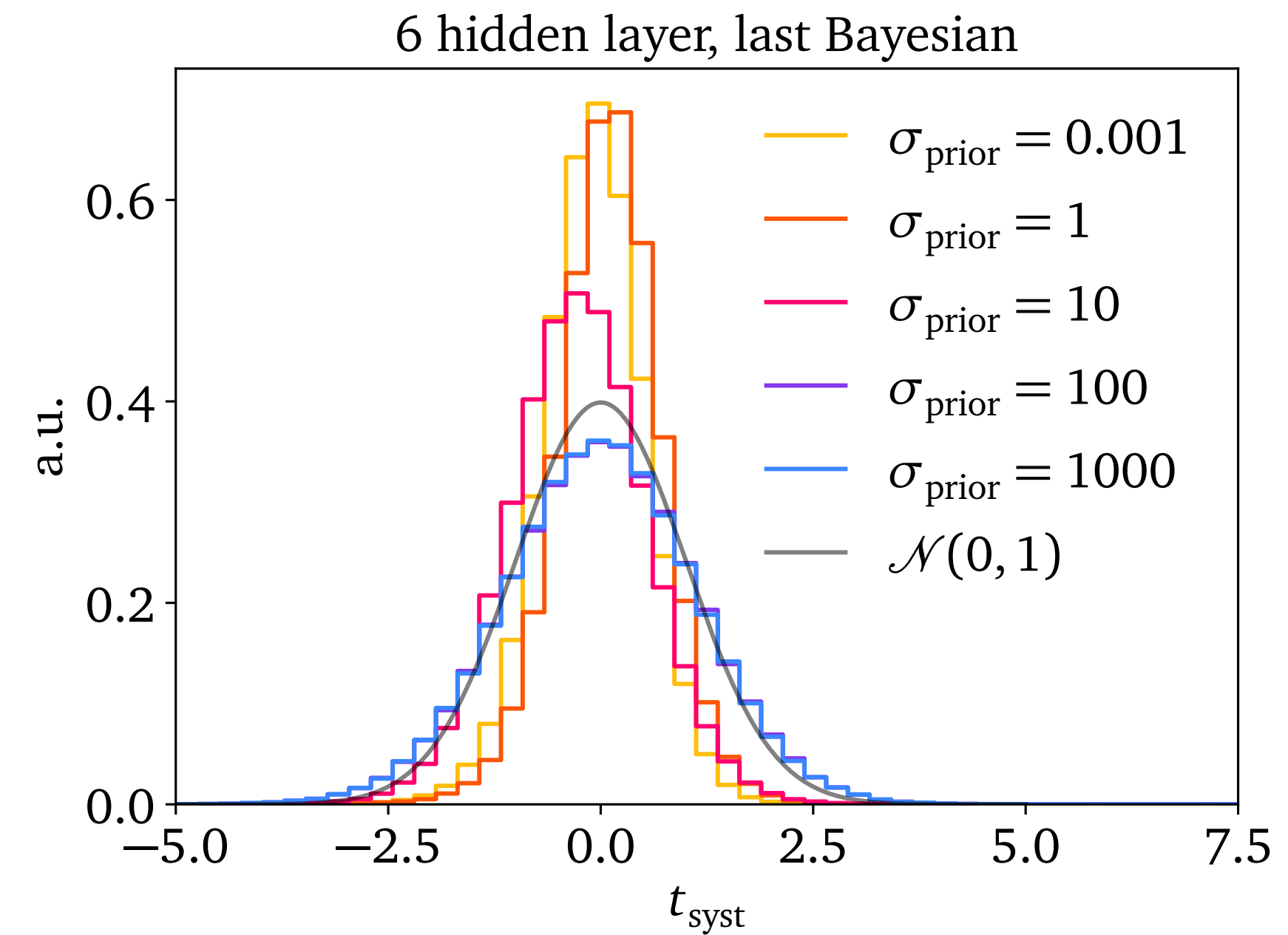
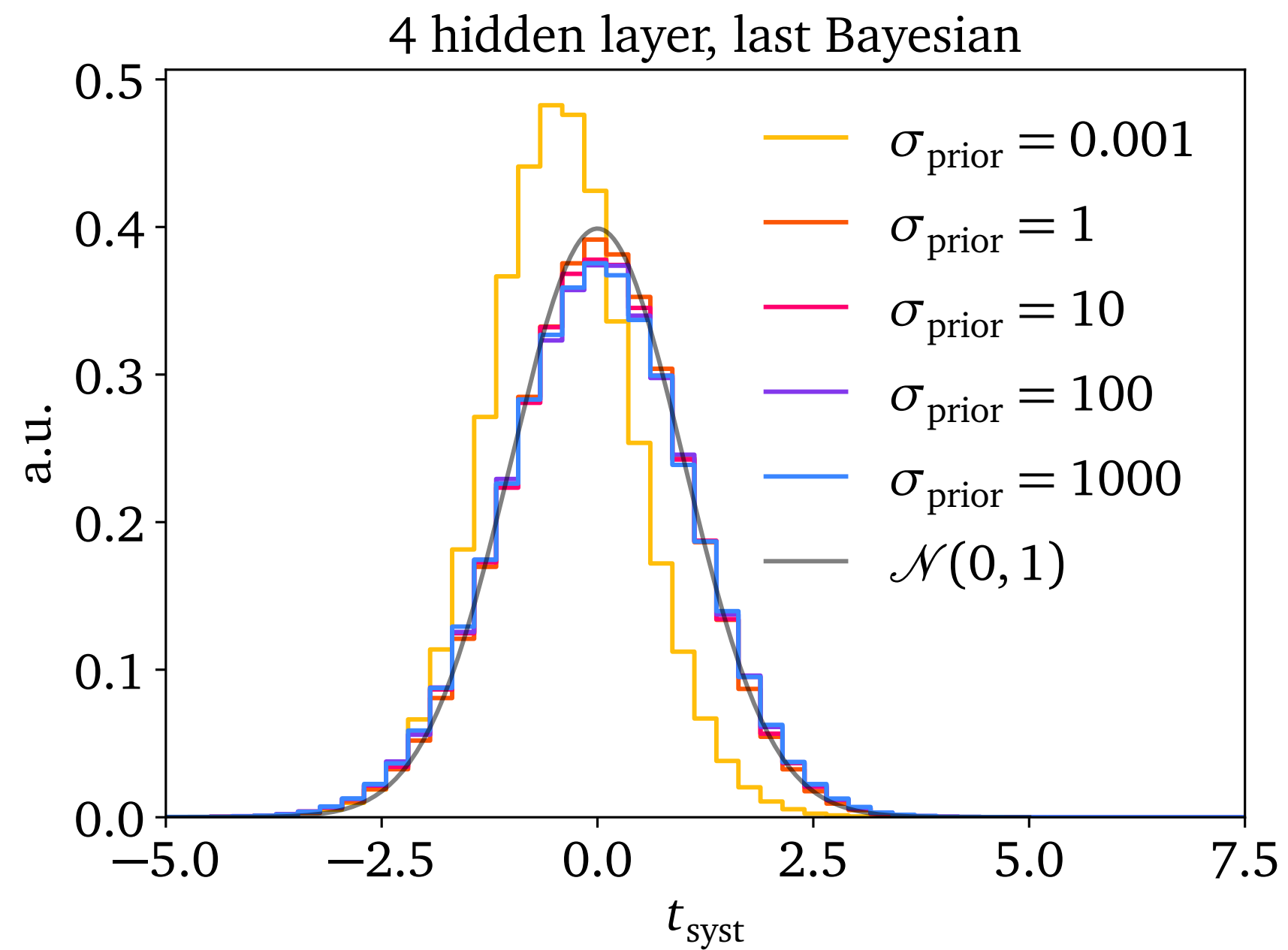
➔ **More expressivity** and better **sensitivity** for small noise with more layers

➔ Improvement of intrinsic uncertainty to 0.3%

Prior influence in the BNN



Prior influence in the BNN

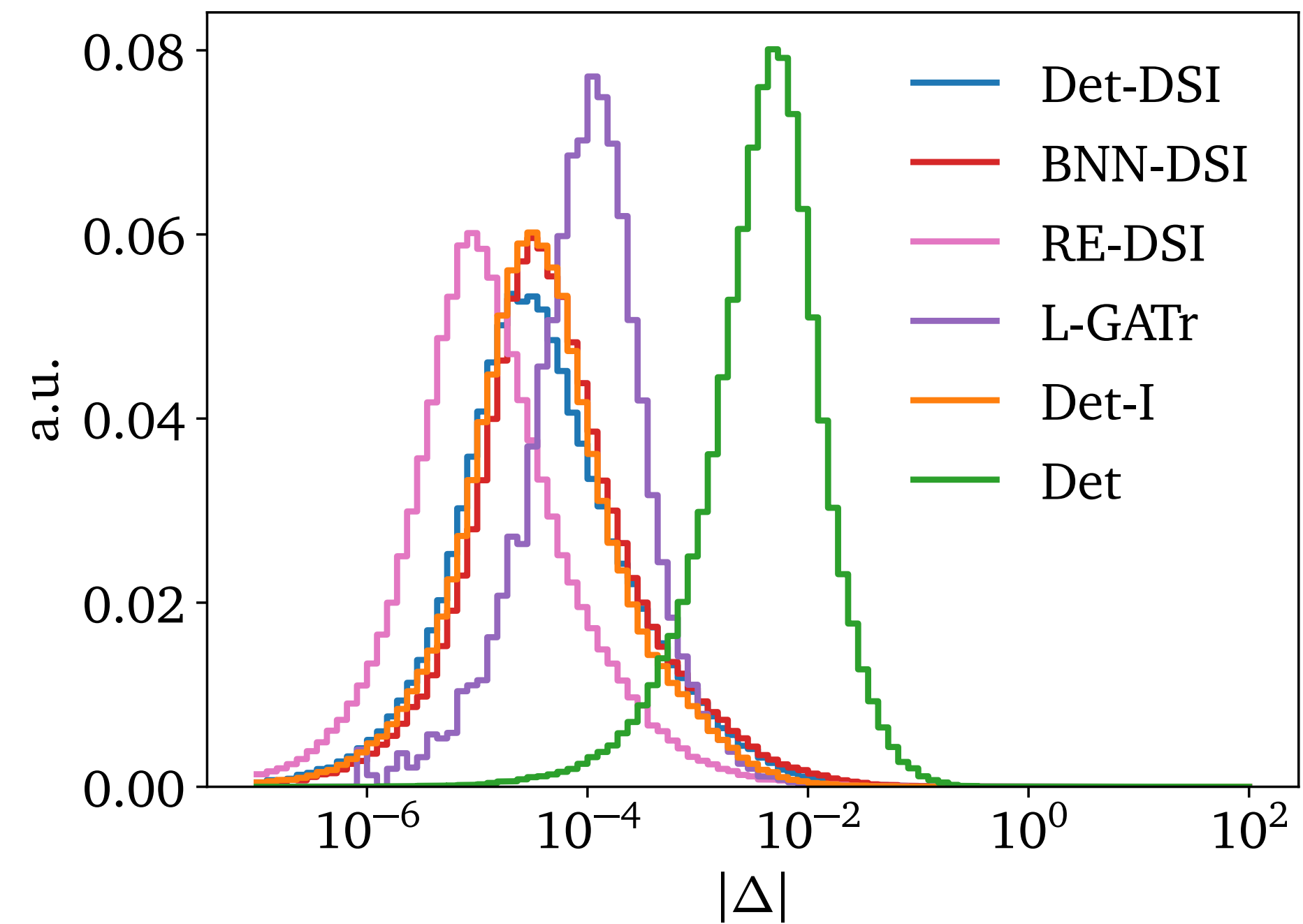
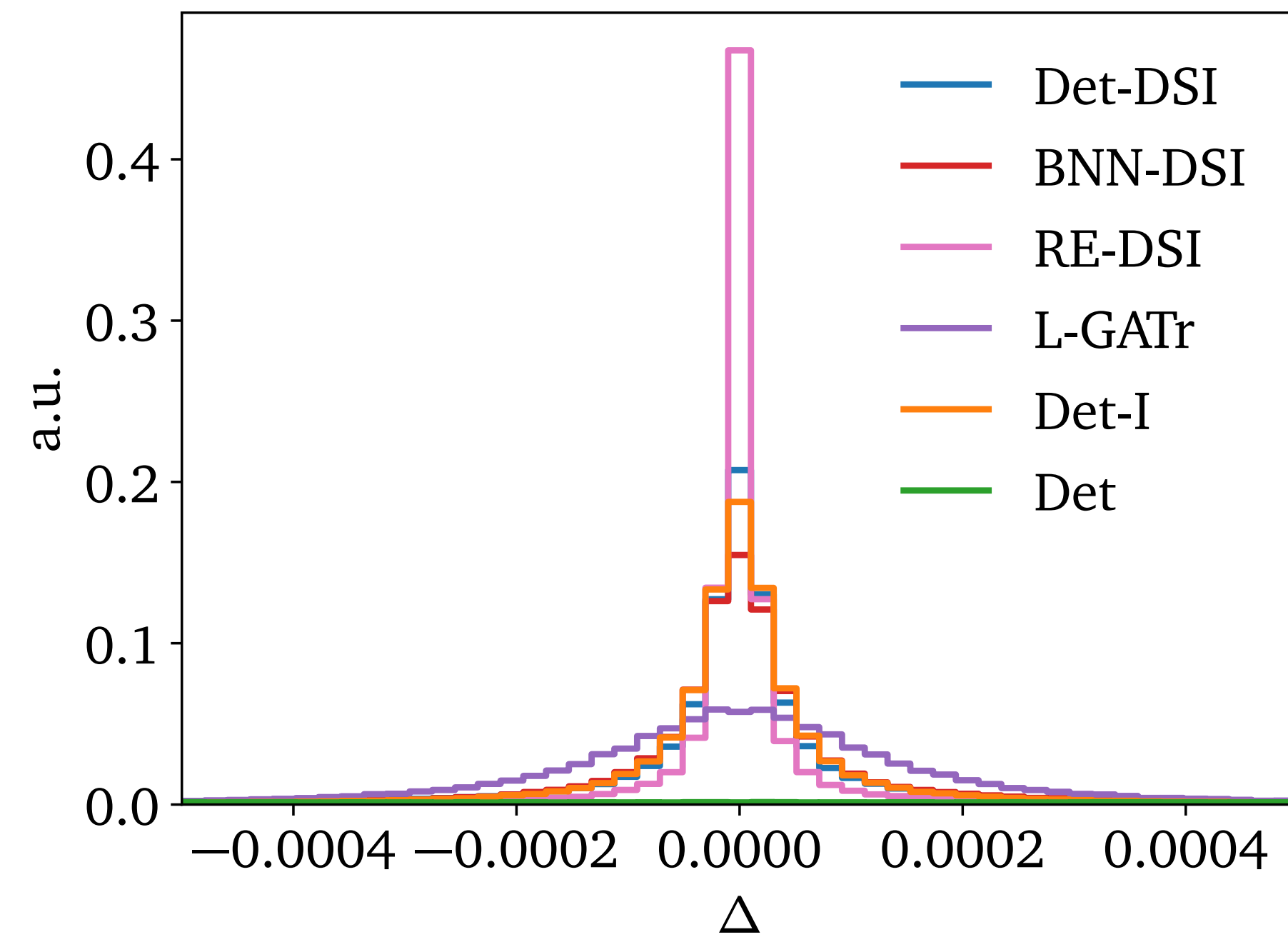


- ➡ Results don't depend on prior
- ➡ For more layers a larger prior is needed

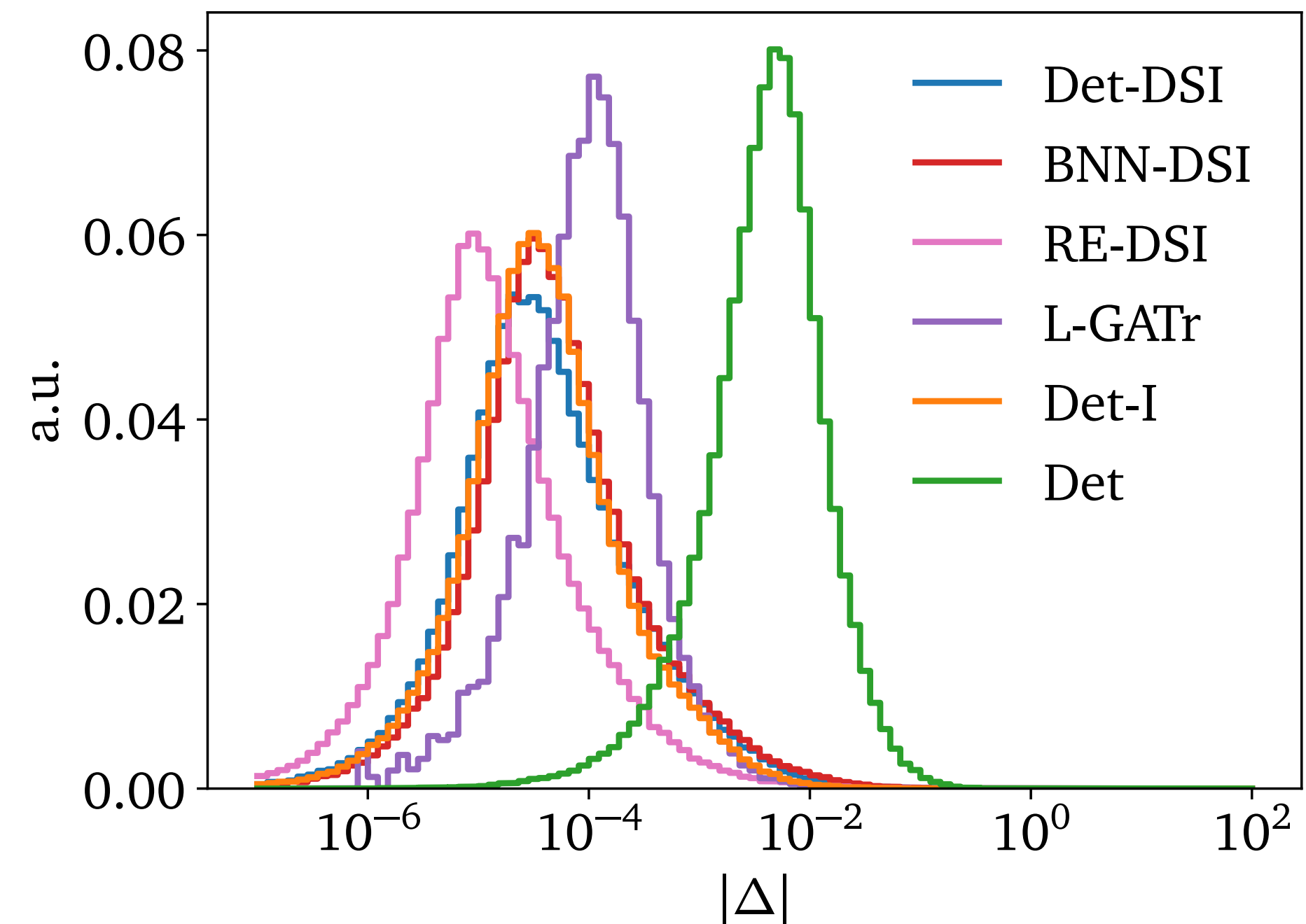
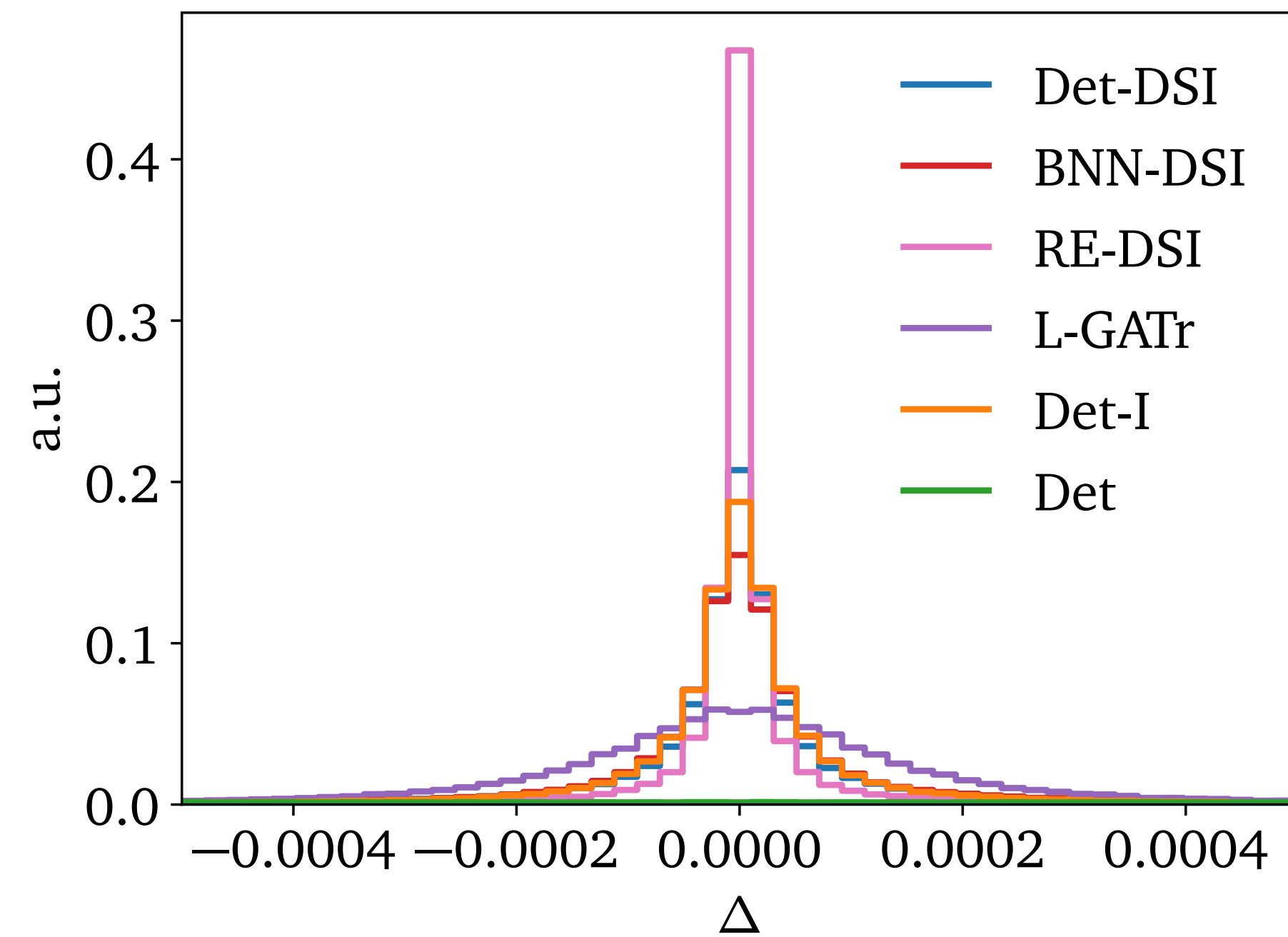
Testing advanced architectures

- Enhance standard networks through representation learning:
 1. **Deep Sets** (DS): learns embedding for each particle type
 2. **Deep Sets Invariants** (DSI): DS with Lorentz invariance added as input
 3. **L-GATr**: fully Lorentz equivariant network architecture [\[2411.00446\]](#)

Advanced architectures - Accuracy

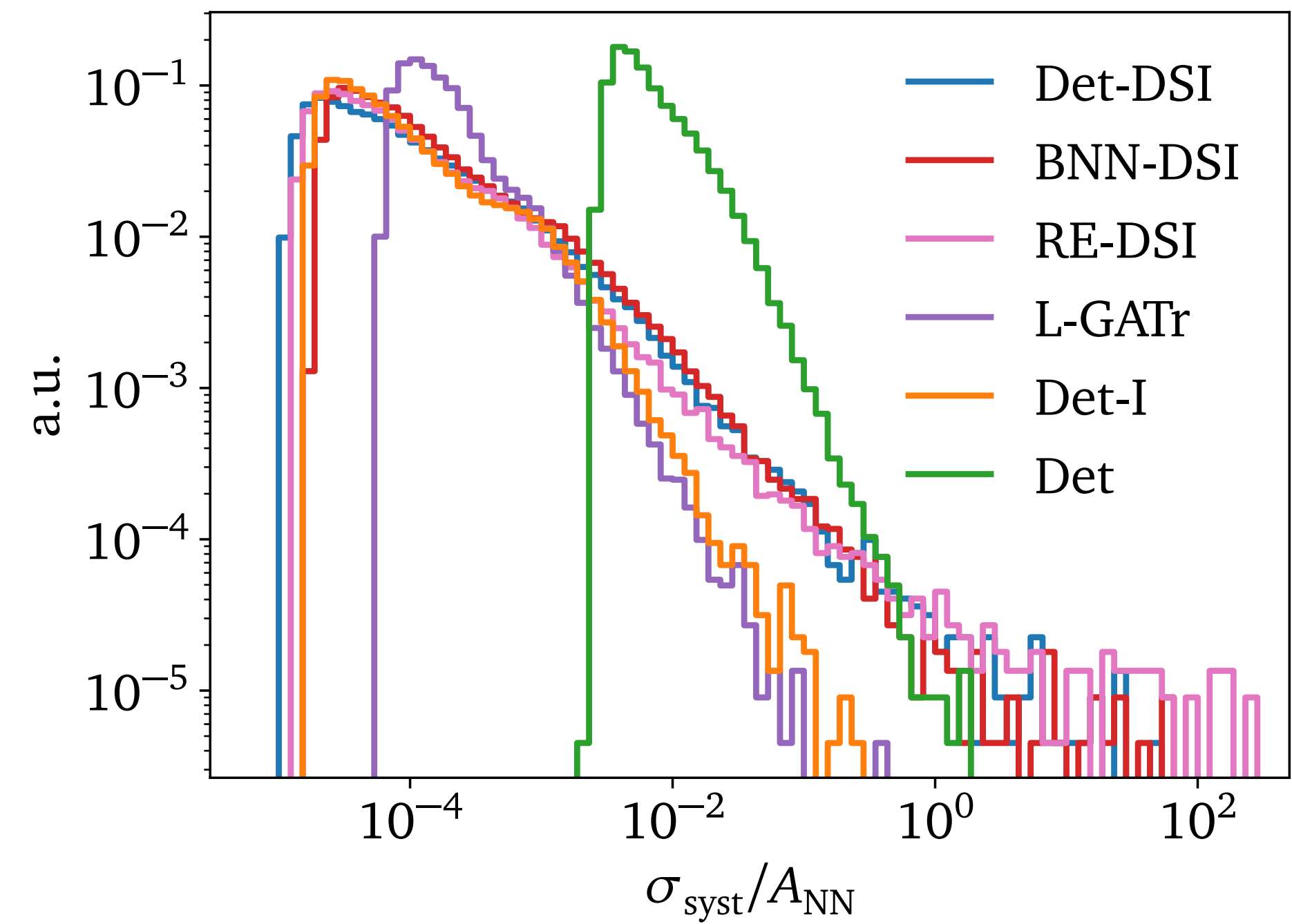
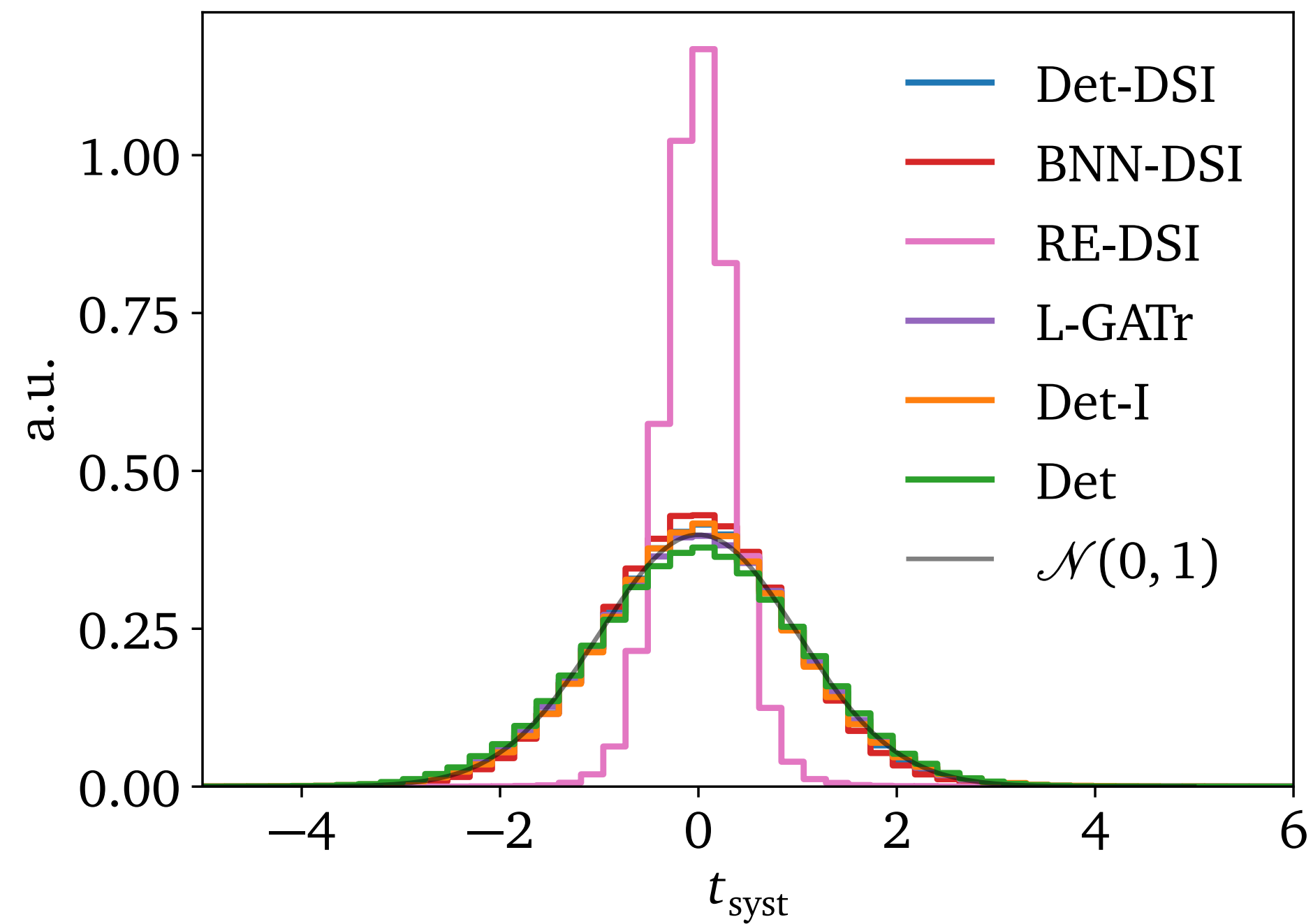


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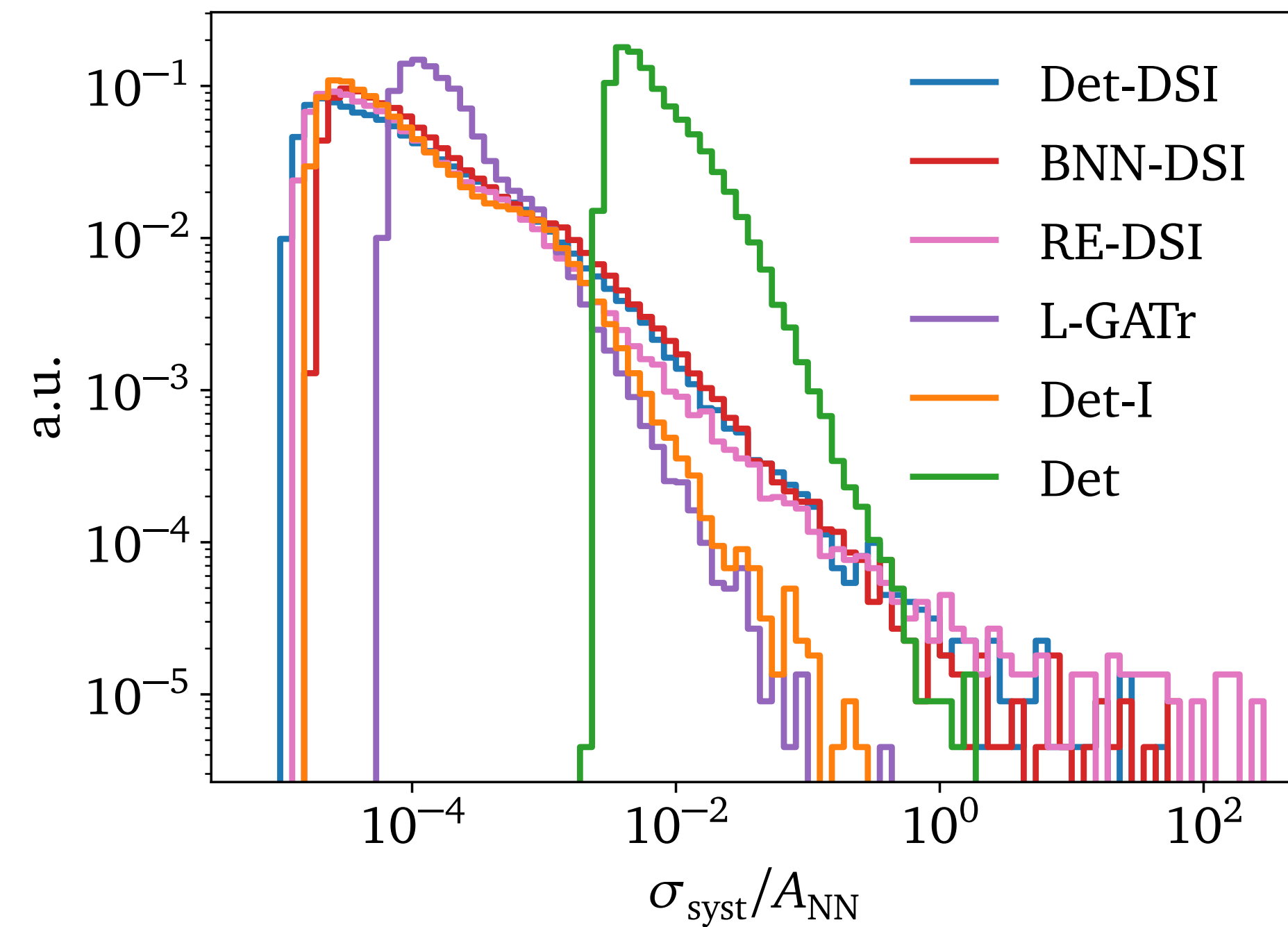
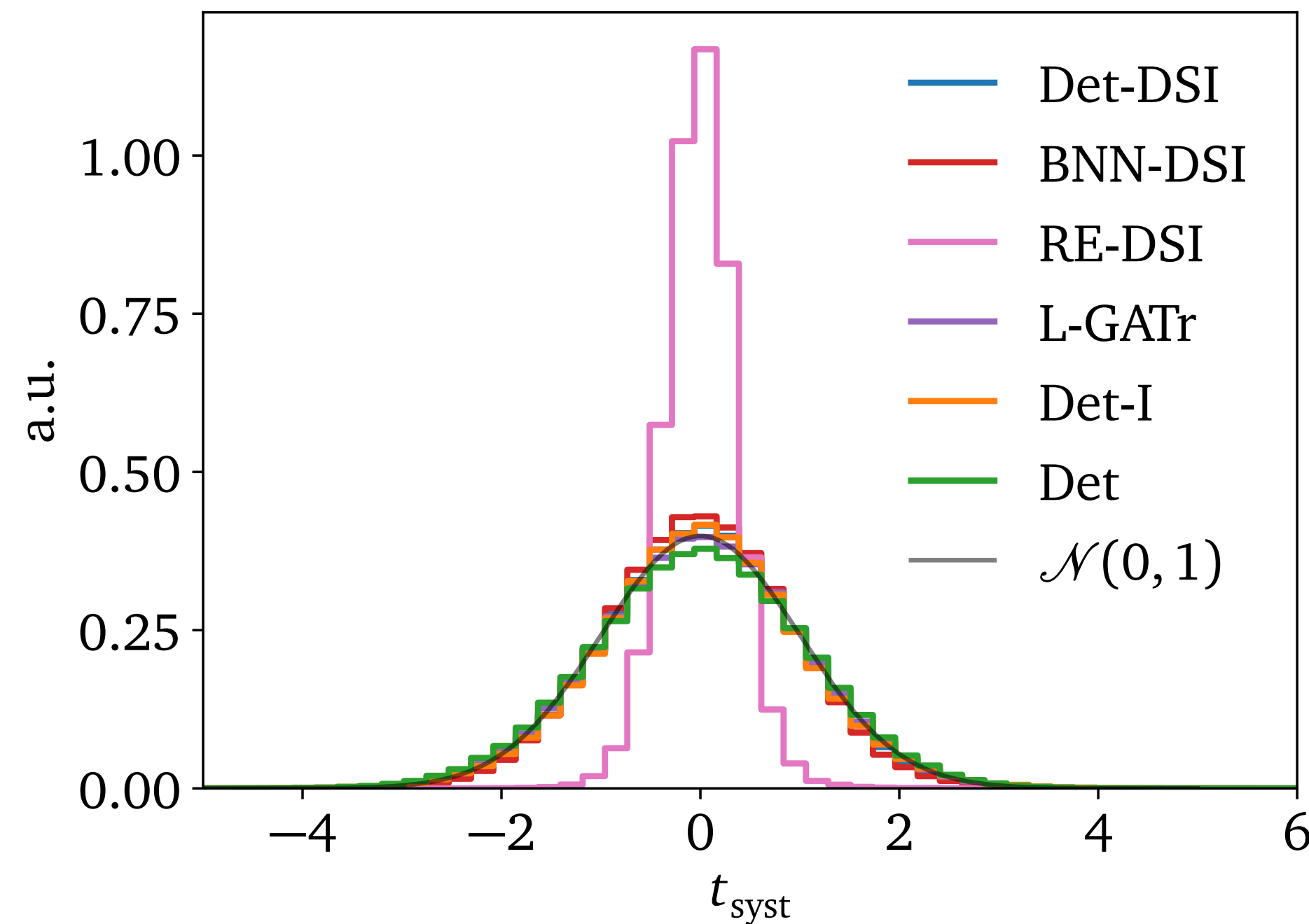


➡ **Controlled accuracy** to 10^{-5} level

Advanced architectures - Uncertainties



Advanced architectures - Uncertainties



➡ **Calibrated uncertainty** with **precision** on 10^{-5} level

➡ **Data preprocessing** gain improvement in intrinsic uncertainties

Conclusion

1. Able to track systematic and statistical uncertainties
2. Networks are calibrated (if not: calibration possible)
3. RE benefits from ensemble nature in precision
4. Networks are able to give controlled accuracy on 10^{-5} level

Conclusion

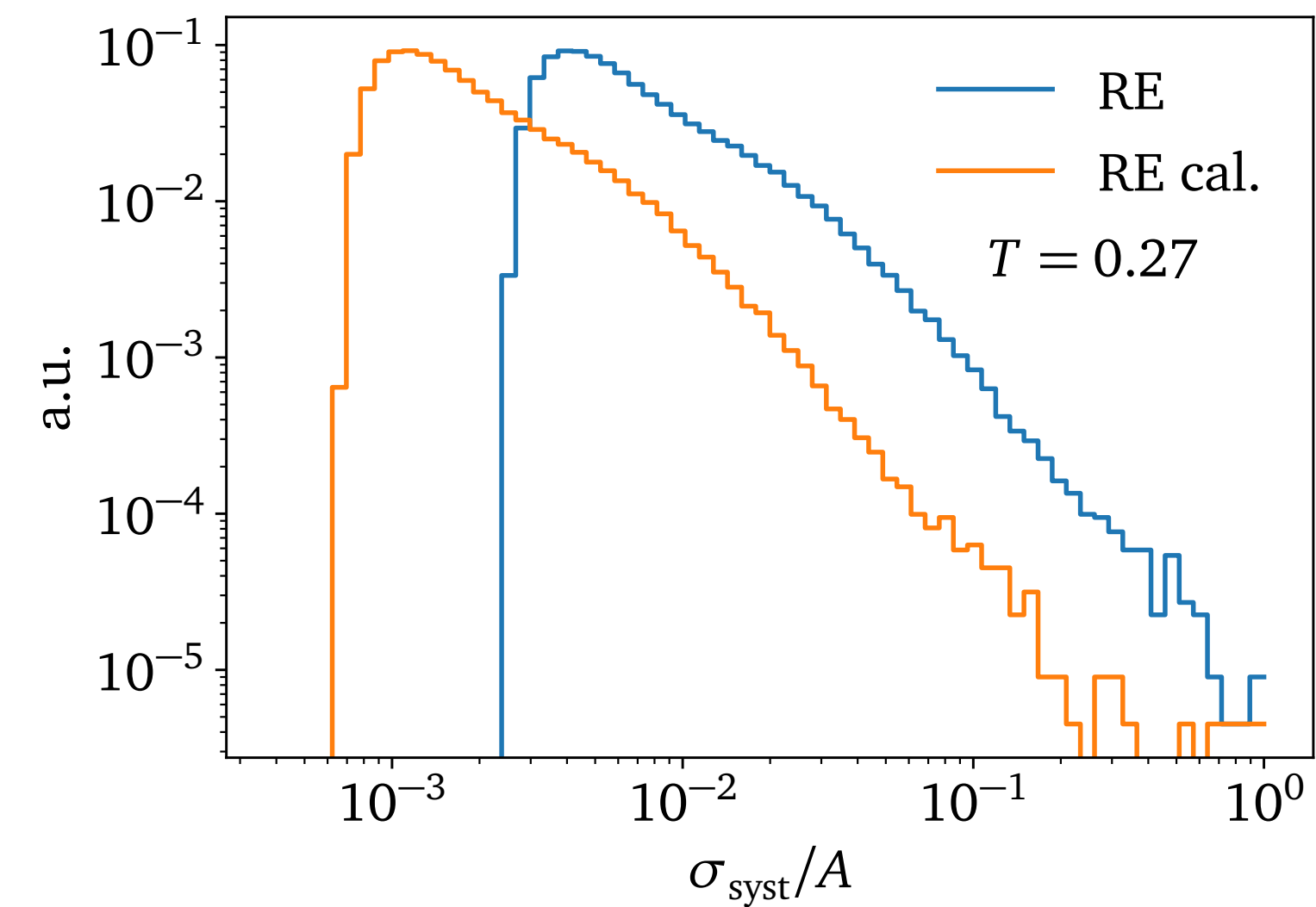
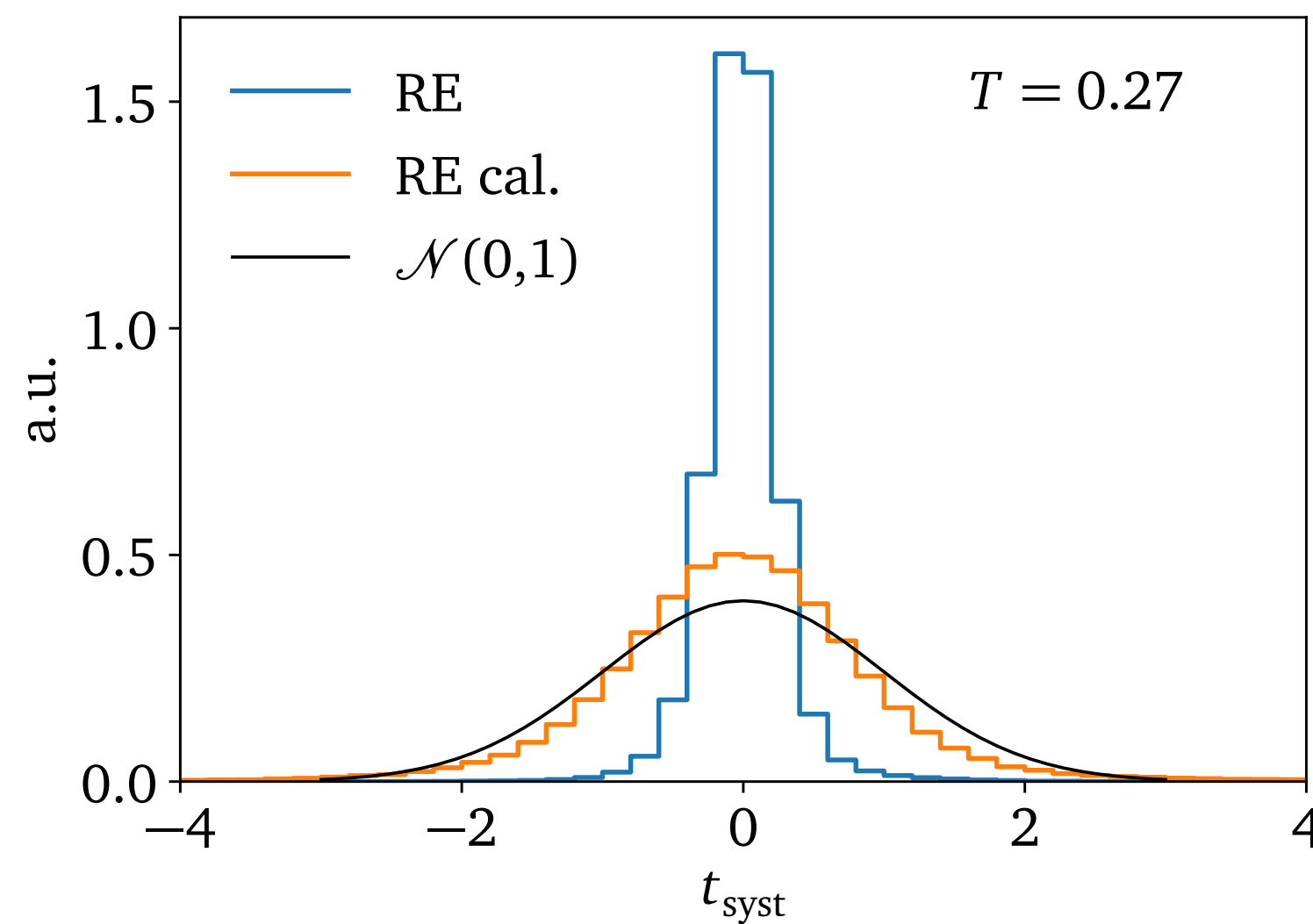
1. Able to track systematic and statistical uncertainties
2. Networks are calibrated (if not: calibration possible)
3. RE benefits from ensemble nature in precision
4. Networks are able to give controlled accuracy on 10^{-5} level

Thank you for your attention!

Back up / Additional material

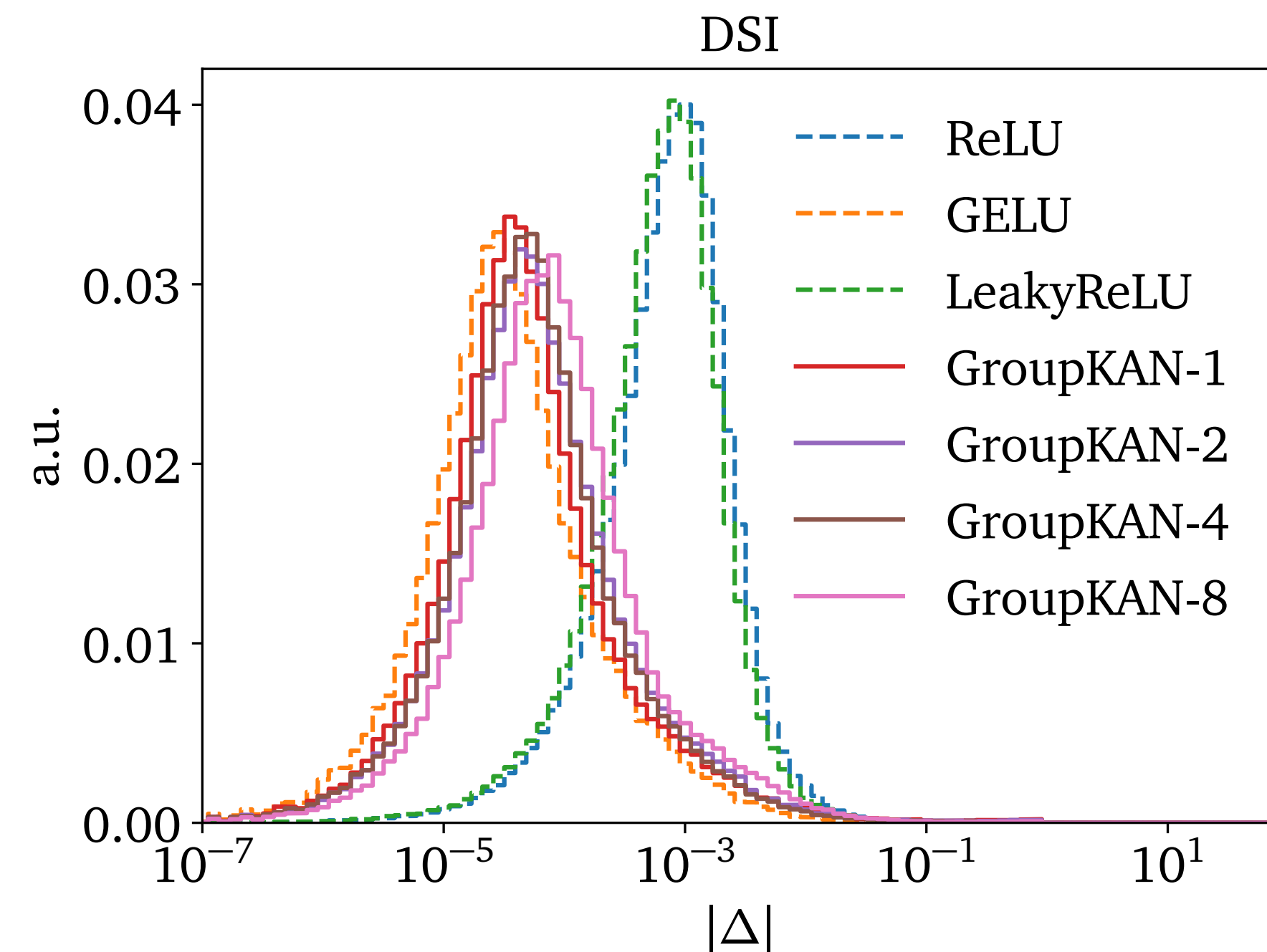
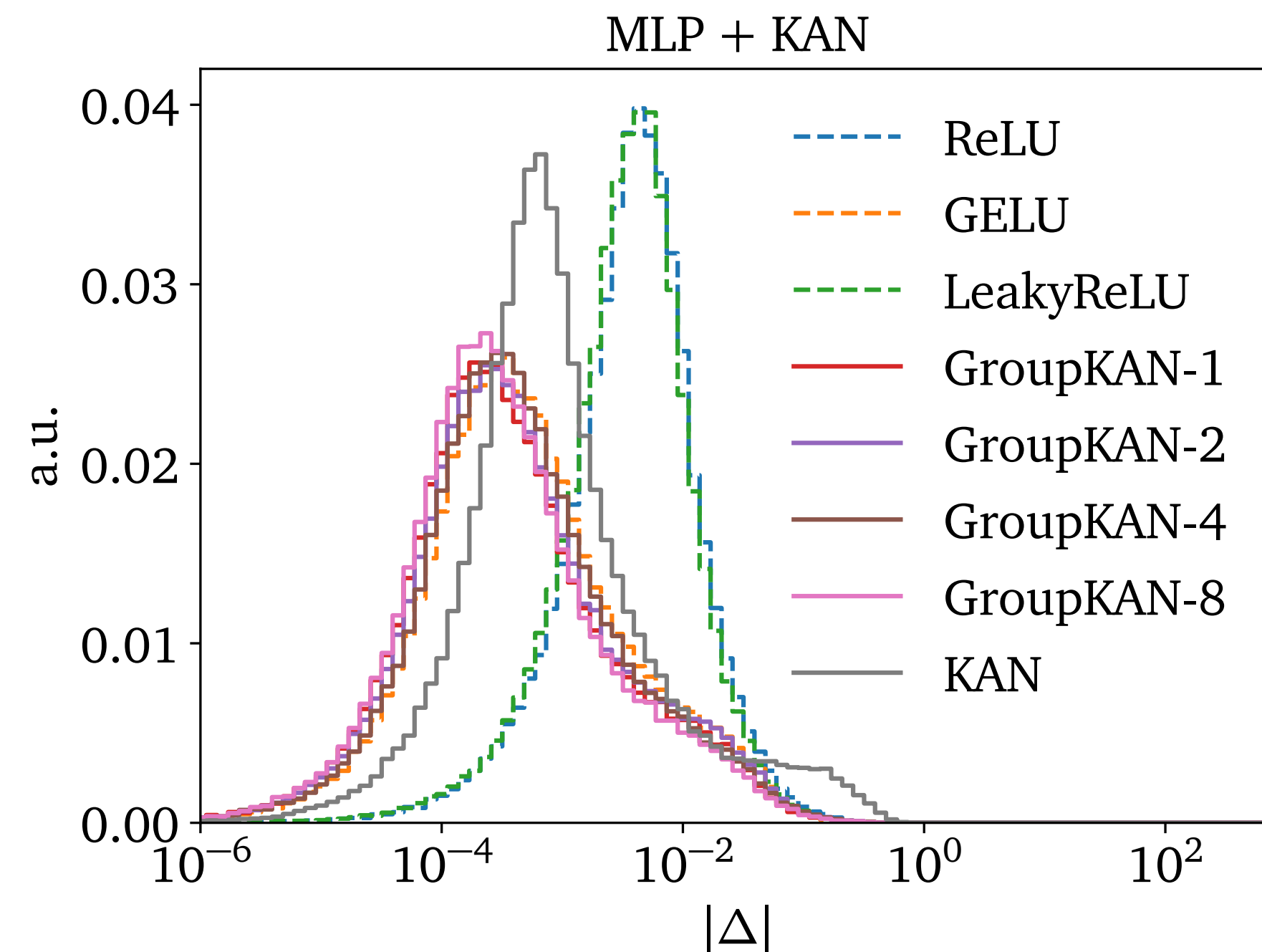
Calibration of networks

- Calibrate RE by introducing scaling parameter T : $\sigma_{\text{syst}} \rightarrow \sigma_{\text{syst}} \times T$
- T estimated by using stochastic gradient descent $\mathcal{L}_T(x) = \left\langle \frac{|A_{\text{true}}(x) - \bar{A}(x)|^2}{2\sigma^2(x)T^2} + \log \sigma(x)T \right\rangle_{x \sim D_{\text{train}}}$

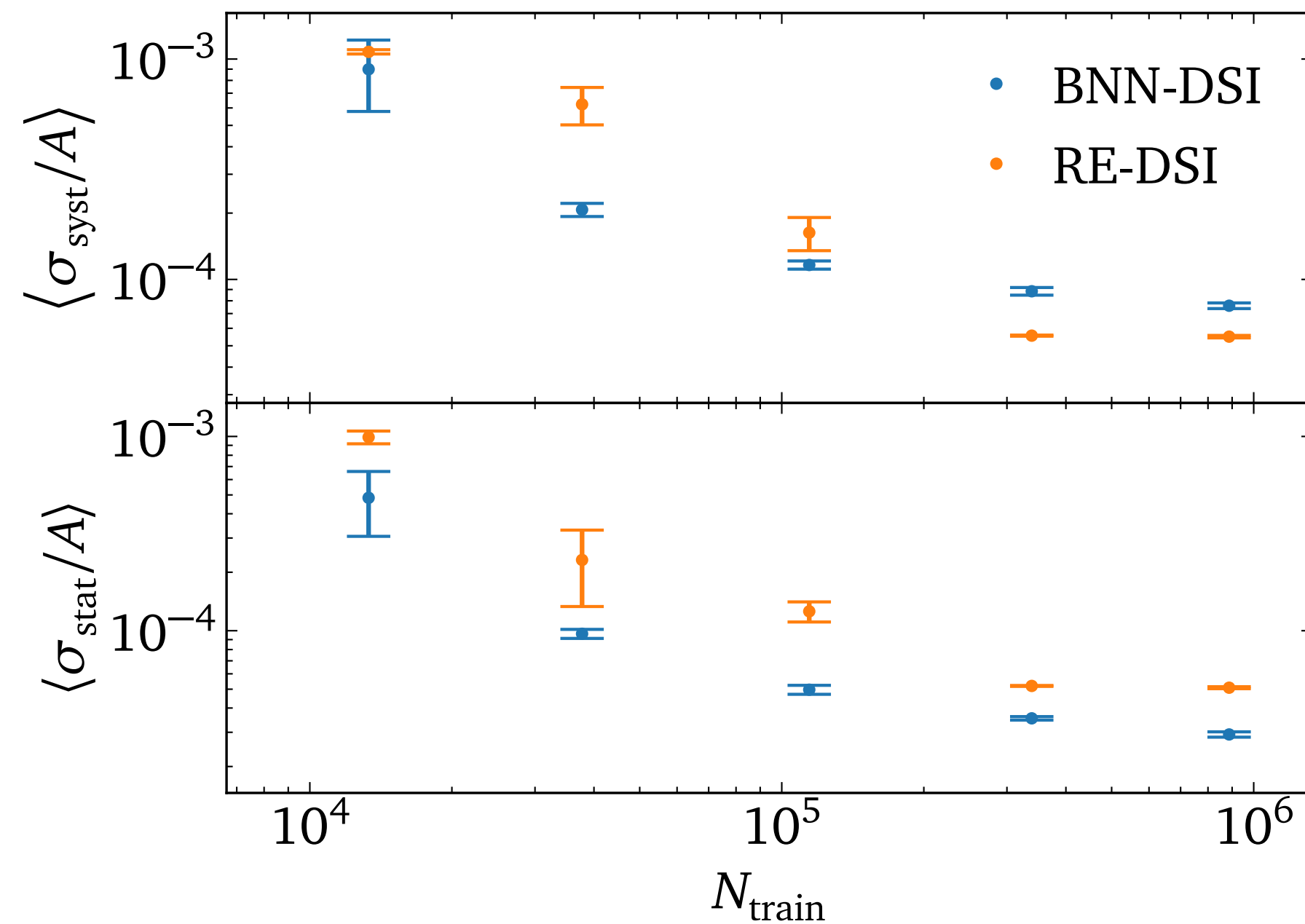


Kolmogorov-Arnold networks (KANs)

- Use KANs for calibration
- GroupKANs allow for learnable activation functions

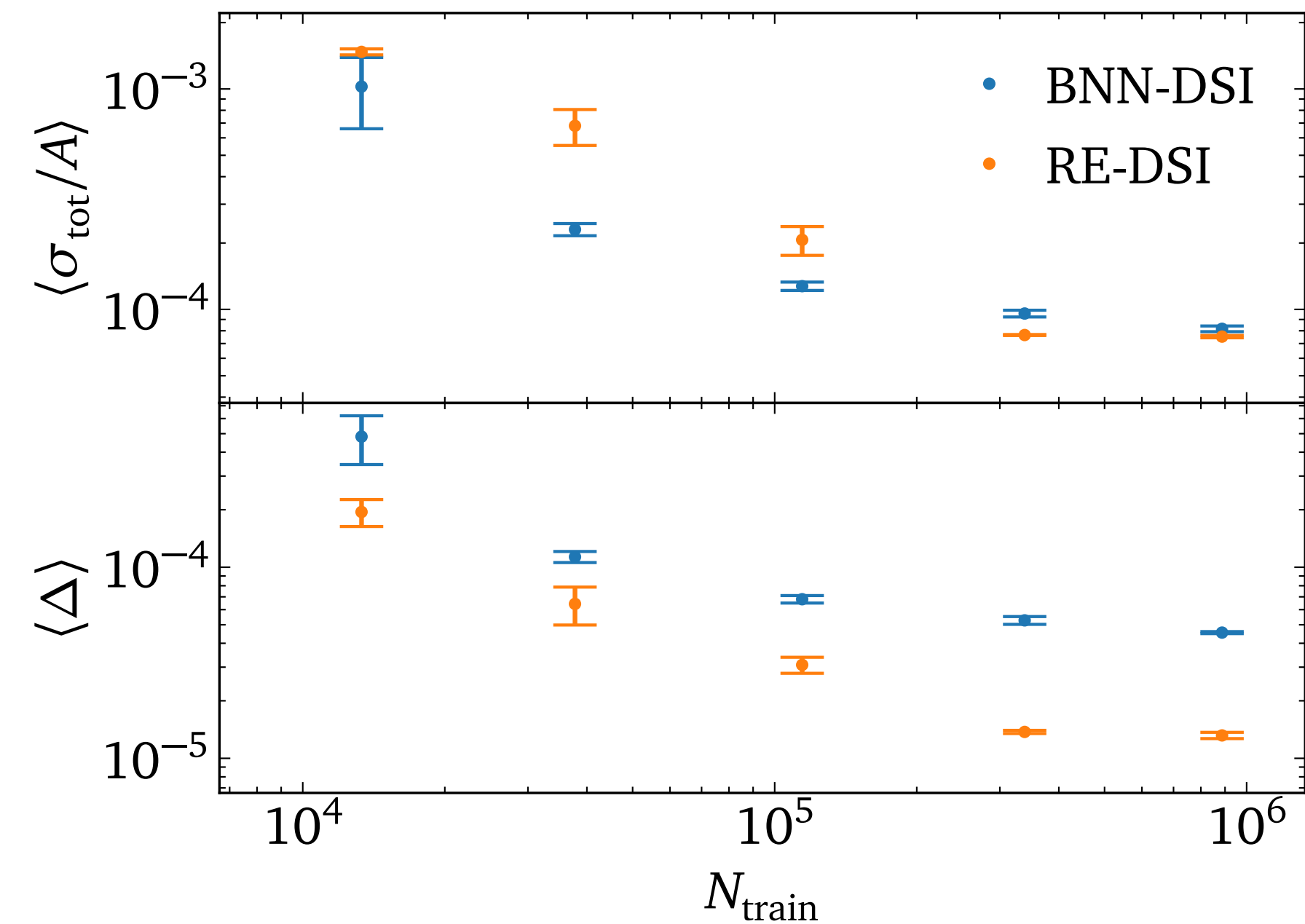


Relative uncertainty vs training size



➡ σ_{syst} always larger

➡ σ larger for RE-DSI than BNN-DSI



➡ Difference in σ_{tot} for small data

➡ RE-DSI more accurate in prediction