

Generation of PXD background using generative models

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The Pixel Vertex Detector (PXD)



- The Pixel Vertex Detector (PXD) is the innermost semi-conductor sub-detector of Belle II, at 1.4 cm from the collision point.
- The sensitive area of the PXD is made up by 40 modules. Each module consists of a 250 × 758 pixel matrix.
- Inner layer: 16 modules implemented into 8 ladders.
- Outer layer: 24 modules implemented into 12 ladders.





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 - Monte Carlo generation —> shows sizeable discrepancies with measurements.
 - Taking random trigger events.
- Problem: large amount of resources required for storage and distribution of the background data.
- Solution: generate background hits on the fly for each sensor.



Generative Adversarial Network



Generating pixels with GAN



Previous approach:

 GAN conditioned on sensor number with a transformer-based relational reasoning module to reproduce the correlations between sensors(IEA-GAN).

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New approach: generate the background using a GAN without conditioning on the sensor number.

- Generate instances of background for all sensors at once.
- ▶ Wasserstein GAN with CNN layers used in the Generator and Discriminator.





The generated images are visually very similar, but with some subtle differences.



Evaluation - Occupancy per sensor

The model seems to reproduce quite well the sensor occupancy, aside from some minor details probably due to some fluctuations in the weights of the model.



Evaluation - Correlation

The model does not reproduce correctly the correlation between the sensor occupancy.



Evaluation - helix parameters resolution

GAN background can be used to reproduce resolution of the helix parameters.





Evaluation: Clusters

The generated background images have different clusters distributions.



Cluster generation with GAN

- Train GAN to directly generate clusters instead of full sensor pixels.
- Trained using clusters of sizes from 1 to 30.
- Training dataset uniform in cluster size.



Figure: Example of generated clusters



Evaluation - helix parameters resolution



Evaluation - Vertex reconstruction

- Vertex resolution of D^0 in the decay $D^0 \to K^- \pi^+$
- Drop in efficiency when taking into account the background.





 $v - v_{MC}$ [cm]



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Diffusion model: forward process



$$q(\mathsf{x}_t|\mathsf{x}_{t-1}) = \mathcal{N}(\mathsf{x}_t; \sqrt{1-\beta_t}\mathsf{x}_{t-1}, \beta_t\mathbb{I}) \qquad \{\beta_t \in (0,1)\}_{t=1}^T$$

Diffusion model: inverse process

Example image of generated background

Preliminary results: charge distribution

Simulated charge distribution

- IDEA: consider a point cloud representation of the BKG image and use a Graph Neural Network to predict the noise.
- ▶ In the GNN edge convolutional layers are employed.

GNN: result

GNN: evaluation

Summary and conclusions

- Successfully trained a GAN to generate PXD hitmaps.
- Differences between simulated and generated images, especially regarding sensor occupancy correlation and clusters.
- Generated background reproduces helix parameters resolution well.
- Successfully trained a GAN to generate clusters.
- Generated clusters correctly reproduce the helix parameter resolution.
- ► Trained a diffusion model to generate background images.

Conclusions and outlook:

- Demonstrated that generative models can produce PXD background with the required accuracy.
- Possibility to use other methods which do not involve ML i.e. constructing BKG files by sampling techniques.

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Thanks for your attention!

Backup - Generator

Figure: Generator architecture

Backup - Discriminator

Figure: Discriminator architecture

Evaluation: cluster size

