

NN reconstruction development and performance

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 $t\bar{t}$ reconstruction meeting

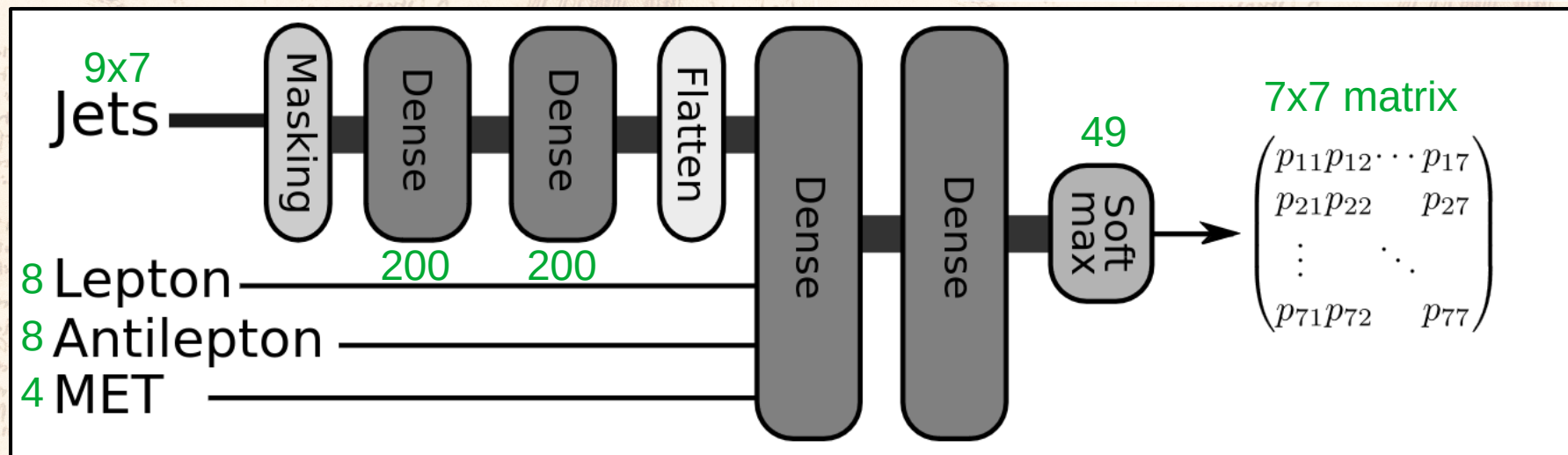
Jonas' NN

- Feed-forward NN developed by Jonas as alternative to Sonnenschein
- Gitlab repo for training (on pepper outputs):
<https://github.com/jrueb/reconn/tree/master>
- Implementation in pepper:
https://gitlab.cern.ch/jrubenac/pepper/-/blob/HIG-22-013/pepper/kinreco_ttbar_nn.py?ref_type=heads
- Note: all truth level results are with last copy bottoms- not best choice, see Tim's talk

Neural Network for **bottom jet tagging**

- **Input:**
 - 7 jets 4-momenta + DeepJet b tag
 - All 4-momenta are given in xyzE and $p_T\phi\eta m$ coordinates
- **Output:**
 - A 7x7 matrix. Each entry O_{ij} is interpreted as the probability that the ij jets come from $b\bar{b}$ quarks

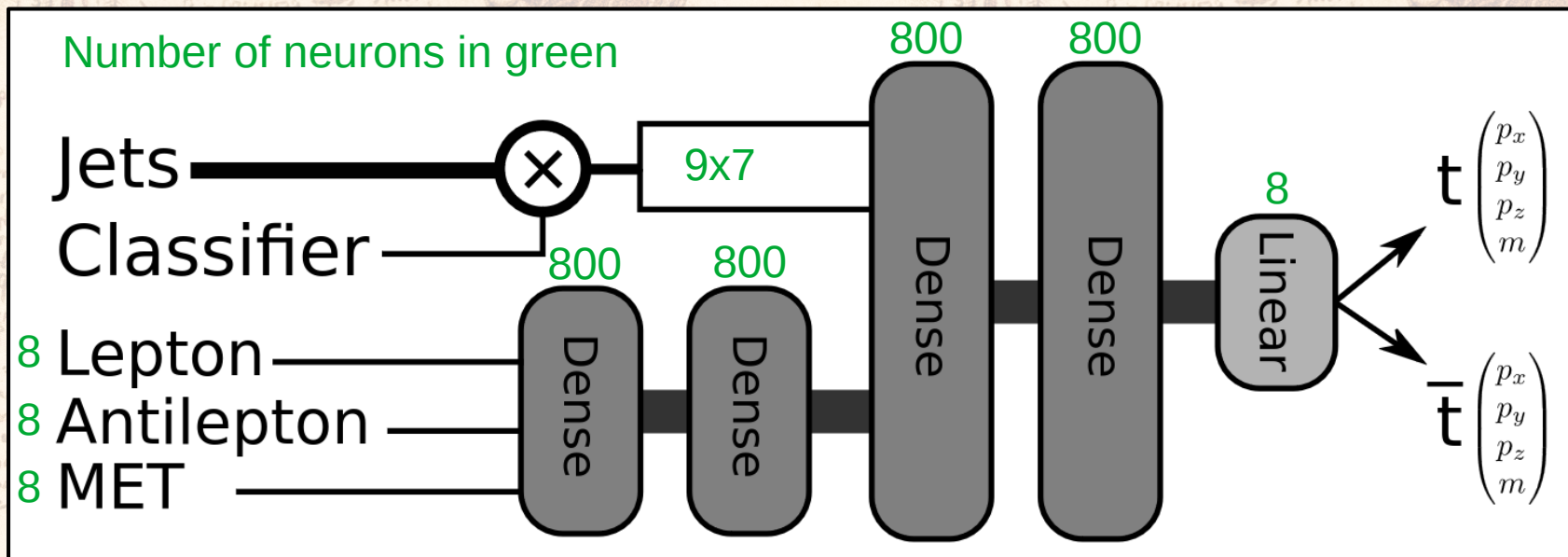
Number of neurons in green



Dropout probability for each layer is 0.25

Neural Network for **top quarks** 4-momenta reconstruction

- **Input:**
 - 7 jets 4-momenta + DeepJet b tag
 - All 4-momenta are given in xyzE and $p_T\phi\eta m$ coordinates
- **Output:**
 - Reconstructed $t\bar{t}$ 4-momenta in xym coordinates



Dropout probability for each layer is 0.25

Useful Definitions

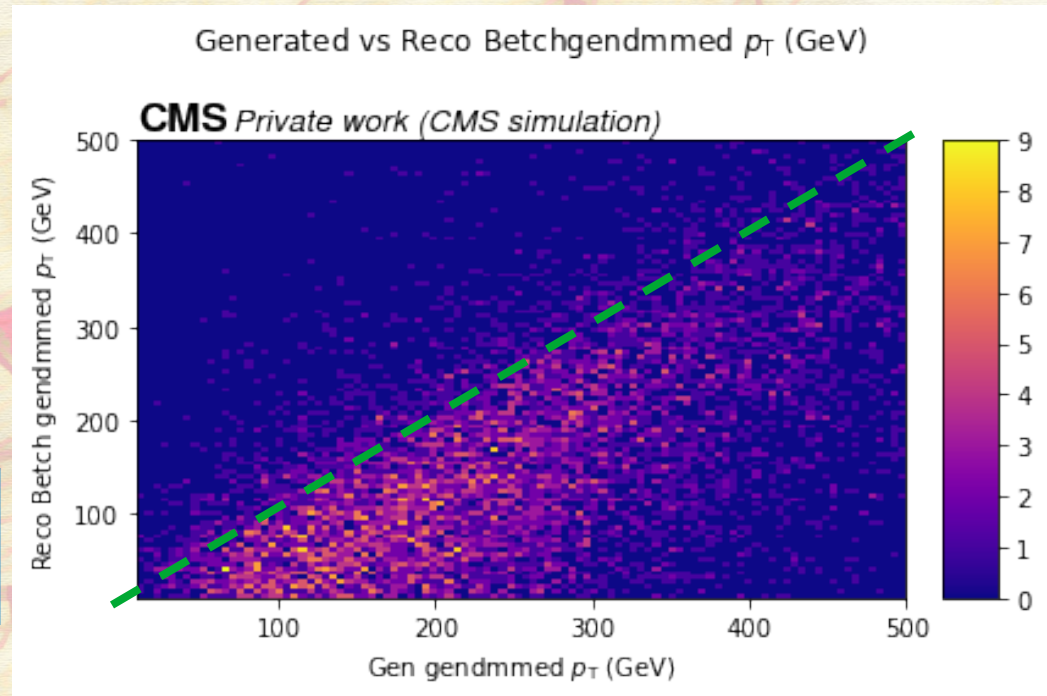
$f(x)$ is the **prediction**, t represents the **true value**

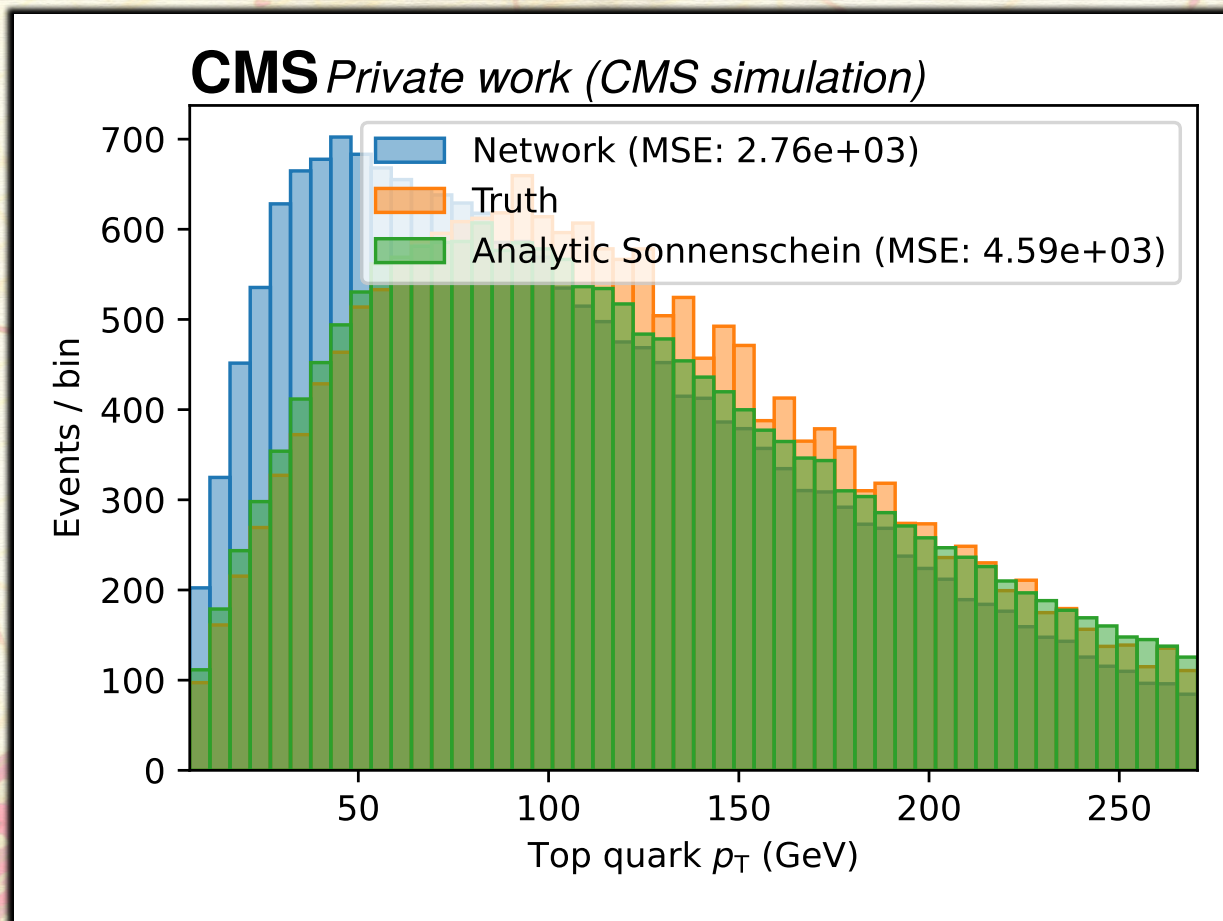
$$Bias = \frac{1}{N} \sum_{i=1}^N (f(x_i) - t_i)$$

$$std\ dev = \sqrt{\frac{1}{N} \sum_{i=1}^N (f(x_i) - t_i)^2 - (bias)^2}$$

$$Relative\ Bias = \frac{1}{N} \sum_{i=1}^N \left(\frac{f(x_i) - t_i}{t_i} \right)$$

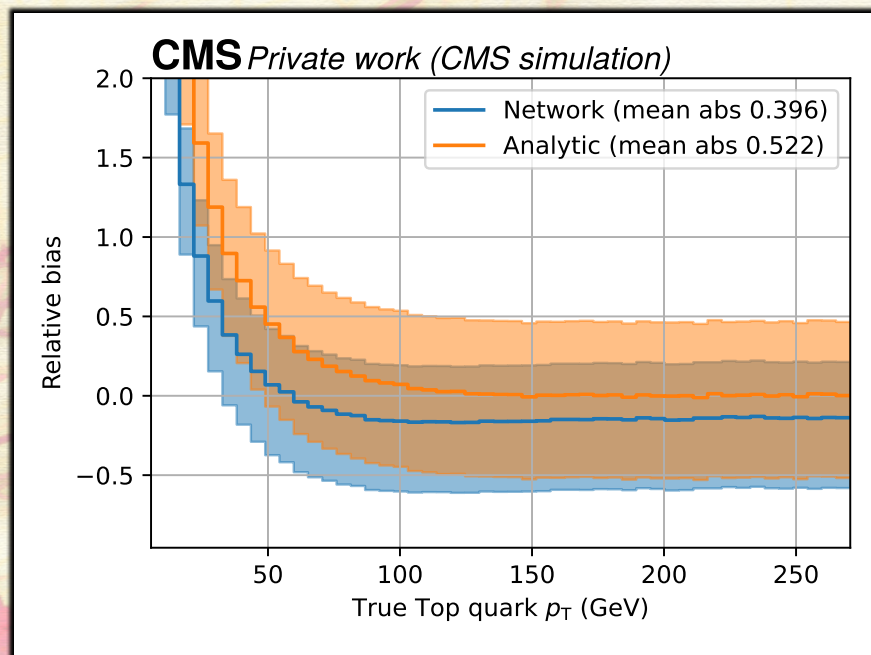
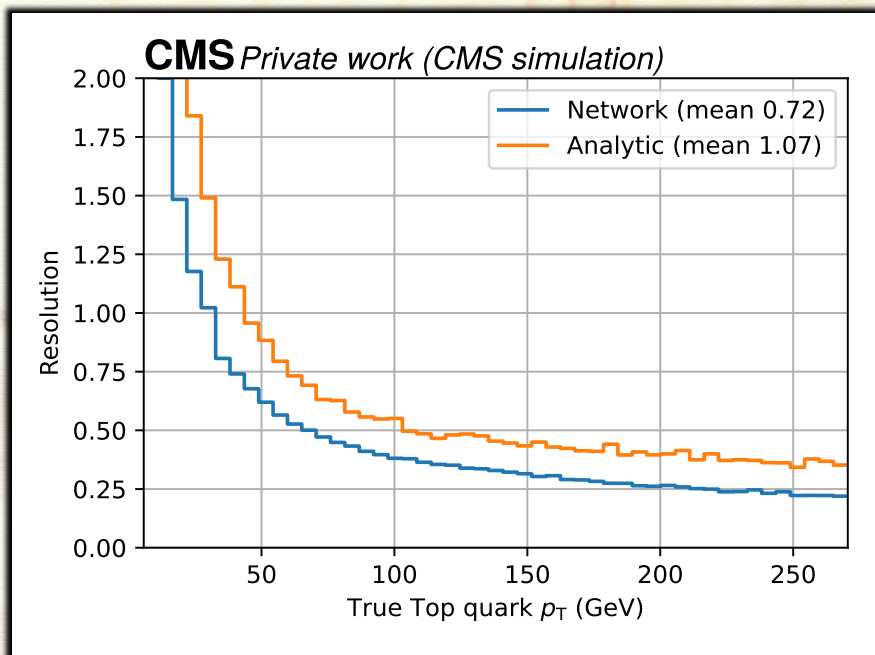
$$Resolution = \sqrt{\frac{1}{N} \sum_{i=1}^N \left(\frac{f(x_i) - t_i}{t_i} \right)^2 - (relative\ bias)^2}$$







Results with SM training

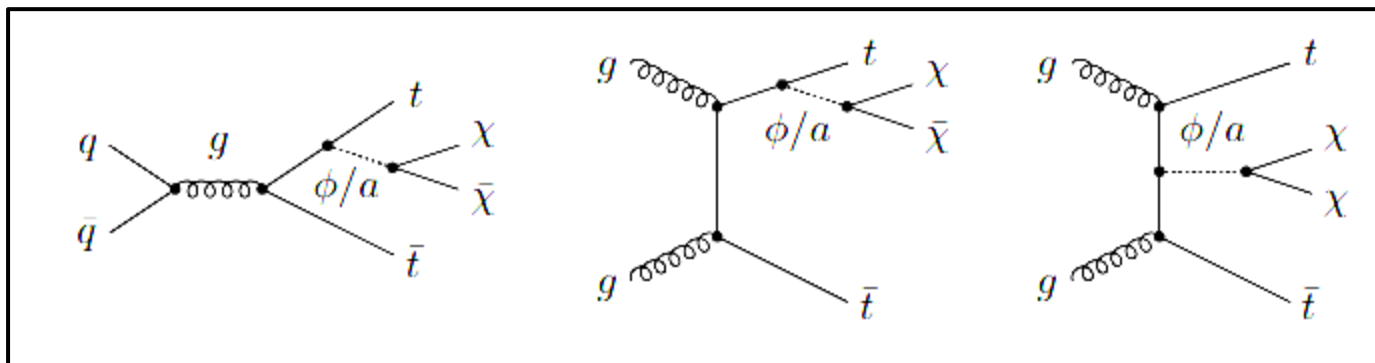


Emanuele's DM studies

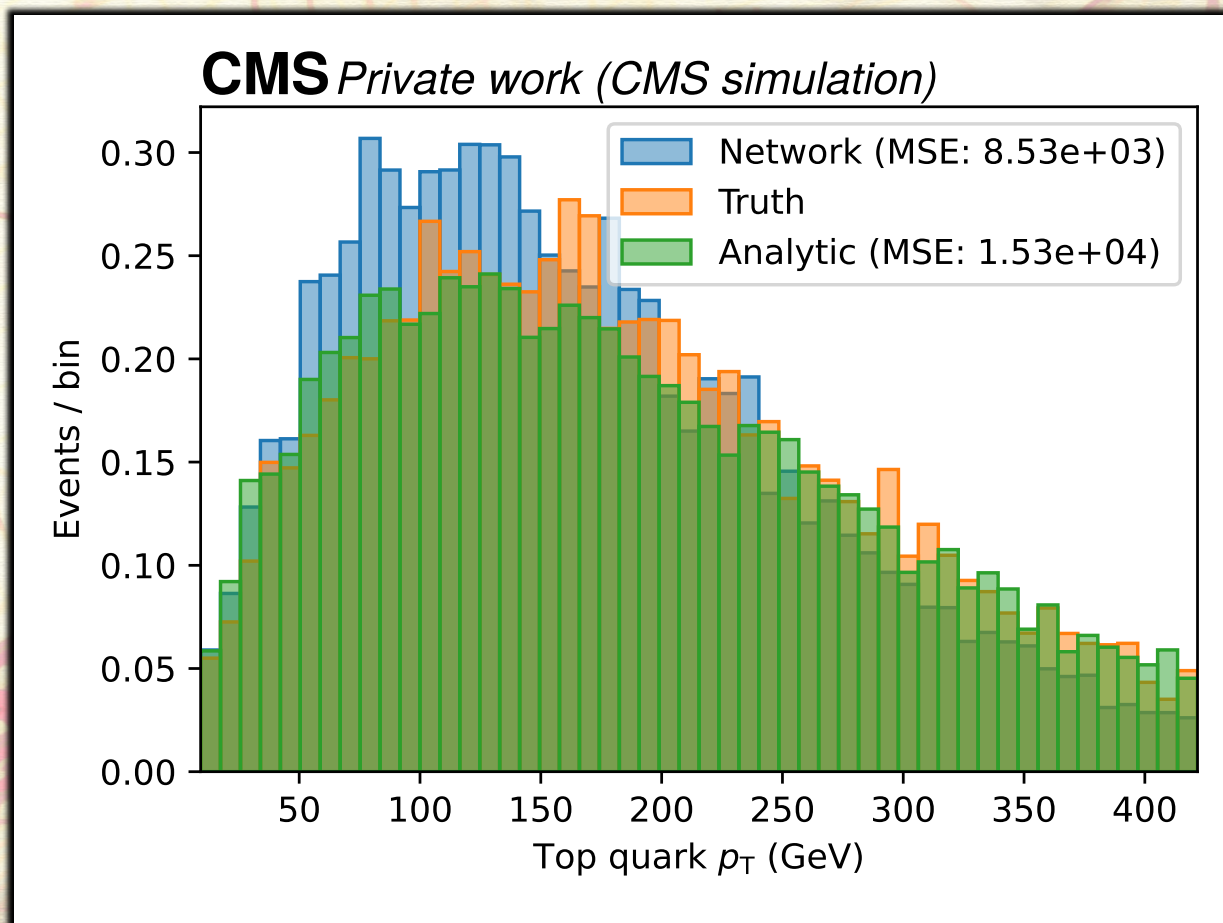
- tt+DM is particularly interesting as an extension as DM adds third source of MET
- Problem is under-constrained
- However some variables can discriminate, e.g.:

$$M_{T2}^{ll} = \min_{p_\nu + p_{\bar{\nu}} = p_T^{miss}} [\max(m_T(p_{l+}, p_\nu), m_T(p_{l-}, p_{\bar{\nu}}))]$$

- A good NN should be able to do equally well



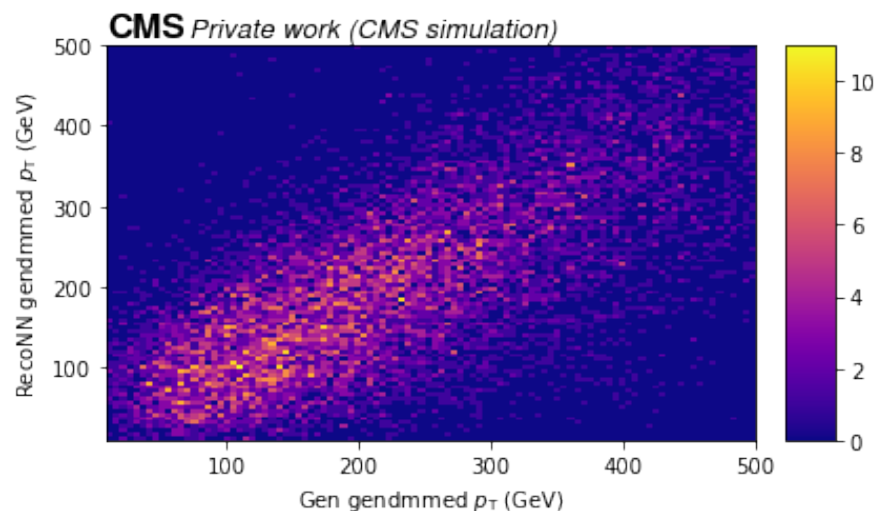
Mediator mass 50 GeV: t quark p_T



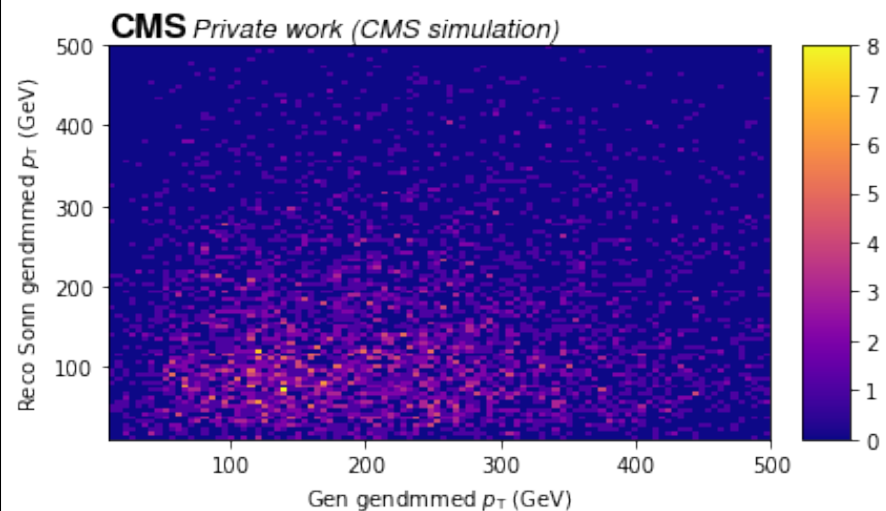


Mediator mass 500 GeV: DM p_T

Generated vs Reco NN gendmmed p_T (GeV)



Generated vs Reco Sonn gendmmed p_T (GeV)

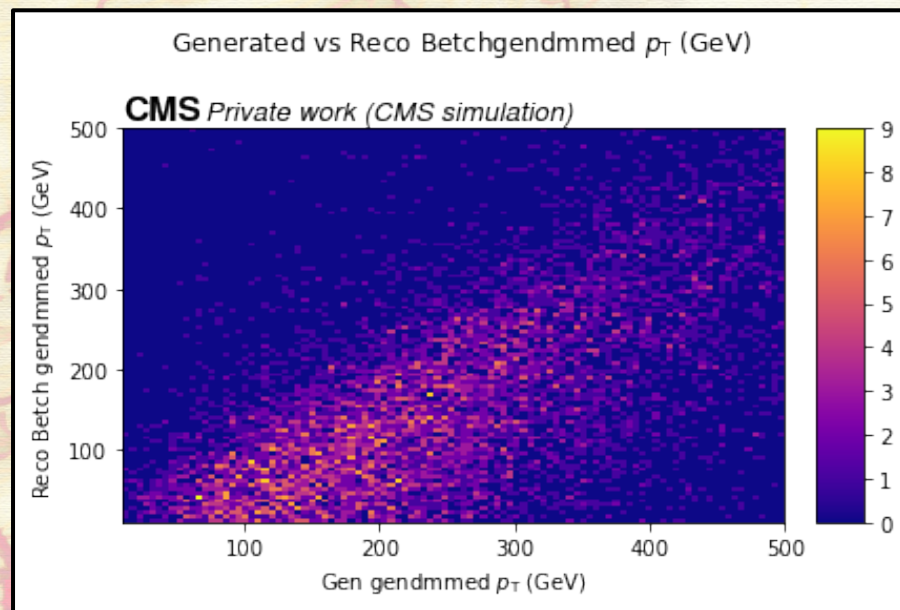
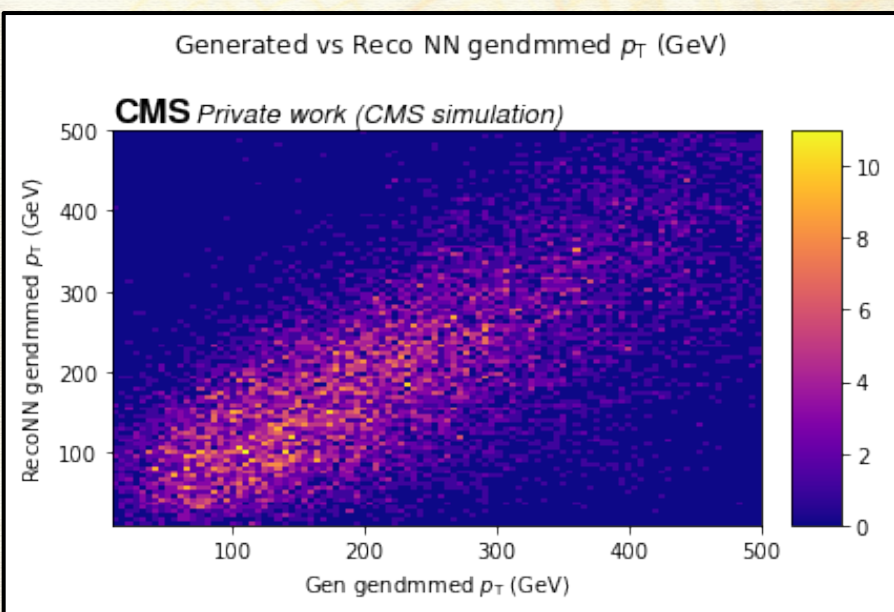




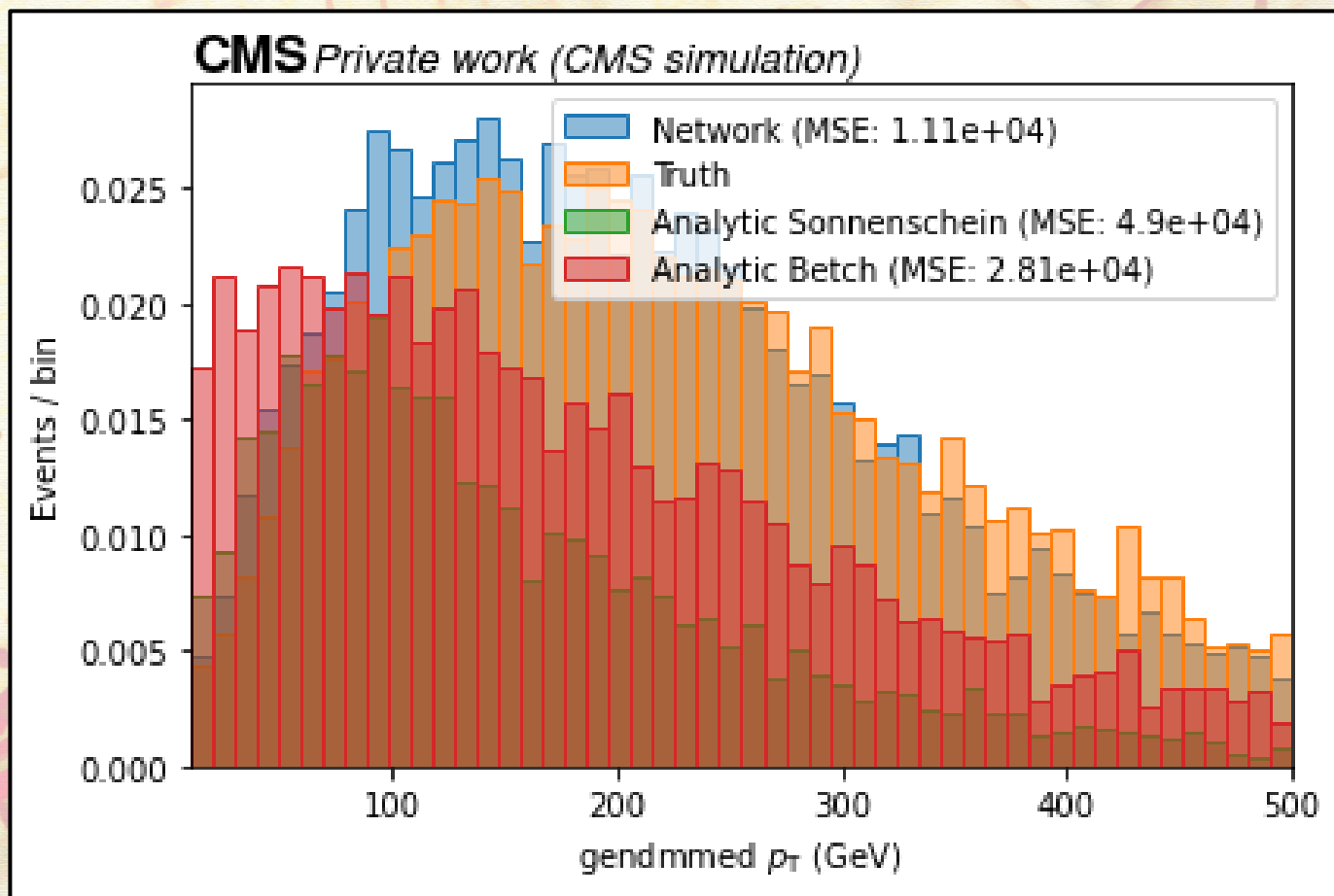
Results with DM training



Mediator mass 500 GeV: DM p_T



Mediator mass 500 GeV: DM p_T

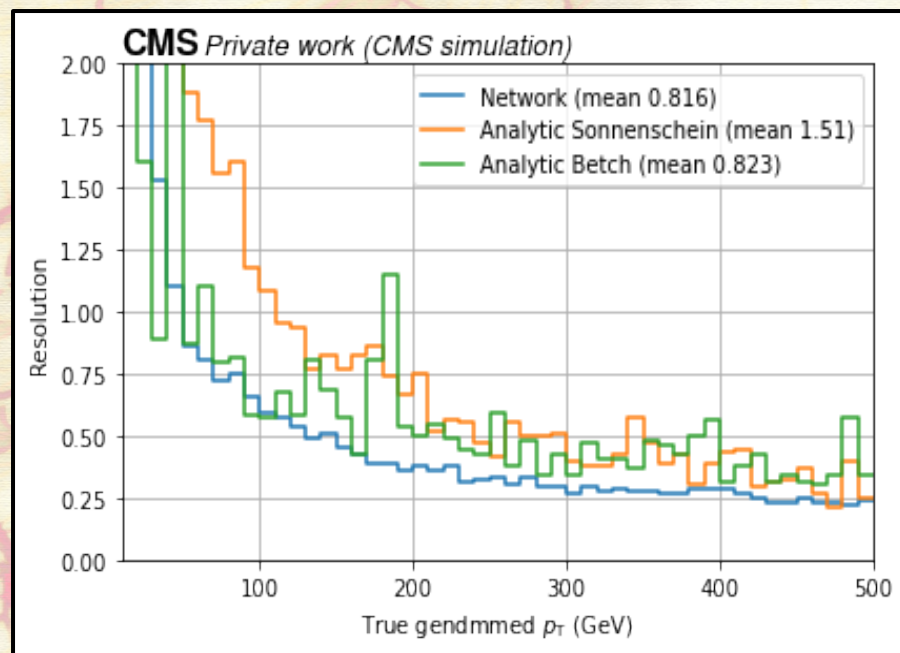
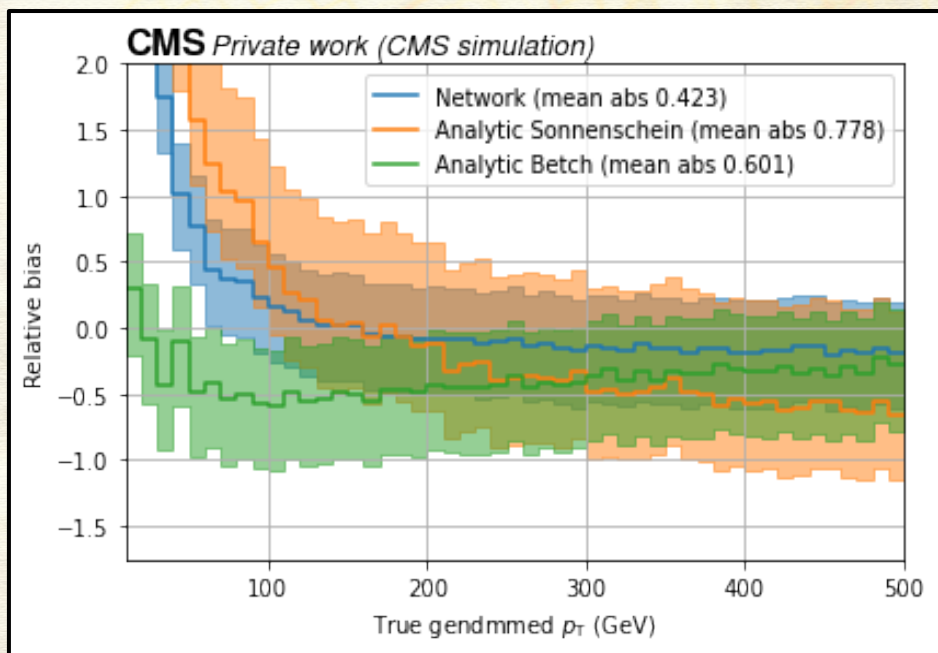




Results with DM training



Mediator mass 500 GeV: DM p_T

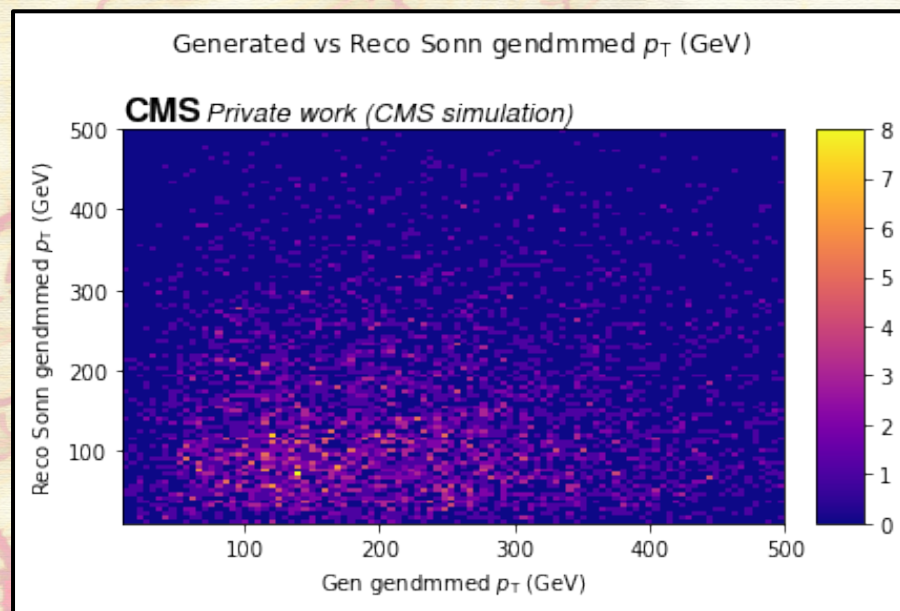
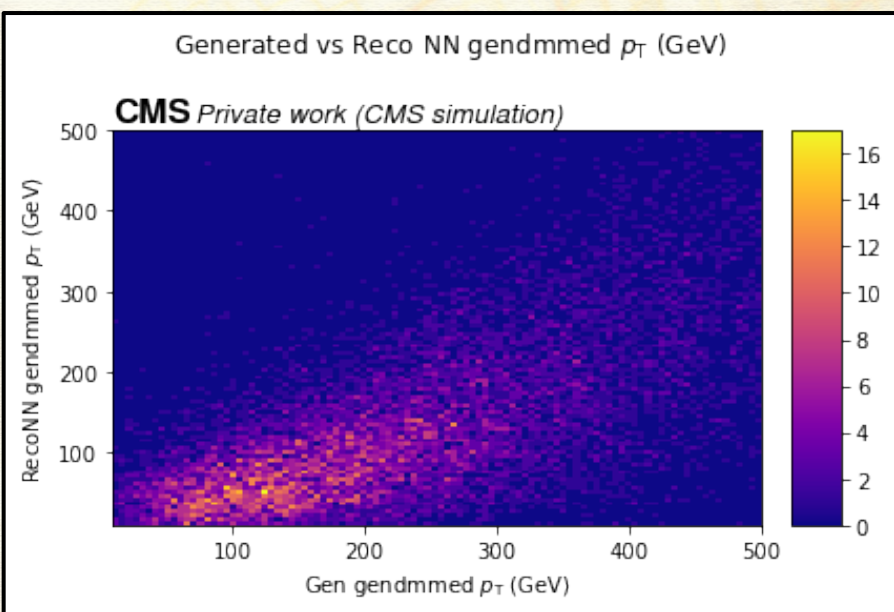




Results with DM training



Mediator mass training 50 GeV, valid 500 GeV:
DM p_T

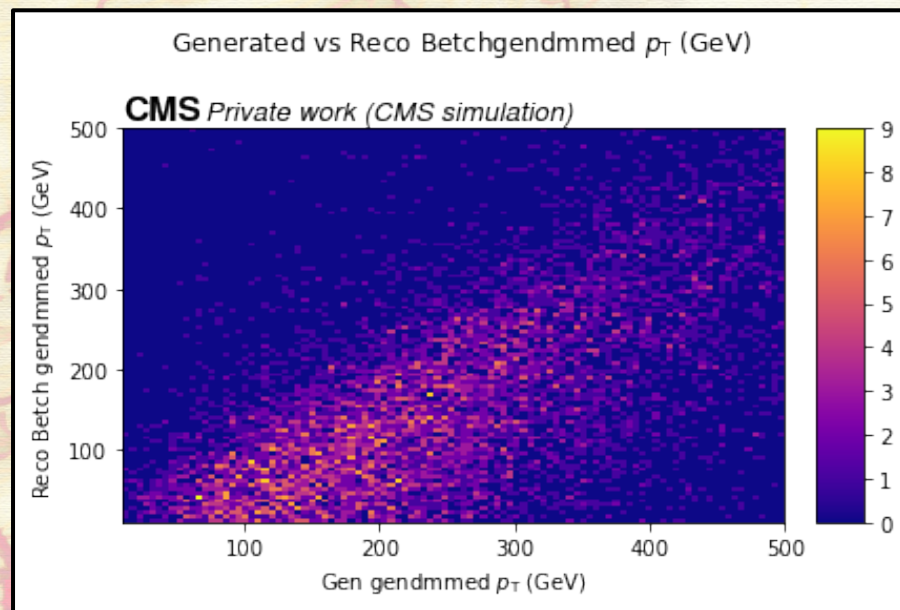
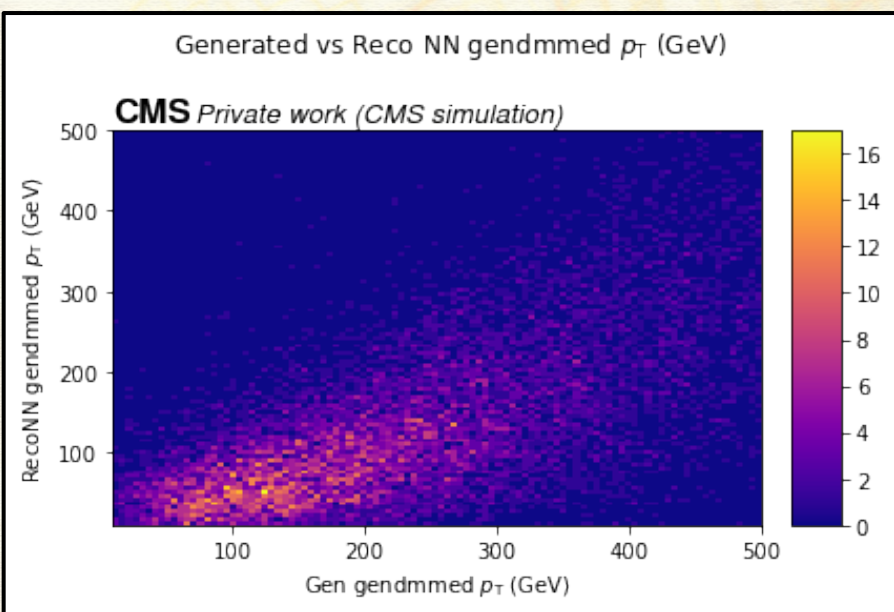




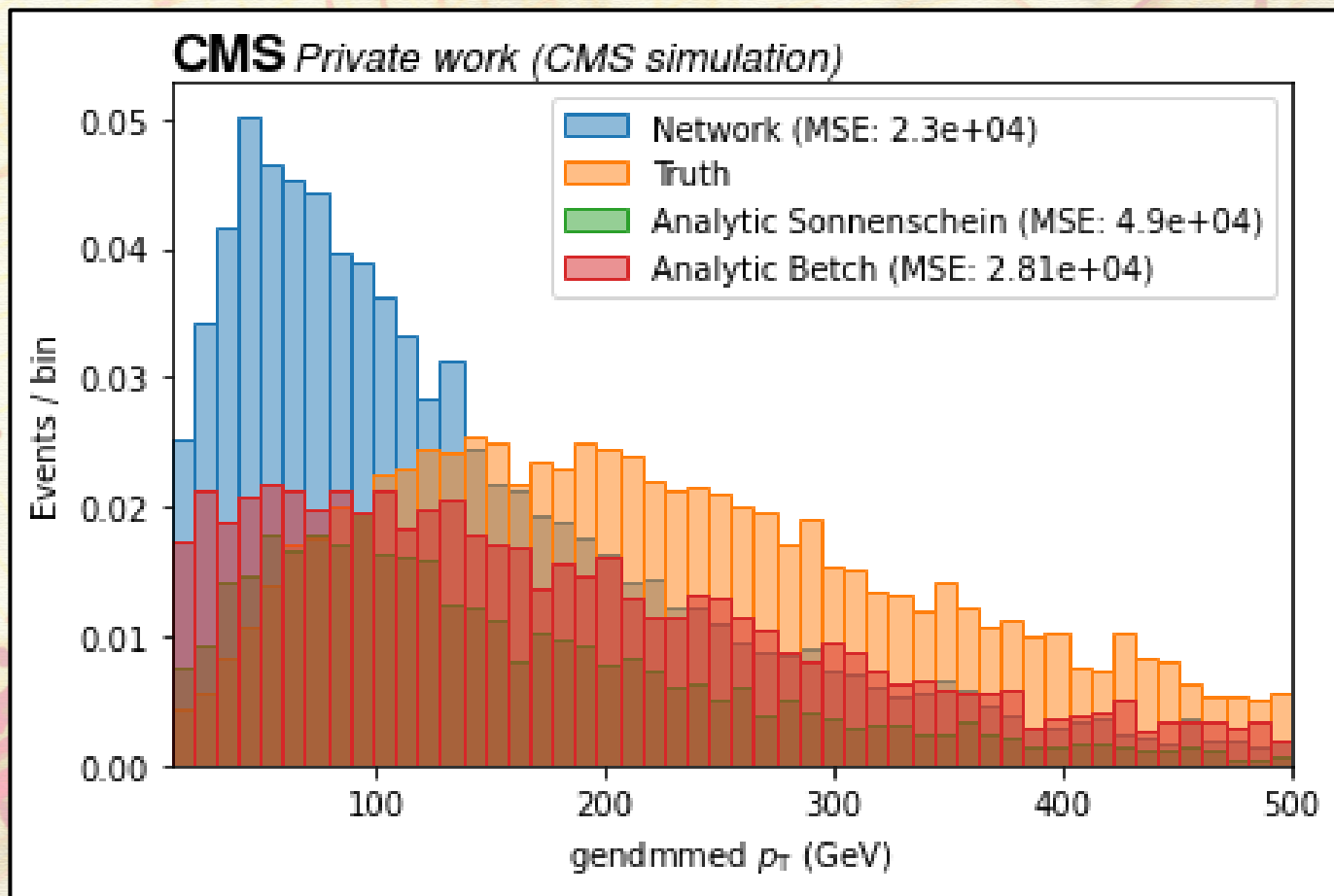
Results with DM training



Mediator mass training 50 GeV, valid 500 GeV:
DM p_T



Mediator mass training 50 GeV, valid 500 GeV:
DM p_T

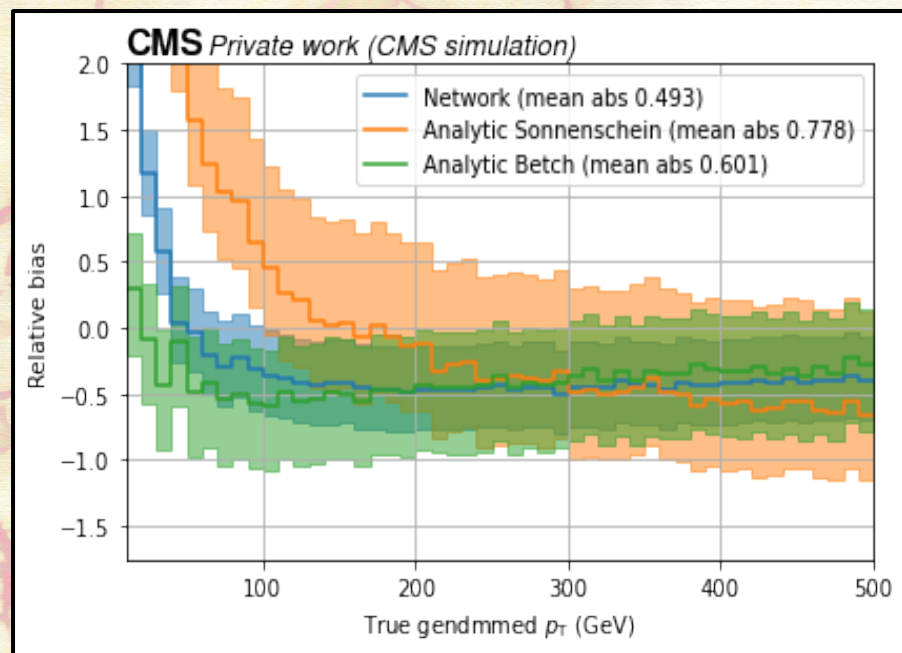
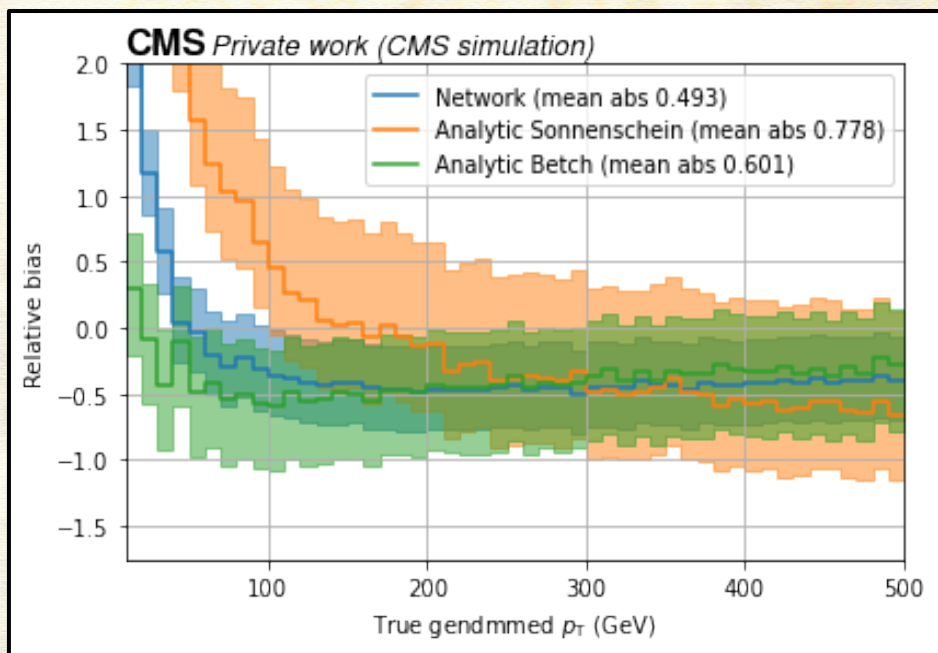




Results with DM training



Mediator mass training 50 GeV, valid 500 GeV:
DM p_T



Conclusions

- Jonas' NN is available, and easy to interface to pepper
- Offers improved resolution, at the cost of higher bias and model dependency
- Two part NN: b-jet assignment and actual reco
 - Would be good to test improvement from Sonnenschein with b-jet assignment NN
- tt+DM is interesting extension case to test model independence



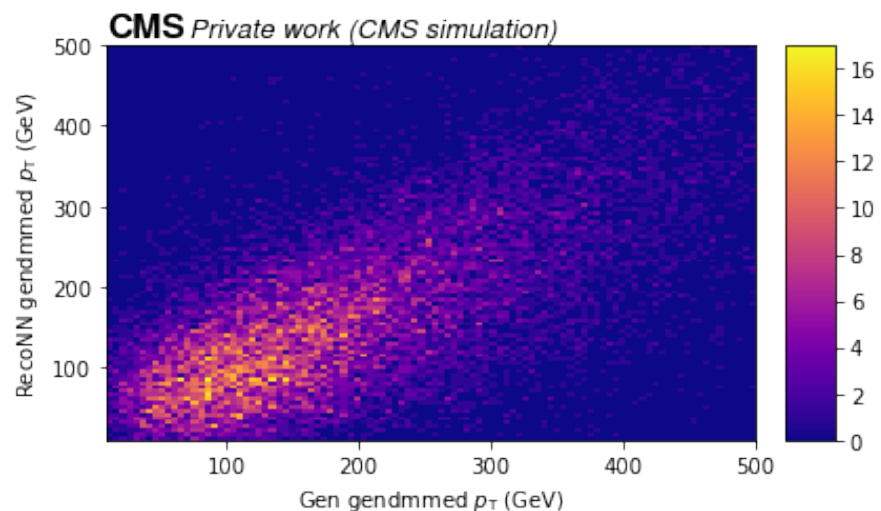
Thanks for your attention

First presentation: 07.08.24
Emanuele Coradin

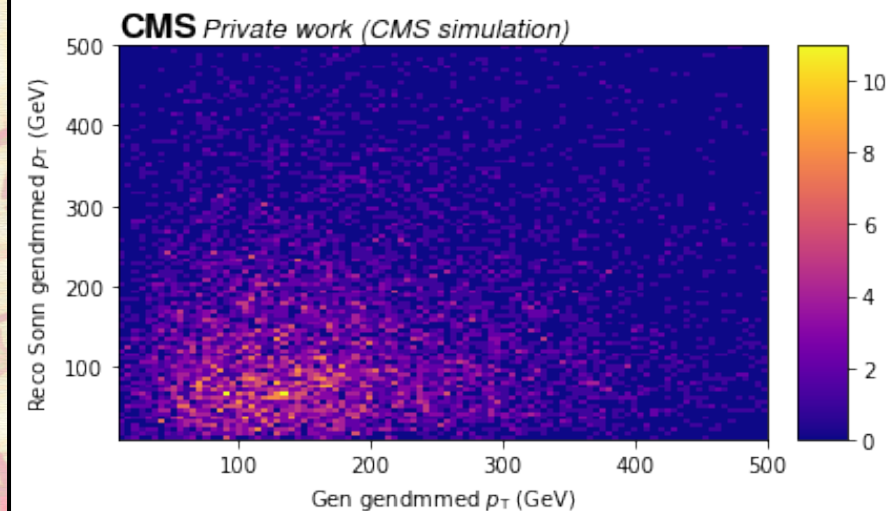


Mediator mass 250 GeV: DM p_T

Generated vs Reco NN gendmmed p_T (GeV)



Generated vs Reco Sonn gendmmed p_T (GeV)

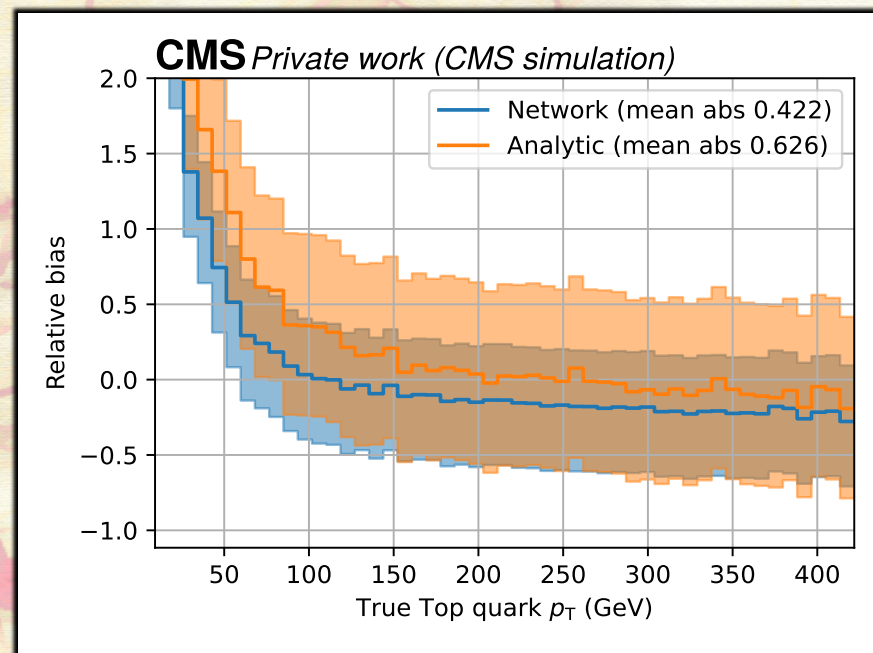
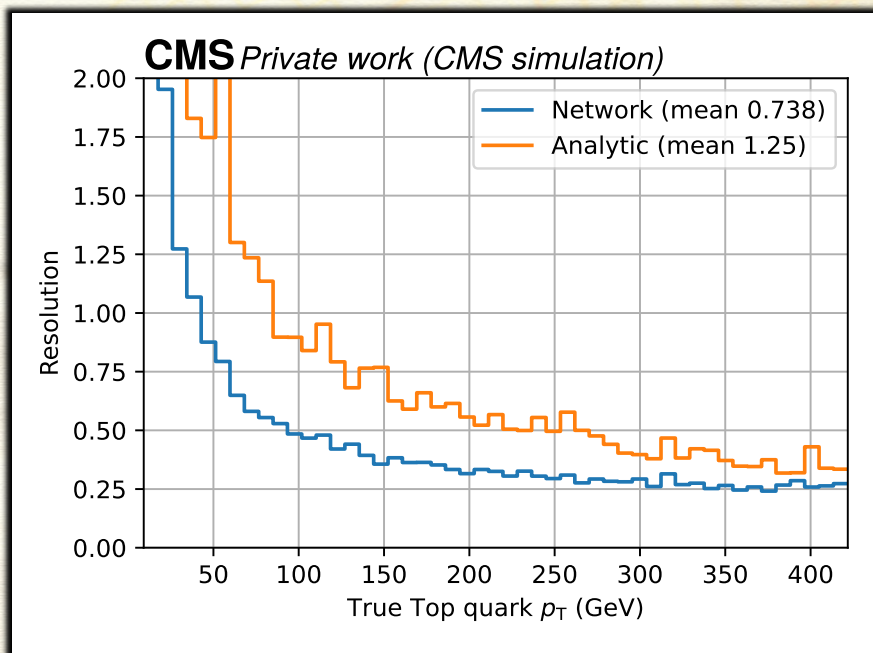




Results with SM training



Mediator mass 50 GeV: t quark p_T

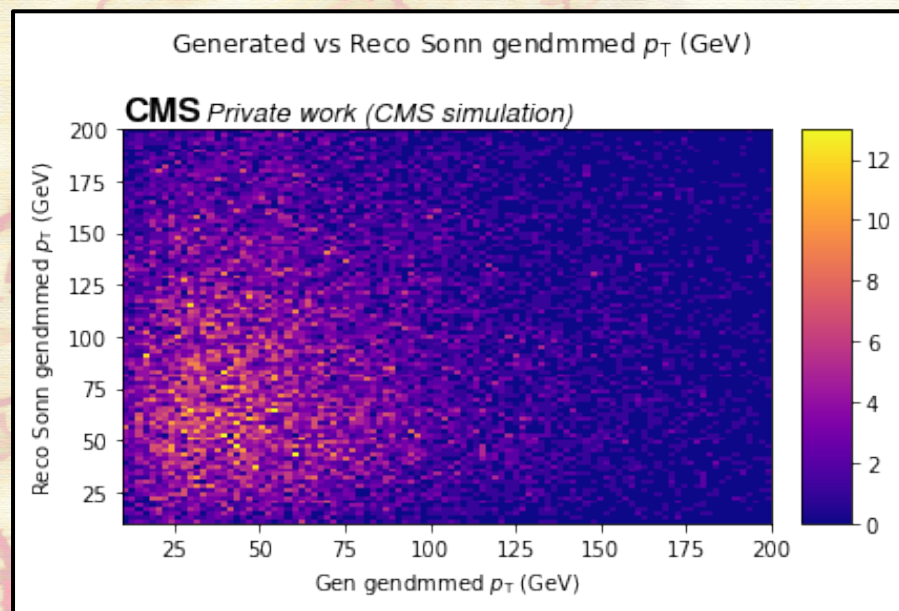
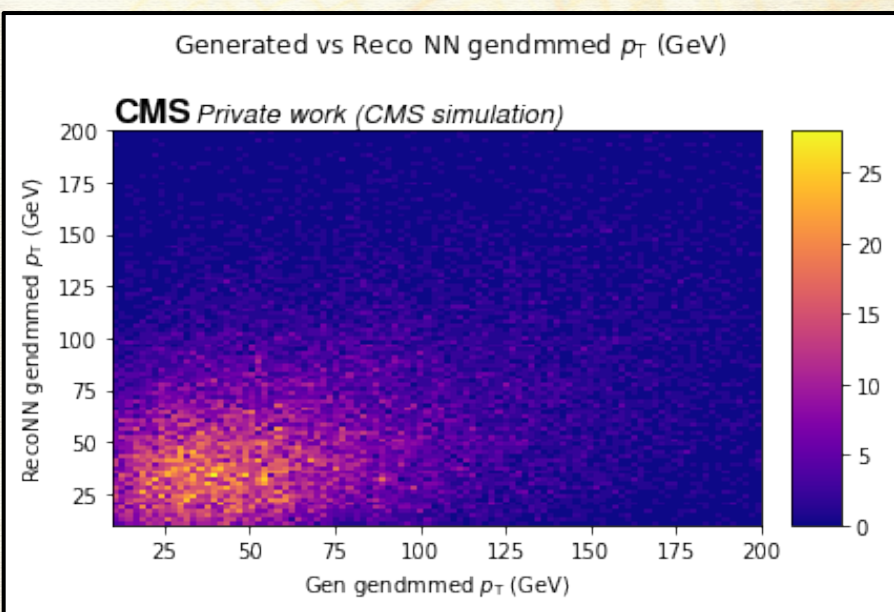




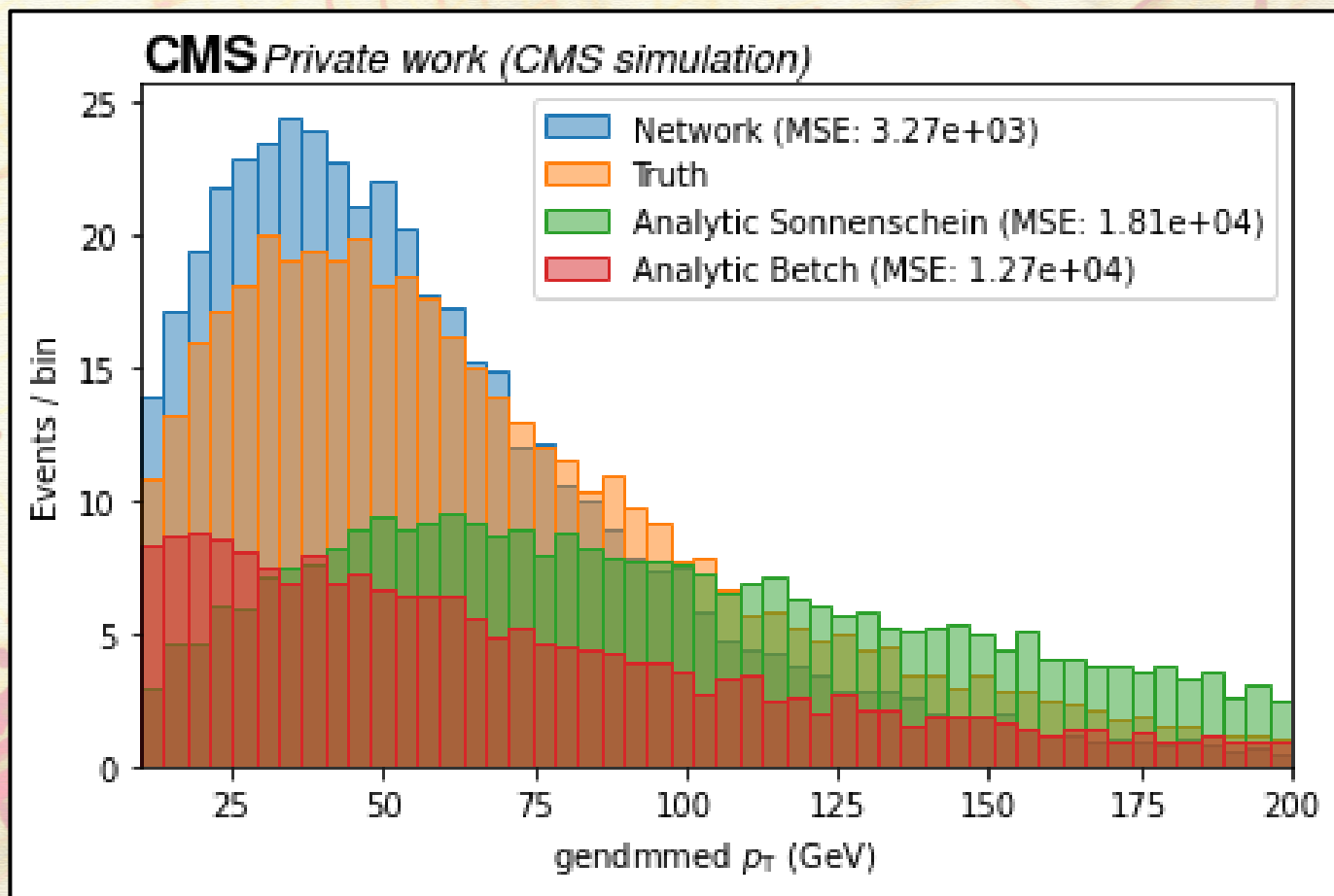
Results with DM training



Mediator mass 50 GeV: DM p_T



Mediator mass 50 GeV: DM p_T

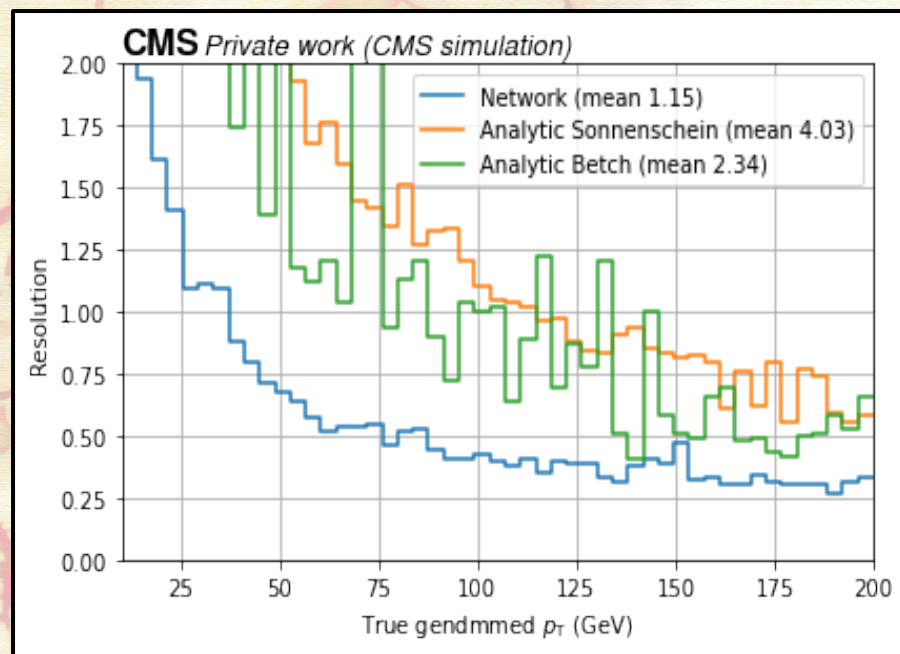
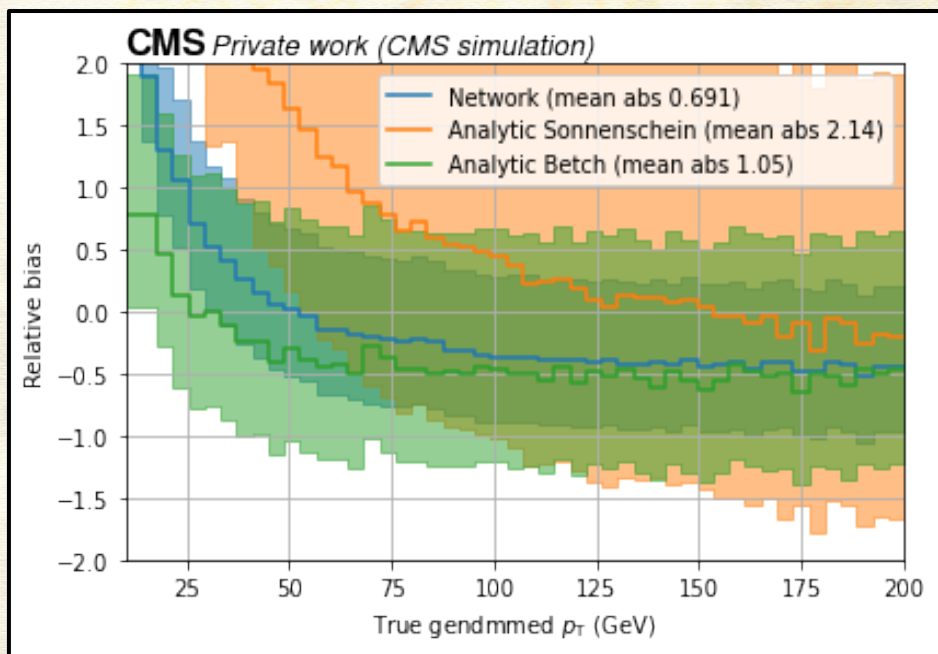




Results with DM training

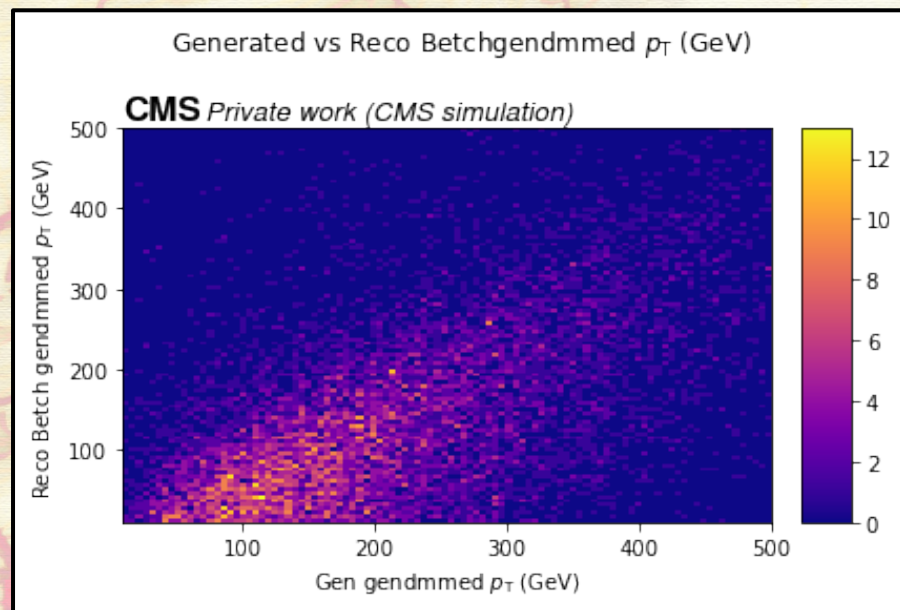
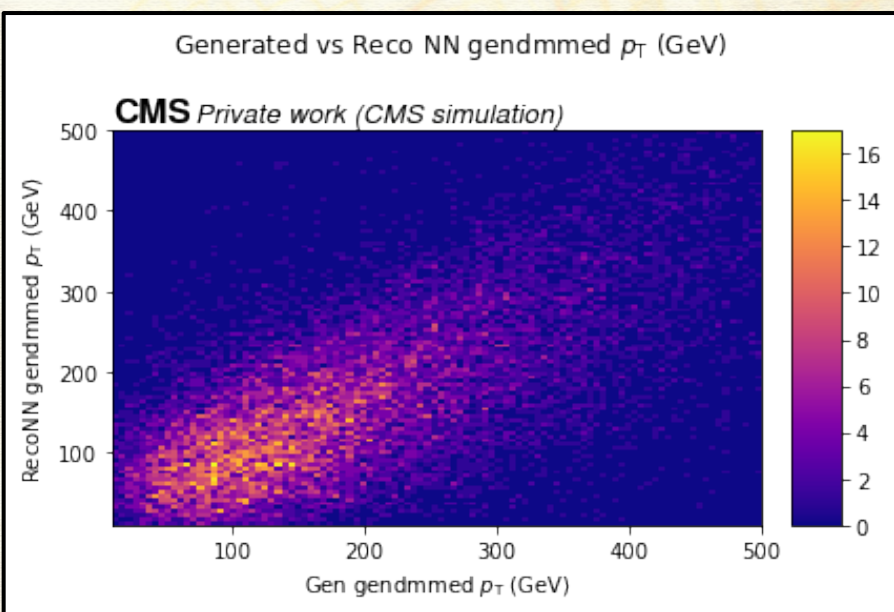


Mediator mass 50 GeV: DM p_T

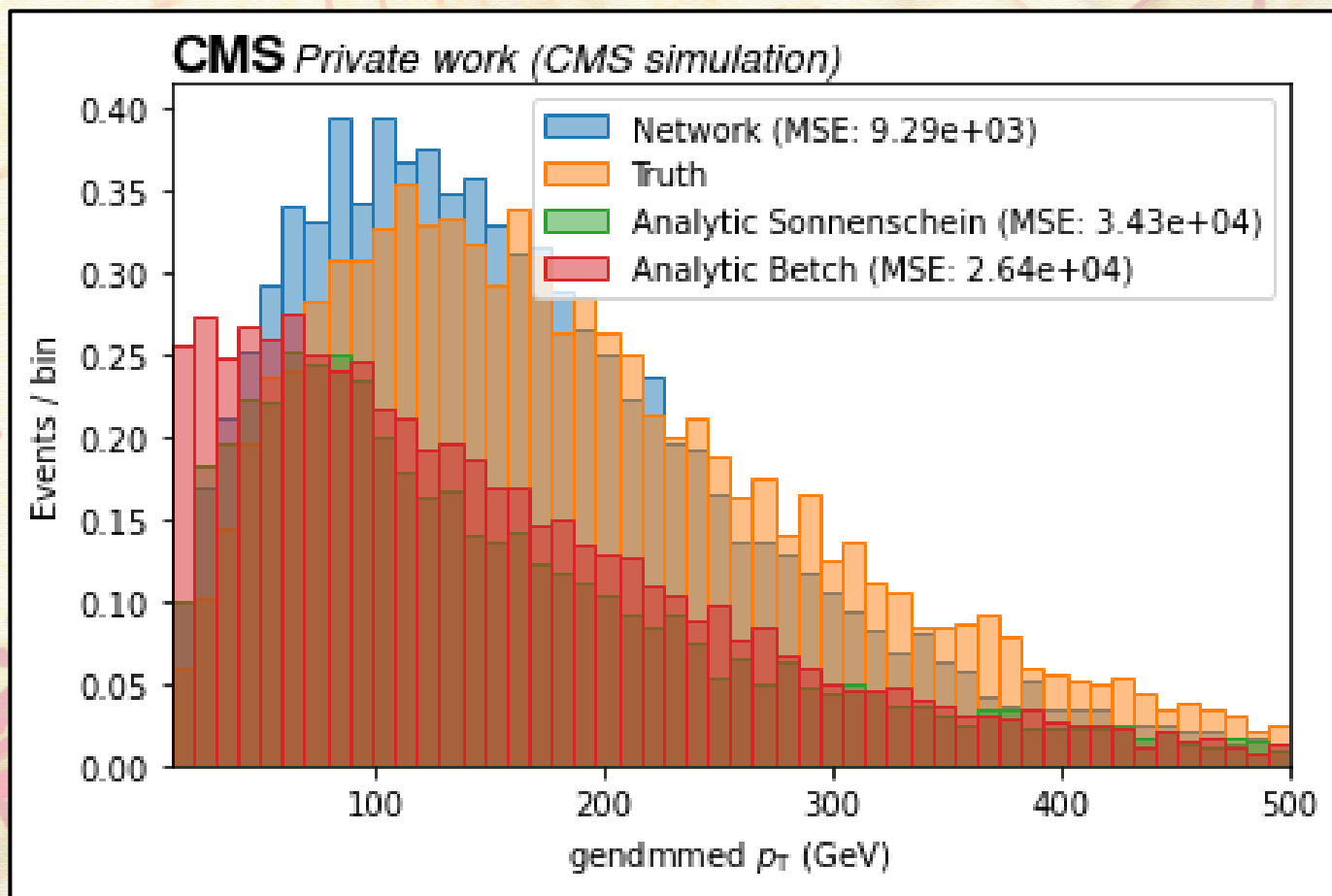




Mediator mass 250 GeV: DM p_T



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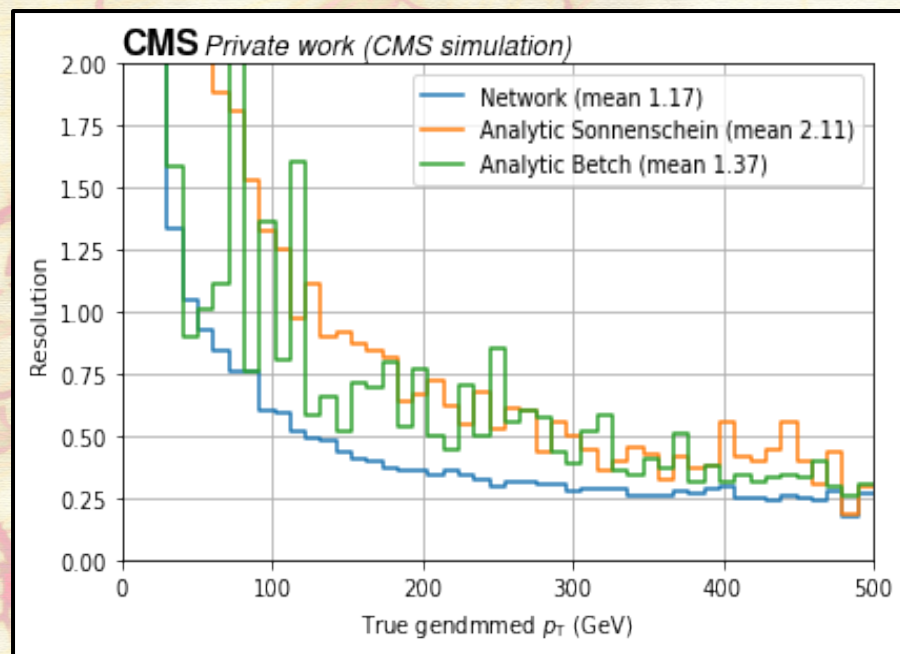
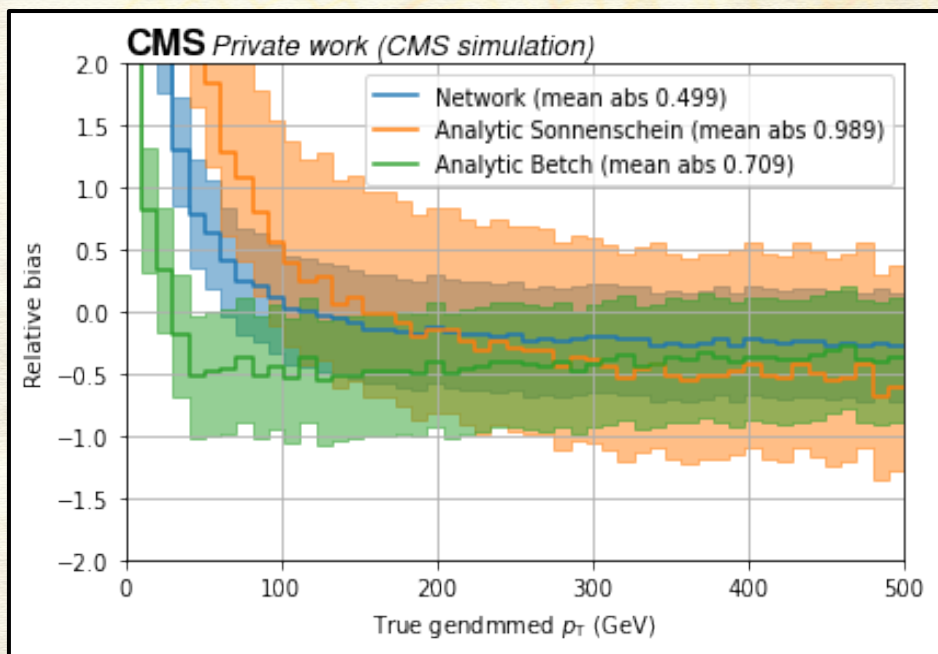




Results with DM training



Mediator mass 250 GeV: DM p_T





Mediator mass training 50 GeV, valid SM, 500 GeV:
DM p_T

