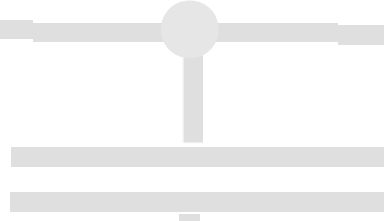


CMSPIXEL
UPGRADE



LINEARITY

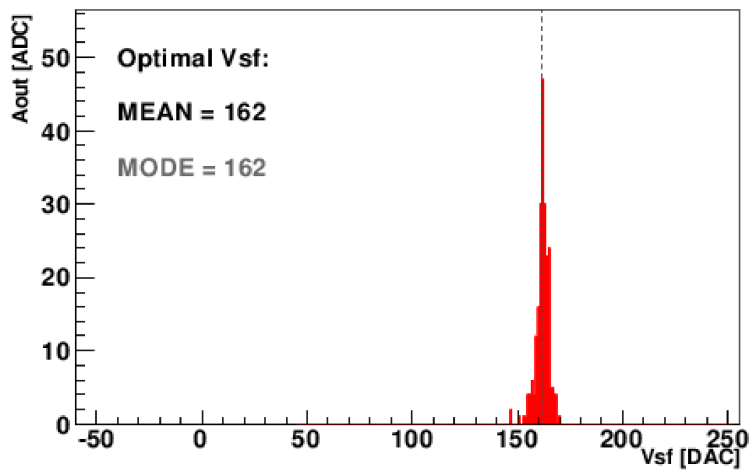
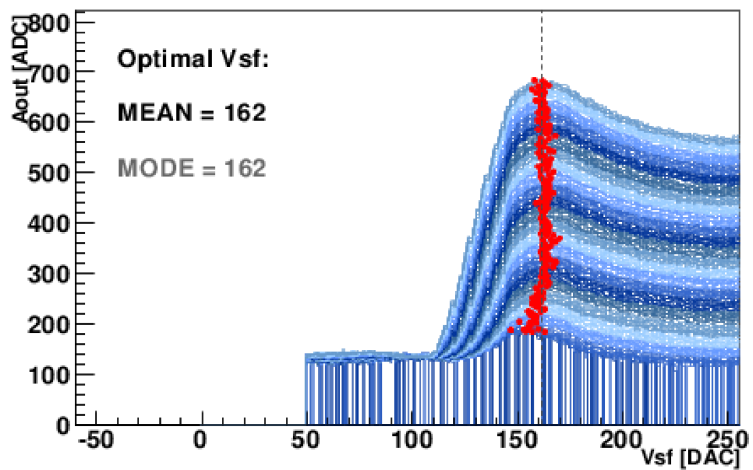
15 Nov 2011

HABIB

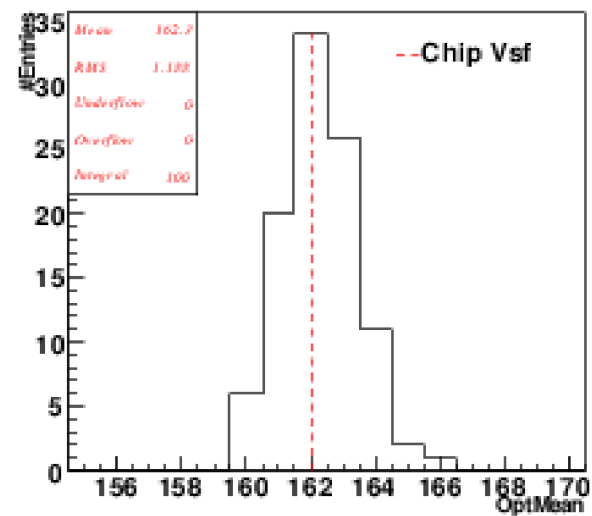
PETRUKHIN

PITZL PLACAKYTE

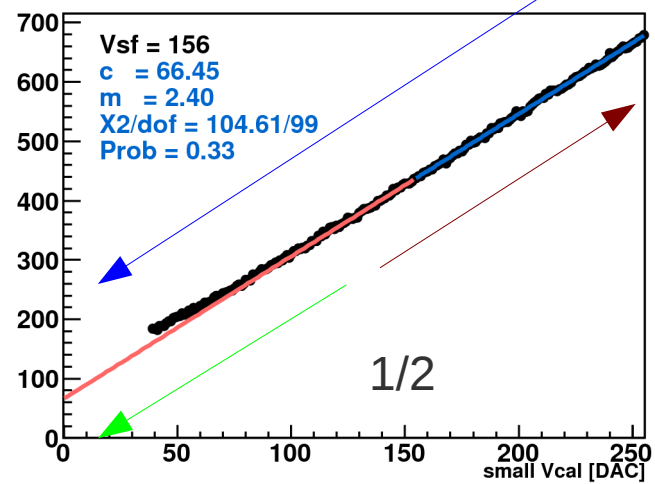
PIXEL



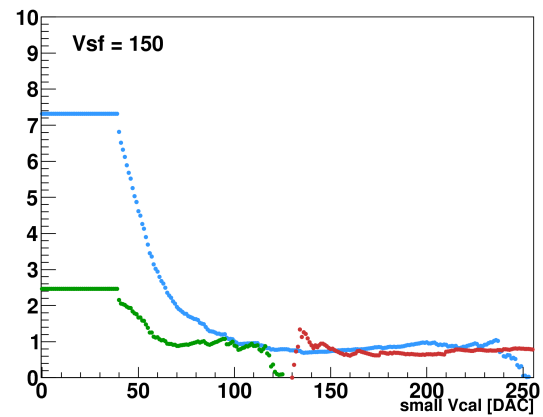
ROC



Aout vs small Vcal vs Vsf

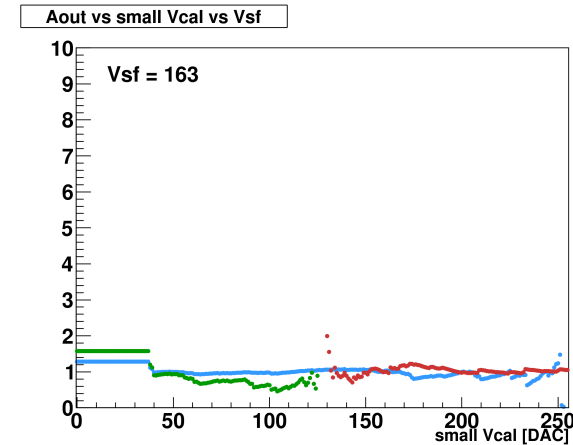
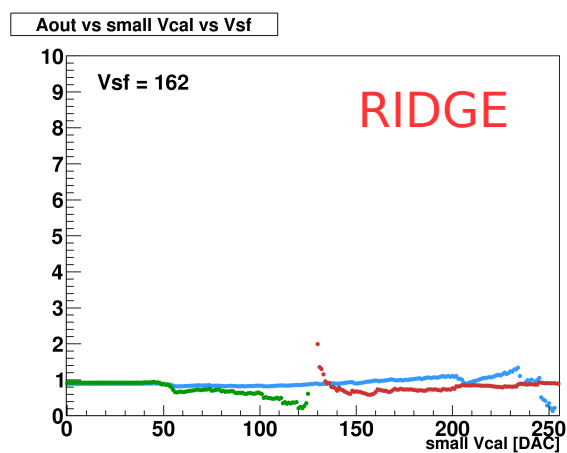
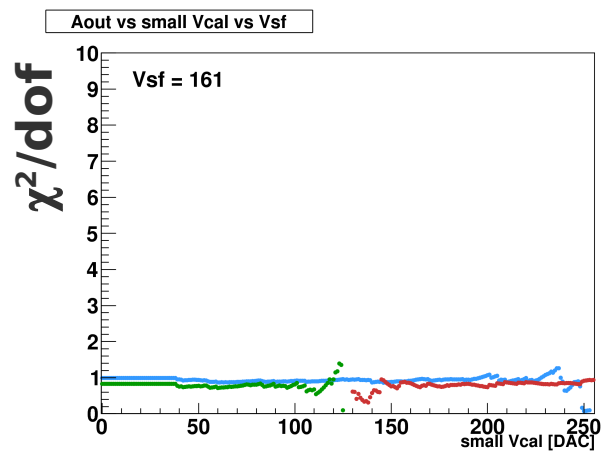
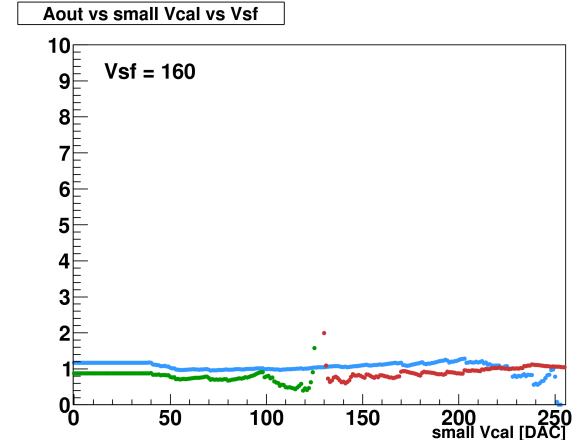
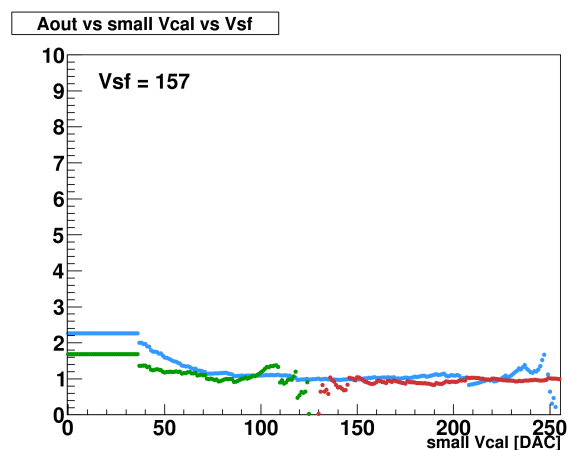
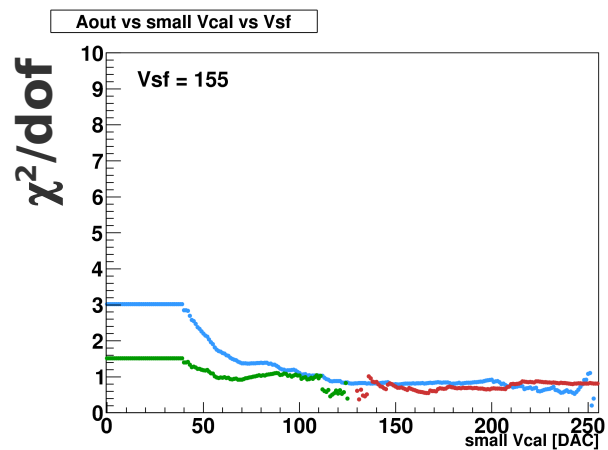
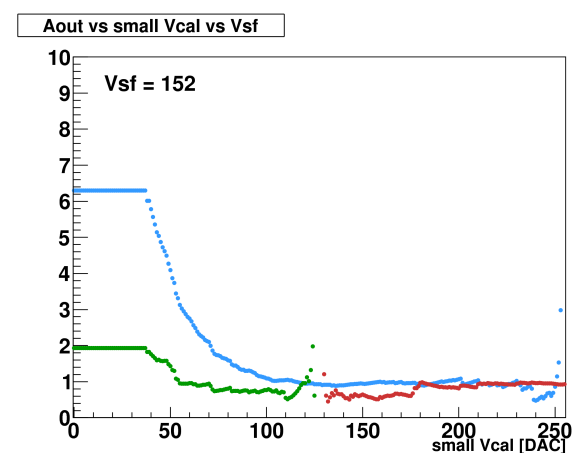
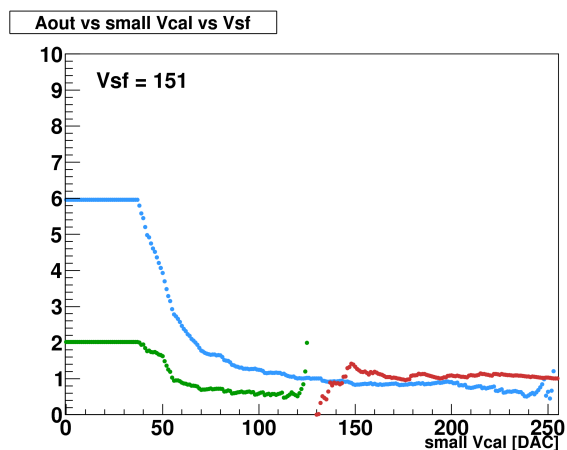
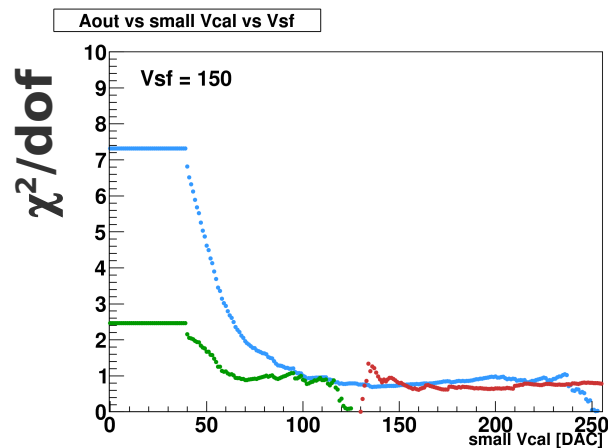


Aout vs small Vcal vs Vsf



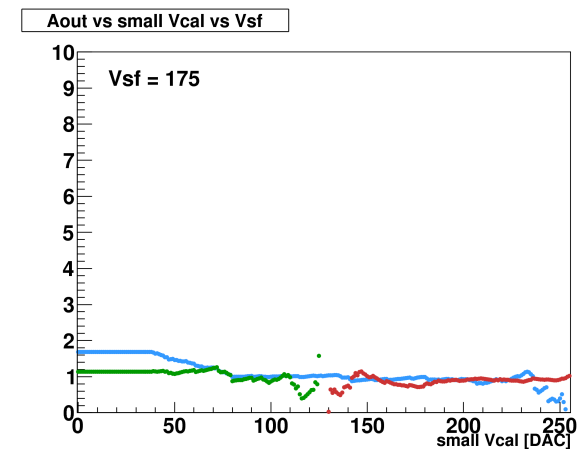
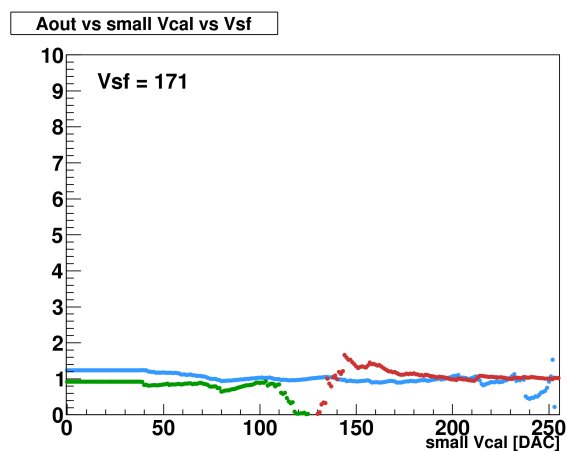
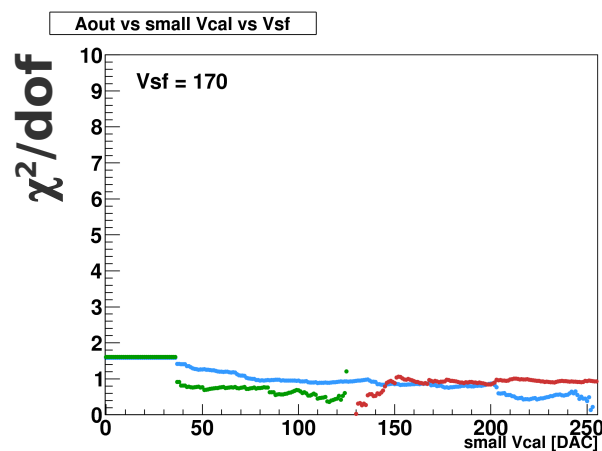
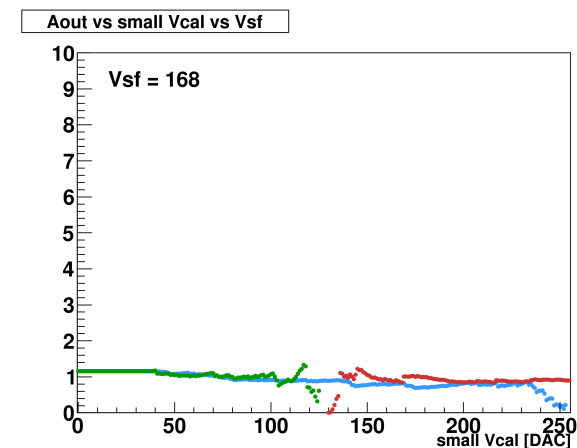
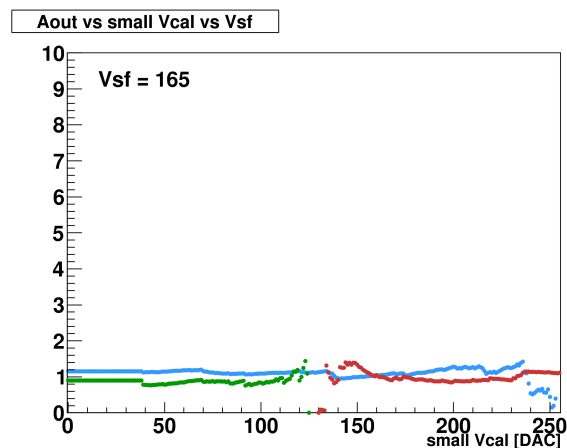
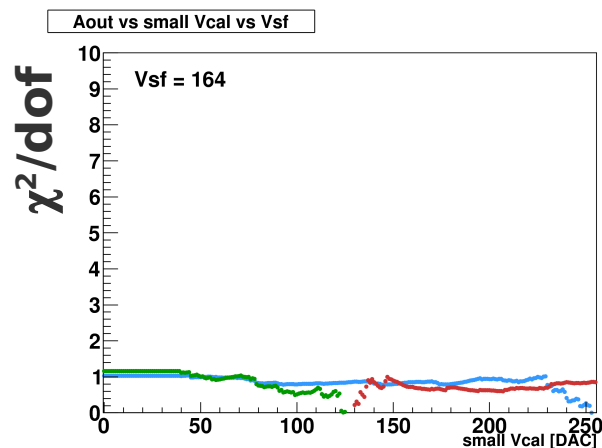
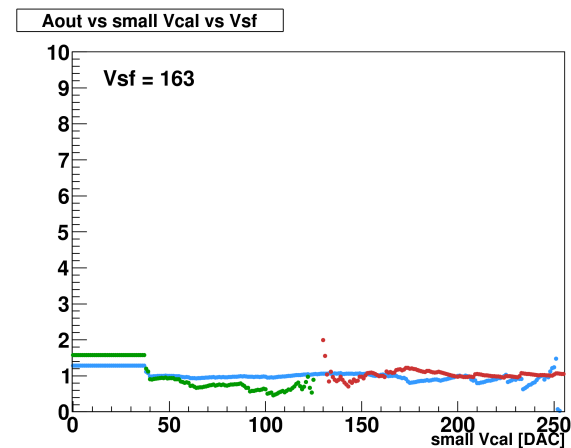
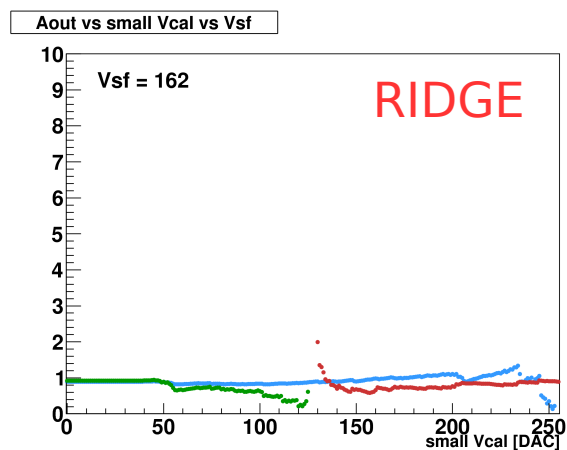
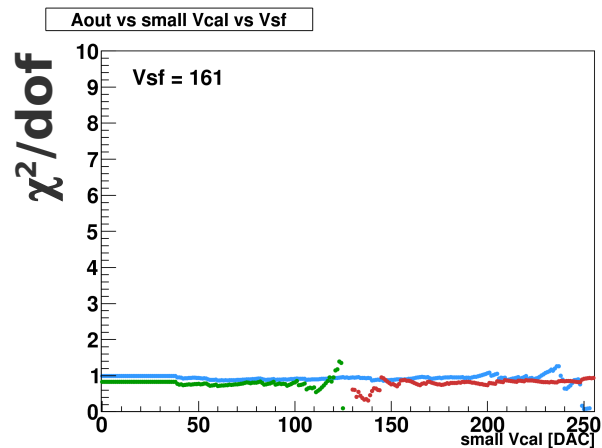
Goodness of fit (Vsf)

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



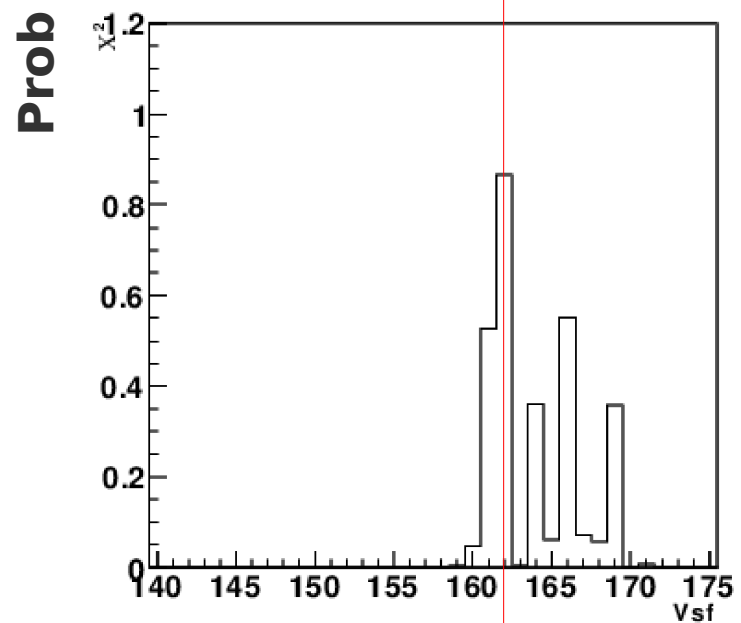
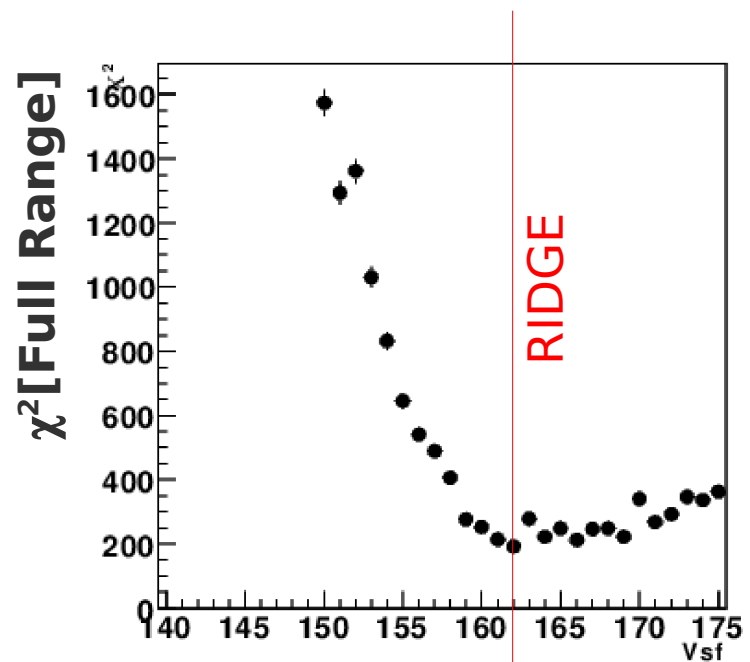
Goodness of fit (Vsf)

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



Goodness of fit (Vsf)

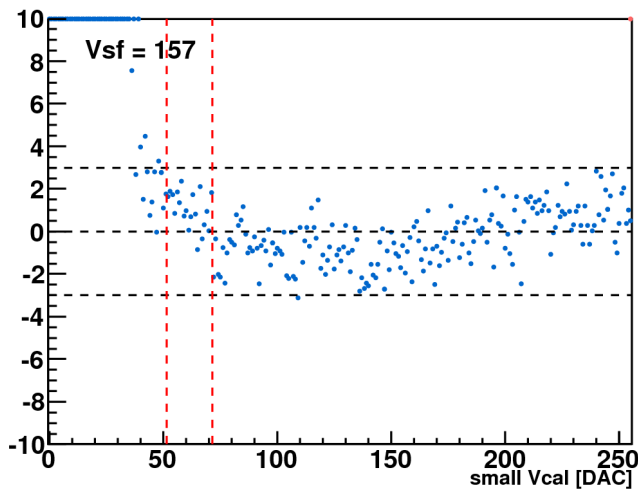
PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



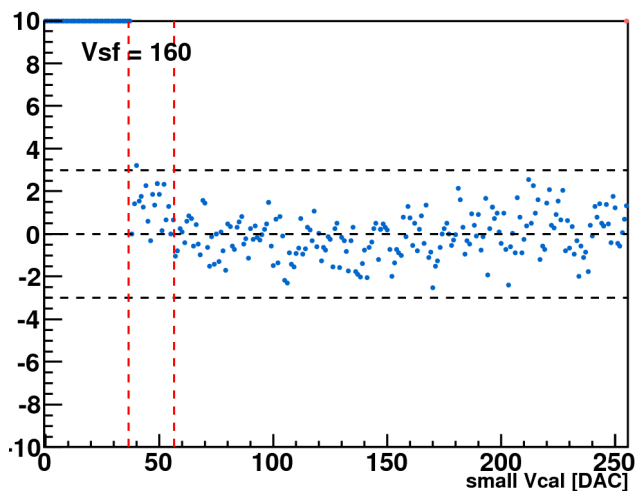
Pulls (Vcal)

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162

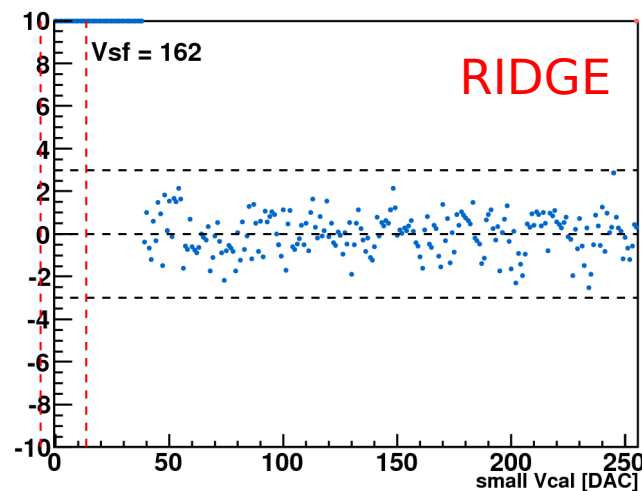
Aout vs small Vcal vs Vsf



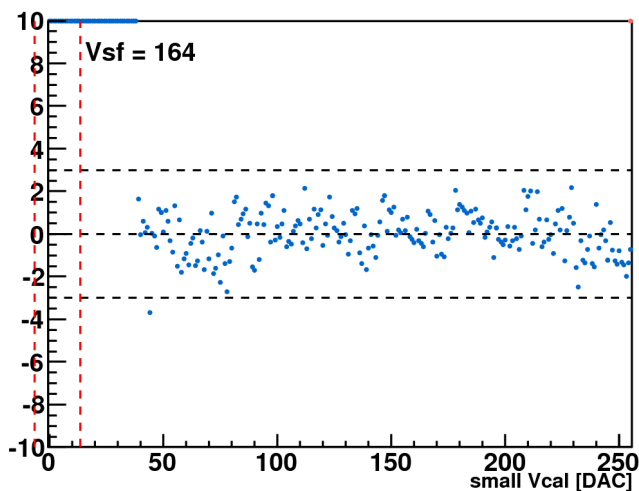
Aout vs small Vcal vs Vsf



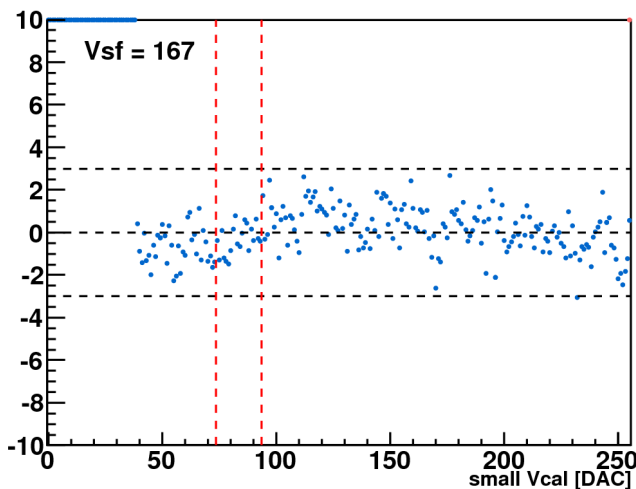
Aout vs small Vcal vs Vsf



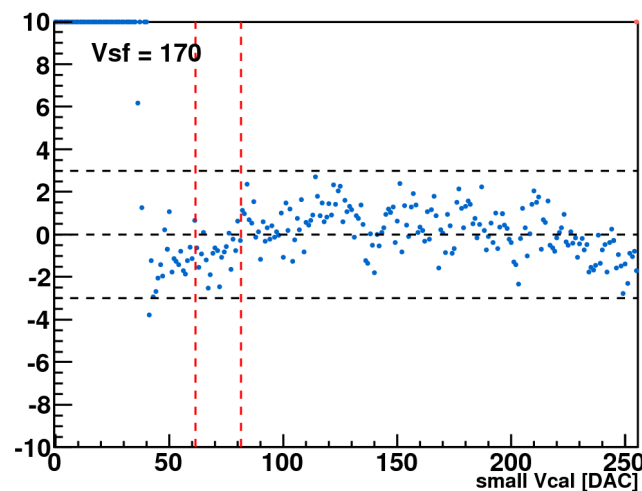
Aout vs small Vcal vs Vsf



Aout vs small Vcal vs Vsf

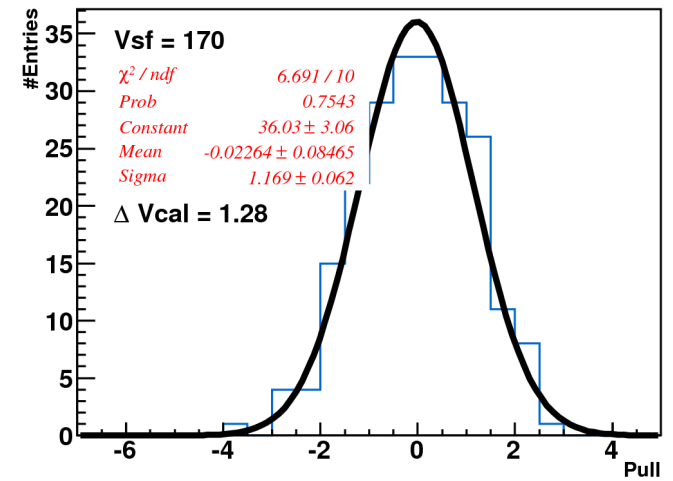
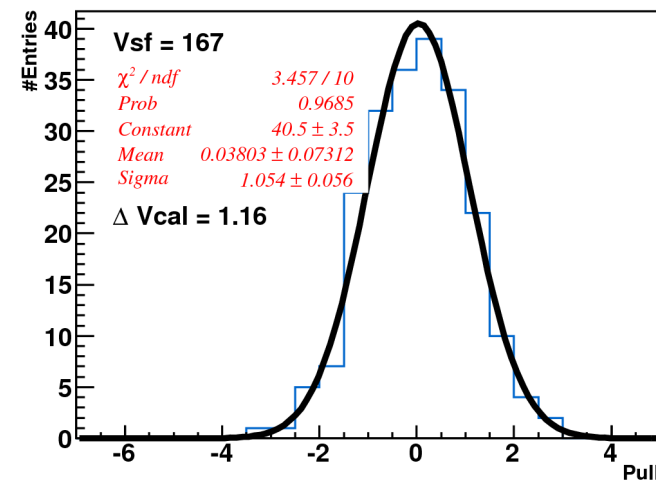
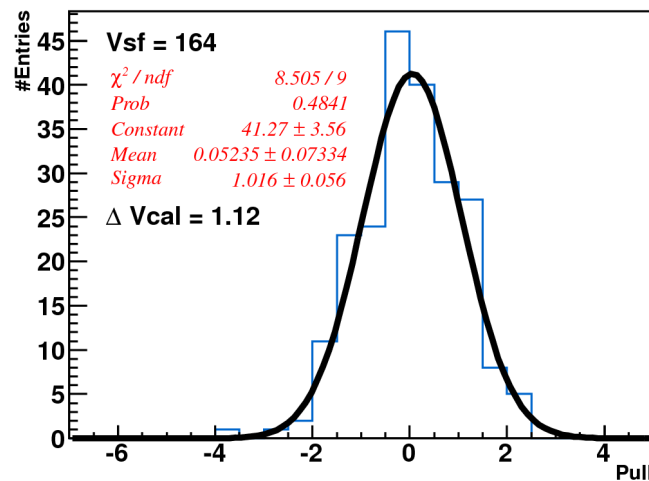
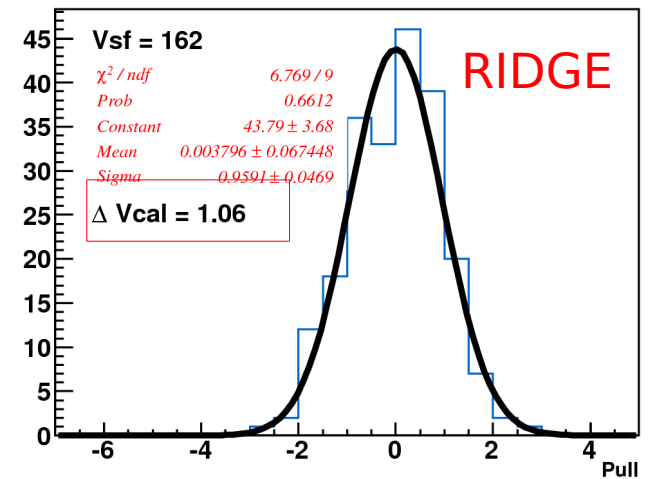
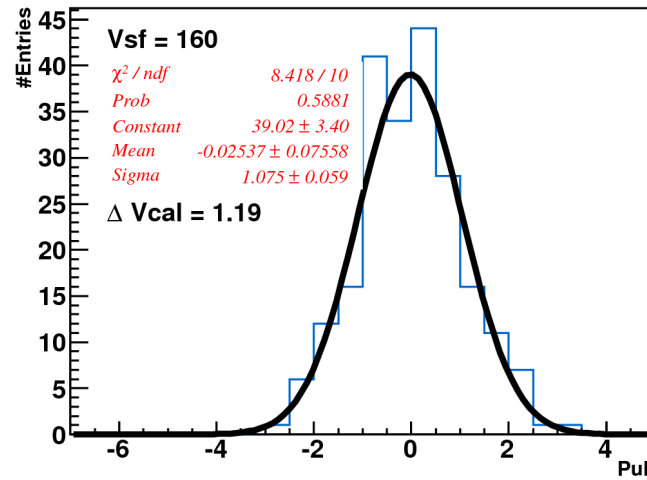
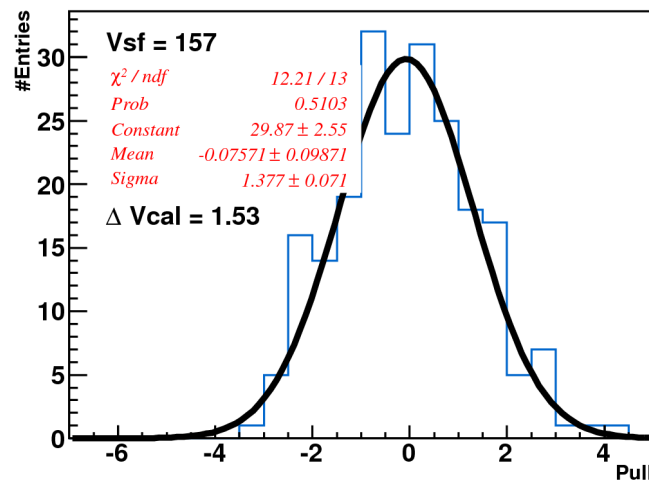


Aout vs small Vcal vs Vsf



Pull Distribution & Noise

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



Width of Pull = 0.96

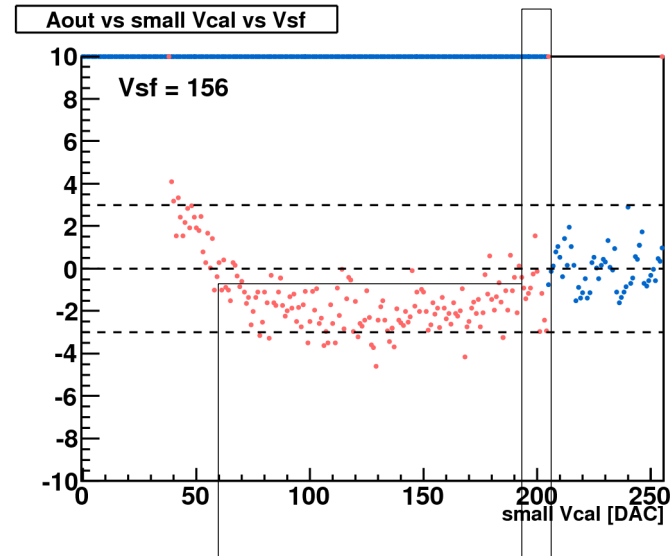
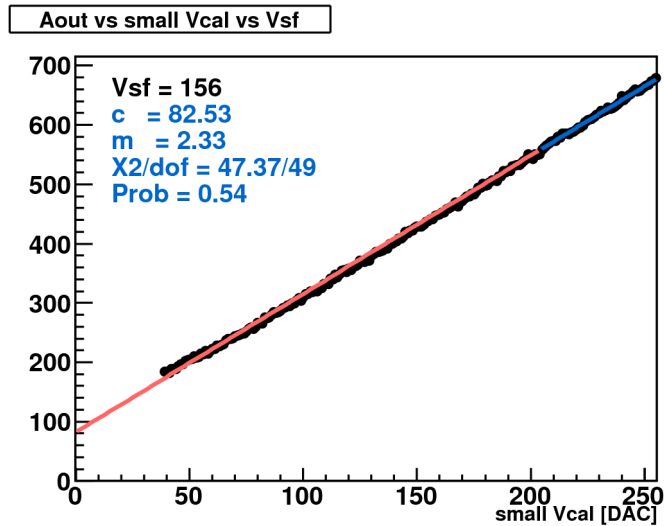
$\Delta \text{Aout} = 2.6$

Noise = Width of Pull * ΔAout = 2.496

$\Delta \text{Vcal}|_{\text{noise}} = \text{Noise}/m = 2.496/2.36 = 1.06$

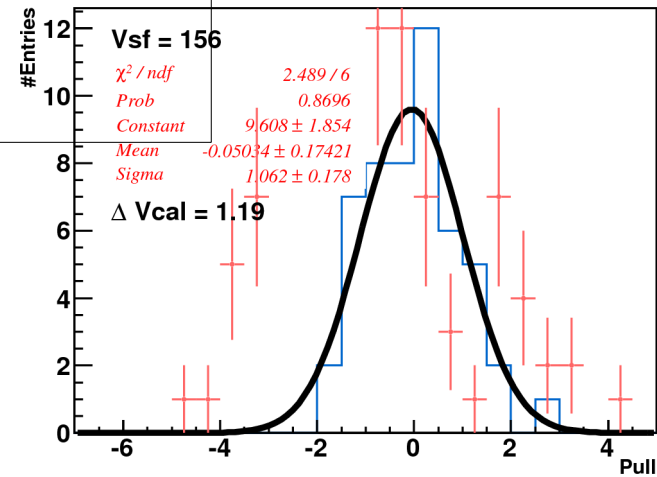
Linearity Range

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



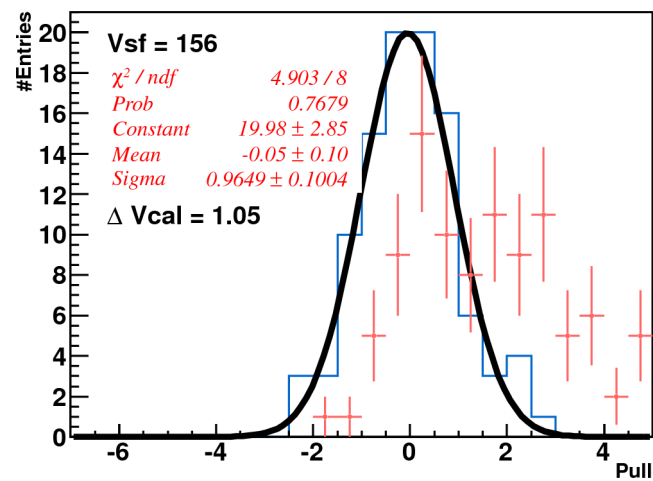
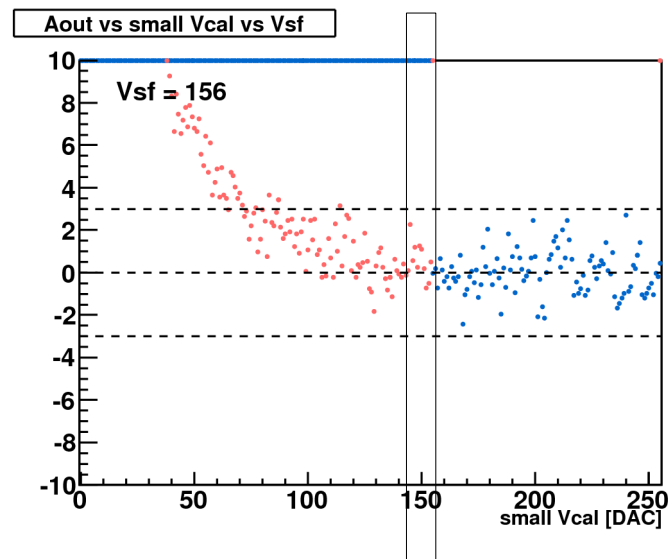
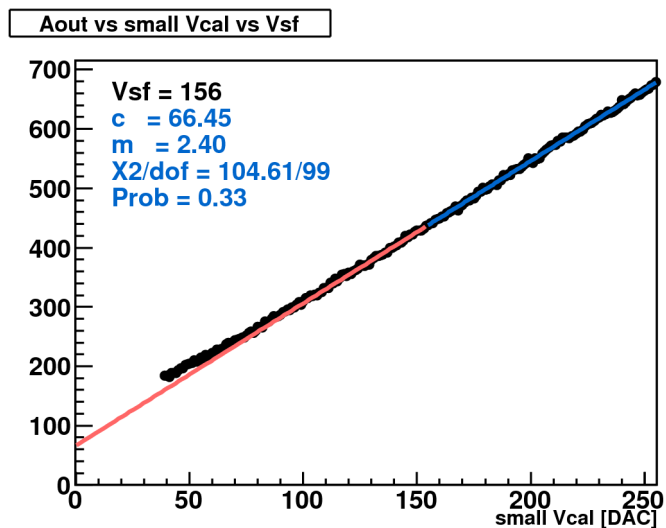
Check if next **15 entries**
 have all the same sign

$$\text{Prob} = 1/2^{15} = 1/32000$$



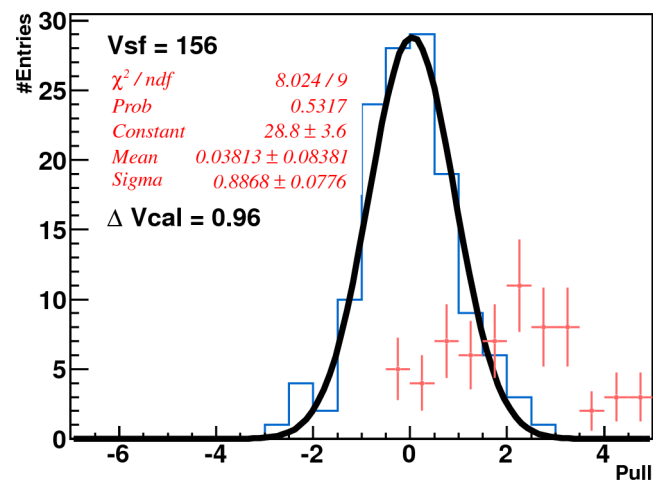
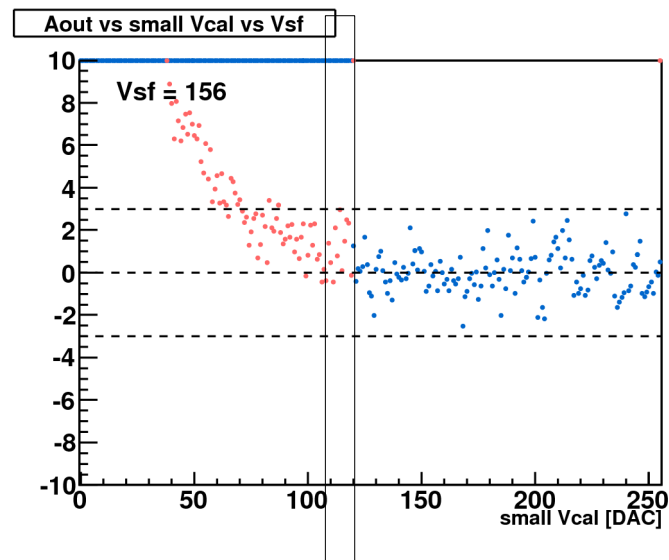
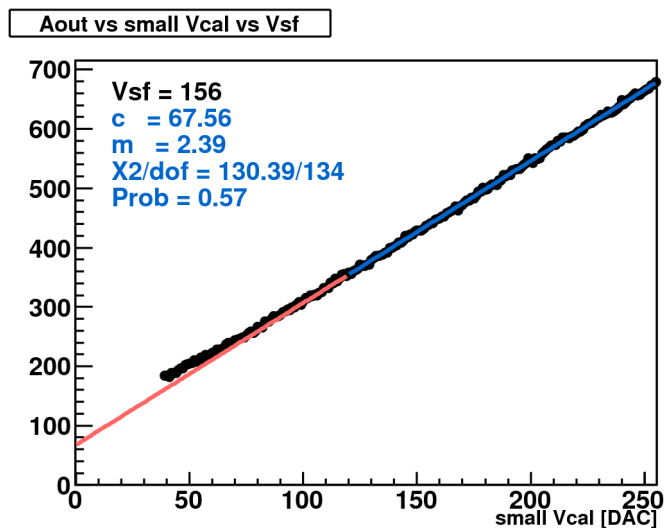
Linearity Range

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



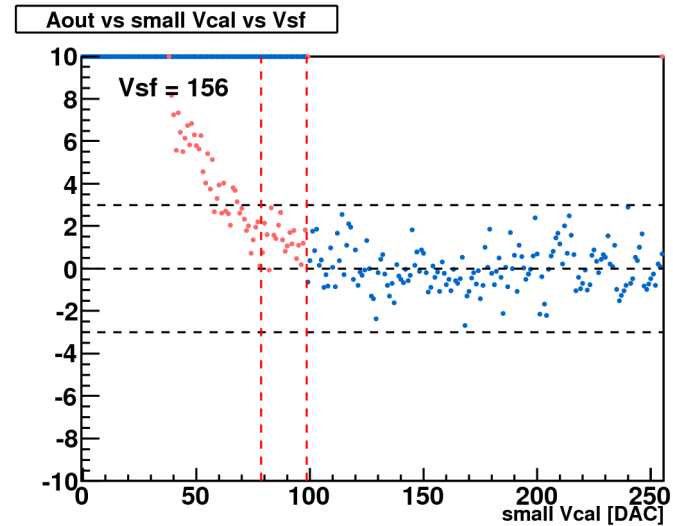
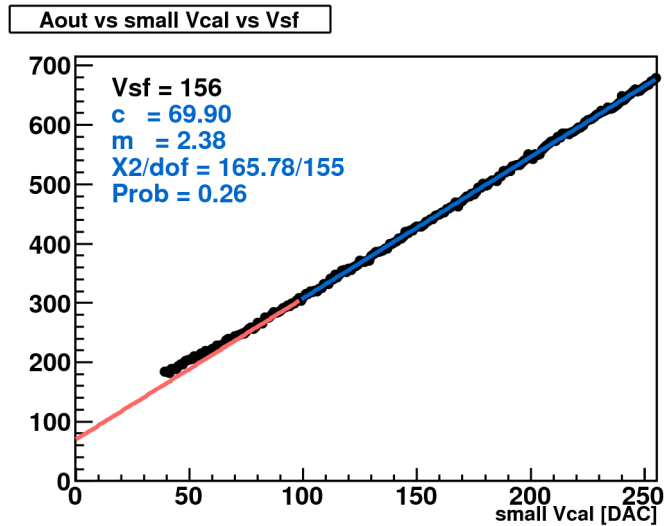
Linearity Range

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



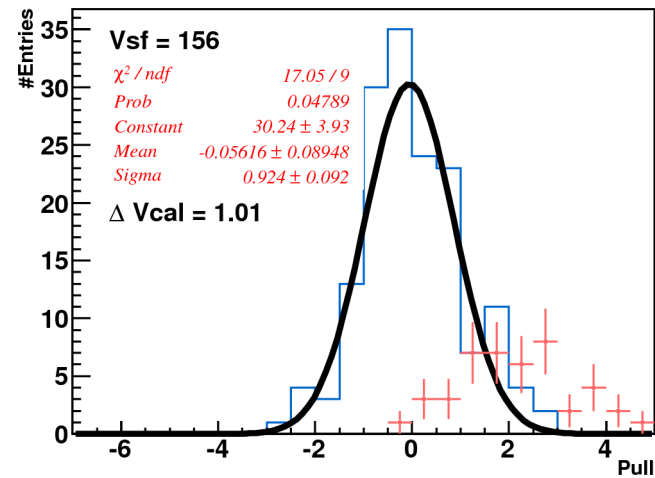
Linearity Range

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



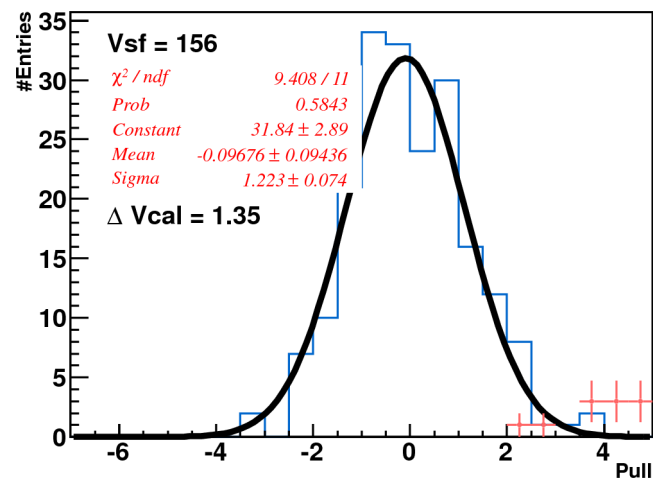
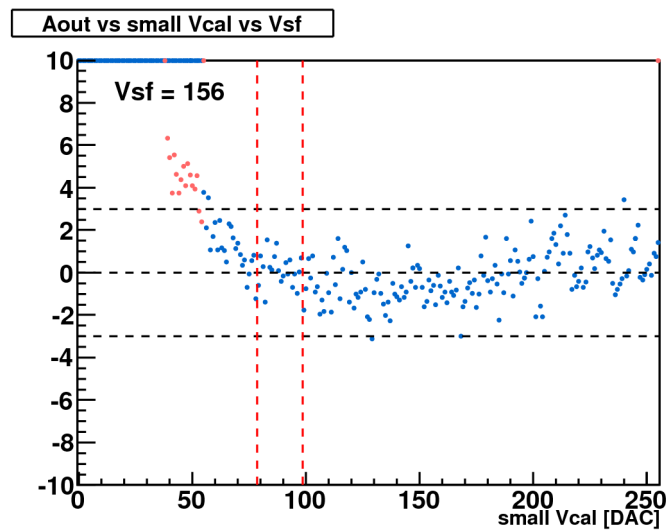
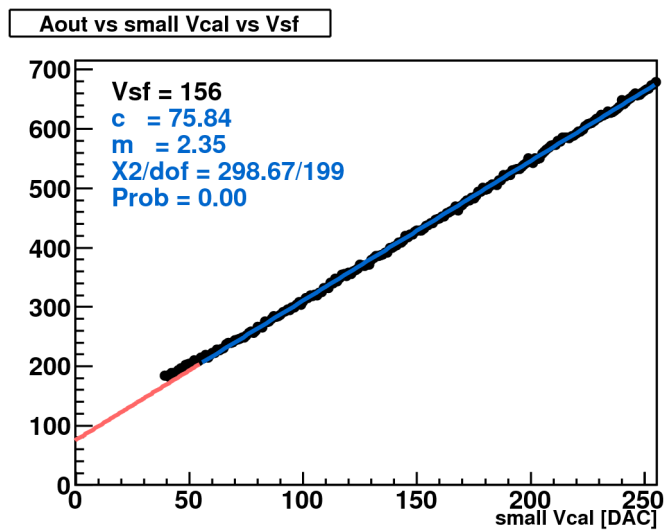
Linearity range found.

Number of good bins (NGB)
= 157



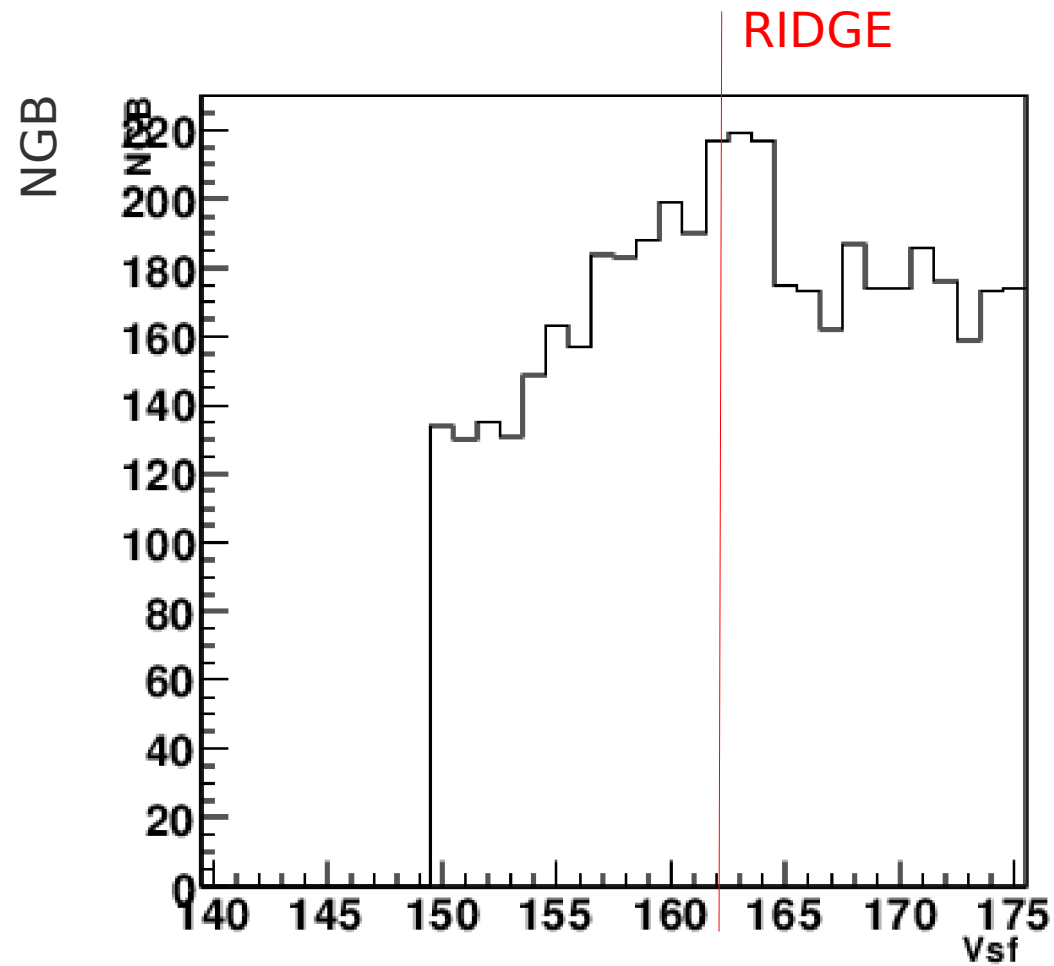
Linearity Range

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



Linearity Range

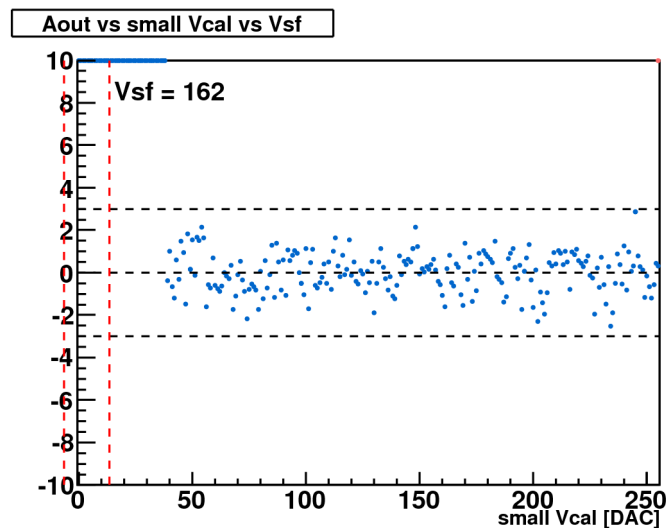
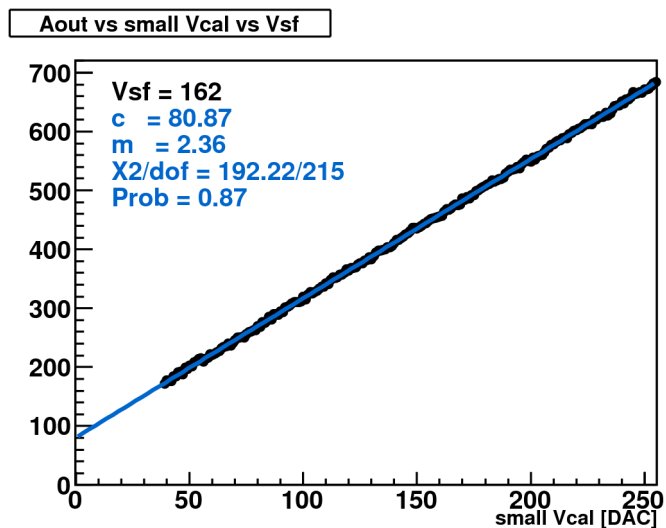
PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



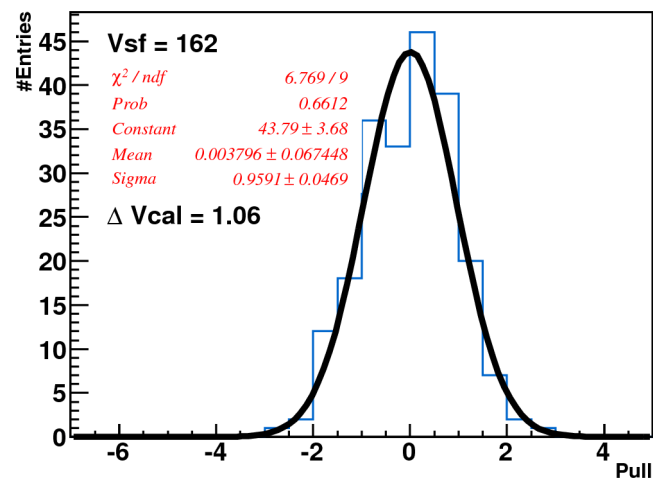
Full range of linearity near ridge. Decreases on either side.

Linearity Range

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162

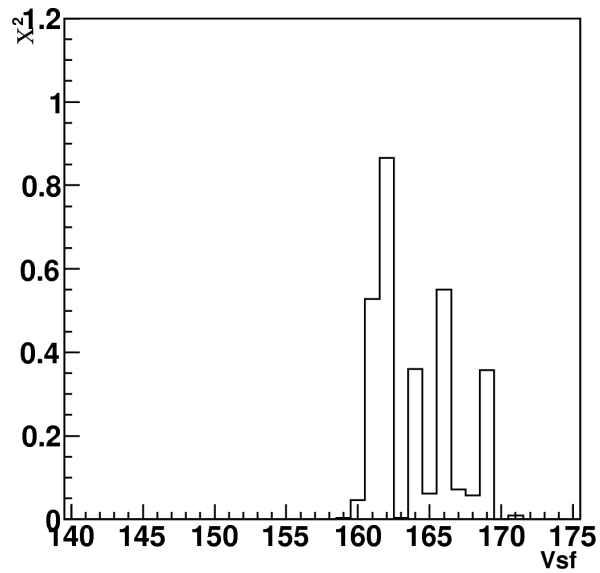
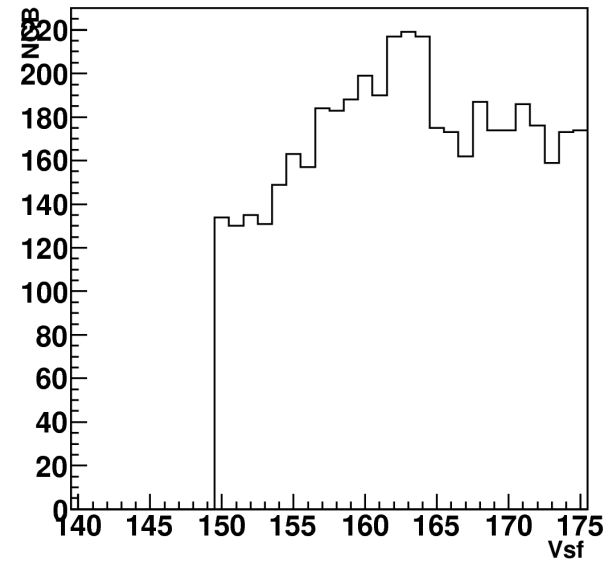
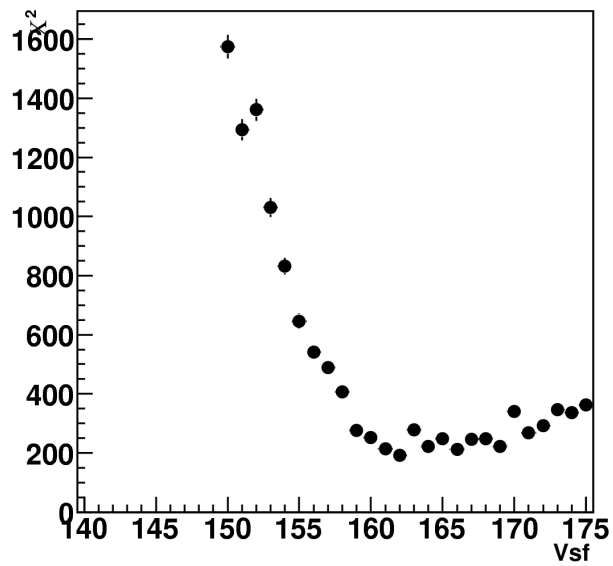


RIDGE



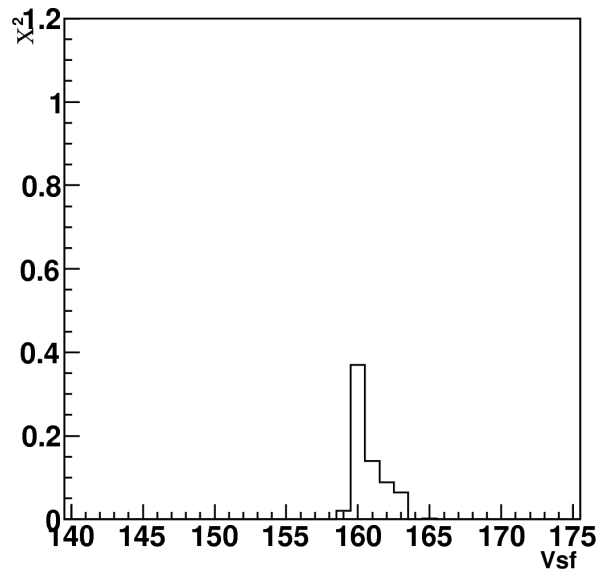
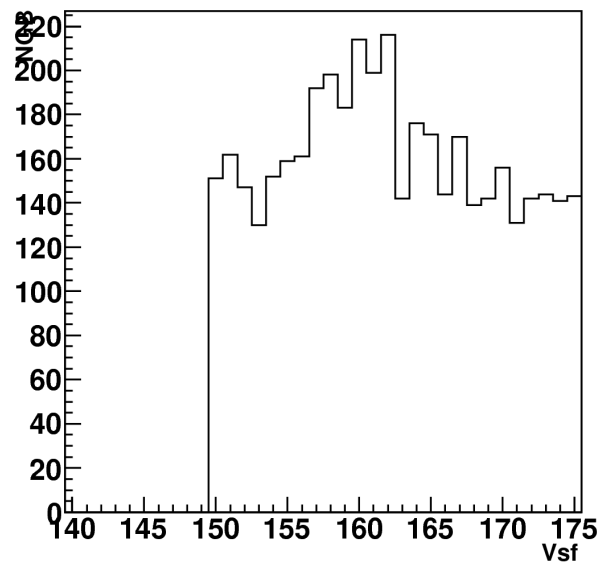
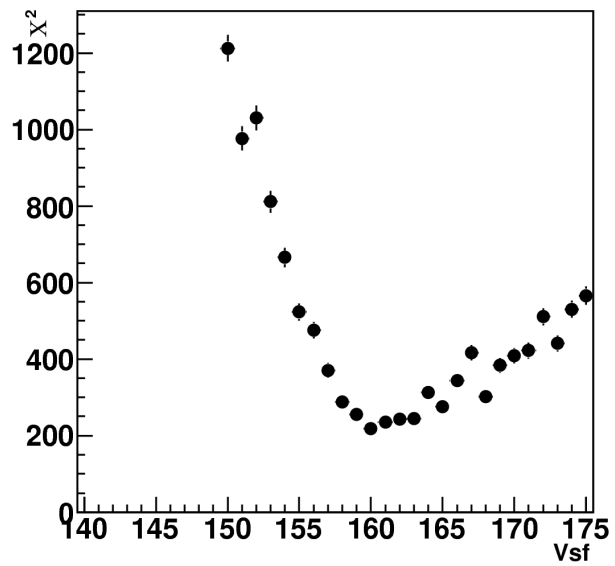
Linearity Range

PIXEL: COL = 0 , ROW = 40 , RIDGE = 162



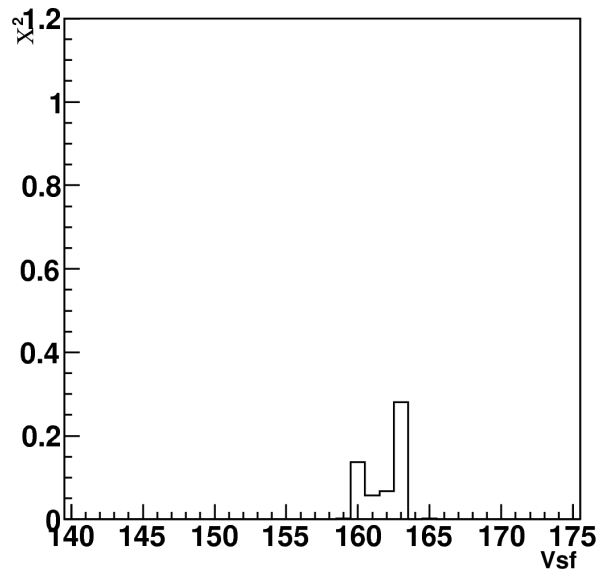
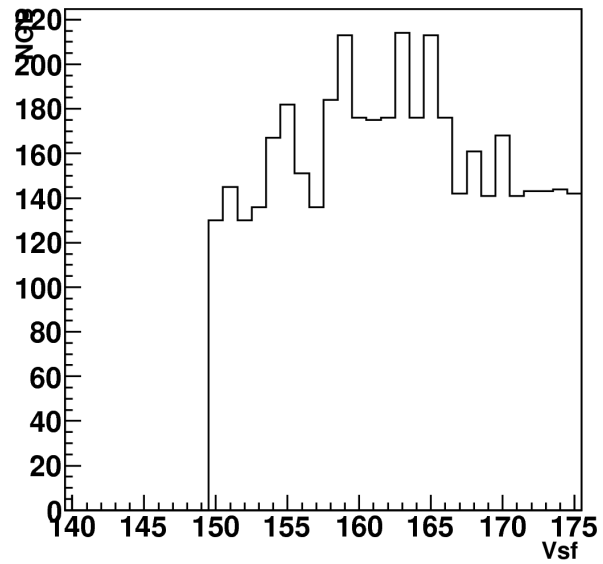
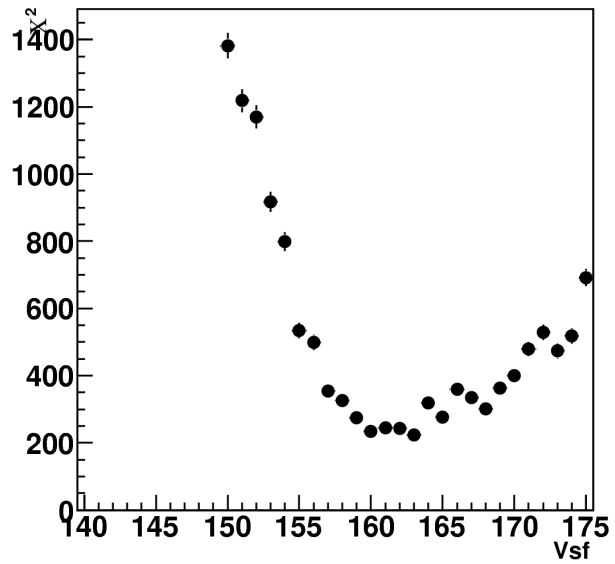
Linearity Range

PIXEL: COL = 40 , ROW = 40 , RIDGE = 162



Linearity Range

PIXEL: COL = 25 , ROW = 56 , RIDGE = 165



Conclusions:

Linearity [Chi2 and Linear Range] is best
At the ridge.

Expect uncorrelated error of 1 unit in
Small V_{cal} due to noise.