

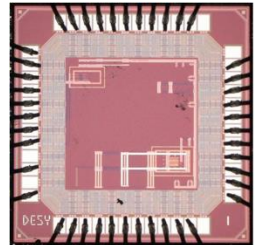
# Summer program presentation

## Detector charge calibration of the DESY CHIP V2

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DESY Summer program 2025

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# OVERVIEW

## 1. Motivation

Tangerine R&D

MAPS vs. Hybrid detectors

## 2. MAPS R&D

## 3. The DESY Chip V2

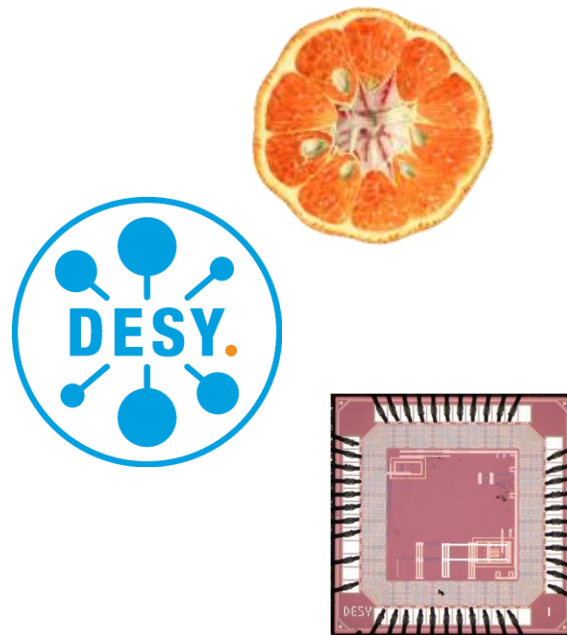
## 4. LAB measurements

## 5. Data analysis

Layout comparison

Charge calibration

## 6. Summary and next steps



# MOTIVATION – Tangerine R&D

The demand for performance and precision in HEP has driven **R&D**.

Requirements of next-generation lepton collider experiments:

- ✓ **Material budget**:  $< 0.05\% X/X_0$
- ✓ **Single-point resolution**:  $\sim 3\mu\text{m}$
- ✓ **Time resolution**:  $\sim 1\text{-}10\text{ ns}$
- ✓ **Rate capabilities**: 1 MHz particle rate
- ✓ **Granularity**:  $< 25\text{ }\mu\text{m} \times 25\text{ }\mu\text{m}$



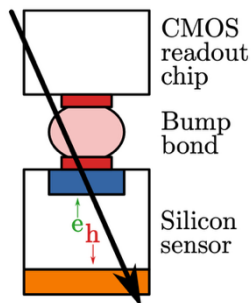
The **Tangerine project** (**TowArds Next GEneration SilicoN DEtectors**) began in 2020 to develop detectors for next generation lepton colliders.

- Development of **MAPS** (monolithic active pixel detectors) in a **65 nm CMOS** (Complementary Metal-Oxide-Semiconductor) Imaging technology.

# MOTIVATION – MAPS vs. Hybrid detectors

## Hybrid detectors

Sensor and readout electronics produced separately and connected using **bump bonding**.

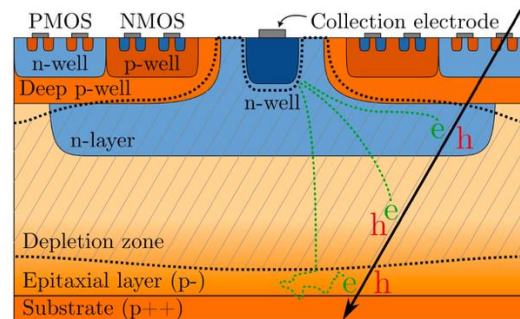


— Pixel sizes are constrained by the bump bonding pitch.

## MAPS

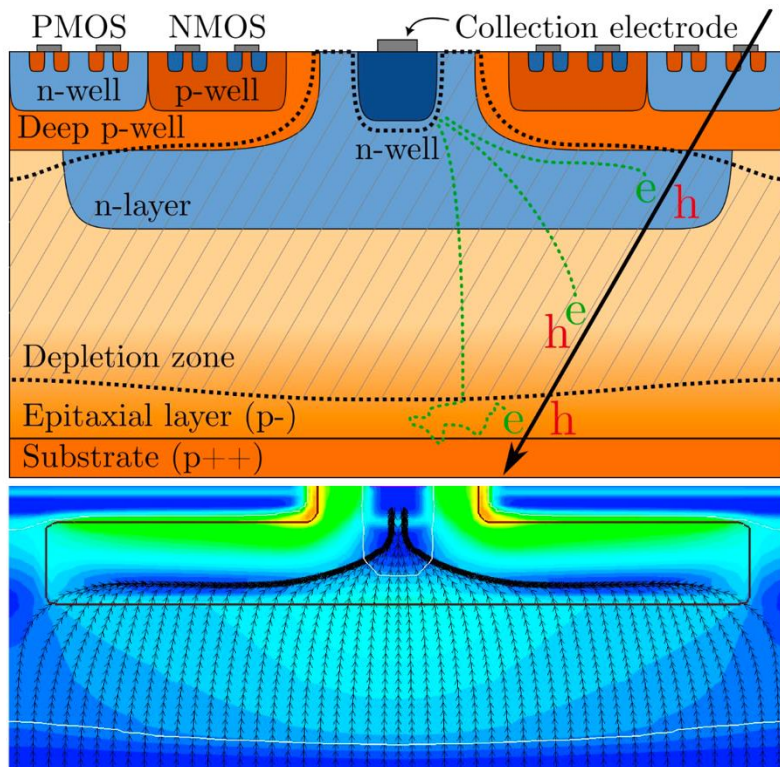
Sensing element and the readout circuitry **integrated in a single silicon layer**.

✓ Lighter, thinner, and capable of higher granularity.



*Monolithic pixel sensor profile, DESY Chip V2, J. Dilg Master's Thesis*

# MAPS R&D



- Adding an **n-layer** extends the depletion zone to the pixel edges.
- Introducing a **gap** in the n-layer increases the lateral electric field near the edges, leading to a **faster response**.

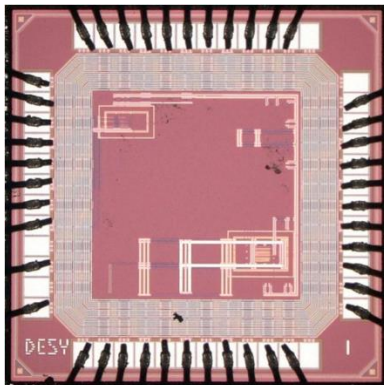
When a particle passes through the detector, it causes **ionization**, generating **free electron-hole pairs**.

**Drift** under the influence of an electric field established by an external voltage.

Detection as **electrical signal** in the **collection electrodes**.

*Monolithic pixel sensor profile, DESY Chip V2 and Electric field simulation (generic doping profile, electronics not included), J. Dilg Master's thesis*

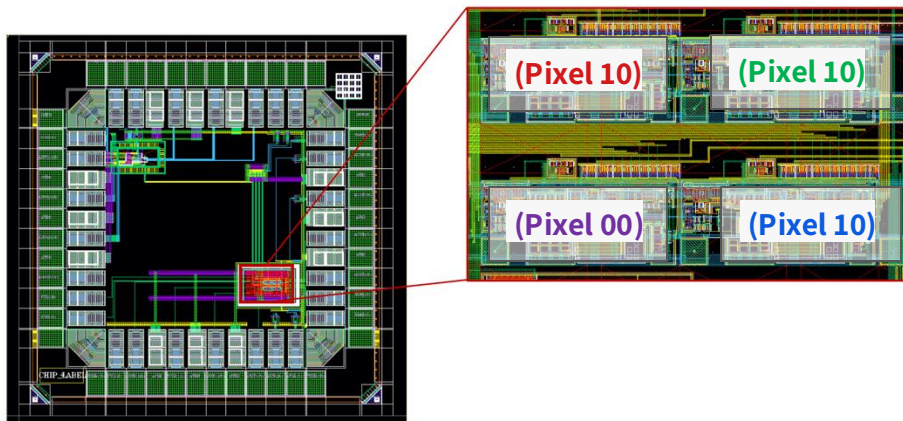
# DESYPHY CHIP V2



## DESYPHY CHIP V2 OR DESYPHY ER1

- Designed at DESYPHY
- $2 \times 2$  pixel matrix
- $35 \times 25 \mu\text{m}^2$  pitch
- In-pixel amplifier and analog output

## Pixel Arrangement

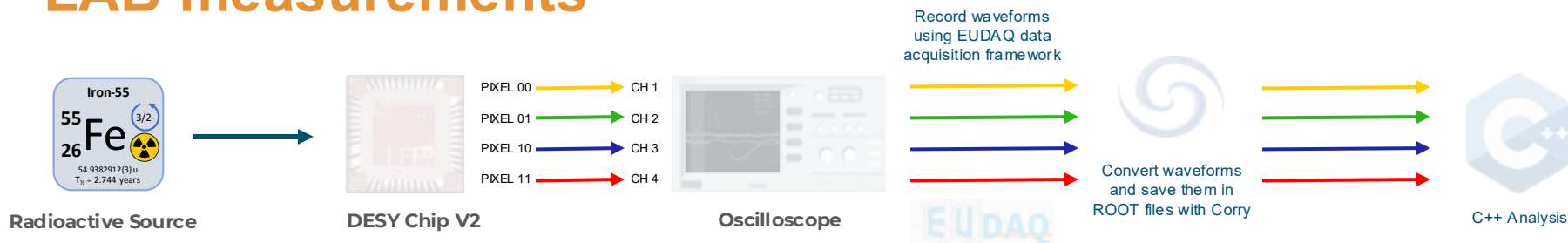


Study the performance of two n-gap layouts with different n-gap sizes:

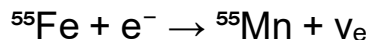
- $4 \mu\text{m}$
- $2.5 \mu\text{m}$

A **larger n-gap** enhances the **lateral electric field near the pixel edges**, which leads to a **faster response**.

# LAB measurements

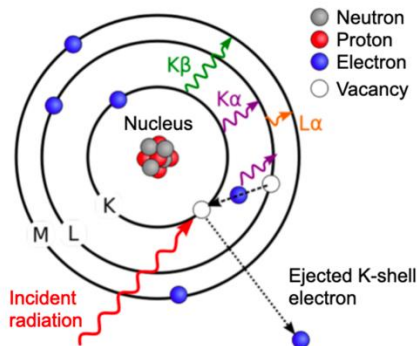


$^{55}\text{Fe}$  decays by electron capture of an inner-shell electron (usually K shell):

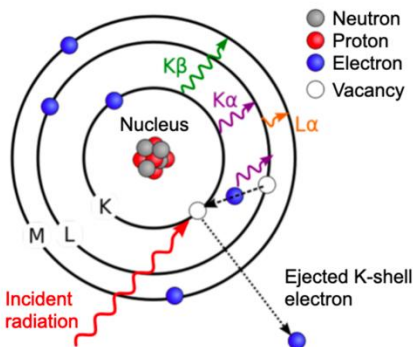


Vacancy in the K shell filled by other  $e^-$  releasing energy:

- **X-ray emission:** a photon is emitted.
- **Auger electron emission:** the energy is transferred to another electron, which gets ejected from the atom.



# LAB measurements



The emission lines of **X-rays** are used for calibration, knowing that the energy required to **create an electron-hole pair in silicon is 3.66 eV**, via the **photoelectric effect**.

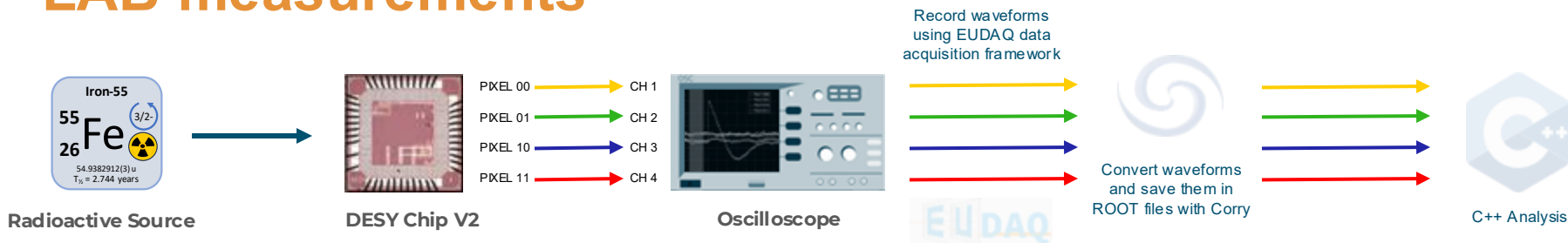
- **$K_\alpha$  lines:** transitions from L  $\rightarrow$  K shell
  - $K_{\alpha 1} = 5.89875 \text{ keV}$  (16.2%)
  - $K_{\alpha 2} = 5.88765 \text{ keV}$  (8.2%)
  - As a single  **$K_\alpha$  5.895 keV X-ray  $\sim$  1617 eh-pairs (25 %).**

- **$K_\beta$  line:** transition from M  $\rightarrow$  K shell
  - **6.491 keV  $\sim$  1778 eh-pairs (2.85%)**

Auger electrons:  $\sim 5.19 \text{ keV}$  (60.1%) – not detected



# LAB measurements

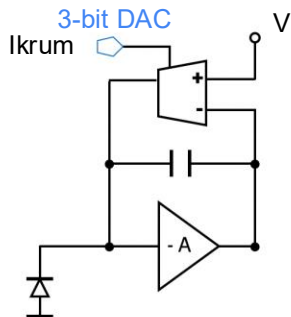


**CSA** (charge sensitive amplifier) converts induced current into a **voltage signal**

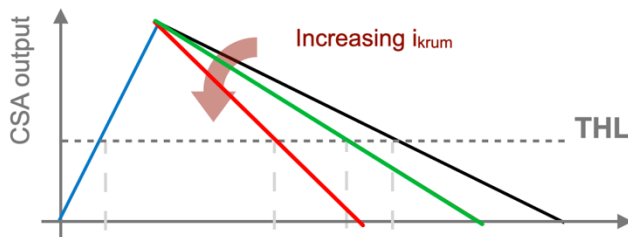


Signal is processed and recorded with the **oscilloscope**.

## In-pixel frontend:

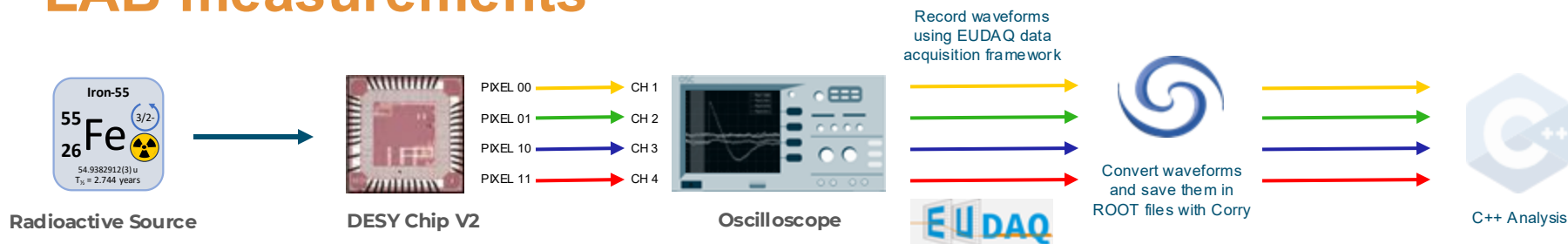


The **Krummenacher current** (**ikrum**) returns the CSA output to baseline after each hit.



The strength of the **ikrum** can be tuned individually for each pixel through a **3 bit DAC**.

# LAB measurements



The signal is processed and recorded with the **oscilloscope**. → Digitalized with **Corryvreckan**.

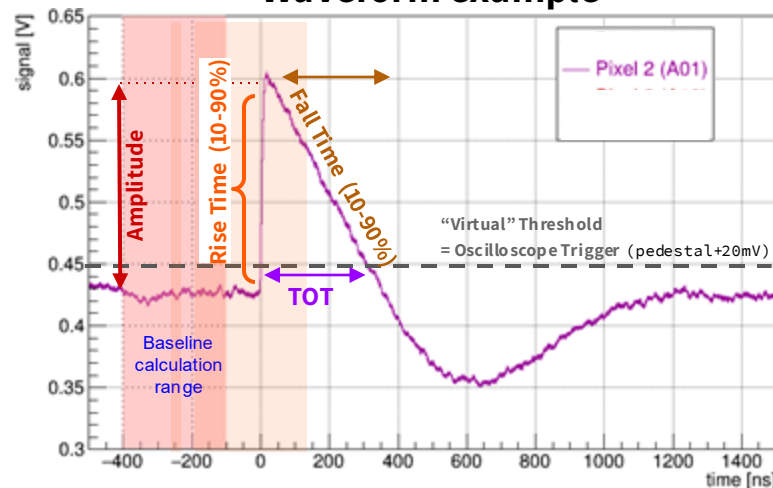
Measurable quantities:

- ▶ Pedestal (Baseline)
- ▶ Amplitude
- ▶ Time over Threshold (scope thr.)
- ▶ Rise Time (10-90%)
- ▶ Fall Time (10-90%)
- ▶ RMS of the noise

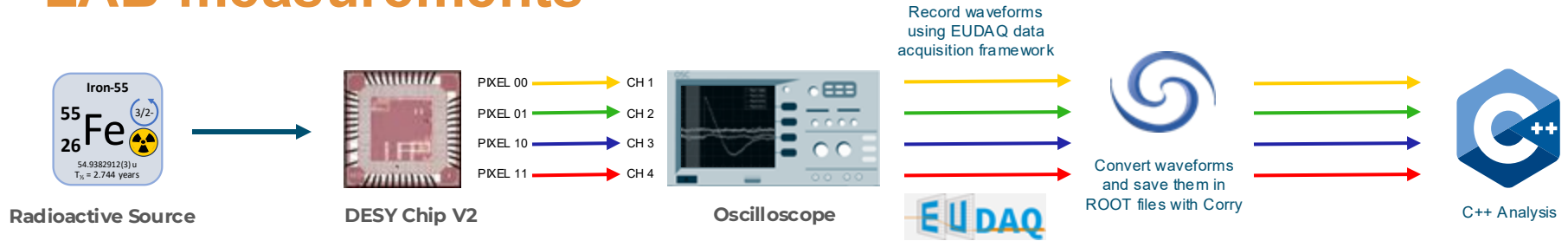
The amplitude is calculated as the maximum of the waveform minus the baseline.

The **amplitude** of the pulse is directly **proportional to the collected charge**.

## Waveform example



# LAB measurements



## → Data analysis in C++

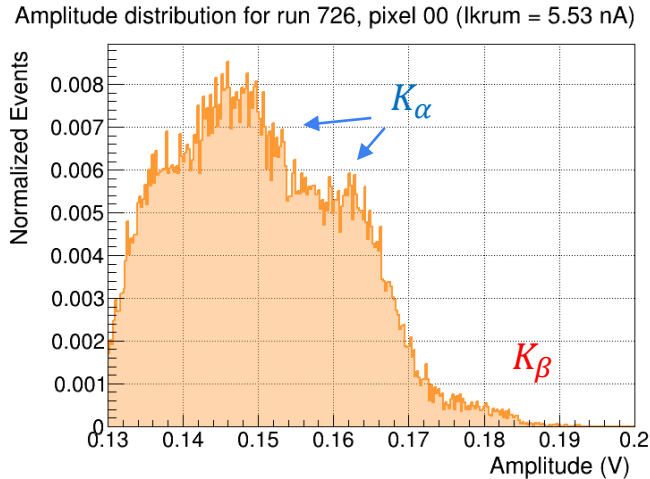
- Calculate the **4  $\mu\text{m}$  n-gap layout** detector **gain factor  $G$**  using a  $^{55}\text{Fe}$  source fitting  $K_\alpha$  and  $K_\beta$  peaks with the calibration constrained such that 0 V corresponds to 0 electron-hole pairs.
- **Compare the performance** of the two **n-gap layouts (2.5  $\mu\text{m}$  and 4  $\mu\text{m}$ )** to evaluate the impact of gap size on detector response.

$$G = \frac{\text{waveform amplitude (V)}}{\text{number of deposited charges (e)}}$$

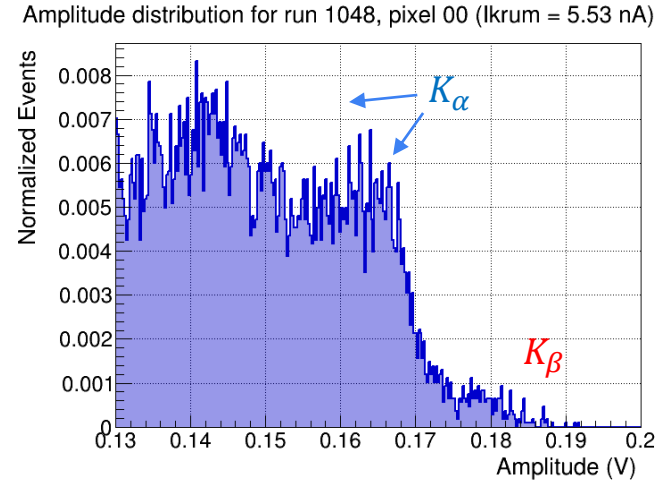
# ANALYSIS – Layout comparison

Peaks of the spectrum of  $^{55}\text{Fe}$  for 4  $\mu\text{m}$  and 2.5  $\mu\text{m}$ .

4  $\mu\text{m}$



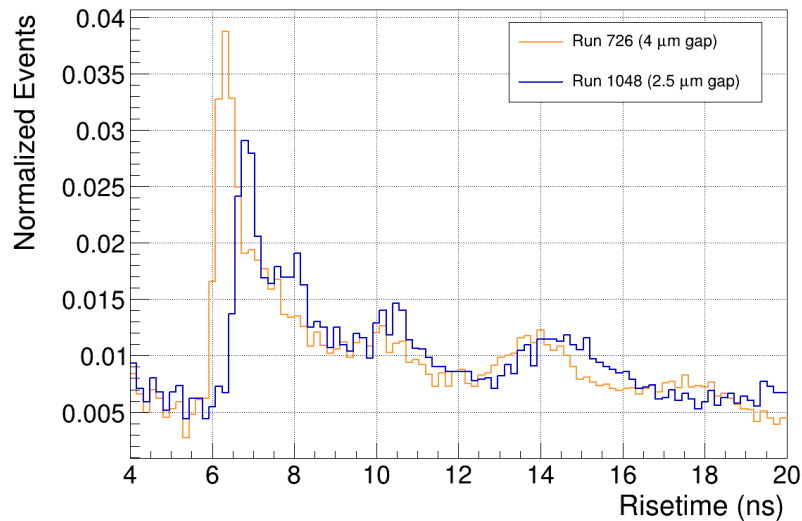
2.5  $\mu\text{m}$



- The  $K_\alpha$  peak appears doubled due to the rectangular geometry of the detector, which causes a non-uniform detector response.
- The  $K_\beta$  peak is comparatively very small (2.85%)

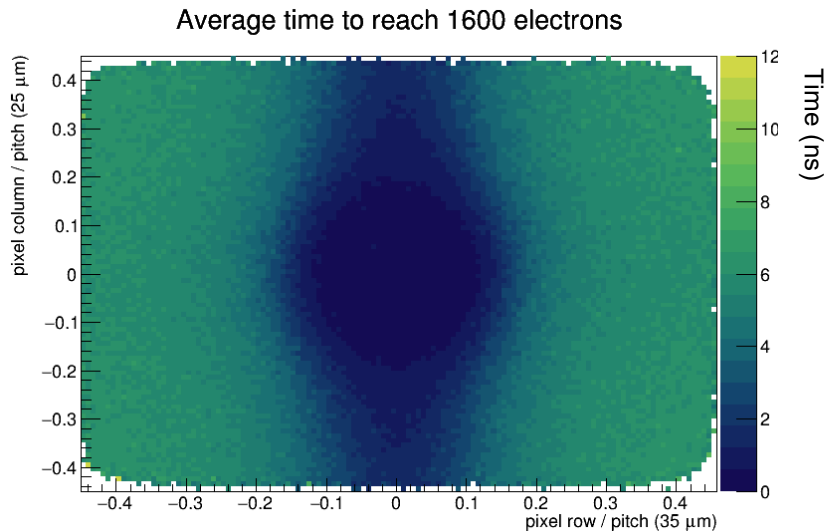
# ANALYSIS – Layout comparison

Risetime distributions for runs 726 and 1048  
Pixel 00 (I<sub>krum</sub> = 5.53 nA)



- Faster response for the **4 μm** n-gap

- Rectangular geometry of the pixels causes a non-uniform charge collection



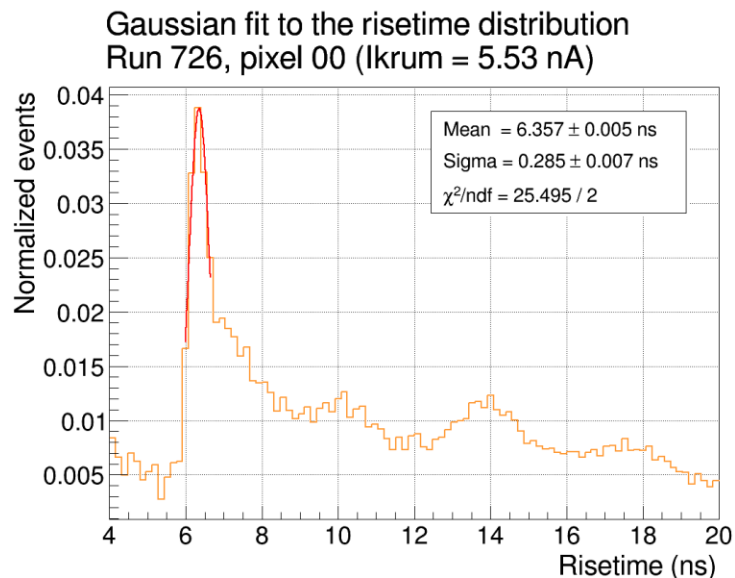
*Simulation by Håkan Wennlöf, 2024*

Solution: **Cut based on the signal rise time** to do the calibration of the **4 μm** n-gap layout.

# ANALYSIS - Charge calibration

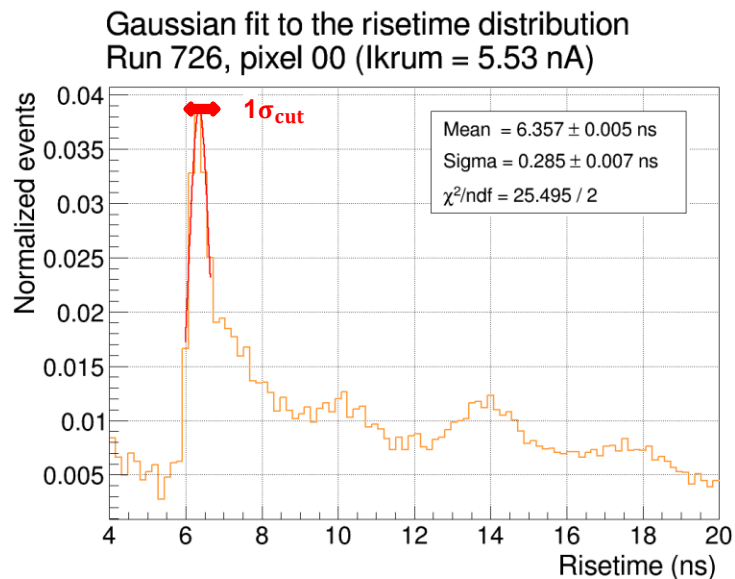
Apply a cut by selecting only the **fastest-response events**, followed by a Gaussian fit to the first peak.

Cut on the amplitude using the mean of the rise time fit  $\pm n\sigma_{\text{cut}}$

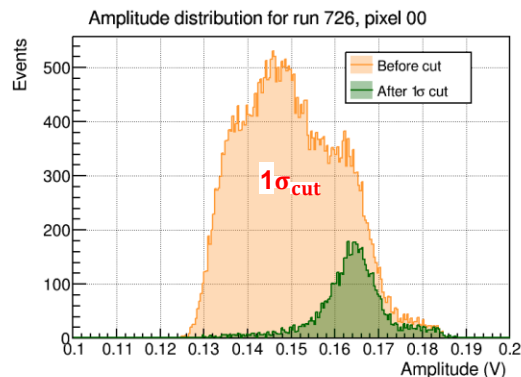


# ANALYSIS - Charge calibration

Apply a cut by selecting only the **fastest-response events**, followed by a Gaussian fit to the first peak.

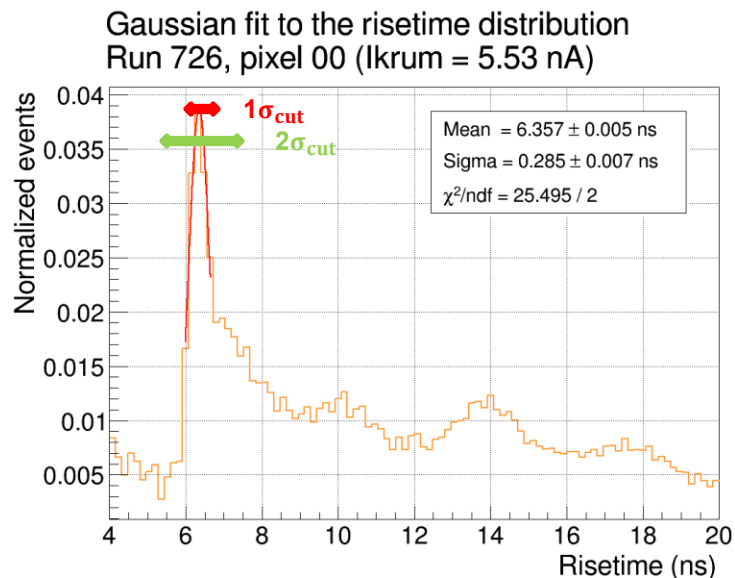


Cut on the amplitude using the mean of the rise time fit  $\pm n\sigma_{\text{cut}}$

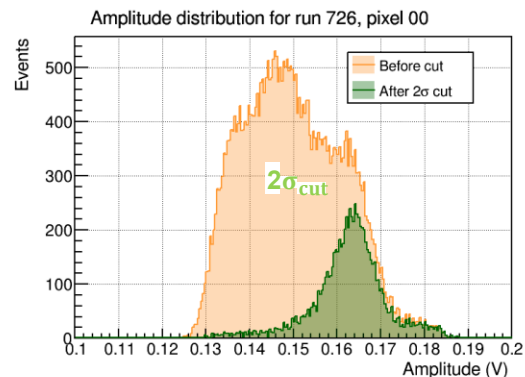
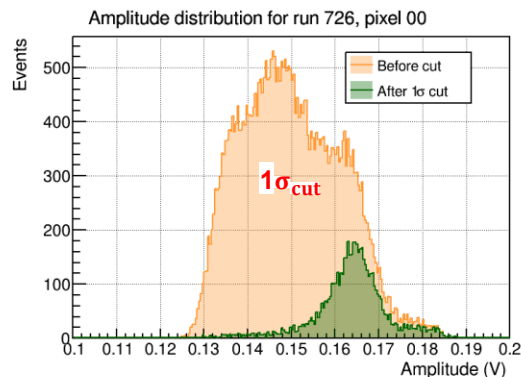


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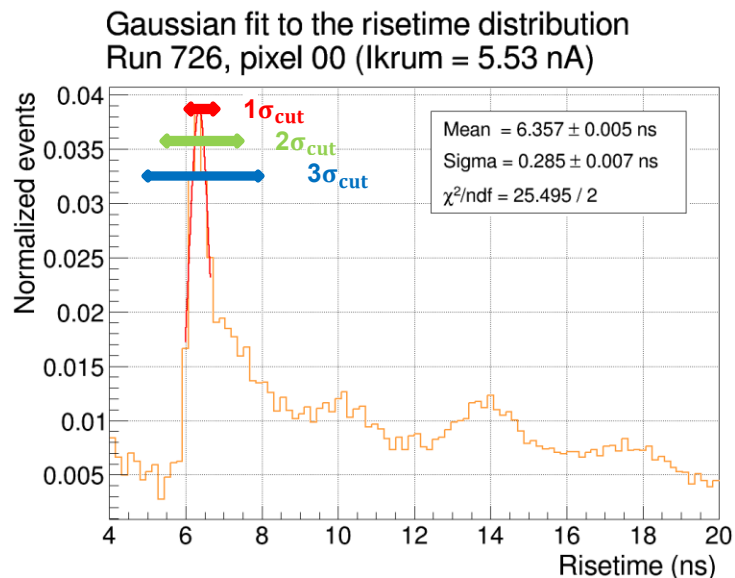
Cut on the amplitude using the mean of the rise time fit  $\pm n\sigma_{\text{cut}}$



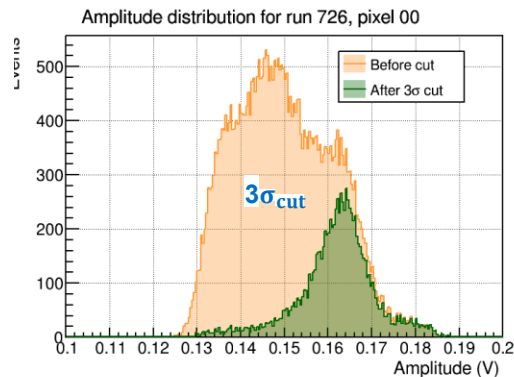
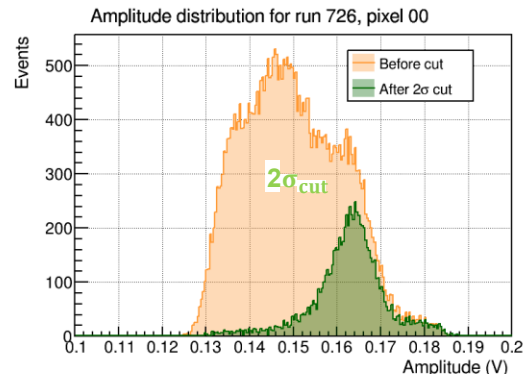
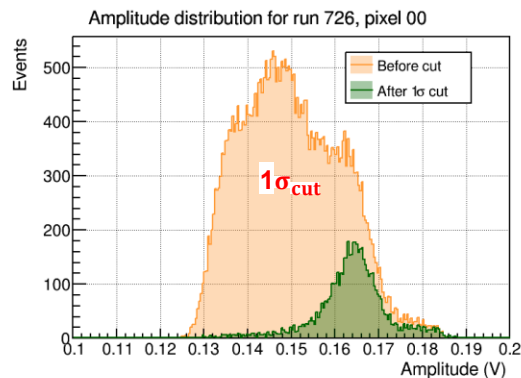


# ANALYSIS - Charge calibration

Apply a cut by selecting only the **fastest-response events**, followed by a Gaussian fit to the first peak.

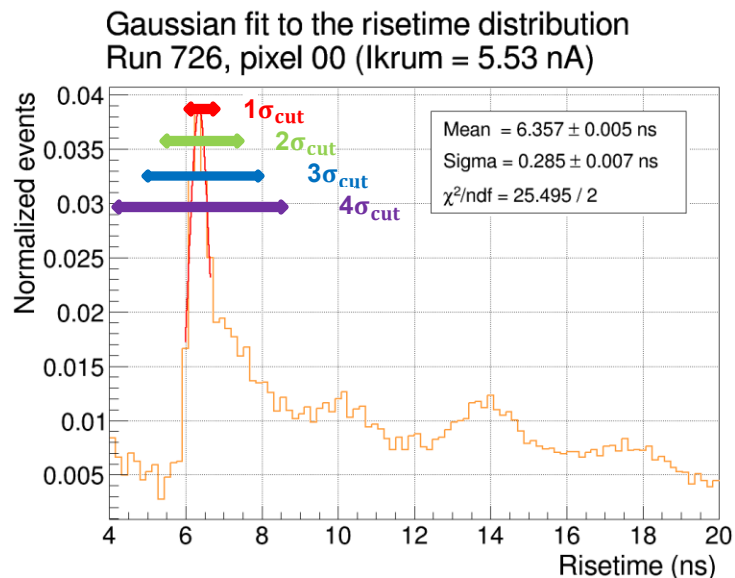


Cut on the amplitude using the mean of the rise time fit  $\pm n\sigma_{\text{cut}}$

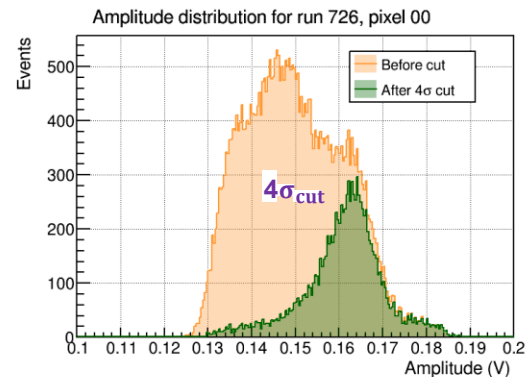
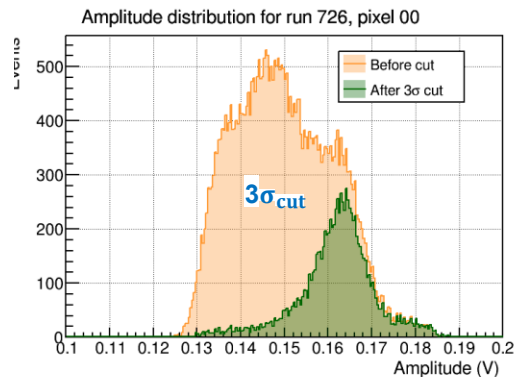
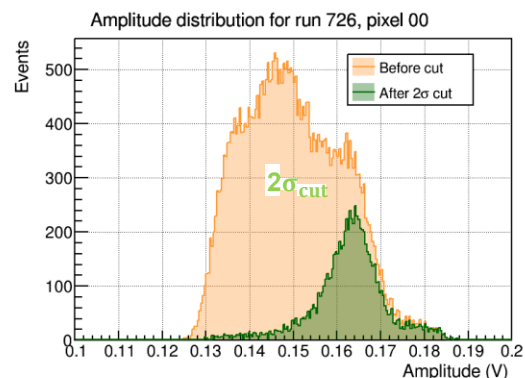
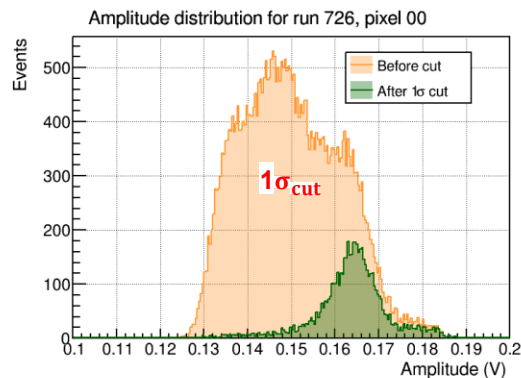


# ANALYSIS - Charge calibration

Apply a cut by selecting only the **fastest-response events**, followed by a Gaussian fit to the first peak.



Cut on the amplitude using the mean of the rise time fit  $\pm n\sigma_{\text{cut}}$

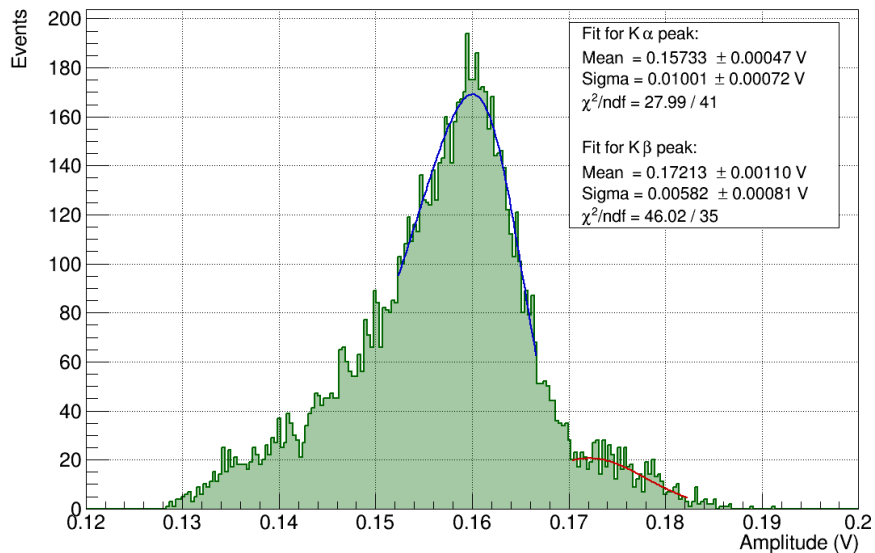


# ANALYSIS - Charge calibration

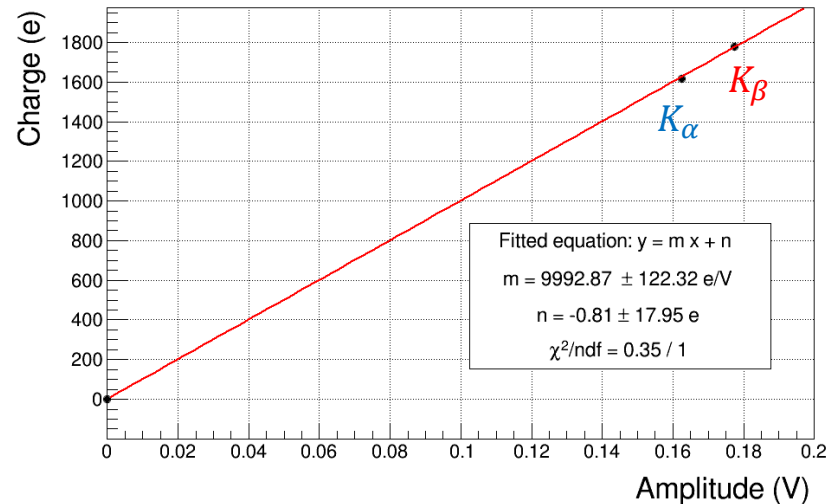
Skewed gaussian fit for  $K_\alpha$  and gaussian fit for  $K_\beta$  for the case of  $3\sigma_{\text{cut}}$ .



Fits for  $K_\alpha$  and  $K_\beta$  peaks after the cut

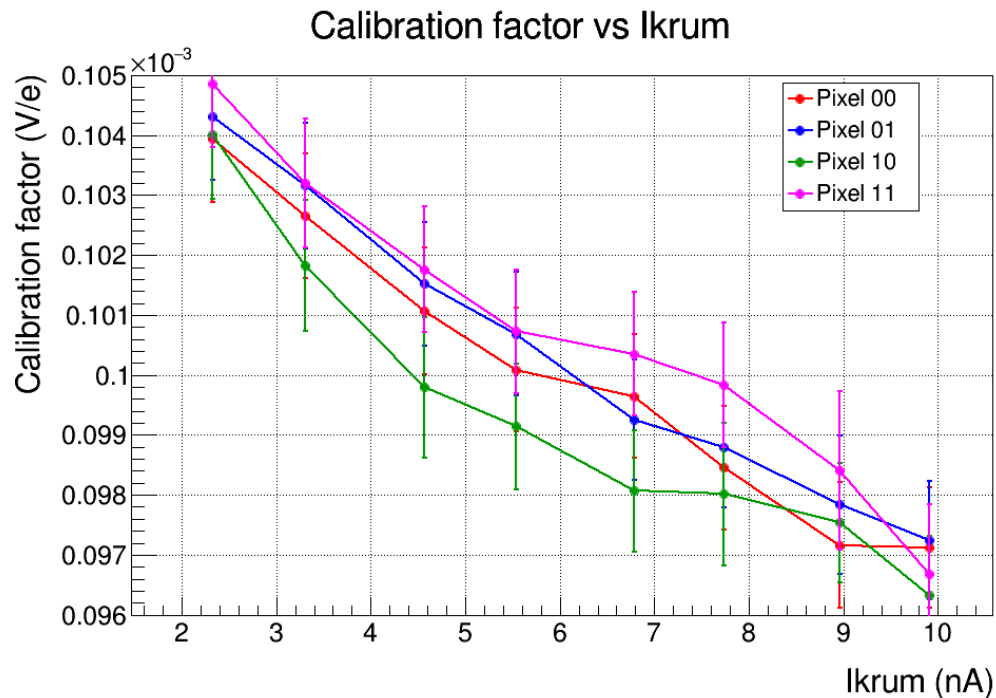


Linear calibration fit (Charge vs Amplitude)



# ANALYSIS - Charge calibration

Repeating the procedure for every pixel and each run, applying a size cut of  $3\sigma$  for the **4  $\mu\text{m}$**  n-gap layout:



The **calibration factor** in V/e decreases with the  **$I_{\text{krum}}$** .

Large uncertainties observed for this method.

# SUMMARY

Comparison between the **4  $\mu\text{m}$  and 2.5  $\mu\text{m}$**  n-gap layouts.



The **4  $\mu\text{m}$**  layout shows a **faster response**.

The **charge calibration factors** were obtained for different values of the  $I_{\text{krum}}$  and their dependence was studied for the **4  $\mu\text{m}$**  n-gap layout.

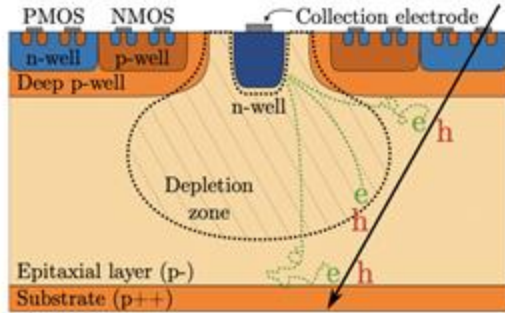


Calibration factor **decreases with  $I_{\text{krum}}$** .

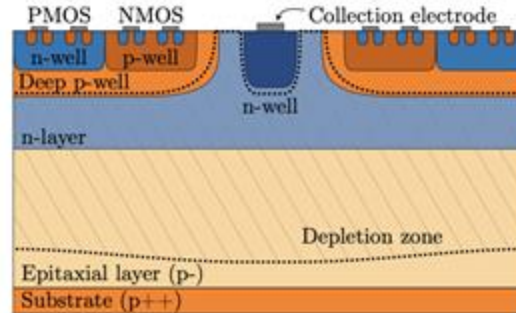
# NEXT STEPS

- Calibration can be improved using the **slope** obtained for **each cut size** and adding more points to the fit.
- Perform the **calibration for the 2.5  $\mu\text{m}$  layout** to complete the comparison between both layouts.
- Apply this calibration to the **test beam data** and allow comparison with other chips.

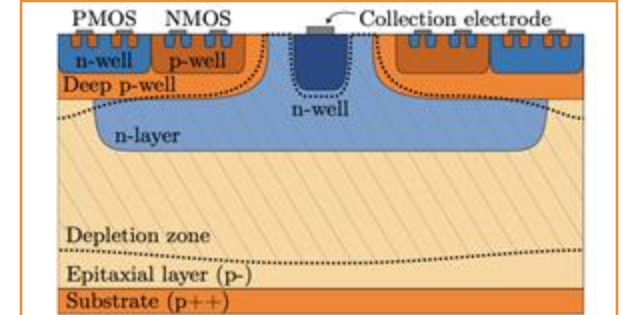
# Backup– MAPS different layouts



Standard layout

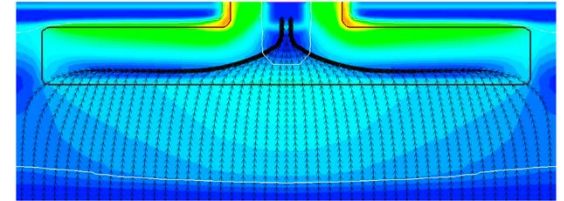


n-blanket layout



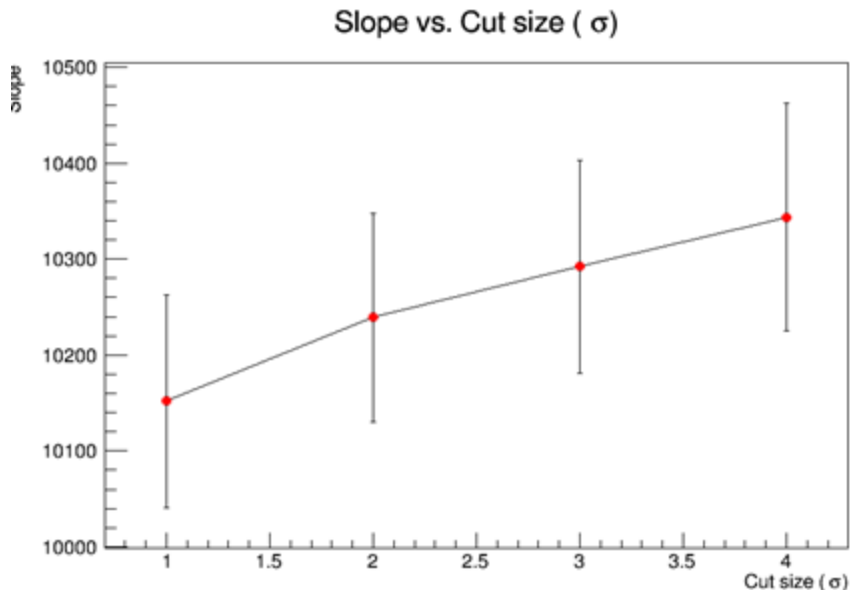
n-gap layout

- Adding an **n-layer** extends the depletion zone to the pixel edges.
- Introducing a **gap** in the n-layer increases the lateral electric field near the edges.



# Backup – Slope vs. Cut size

Repeat for each cut size to study the **slope as a function of the cut size**.



**The slope increases with the cut size.**

We propose using the mean of the slopes for each cut size, and combining the standard deviation with the mean of the slope errors.