

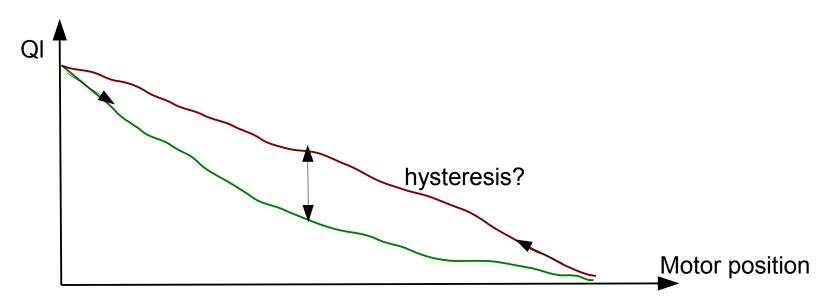
Middle layer server for loaded Q characterization

Katarzyna Gnidzińska DMCS, <u>Łódź</u>

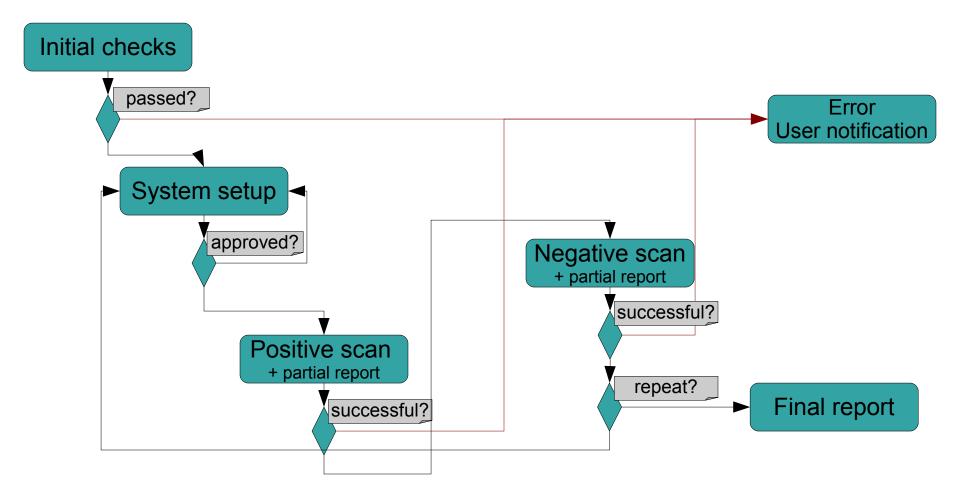


Idea of Q_I characterization

- Output: Q, vs motor position transfer function
- Other parameters : end switch motor position, Q₁ range
- For each cavity, each cryomodule
- May be different gradients



Test schema



Challenges

- To ensure all the parameters are correctly set and the conditions are steady during the test
- Important to foresee all possible exceptions
 - What kind of exceptions?
 - * How to handle them?
- Clear and reliable reports/notifications
- Yet not to bother user with constant requests for approval and manual adjustments
- To ensure there is no risk of endless loop timeouts

Exception recognition

Possible kinds of problems:

- interactions with other servers (~ read/write exception)
- motor position related end is reached?, correct movement, busy/ready
 necessity of timeouts
- ...?

<pre>[* INITIAL CHECKS *] [] [] [] [] [] [] [* SYSTEM SETUP *] [] [] [* RECORDING *]</pre>	location: C1.ACC7 location: C1.ACC7	motor server up LLRF server up piezo server up cavity slow tuners server up Tue Aug 14 09:31:23 2012 SP settings reachable. status_detuning : 0	
[ERROR	TAL CHECKS *] locati	al tests FAILED ! Read Exception. TTF2.RF/LLRF.QLSET/C1.ACC2/ERROR	
[* SYSTEM SETUP *] [] [] [ERROR]	location: C1.ACC6 location: C1.ACC6 location: C1.ACC6		

Implementation strategy

How to implement it in a DOOCS server?

- Dedicated classes of exceptions for each possible problem
- Test conditions checked all the time during testing
- Simultaneous tests for a number of modules in one cavity/ one module/ modules in different cavities if necessary

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Thank you for your attention

