

Limits in High Energy Physics

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Tutorial/lecture for the
Terascale Statistics School

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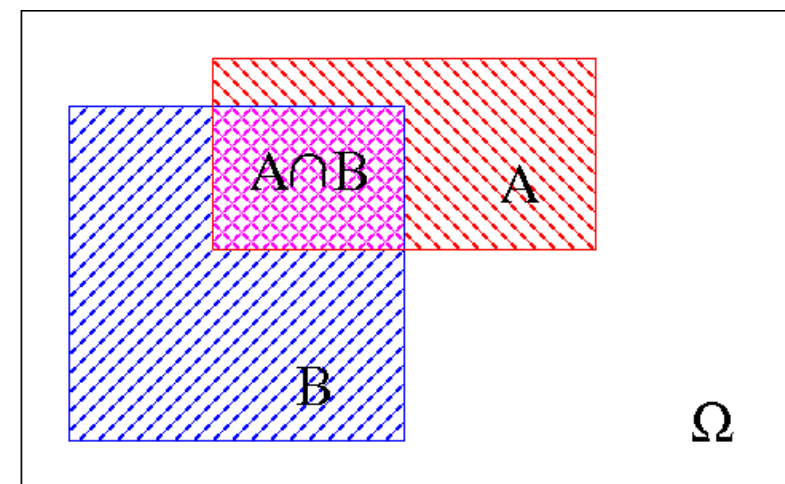
Outline

- Part I: basic concepts, Bayes and Frequentist, simple example
- Part II: Poisson with background, expected limit, CL_s method
- Part III: systematic uncertainties and many channels, hybrid method, profile likelihood
- Exercises: Lecture is interleaved by exercises ~10-15 minutes each. Solutions are discussed in the lecture
- **ROOT macros for exercises:**
`www.desy.de/~sschmitt/LimitStatSchool2013/macros`
- **If available on our computer, use wget:**
`wget -N -nd www.desy.de/~sschmitt/LimitStatSchool2013/macros.list`
`wget -N -nd -i macros.list`

Probability theory: selected items

- Elements of Ω : events, outcomes of an experiment
- Probability of a set A : $0 \leq P(A) \leq 1, P(\Omega) = 1 \quad P(\Omega \setminus A) = 1 - P(A)$
 $P(\Omega) = 1, P(\emptyset) = 0$
- Example: Poisson distribution $P(\{N\}) = \frac{e^{-\mu} \mu^N}{N!}, \Omega = \{0, 1, 2, \dots\}, A = \{N\}$
- Conditional probability of A given B : $P(A|B) = \frac{P(A \cap B)}{P(B)}$
- Bayes' law:

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$



Probability densities

- Probabilities on discrete sets: each element has a finite probability

Example: Poisson distribution

→ For event counts

$$P(\{N\}) = \frac{e^{-\mu} \mu^N}{N!}$$

$$\Omega = \{0, 1, 2, \dots\}$$

- Probability densities: probabilities are defined by integrals

Example: normal distribution

→ For systematic errors

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$$\Omega = \mathbb{R}$$

$$P(a \leq x \leq b) = \int_a^b f(x) dx$$

Parameters

Parameters of a probability density/distribution



The outcome of the experiments/possible observations

Examples:

- Poisson distribution:

$$P(\{N\}) = \frac{e^{-\mu} \mu^N}{N!}$$

μ is a parameter

- Normal distribution:

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

μ and σ are parameters

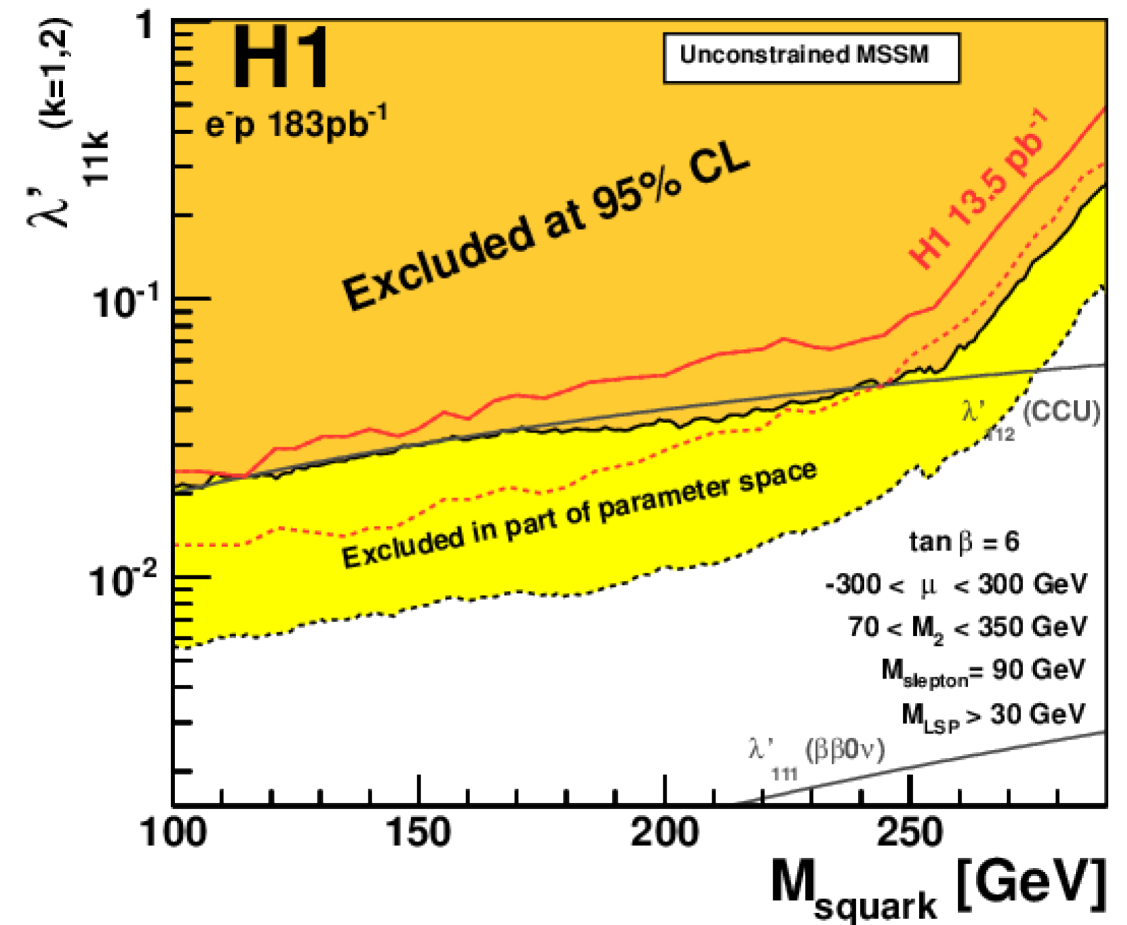
- Symbol for (a set of) parameters: θ

Types of parameters

- During limit setting, parameters may be **fixed** or **variable**
- Types of variable parameters:
 - **Parameter of interest**
 - Limits are set on this parameter (e.g. Higgs coupling)
 - **Nuisances**
 - These are “not of interest” (e.g. background normalisation)
- Special case of “fixed” parameters:
 - **Parameter scan**
 - limit calculation is repeated many times (e.g. Higgs mass)

Example: limit with parameter scan

- Example: search for R_p violating SUSY at HERA (resonant single squark production)
- Limit is set on the R_p-violating coupling λ
- squark mass scanned (y-axis)
- Other SUSY parameters are also scanned (yellow area)



Example plot: Search for Squarks in R-parity Violating Supersymmetry in ep Collisions at HERA, Eur.Phys.J.C71 (2011) 1572

Frequentist/Bayesian probability

- Frequentist view: probabilities describe the outcomes of experiments

Models have unknown parameters. Probabilities (to make the given observation) are quoted as a function of the parameters

- Bayesian extension: probabilities are also used to describe the “degree of belief” in parameters.
→ The parameters themselves have probabilities assigned.

Bayesian definitions

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$

- **Prior:** $P(B)$ where B is the theory
- **Likelihood:** $P(A|B)$ where A is the measurement
- **Posterior:** $P(B|A)$ is the result of the analysis

- $P(A)$ has no special name. The normalisation is often calculated using the relation $P(B|A) + P(\sim B|A) = 1$

Exercise 1 (Bayes' law)

- Disease and a test for the disease
- 0.1% of the population have the disease (prior)
- If one has the disease, the test is positive with 99% probability (likelihood)
- If one does not have the disease, the test is positive with 1% probability
- What is the posterior probability to have the disease, given a positive test?

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$

Exercise 1 (Bayes' law)

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- What is the posterior probability to have the disease, given a positive test?

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$

A: positive test
B: has disease

Prior: $P(B)=0.001$

Likelihood: $P(A|B)=0.99$

$P(A|\sim B) = 0.01$

Normalisation:

$P(A)=P(A\cap B)+P(A\cap\sim B)=$

$P(A|B)*P(B)+P(A|\sim B)*P(\sim B)=$

$0.99*0.001+0.01*0.999= 0.01098$

Posterior: $P(B|A)=$

$0.99*0.001/0.01098 = 9\%$

Because the disease is so rare, the probability is only 9%.

The test has to be improved, 1% of false-positive tests is too much

Probabilities in high energy physics

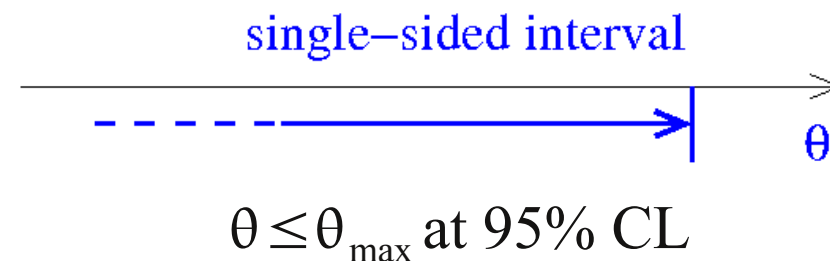
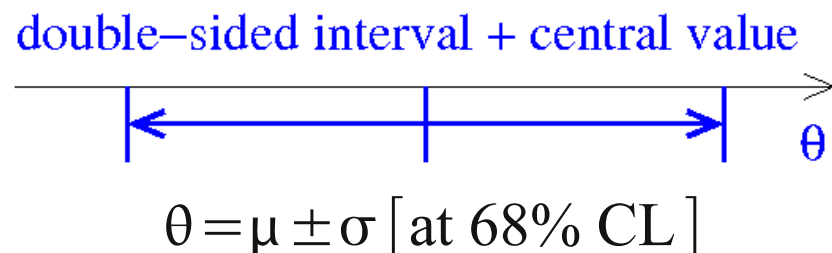
- Probability: predict number of events given the theory (parameter of interest) and the experimental setup (nuisances)
- Question: what does a specific observation tell about the theory
- Frequentist: give for each theory the probability of the observation (there is no probability for a theory)
- Bayes: assign probability (degree of belief) to theories
- High energy physics: make use of both views (preference for frequentist, in particular for discoveries)

Confidence intervals, Limits

- Confidence intervals tell about parameters of the theory
- Confidence level (CL): associated probability
 - Different meaning of CL Frequentist/Bayesian:

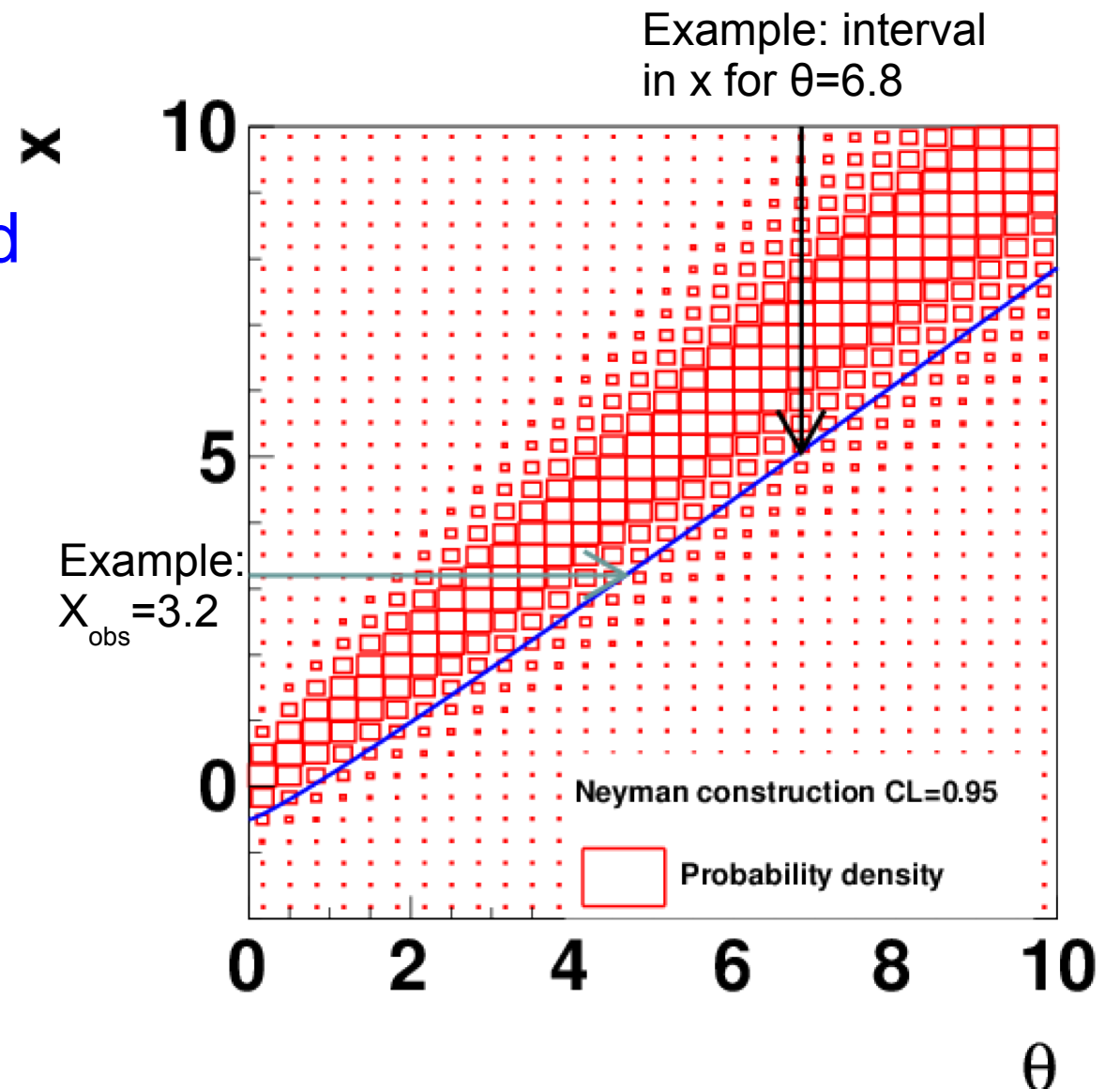
Frequentist: $CL=P(\text{observation})$ Bayesian: $CL=P(\text{theory})$

- Double-sided interval: measurement (usually $CL=68\%$)
- Single-sided: limit (often $CL=95\%$)

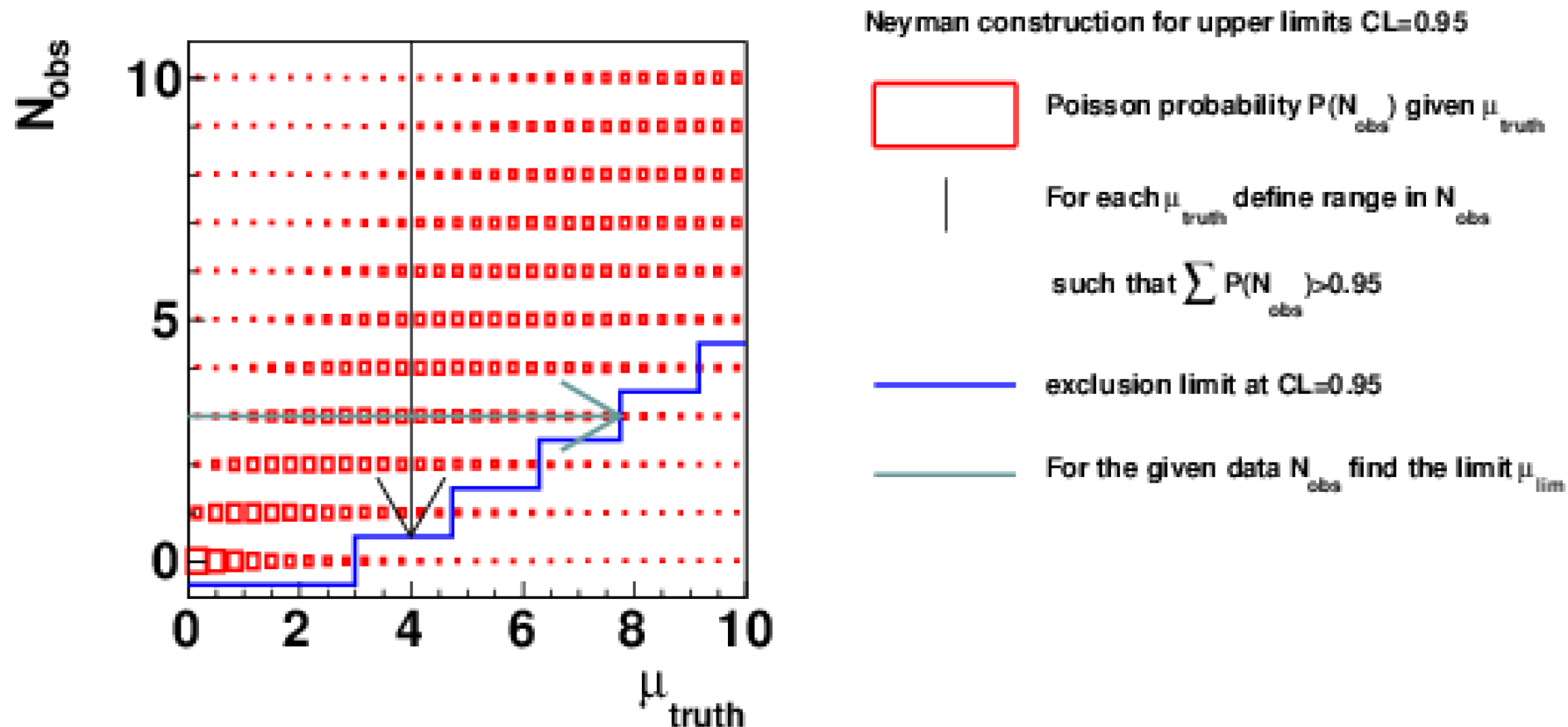


Frequentist limit: Neyman construction

- For each value of the parameter θ , find single-sided interval with probability $\geq CL$ (CL is fixed, e.g. $CL=0.95$)
- Interconnect interval edges
- For a given observation find the largest θ , where x_{obs} is just contained in the interval \rightarrow limit on θ



Frequentist upper limit, Poisson data



- Neyman construction, for each μ find N_{obs} -interval with $P \geq CL$
- Then: read off μ_{limit} for a given N_{obs}
- Note: discrete N_{obs} but continuous $\mu \rightarrow$ steps in the limit

Exercise 2 (Neyman construction)

- Poisson experiment, determine limits on the parameter μ , given N_{obs}
 - determine the range $N_{\text{obs}} \leq N \leq \infty$ for $CL=0.95$ and $\mu=2,3,5,10$. What is the probability to find the measurement in these ranges
 - determine the limit on μ for $N_{\text{obs}}=0,2,10,100$
- Hint: the probability to find N in the interval $N_{\text{obs}} \leq N \leq \infty$ is given by:

$N_{\text{obs}} \leq N \leq \infty$ is given by:

$$\text{Probability: } \sum_{N \geq N_{\text{obs}}} \frac{e^{-\mu} (\mu)^N}{N!} = 1 - \alpha = 1 - \text{TMath::Prob}(2 * \mu, 2 * N_{\text{obs}})$$

$$\text{Inverse function: } 2 * \mu = \text{TMath::ChisquareQuantile}(1 - \alpha, 2 * N_{\text{obs}})$$

(a)

μ	N_{obs}	$1-\alpha$
2		
3		
5		
10		

(b)

N_{obs}	μ_{limit}
0	
2	
10	
100	

Exercise 2 (Neyman construction)

- Poisson experiment, determine limits on the parameter μ , given N_{obs}
 - determine the range $N_{\text{obs}} \leq N \leq \infty$ for $CL=0.95$ and $\mu=2,3,5,10$. What is the probability to find the measurement in these ranges
 - determine the limit on μ for $N_{\text{obs}}=0,2,10,100$
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$$\text{Inverse function: } 2 * \mu = \text{TMath::ChisquareQuantile}(1 - \alpha, 2 * N_{\text{obs}})$$

(a)

μ	N_{obs}	$1-\alpha$
2	0	1
3	1	0.95
5	2	0.96
10	5	0.97

(b)

N_{obs}	μ_{limit}
0	3.0
2	6.3
10	17.0
100	118.1

Coverage

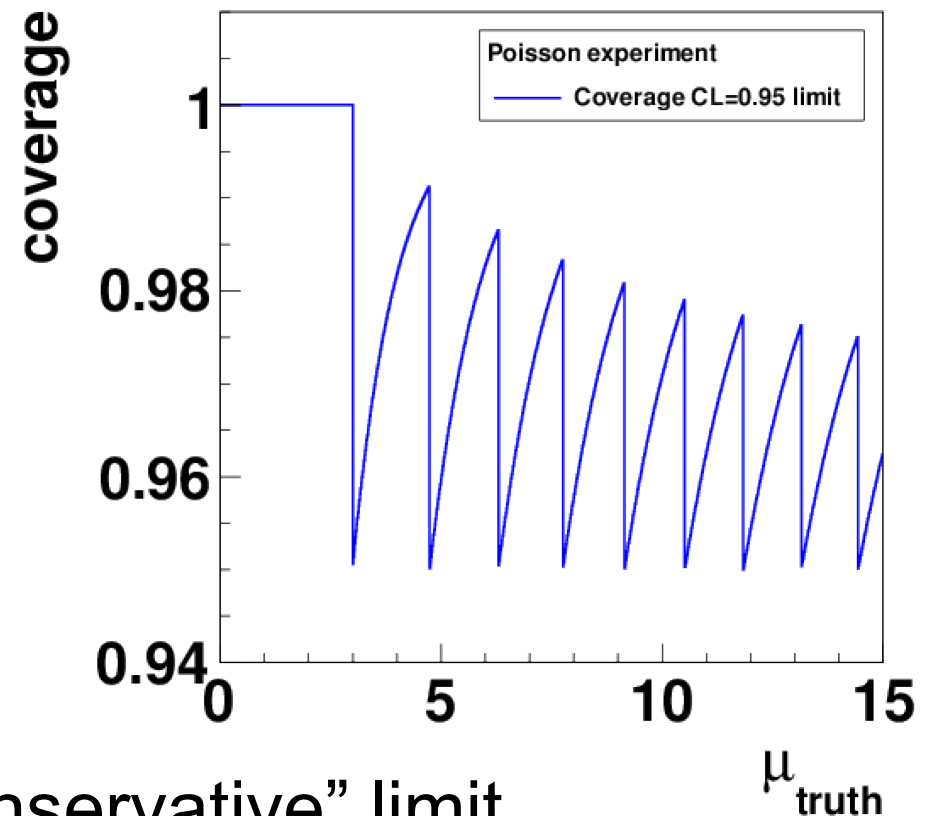
- **Coverage**: given a limit procedure, calculate for each θ the probability to exclude the theory

- Poisson example (exercise 2)

$$P_{\text{excl}}(\mu_{\text{truth}}) = \sum_N P_{\mu, \text{truth}}(N) \Theta(\mu_{\text{truth}} \leq \mu_{\text{limit}}(N))$$

$$\text{where } \Theta(\mu_{\text{truth}} \leq \mu_{\text{limit}}) = \begin{cases} 1 & \text{if } \mu_{\text{truth}} \leq \mu_{\text{limit}} \\ 0 & \text{otherwise} \end{cases}$$

- coverage=0.95: exact coverage
- coverage<0.95: undercoverage
- coverage>0.95: overcoverage, “conservative” limit
- “Simple” Poisson case: overcoverage (discrete measurement)



Bayesian limits

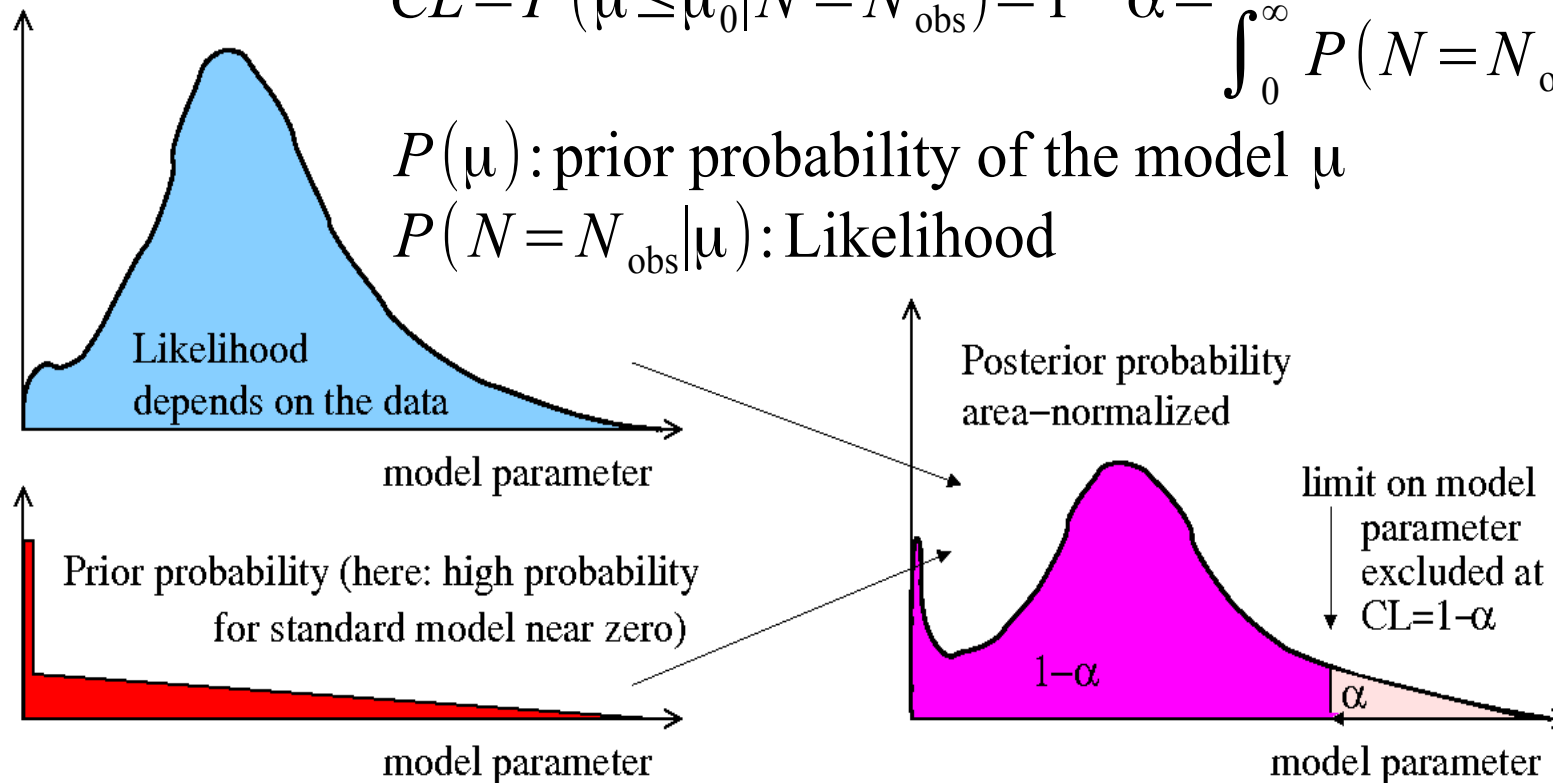
- Bayesian limit: exclude a set of theories, such that the posterior probability of the excluded theories is 1-CL

Enumerator: integrate over allowed theories

$$CL = P(\mu \leq \mu_0 | N = N_{\text{obs}}) = 1 - \alpha = \frac{\int_0^{\mu_0} P(N = N_{\text{obs}} | \mu) P(\mu) d\mu}{\int_0^{\infty} P(N = N_{\text{obs}} | \mu) P(\mu) d\mu}$$

$P(\mu)$: prior probability of the model μ
 $P(N = N_{\text{obs}} | \mu)$: Likelihood

Denominator: integrate all theories (normalisation)



Bayesian limit: integrate over models, fixed N_{obs}

Frequentist limit: integrate over N_{obs} , test each model

Exercise 3 (Bayesian limit)

- Exercise 3a: Bayesian limit for $N_{\text{obs}} = 0, 2, 10, 100$ (flat prior) (use Root macro)
- Exercise 3b: use a prior $P(\mu) = \mu$, $N_{\text{obs}} = \{0, 2, 10, 100\}$
- Exercise 3c: use a flat prior up to $\mu_{\text{max}} = 90$, set prior to zero above μ_{max}
- Compare to exercise 2
- Bayesian limit with arbitrary prior \rightarrow numerical integration
- `GetPosterior.C(muLimit, nObs)`
- $$\text{Posterior} \sim \int_0^{\mu_0} d\mu \text{Prior}(\mu) \frac{\exp[-\mu] \mu^{N_{\text{obs}}}}{N_{\text{obs}}!}$$
- Vary muLimit until Posterior=0.95

	frequentist	Bayes flat	Bayes $P(\mu) = \mu$	Bayes flat $\mu_{\text{max}} = 90$
N_{obs}	μ_{limit}	μ_{limit}	μ_{limit}	μ_{limit}
0	3.0			
2	6.3			
10	17.0			
100	118.1			

Bayesian limit exercise

- Exercise 3a: Bayesian limit for $N_{\text{obs}} = 0, 2, 10, 100$ (flat prior)
(use Root macro)
- Exercise 3b: use a prior $P(\mu) = \mu$, $N_{\text{obs}} = \{0, 2, 10, 100\}$
- Exercise 3c: use a flat prior up to $\mu_{\text{max}} = 90$, set prior to zero above μ_{max}
- Compare to exercise 2

- For this example: Bayes flat = Frequentist
- Prior $P(\mu) = \mu$ gives more conservative limit
- $\mu_{\text{max}} = 90$ fails for $N_{\text{obs}} = 100$

	frequentist	Bayes flat	Bayes $P(\mu) = \mu$	Bayes flat $\mu_{\text{max}} = 90$
N_{obs}	μ_{limit}	μ_{limit}	μ_{limit}	μ_{limit}
0	3.0	3.0	4.7	3.0
2	6.3	6.3	7.8	6.3
10	17.0	17.0	18.2	17.0
100	118.1	118.2	119.3	89.7

Lecture Part I, Summary

- Setting limits: related to parameter estimation, hypothesis tests
- Limit: special case of a confidence interval (single-sided)
- Frequentist limit: Neyman construction (sum over observations)
- Concept of “coverage”: test the validity of the limit procedure
- Bayesian limit: integral over parameter of interest
- Dependence on the choice of prior (for parameter of interest)

Limits with background

- Expected number of events: sum of a signal and background cross section, times integrated luminosity

$\mu = s + b$, s, b : signal and background event yield, respectively

- $s=0$: standard model
- $s>0$: new physics
- Assume background known. What is the limit on the signal?
- Frequentist: set limit on μ , then subtract b
- Bayesian: use prior probability which is zero for $s<0$

Exercise 4 (limit with background)

- Calculate Frequentist and Bayesian limits for $N_{\text{obs}} = \{0, 2\}$ and $b = \{0.5, 2.0, 3.5\}$
- Poisson parameter: $\mu = s + b$

	b=0.5		b=2.0		b=3.5	
	$N_{\text{obs}} = 0$	$N_{\text{obs}} = 2$	$N_{\text{obs}} = 0$	$N_{\text{obs}} = 2$	$N_{\text{obs}} = 0$	$N_{\text{obs}} = 2$
Bayesian						
Frequentist						

- Frequentist: use methods from exercise 2
- Bayes: try to modify exercise 3 macro, or use macro `GetPosteriorWithBackground.C`

Exercise 4 (limit with background)

- Calculate Frequentist and Bayesian limits for $N_{\text{obs}} = \{0, 2\}$ and $b = \{0.5, 2.0, 3.5\}$ Poisson parameter: $\mu = s + b$

	b=0.5		b=2.0		b=3.5	
	$N_{\text{obs}} = 0$	$N_{\text{obs}} = 2$	$N_{\text{obs}} = 0$	$N_{\text{obs}} = 2$	$N_{\text{obs}} = 0$	$N_{\text{obs}} = 2$
Bayesian	3.0	5.8	3.0	4.8	3.0	4.3
Frequentist	2.5	5.8	1.0	4.3	-0.5	2.8

- Problem for Frequentist limit, $N_{\text{obs}} = 0$ and $b = 3.5$:

limit excludes all signal above $s = -0.5$.

Even the “standard model” $s = 0$ is excluded

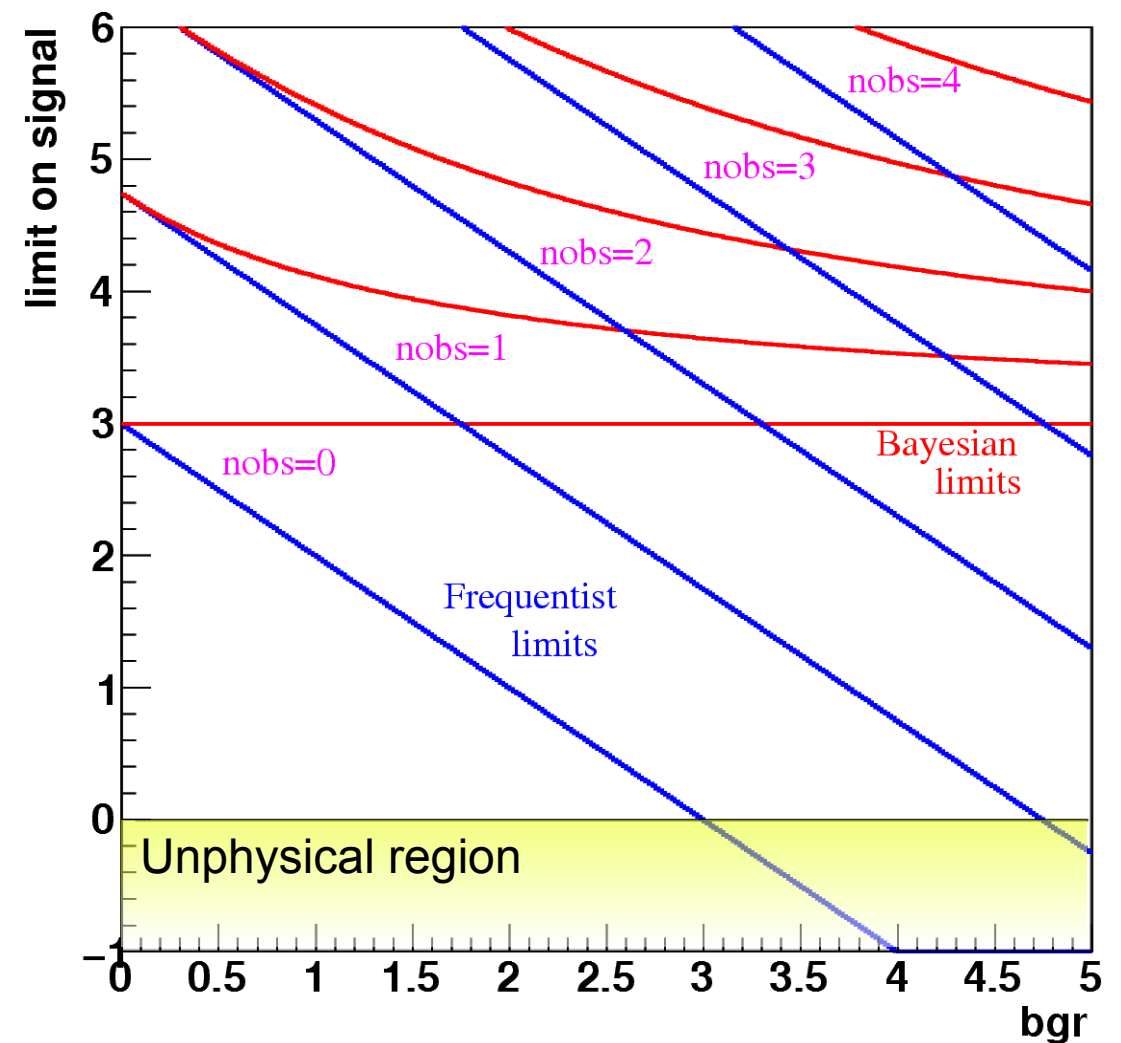
Discussion Exercise 4

- Frequentist analysis can give limits where **all** models are “excluded” at a given CL (even the model with $s=0$)

$$N_{\text{obs}} = 0, \mu = s+b, b=3.5$$

→ limit $s < -0.5$ @ 95% CL but $s \geq 0$ physical bound

- Bayesian limit uses prior knowledge $s \geq 0$



Limits near a boundary

- What to do if frequentist analysis excludes parameters beyond the sensitivity of the experiment or beyond boundaries?
- Give expected limit to show sensitivity of the experiment (exercise 5)
- CL_s method, also known as “modified frequentist” (exercise 6)
- Bayesian methods (see exercise 4)

Expected limit (exercise 5)

- Expected limit: limit weighted by background probability

$$\langle S_{\text{limit}} \rangle = \sum_{n=0}^{\infty} \frac{e^{-b} b^n}{n!} \text{LimitOnSignal}(b, n)$$

	b=0.5		b=2.0		b=3.5	
	N _{obs} =0	N _{obs} =2	N _{obs} =0	N _{obs} =2	N _{obs} =0	N _{obs} =2
Bayesian	3.0	5.8	3.0	4.8	3.0	4.3
Frequentist	2.5	5.8	1.0	4.3	-0.5	2.8
Expected						

- Calculate expected limits for $b=\{0.5,2.0,3.5\}$
- Macro GetExpectedLimit.C

Expected limit (exercise 5)

- Expected limit: limit weighted by background probability

$$\langle S_{\text{limit}} \rangle = \sum_{n=0}^{\infty} \frac{e^{-b} b^n}{n!} \text{LimitOnSignal}(b, n)$$

	b=0.5		b=2.0		b=3.5	
	N _{obs} =0	N _{obs} =2	N _{obs} =0	N _{obs} =2	N _{obs} =0	N _{obs} =2
Bayesian	3.0	5.8	3.0	4.8	3.0	4.3
Frequentist	2.5	5.8	1.0	4.3	-0.5	2.8
Expected	3.3		4.2		4.9	

- Problematic case: expected limit differs a lot from observed limit
 → Recognize statistical fluctuation or problem with background

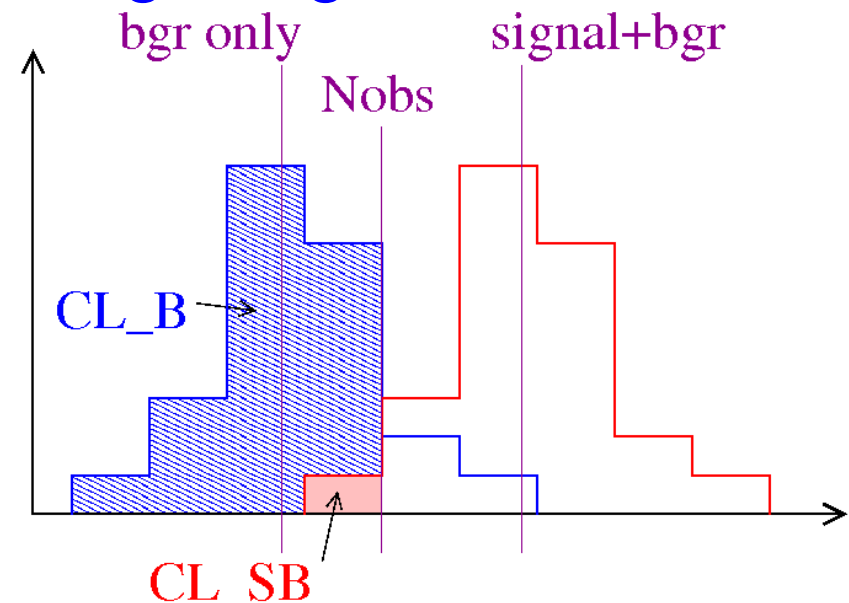
The CL_S (modified frequentist) method

- **Frequentist limit:** $1 - CL \geq \alpha = CL_{SB} = P(N \leq N_{obs}; \mu = s + b)$
- **CL_S limit:** $1 - CL \geq CL_S = \frac{CL_{SB}}{CL_B} = \frac{P(N \leq N_{obs}; \mu = s + b)}{P(N \leq N_{obs}; \mu = b)}$

- Probability is normalized to background probability
- $CL_B \leq 1 \rightarrow CL_S \geq CL_{SB}$: same α requires larger signal

Limit is “conservative”

- For zero signal: $CL_S = 1$
 \rightarrow zero signal is never excluded



Exercise 6 (CL_s method)

- **Frequentist limit:** $1 - CL \geq \alpha = CL_{SB} = P(N \leq N_{obs}; \mu = s + b)$
- **CL_s limit:** $1 - CL \geq CL_s = \frac{CL_{SB}}{CL_B} = \frac{P(N \leq N_{obs}; \mu = s + b)}{P(N \leq N_{obs}; \mu = b)}$

	b=0.5		b=2.0		b=3.5	
	$N_{obs} = 0$	$N_{obs} = 2$	$N_{obs} = 0$	$N_{obs} = 2$	$N_{obs} = 0$	$N_{obs} = 2$
Bayesian	3.0	5.8	3.0	4.8	3.0	4.3
Frequentist	2.5	5.8	1.0	4.3	-0.5	2.8
CL_s						
Expected	3.3		4.2		4.9	

- Use macro `GetCLsLimit.C` to calculate CL_s , iterate to get limit

Exercise 6 (CL_s method)

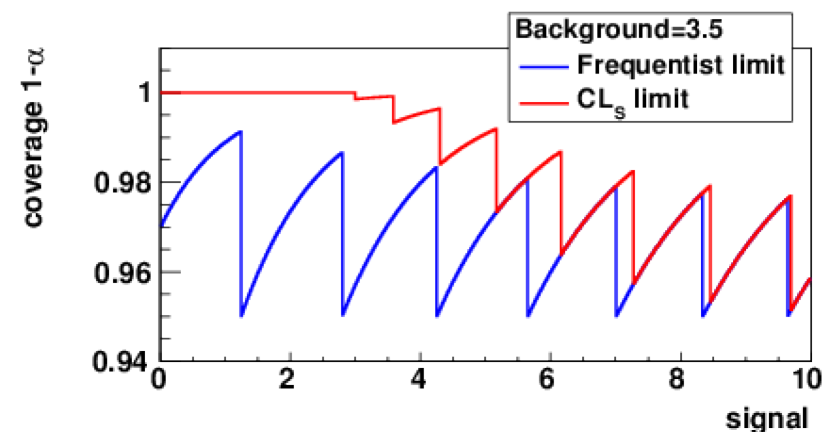
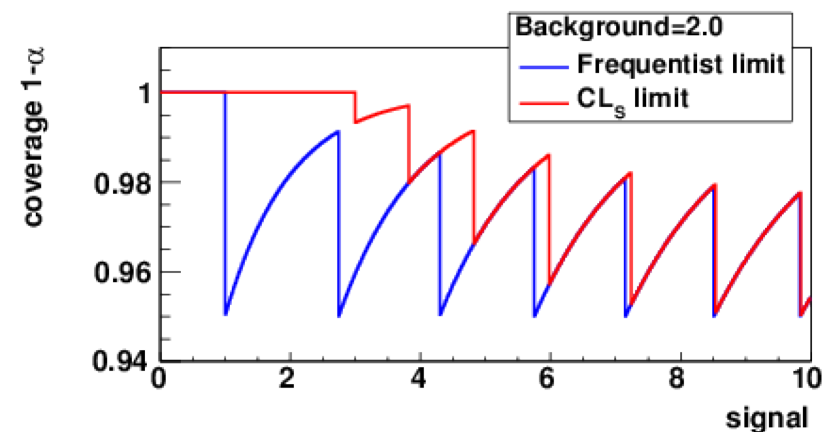
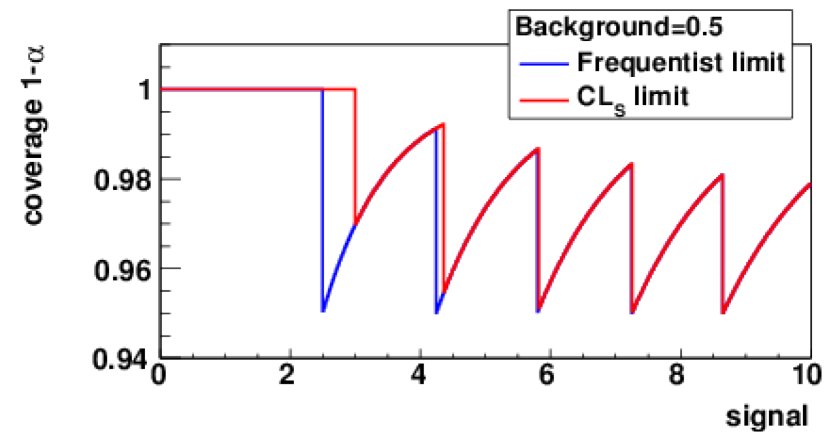
- **Frequentist limit:** $1 - CL \geq \alpha = CL_{SB} = P(N \leq N_{obs}; \mu = s + b)$
- **CL_s limit:** $1 - CL \geq CL_s = \frac{CL_{SB}}{CL_B} = \frac{P(N \leq N_{obs}; \mu = s + b)}{P(N \leq N_{obs}; \mu = b)}$

	b=0.5		b=2.0		b=3.5	
	$N_{obs} = 0$	$N_{obs} = 2$	$N_{obs} = 0$	$N_{obs} = 2$	$N_{obs} = 0$	$N_{obs} = 2$
Bayesian	3.0	5.8	3.0	4.8	3.0	4.3
Frequentist	2.5	5.8	1.0	4.3	-0.5	2.8
CL_s	3.0	5.8	3.0	4.8	3.0	4.3
Expected	3.3		4.2		4.9	

- For this example, CL_s is identical to Bayesian (with flat prior)

Limits with background, coverage

- CL_s method avoids problem with limits better than the experiments sensitivity
- Disadvantage: CL_s method is conservative, in particular for small signals

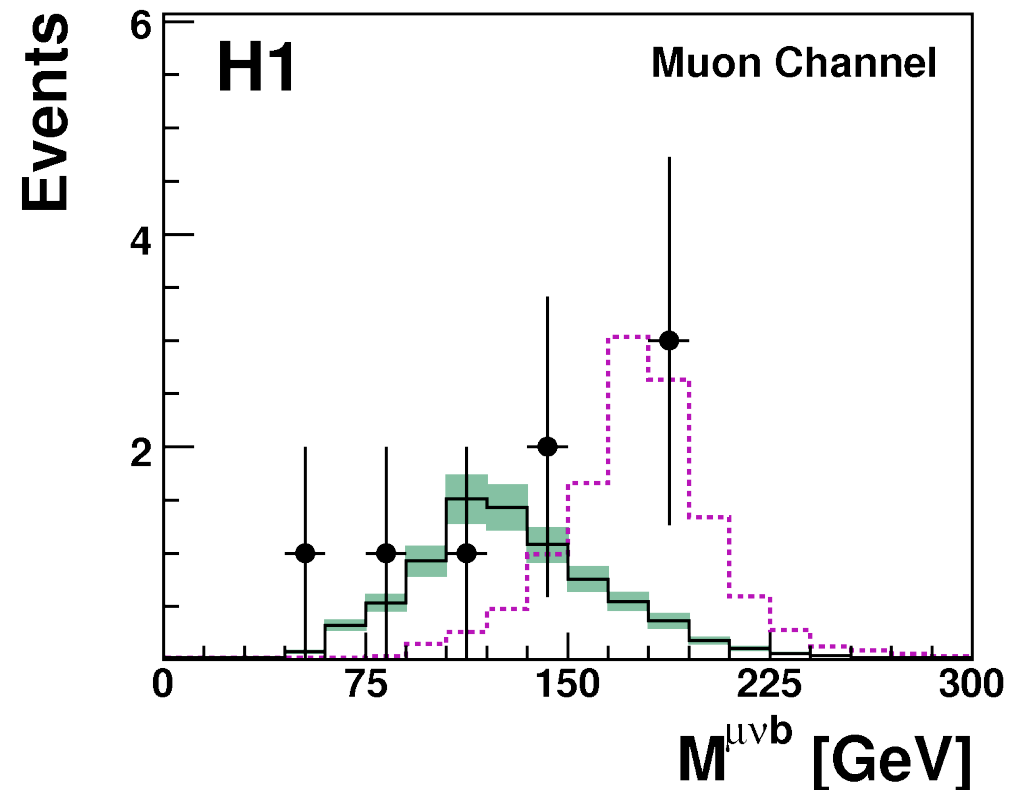


Lecture part II, summary

- Poisson experiment with background
- Unnaturally good limit if number of events is much smaller than background expectation
- “Solutions”:
 - Quote expected limit (sensitivity of the experiment)
 - CLS method (never excludes background-only)
 - Bayesian method (prior knows about boundaries)

Systematic errors, multiple bins/channels

- Examples discussed so far : events are counted in a single channel, no systematic errors
- General case: several channels (or bins) and systematic errors
- Example: mass distribution with N bins (signal and bgr shape)
 - N channels to be combined
 - Background normalisation error



Example plot: search for single top production at HERA, Phys.Lett. B678 (2009) 450

Simple example with two syst. errors

- Consider signal in one bin

$\mu = l(s + b)$, l : integrated luminosity, s, b : signal, background cross sections

with systematic errors:

$$l = l_{\text{obs}} \pm \sigma_l, \quad b = b_{\text{obs}} \pm \sigma_b$$

- Full probability density has three contributions

$$P_{s,l,b}(N_{\text{obs}}, l_{\text{obs}}, b_{\text{obs}}) = \underbrace{\frac{e^{-l(s+b)} (l(s+b))_{\text{obs}}^{N_{\text{obs}}}}{N_{\text{obs}}!}}_{\text{event counting}} \underbrace{\frac{1}{\sqrt{2\pi}\sigma_l} e^{-\frac{(l-l_{\text{obs}})^2}{2\sigma_l^2}}}_{\text{measurement of } l} \underbrace{\frac{1}{\sqrt{2\pi}\sigma_b} e^{-\frac{(b-b_{\text{obs}})^2}{2\sigma_b^2}}}_{\text{measurement of } b}$$

- Three channels (measurements): $N_{\text{obs}}, l_{\text{obs}}, b_{\text{obs}}$
- Nuisances l, b and parameter of interest s

Simple Example???

$$P_{s,l,b}(N_{\text{obs}}, l_{\text{obs}}, b_{\text{obs}}) = \underbrace{\frac{e^{-l(s+b)} (l(s+b))^{N_{\text{obs}}}}{N_{\text{obs}}!}}_{\text{event counting}} \underbrace{\frac{1}{\sqrt{2\pi\sigma_l}} e^{-\frac{(l-l_{\text{obs}})^2}{2\sigma_l^2}}}_{\text{measurement of } l} \underbrace{\frac{1}{\sqrt{2\pi\sigma_b}} e^{-\frac{(b-b_{\text{obs}})^2}{2\sigma_b^2}}}_{\text{measurement of } b}$$

- Three observables: $N_{\text{obs}}, l_{\text{obs}}, b_{\text{obs}}$
- Nuisances l, b and parameter of interest s
- This looks quite complicated already
- Observed: $N_{\text{obs}}, l_{\text{obs}}, b_{\text{obs}}$ and parameters l, b, s
 - Neyman construction in six dimensions? Perhaps not...
- How to get rid of nuisance parameters?
- How to combine channels (measurements)?

Bayesian method

$$L(s, l, b) = \underbrace{\frac{e^{-l(s+b)} (l(s+b))_{\text{obs}}^N}{N_{\text{obs}}!}}_{\text{event counting}} \underbrace{\frac{1}{\sqrt{2\pi}\sigma_l} e^{-\frac{(l-l_{\text{obs}})^2}{2\sigma_l^2}}}_{\text{measurement of } l} \underbrace{\frac{1}{\sqrt{2\pi}\sigma_b} e^{-\frac{(b-b_{\text{obs}})^2}{2\sigma_b^2}}}_{\text{measurement of } b}$$

- Bayesian treatment of nuisance parameters: the measurements l_{obs} and b_{obs} correspond to priors for l, b
- Define marginalized likelihood, where the nuisances are integrated out

$$L(s) = \int dl db L(s, l, b)$$

- Only depends on s (and the observations $N_{\text{obs}}, l_{\text{obs}}, b_{\text{obs}}$)
- Analysis (Bayesian) as for the case without systematic errors

Hybrid method

$$P_{s,l,b}(N_{\text{obs}}, l_{\text{obs}}, s_{\text{obs}}) = \underbrace{\frac{e^{-l(s+b)} (l(s+b))_{\text{obs}}^{N_{\text{obs}}}}{N_{\text{obs}}!}}_{\text{event counting}} \underbrace{\frac{1}{\sqrt{2\pi\sigma_l}} e^{-\frac{(l-l_{\text{obs}})^2}{2\sigma_l^2}}}_{\text{measurement of } l} \underbrace{\frac{1}{\sqrt{2\pi\sigma_b}} e^{-\frac{(b-b_{\text{obs}})^2}{2\sigma_b^2}}}_{\text{measurement of } b}$$

- Bayesian treatment of nuisance parameters: the measurements l_{obs} and b_{obs} correspond to priors for l, b
- Use marginalized likelihood as if it were the probability density for N_{obs} (after integrating out the nuisances)

$$P_{s, \text{marginalized}}(N_{\text{obs}}) = \int dl db P_{s,l,b}(N_{\text{obs}}, \dots)$$

- Only depends on s (and the observation N_{obs})
- Analysis (Neyman) as for the case without systematic errors

Exercise 7 (limits from hybrid method)

- CL_s limit, systematic error treated with hybrid method $\mu = l(s+b)$
- Background error: zero or $\sigma_b = 50\%$ [$b_{obs} = \{0.5, 3.5\}$]
- Luminosity error: zero or $\sigma_l = 10\%$ [$l_{obs} = 1.0$]

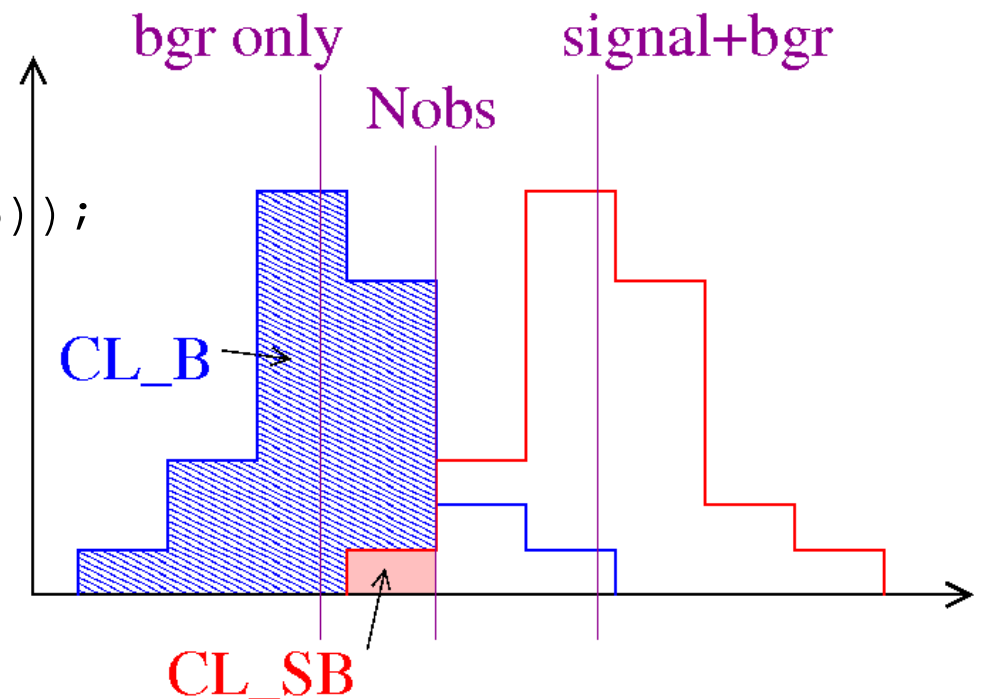
CL _s limits	b=0.5		bgr=3.5	
	N _{obs} = 0	N _{obs} = 2	N _{obs} = 0	N _{obs} = 2
No syst	3.0	5.8	3.0	4.3
$\sigma_b/b=50\%$				
$\sigma_l/l=10\%$				
Both syst.				

Use root macro
GetClsSys.C

Exercise 7 (limits from hybrid method)

- Typical example for the use of Monte Carlo methods to calculate probabilities
- Probabilities are calculated by counting the outcomes of toy experiments

```
l=rnd->Gaus(1.0,dLumi);  
b=rnd->Gaus(bgr,dBgr);  
Int_t n_b=rnd->Poisson(l*b);  
Int_t n_sb=rnd->Poisson(l*(signal+b));  
.  
.  
if(n_b<=nobs) nexp_b += 1.0;  
if(n_sb<=nobs) nexp_sb += 1.0;  
.  
.  
Double_t cl_s=nexp_sb/nexp_b;
```



Exercise 7 (limits from hybrid method)

- Background error: zero or $\sigma_b=50\%$ [$b_{\text{obs}}=\{0.5, 3.5\}$] $\mu = L(s+b)$
- Luminosity error: zero or $\sigma_l=10\%$ [$l_{\text{obs}}=1.0$]
- Systematic errors make limits somewhat worse

CL _s limits	b=0.5		bgr=3.5	
	N _{obs} =0	N _{obs} =2	N _{obs} =0	N _{obs} =2
No syst	3.0	5.8	3.0	4.3
$\sigma_b/b=50\%$	3.0	5.8	3.0	4.9
$\sigma_l/l=10\%$	3.1	6.0	3.2	4.5
Both syst.	3.1	6.0	3.1	5.0

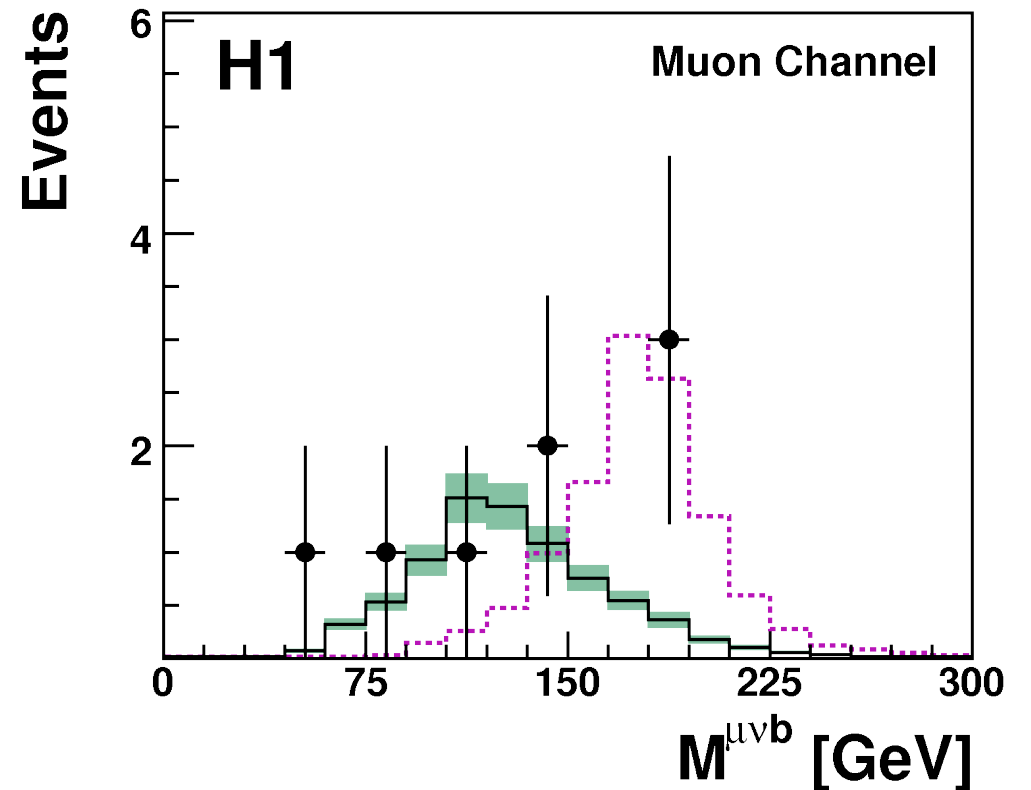
Small background:
background error
has little influence

Large background:
background error
has larger influence

Luminosity error
visible in all cases

Multiple bins/channels

- Case of multiple bins/channels brings additional complication for Frequentist analysis:
- Many bins: vector of observations
- Neyman construction: not possible for a vector of observations
- Solution: define 1-dimensional random variable (test statistic X)



Test statistic:

$X = X(N_1, N_2, N_3, \dots)$
where N_1, N_2, N_3, \dots are the event counts in bin 1, 2, 3, ... respectively

Choice of the test statistics

- **Log Likelihood ratio** $X = \log \left[\frac{L(\text{signal+bgr})}{L(\text{bgr})} \right]$
- **Likelihood normalized to maximum** $X = \log \left[\frac{L(\text{signal+bgr})}{L_{\max}} \right]$
- **Other choices: weighted sum of all channels, weight taken from signal/bgr ratio or something similar**

$$X = \sum w_i N_i^{\text{obs}}, \text{ where for example } w_i = \frac{(s_i + b_i) - b_i}{(s_i + b_i) + b_i}$$

- **Note: log of likelihood ratio also is a weighted sum:**

$$\log L(\text{signal+bgr}) - \log L(\text{bgr}) \sim \sum_i \underbrace{\log \left(1 + \frac{s_i}{b_i} \right)}_{w_i} N_i^{\text{obs}}$$

What is a good test statistic?

- Good sensitivity to signal
- Little sensitivity to systematic effects
- Ideal case: probability density $P(X)$ of test statistic is largely independent of the nuisances
→ use of hybrid method not needed → pure frequentist limit

- “Standard” choice: profile likelihood ratio
- Idea: nuisances are estimated from the data

$$X(s|\text{measurements}) = -2 \log \left[\frac{L(s, \hat{\theta}(s))}{L(\hat{s}, \hat{\theta})} \right]$$

s : signal strength, θ : nuisances

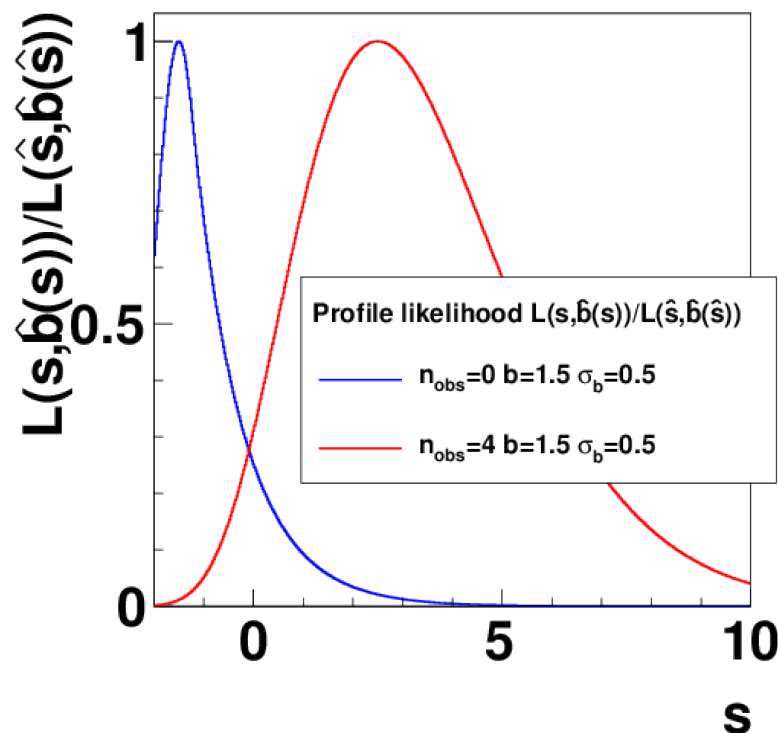
$L(s, \theta)$: Likelihood function

$\hat{\theta}(s)$: value of θ which maximizes L given s

\hat{s} and $\hat{\theta}$: global maximum of L

Profile likelihood ratio

- Basic idea: nuisances are estimated from the data
- Likelihood ratio: maximum indicates signal position
- Numerical analysis: use $-2 \cdot \log(\text{likelihood ratio})$
- $X(s)$ has a minimum near the best signal



$$X(s|\text{measurements}) = -2 \log \left[\frac{L(s, \hat{\theta}(s))}{L(\hat{s}, \hat{\theta})} \right]$$

s : signal strength, θ : nuisances

$L(s, \theta)$: Likelihood function

$\hat{\theta}(s)$: value of θ which maximizes L given s

\hat{s} and $\hat{\theta}$: global maximum of L

Profile likelihood analysis

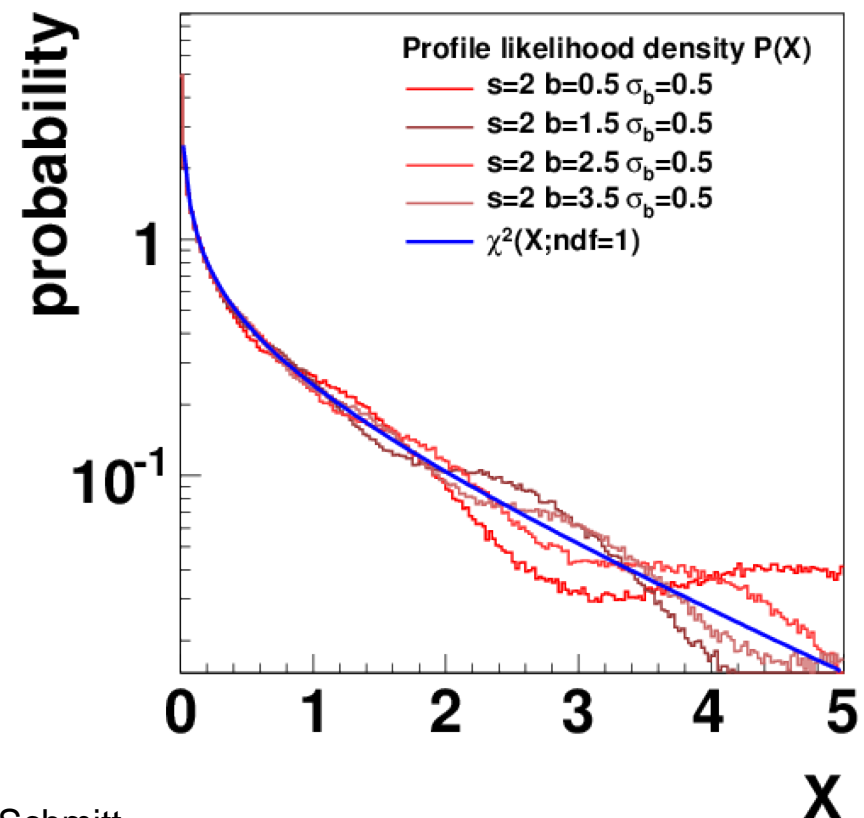
- Profile likelihood is expected to have probability density

$$P(X) \simeq \chi_{ndf=1}^2(X)$$

in the large sample limit

- Direct access to CL_{SB} , CL_S using `Tmath::Prob()`
- Need to verify $P(X)$ and dependence on nuisances with Monte Carlo methods

- Example: $\mu = s + b$
- Measurements: N_{obs} and b_{obs}
- Vary $b \rightarrow$ some influence



Summary

- Basic concepts of setting limits:
 - Frequentist/Bayesian methods
 - Coverage, expected limit, CL_s method
 - Systematic errors, nuisances, marginalization
 - Combining channels: test statistic, e.g. likelihood
 - Standard method: profile likelihood

Backup

Calculation of Poisson sums

- Sum over Poisson terms is related to χ^2 distribution with number-of-degrees of freedom “k”:

$$\chi^2(x; k) = \frac{x^{k/2-1} e^{-x/2}}{2^{k/2} \Gamma(k/2)} \quad P(N; \mu) = \frac{e^{-\mu} \mu^N}{N!}$$

- Poisson sum equals integral over χ^2 distribution (partial integration)

$$\alpha(\mu, N) = \int_{2\mu}^{\infty} \chi^2(x; 2(N+1)) dx = \sum_{i=0}^N P(i; \mu)$$

- Standard functions for χ^2 integrals:

$$\alpha(\mu, N) = \text{TMath}::\text{Prob}(2*\mu, 2*(N+1)) \text{ and}$$

$$\mu = 0.5 * \text{TMath}::\text{ChisquareQuantile}(1-\alpha, 2*(N+1))$$

Frequentist upper limit, Gaussian case

$$CL = \int_{x_{\text{obs}}}^{\infty} \exp\left[-1/2\left(\frac{x - \mu_{\text{truth}}}{\sigma}\right)^2\right] \frac{1}{\sqrt{2\pi}\sigma} dx$$

- Fixed σ , measurement x_{obs} , parameter of interest μ_{truth}
- Define 95% probability area under Gaussian
- If μ_{truth} is too large, it is outside the 95% → **excluded**

Limits with background, comparison

- Frequentist limit may become “unphysical” or “too good”
- Expected limit: sensitivity of the experiment
- CL_s method: normalize to “standard model”, never exclude zero signal
- Disadvantage of CL_s ? Study coverage

