Precision assembly of back-to-back "2S" modules and Front-to-back Metrology

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Precision Assembly of 2S Modules

Aim at front-to-back alignment accuracy of $\approx 15 \ \mu m$ derived from target resolution of on-module *pt* measurement.

We know that gantry assembly robots can achieve $\approx 10 \ \mu m$ standard deviation for single sided modules.

Strategy:

- place alignment marks on both sides of the double-sided 'fold-around' hybrid (using hybrid photolithography)
- measure position of marks on hybrid after hybrid assembly and store results in data base
- \rightarrow aim: front-to-back alignment of hybrid marks known to $\approx 5 \ \mu m$
- \rightarrow need to develop optical metrology set-up to do this
- glue sensors to hybrids using gantry robots and hybrid mark coordinates from data base
- \rightarrow alignment of sensors to hybrid marks on same side $\approx 10 \ \mu m$
- → alignment of front sensor to back sensor $\approx \sqrt{(10 \ \mu m)^2 + (5 \ \mu m)^2 + (10 \ \mu m)^2} = 15 \ \mu m$



Front-to-back Metrology

Options:

- transprent fiducials a la ATLAS-SCT 'turn plate'
- \rightarrow works (ATLAS exprience)
- \rightarrow requires to flip the hybrid/module/petal during measurement
- \rightarrow requires to mount the hybrid/module/petal in a frame which holds the fiducial
- simultaneous measurement on both sides
- \rightarrow main question: how to align the microscopes on both sides?
- → we are currently investigating the option to use an axis of rotation for this purpose

one version is shown to the right alternative: house microscopes in separate but precisely aligned bearings





Next Steps

- prepare technical drawings of 2S module with 'fold-around' hybrid
- build a dummy hybrid/module
- \rightarrow exercise hybrid carrier machining
- \rightarrow exercise hybrid assembly
- \rightarrow exercise module assembly
- work out details of optical front-to-back metrology
- eventually build a test version of the 'rotating double microscope'