

Movable emittance-meter data analysis methodology

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on behalf of the SPARC collaboration





Outline

The emittance meter experiment at SPARC.

Single moving slit method for measuring emittance at low energy.

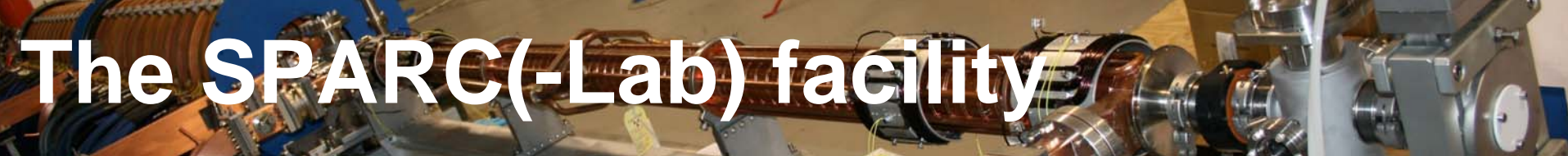
SPARC data analysis procedure

Main building blocks

Motivation for the analysis choices

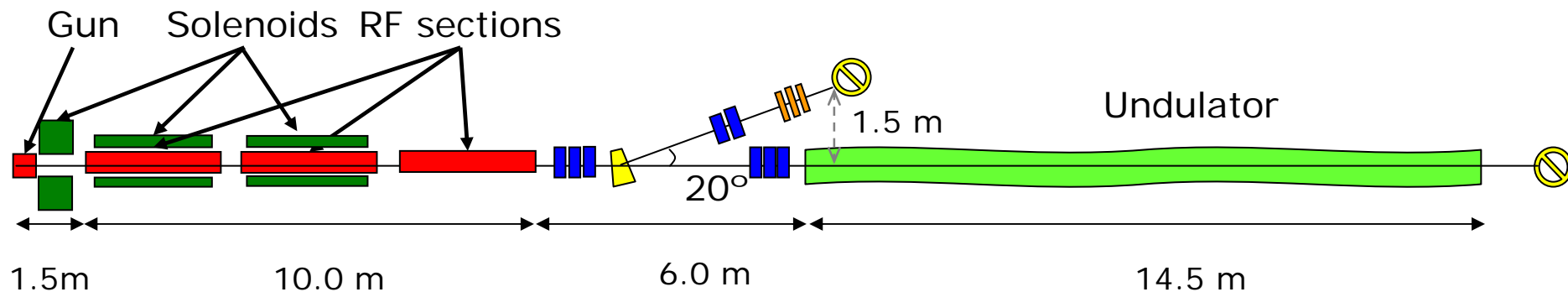
Example taken from the benchmark data

Conclusion



The SPARC(-Lab) facility

MAIN GOAL: R&D activity oriented to the development of a **high brightness photoinjector** to drive SASE FEL experiments



GUN PARAMETERS

Frequency 2856 MHz
Peak Field 120 MV/m

Beam Energy 5.6 MeV

Charge 1 nC

Emittance < 2 mm-mrad

Laser 10 ps (Flat Top with <2 ps rise time)

LINAC PARAMETERS

Frequency 2856 MHz
Accelerating Field 25 MV/m

Beam Energy 155 MeV

Energy Spread 10^{-3}

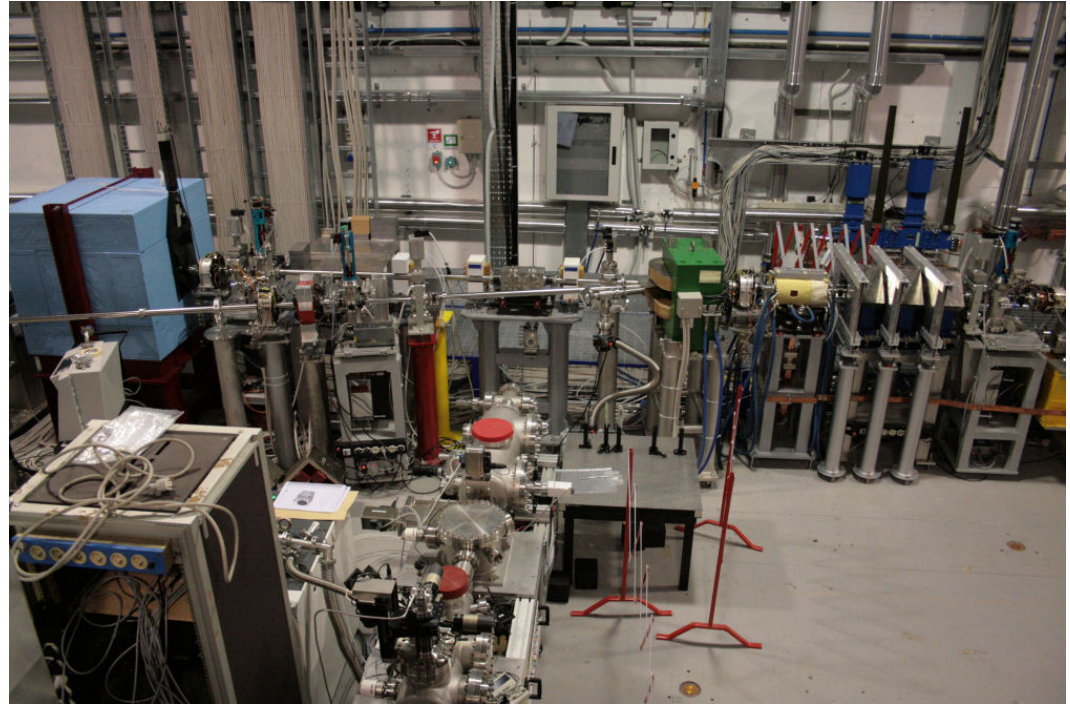
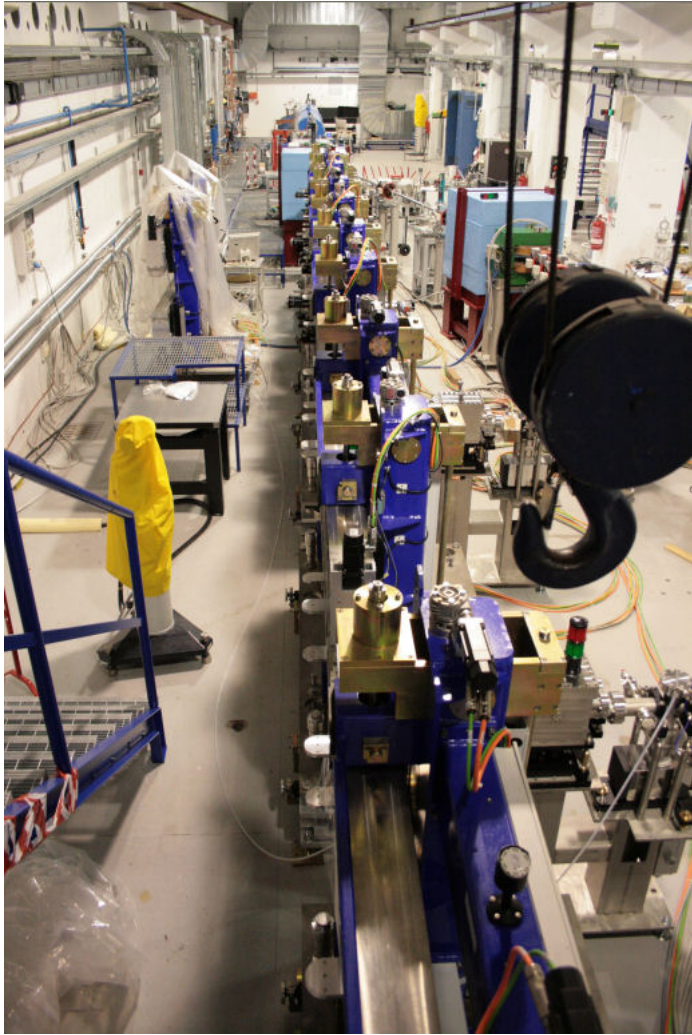
Peak Current 100 A

FEL PARAMETERS

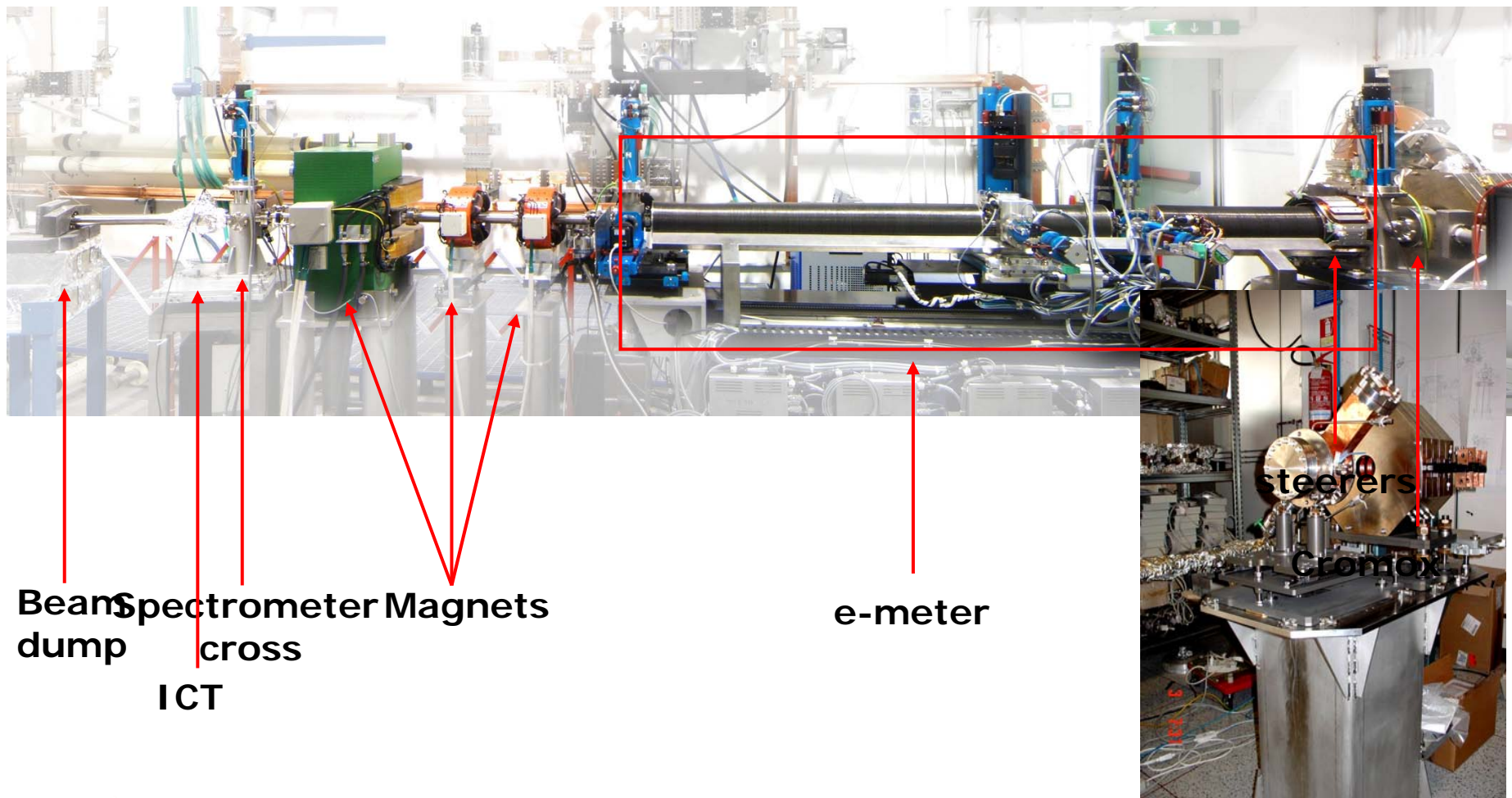
Wavelength 530 nm

Undulator period 2.8 cm

The SPARC(-Lab) facility today



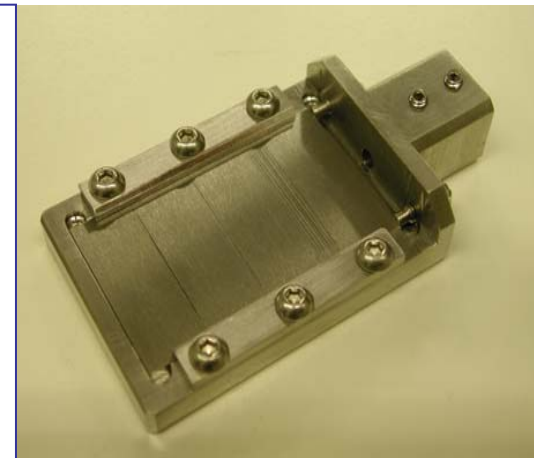
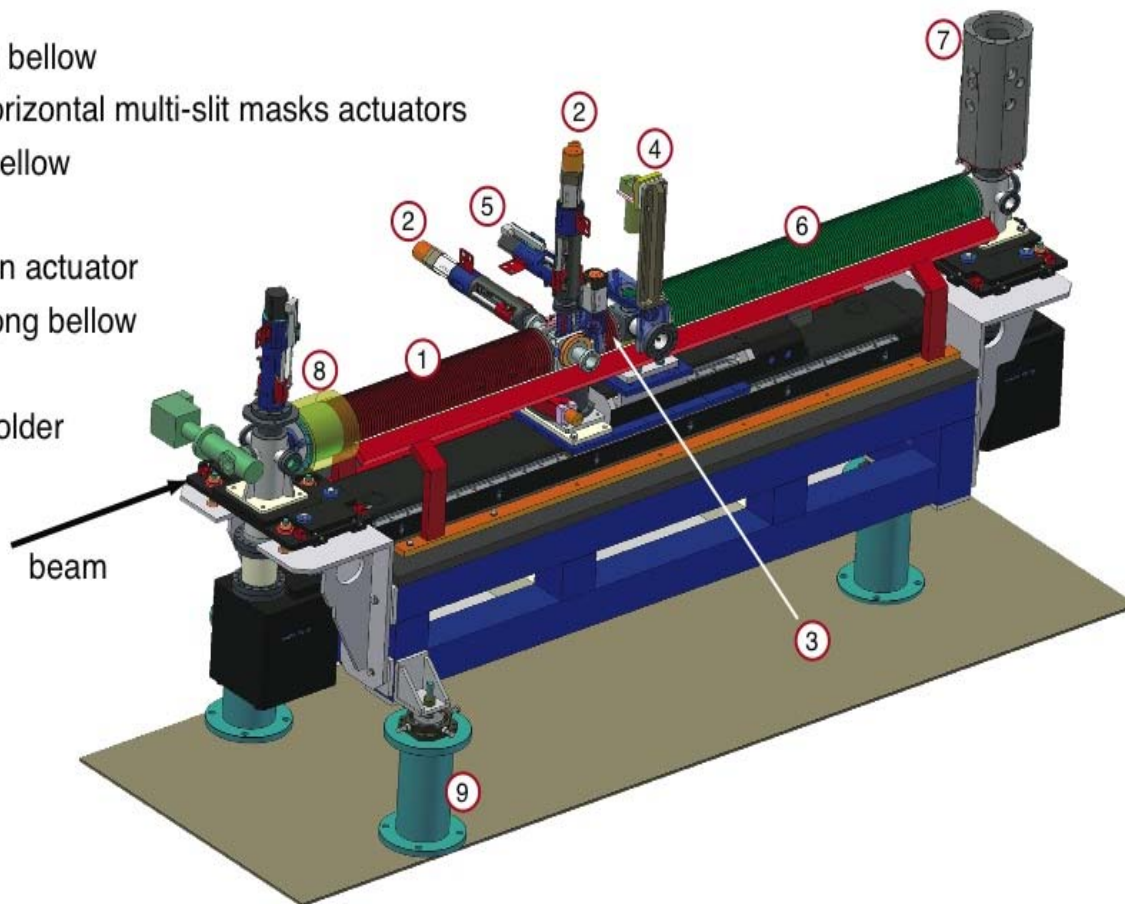
Emittance-meter relevant diagnostics





E-meter specifications

- 1 - upstream long bellow
- 2 - vertical and horizontal multi-slit masks actuators
- 3 - intermediate bellow
- 4 - CCD camera
- 5 - Ce:YAG screen actuator
- 6 - downstream long bellow
- 7 - alignment tool
- 8 - steering coil holder
- 9 - leg extender



Slit width = $50\ \mu\text{m}$

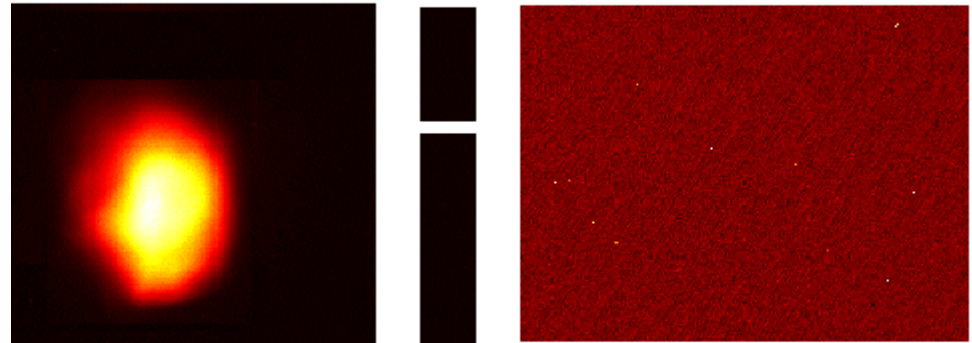
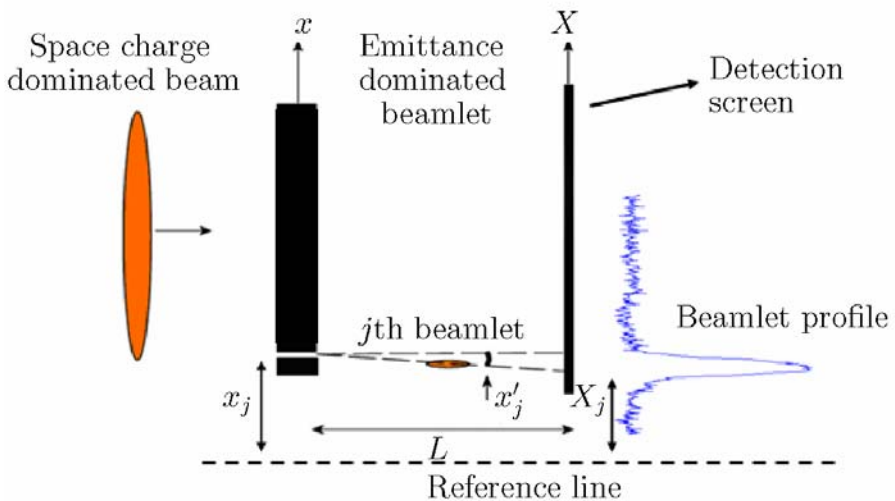
8 bit CCD cameras

$14.65\ \mu\text{m}/\text{pixel}$

Emittance meter allows to measure emittance as a function of the position in the drift space after the gun.



Single moving slit measurement



$\pm 3 \sigma$ of the beam transverse spot.

$L=40$ cm

13 positions

$$\varepsilon^2 = \gamma^2 \left(\langle x^2 \rangle \langle x'^2 \rangle - \langle x x' \rangle^2 \right) =$$

$$= \gamma^2 \left\{ \left[\sum_{j=1}^{N_b} \frac{A_j}{A_{tot}} (x_j - \langle x \rangle)^2 \right] \left[\sum_{j=1}^{N_b} \frac{A_j}{A_{tot}} \left[\sigma_j'^2 + (x'_j - \langle x' \rangle)^2 \right] \right] - \left[\sum_{j=1}^{N_b} \frac{A_j}{A_{tot}} x_j x'_j - \langle x \rangle \langle x' \rangle \right]^2 \right\}$$

$$x'_j = \frac{x_j - X_j}{L} \rightarrow \text{beamlet divergence}$$

$$A_{tot} = \sum_{j=1}^{N_b} A_j$$

rms spread in divergence

$$A_j = \sum_{i=1}^{\mathcal{N}_j} I_{i,j}$$

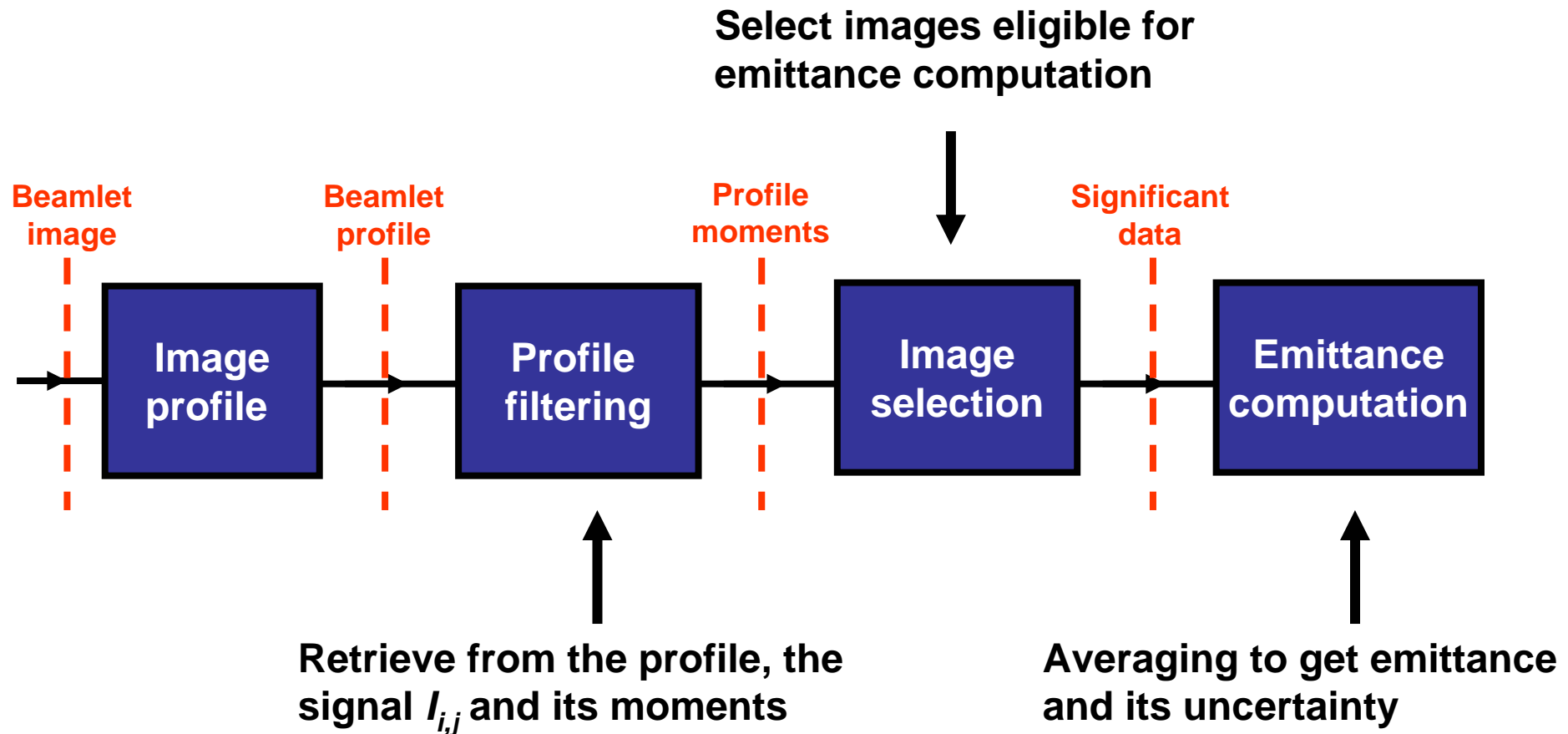
$$X_j = K_{cal} \sum_{i=1}^{\mathcal{N}_j} \frac{I_{i,j}}{A_j} i$$

$$\sigma_j' = \frac{K_{cal}}{L} \sqrt{\sum_{i=1}^{\mathcal{N}_j} \frac{I_{i,j}}{A_j} \left(i - \frac{X_j}{K_{cal}} \right)^2}$$



Data analysis algorithm

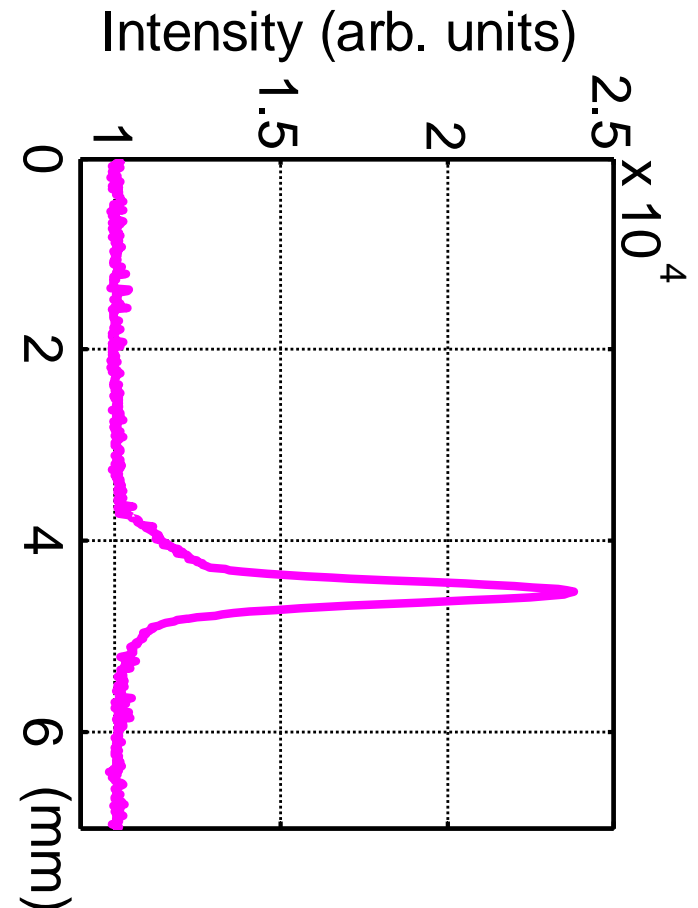
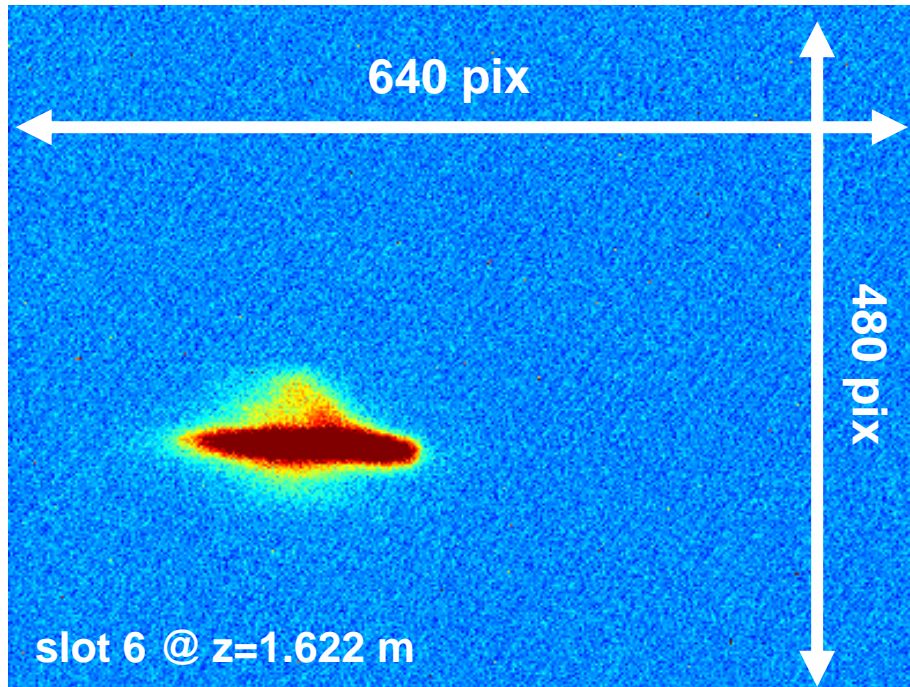
Automatic procedure, used both in control room during data taking and and for the following data analysis.





From beamlet to profile

Typical beamlet profile:
beam signal over a baseline.



SPARC

Baseline: constant, $1e4$ Intensity arb. units

$$\sigma'_j < 1 \text{ mrad}$$

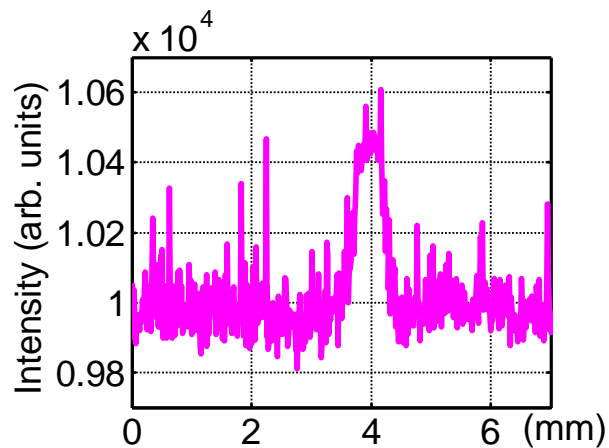
SNR: 2.5 - 30



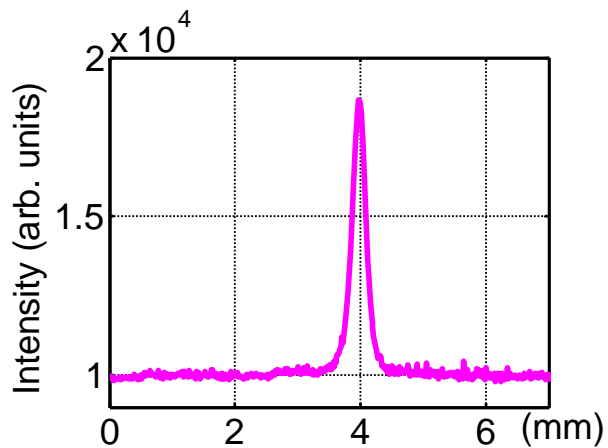


Typical beamlet profiles

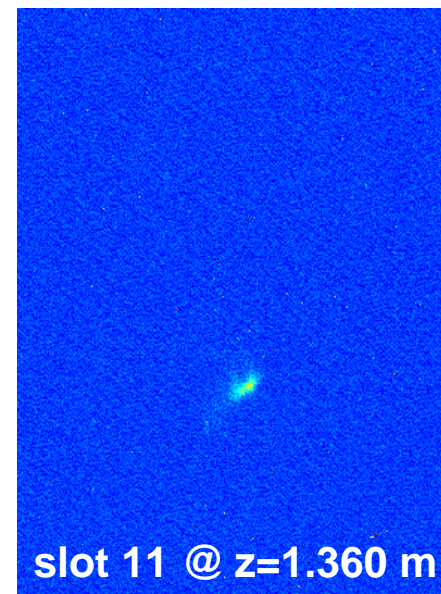
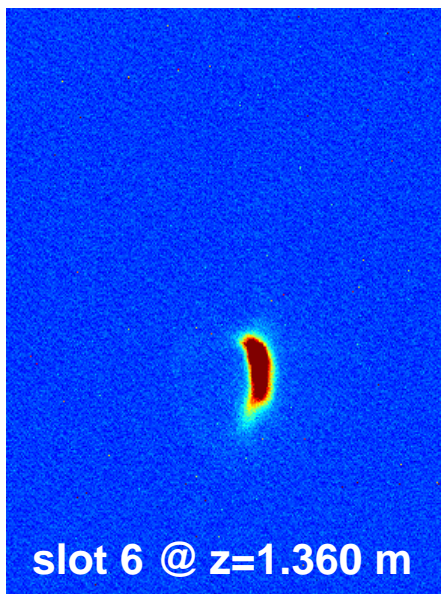
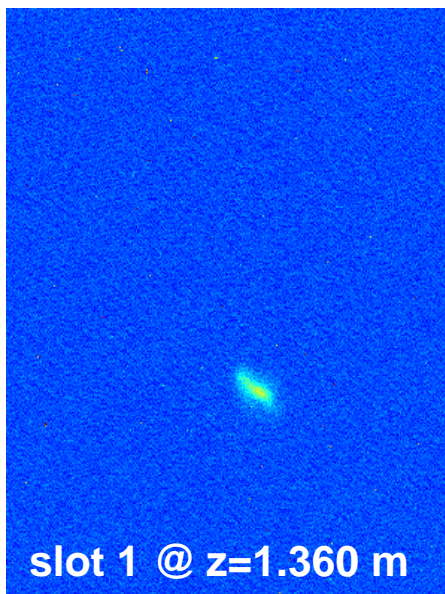
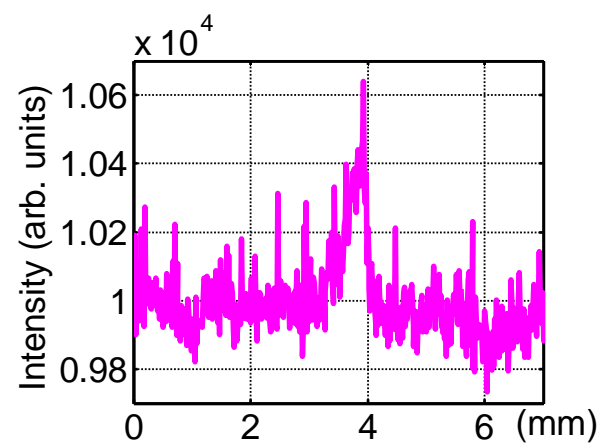
Lateral slit



Central slit

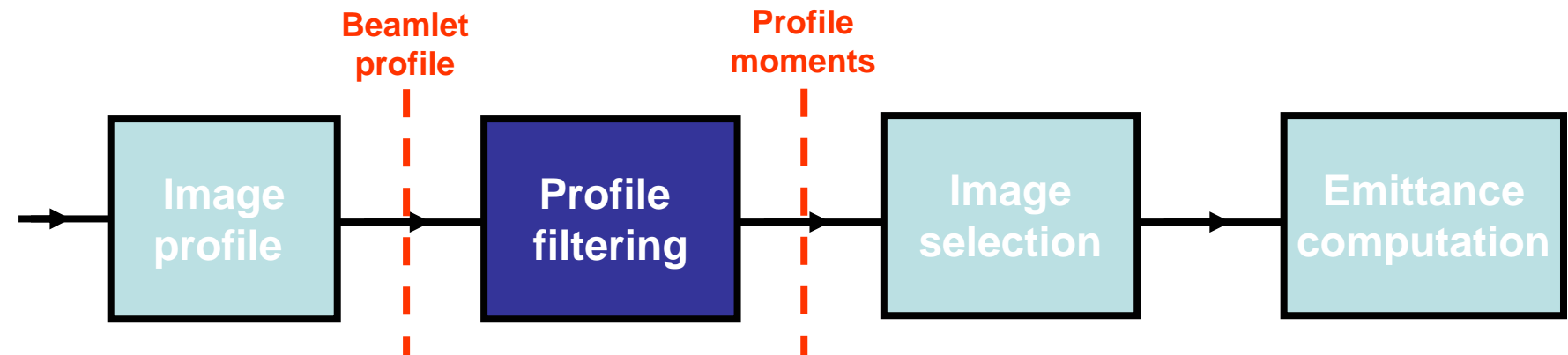


Lateral slit

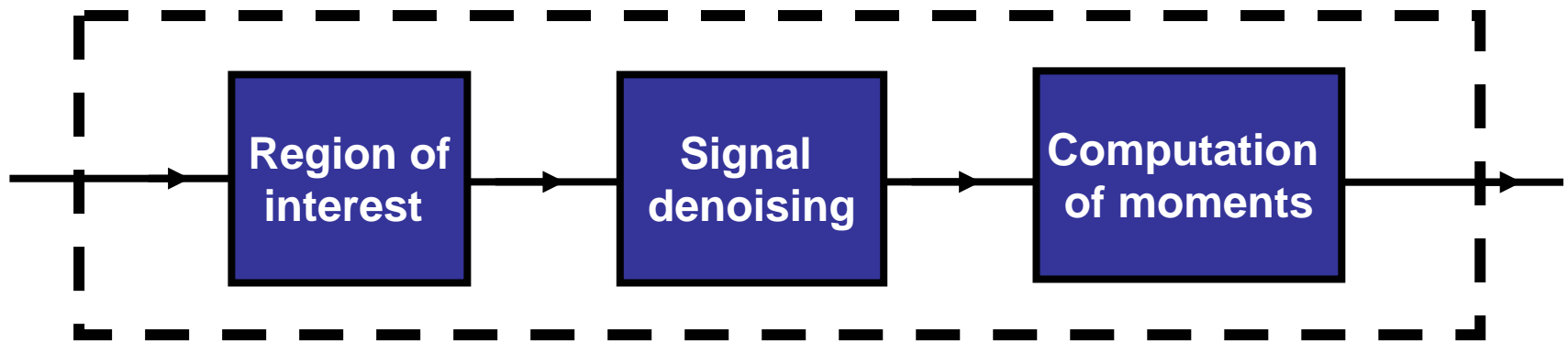




Profile filtering



Profile Filtering



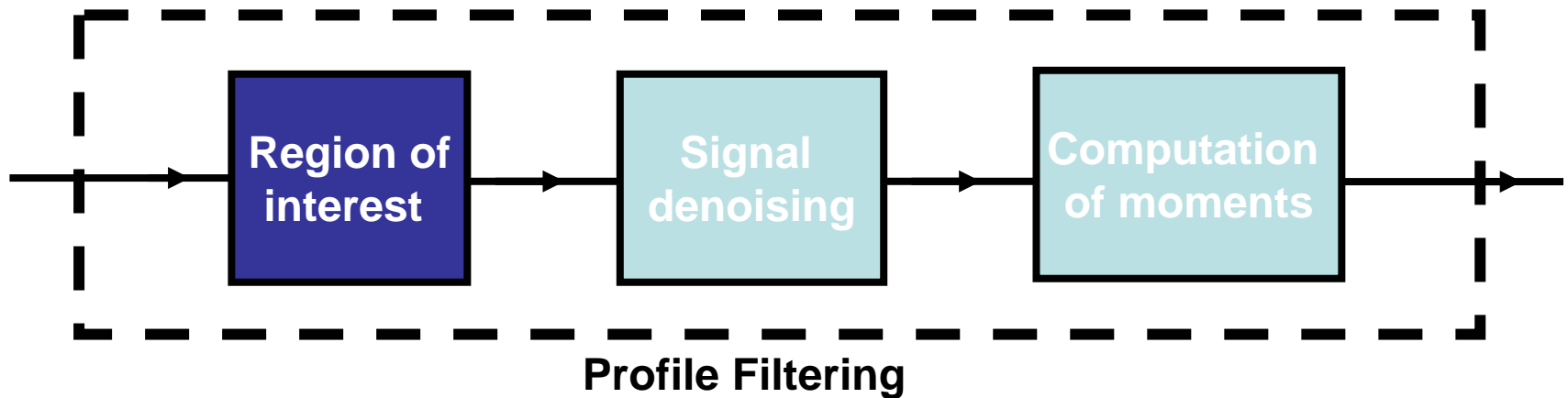


Profile filtering: Region Of Interest

To select the profile ROI the signal is fitted with a Gaussian function of area **A**, mean **m**, rms value **σ** and base line **h**.

Initial parameters are calculated from the smoothed profile (moving average).

To calculate the initial values for base line **h** and rms width **σ** , an initial window corresponding to a width that would have a signal with angles spread **4 times bigger than our maximum value**, centered around the maximum is taken; the base line is calculated averaging all the pixel out of window, while the initial rms value will be that of the signal inside the window.





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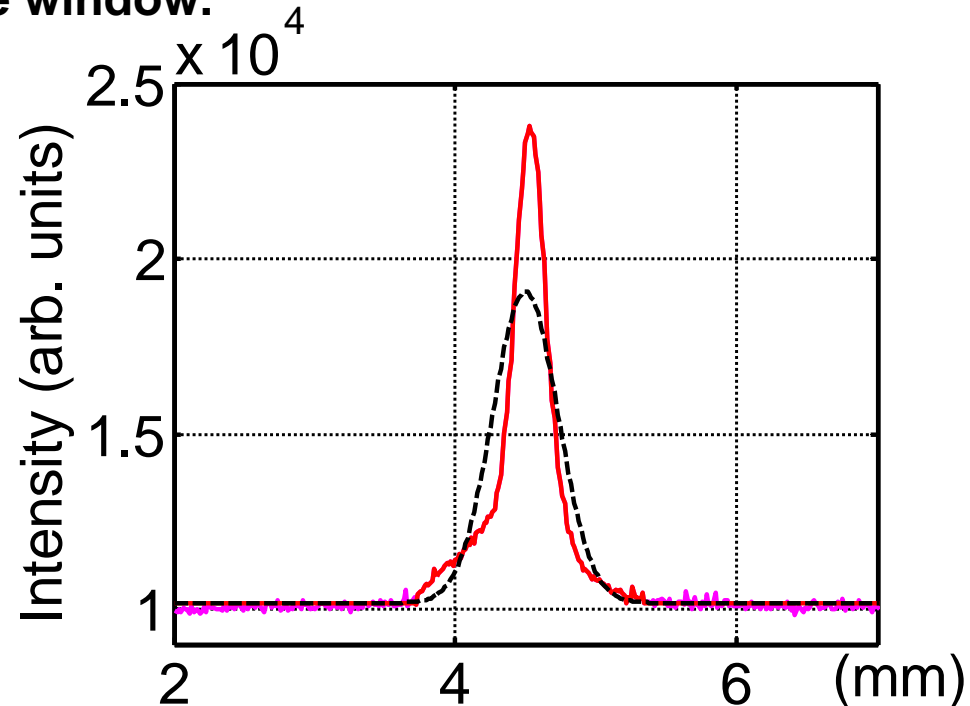
Region Of Interest:

$\pm 5\sigma$ around the mean **m**

Violet line: original signal

Red line: selected signal

Black line: Gaussian fit



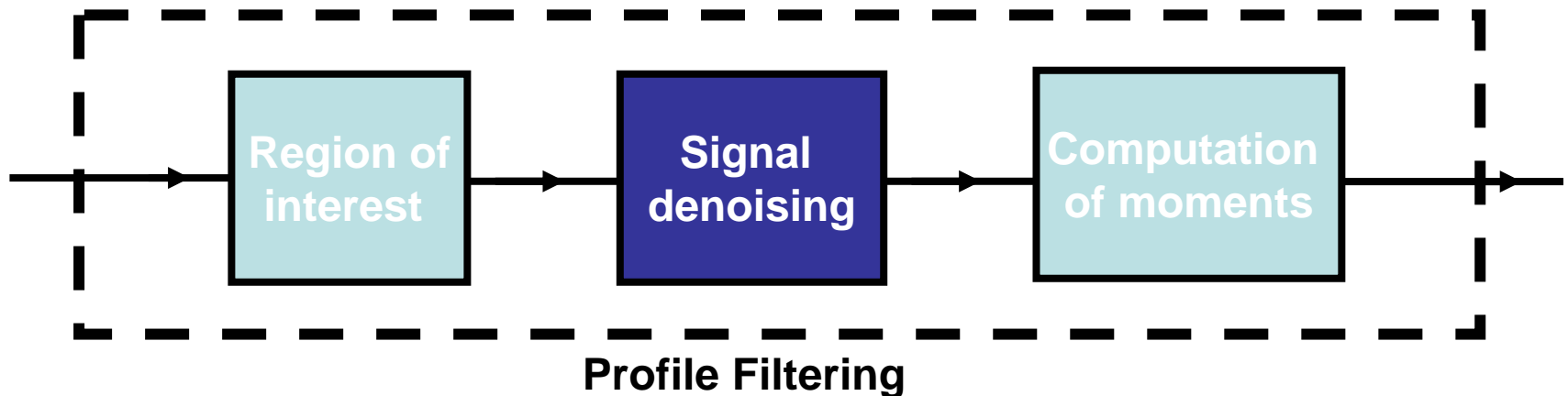


Profile filtering: signal denoising

The moments of the actual beamlet charge distribution are different from the parameters of the Gaussian fit used before for the ROI computation.

We consider the signal inside the ROI after the baseline subtraction.

Iterative procedure that computes profile centroid m and rms width σ , then shrinks the region of interest up to $\pm 3\sigma$ around m and eventually recomputing the same parameters again. The procedure stops when new values match the previous iteration ones and it converges typically after 4-5 iterations.





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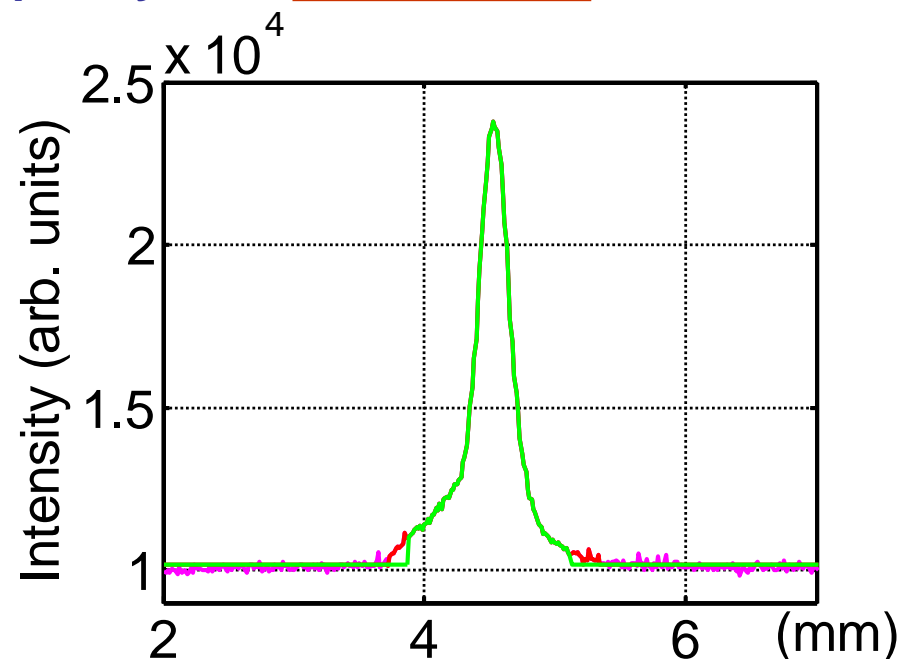
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Violet line: original signal

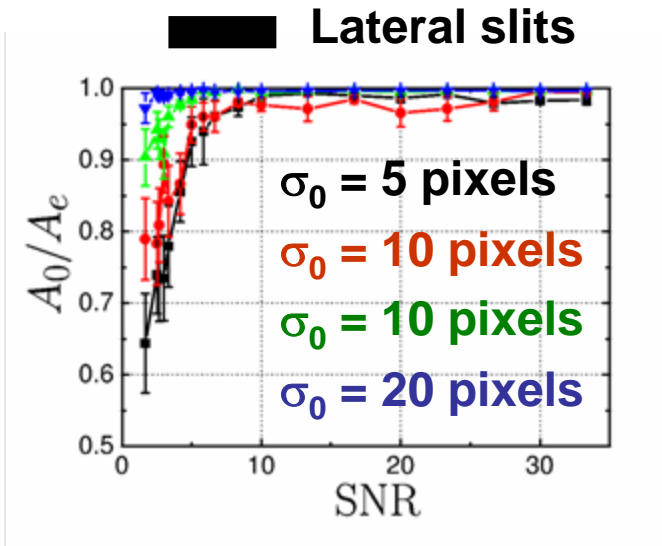
Red line: selected signal

Green line: filtered signal





Profile filtering validation



Averaging over 50 noisy Gaussian signals
 (error bars st. dev. of the average)

A_0, σ_0 Original signal parameters

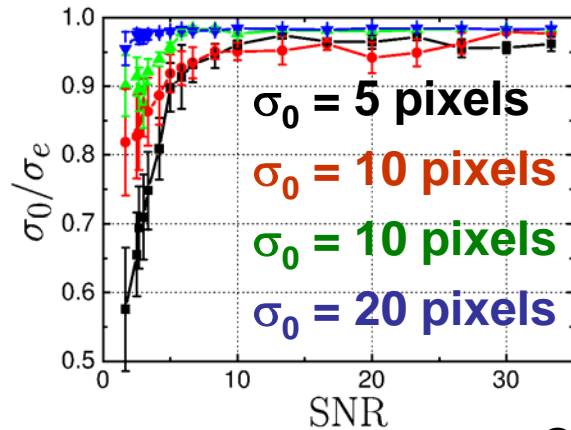
A_e, σ_e reconstructed signal parameters

A_0/A_e differs from unity because of the fraction of the beamlet left out from reconstruction which decreases with increasing of SNR.

The precision (error bars) increases with σ_0 .

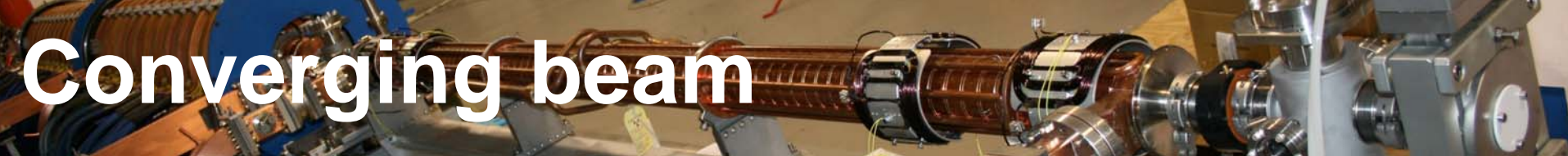
Noise affects the tails of the signal and σ_0/σ_e is more sensible to it.

Additional error correction needed for lateral slits (low SNR).

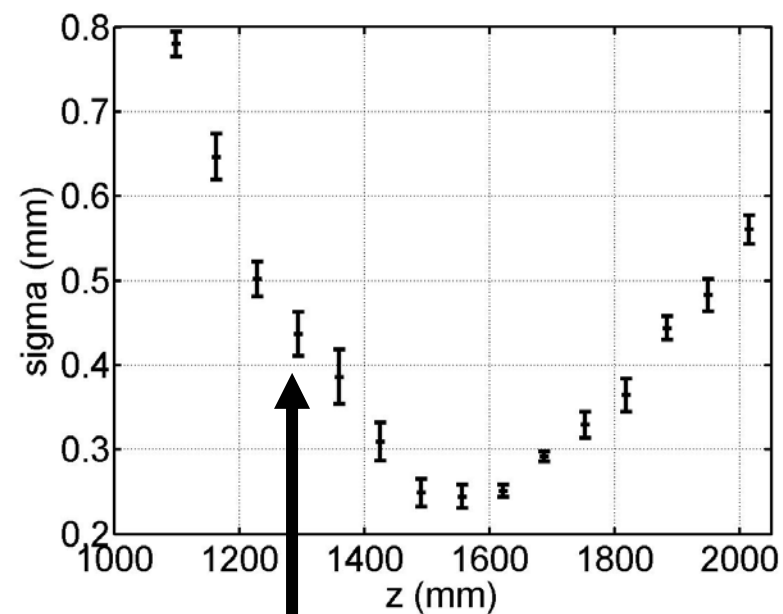


Central slits



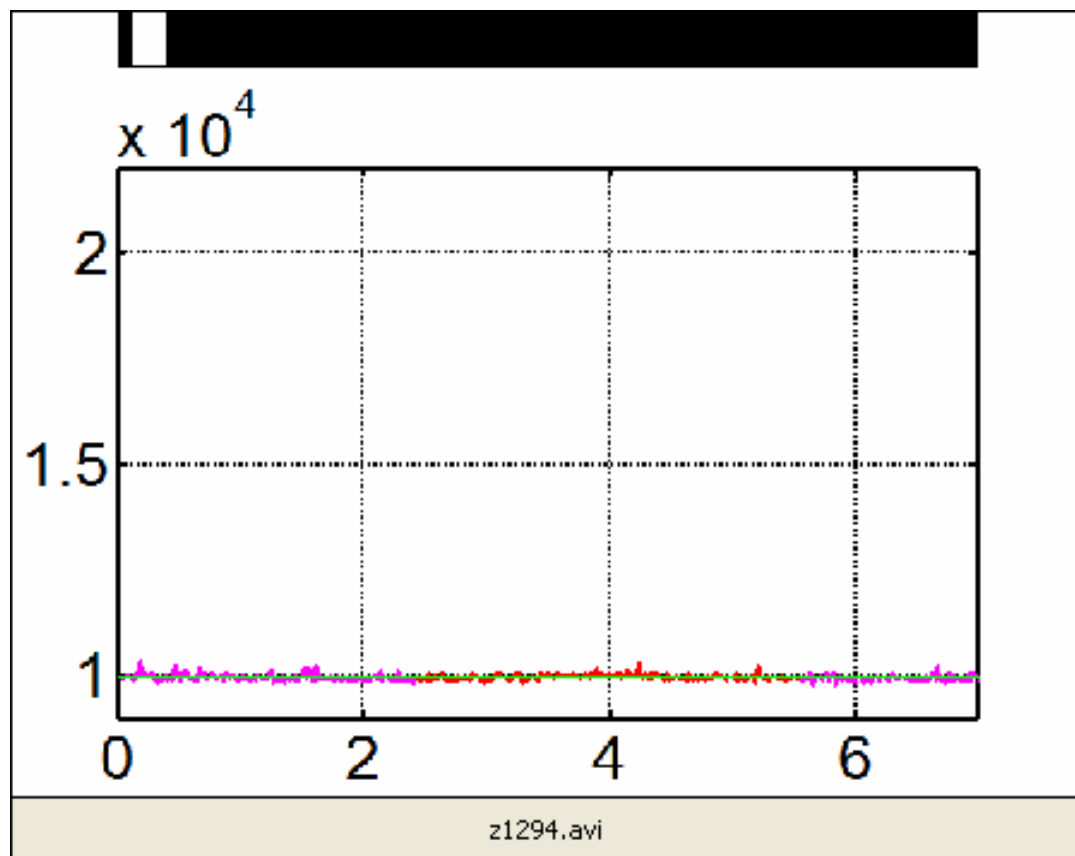


Converging beam



Last
slit

First
slit



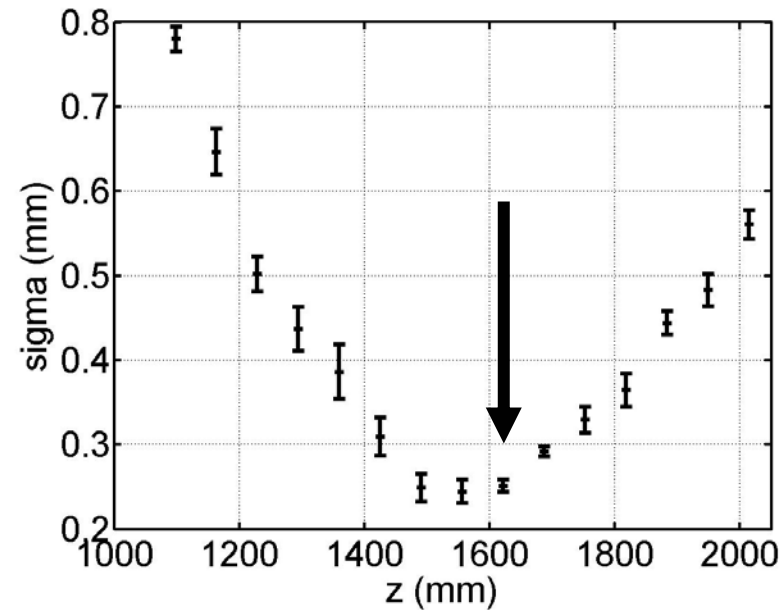
Violet line: original signal

Red line: selected signal

Green line: filtered signal



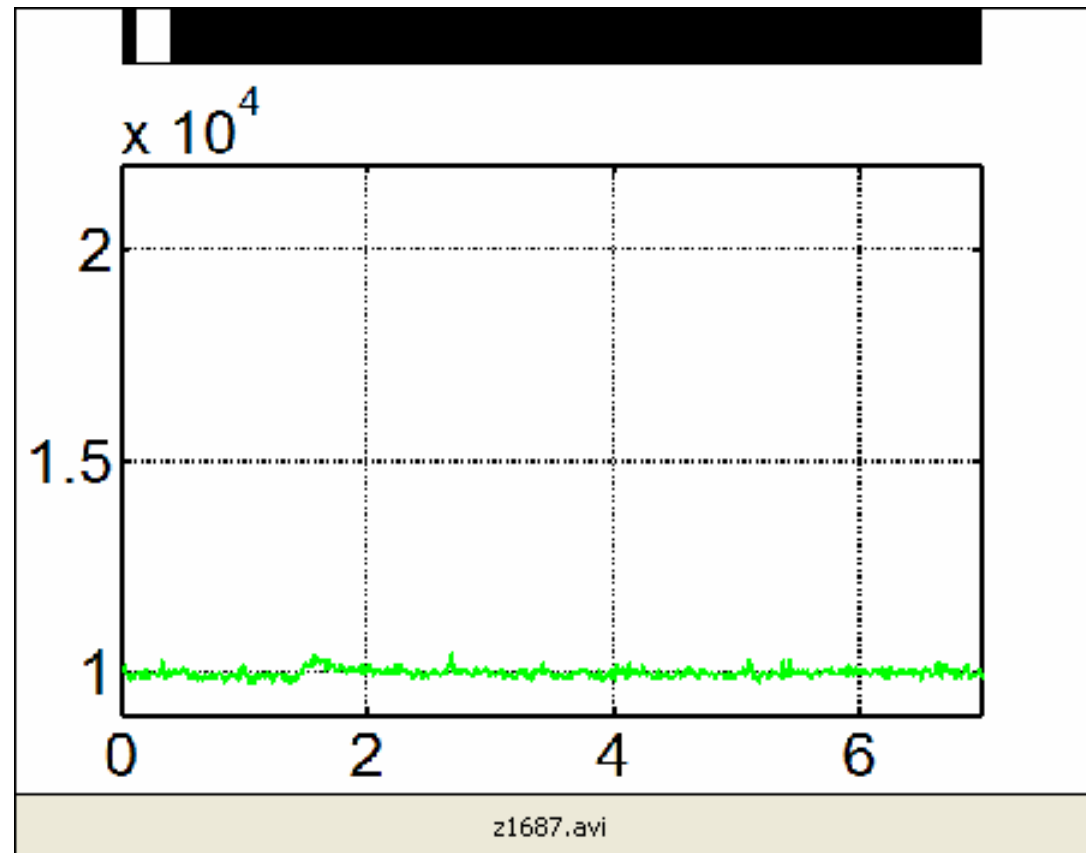
Diverging beam



Diverging beam: bigger centroids swing

**Last
slit**

**First
slit**



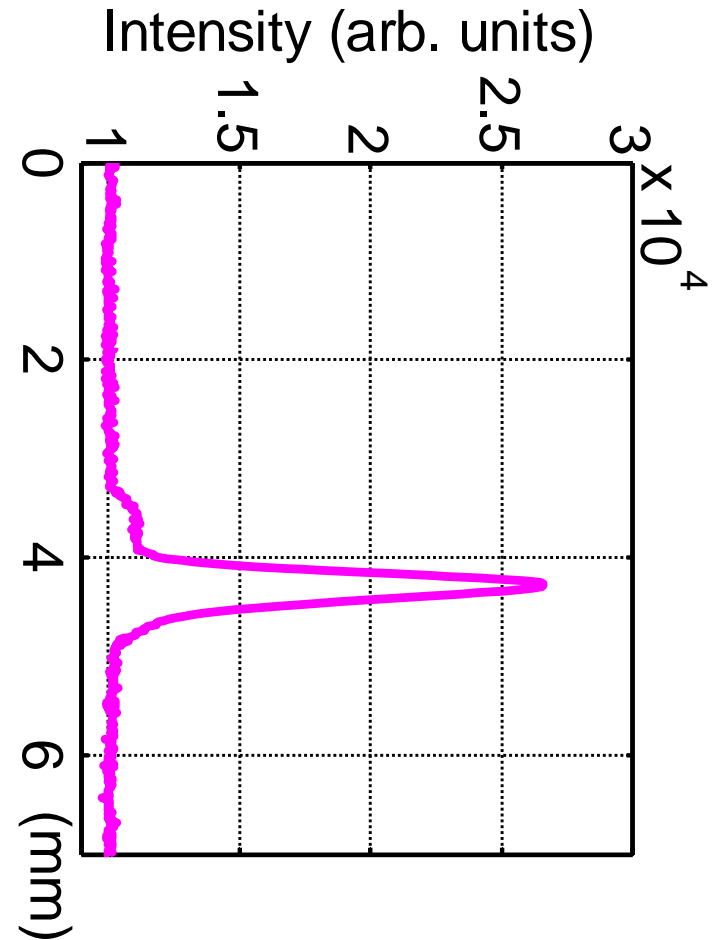
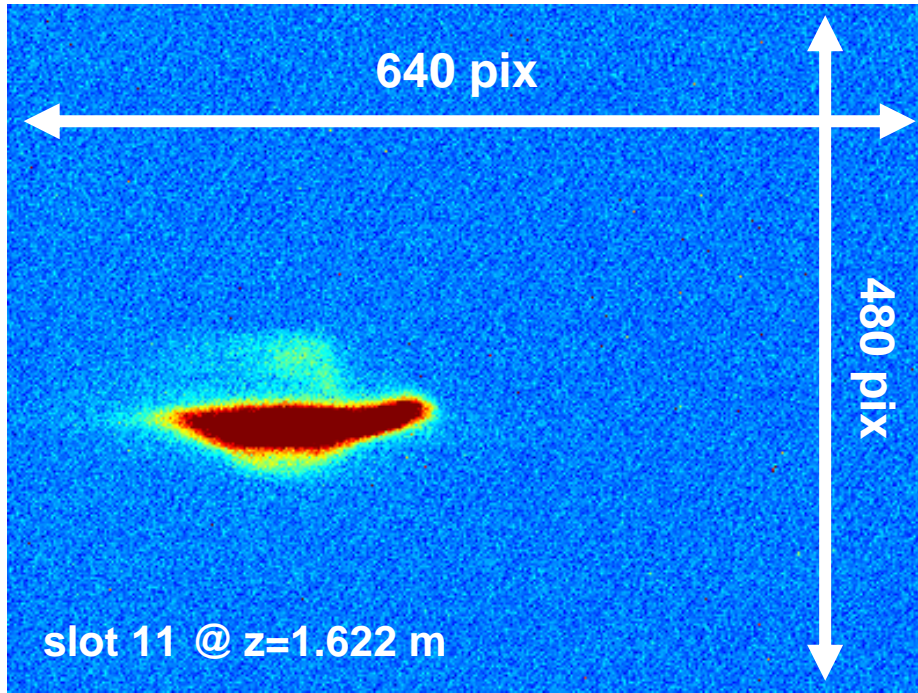
Violet line: original signal

Red line: selected signal

Green line: filtered signal



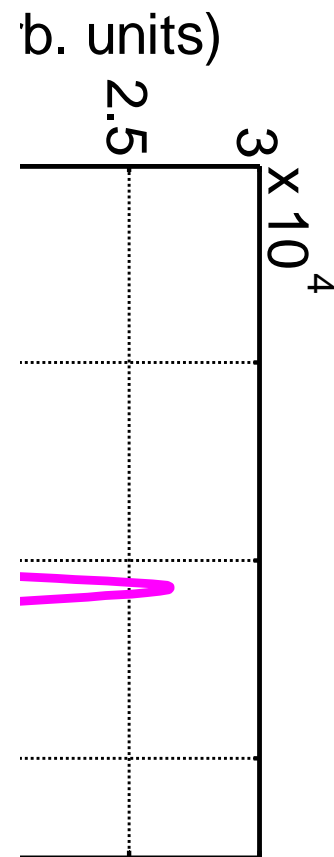
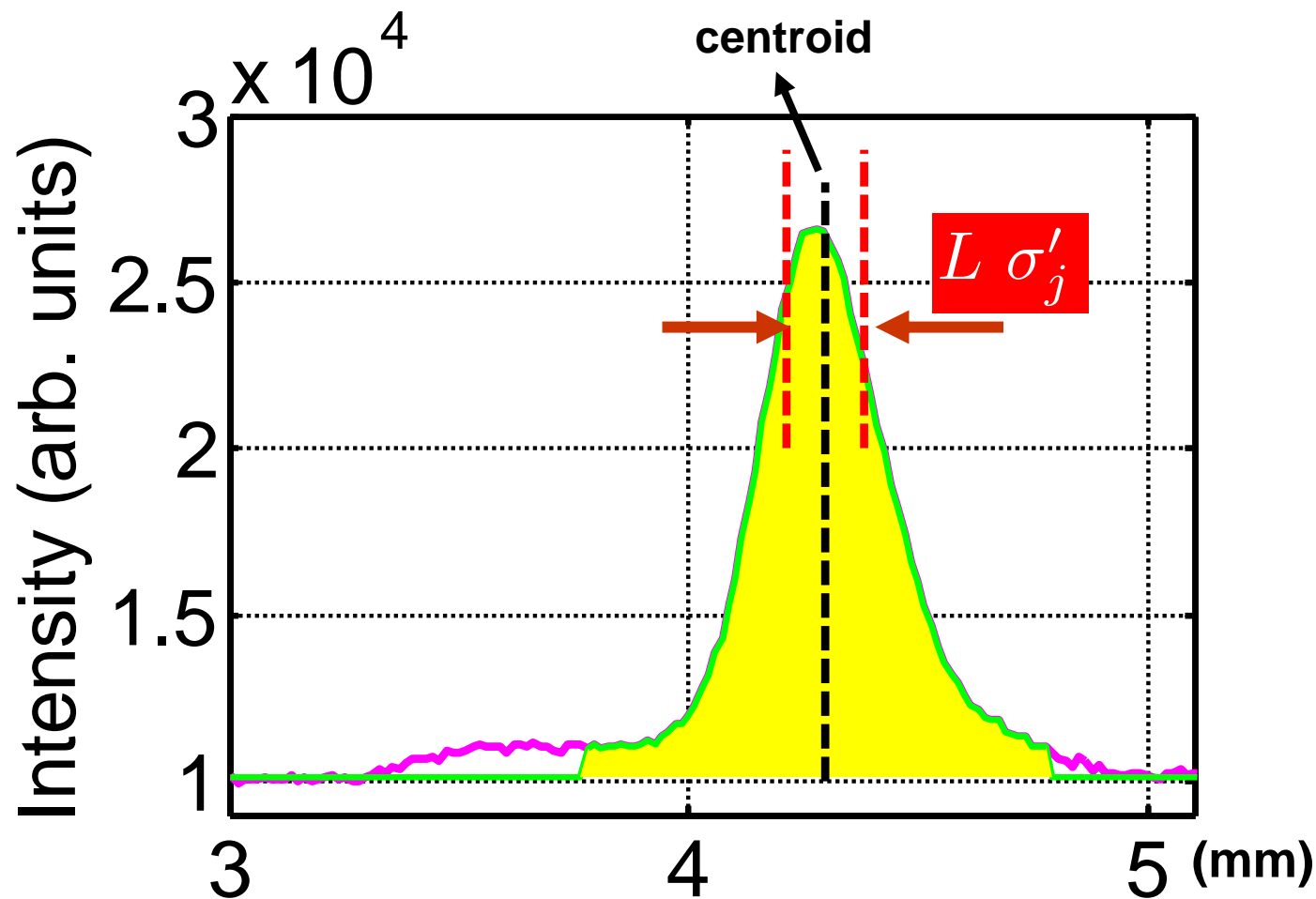
Profile filtering critical case



“Two” signals with one much bigger than the other.



Profile filtering critical case

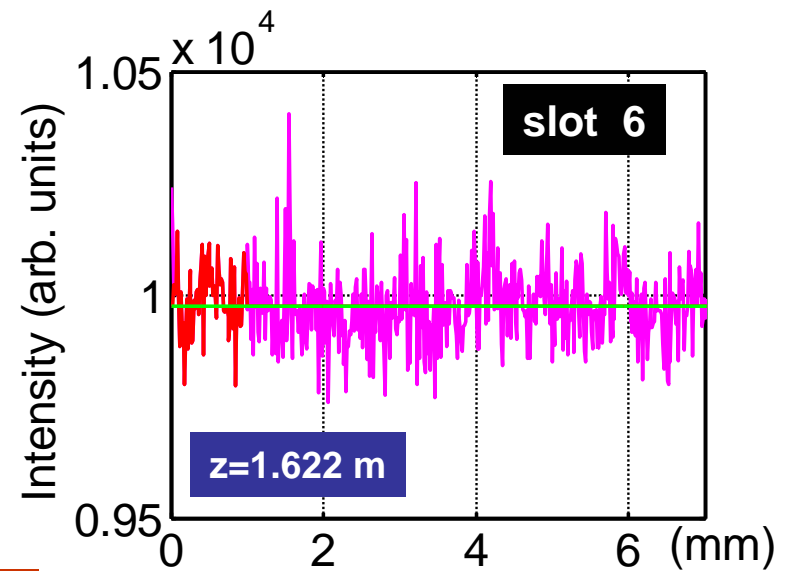
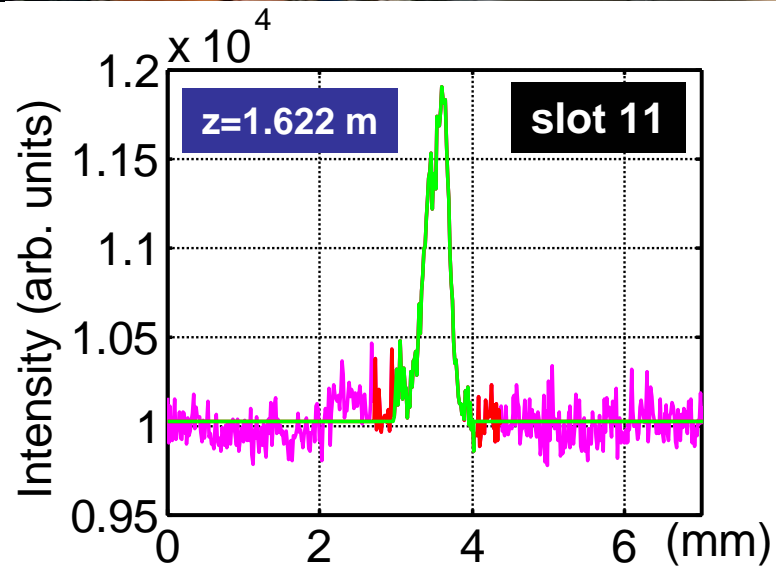


$$\frac{\text{Signal Charge} - \text{Approx. Charge}}{\text{Signal Charge}} < 6\%$$

“Variable” charge cut



Profile filtering: other examples



Need of an image selection criteria

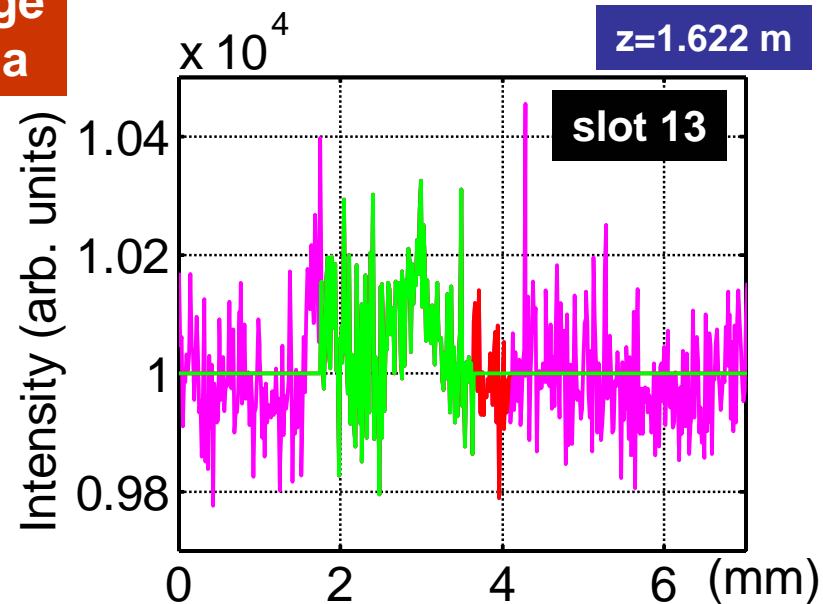
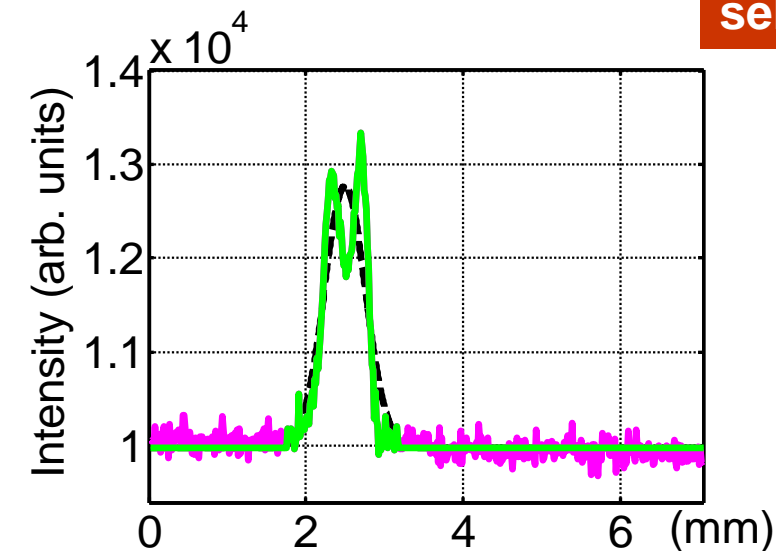
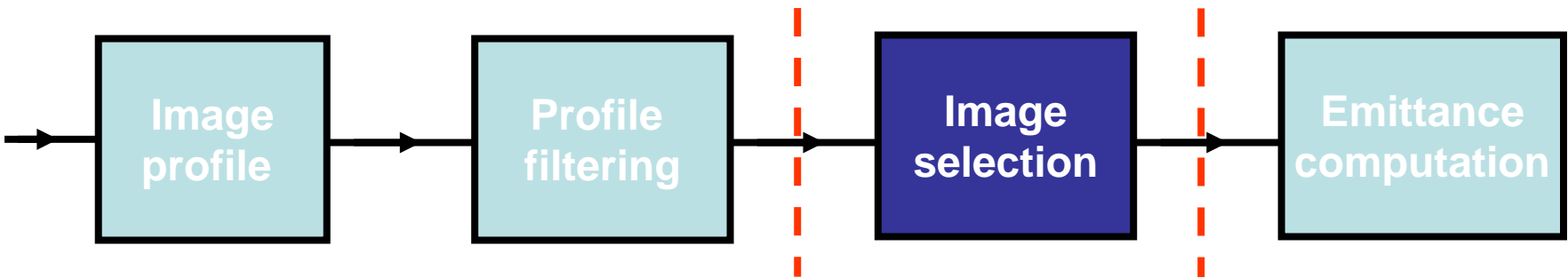




Image selection criteria

Profile
moments

Significant
data



Comparison of images
from the same slit



Consistency check
on each image

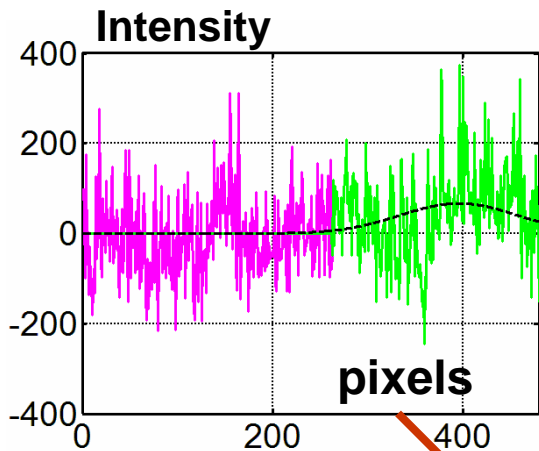
Comparison of images
from different slit



Single image correction

The program may fit noise resulting in beamlet divergence bigger and/or area is smaller than typical values.

Thresholds on the maximum spread in divergence and on the minimum signal area.



Measurement footprint

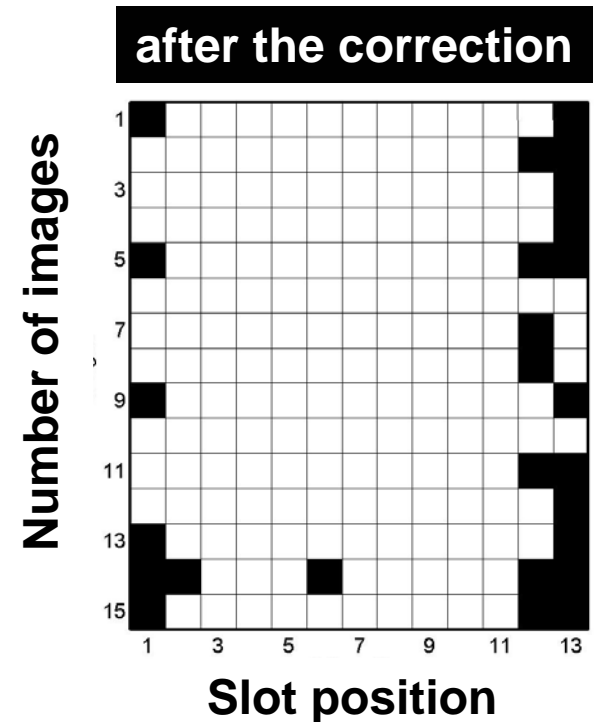
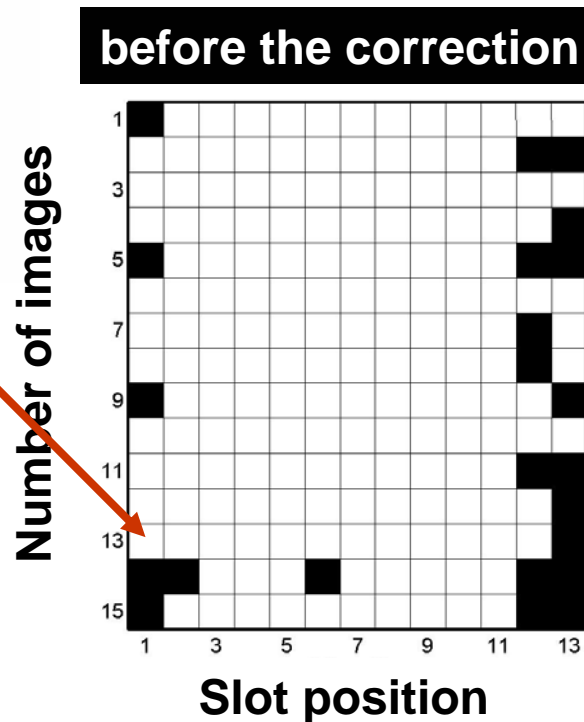


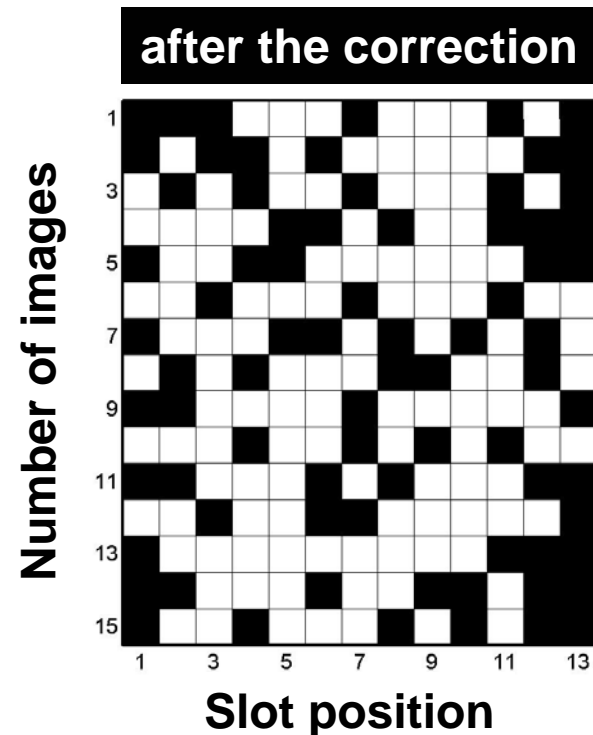
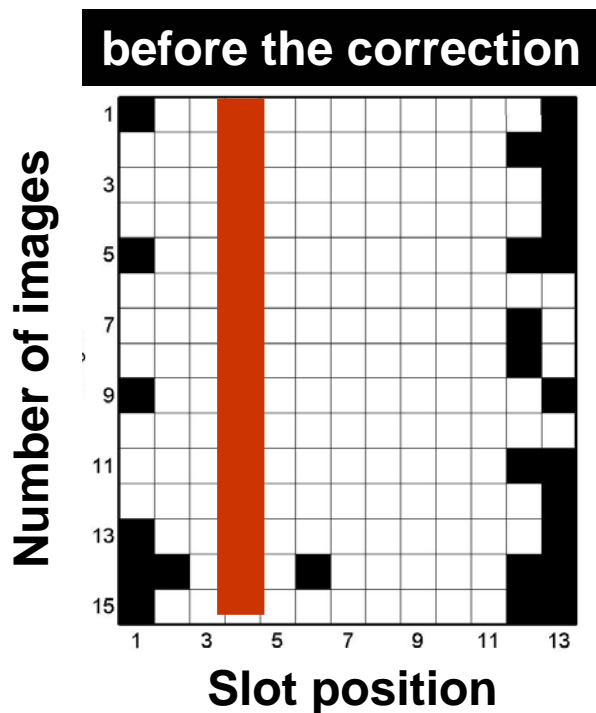


Image selection: average correction

Discard systematically bad data, at the price of loosing some good one.

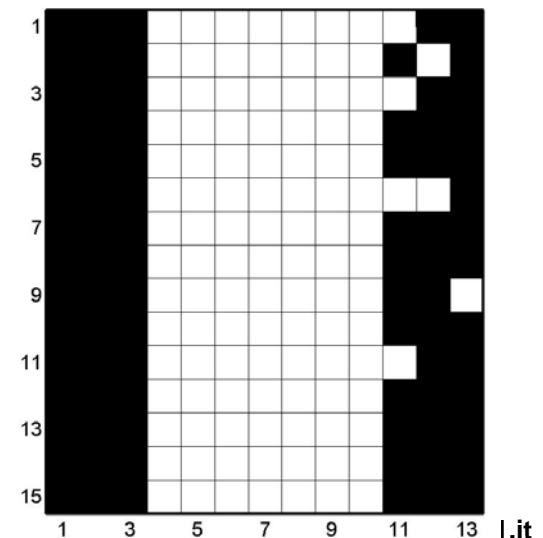
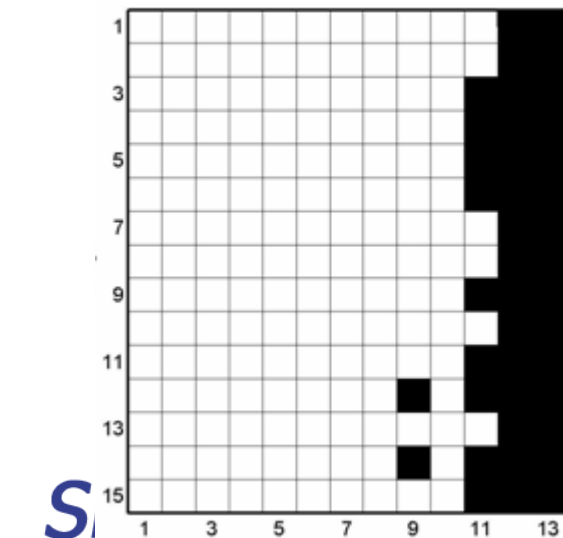
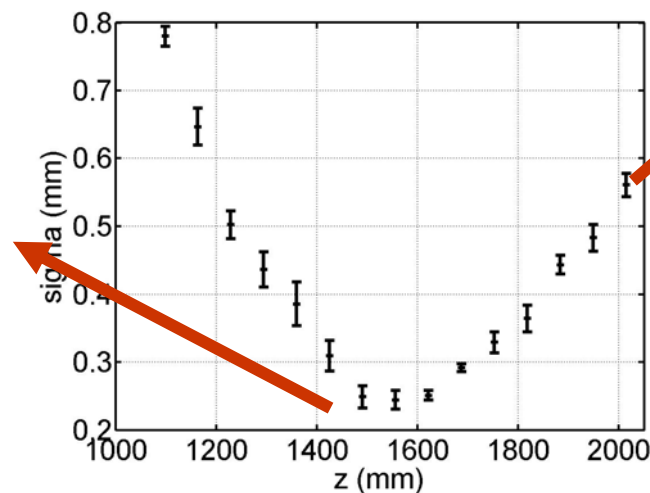
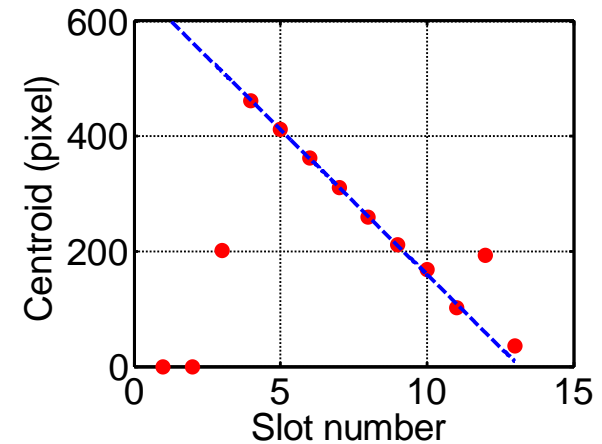
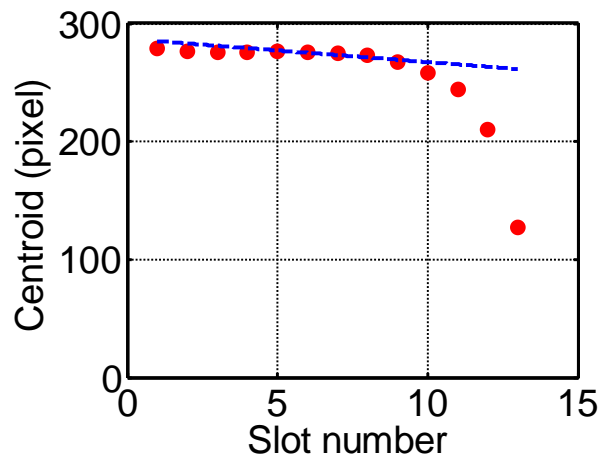
Average and standard deviation s_d on the slit values (area, centroid and beamlet spread) are computed. If a value is outside $\pm 1.5 s_d$ the profile is discarded.

If the average area is too small (below a threshold), all the slot is thrown.



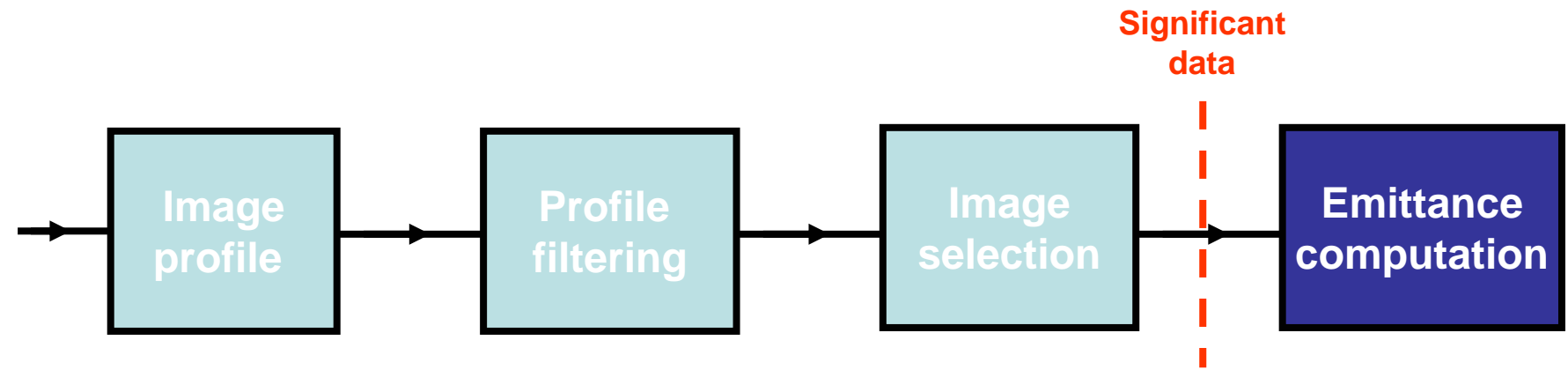


Lateral slit is tagged as wrong if their average centroid value is too different from the one predicted by the linear interpolation of the central slit centroids.



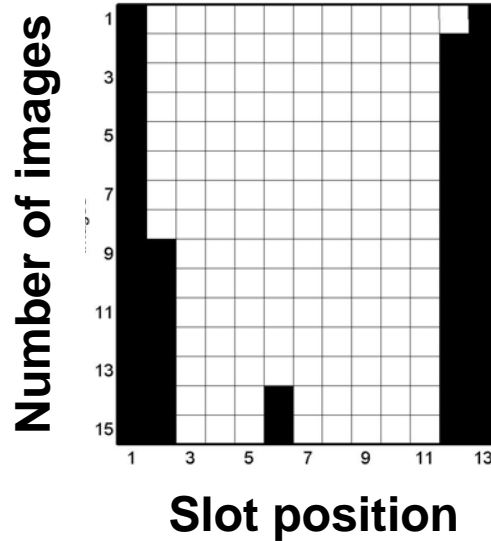
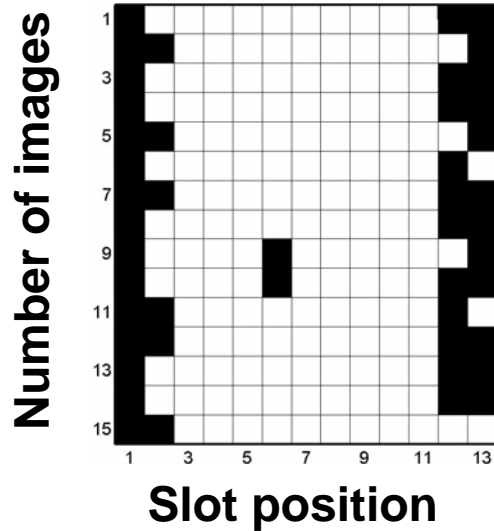


Emittance computation



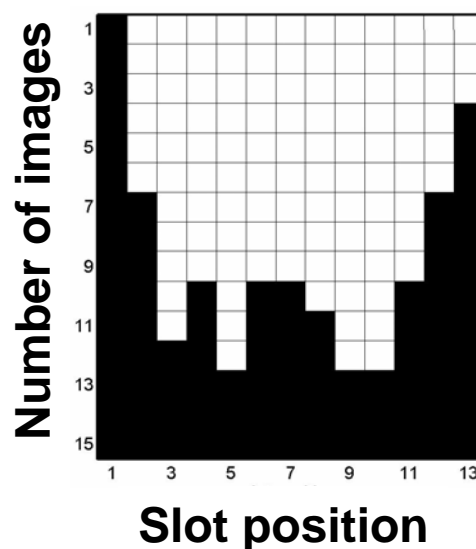
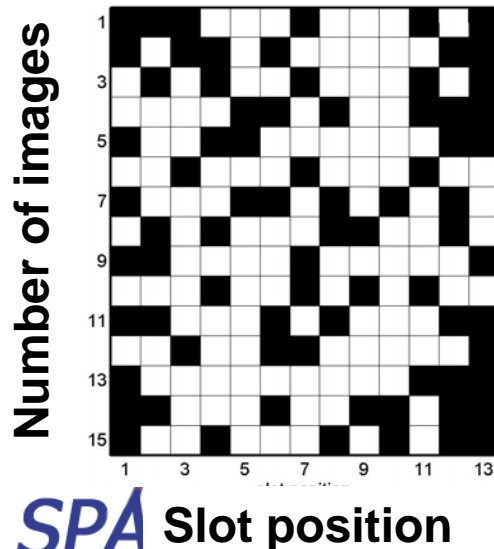


Data shuffling



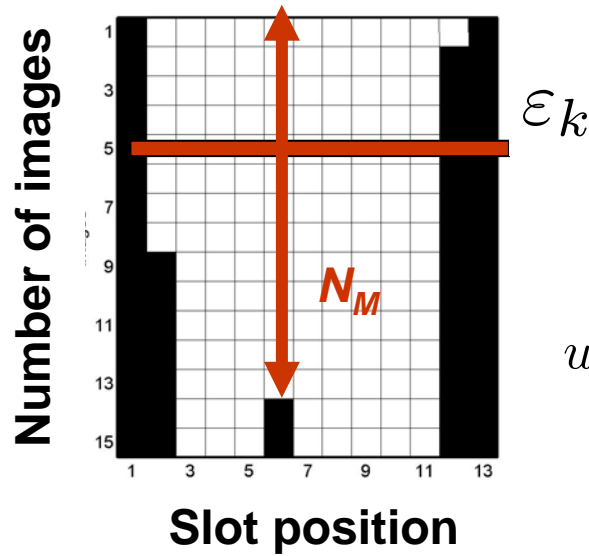
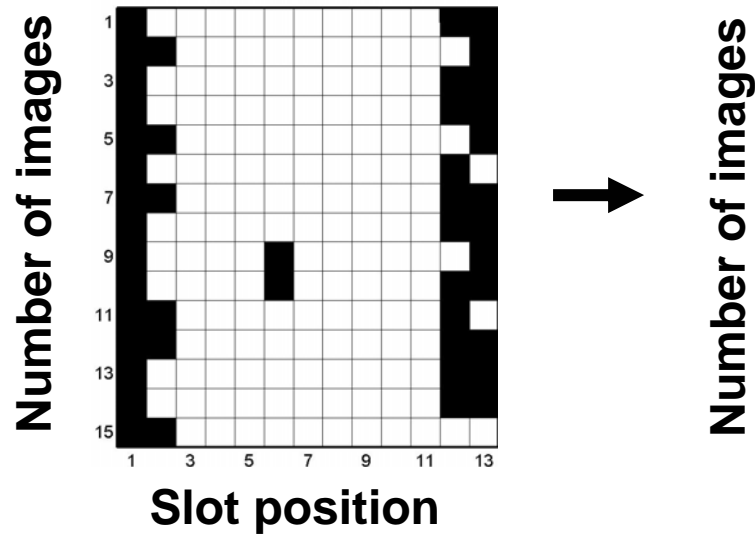
Each square is
a different beam

Each square is
equivalent to the ones
on the same column.



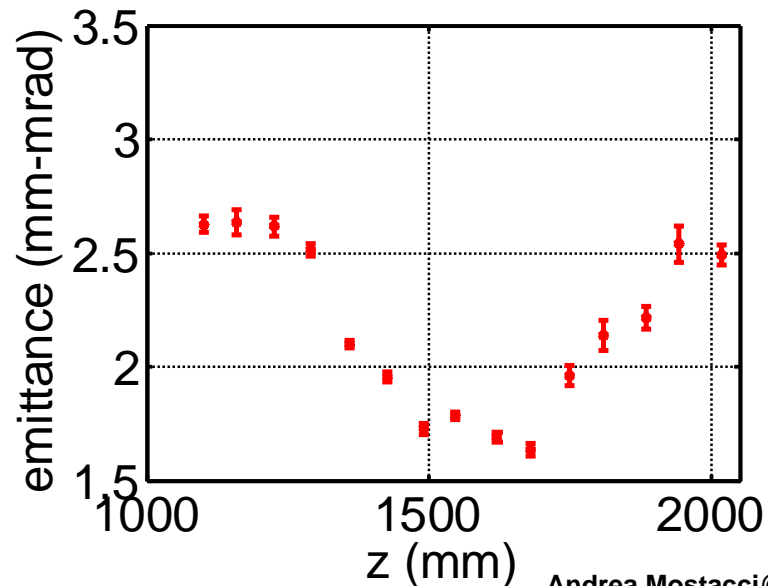
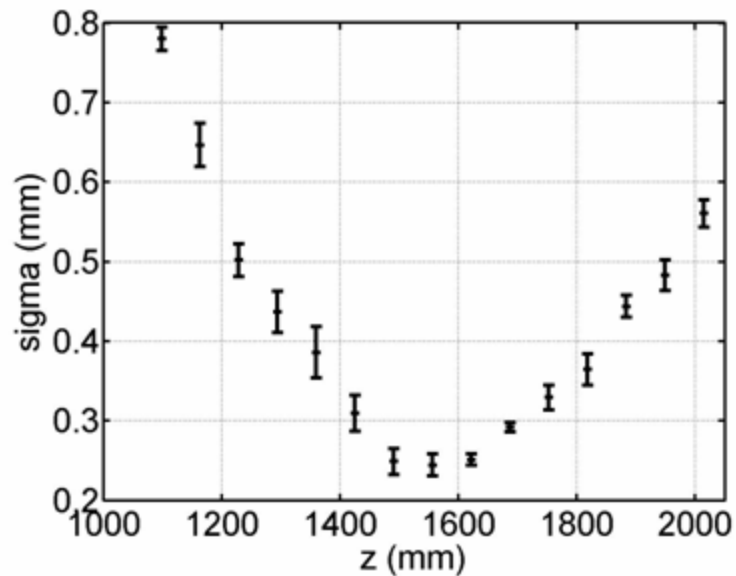


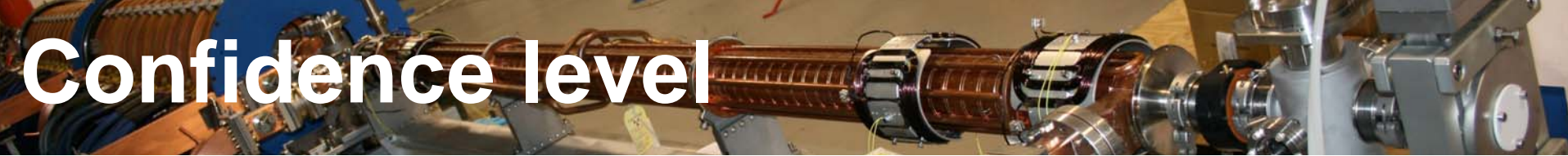
Measurement uncertainty



$$\bar{\varepsilon} = \frac{\sum_{k=1}^{N_M} \varepsilon_k}{N}$$

$$u(\varepsilon) = \sqrt{\sum_{k=1}^{N_M} \frac{(\varepsilon_k - \bar{\varepsilon})^2}{N_M(N_M - 1)}} = \frac{\sigma}{\sqrt{N_M}}$$





Confidence level

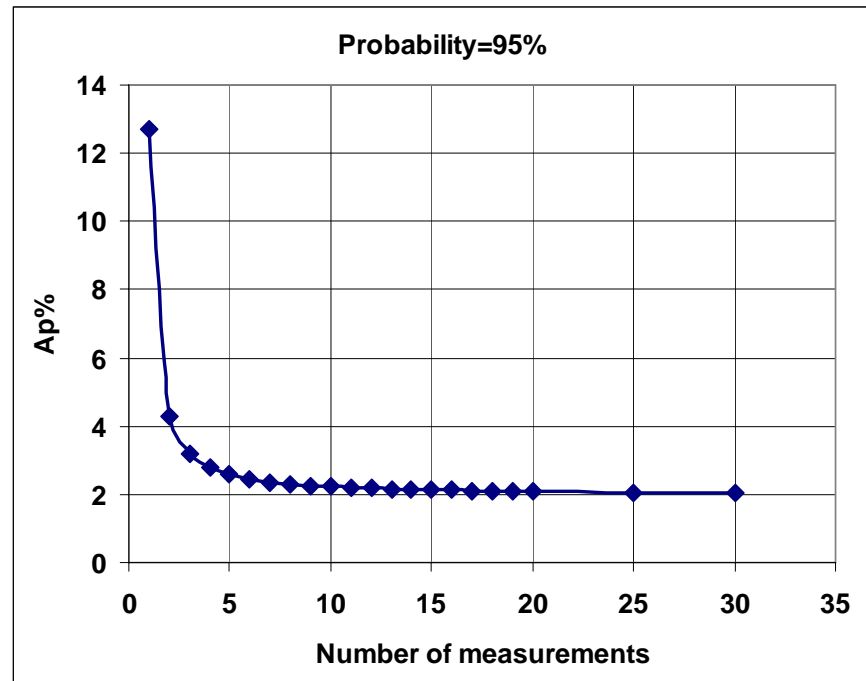
In comparison between measurements and/or simulations the error bar on experimental data are equal to the statistical error multiplied by a factor depending on the confidence level (95%) that gives a measure of the goodness of the comparison.

$$\varepsilon = \bar{\varepsilon} + A_{P\%} \frac{\sigma}{\sqrt{N}}$$

N =number of measurements

σ =standard deviation

$AP\%$ = a factor given by the t-distribution corresponding to a defined $P\%$ probability

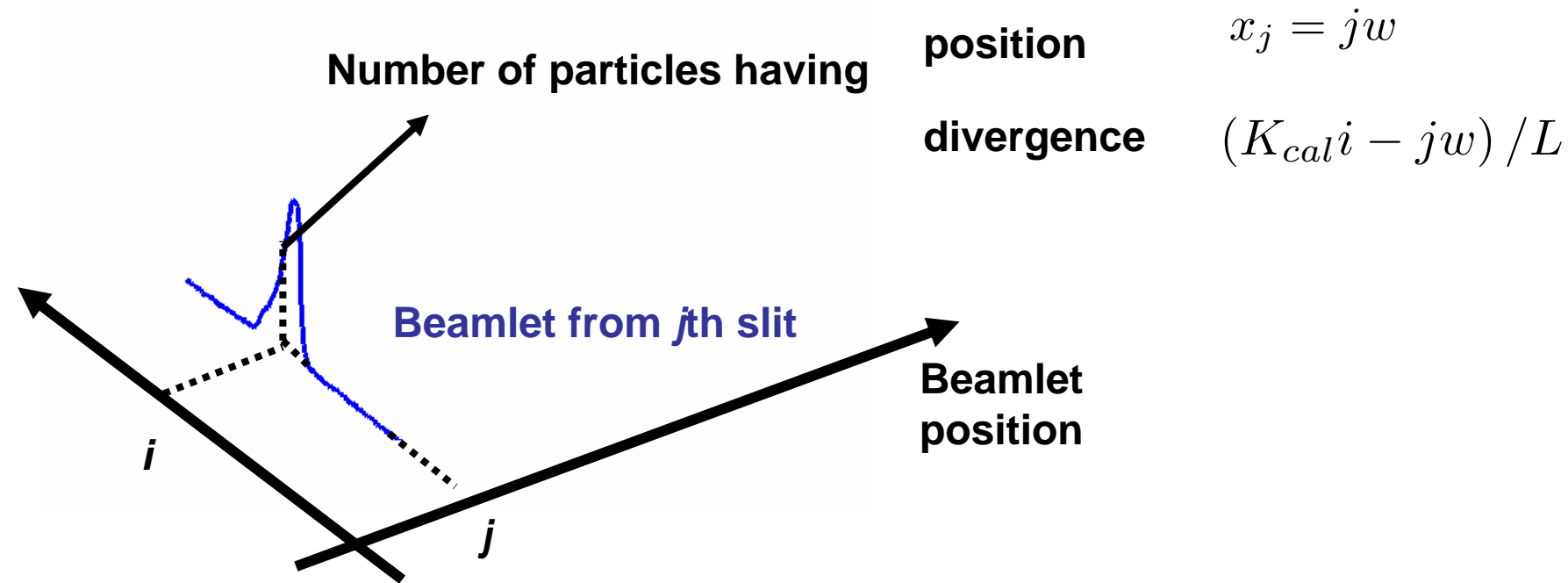


■ Assumption: the set of observations follow a normal distribution



Trace space reconstruction (I)

Graphical reconstruction of the phase space to retrieve emittance and Twiss parameters and permit better insight on beam dynamics.

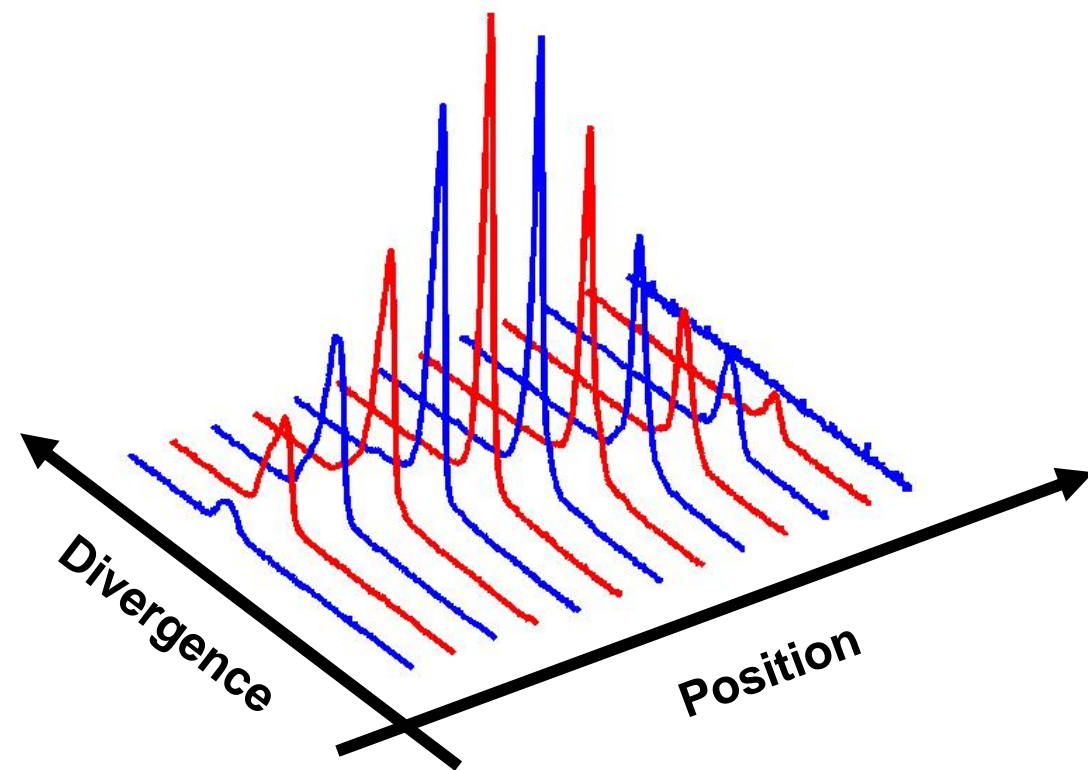


To combine the trace space in a data matrix, one needs to shift the vector $\overline{I_{i,j}}$ changing the index $i \rightarrow i - jw/K_{cal}$ (the divergence unit being K_{cal}/L) and use it as the j th of N_b columns (filling with zeros the missing data).

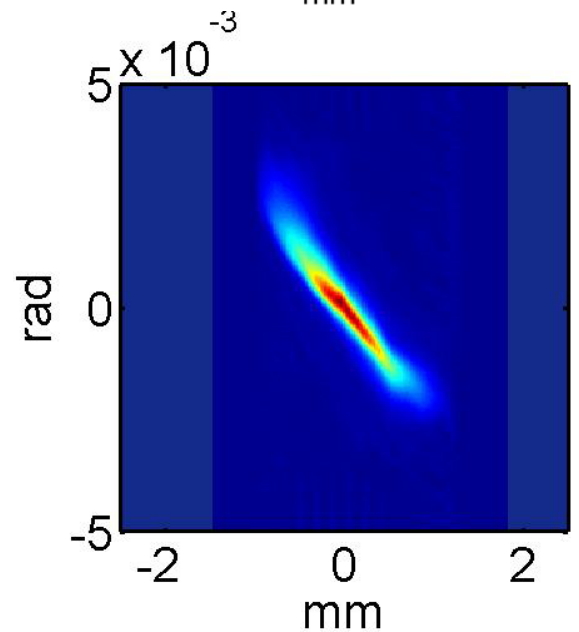
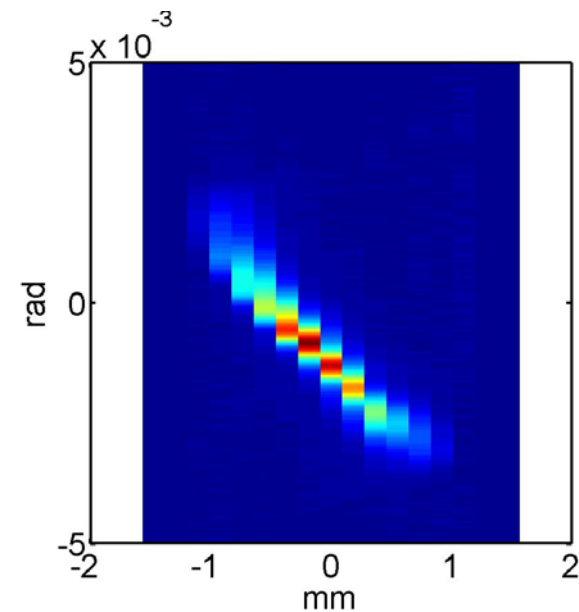


Trace space reconstruction (II)

$z=1.294$ m

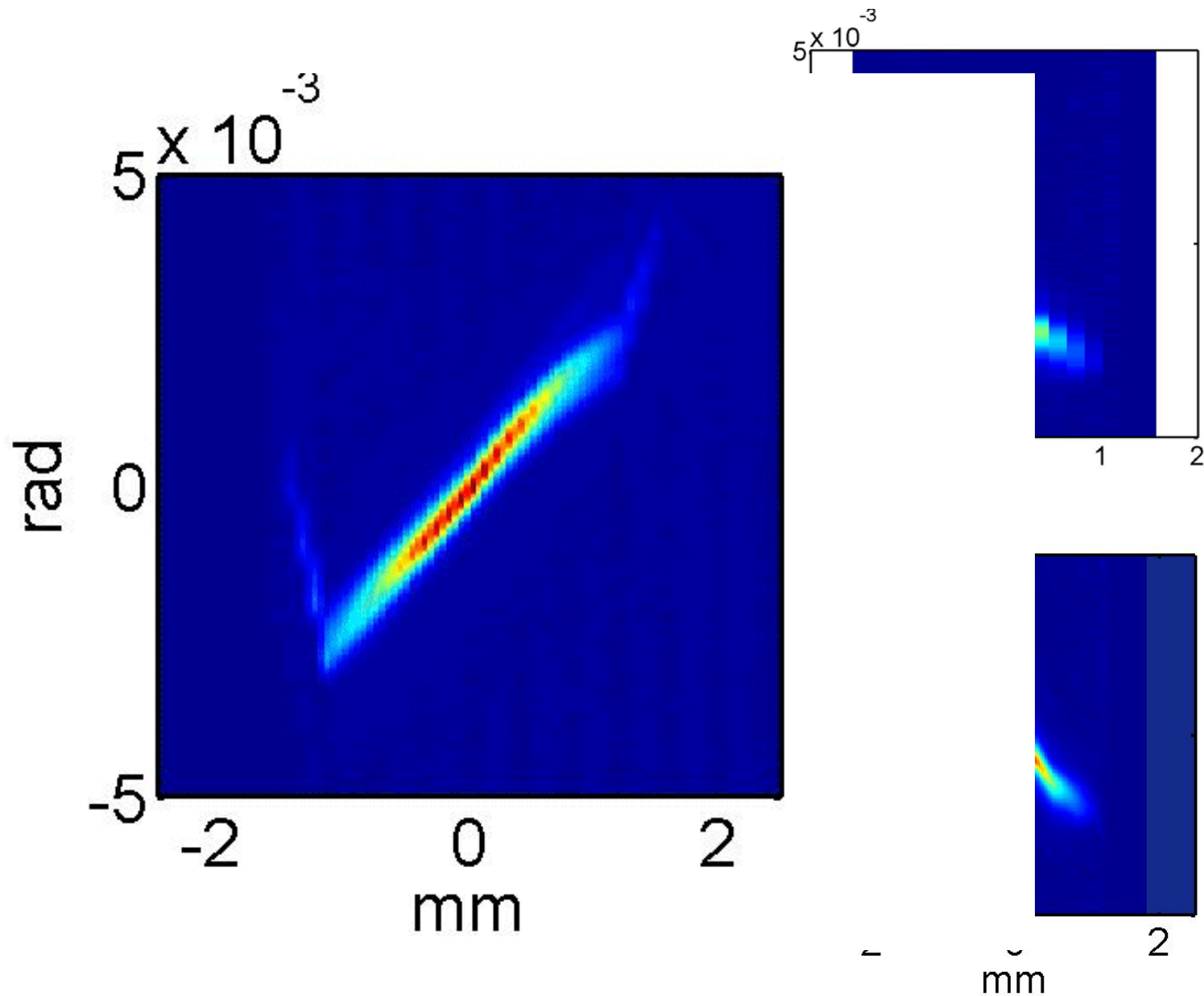
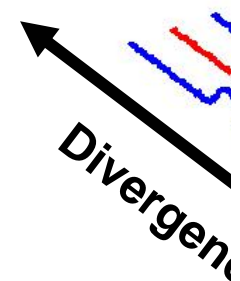


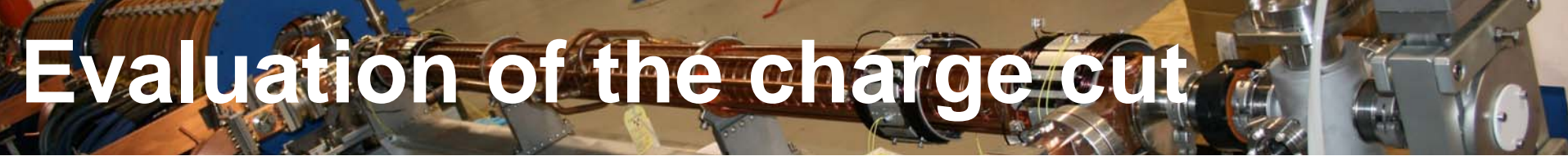
Interpolation along
the trace space axis.





Trace space reconstruction (II)





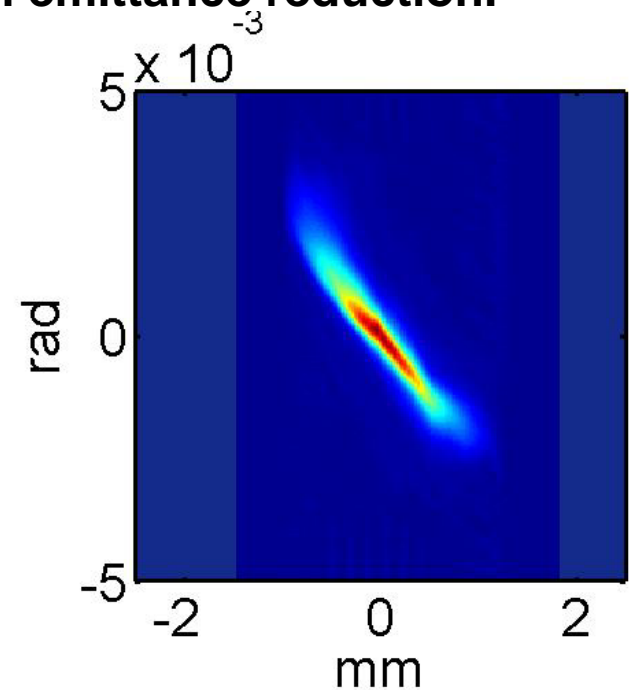
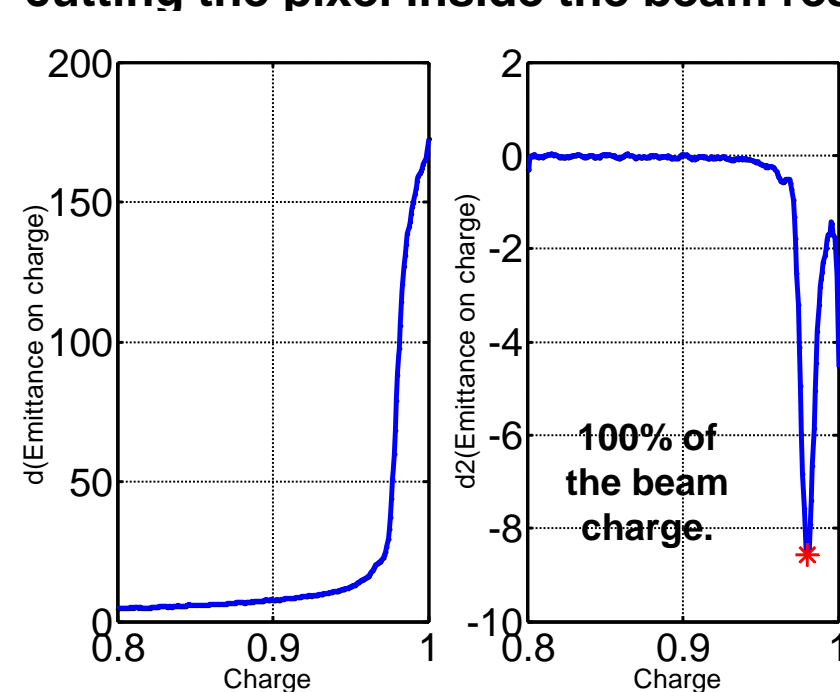
Evaluation of the charge cut

Profile filtering introduces a charge cut.

SPARC-EBD-07-003

Every pixel of a trace space is associated to its contribution to the total emittance, and all the pixels are sorted. Starting from the ones with highest contribution (outside the beam core), they are cut away calculating the first and second derivative of the emittance with respect to the charge.

Cutting the pixel outside the beam causes a strong emittance reduction, while cutting the pixel inside the beam results in a small emittance reduction.





Emittance from trace space: results

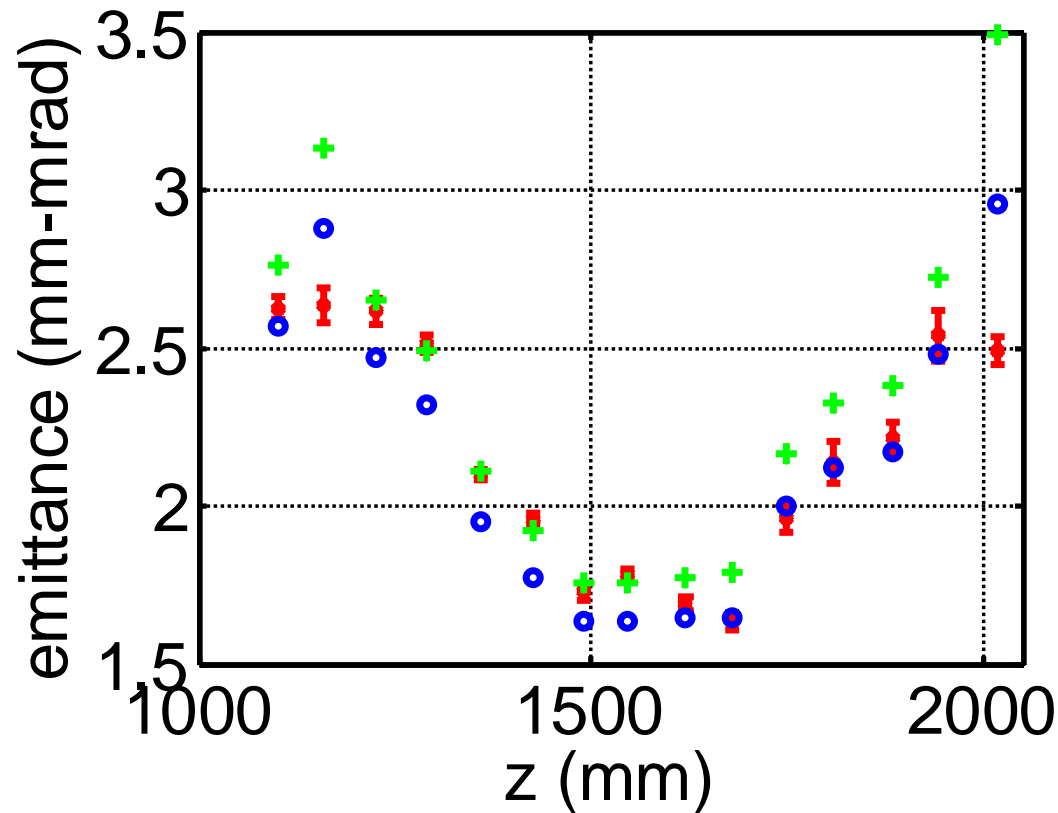


Image selection

95% charge cut

93% charge cut



Conclusion

Emittance meter allows the study of emittance evolution along the beam propagation axis just after a photoinjector.

The SPARC data analysis procedure is automatic, reasonably fast and robust enough so that it was implemented in the automatic control room procedure.

The SPARC data analysis main blocks are:

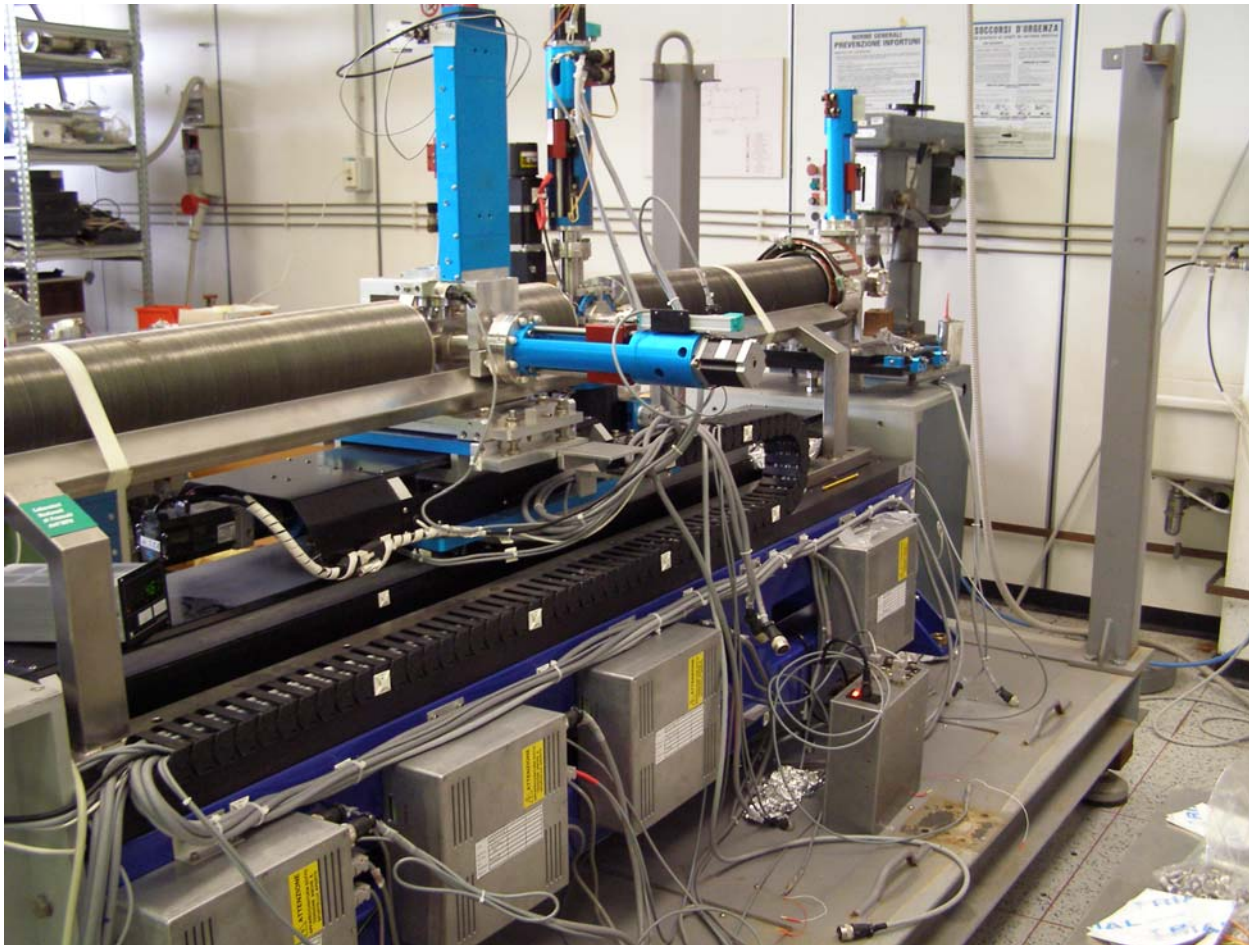
- profile filtering for noise suppression**
- the image selection**
- uncertainty evaluation**
- trace space reconstruction**

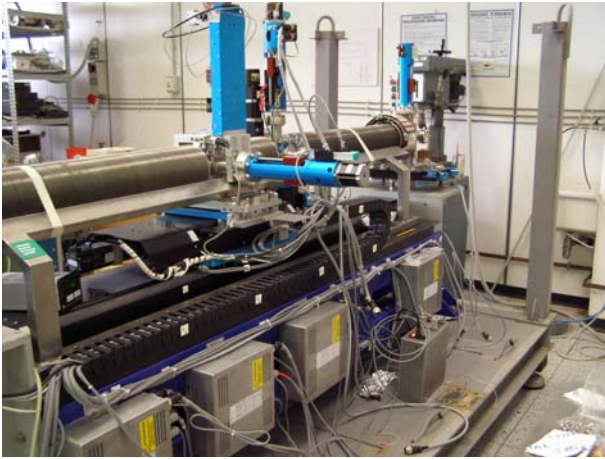
Quantitative estimation of the beam charge percentage actually associated to the emittance value retrieved by the automatic algorithm is found with reconstructed trace space analysis.

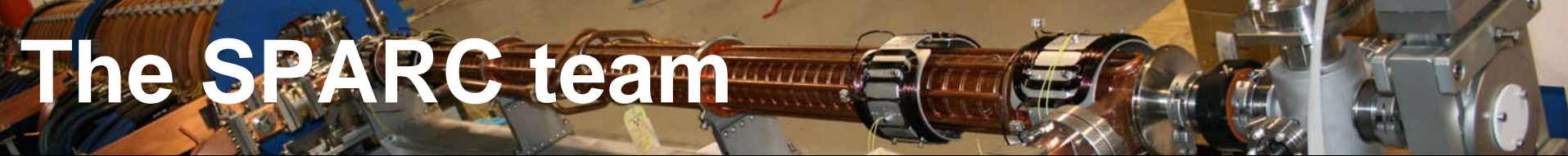


The emittance meter today

The **movable** emittance meter







The SPARC team

