# 11D supergravity from the non-linear realisation of E11

Alexander Tumanov

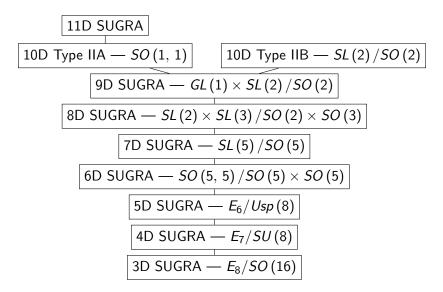
King's College London

DESY, 01.03.16

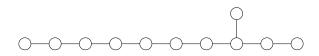
# Presentation plan

- Introduction
  - ► E11 conjecture
  - Non-linear realisations
- E11 in 11D
- Conclusions

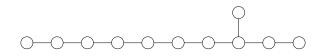
#### Exceptional symmetries of maximal supergravities



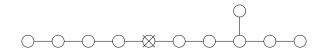
E11 Dynkin diagram



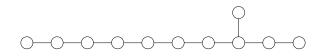
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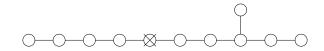
5D SUGRA —  $GL(5) \times E_6$ 



E11 Dynkin diagram



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11D SUGRA — GL(11)



All maximal supergravity theories in every dimension are contained in the non-linear realisation of the E11 algebra. Theories in different dimensions correspond to different decompositions of E11 into representations of its simple subalgebras.

#### E11 conjecture

The non-linear realisation of the E11 algebra is the low energy effective action of the theory of strings and branes.

- P. West, 2001 0104081
- P. West, 2003 0307098

 $G \supset H$ , H - local subgroup,  $l_1$  - vector representation of G

$$\left[R^{\alpha}, R^{\beta}\right] = f^{\alpha\beta}{}_{\gamma} R^{\gamma}, \quad [R^{\alpha}, L_{A}] = - (D^{\alpha})_{A}{}^{B} L_{B}$$

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Regular NLR: $g = e^{A_{\alpha} R^{\alpha}}$ NLR of a space-time symmetry group: $g = e^{x^A L_A} e^{A_{\alpha} R^{\alpha}}$ 

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#### Symmetries of NLR

- Rigid (global)  $g \longrightarrow s g, s \in G$
- Local  $g \longrightarrow g h, h \in H$

The Cartan form

$$\mathcal{V} = g^{-1} dg = \mathcal{V}_L + \mathcal{V}_E$$
$$= dx^{\Pi} \left( E_{\Pi}{}^A L_A + G_{\Pi|\alpha} R^{\alpha} \right) = dx^{\Pi} E_{\Pi}{}^A \left( L_A + G_{A|\alpha} R^{\alpha} \right)$$
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#### Transformations of the Cartan form

- Under rigid  $\mathcal{V} \longrightarrow \mathcal{V}$
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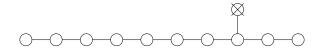
#### The dynamics

- The action  $S = \int d^d x Tr\{P^2\}$
- Direct derivation of the equations of motion

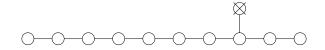
#### Examples

- Pions are described by the NLR of SU(2) × SU(2) with a local subgroup SU(2) (spontaneous breaking of the chiral symmetry).
- ► Minkowski space is described by the NLR of the Poincare group with the local subgroup SO (1, D - 1).
- ► Superspace is described by the NLR of the Super-Poincare group with the local subgroup SO(1, D - 1).
- Gravity can be described by the NLR of  $IGL(D) = \mathbb{R}^D \rtimes GL(D)$  with the local subgroup SO(1, D-1).
- In D-dimensional supergravity the scalars belong to the coset of the NLR of E (11 − D) (SL(2, ℝ) for 10D Type IIB theory).

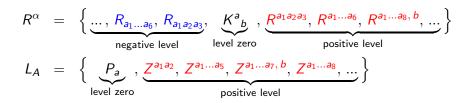
E11 is decomposed into representations of GL(11)



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Generators of E11 and its vector representation



#### The group element $g = g_L g_E$

$$g_{E} = e^{A_{\alpha} R^{\alpha}} = \dots e^{A_{a_{1}\dots a_{6}} R^{a_{1}\dots a_{6}}} e^{A_{a_{1}a_{2}a_{3}} R^{a_{1}a_{2}a_{3}}} e^{h_{a}{}^{b} K^{a}{}^{b}}$$
$$g_{L} = e^{x^{A} L_{A}} = e^{x^{a} P_{a}} e^{x_{a_{1}a_{2}} Z^{a_{1}a_{2}}} e^{x_{a_{1}\dots a_{5}} Z^{a_{1}\dots a_{5}}} \dots$$

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$$g_L = e^{x^A L_A} = e^{x^a P_a} e^{x_{a_1 a_2} Z^{a_1 a_2}} e^{x_{a_1 \dots a_5} Z^{a_1 \dots a_5}} \dots$$

#### Relation to the supergravity

 $e_{\mu}{}^{a} = (e^{h})_{\mu}{}^{a}$  - vielbein.  $A_{a_{1}a_{2}a_{3}}$  - the 3-form of 11D SUGRA, couples to the M2 brane.  $A_{a_{1}...a_{6}}$  - the 6-form of 11D SUGRA (magnetic dual of the 3-form), couples to the M5 brane.

 $L_A$  multiplet contains all the brane charges.

We choose the Cartan involution subalgebra of E11, called  $I_c(E_{11})$ , to be the local subalgebra of the NLR.

Cartan involution subalgebra is an algebra built from the generators of the following form:  $E_{\alpha} - F_{\alpha}$ .

AT, Peter West, 2015 — 1601.03974 Level 1  $I_c(E_{11})$  transformation

$$g \longrightarrow g h, \quad h = 1 - \Lambda_{a_1 a_2 a_3} \left( R^{a_1 a_2 a_3} - \eta^{a_1 b_1} \eta^{a_2 b_2} \eta^{a_3 b_3} R_{b_1 b_2 b_3} \right)$$

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First order vector equation — duality relation between the 3-form and the 6-form

$$E_{a_1...a_4} = G_{[a_1, a_2 a_3 a_4]} - \frac{1}{48} \varepsilon_{a_1...a_4}^{\ b_1...b_7} G_{b_1, b_2...b_7} = 0$$
  
$$\delta E_{a_1...a_4} = \frac{1}{24} \varepsilon_{a_1...a_4}^{\ b_1...b_7} \Lambda_{b_1 b_2 b_3} E_{b_4...b_7} + \text{gravity part}$$

Second order vector equations — 3-form equation of 11D  $\operatorname{SUGRA}$ 

$$E^{a_1a_2a_3} = \frac{1}{2} G_{b,c}{}^c G^{[b,a_1a_2a_3]} - 3 G_{b,c}{}^{[a_1|} G^{[b,c|a_2a_3]]} - G_{c,b}{}^c G^{[b,a_1a_2a_3]}$$
$$+ (\det e)^{\frac{1}{2}} e_b{}^{\mu}\partial_{\mu} G^{[b,a_1a_2a_3]} + \frac{1}{48} \varepsilon^{a_1a_2a_3b_1...b_8} G_{[b_1,b_2b_3b_4]} G_{[b_5,b_6b_7b_8]} = 0$$

Second order vector equations — 3-form equation of 11D  $\operatorname{SUGRA}$ 

$$\begin{split} E^{a_{1}a_{2}a_{3}} &= \frac{1}{2} G_{b,c}{}^{c} G^{[b,a_{1}a_{2}a_{3}]} - 3 G_{b,c}{}^{[a_{1}|} G^{[b,c|a_{2}a_{3}]]} - G_{c,b}{}^{c} G^{[b,a_{1}a_{2}a_{3}]} \\ &+ (\det e)^{\frac{1}{2}} e_{b}{}^{\mu}\partial_{\mu} G^{[b,a_{1}a_{2}a_{3}]} + \frac{1}{48} \varepsilon^{a_{1}a_{2}a_{3}b_{1}...b_{8}} G_{[b_{1},b_{2}b_{3}b_{4}]} G_{[b_{5},b_{6}b_{7}b_{8}]} = 0 \\ \delta E^{a_{1}a_{2}a_{3}} &= \frac{1}{24} \varepsilon^{\mu_{1}...\mu_{4}\lambda_{1}...\lambda_{7}} e^{a_{1}}_{\mu_{1}} e^{a_{2}}_{\mu_{2}} e^{a_{3}}_{\mu_{3}} \partial_{\mu_{4}} \left( (\det e)^{-\frac{1}{2}} E_{\lambda_{1}...\lambda_{4}} \Lambda_{\lambda_{5}\lambda_{6}\lambda_{7}} \right) \\ &+ 210 E_{b_{1}...b_{4}} G^{[b_{1},b_{2}b_{3}b_{4}} \Lambda^{a_{1}a_{2}a_{3}]} + \frac{3}{2} E_{b}^{[a_{1}} \Lambda^{a_{2}a_{3}]b} \end{split}$$

 $E_a^b$  is the gravity (Einstein) equation

#### Gravity equation

$$E_{a}^{\ b} = \underbrace{(\det e) \ R_{a}^{\ b}}_{\text{gravity}} - \underbrace{48 \ G_{[a, c_{1}c_{2}c_{3}]} \ G^{[b, c_{1}c_{2}c_{3}]} + 4 \ \delta_{a}^{b} \ G_{[c_{1}, c_{2}c_{3}c_{4}]} \ G^{[c_{1}, c_{2}c_{3}c_{4}]}}_{\text{stress-energy tensor}}$$

$$R_a^{\ b} = e_a^{\ \mu} \partial_\mu \, \omega_{\nu,}^{\ bd} \, e_d^{\ \nu} - e_a^{\ \mu} \partial_\nu \, \omega_{\mu,}^{\ bd} \, e_d^{\ \nu} + \omega_{a,}^{\ b}{}_c \, \omega_{d,}^{\ cd} - \omega_{d,}^{\ b}{}_c \, \omega_{a,}^{\ cd}$$

Ultimate check — variation of the gravity equation

$$\begin{split} \delta \, E_{ab} &= -72 \, \Lambda^{c_1 c_2}{}_{(a} \, E_{b) c_1 c_2} + 8 \, \eta_{ab} \, \Lambda^{c_1 c_2 c_3} \, E_{c_1 c_2 c_3} \\ &- 4 \, \varepsilon_{(a}{}^{c_1 \dots c_{10}} \, G_{[b), \, c_1 c_2 c_3]} \, E_{c_4 \dots c_7} \, \Lambda_{c_8 c_9 c_{10}} \\ &+ \frac{1}{3} \, \eta_{ab} \, \varepsilon^{c_1 \dots c_{11}} \, G_{[c_1, \, c_2 c_3 c_4]} \, E_{c_5 \dots c_8} \, \Lambda_{c_9 c_{10} c_{11}} \end{split}$$

## Conclusions

- On the low levels of the NLR of E11 we find the entire field content of the bosonic sector of 11D SUGRA. The equations of motion are uniquely determined by the NLR.
- ► The same kind of analysis can be repeated for any D ≤ 11. For the 5D case see AT, Peter West, 2015 — 1512.01644
- Apart from the usual supergravity fields the E11 theory contains an infinite number of higher level fields and coordinates. Some classes of the fields represent well understood extensions of the supergravity theories (magnetic duals of supergravity fields, gauged supergravities), while other might represent some new phenomena (example: dual graviton).
- The NLR of E11 is a vast theory that contains all maximal supergravities at the same time. This means that E11 approach could be the correct way of looking at the low-energy limit of the theory of strings and branes.

Thank you