BAM Electronics

Overview & Specifications

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BAM Generation 3 - Overview on Specifications for Electronic System

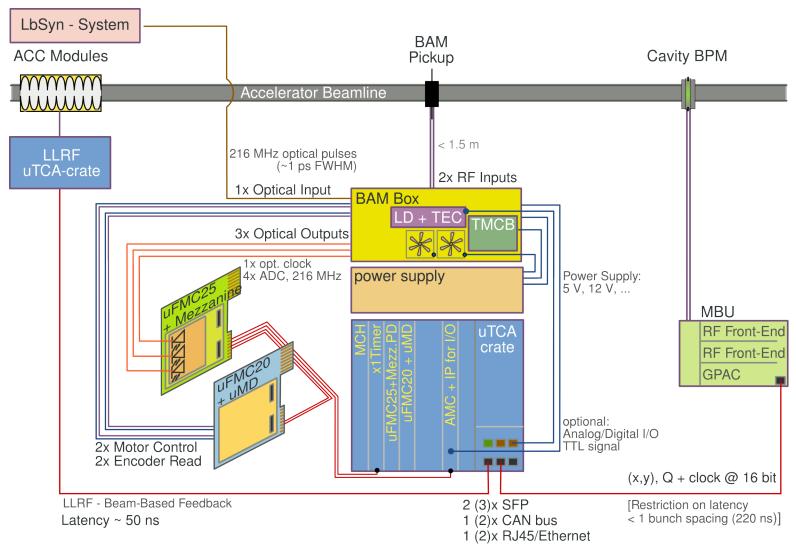
2nd Follow-up Meeting on MTCA.4 Board Development

15. October 2013, DESY





System Overview & Interfaces





Interfacing

- > DFMC25 ↔ DFMC20+MD22
 - ideally, communication via backplane
 - MD22:
 - > control of 2 stepper motors
 - > read-out of position encoder: EnDat2.2 data format
 - data rates: 10 Mbit/sec
- > DFMC25 ↔ I/O cards
 - Option: control of optical switch (e.g. via TTL signal)
 - synchronised to machine trigger



uFMC25 + mezzanine & PD: open questions

> Challenge:

- Conversion of laser pulses (~ps FWHM) to electr. Signal (clear pulse w/ flat baseline)
- Sampling rate of 216 MHz (laser rep. Rate):
 - > 2 channels
 - 2x ADCs per channel (peak & baseline)

Requirements & Current Status:

PD input:

- PD output power level wrt optical input power
- > set diff. amplifier according to expected opt. power
- > characterisation of pulses (pronounced separation between peak & baseline):
 - first tests promising: clean shape of PD output
- amplitude jitter at peak & baseline
- ADC performance:
 - dynamic range
 - buffer current for optimal SFDR
 - > employment of time shifters
 - > SNR
 - > ENOB
 - > max. clock jitter wrt to full BW signals
 - > amplitude jitter (peak & baseline):
 - first estimation promising, but with single FMC carrier in MTCA crate



Firmware & Server

> Basic firmware for FMC25

- Data processing in FPGA:
 - specialised firmware for BAM signal processing
 - collecting data from other diagnostics: BPM, BCM, ...
 - sending data packets to LLRF for intra-train FB
- > BAM Server for "slow" operations
 - averaging, internal feedbacks, ...



Rough timeline

- Original Plan (Feb. 2013): Boards ready for installation
 - FLASH /FLASH II:

