

Fast vertexing and tracking @ HLT in multijet and MET trigger paths

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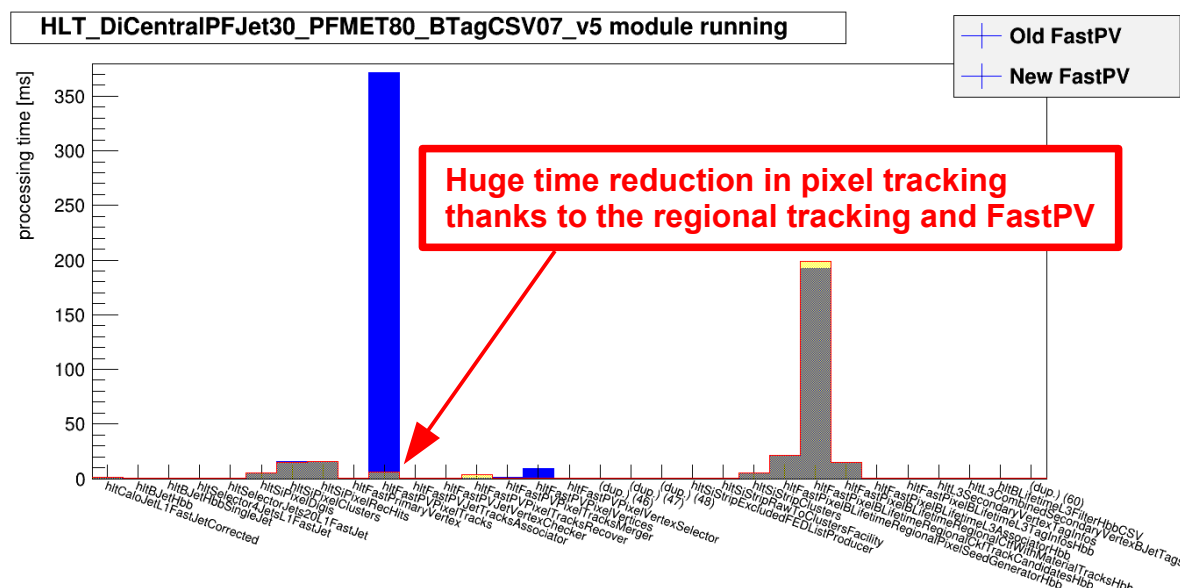
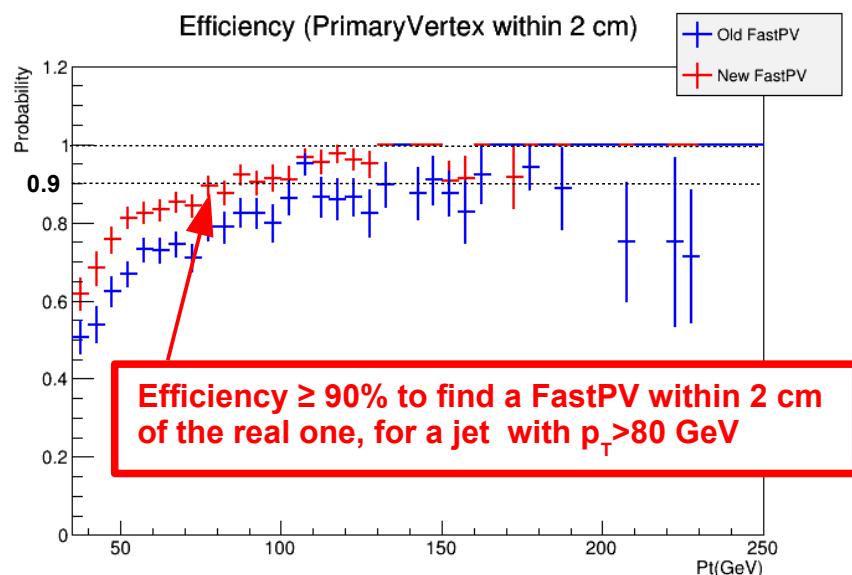




Previous results



- ✓ The last results we presented in TSG meeting are (
<https://indico.cern.ch/getFile.py/access?contribId=2&resId=0&materialId=slides&confId=259619>
):
 - ✓ an improvement of the FastPixelVertex algorithm → **more efficiency to find the FastPV;**
 - ✓ an useful exploitation of the pixel regional tracking with FastPV constraint → **very fast tracking without lose efficiency.**





Some applications



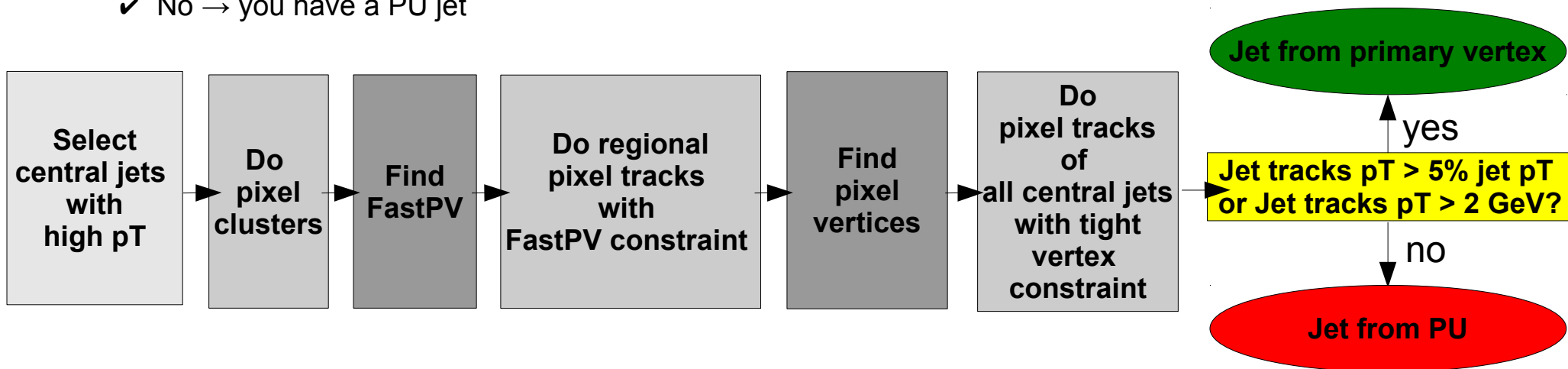
- ✓ In $Z(\nu\nu)H(bb)$ sample with $\langle\text{PU}\rangle\sim 60$ **we can find the primary vertex within $50\text{ }\mu\text{m}$ in $\sim 87.1\%$ times, in less than 50 ms** (running time, after CaloJets modules).
- ✓ So we propose to use the pixel regional tracking also to define a **JetNoPU tagging** and use it to reduce the rate in **multi-jet trigger**.
- ✓ We can exploit the JetNoPU tagging also to calculate a kind of “**MHTnoPU**” for **MET trigger** to improve the performances.



JetNoPU tagging



- ✓ In order to tag PU jets we run the following sequence:
 - ✓ **select the jets with higher Pt** (eg. $P_t > 40$) and central ($|\eta| < 2.4$);
 - ✓ do the pixel clusters;
 - ✓ find the **FastPrimaryVertex** (with a resolution of ~ 1.5 cm);
 - ✓ do the **regional pixel tracks** around the jets and with the FastPV constraint (1.5 cm);
 - ✓ find the **pixel vertices** (with a resolution of ~ 50 μm);
 - ✓ do the **regional pixel tracks of all jets** with the pixel vertex constraint (0.5 cm);
 - ✓ **select tracks with a distance from jets direction smaller then 450 μm** ;
 - ✓ the **sum of jet tracks momentum is greater then 5% of jet momentum OR then 2 GeV?**
 - ✓ Yes \rightarrow you have a no PU jet.
 - ✓ No \rightarrow you have a PU jet

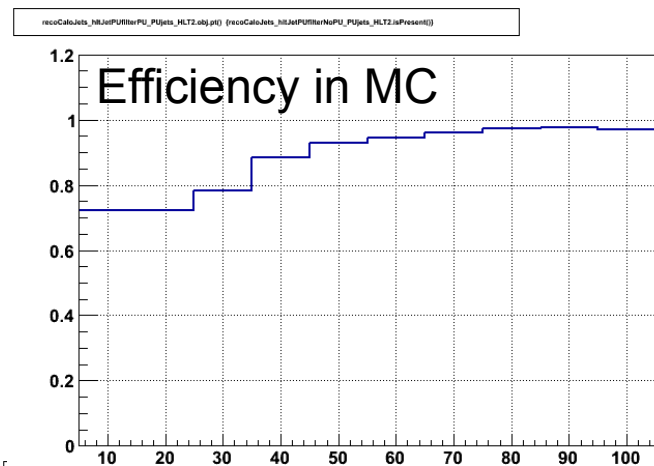




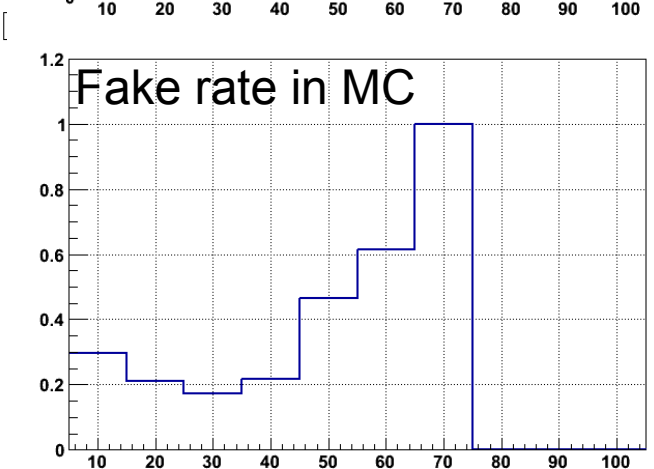
JetNoPU efficiency



- ✓ We tested the JetNoPU in data (L1QuadCJet40) and MC (Z(vv)H(bb)), both with $\langle \text{PU} \rangle \sim 60$.
- ✓ We use as signal PFnoPU jets in data and GenJets in MC

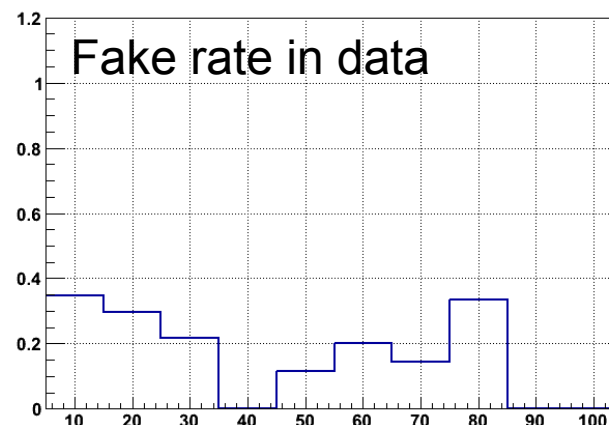
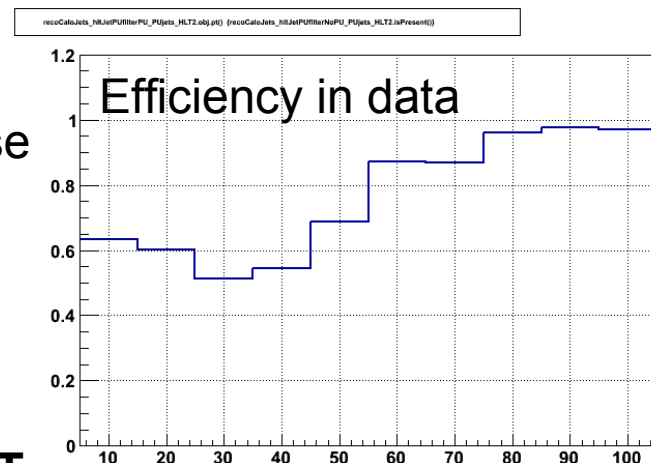


High efficiency in the high pT region, because we have more tracks.



More fake rate in low pT region, because we cut with looser threshold (jet tracks $p_T > 5\%$ jet p_T)

More fake rate in high pT region simply because we consider the vertex of the leading jet as primary.

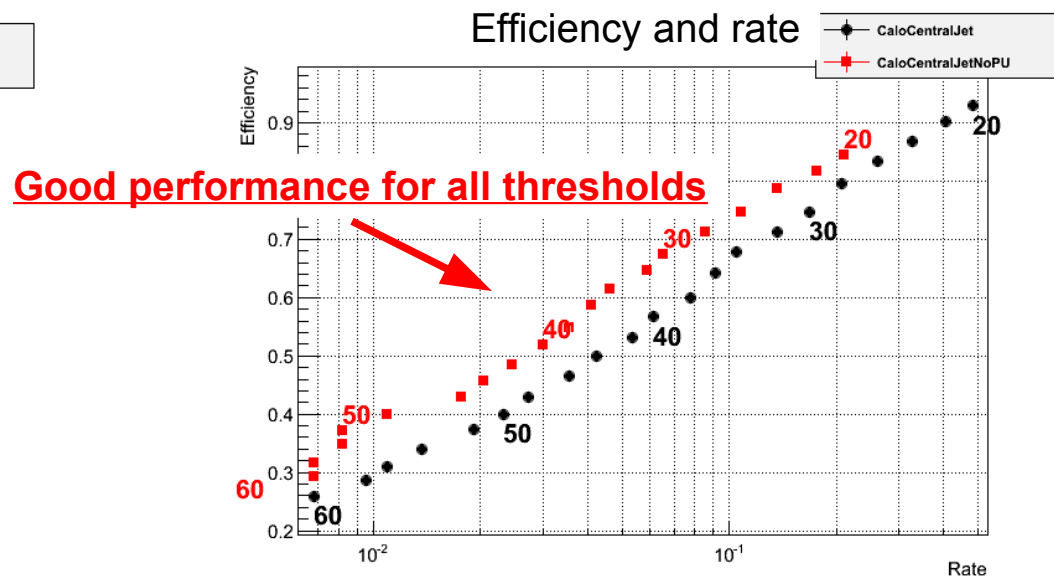
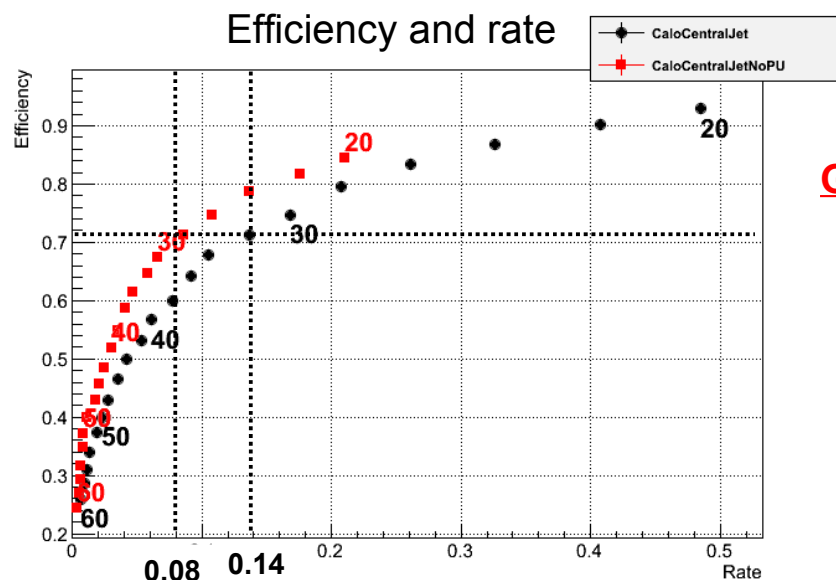




MultiJet trigger



- ✓ Let's see how it works in a multi-jet trigger.
- ✓ We use MinBias data to measure the rate and RadionToHH_4b_M-450_TuneZ2star_8TeV as signal to measure the efficiency.
- ✓ Both have been preselected with L1DoubleJetC64 and requiring two central CaloJet with $p_T > 64$ GeV. The mean PU is 60 for both data and MC.
- ✓ The plots show the efficiency and the rate, normalized after the pre-selection, as a function of the threshold of QuadCentralCaloJet and QuadCentralCaloJetNoPU cuts.
- ✓ **Thanks to JetNoPU we can reduce the rate up to a factor two, keeping the same efficiency!**

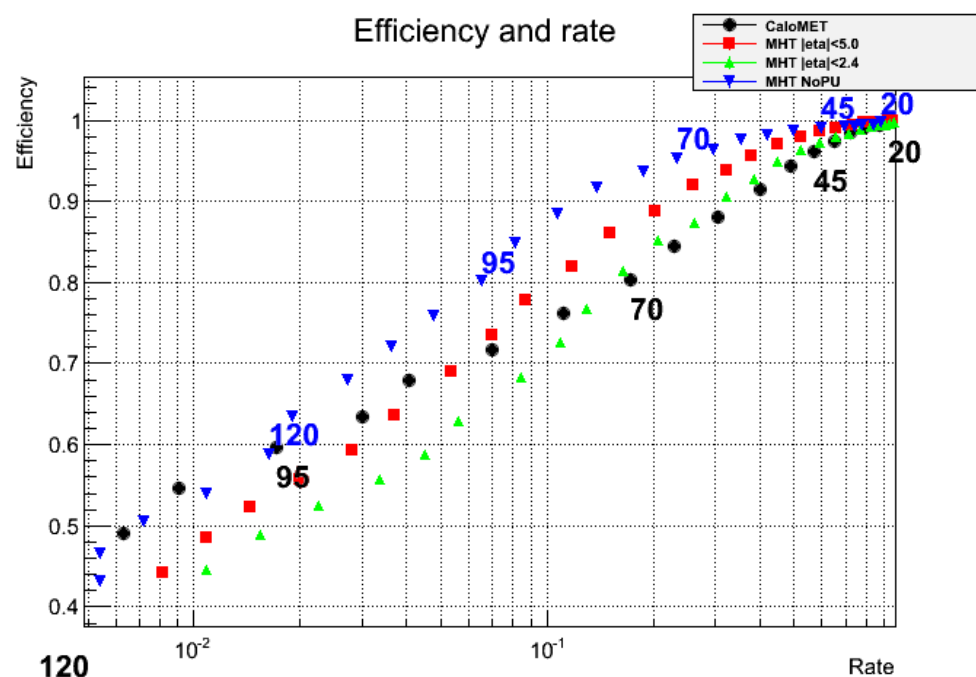
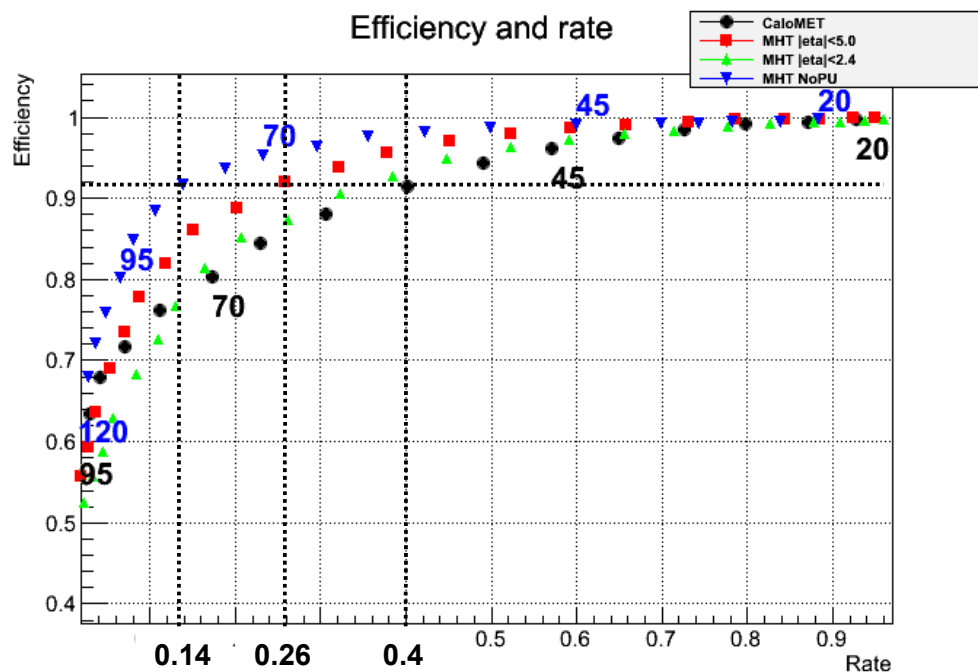




MET trigger



- ✓ For the MET trigger test we use MinBias data to measure the rate and $Z(\nu\nu)H(bb)$, with $\text{GenMET} > 80$ GeV, as signal to measure the efficiency.
- ✓ Both have been preselected with L1ETM40 and requiring two central CaloJet with $p_{T1} > 40$ GeV and $p_{T2} > 20$ GeV. The mean PU is 60 for both data and MC.
- ✓ The plots show the efficiency and the rate, normalized after the pre-selection, as a function of the threshold of MET, MHT ($|\eta| < 2.4$), MHT ($|\eta| < 5$) and MHTNoPU cuts.
- ✓ Here, MHT is defined as the module of the vector sum of the jet momentum with $p_T > 20$ and in the eta range. MHTnoPU is calculated using JetNoPU with $p_T > 20$ in $|\eta| < 2.4$ and all jets with $p_T > 40$ in $2.4 < |\eta| < 5$
- ✓ **Thanks to jetNoPU we can reduce the rate, keeping the same efficiency, up to a factor of two, compared to CaloMHT, or a factor of four, compared to CaloMET**





Working points



- ✓ Here we report some working point in order to summarize the results that we can achieve thanks to JetNoPu @ HLT.
- ✓ We compare the rate of the old vs new cut with, with the same efficiency.

Trigger	Old cut	New cut	Old rate	New rate
Multijet	QuadCentJet>32	QuadCentJetNoPU>28	0.14	<u>0.08</u>
MET	MET>80 MHT>55	MHTnoPU>80	0.40 0.26	<u>0.14</u>



Use case: HLT DiCentralPFJet30 PFMET80 BTagCSV07



- ✓ As use case we propose an update of HLT DiCentralPFJet30 PFMET80 BTagCSV07 trigger path.
- ✓ We use 968 events of $Z(\nu\nu)H(bb)$ signal with offline $PFMET > 100$ GeV, 2 b-jet in $|\eta| < 2.4$ and pass L1_ETM40.
- ✓ We use 3682 events MinBias data passed L1_ETM40.
- ✓ Both samples have $\langle PU \rangle \sim 60$.



Old trigger



✓ The old trigger selection for minbias data and signal is:

Filter	Data	Signal
L1_ETM40	36872	968
MET65	8918	829
DoubleJetC20	6023	800
FastPVSelector	5027	800
Online CSV>0.7	159	566
DoublePFJetC30	120	515
PFMET80	56	482
Ratio(HLT/L1)	0.15%	50%

rate(L1_ETM40) ~ 105 kHz!
if <PU>~60 and bunch spacing 50ns



New trigger



✓ The new trigger selection for MinBias data and signal is:

**We'll add the
DoubleJetC20 filter**

Filter	Data	Signal
L1_ETM40	36872	968
MET40	24920	829
SingleJetC40	7514	829
MHT60	4014	829
FastPVSelector	3016	829
MHTnoPU80	568	800
Online CSV>0.7	43	566
Ratio(HLT/L1)	0.11%	58%



Comparison



- ✓ The new HLT path has:
 - ✓ an **efficiency** on signal of **58%** (instead of 50%);
 - ✓ a **rate reduction** to **0.11%** (instead of 0.15%).
- ✓ The mean time needed to the new trigger path is only **61 ms** on L1_ETM40 preselected data (instead of 153 ms):
 - ✓ Note: to calculate the real HLT timing we should divide it by $\text{rate(L1)}/\text{rate(L1_ETM40)} \sim 17$.
- ✓ We get this time reduction thanks to:
 - ✓ a better FastPV efficiency to find the right PV;
 - ✓ the regional pixel tracking;
 - ✓ (removing the PF sequence)



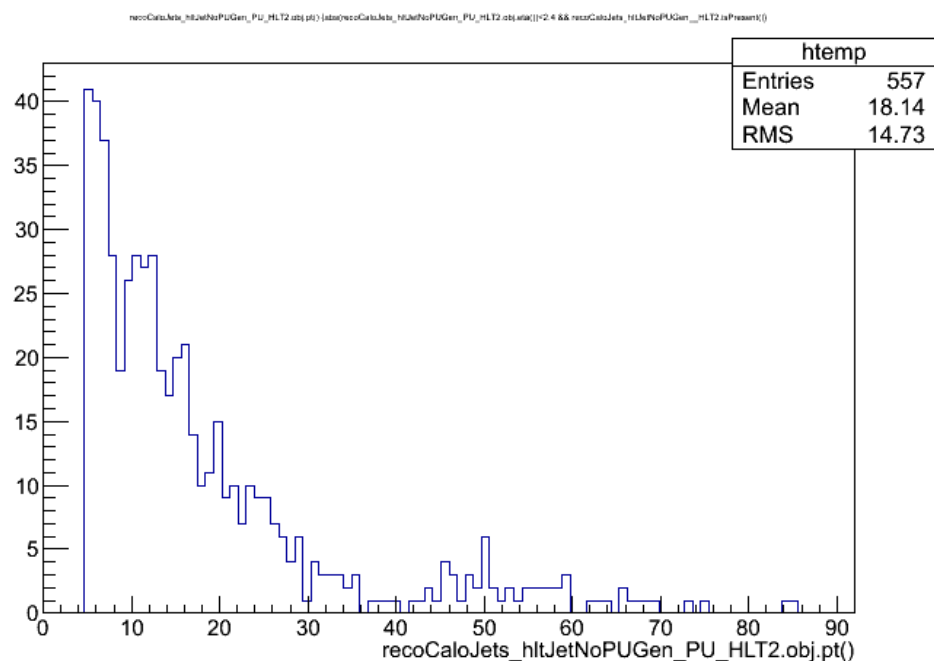
Conclusions



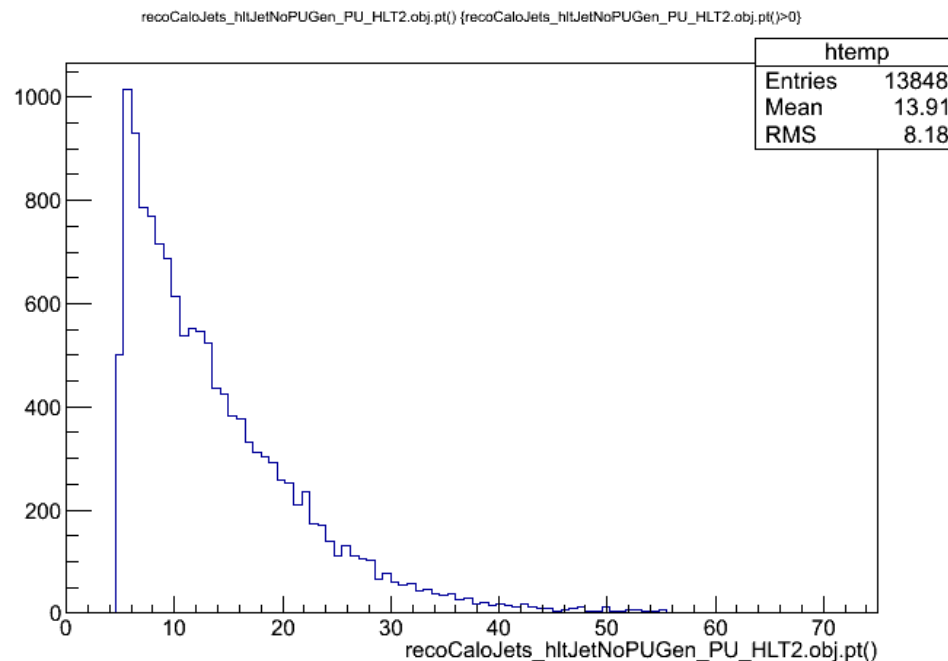
- ✓ FastPV and regional pixel tracking are very fast → we can find the primary vertex in 50 ns with a resolution of $\sim 50\mu\text{s}$.
 - ✓ Note: we could further reduce this time using a regional pixel clustering!
- ✓ So we can use them to recognize jet from PU.
- ✓ Using JetNoPU tagging in trigger paths, with the same efficiency, we can reduce the rate:
 - ✓ up to a factor x2 in a QuadCentralJet trigger;
 - ✓ up to a factor x4 in a CaloMET trigger (x2 compared with CaloMHT).
- ✓ An update of HLT DiCentralPFJet30 PFMET80 BTagCSV07 has been studied has use case:
 - ✓ the result is a faster trigger (factor x2),
 - ✓ with an high efficiency (50% → 58%),
 - ✓ and better rate reduction (0.15% → 0.11%)!



Pt distribution of PU jets



Using 155 events of
Z(vv)H(bb) with $\langle \text{PU} \rangle \sim 60$



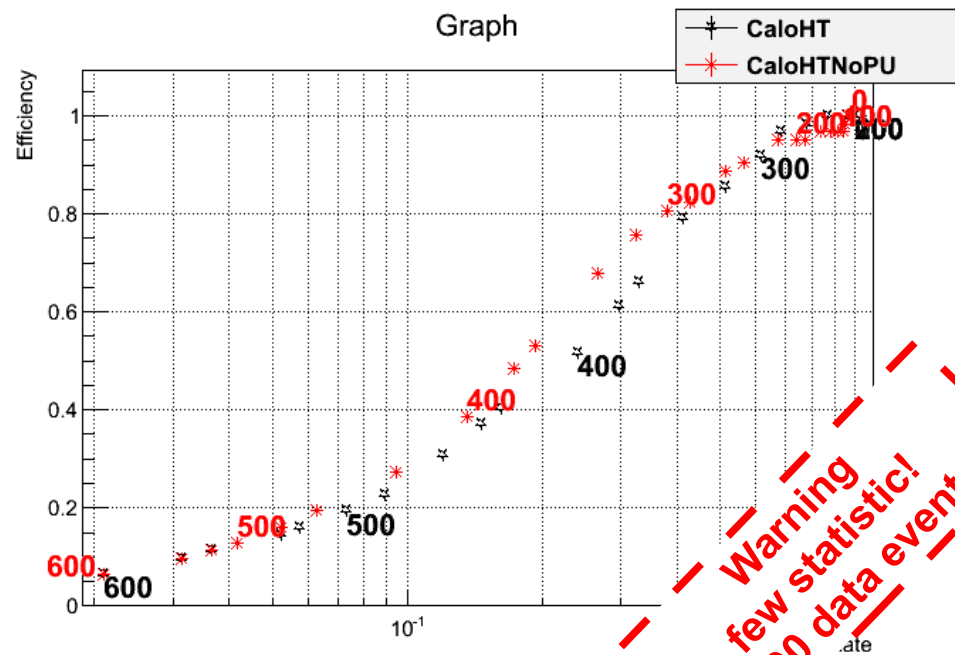
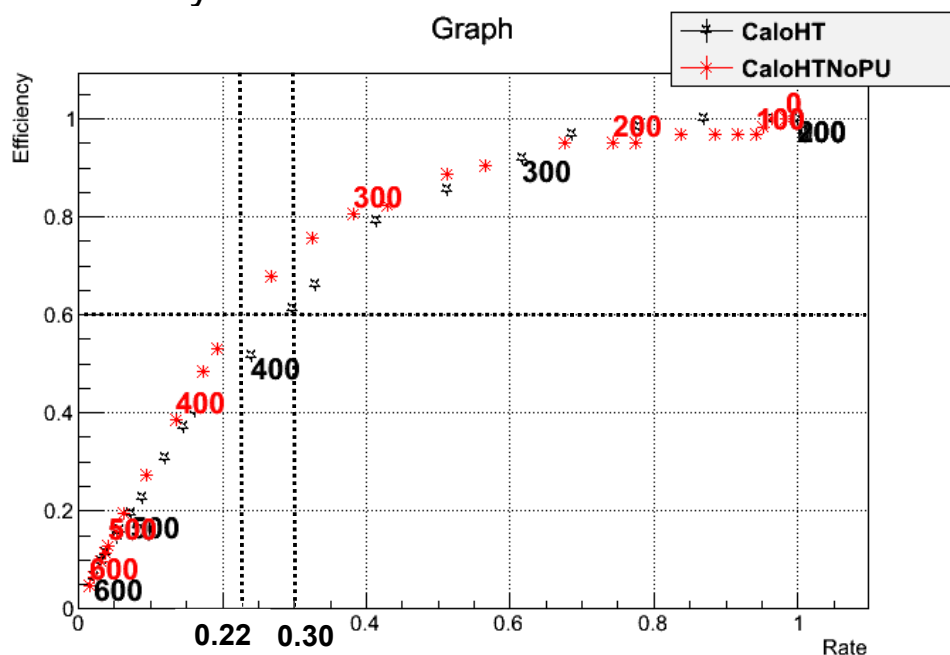
Using 2410 events of
Z(vv)H(bb) with $\langle \text{PU} \rangle \sim 60$



HT trigger



- ✓ Here we use MinBias data, to measure the rate, and MinBias data with offline PFnoPU HT>300 GeV preselected as signal to measure the efficiency.
- ✓ Both samples have $\langle \text{PU} \rangle \sim 60$ and they are preselected with L1QuadJetC40.
- ✓ Here HT is defined as the scalar sum of the momentum of the jet with $|\eta| < 2.4$ and $p_t > 30 \text{ GeV}$
- ✓ The plot shows the efficiency and rate, normalized after the pre-selection, as a function of the threshold of CaloHT and CaloHTnoPU.
- ✓ Here we get a small improvement, up to about 30% of rate reduction maintaining the same efficiency.



Warning
few statistic!
(~200 data events)

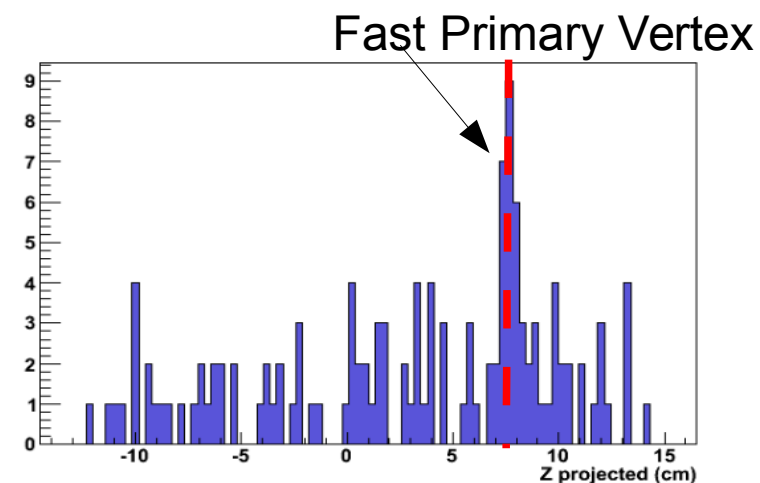
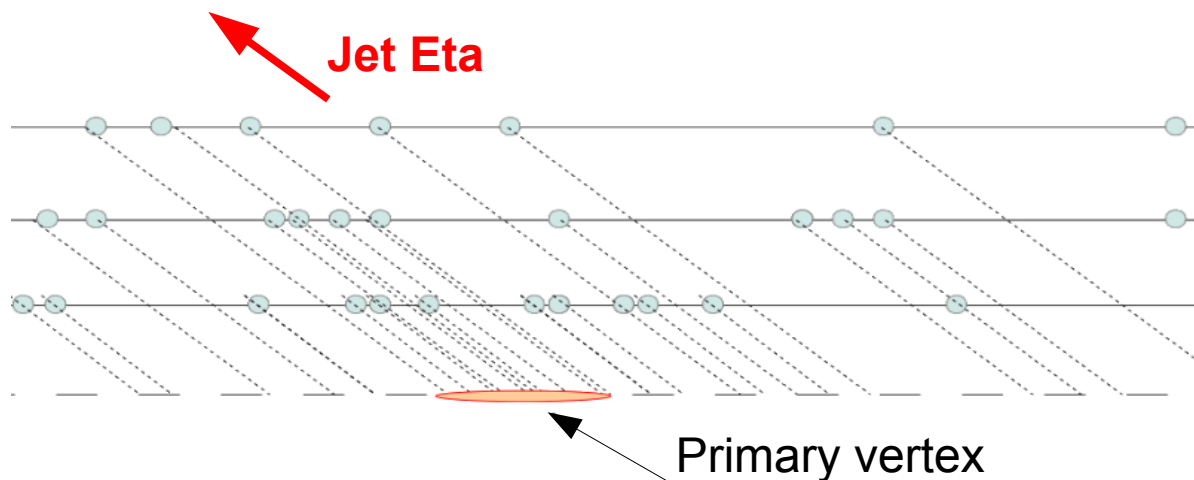




Fast Pixel Primary Vertex



- ✓ The Fast Pixel Primary Vertex is an algorithm used to find the Primary Vertex before tracking.
- ✓ Given a jet ($p_T > 40$ and $|\eta| < 1.6$), the compatible pixel clusters are selected requiring that:
 - ✓ the clusters in pixel layers and the jet must to have the same phi coordinate;
 - ✓ the cluster sizes along Y have to be compatible with the eta of the jet (jets with high eta have clusters with a long size Y);
 - ✓ the cluster sizes X have to be small in order to select only high p_T tracks.
- ✓ These clusters are projected along z using the jet eta direction.
- ✓ The “peak” in the z projections distribution is the Fast Primary Vertex.





Updates and tests



- ✓ We'll show two kinds of updates:
 - ✓ An improved version of the algorithm used to find the FastPV.
We propose to:
 - ✓ weight the clusters in order to get better performances;
 - ✓ extend the jet acceptance to $|\eta| < 2.4$, exploiting also the clusters from pixel EndCaps.
 - ✓ A different way to find the Primary Vertex using the Pixel tracks, exploiting the regional tracking and FastPV.



Cluster weight

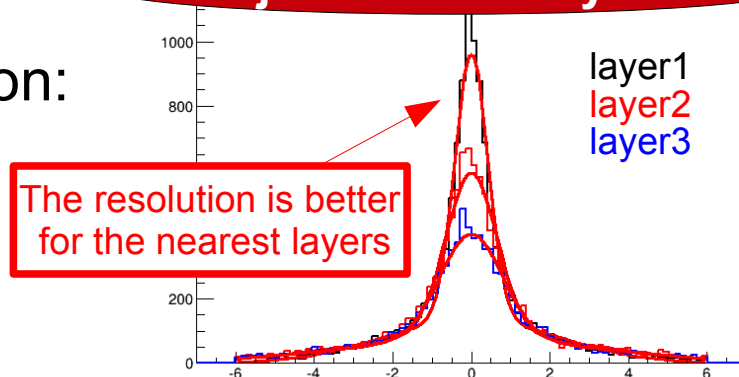


✓ We propose to weight the clusters depending on:

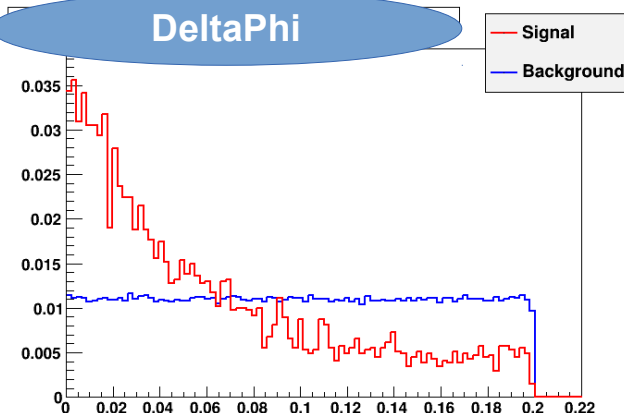
- ✓ DeltaPhi between cluster and jet;
- ✓ Difference between the cluster size Y and the one expect by jet eta;
- ✓ Cluster rho coordinate;
- ✓ Cluster charge;
- ✓ Cluster size X.

✓ The distributions of these variables are shown for clusters with a z-projection **near** ($<0.2\text{cm}$) or **far** ($>2\text{cm}$) the real primary vertex.

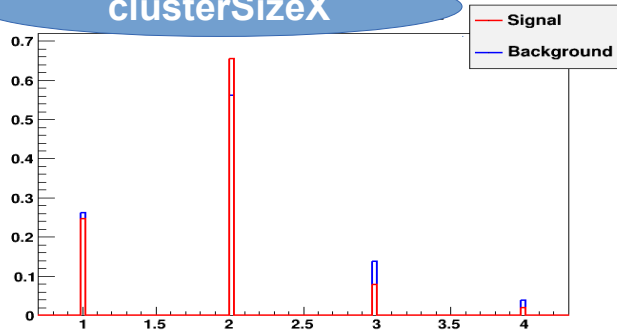
zProjection-PrimaryVertex



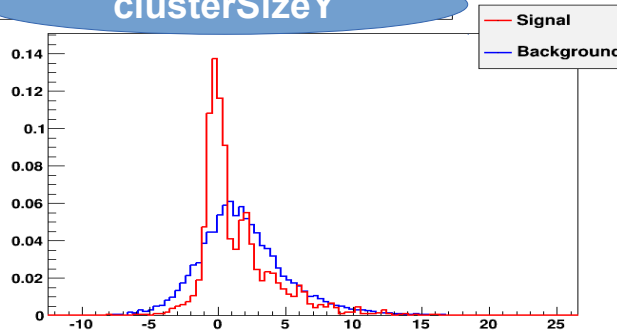
DeltaPhi



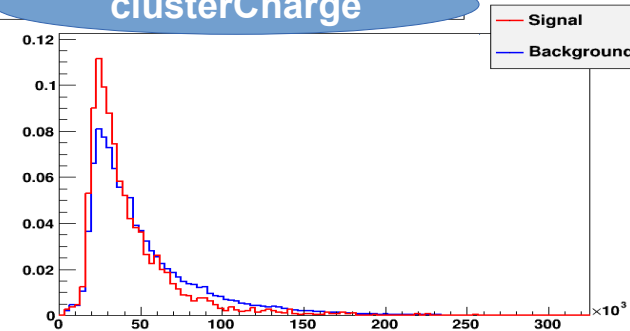
clusterSizeX



clusterSizeY



clusterCharge



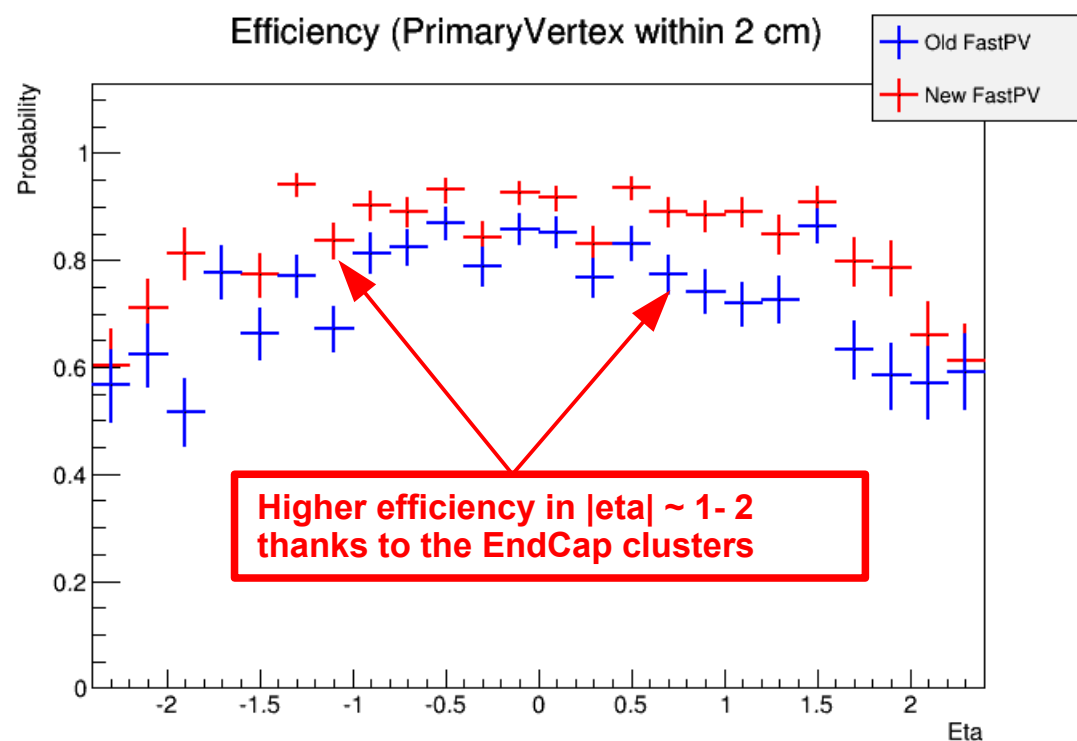
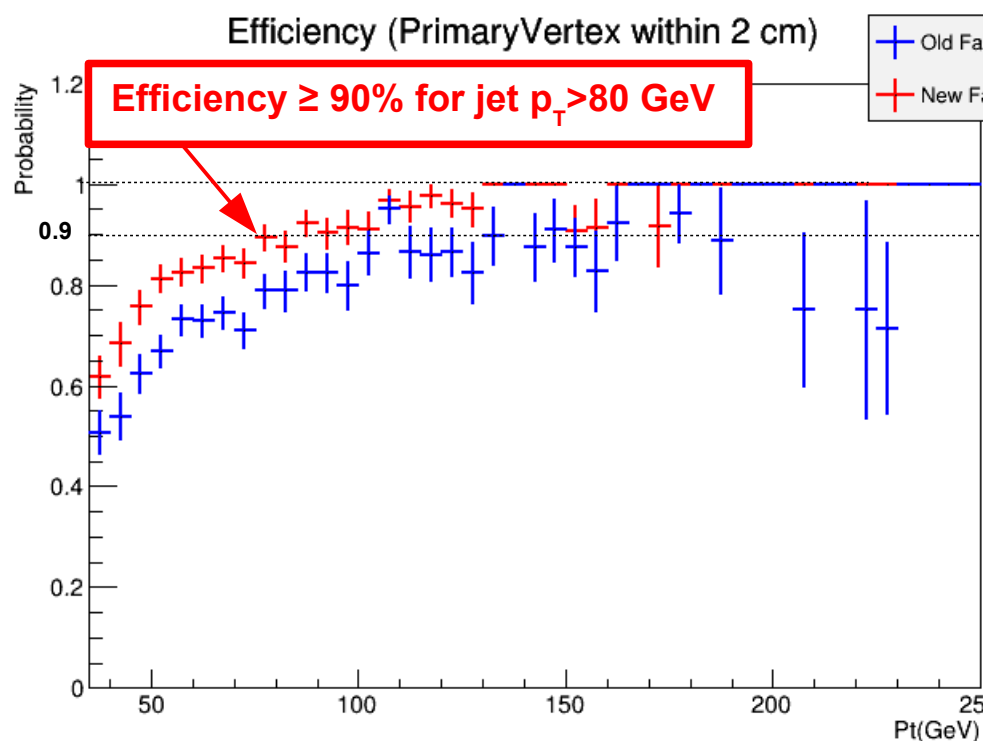


Performance of the new FPV

- ✓ We've measured the performance of the new FastPrimaryVertex using:

ZH_ZtoNuNu_HtoBB_M-125_8TeV-powheg-herwigpp/Summer12-START50_V13-v3/GEN-SIM (RAW produced using $\langle \text{PU} \rangle \sim 60$)

- ✓ Here, we've measured the efficiency to find the PV within an error of 2 cm, using a single jet, as a function of jet p_t and jet η .



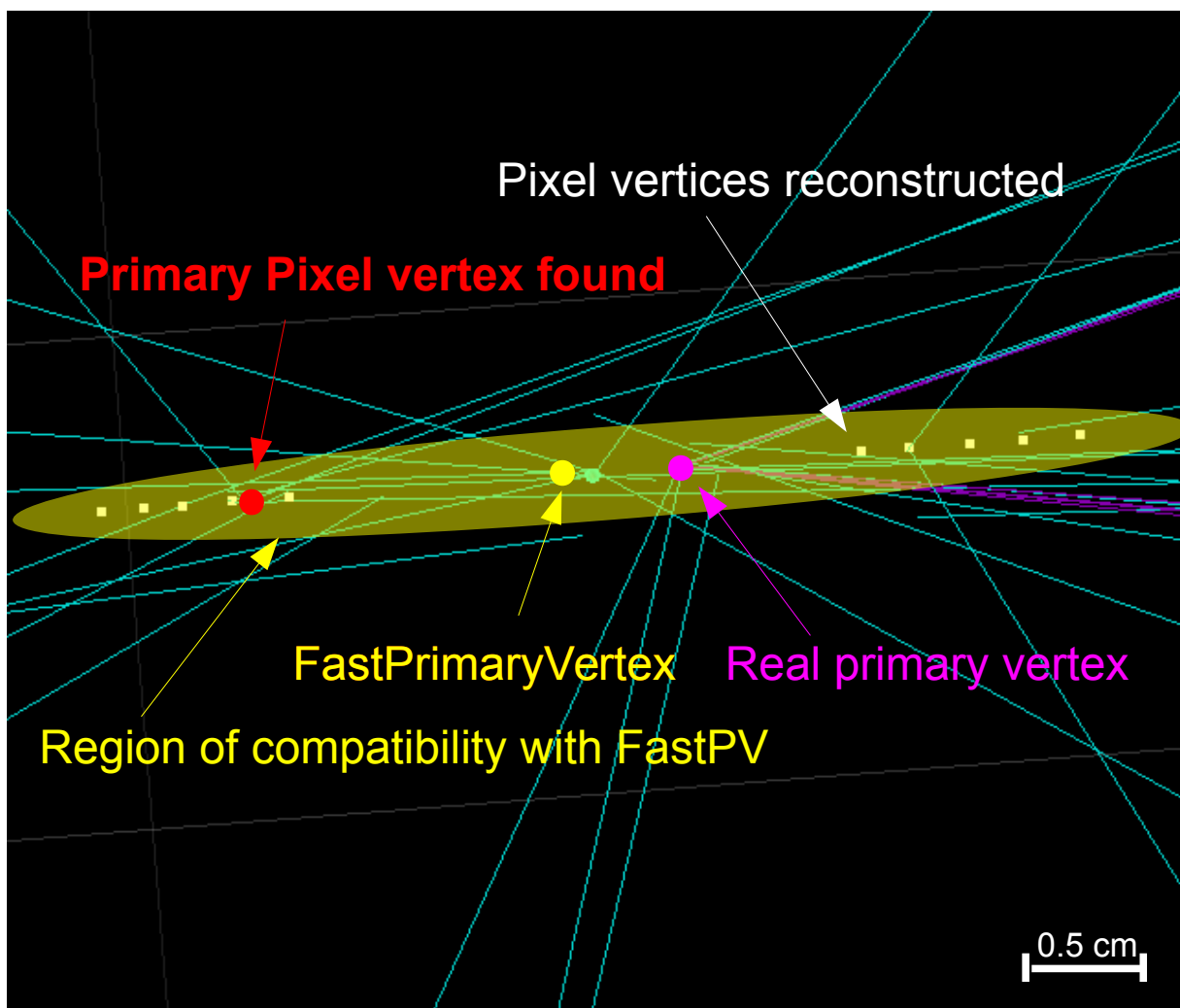


Pixel tracking

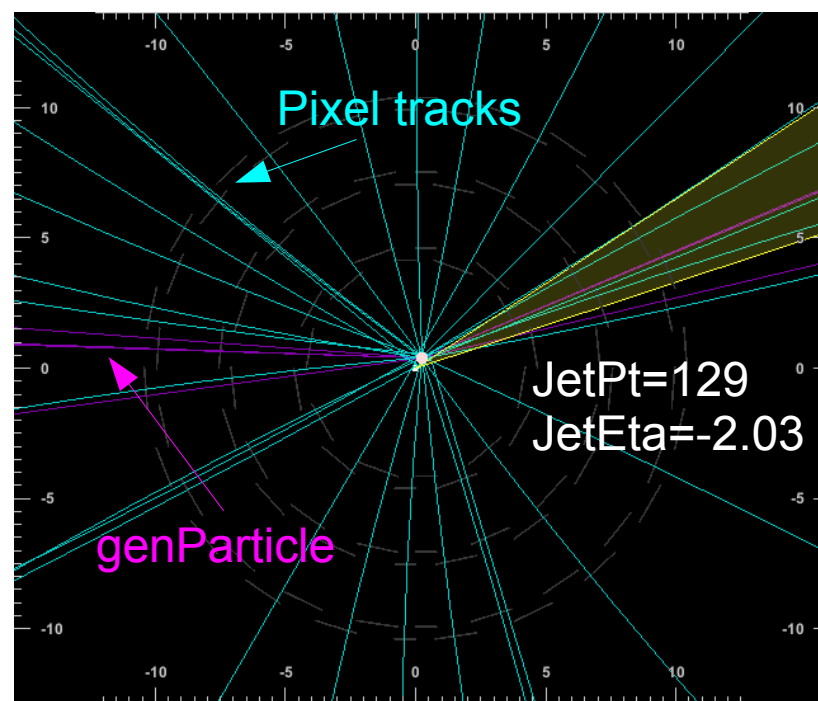


- ✓ In the present FastPV sequence we do a total pixel tracking with the FastPixelVertex constraint (1.5 cm).
- ✓ Instead, we propose to do only a regional pixel tracking around selected jets still with the FastPV constraint.
- ✓ The effects are:
 - ✓ A faster tracking! (as expected)
 - ✓ Higher efficiency to find the real Primary Vertex with Pixel tracks. (not so trivial!)
- ✓ Let's see an example.

Example: old pixel tracks



- ✓ All tracks compatible with the FastPV within 1.5 cm are reconstructed.
- ✓ We get the wrong PixelVertex!

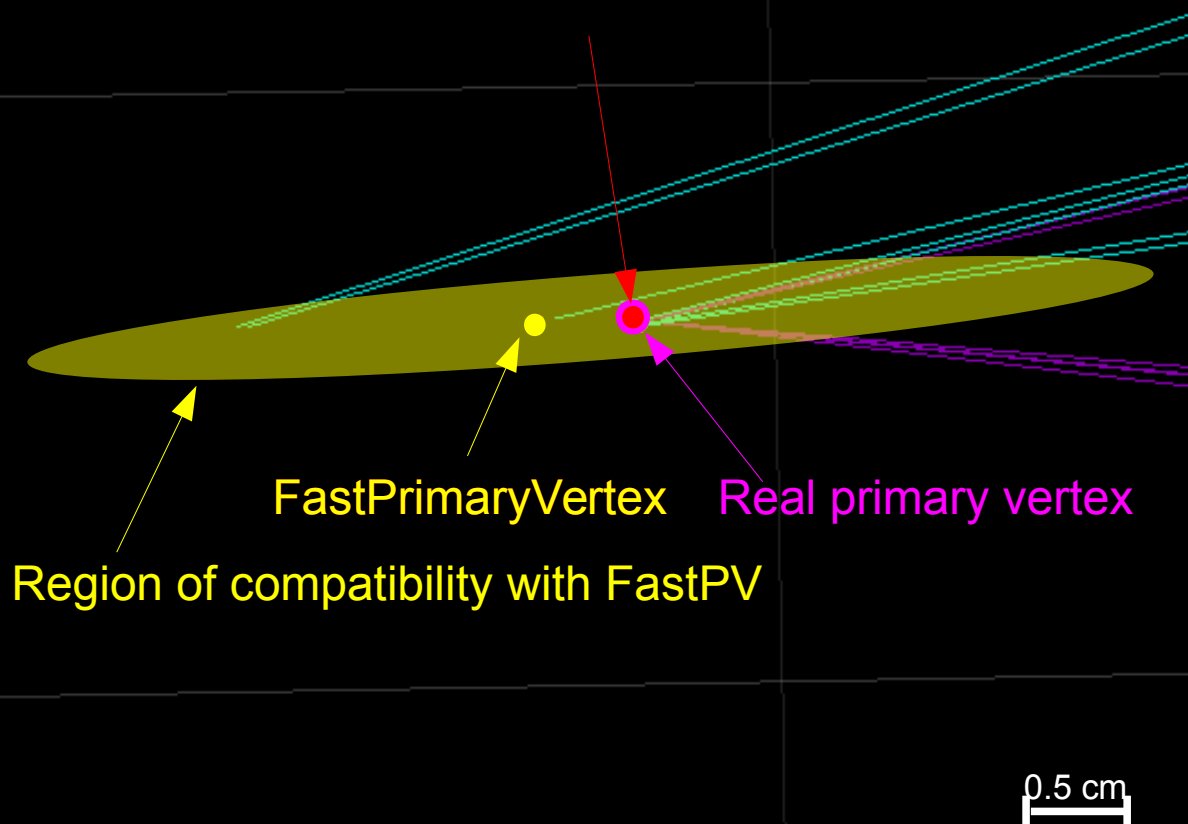




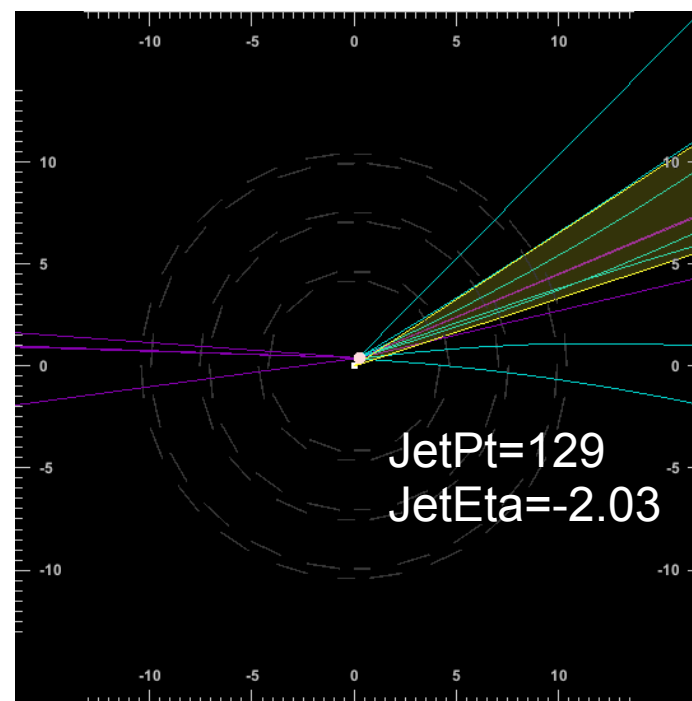
Example: new pixel tracks



Only the good pixel primary vertex is reconstructed



- ✓ Here, only regional tracks are used (with the FastPV constraint).
- ✓ We get the right PixelVertex!





Test in a HLT path



- ✓ Finally we tested the updates in
HLT_DiCentralPFJet30_PFMET80_BTagCSV07 path using:
 - ✓ Data: MinimumBias special run 190782 ($\langle \text{PU} \rangle \sim 60$)
 - ✓ 36.8k events after L1_ETM40 preselection;
 - ✓ 2.2k events after other calo cuts ($\text{MET} > 80$ & jet $\text{Pt}_1 > 40$ & jet $\text{Pt}_2 > 20$).
 - ✓ MC: /ZH_ZtoNuNu_HtoBB_M-125_8TeV-powheg-herwigpp/Summer12-START50_V13-v3 (with $\langle \text{PU} \rangle \sim 60$)
 - ✓ 1.8k events after L1_ETM40 preselection;
 - ✓ 1.1k events after other calo cuts ($\text{MET} > 80$ & jet $\text{Pt}_1 > 40$ & jet $\text{Pt}_2 > 20$).
- ✓ Let's see the results...



Test on signal



- ✓ For signal, the new algorithm finds:
 - ✓ Always a FastPV (instead of ~87% of the old one);
 - ✓ a good FastPV (<1.5 cm) in **~90% times (instead of ~74%)**;
 - ✓ a bad FastPV (>1.5 cm) only in ~10% times (instead of ~13%).
- ✓ We can reject events without FastPV without lose efficiency!
- ✓ **After tracking, the new algorithm finds the right primary vertex within $50\text{ }\mu\text{m}$ in ~87.1% times (it was ~83.2%).**
- ✓ The efficiency after the b-tag filter is ~67.3% (it was ~65.6%).



Test on data



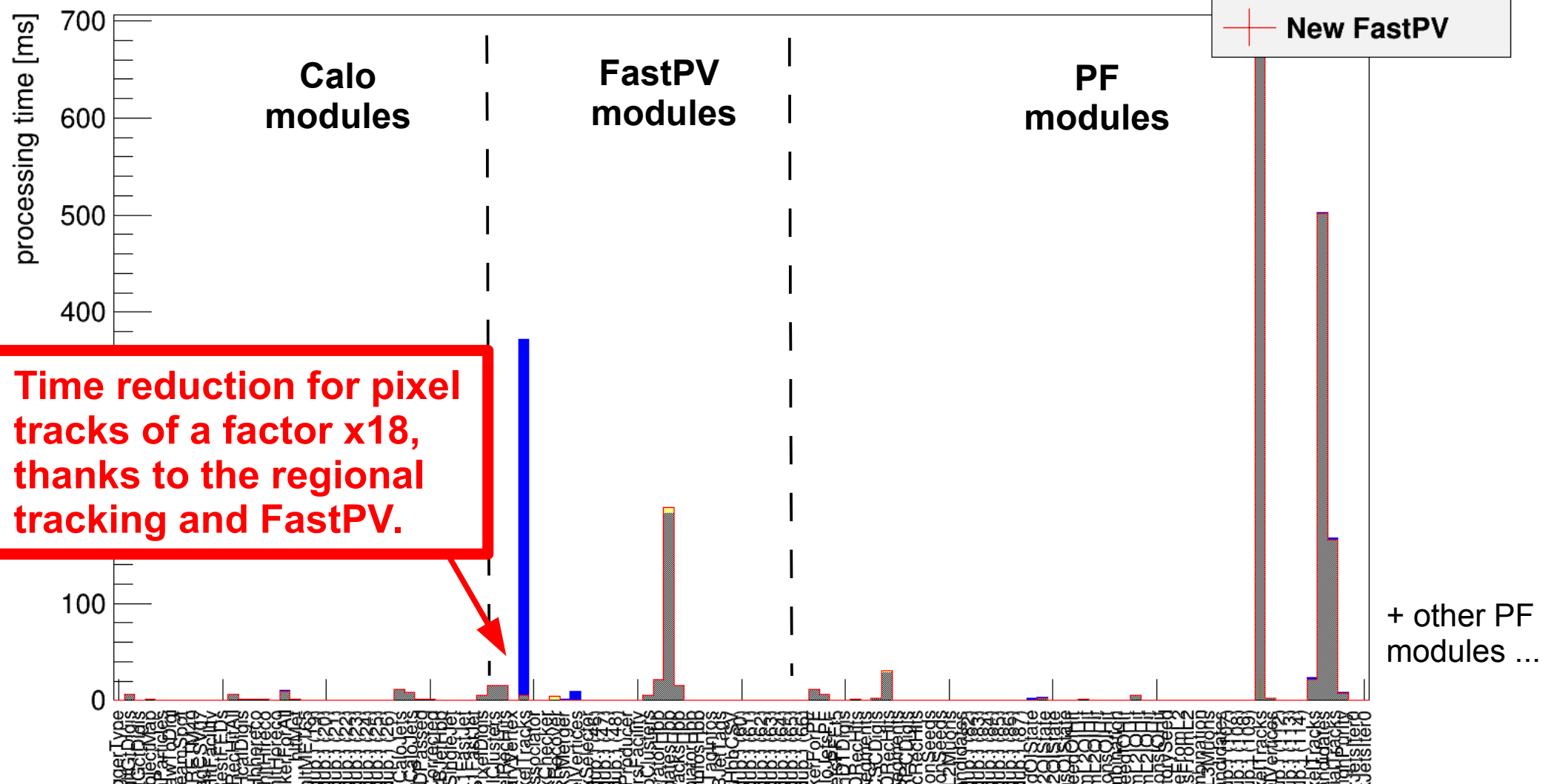
- ✓ In MinimumBias events, the new FastPV find a primary vertex in about $\sim 82\%$ of events (it was $\sim 77\%$).
 - ✓ So we reject the 18% of events without FastPV.
- ✓ The final efficiency for MinimumBias events, after the b-tag filter, is $\sim 3.55\%$ for the new algorithm and $\sim 3.46\%$ for the old algorithm.



Time module running



HLT_DiCentralPFJet30_PFMET80_BTagCSV07_v5 module running

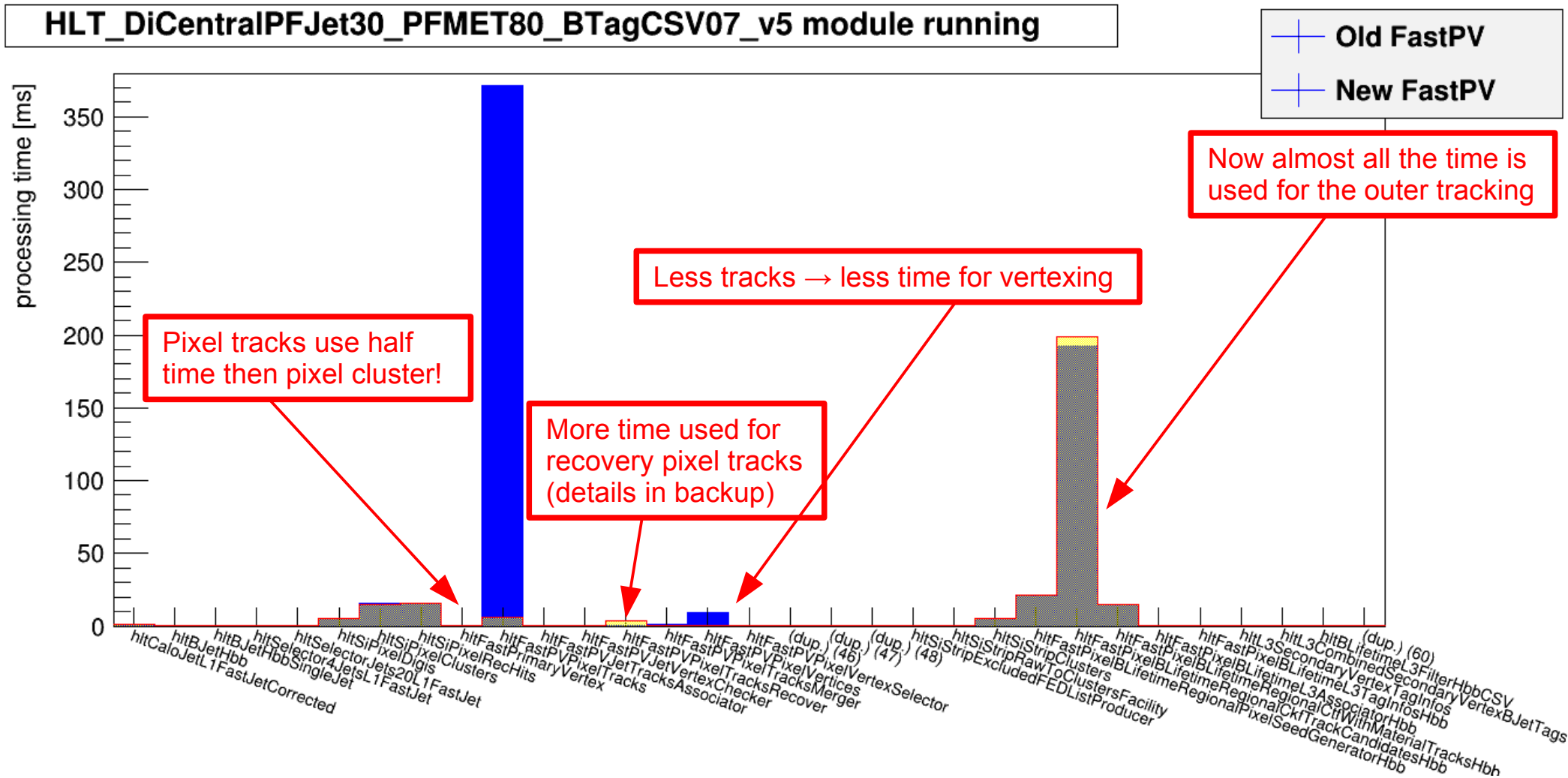




Time module running zoom



HLT_DiCentralPFJet30_PFMET80_BTagCSV07_v5 module running

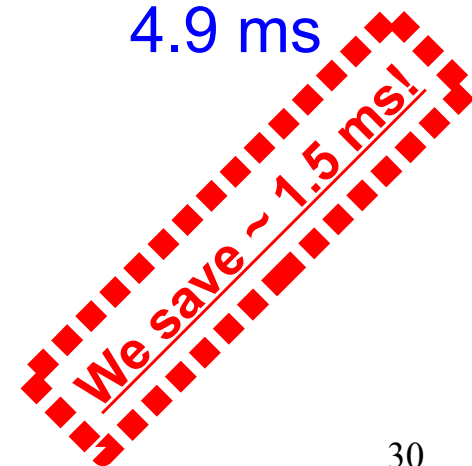




Timing



- ✓ We've used L1_ETM40 preselected events. To estimate the mean time used for a L1-pass events we divide it for $\text{rate(L1)}/\text{rate(L1_ETM40)} \sim 17$
- ✓ So the estimated mean time used by the trigger path is:
 - ✓ Calo: 2.1 ms (new Fast PV) vs 2.1ms (old FastPV)
 - ✓ Calo+Btag: 2.8 ms vs 4.3 ms
 - ✓ Calo+Btag+PF: 3.3 ms vs 4.9 ms





Conclusions



- ✓ The performance of the FastPrimaryVertex algorithm has been improved using the cluster weightings and exploiting the pixel clusters from EndCaps.
- ✓ The new algorithm has a higher efficiency to find the right primary vertex.
- ✓ The regional pixel tracking gives us a faster trigger with more efficiency to find the right Primary Vertex!
- ✓ The new FastPV has been tested in HLT DiCentralPFJet30 PFMET80 BTagCSV07 trigger path using high PU data and simulated signal.
- ✓ **With the new setting we have a small increase of efficiency and rate, and a faster trigger!**



Outlook



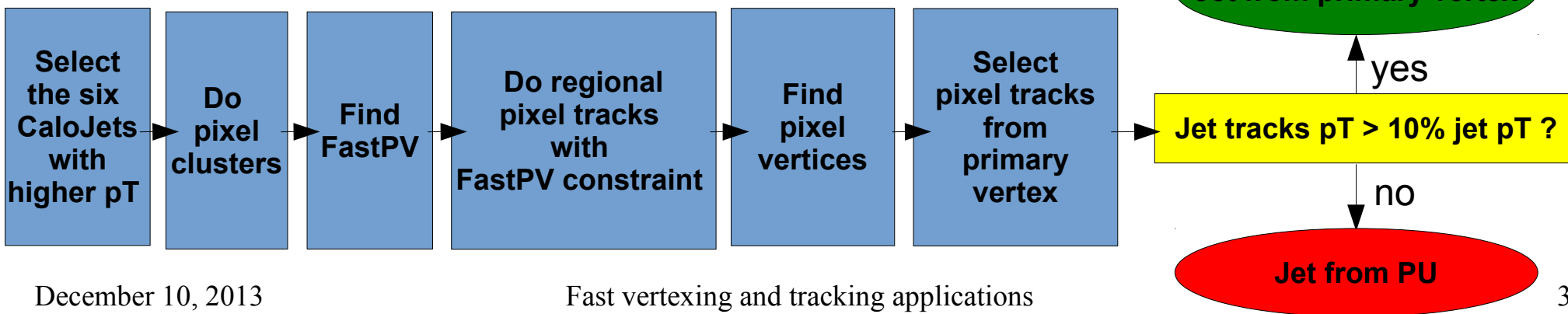
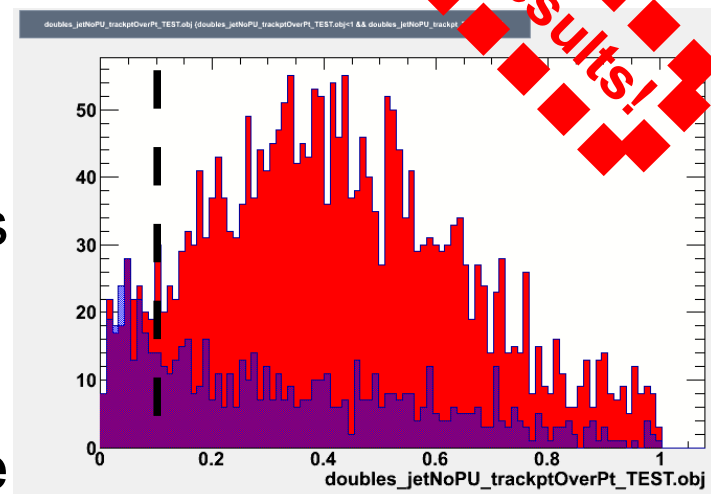
- ✓ Recover some inefficiencies due to bad pixel vertexing, after FastPV.
- ✓ Check the tracking in the outer tracker to improve the b-tag efficiency.
- ✓ Do regional pixel cluster instead of the (slow) full pixel clustering.
- ✓ **Exploit FastPV and regional pixel tracking in multijet trigger in order to reject PU jets.**
- ✓ Study of other possible use cases (eg. find hadronic taus, calculate tracking isolation).



Multijet trigger



- ✓ We tested a first implementation of a trigger with a jet PU rejection based on FastPV and regional pixel tracking.
- ✓ We used RadionToHH_4b_M-450_TuneZ2star_8TeV-Madgraph_pythia6 as signal with **<PU> ~60**.
- ✓ After the preselection of HLT_QuadJet45 (parked), we get a reduction of the rate to the 37% and an efficiency on signal of 83%.
- ✓ The jet PU rejection is based on:





Backup



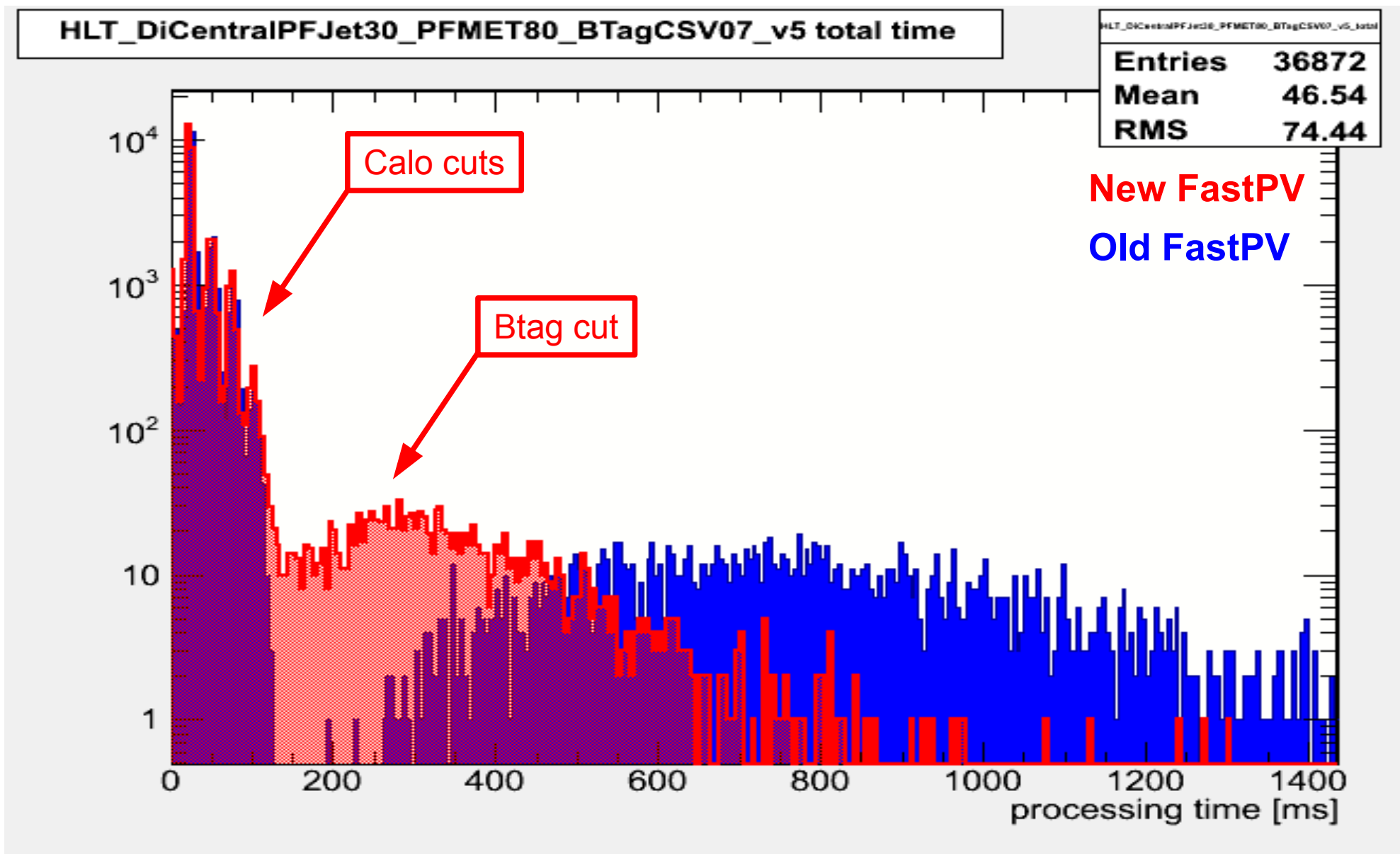
Vertex checker



- ✓ To recover the events with a wrong FastPV, we use the “vertex checker”.
- ✓ For each jet, it check that at least 5% of the energy of the jet is seen in pixel tracks:
 - ✓ If a jet don't pass the checker we redo the regional tracking around the jet, but without the FastPV constraint.
- ✓ With the new algorithm we have more time so we had increased the threshold to pass to 10% of the jet energy.
 - ✓ So now we spend more time in the vertex checker module.

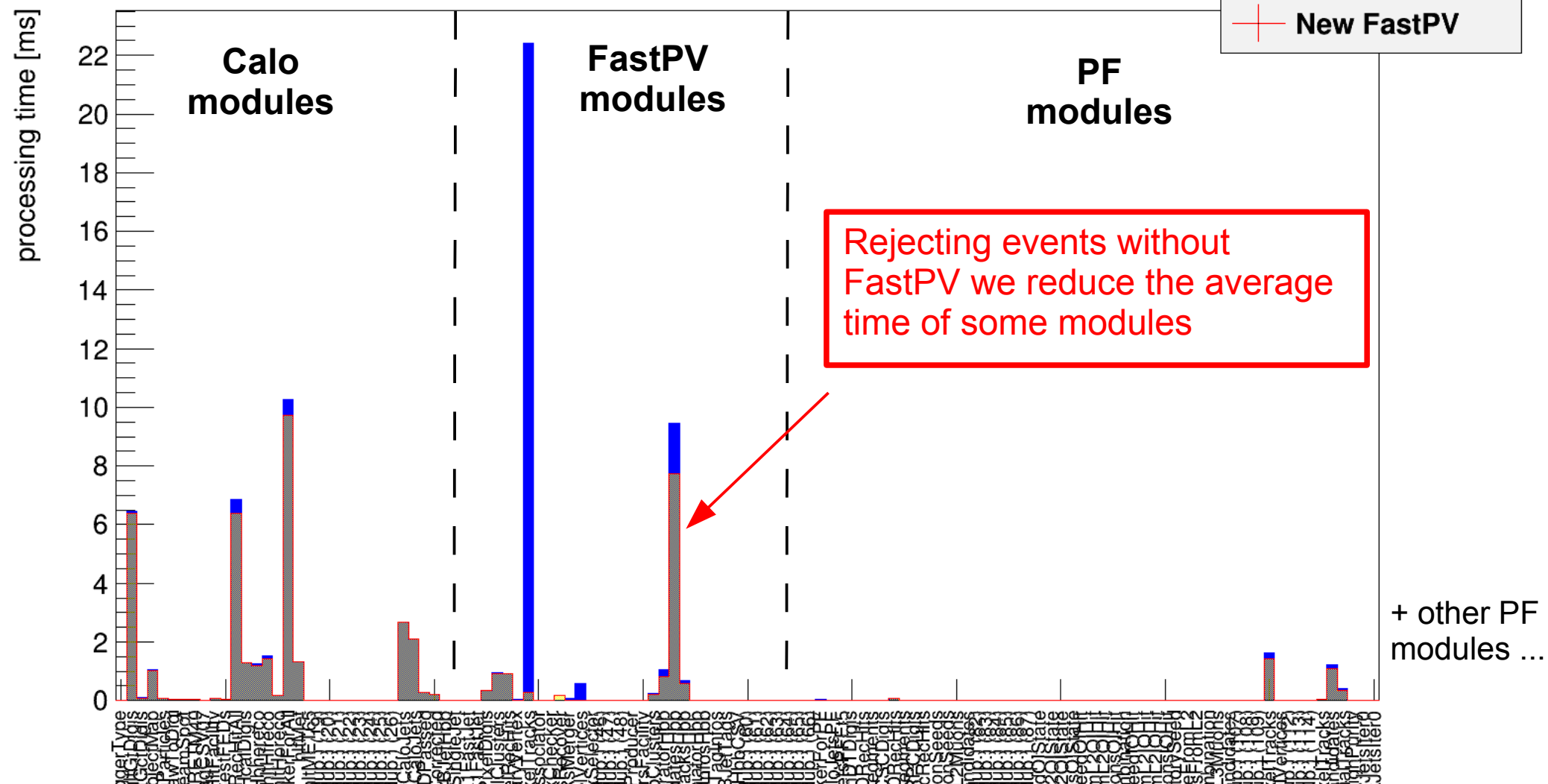


Total time (without PF)



Time module average

HLT_DiCentralPFJet30_PFMET80_BTagCSV07_v5 module average

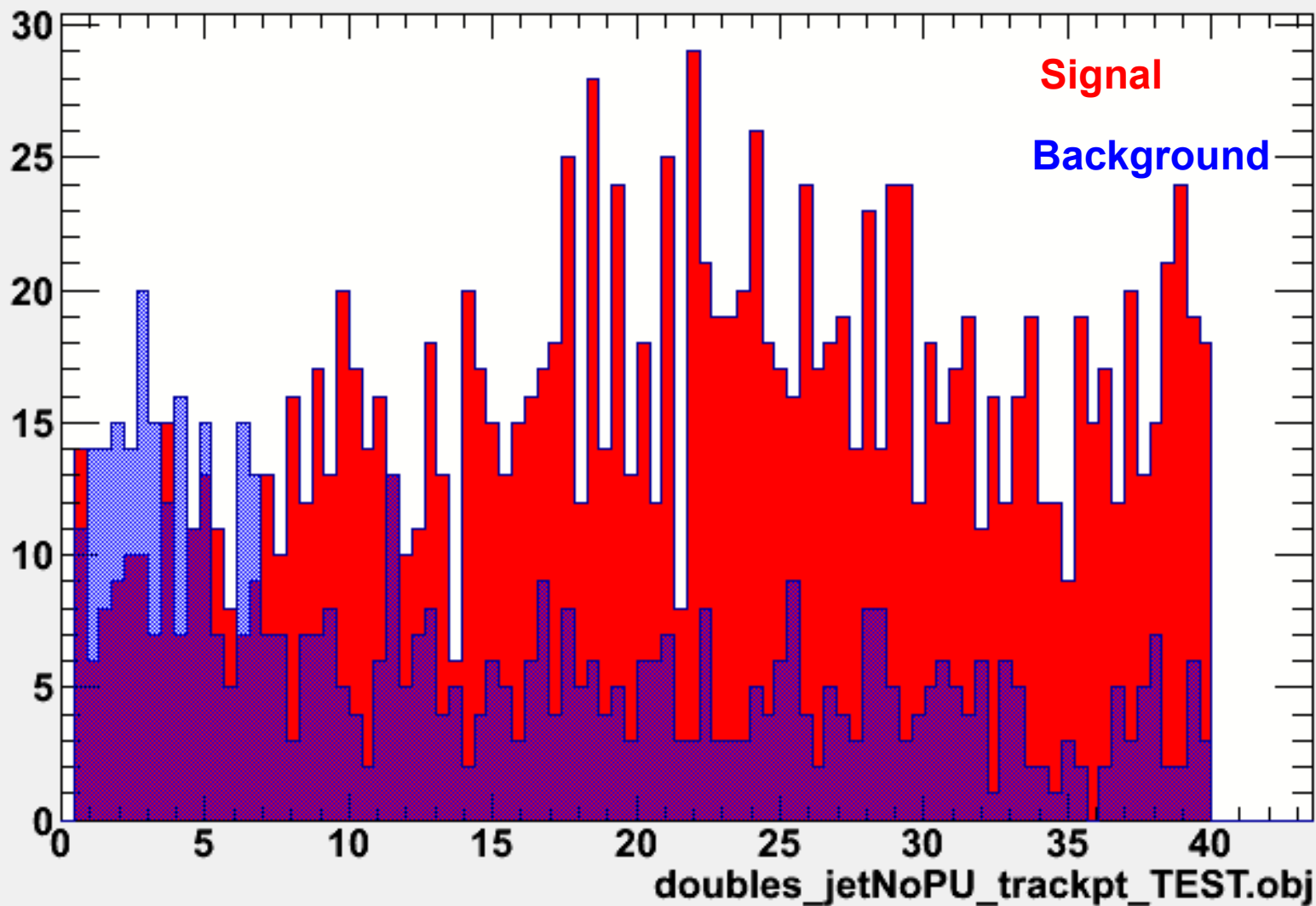




TrackPt



`doubles_jetNoPU_trackpt_TEST.obj {doubles_jetNoPU_trackpt_TEST.obj<40 && doubles_jetNoPU_trackpt_TEST.obj>0}`

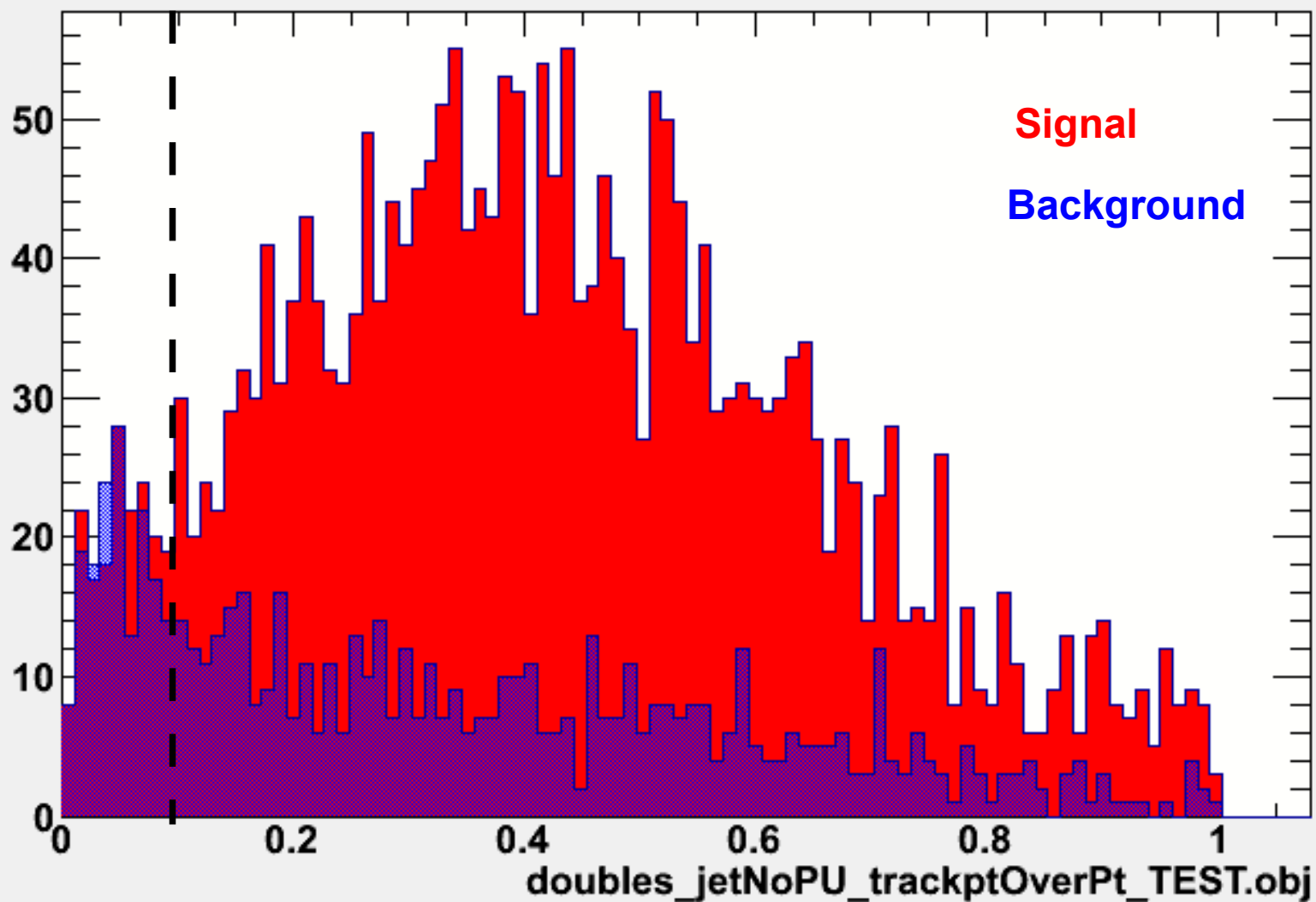




TrackPt/JetPt



`doubles_jetNoPU_trackptOverPt_TEST.obj (doubles_jetNoPU_trackptOverPt_TEST.obj<1 && doubles_jetNoPU_trackpt_TEST.obj>0)`

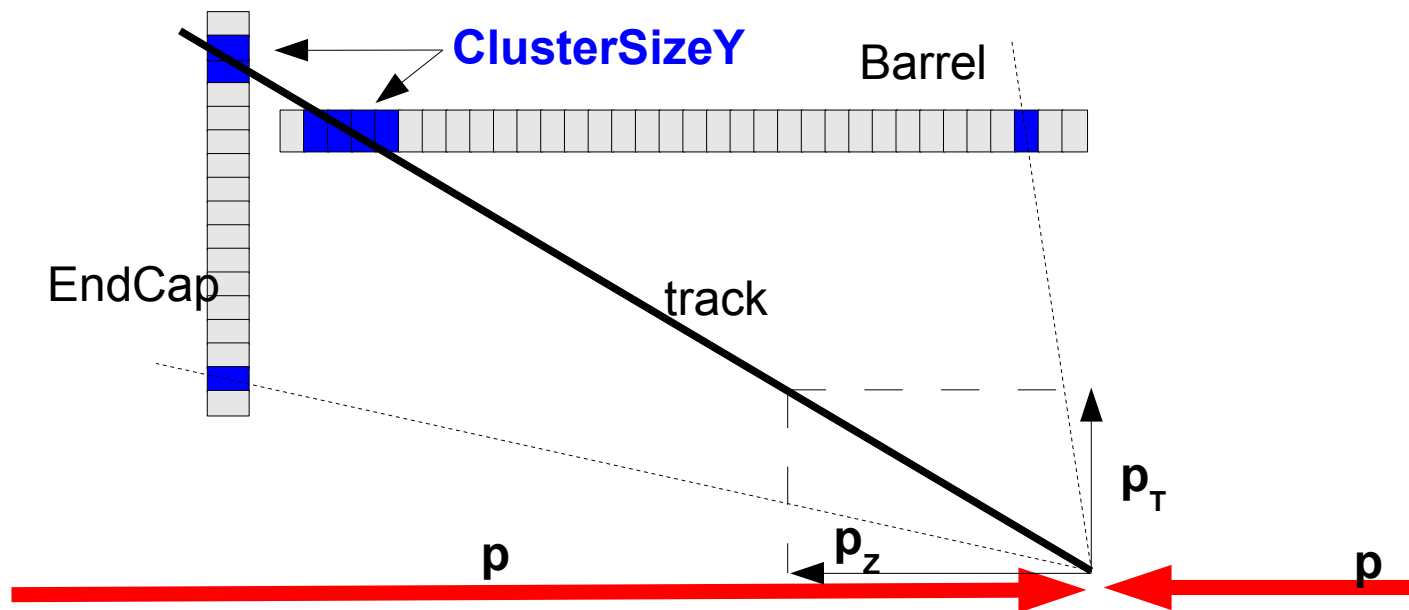




Clusters from EndCaps



- ✓ The projection of an EndCap cluster is similar.
- ✓ The main difference is the different expected clusterSizeY.
 - ✓ For Barrel we expect a clusterSizeY near to $1.8 * | \text{jetPz} / \text{jetPt} |$.
 - ✓ For EndCap we expect a clusterSizeY near to $1.8 * | \text{jetPt} / \text{jetPz} |$.



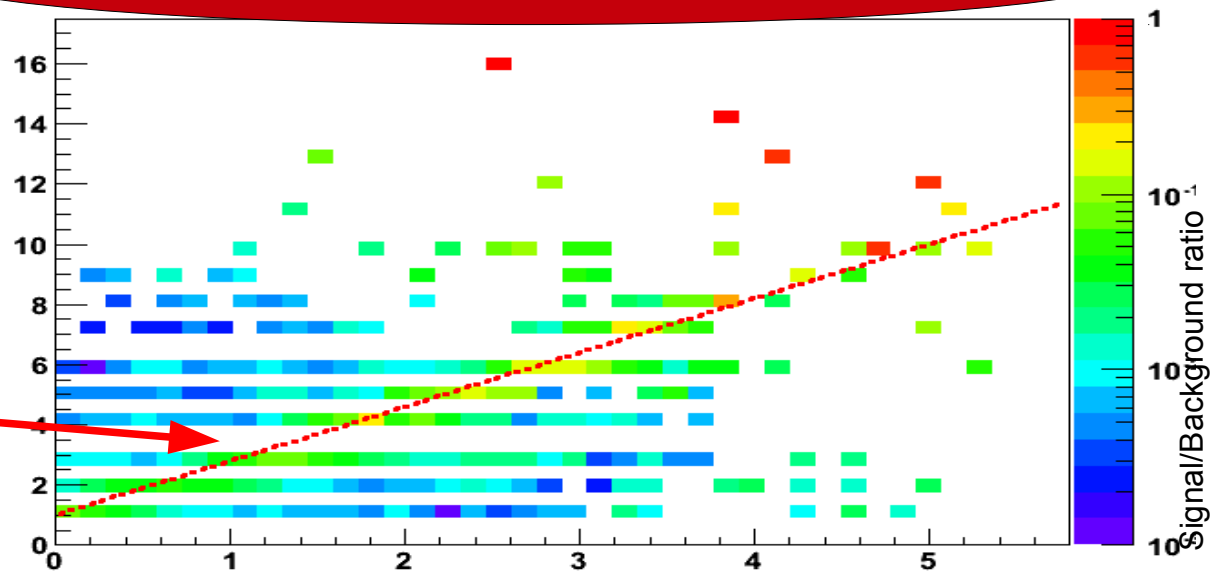


Cluster Size Y vs jet Eta



ClusterSizeY vs $|\text{jetPz}/\text{jetPt}|$

Better agreement
using 1.8 instead of 2.0





PileUp distribution



pileup

