ATLAS Fast Framework

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Elmar Ritsch (Univ. Innsbruck, CERN) on behalf of the ATLAS collaboration

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Overview

$\ensuremath{\mathcal{O}}$ Framework Vision

one flexible and common framework

O Framework Requirements

reproducibility, predictability

\mathcal{O} Simulator Requirements

many simulators talking to one common framework

\mathcal{O} Challenges

and lessons learned

ATLAS Simulation Engines (recap)



Geant4 + Frozen Showers

- the top dog, used by many HEP experiments, extensively used in ATLAS
- high accuracy simulation of particle-material interactions
- takes a huge amount of CPU resources

FastCaloSim

- parameterized calorimeter simulation
- much much faster calorimeter simulation compared to Geant4
- parameterized calorimeter punch-through module

Fatras

- fast tracker simulation
- based on a simplified geometry description and particle-material interaction model

Consequence

- increasing number of ATLAS detector simulation engines
- $\rightarrow\,$ complex and incompatible setups



The Integrated Simulation Framework (ISF)

ISF Vision

- one framework for various simulation engines
 - core ISF responsibilities: ISF particle stack, particle routing, MC truth handling, barcode service
- allow to select simulation engine on a particle level
 - speedup expected
 - modularity allows for various parallelization approaches



The First Multi-Simulator ISF Run







Basic Router Requirements

- static routing rules: e.g. using kinematic parameters or particle type
- dynamic routing which considers other particles in the event
- simple to configure
- intuitive, no deep knowlegde of the ISF should be needed



Two Examples

- Particle Type Selector: send all muons to SimulatorA
- Kinematic Particle Selector: send all high η particles to SimulatorB

Pros

- order independent
- fully **consistent**: with the knowledge of particles after event simulation, the exact same decisions would have been made
- intuitive for the user
- single pass (each particle only simulated once)

Keep in Mind

- selector decisions may contradict each other
- $\rightarrow\,$ selectors need to be defined in a priority list

Dynamic Router Example: Cone Selector





Dynamic Cone Selector

- the dynamic selector registers a cone for each new electron in the event
- all particles inside a cone are to be simulated in a certain simulation

Attention!

- decision on pion depends on the simulation order
- if π simulated before conversion: inconsistent selector decision

ISF Router Requirements





Router Requirements

- reproducible results
- order independence: important for concurrent processing
- arbitrary (dynamic) routing rules which may consider other particles in the event
- single pass: no re-simulation of the same particle (due to changing filter decisions)
- event consistency: with the knowledge of particles after event simulation, the same router decisions would have been made
- intuitive ISF routing logic and configuration

ISF Core Design

Main Components

- SimKernel: responsible for sending particles to simulators
 - Athena Algorithm with the main particle loop
- **ParticleBroker**: stores particles and determines which simulator should be used for each particle
 - uses RoutingChain to determine appropriate simulator
 - separate RoutingChains for each sub-detector



ISF Requirements to Simulators



Simulator Requirements

- particle handling: ISF internal particle collection ('StackManager')
- MCTruth: central ISF MC truth manager responsible for truth + barcode recording
- shared hit containers: various simulators writing into the same hit containers
- sub-detector boundaries: simulators give particles back to ISF on boundaries \rightarrow new routing decision required, due to varying technologies in different sub-detectors



ISF Setups in use / under validation

Classical setups

- $\rightarrow~$ static routing rules only
 - full Geant4 for all sub-detectors
 - ATLFASTII: G4 for InDet and muons, FastCaloSim for calorimeter
 - ATLFASTIIF: Fatras for InDet and muons, FastCaloSim for calorimeter

Dynamic particle routing

 \rightarrow dynamic, only at generator event-level

- signal decay products in Geant4, rest in Fatras/FastCaloSim
- **cones around signal** decay products in Geant4, rest in Fatras/FastCaloSim
 - inside/outside cones checked at generator event-level
 - optionally re-check if particle still inside cone at InnerDet/Calo boundary

 $(Z \rightarrow ee, H \rightarrow 4\ell)$

Challenges

Partial Event Simulation for $H \rightarrow \gamma \gamma$



Why ISF?

- need high statistics
- need accurate description of photons in ID and Calo
- \rightarrow simulate only parts of the event with ISF
- ightarrow region of interest is in cones around EvGen signal photons



Partial Event Simulation: What you gain

What you gain

- spending less (no) simulation time on SimHits no one cares about
- smaller simulation output files
- faster Digitization
- faster Reconstruction



Partial Event Simulation: Where you lose

Where you lose

- global event variables gone $(\sum E_T, \text{ missing } E_T)$
- $\rightarrow\,$ analysis side covered in Andi's talk



Unconverted photons

- two photons not converted
- some charged particles inside cones creating hits



Bending out particles I

- two photons not converted
- charged particle initially inside cone bends out
- one electron from pair conversion bends out from the cone
 - $\rightarrow\,$ some CPU time spent on information that is not needed



Bending out particles II

- two photons, one undergoes pair-conversion
- charged particle initially inside cone bends out
 - $\rightarrow\,$ some CPU time spent on information that is not needed



Particles bending out massively

a lot of initial particles bending out of cones

 $\rightarrow\,$ quite a lot CPU time spent on information that is not needed



Bookkeeping



Bookkeeping

- a number of simulators now creating hits for the same detectors
- simulators may need to know a particle's previous simulator type
- $\bullet\,$ bookkeeping neccessary \rightarrow which particles and hits created by which simulator
- $\rightarrow~$ encode simulator identifier into truth particle barcode
- ightarrow barcode is stored in MC-truth representation and sensitive detector hits



Simulator Consistency





Simulator Consistency

- output of simulator A and simulator B is input for simulator C
- simulators A and B have different tunings, energy cuts, ...
- \rightarrow simulation output for exactly the same generator particle will be different between simulator A and simulator B
- \Rightarrow consequently *simulator* C output will be different
- \rightarrow simulator C may need to take into account the originating simulator of a particle

Simulator Consistency – Scenario Example Scenario

- signal electrons simulated with Geant4 (produces many low-E secondaries)
- rest of ID simulated with Fatras (much higher secondary threshold)
- FastCaloSim takes any of the secondaries for calo simulation
 - $\rightarrow\,$ does not distinguish between Fatras or G4 secondaries
 - \rightarrow will be over/under-estimating the energy in the calorimeter





Parametrized Simulation

- fast punch-through simulation parametrized with Geant4 input/output
- needs to be parametrized together with FastCaloSim (highly correlated)



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Summary

- ISF is becoming the future ATLAS detector simulation framework
- ISF able to reproduce all current detector simulation setups
- ISF allows to combine simulation engines on a particle level
- balance between accuracy and speed on a particle level
- ISF can simulate only **parts of the event** (eg. signal only)
 - consequently saves diskspace, speeds up digitization and reconstruction
- validating first usecases of mixed full/fast simulation setups
 - do we need to correlate simulators?

Outlook

- studies on various parallelization approaches: multithreading, vectorization, ...
- more ISF usecases to come

Backup

ISF Routing Chain: Functionality





- 1. a particle is taken from the particle collection
- 2. SimulationSelectors are asked in a specific order whether they would select the particle
- 3. in case a SimulationSelector does not take the particle, it will be handed over to the next in the chain
- 4. the first SimulationSelector which returns true decides that the particle will be sent to the simulation attached to this SimulationSelector

ISF Routing Chain: Pros and Cons





- single pass: each particle simulated only once
- order independent
- intuitive in its functionality

Cons

• does not support fully dynamic SimulationSelectors, eg. the cones around every electron in the simulated event

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The User and the Routing Chain





How the user interacts with the Routing Chain

- user implements SimulationSelector(s) which make yes/no decisions
- user defines one Simulator for each SimulationSelector
- user specifies the order in which the SimulationSelector will be used:

```
ISFRouter.SimSelectorID = [ Selector1, Selector2, DefaultIDSelector ]
ISFRouter.SimSelectorCalo = [ Selector3, DefaultCaloSelector ]
ISFRouter.SimSelectorMS = [ Selector4, Selector5, DefaultMSSelector ]
```

• no deep insight in ISF functionality required by the user

MC Truth and Barcodes in ISF I





MC Truth and Barcodes in ISF II





TruthService

- one array of TruthStrategies per sub-detector
- TruthStrategies make a boolen decision based on information they can get from ITruthIncident: primary/secondary particle energy, type, number, interaction process, ...
- TruthIncident will be written to MCTruth only if at least one TruthStrategy in the corresponding array returned true

BarcodeService

- interchangeable Athena service
- no ISF dependency
- generates particle and vertex barcodes
- uses parent particle barcode and interaction type to generate secondary barcodes and update primary particle barcode
- current implementation reproduces MC12 behaviour, but ISF allows for way more:
- eg allows for *shared child particle barcodes* in case the truth incident is not recorded

Approach 3: Routing Chain with Incremental Locks



- 1. first filter will only be updated during read-in, afterwards: locked
- 2. simulate all particles selected by the first filter (update all dynamic filters)
- 3. simulate all child particles which are selected by the first filter until no more child particles of any generation are selected (*update filters*)
- 4. second filter will be locked
- 5. simulate all particles selected by the second filter (*update all dyn. filters down the chain*)
- 6. simulate all particles (and child particles) selected by the first two filters (*update filters down the chain*)

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Particle Barcode Handling in ISF





- parent particle keeps same barcode
- all child particles will be assigned the same barcode
 - allows eg. SimHit to parent particle association
- nothing will be added to the HepMC TruthEvent on StoreGate

Truth Incident stored



- update parent barcode after vertex
- each child particle gets a unique barcode
- adding all particles to the HepMC TruthEvent on StoreGate

in both cases, the parent particle barcode and an interaction process identifier are available to generate the corresponding new child barcodes or updated barcodes

Calorimeter MC Truth and Barcode Service



Status in MC12

- TrackRecords at CaloEntry, MuonEntry and MuonExit surfaces
- in favour of CPU time and disk space (**big impact**!), much fewer truth strategies inside calo compared to ID
- only **muon Bremsstrahlung** in HepMC TruthEvent: $E_{kin,\mu} > 500$ MeV and $E_{kin,\gamma} > 100$ MeV

Possibilities in ISF

- TrackRecords still there
- CPU time and disk space restrictions still apply
- Flexible Barcode Service:
 - possible to encode information about parent particle in all child particles
 - eg. would allow to to trace back particles at MuonEntry to initial particle CaloEntry, by using the barcode only
 - ISF-independent AthService which could be used for barcode encoding and decoding