

Parameter estimation (Fitting)

Terascale Statistics Tools School

1/2th April 2014, DESY Hamburg

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- Today: Least Squares fits
- Tomorrow: Maximum Likelihood fits and Masspeakfit-Tutorial (MINUIT)

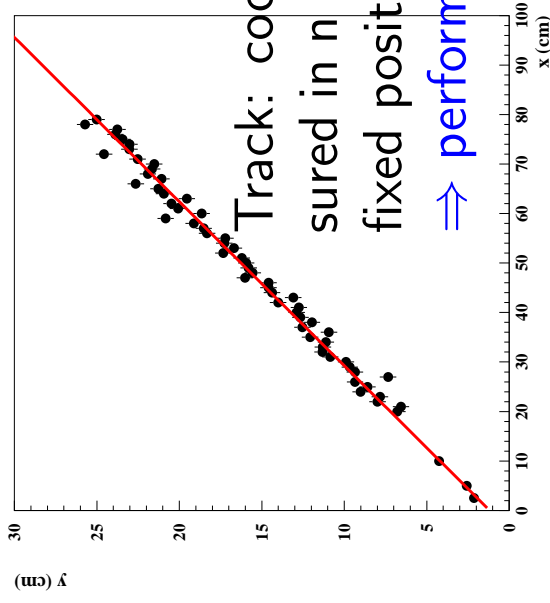
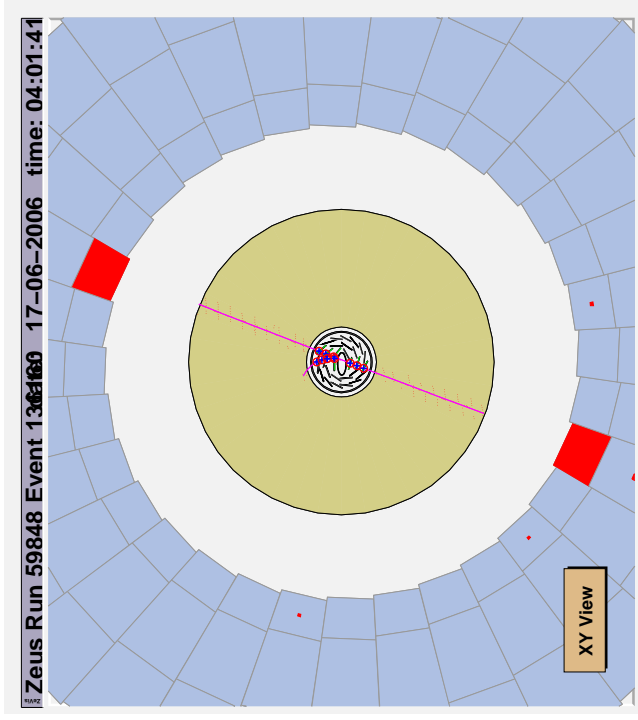
Literature:

- Roger Barlow: “Statistics, A Guide To The Use Of Statistical Methods In The Physical Sciences” Wiley & Sons, 1994
- Jay Orear: “Notes on Statistics for Physicists, Revised”, 1958,
http://www.astro.washington.edu/users/ivezic/Astr507/orear.pdf
- Olaf Behnke, Kevin Kröniger, Gregory Schott and Thomas Schörner Sadenius: “Data Analysis in-High-Energy-Physics” Wiley & Sons, 2013

Intro: Fitting is essential for our measurements!

Example: for possible discovery

$Z' \rightarrow \mu^+ \mu^-$ need precise muon track fits

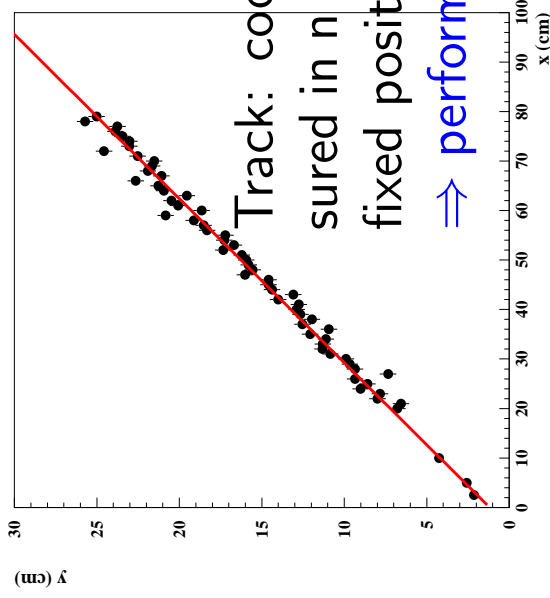
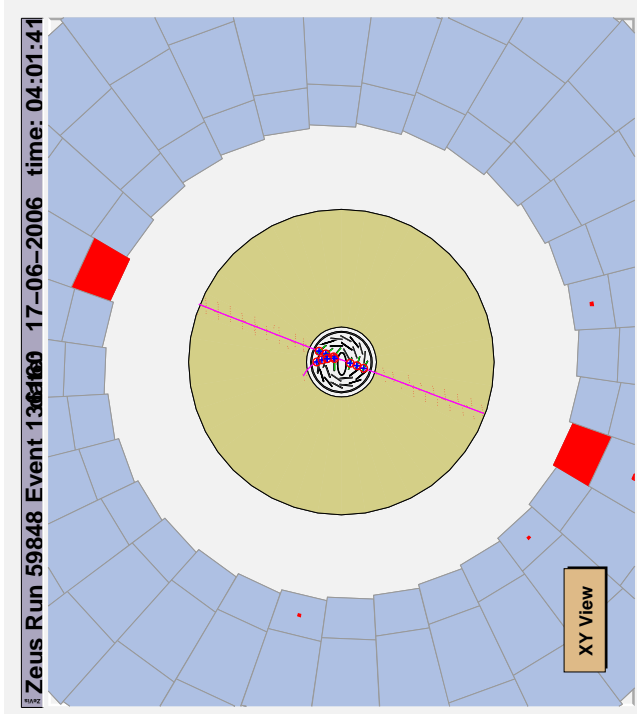


Track: coordinates y_i measured in n detector layers at fixed positions x_i
 \Rightarrow perform track fit

Intro: Fitting is essential for our measurements!

Example: for possible discovery

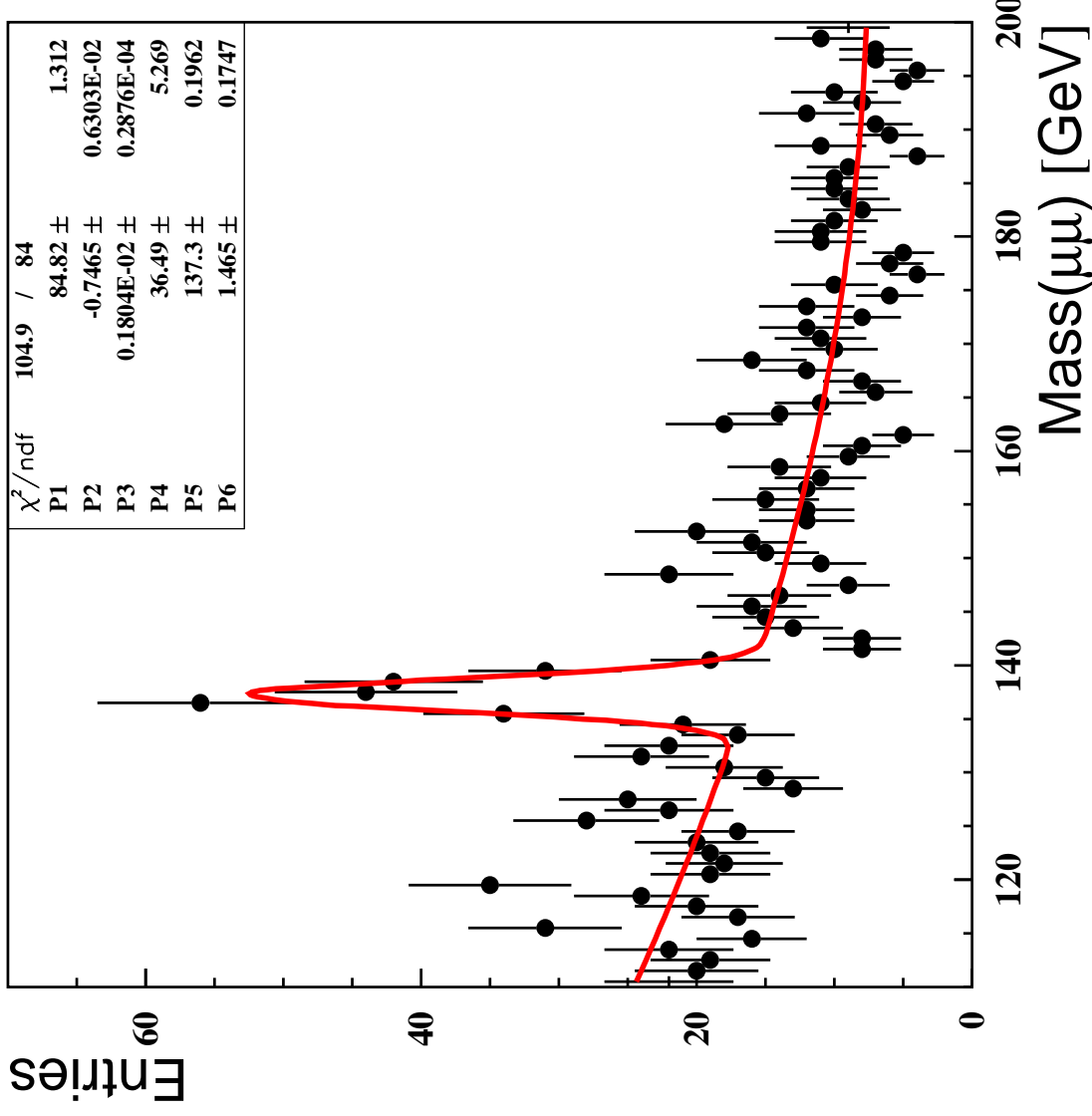
$Z' \rightarrow \mu^+ \mu^-$ need precise muon track fits



- Typical Assumptions:
 - Measurements with gaussian uncertainties
 - Linear(ized) model: $y = a_0 + a_1x + a_2x^2$ (but could also use exact track helix model)
- Construct χ^2 :
 - $$\chi^2 = \sum_i \frac{[y_i - (a_0 + a_1x + a_2x^2)]^2}{\sigma_i^2}$$
 - Determine a_0, a_1, a_2 by finding χ^2 minimum (normal equations)
- Check consistency:
 - use χ^2 and χ^2 -fit probability, reject outliers
- Analyse results:
 - parameters, errors and correlations (error ellipses), track trajectory error band
 - calculate momentum (error propagation)
- Analyse $\mu^+ \mu^-$ mass spectrum obtained from many events ⇒ see next page

Fitting is essential: Mass peak fit

Fit of mass spectrum with p2+g (option I)



Relevant questions:

- What you **really** want to know: Number of signal events, (cross section) mass and width of resonance
- Fit:
 - Use Poisson likelihood or χ^2 fit?
 - Parametrisation for signal and background
 - Choice of binning
 - etc.

All being discussed tomorrow!

Least Squares Fit lecture overview

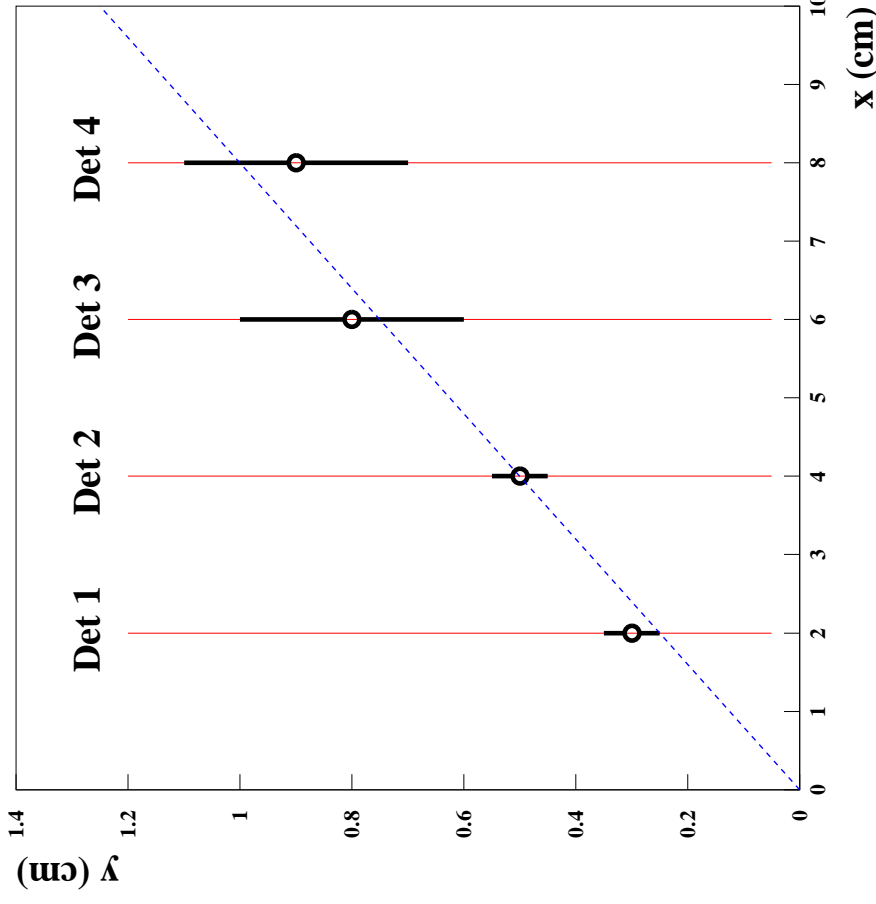
- 1) Least square χ^2 -fit method
 - most simple example: averaging measurements
- 2) Check consistency of a fit using χ_{min}^2
 - expected χ_{min}^2 distributions, reject outliers
- 3) Linear least square fits
 - examples, normal equations, straight line fit
- 4) Non Linear least square fits
 - fitting a gaussian with unknown peak position

1. Least square χ^2 -fit method

Please do not call it “schi.-squared-fit”

Method of least squares fit - Intro

Example: Particle trajectory measurement



n -measurements y_i \pm σ_i
at fixed x_i

Model: $y = f(x, a)$

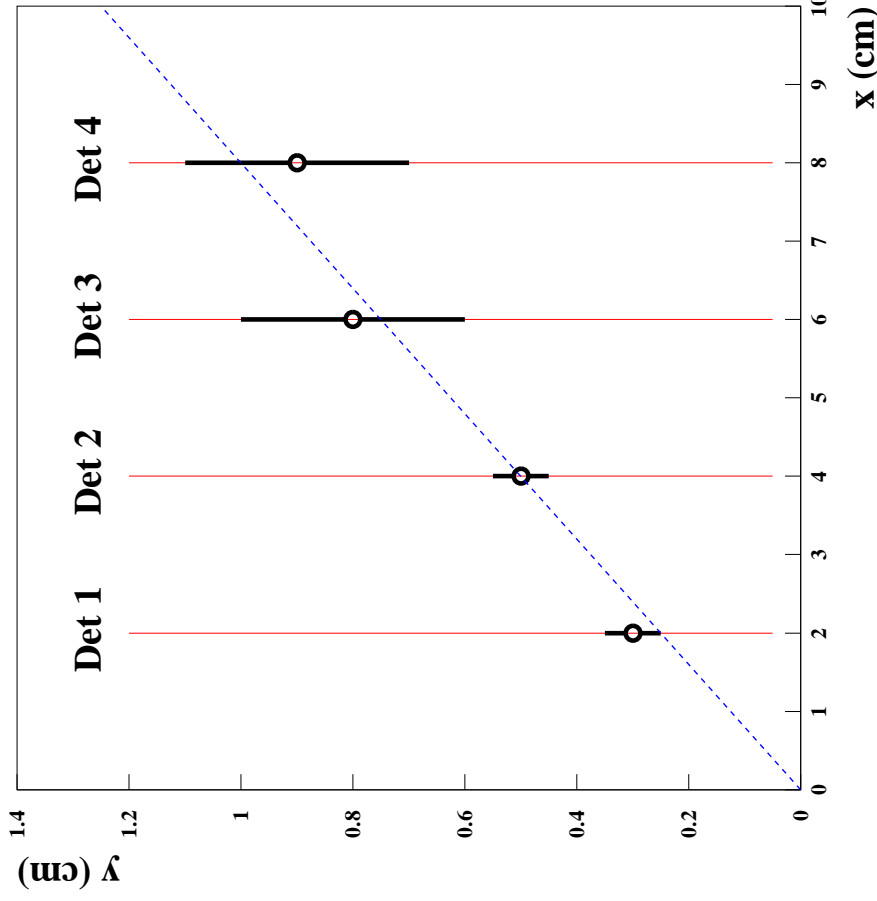
here: $y = ax$

\Rightarrow how to determine a ?



Method of least squares fit - Intro

Example: Particle trajectory measurement



n -measurements y_i \pm σ_i
at fixed x_i

Model: $y = f(x, a)$

here: $y = ax$

\Rightarrow how to determine a ?

\Rightarrow Idea: for correct a one expects: $|y_i - f(x_i, a)| \lesssim \sigma_i$

Method of least squares fit - Intro

$$\chi^2 = \sum_{i=1}^n \frac{(y_i - f(x_i, a))^2}{\sigma_i^2}$$

↔ Minimum w.r.t a

⇒ determine estimator \hat{a} from $\frac{d\chi^2}{da} = 0$

⇒

Method of least squares fit - Intro

$$\rightarrow \chi^2 = \sum_{i=1}^n \frac{(y_i - f(x_i, a))^2}{\sigma_i^2} \leftrightarrow \text{Minimum w.r.t } a$$

\Rightarrow determine estimator \hat{a} from $\frac{d\chi^2}{da} = 0$

$$\Rightarrow \frac{d\chi^2}{da}|_{a=\hat{a}} = 2 \cdot \sum_{i=1}^n \frac{(y_i - f(x_i, a))}{\sigma_i^2} \cdot \frac{df(x_i, a)}{da} = 0$$

In general not analytically solvable.

\Rightarrow use iterative (numerical) methods (MINUIT, Mathematica)

Method of least squares fit

Most general case

- y_i, y_j correlated measurement. with cov. V_{ij}
- m fitparameters \vec{a}

$$\chi^2 = \sum_{i,j=1}^n (y_i - f(x_i, \vec{a})) V_{ij}^{-1} (y_j - f(x_j, \vec{a}))$$

↑

=

Method of least squares fit

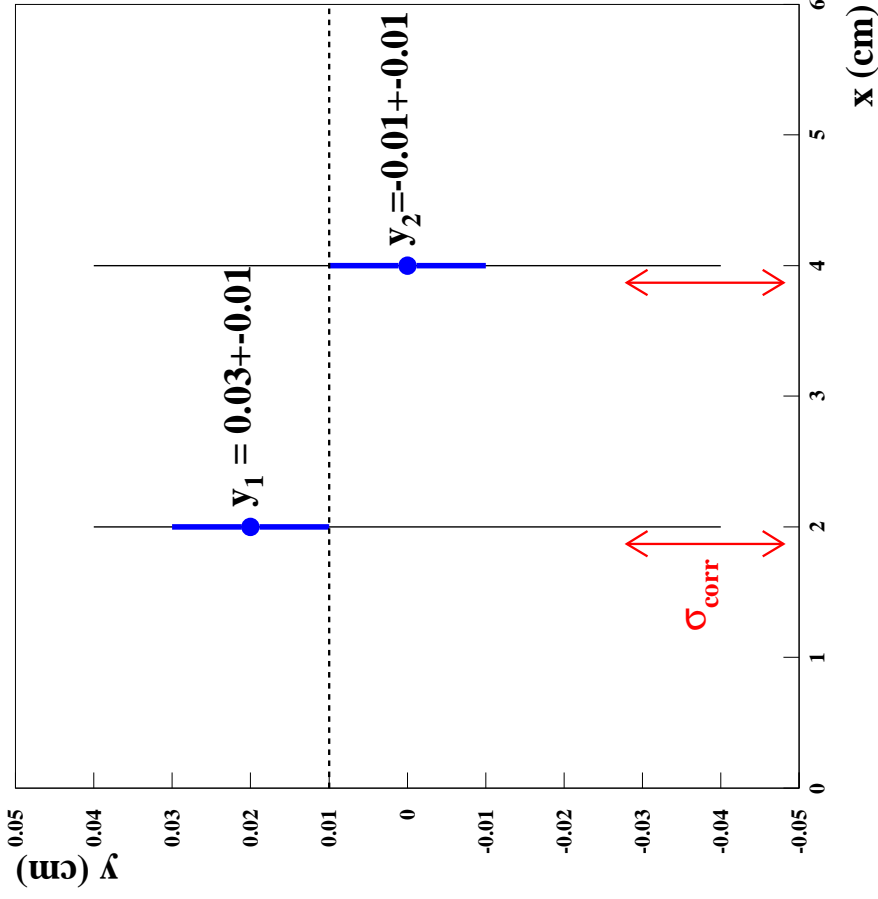
Most general case

- y_i, y_j correlated measurement. with cov. V_{ij}
- m fitparameters \vec{a}

$$\begin{aligned}\chi^2 &= \sum_{i,j=1}^n (y_i - f(x_i, \vec{a})) V_{ij}^{-1} (y_j - f(x_j, \vec{a})) \\ &= (\vec{y} - \vec{f}(\vec{a}))^t V^{-1} (\vec{y} - \vec{f}(\vec{a}))\end{aligned}$$

↑

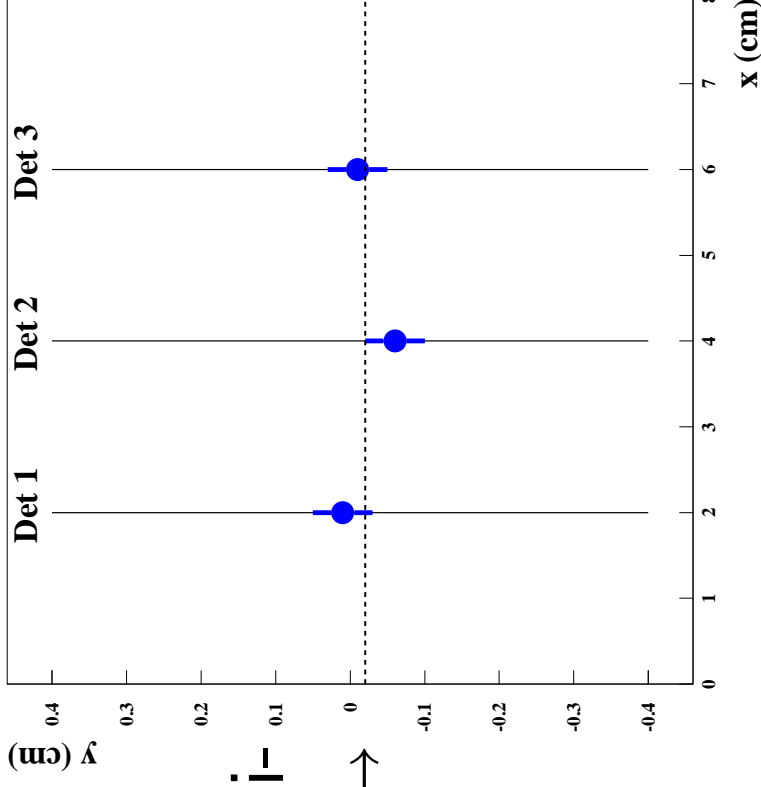
Example for two correlated measurements



Measure track in two detector layers
with global position uncertainty

$$V = \begin{pmatrix} 0.01^2 + \sigma_{\text{corr}}^2 & \sigma_{\text{corr}}^2 \\ \sigma_{\text{corr}}^2 & 0.01^2 + \sigma_{\text{corr}}^2 \end{pmatrix}$$

Fit of a constant



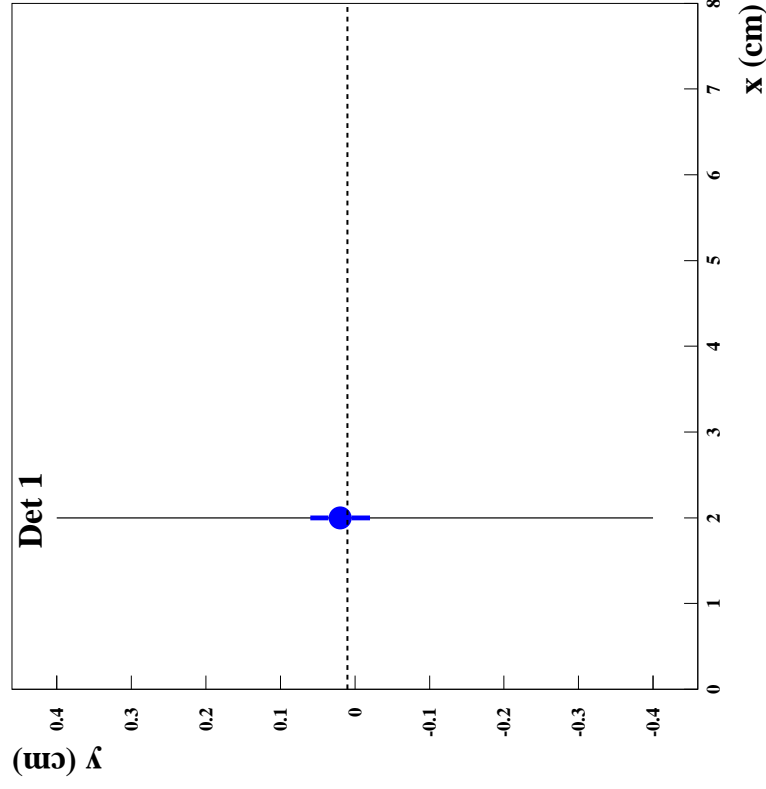
Measure position of horizontally flying particle \longrightarrow

\longrightarrow Averaging of n measurements $y_i \pm \sigma_i$

$$\chi^2 = \sum_i^n \frac{(y_i - a)^2}{\sigma_i^2}$$

Fit of a constant (one measurement)

“Idiot example” of one measurement $y_1 \pm \sigma_1$:



$$\chi^2 = \frac{(y_1 - a)^2}{\sigma_1^2}$$

$$\text{Min. } \chi^2 : \frac{d\chi^2}{da} = 0$$

→ Estimated value: $\hat{a} = y_1$

→ Error propagation: $\sigma_{\hat{a}} = \sigma_1$

True and inverse probability densities for one measurement

with gaussian uncertainty: $\hat{a} = y_1$, $\sigma_{\hat{a}} = \sigma_1$

True probability density to observe \hat{a} for given true value a_0 :

$$p = \frac{1}{\sqrt{2\pi}\sigma} \cdot e^{-\frac{(\hat{a}-a_0)^2}{2\sigma^2}}$$

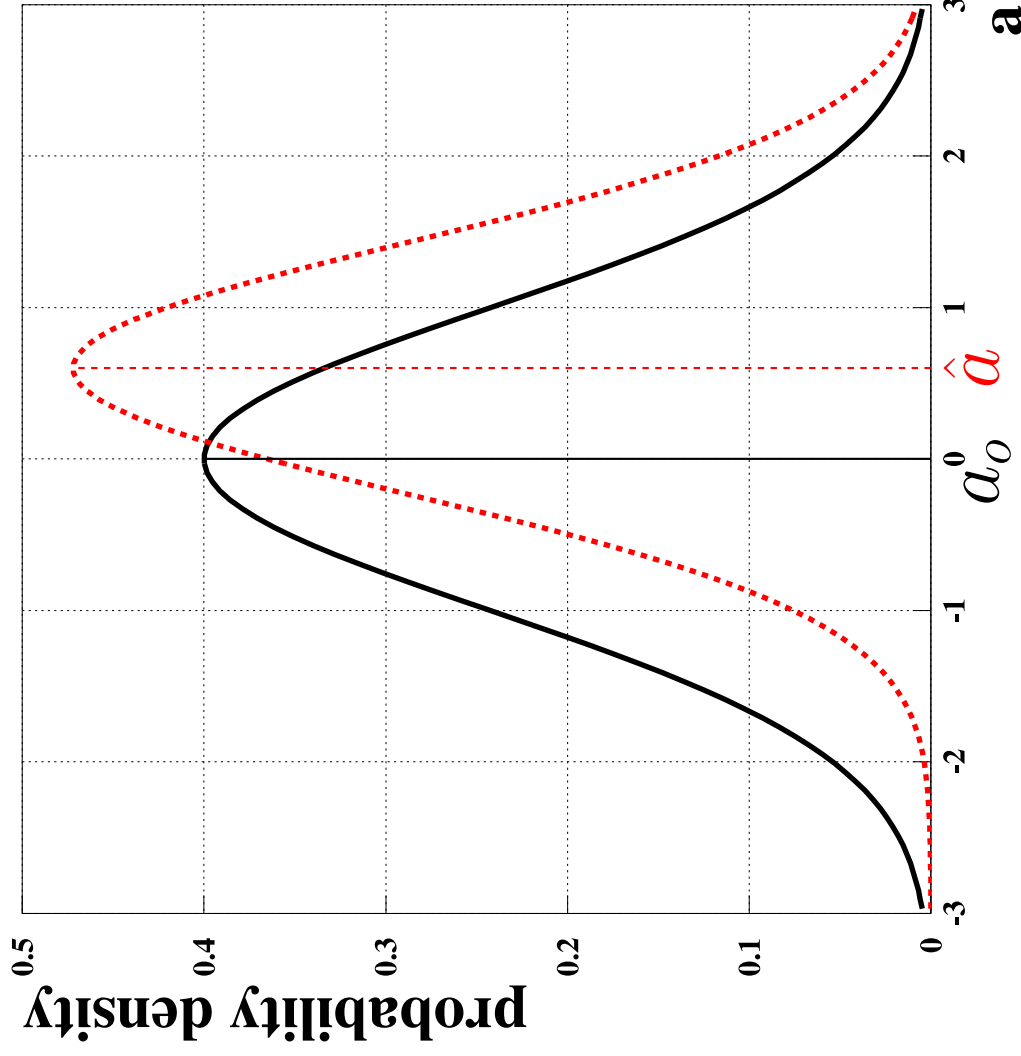
But what if we don't know a_0 ?

Estimate "inverse probability density" for a_0 from measurement $\hat{a} \pm \sigma_{\hat{a}}$:

$$p = \frac{1}{\sqrt{2\pi}\sigma_{\hat{a}}} \cdot e^{-\frac{(\hat{a}-a_0)^2}{2\sigma_{\hat{a}}^2}}$$

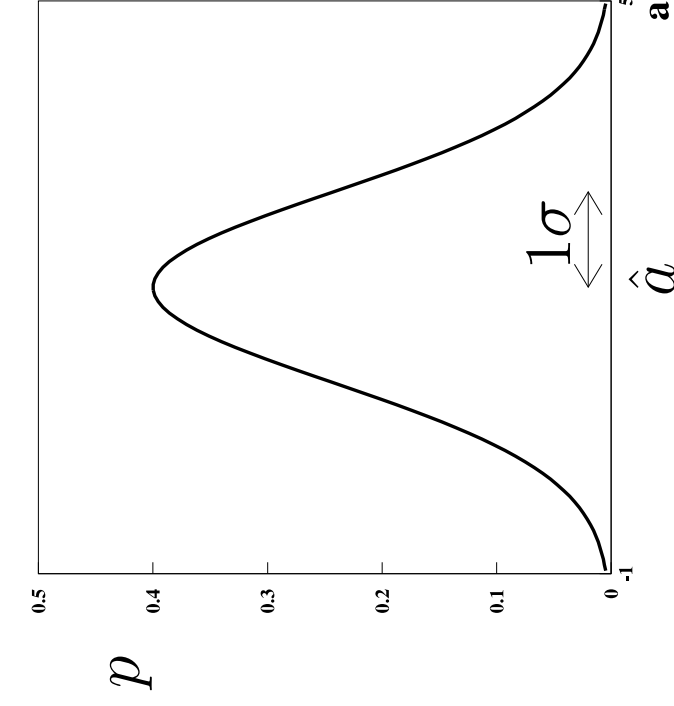
Note: this is the Bayesian posterior probability density and not a real prob. density!

from now on we will use a as synonym for a_0 !



Fit of a constant (one measurement)

Inverse probability density for true a :



$$p \sim e^{-\frac{(a-\hat{a})^2}{2\sigma_{\hat{a}}^2}}$$

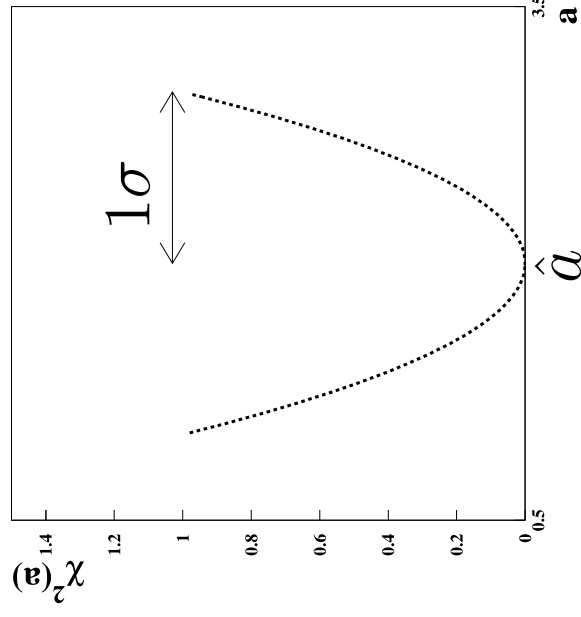
with $\chi^2 = \frac{(a-\hat{a})^2}{\sigma_{\hat{a}}^2} \Rightarrow p \sim e^{-\chi^2/2}$

Two methods to determine $\sigma_{\hat{a}}^2$:

$$\frac{1}{\sigma_{\hat{a}}^2} = \frac{1}{2} \frac{d^2 \chi^2}{da^2} \Big|_{a=\hat{a}} \quad \text{or from}$$

$$\chi^2(\hat{a} \pm \sigma_{\hat{a}}) - \chi^2(\hat{a}) = 1$$

Note: These are the two standard error determination methods for χ^2 fits! In general the second one is more reliable (See Max. Likelihood lecture)



Fit of a constant - many measurements

Probability density for true value a to observe measurements

y_i , with $i = 1, n$:

$$\begin{aligned} p(y_1, y_2, \dots, y_n | a) &\propto \prod_{i=1}^n e^{-\frac{(y_i - a)^2}{2\sigma_i^2}} \\ &= e^{-\frac{1}{2} \sum_{i=1}^n \frac{(y_i - a)^2}{\sigma_i^2}} = e^{-\chi^2/2} \end{aligned}$$

but we don't know true a ,

so let's turn the whole thing around to estimate probability density for true a from the measurements

Fit of a constant - many measurements

$$p(y_1, y_2, \dots, y_n | a) = e^{-\chi^2/2}$$

Expand χ^2 around its minimum at \hat{a} :

$$\chi^2 = \chi^2(\hat{a}) + \underbrace{\frac{d\chi^2}{da}}_{=0} \Big|_{a=\hat{a}} \cdot (a - \hat{a}) + \frac{1}{2} \frac{d^2\chi^2}{da^2} \Big|_{a=\hat{a}} \cdot (a - \hat{a})^2$$

Fit of a constant - many measurements

$$p(y_1, y_2, \dots, y_n | a) = e^{-\chi^2/2}$$

Expand χ^2 around its minimum at \hat{a} :

$$\chi^2 = \chi^2(\hat{a}) + \underbrace{\frac{d\chi^2}{da}}_{=0} \Big|_{a=\hat{a}} \cdot (a - \hat{a}) + \frac{1}{2} \frac{d^2\chi^2}{da^2} \Big|_{a=\hat{a}} \cdot (a - \hat{a})^2$$

$$= \chi^2(\hat{a}) + H \cdot (a - \hat{a})^2 \quad \text{with } H = \frac{1}{2} \frac{d^2\chi^2}{da^2} \Big|_{a=\hat{a}} \quad \begin{array}{l} \text{'Hesse matrix'} \\ \text{(for one par. a number)} \end{array}$$

$$\Rightarrow p(y_1, y_2, \dots, y_n | a) \propto \underbrace{e^{-\frac{\chi^2(\hat{a})}{2}}}_{e^{-\frac{1}{2} H \cdot (\hat{a} - a)^2}} \cdot \underbrace{\phantom{e^{-\frac{1}{2} H \cdot (\hat{a} - a)^2}}}_{\text{gaussian density}}$$

Fit consistency gaussian density

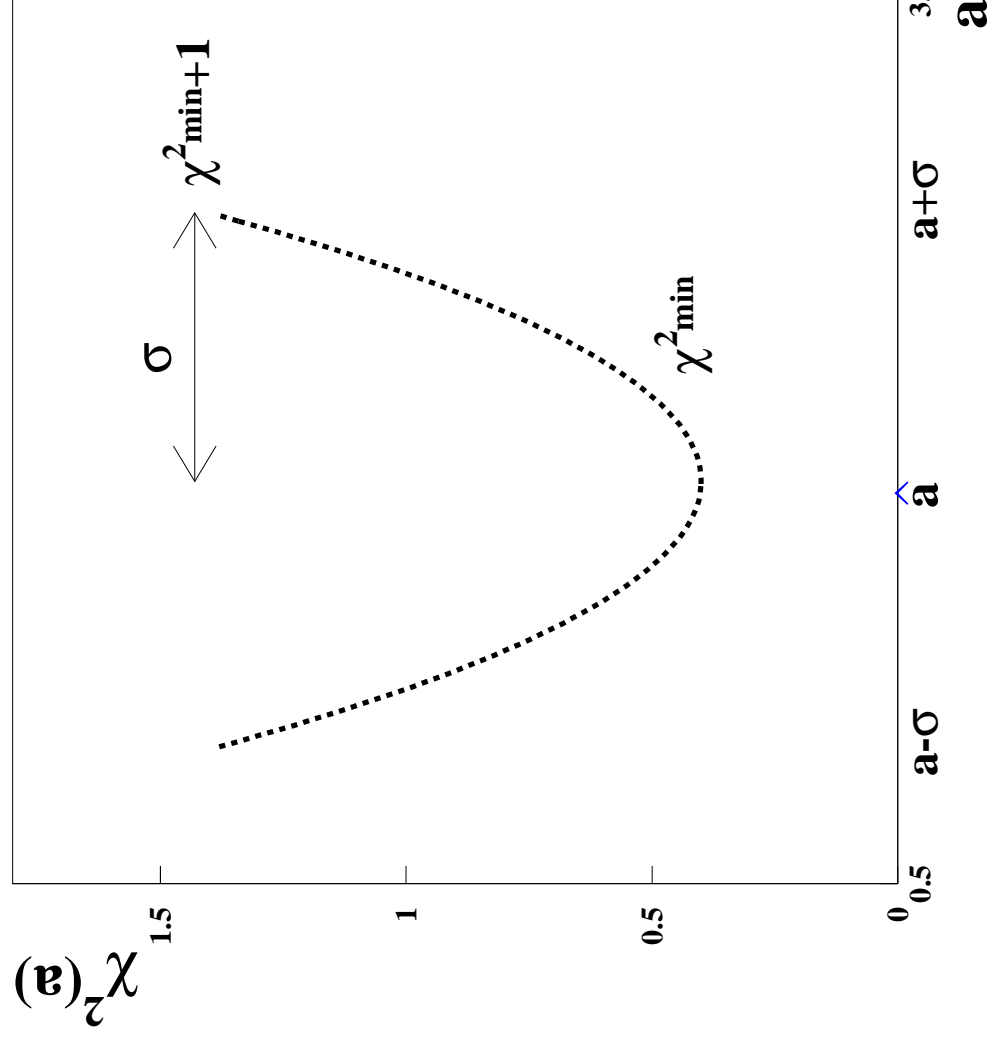
\Rightarrow interpreted as *inverse probability density for true a* :

Gaussian distribution around \hat{a} with width $\sigma = H^{-1/2}$

Generalisation to any one-parameter (linear) fit

$$\chi^2(a) = \chi^2(\hat{a}) + \frac{(a - \hat{a})^2}{\sigma_{\hat{a}}^2}$$

$$\rightarrow \chi^2(\hat{a} \pm 1\sigma_{\hat{a}}) = \chi^2(\hat{a}) + 1 = \chi_{min}^2 + 1$$



→ Read error directly
from χ^2 curve

Mini-exercise Averaging of two meas. via χ^2 parabolas

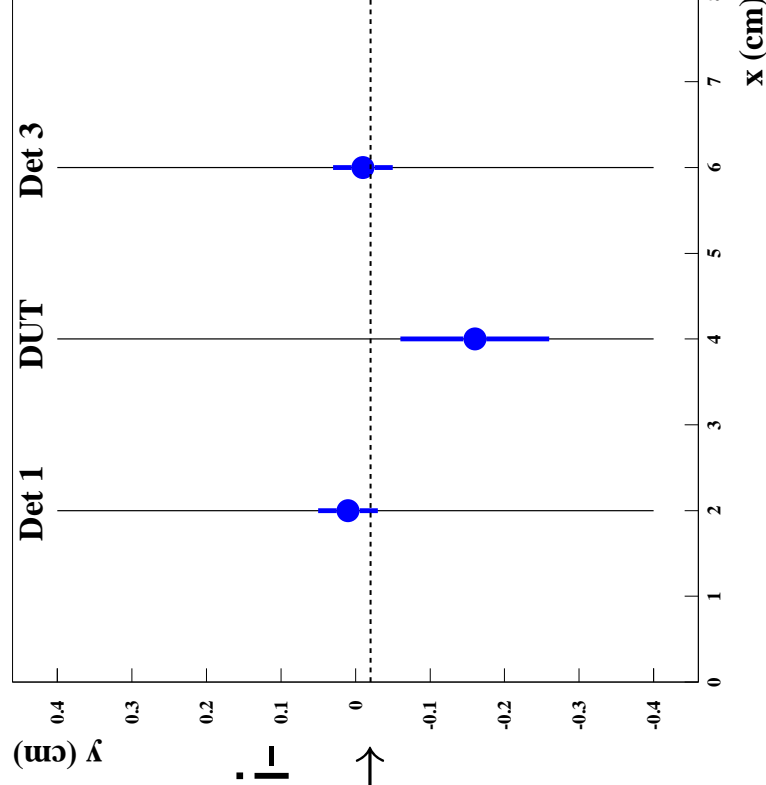
Paper exercise

Averaging several measurements

n measurements $y_i \pm \sigma_i$ (Note: $\sigma_1 \neq \sigma_2$, etc.)

(Quiz question: Why is $\frac{1}{n}\sum y_i$ not the best average?)

Measure position of horizontally flying particle \longrightarrow



Averaging several measurements

n measurements $y_i \pm \sigma_i$:

$$\chi^2 = \sum_{i=1}^n \frac{(y_i - a)^2}{\sigma_i^2}$$

$$\frac{d\chi^2}{da} = 0 = \sum_{i=1}^n \frac{-2(y_i - a)}{\sigma_i^2} = -2 \sum_{i=1}^n \frac{y_i}{\sigma_i^2} + 2a \sum_{i=1}^n \frac{1}{\sigma_i^2}$$

Averaging several measurements

n measurements $y_i \pm \sigma_i$:

$$\chi^2 = \sum_{i=1}^n \frac{(y_i - a)^2}{\sigma_i^2}$$

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$$\rightarrow \hat{a} = \frac{\sum_{i=1}^n \left[\frac{y_i}{\sigma_i^2} \right]}{\sum_{i=1}^n \left[\frac{1}{\sigma_i^2} \right]}$$

$$\frac{1}{\sigma_{\hat{a}}^2} = \frac{1}{2} \frac{d^2\chi^2}{da^2} = \sum_{i=1}^n \frac{1}{\sigma_i^2}$$

Averaging - just reformulated

→ Single measurements contribute with weight $G_i = \frac{1}{\sigma_i^2}$;

Define $G_s := \sum_{i=1}^n G_i$; Hesse matrix $H = \frac{1}{2} \frac{d^2 \chi^2}{da^2} = G_s$

$$\hat{a} = \frac{1}{\sum_{i=1}^n G_i} \cdot \sum_{i=1}^n G_i y_i = \frac{1}{G_s} \cdot \sum_{i=1}^n G_i y_i$$

$\sigma_{\hat{a}}$ from simple error propagation:

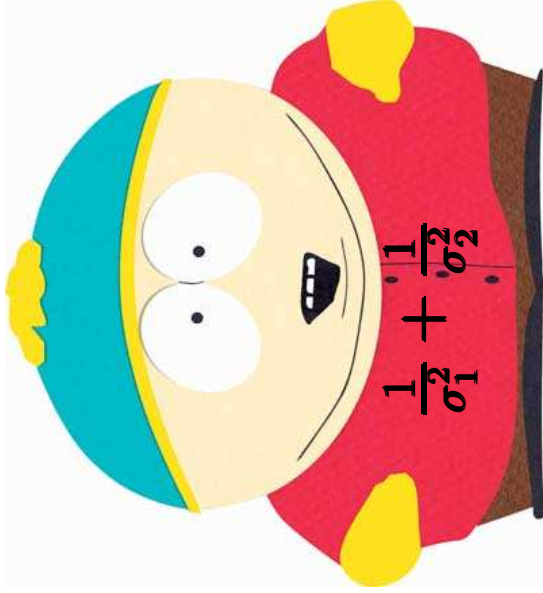
$$\begin{aligned} \sigma_{\hat{a}}^2 &= \sum_{i=1}^n \left(\frac{d\hat{a}}{dy_i} \right)^2 \cdot \sigma_i^2 = \sum_{i=1}^n \left(\frac{G_i}{G_s} \right)^2 \cdot \sigma_i^2 \\ &= \frac{1}{G_s^2} \cdot \sum_{i=1}^n G_i = \frac{1}{G_s} = \frac{1}{\sum_{i=1}^n 1/\sigma_i^2} \end{aligned}$$

⇒ Corollar: least square fitting is nothing else than a clever mapping of measurements to the fitparameters and obtaining fitparameter uncertainties using error propagation

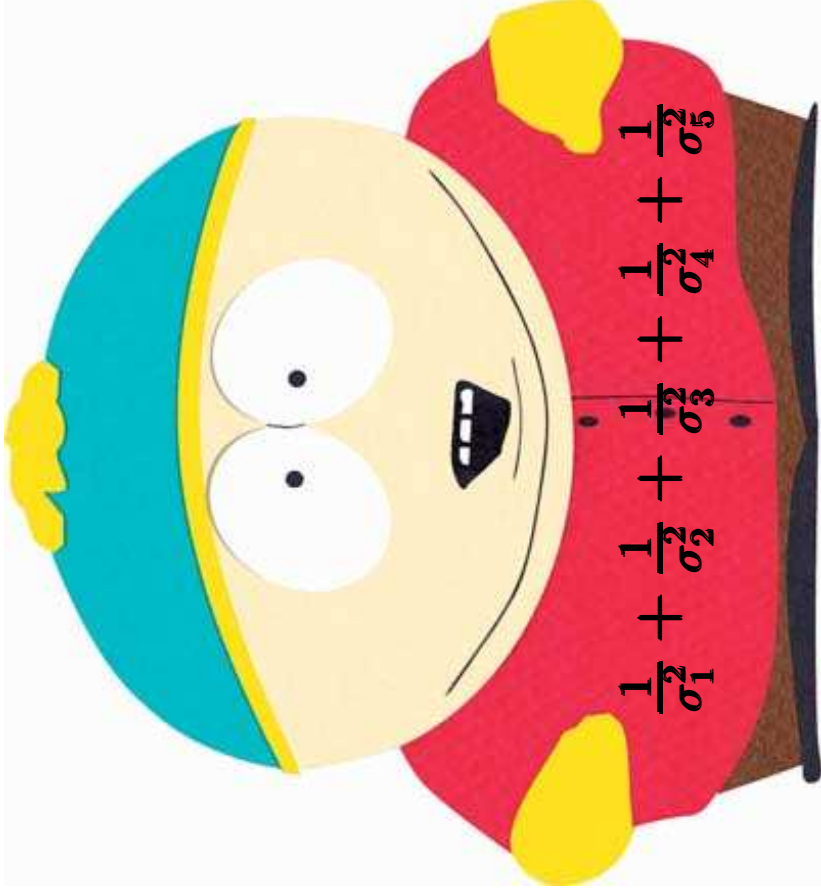
The role of the Hesse matrix

illustrated for weighted average (just a number)

$$H = \frac{1}{2} \frac{d^2 \chi^2}{da^2} = \sum_{i=1}^n \frac{1}{\sigma_i^2}$$



H “grows”
with each
measurement

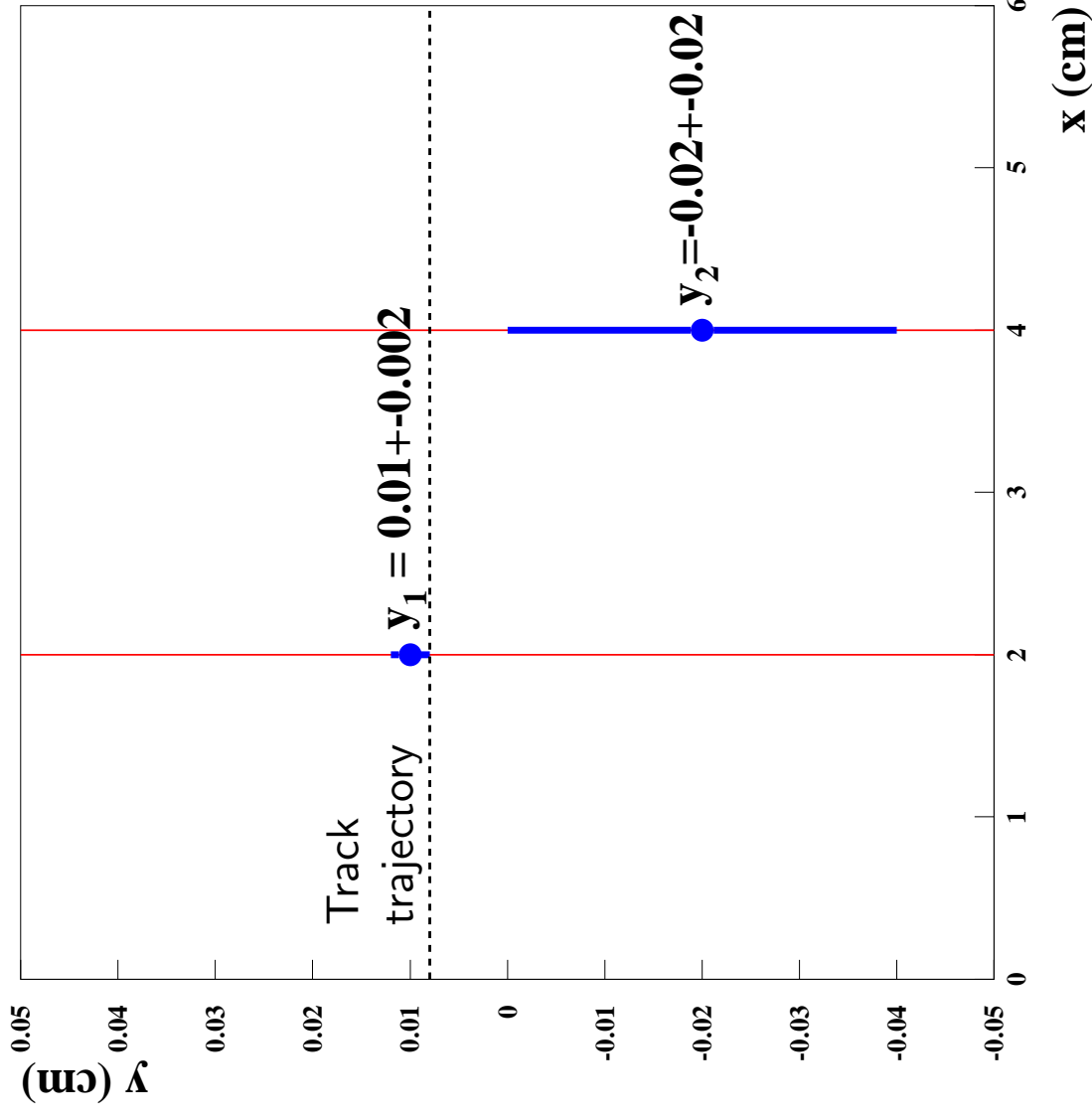


H is “counting the information” from the measurements

Finally $V = H^{-1}$

Note: all this holds also for fits with many parameters

Mini-exercise Weighted average



Determine weighted average of two measurements:

Mini summary of what we have learnt

One parameter fits:

- Least square expression for independent measurements:

$$\chi^2 = \sum_{i=1}^n \frac{(y_i - f(x_i, a))^2}{\sigma_i^2}$$

\Rightarrow get estimator \hat{a} from minimum $\chi^2 \Leftrightarrow d\chi^2/da|_{a=\hat{a}} = 0$

- True physics parameters have a definite value, so true probability densities exist only for the measurements, fitting means in the Bayesian interpretation estimating posterior probability densities for the true parameters

- $\frac{1}{\sigma_{\hat{a}}^2} = \frac{1}{2} \frac{d^2\chi^2}{da^2} |_{a=\hat{a}}$ (general relation)

- $\chi^2(\hat{a} \pm \sigma_{\hat{a}}) = 1$ (general relation, more powerful)

- Averaging several measurements can be easily done graphically by adding individual χ^2 parabolas
- Least square fitting is nothing else than clever mapping of measurements to fit parameters; errors of fit parameters can be obtained from simple error propagation
- The Hesse matrix $H = \frac{1}{2} \frac{d^2\chi^2}{da^2} |_{a=\hat{a}}$ “counts the information” from the measurements

2. Check consistency of a fit using χ^2_{min}

... (when) does it fit like a glove? ...

Consistency of measurements

Recall “inverse probability density” for averaging n measurements:

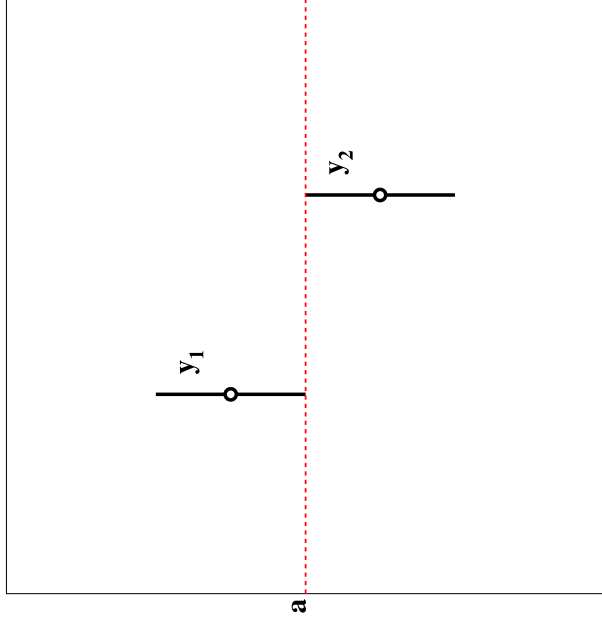
$$\Rightarrow p(y_1, y_2, \dots, y_n | a) \propto \underbrace{e^{-\frac{\chi^2(\hat{a})}{2}}}_{\text{Fit consistency}} \cdot \underbrace{e^{-\frac{1}{2} H \cdot (\hat{a} - a)^2}}_{\text{gaussian density}}$$

Now lets have a closer look at the first term

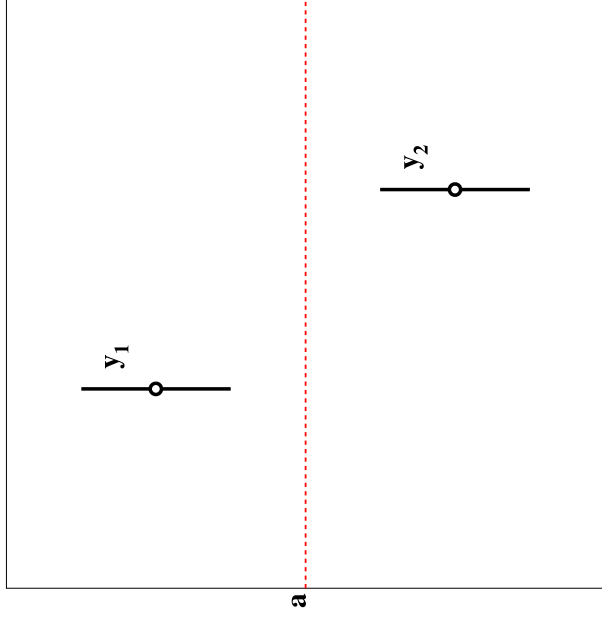
Consistency of measurements

Example: Two measurements $y_1 \pm \sigma_1$ and $y_2 \pm \sigma_2$; the true value a be known, are the measurements consistent with a ?:

Reasonable χ^2



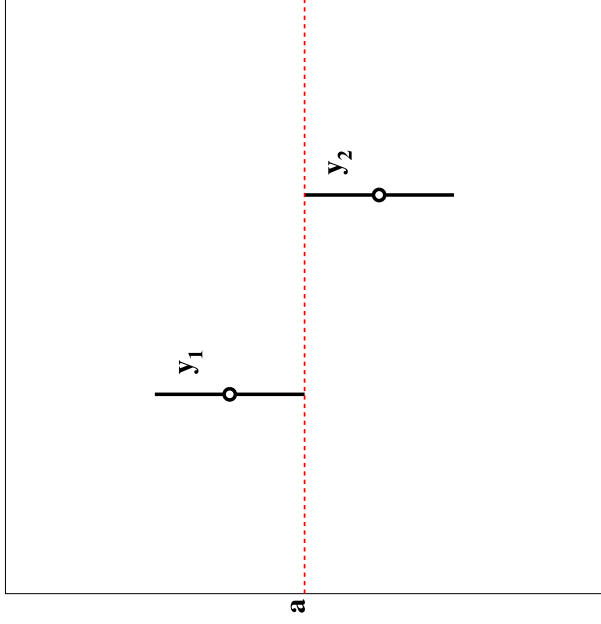
Bad χ^2



Consistency of measurements

Example: Two measurements $y_1 \pm \sigma_1$ and $y_2 \pm \sigma_2$; the true value a be known, are the measurements consistent with a ?:

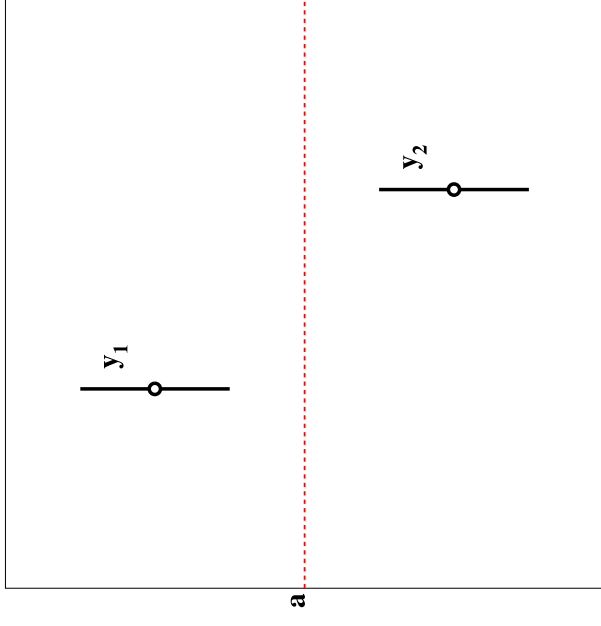
Reasonable χ^2



$$\chi^2 = 2$$

→ χ^2 is a measure of consistency

Bad χ^2



$$\chi^2 = 8$$

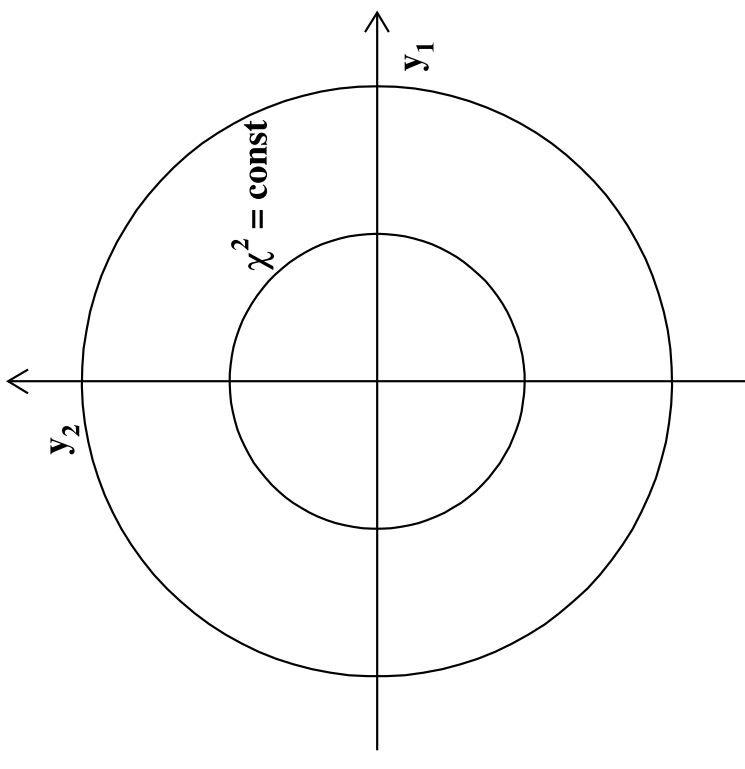
But how should χ^2 be distributed?

χ^2 for two measurements and known true value

Expected density for (y_1, y_2) (simple case $a = 0; \sigma_1 = \sigma_2 = 1$):

$$f(y_1, y_2) = \frac{1}{2\pi} e^{-y_1^2/2} e^{-y_2^2/2} = \frac{1}{2\pi} e^{-r^2/2}$$

$$\text{with } r = \sqrt{y_1^2 + y_2^2} = \sqrt{\chi^2}$$



χ^2 for two measurements and known true value

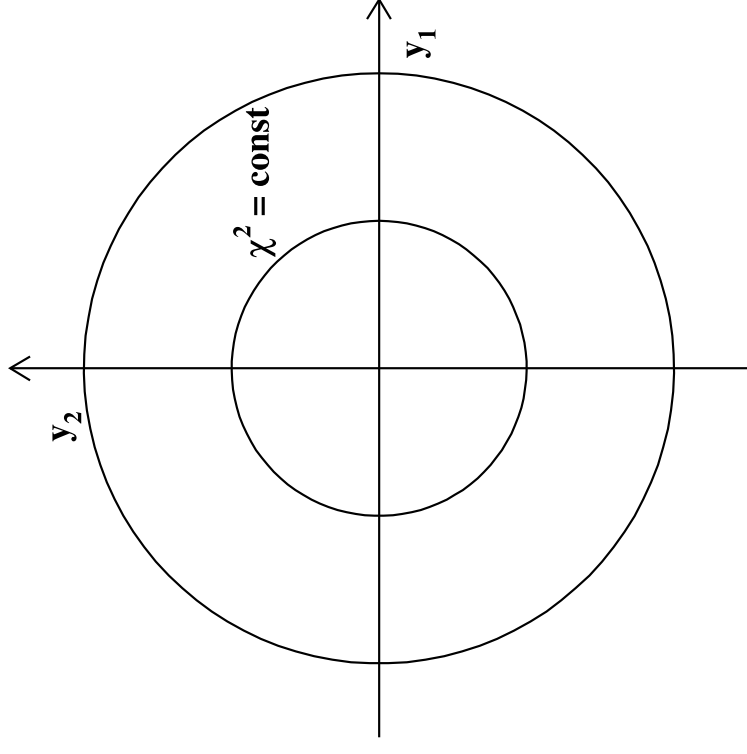
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$$\text{with } r = \sqrt{y_1^2 + y_2^2} = \sqrt{\chi^2}$$

Probability to find value between r and $r + dr$:

$$f(r) dr = 2\pi r dr \frac{1}{2\pi} e^{-r^2/2} = r e^{-r^2/2} dr$$



χ^2 for two measurements and known true value

Expected density for (y_1, y_2) (simple case $a = 0; \sigma_1 = \sigma_2 = 1$):

$$f(y_1, y_2) = \frac{1}{2\pi} e^{-y_1^2/2} e^{-y_2^2/2} = \frac{1}{2\pi} e^{-r^2/2}$$

$$\text{with } r = \sqrt{y_1^2 + y_2^2} = \sqrt{\chi^2}$$

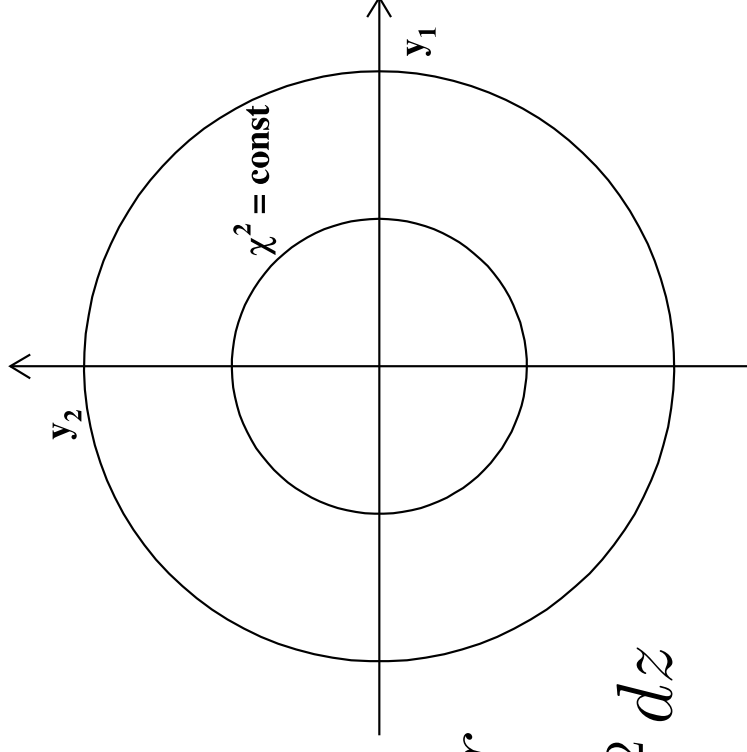
Probability to find value between r and $r + dr$:

$$f(r) dr = 2\pi r dr \frac{1}{2\pi} e^{-r^2/2} dr = r e^{-r^2/2} dr$$

$$z = r^2 : \rightarrow f(z) dz = f(r) \frac{dr}{dz} dz = \frac{1}{2} e^{-z/2} dz$$

\rightarrow introduces χ^2 -distribution for $z = \chi^2$ and two dimensions

$$(\text{ndf}=2): f(z, 2) = \frac{1}{2} e^{-z/2}$$

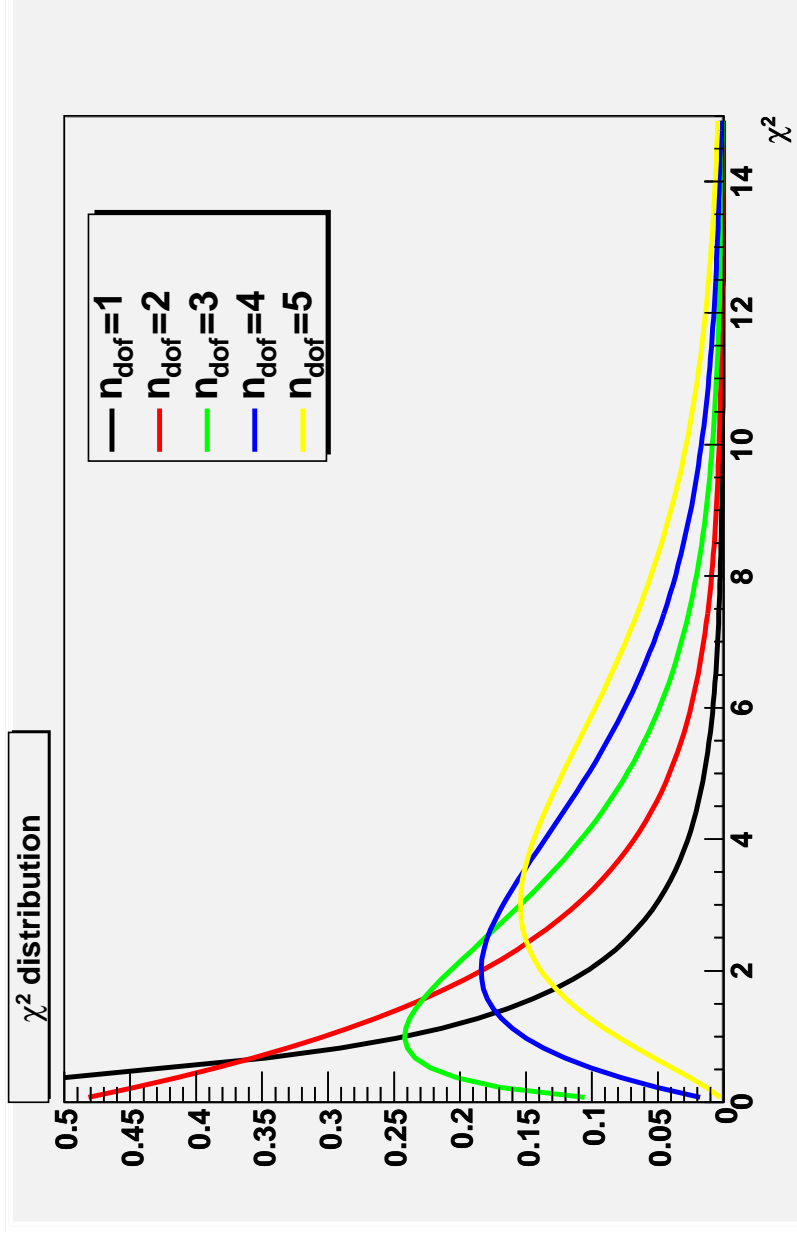


χ^2 -function for n degrees of freedom

→ maps the χ^2 in n dimensions into probability density for χ^2

$$f(\chi^2, n) = \frac{1}{\Gamma(n/2)2^{n/2}} \cdot (\chi^2)^{n/2-1} \cdot e^{-\chi^2/2}$$

$$\text{with } \Gamma(n/2) = \int_0^\infty dt e^{-t} t^{n/2-1}$$



Properties:

$$\int_0^\infty f(\chi^2, n) d\chi^2 = 1$$

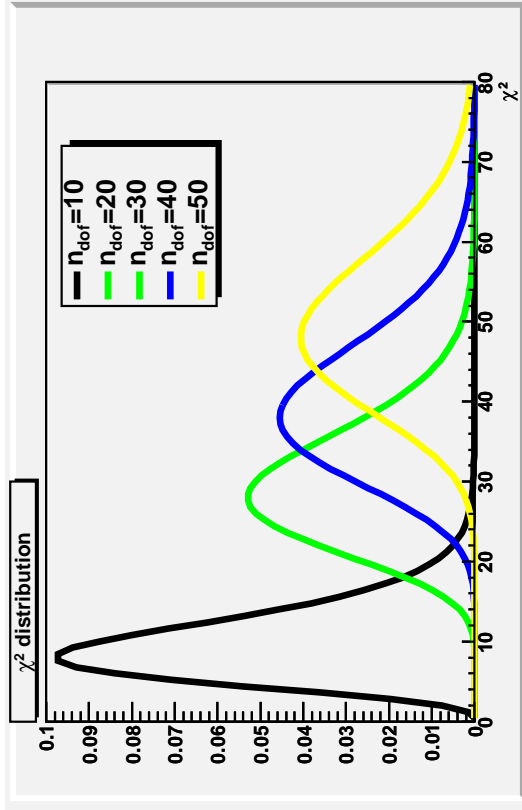
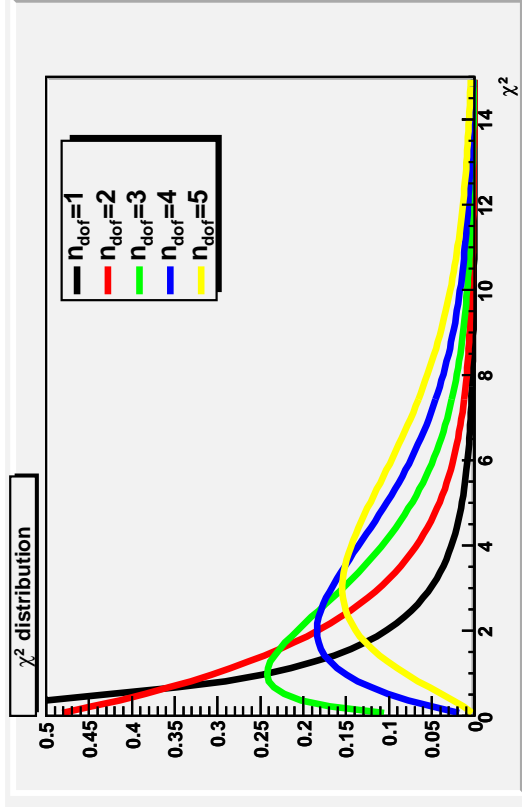
$$\langle \chi^2 \rangle = n$$

$$V(\chi^2) = 2n; \quad \sigma(\chi^2) = \sqrt{2n}$$

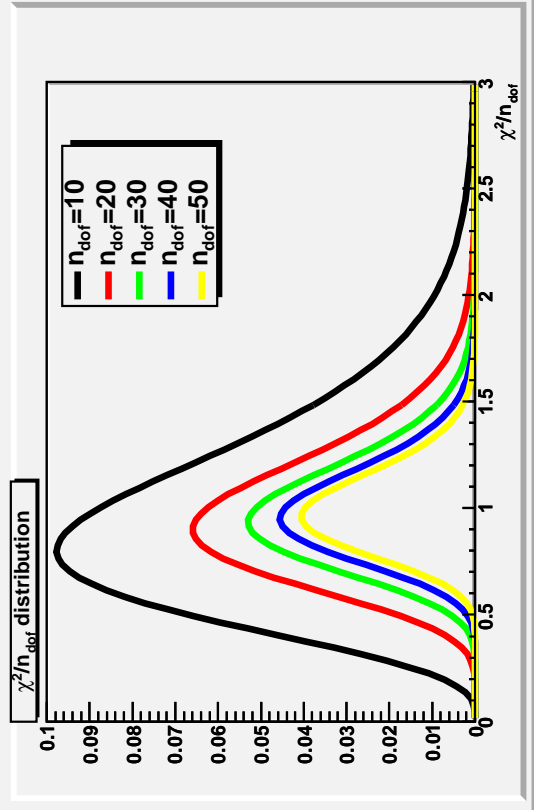
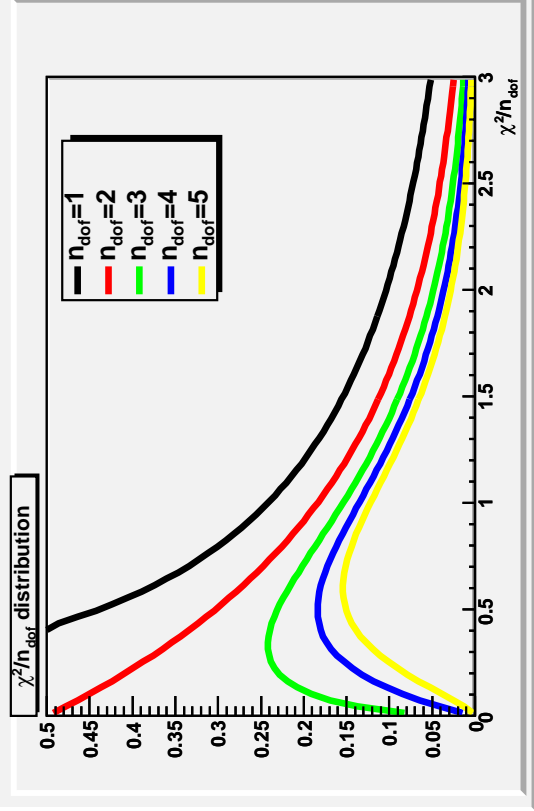
$$\langle \chi^2/n \rangle = 1$$

$$V(\chi^2/n) = 2; \quad \sigma(\chi^2/n) = \sqrt{2/n}$$

χ^2 distributions for various n

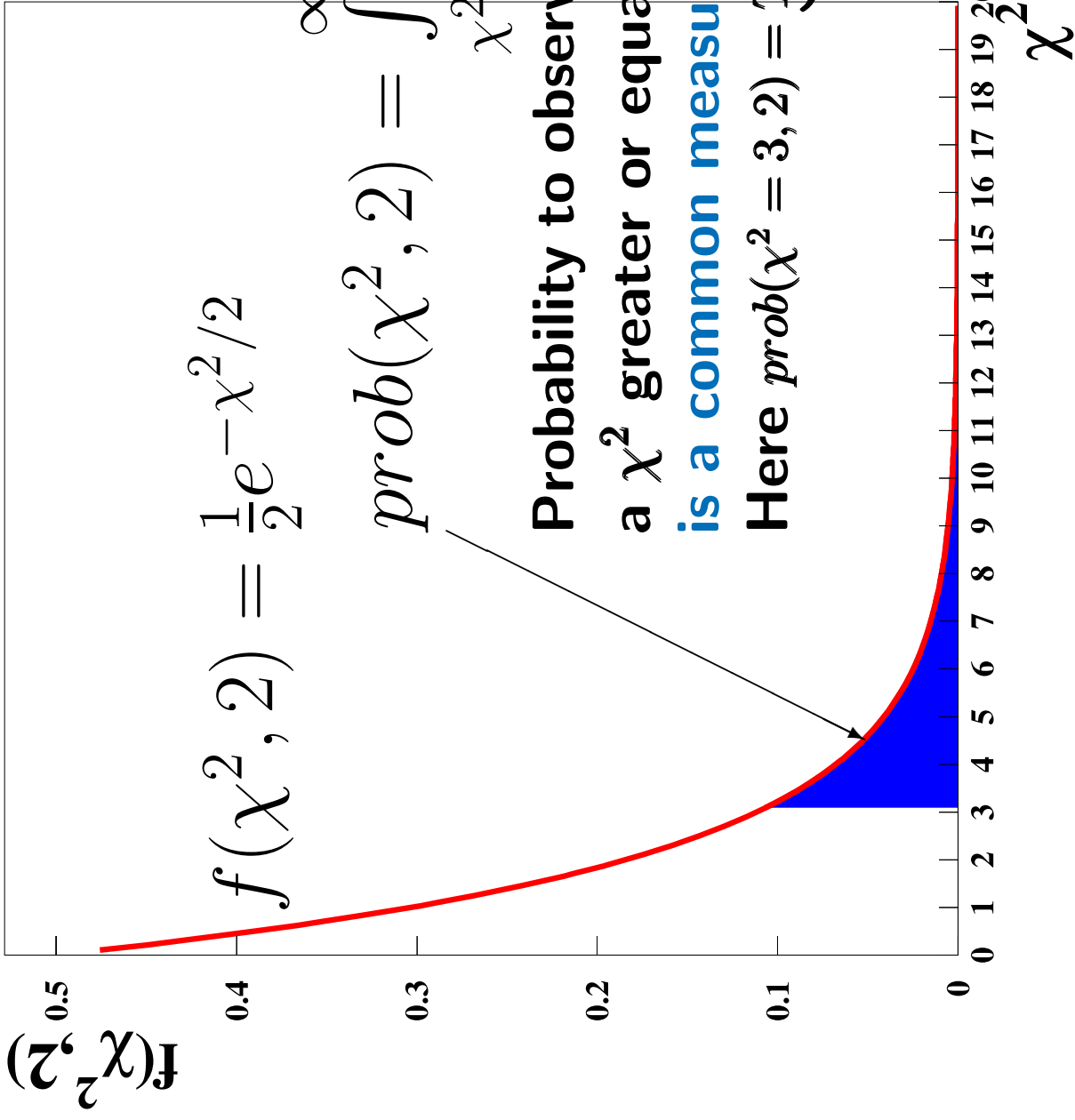


χ^2 distr.



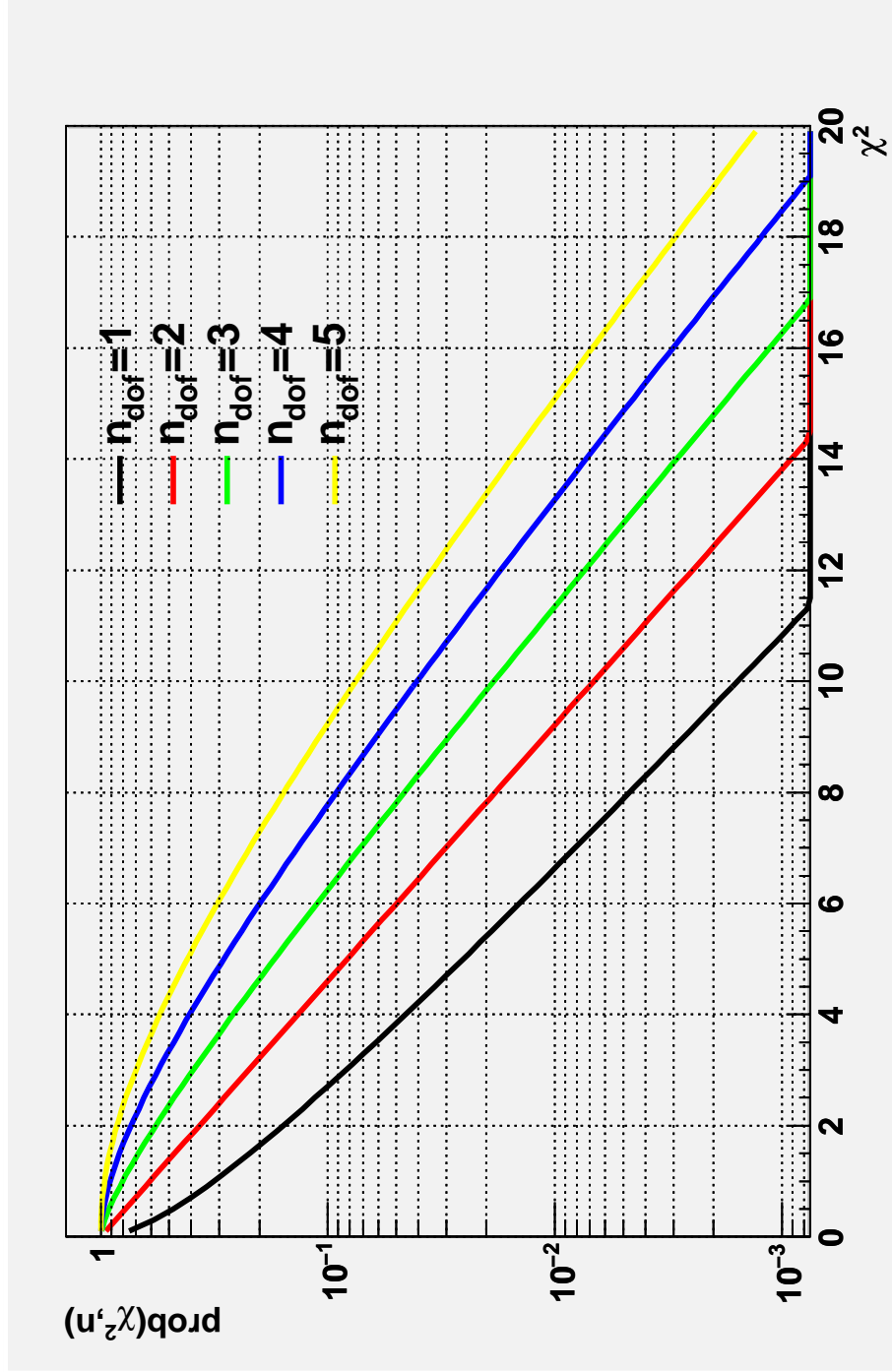
χ^2/n distr.

$f(\chi^2, 2)$ function and $prob(\chi^2, 2)$



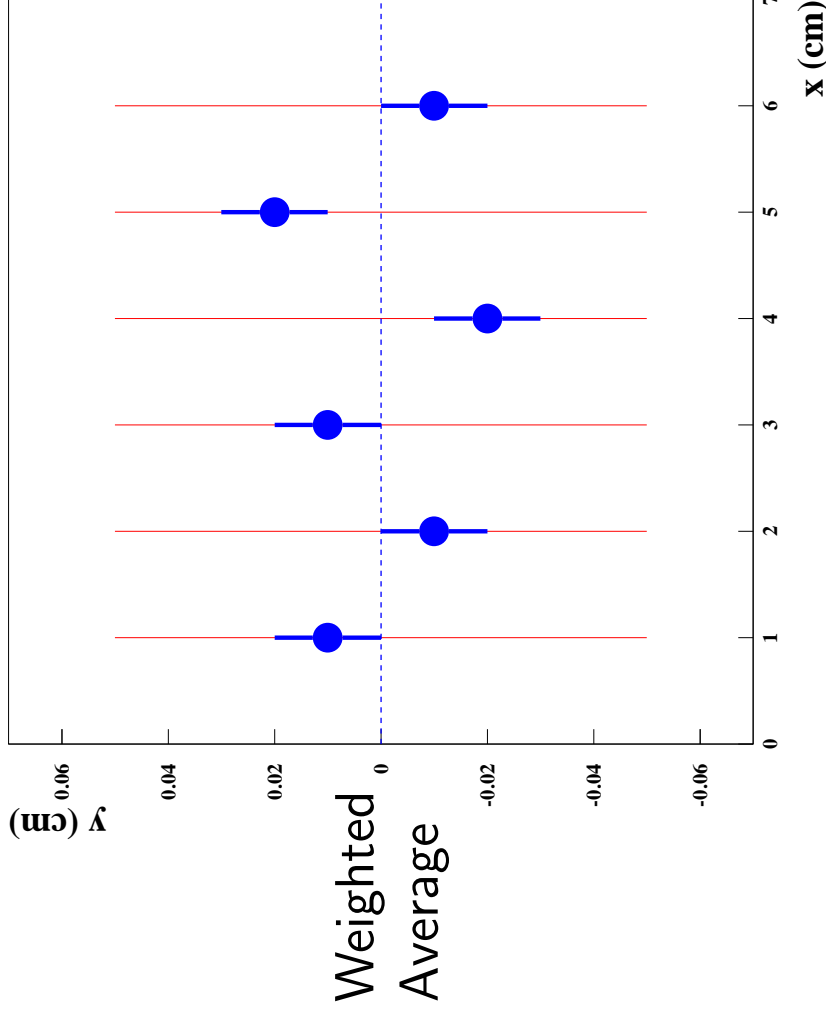
prob(χ^2, n)-function for n degrees of freedom

$$prob(\chi^2, n) = \int_{\chi^2}^{\infty} f(\chi'^2, n) d\chi'^2 = \frac{1}{\Gamma(n/2)} \cdot \int_{\chi^2/2}^{\infty} dt e^{-t} t^{n/2-1}$$



Note: for repeated experiments expect the observed values of $prob(\chi^2, n)$ to be evenly distributed over interval $[0, 1]$

χ^2 for averaging measurements



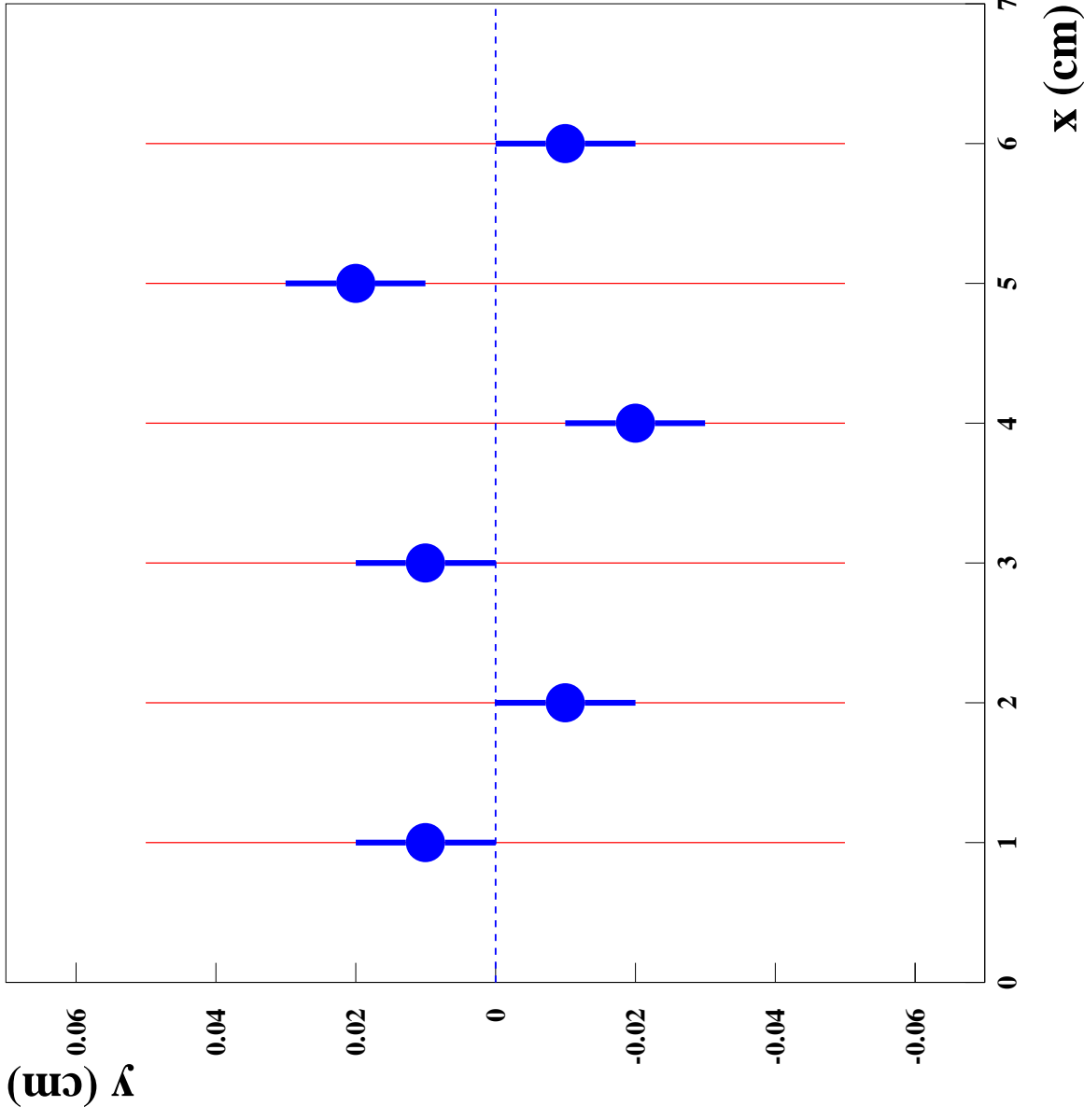
The figure shows the result of a fit of a constant using n measurements. When repeating the fit many times the resulting χ^2_{min} distribution should follow a χ^2 distribution with $n - 1$ degrees of freedom. One degree of freedom is sacrificed to determine the weighted average. A prove for this (for $n = 2$) is given in the appendix.

Mini-exercise χ^2 and probability

The figure shows the result of a fit of a constant.

Determine

- the total χ^2 from reading the figure
- the χ^2 -probability with the ROOT command: **TMath::Prob(χ^2 ,*ndf*)**, where *ndf* is the numbers of degree of freedom.



World average of W boson mass

or how to arrive at a good χ^2

$$\chi_{min}^2 = 10.8, n_{dof} = 4, \text{probability} = 0.029$$

Taking out NuTeV result:

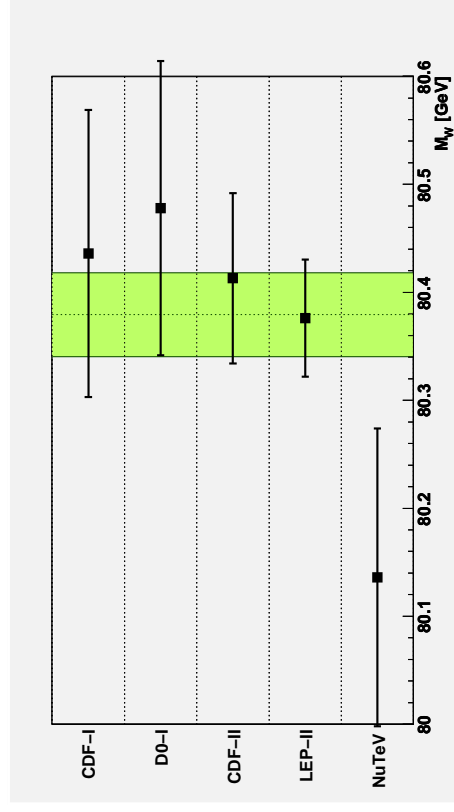
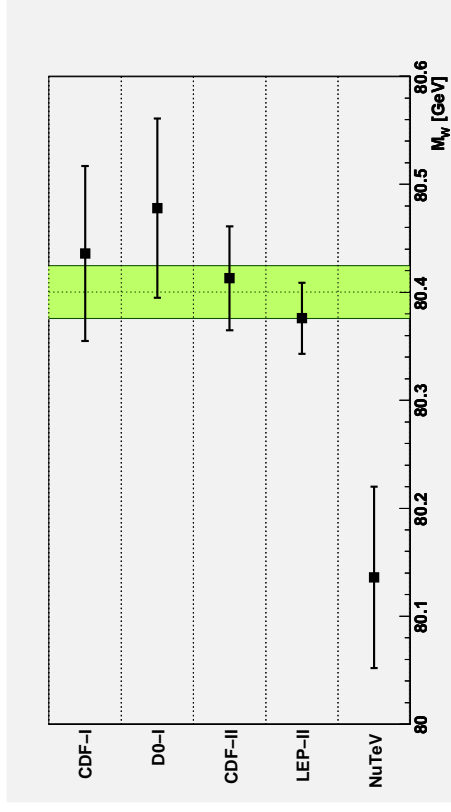
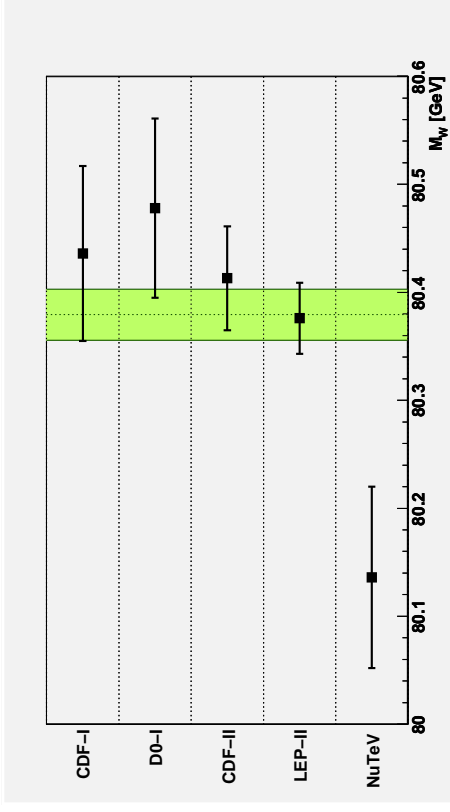
$$\chi_{min}^2 = 1.7, n_{dof} = 3, \text{probability} = 0.64$$

“Outlier rejection”, is this allowed?

$$\text{Scaling all errors by } S = \sqrt{\chi_{min}^2/n_{dof}} = 1.64$$
$$\chi_{min}^2 = 4., n_{dof} = 4, \text{probability} = 0.4$$

Standard procedure by Particle Data group

→ “destroying” the hard work of many experimentalists



Computer exercise: Average 10 measurements with noise:

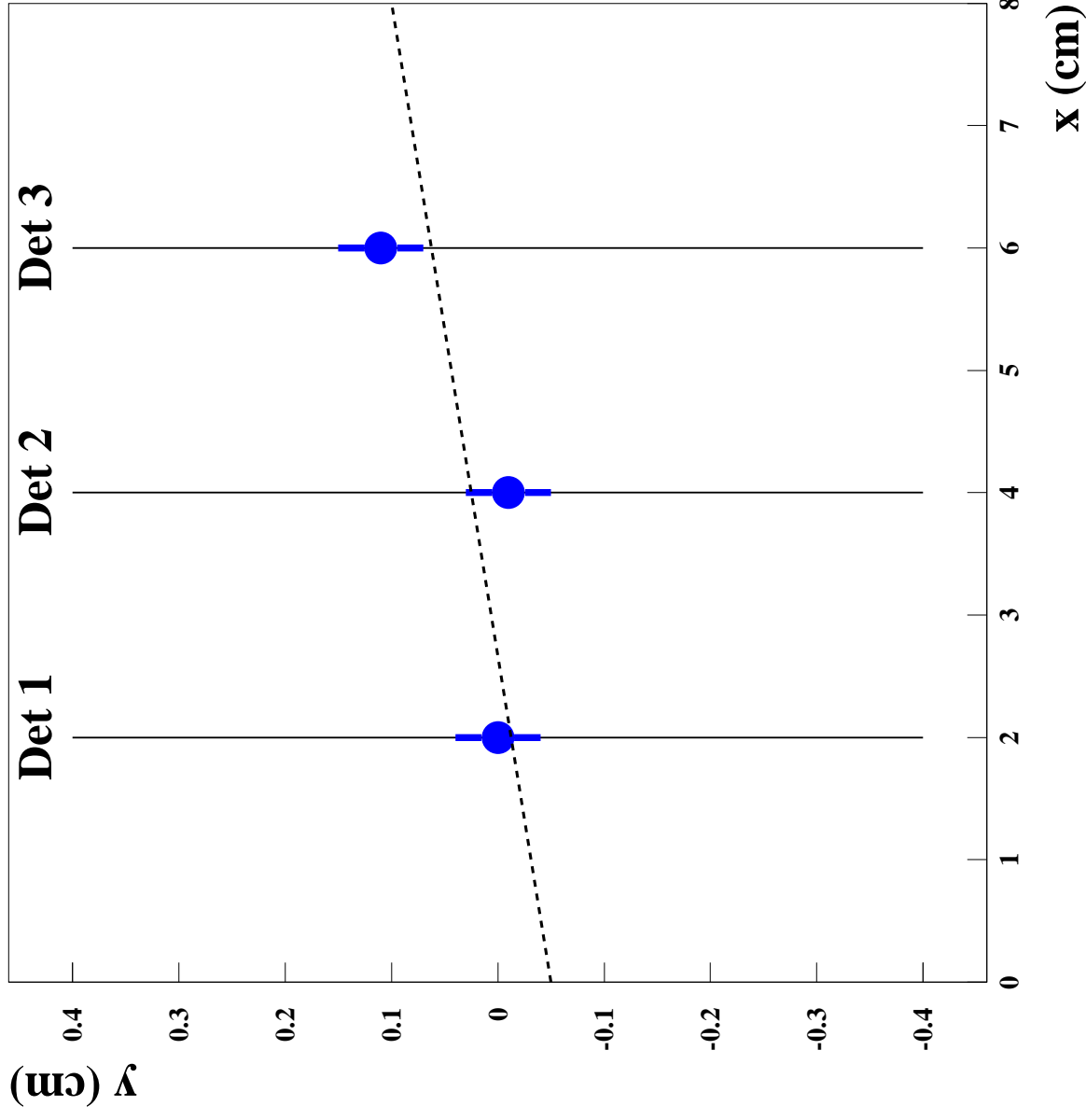
Mini summary of what we have learnt

- The χ_{min}^2 of a fit is a consistency check
- Expect $\chi_{min}^2/n_{dof} \sim 1$ for good fits
- if χ_{min}^2/n_{dof} significantly larger than one then suspect
 - data could contain outliers or errors are (generally) underestimated
 - the fitfunction might not be the correct model for the data
- for repeated experiments (e.g. many track fits) expect for good fits
 - mean value of χ_{min}^2/n_{dof} distribution $\rightarrow 1$
 - and flat $prob(\chi_{min}^2, n_{dof})$ distribution in interval $[0,1]$

3. Linear least square fits

Think linear!

Example: Straight line track trajectory fit



$$y_i = a_0 + a_1 x_i$$

This is a classical linear least square fit problem.

Linear least square fits

\vec{y} vector of n measurements

$$\begin{pmatrix} y_1(x_1) \\ \cdot \\ y_n(x_n) \end{pmatrix}$$

with cov-matrix V

Linear model $\vec{y} = A\vec{a}$,

$$\vec{a} \text{ vector of } m \text{ fitparameters } \begin{pmatrix} a_1 \\ \cdot \\ a_m \end{pmatrix}$$

Example: $y = a_0$;

Linear least square fits

\vec{y} vector of n measurements $\begin{pmatrix} y_1(x_1) \\ \vdots \\ y_n(x_n) \end{pmatrix}$ with cov-matrix V

Linear model $\vec{y} = A\vec{a}$, \vec{a} vector of m fit parameters $\begin{pmatrix} a_1 \\ \vdots \\ a_m \end{pmatrix}$

Example: $y = a_0$; $\rightarrow \vec{a} = (a_0)$; $A = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$

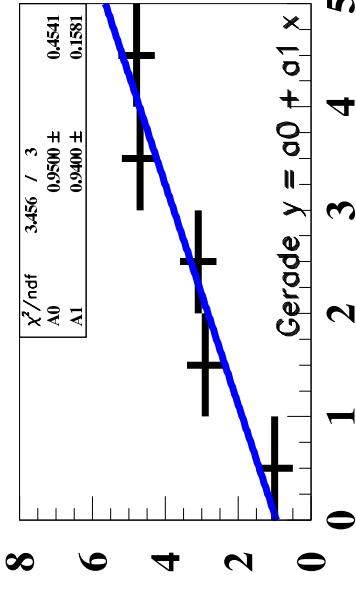
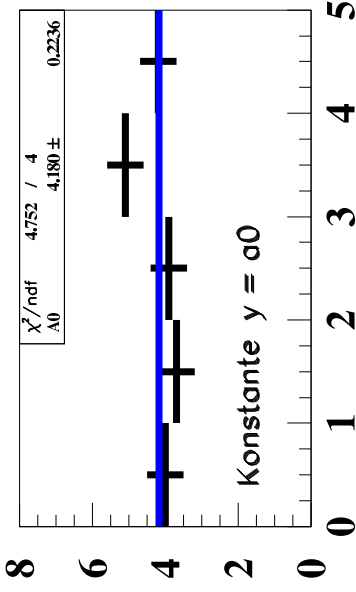
In general: $A = A(\vec{x})$, but no dependence on \vec{a}

“Master formula”: $\chi^2 = (\vec{y} - A\vec{a})^t V^{-1} (\vec{y} - A\vec{a})$

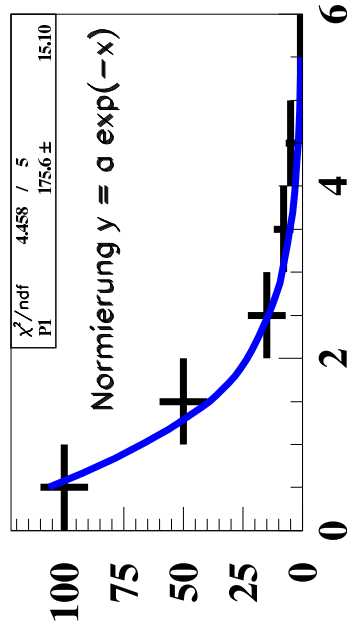
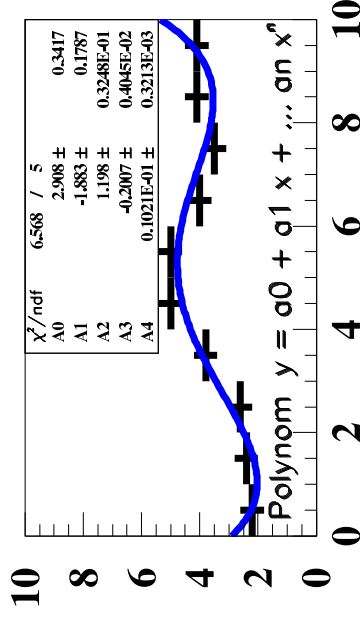
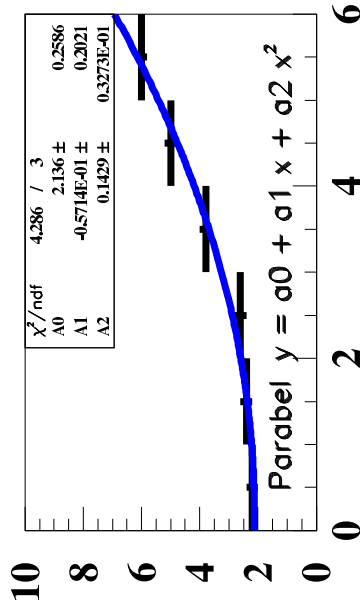
- \rightarrow to be minimised w.r.t \vec{a}
- \rightarrow obtain estimators $\hat{\vec{a}}$ and covariance matrix $V_{\hat{\vec{a}}}$

Examples for linear least square fits

Linear means that y depends linearly on the fit parameters a_i .



$$\vec{a} = \begin{pmatrix} a_0 \\ a_1 \end{pmatrix}; A = \begin{pmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{pmatrix}$$



$$\vec{a} = (a); A = \begin{pmatrix} e^{-x_1} \\ \vdots \\ e^{-x_n} \end{pmatrix}$$

← Watch out: function can be highly non-linear in x

General solution via normal equations

$$\begin{aligned}\chi^2 &= (\vec{y} - A\vec{a})^t V^{-1} (\vec{y} - A\vec{a}) \\ &= \vec{y}^t V^{-1} \vec{y} - 2\vec{a}^t A V^{-1} \vec{y} + \vec{a}^t A^t V^{-1} A \vec{a}\end{aligned}$$

$$\text{Min. } \chi^2 \rightarrow \frac{d\chi^2}{d\vec{a}} = -2A^t V^{-1} \vec{y} + 2A^t V^{-1} A \vec{a} = 0$$

General solution via normal equations

$$\begin{aligned}\chi^2 &= (\vec{y} - A\vec{a})^t V^{-1} (\vec{y} - A\vec{a}) \\ &= \vec{y}^t V^{-1} \vec{y} - 2\vec{a}^t A V^{-1} \vec{y} + \vec{a}^t A^t V^{-1} A \vec{a}\end{aligned}$$

$$\text{Min. } \chi^2 \rightarrow \frac{d\chi^2}{d\vec{a}} = -2A^t V^{-1} \vec{y} + 2A^t V^{-1} A \vec{a} = 0$$

\Rightarrow Normal equation Solution:

$$\begin{aligned}\hat{\vec{a}} &= (A^t V^{-1} A)^{-1} A^t V^{-1} \vec{y} \\ &= H^{-1} A^t V^{-1} \vec{y} \\ &= U A^t V^{-1} \vec{y} \quad \text{with } U = H^{-1} = \text{Cov}(\hat{\vec{a}})\end{aligned}$$

Powerful &
simple linear
algebra

Note: $H = \frac{1}{2} \frac{d^2 \chi^2}{d\vec{a}^2}$ is 'an old friend', the Hesse Matrix

Linear least square fits: Covariance Matrix

Proof that Covariance matrix U of fit parameters

$\hat{\vec{a}}$ is given by $U = H^{-1}$

Use Normal Equations:

$$\hat{\vec{a}} = B\vec{y} \quad \text{with} \quad B = H^{-1}A^tV^{-1}$$

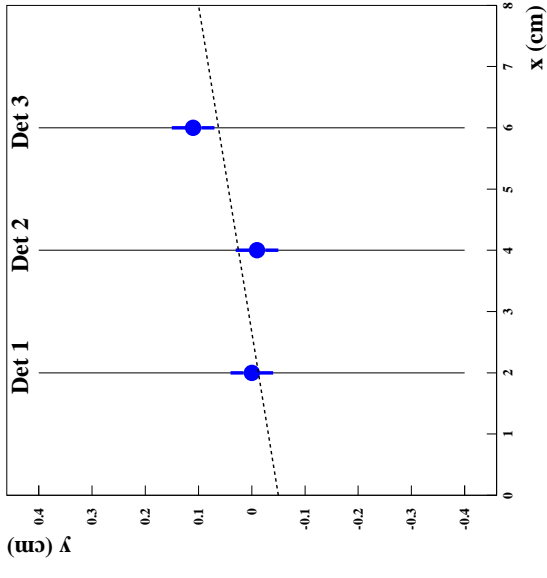
Then apply errorpropagation:

$$\begin{aligned} \rightarrow U &= BV B^t = H^{-1}A^tV^{-1}VV^{-1}AH^{-1} \\ &= H^{-1}A^tV^{-1}AH^{-1} = H^{-1}HH^{-1} = H^{-1} \end{aligned}$$

Straight line fit through n detector layers

$$\chi^2 = \sum_{i=1}^n \frac{(y_i - a_0 - a_1 x_i)^2}{\sigma^2}$$

$$\vec{y} = A\vec{a}; \quad \vec{a} = \begin{pmatrix} a_0 \\ a_1 \end{pmatrix}; \quad A = \begin{pmatrix} 1 & x_1 \\ \cdot & \cdot \\ 1 & x_n \end{pmatrix}; \quad A^t = \begin{pmatrix} 1 & \cdot & 1 \\ x_1 & \cdot & x_n \end{pmatrix}; \quad V = \begin{pmatrix} \sigma^2 & 0 \\ 0 & \sigma^2 \end{pmatrix}$$



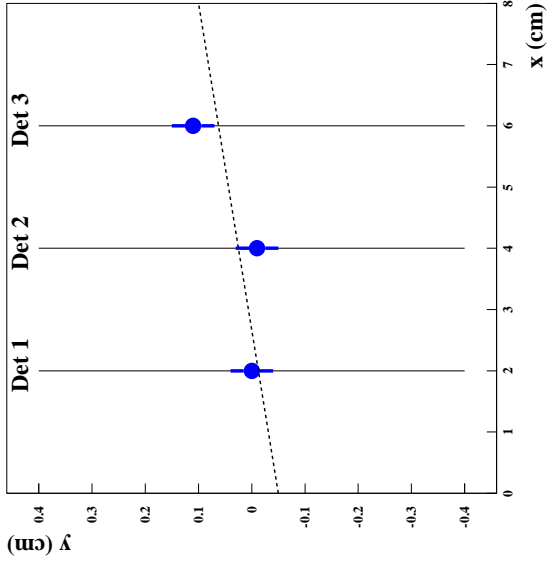
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Apply normal equations:

$$\hat{\vec{a}} = (A^t V^{-1} A)^{-1} A^t V^{-1} \vec{y} = \sigma^2 (A^t A)^{-1} \cdot \frac{1}{\sigma^2} A^t \cdot \vec{y} = (A^t A)^{-1} A^t \cdot \vec{y}$$



Straight line fit through n detector layers

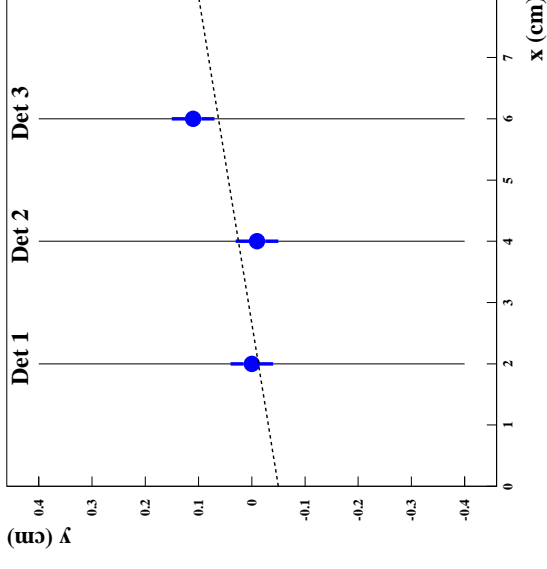
$$\chi^2 = \sum_{i=1}^n \frac{(y_i - a_0 - a_1 x_i)^2}{\sigma^2}$$

$$\vec{y} = A\vec{a}; \quad \vec{a} = \begin{pmatrix} a_0 \\ a_1 \end{pmatrix}; \quad A = \begin{pmatrix} 1 & x_1 \\ \cdot & \cdot \\ 1 & x_n \end{pmatrix}; \quad A^t = \begin{pmatrix} 1 & \cdot & 1 \\ x_1 & \cdot & x_n \end{pmatrix}; \quad V = \begin{pmatrix} \sigma^2 & 0 \\ 0 & \sigma^2 \end{pmatrix}$$

Apply normal equations:

$$\hat{\vec{a}} = (A^t V^{-1} A)^{-1} A^t V^{-1} \vec{y} = \sigma^2 (A^t A)^{-1} \cdot \frac{1}{\sigma^2} A^t \cdot \vec{y} = (A^t A)^{-1} A^t \cdot \vec{y}$$

$$= \begin{pmatrix} \sum_i 1 & \sum_i x_i \\ \cdot & \cdot \\ \sum_i x_i & \sum_i x_i^2 \end{pmatrix}^{-1} \cdot \begin{pmatrix} \sum_i y_i \\ \sum_i x_i y_i \end{pmatrix} = \begin{pmatrix} N & N\bar{x} \\ N\bar{x} & N\overline{x^2} \end{pmatrix}^{-1} \cdot \begin{pmatrix} N\bar{y} \\ N\overline{xy} \end{pmatrix}$$



Straight line fit through n detector layers

$$\chi^2 = \sum_{i=1}^n \frac{(y_i - a_0 - a_1 x_i)^2}{\sigma^2}$$

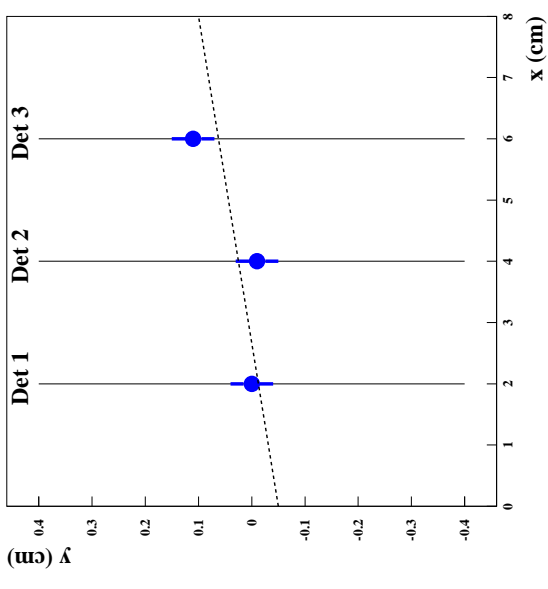
$$\vec{y} = A\vec{a}; \quad \vec{a} = \begin{pmatrix} a_0 \\ a_1 \end{pmatrix}; \quad A = \begin{pmatrix} 1 & x_1 \\ \cdot & \cdot \\ 1 & x_n \end{pmatrix}; \quad A^t = \begin{pmatrix} 1 & \cdot & 1 \\ x_1 & \cdot & x_n \end{pmatrix}; \quad V = \begin{pmatrix} \sigma^2 & 0 \\ 0 & \sigma^2 \end{pmatrix}$$

Apply normal equations:

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$$= \begin{pmatrix} 1 & \bar{x} \\ \bar{x} & \overline{x^2} \end{pmatrix}^{-1} \cdot \begin{pmatrix} \bar{y} \\ \overline{xy} \end{pmatrix} = \frac{1}{\overline{x^2} - \bar{x}^2} \begin{pmatrix} \overline{x^2} & -\bar{x} \\ -\bar{x} & 1 \end{pmatrix} \begin{pmatrix} \bar{y} \\ \overline{xy} \end{pmatrix} = \frac{1}{V[x]} \cdot \begin{pmatrix} \overline{x^2 y} - \bar{x} \overline{xy} \\ -\bar{x} \bar{y} + \overline{xy} \end{pmatrix}$$



Straight line fit through n detector layers

$$\chi^2 = \sum_{i=1}^n \frac{(y_i - a_0 - a_1 x_i)^2}{\sigma^2}$$

$$\vec{y} = A\vec{a}; \quad \vec{a} = \begin{pmatrix} a_0 \\ a_1 \end{pmatrix}; \quad A = \begin{pmatrix} 1 & x_1 \\ \cdot & \cdot \\ 1 & x_n \end{pmatrix}; \quad A^t = \begin{pmatrix} 1 & \cdot & 1 \\ x_1 & \cdot & x_n \end{pmatrix}; \quad V = \begin{pmatrix} \sigma^2 & 0 \\ 0 & \sigma^2 \end{pmatrix}$$

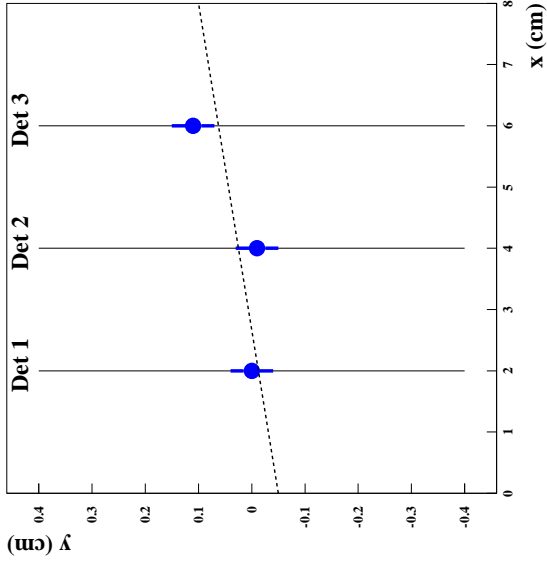
Apply normal equations:

$$\hat{\vec{a}} = (A^t V^{-1} A)^{-1} A^t V^{-1} \vec{y} = \sigma^2 (A^t A)^{-1} \cdot \frac{1}{\sigma^2} A^t \cdot \vec{y} = (A^t A)^{-1} A^t \cdot \vec{y}$$

$$= \begin{pmatrix} \sum_i 1 & \sum_i x_i \\ \cdot & \cdot \\ \sum_i x_i & \sum_i x_i^2 \end{pmatrix}^{-1} \cdot \begin{pmatrix} \sum_i y_i \\ \sum_i x_i y_i \end{pmatrix} = \begin{pmatrix} N & N\bar{x} \\ N\bar{x} & N\overline{x^2} \end{pmatrix}^{-1} \cdot \begin{pmatrix} N\bar{y} \\ N\overline{xy} \end{pmatrix}$$

$$= \begin{pmatrix} 1 & \bar{x} \\ \bar{x} & \overline{x^2} \end{pmatrix}^{-1} \cdot \begin{pmatrix} \bar{y} \\ \overline{xy} \end{pmatrix} = \frac{1}{\overline{x^2} - \bar{x}^2} \begin{pmatrix} \overline{x^2} & -\bar{x} \\ -\bar{x} & 1 \end{pmatrix} \begin{pmatrix} \bar{y} \\ \overline{xy} \end{pmatrix} = \frac{1}{V[x]} \cdot \begin{pmatrix} \overline{x^2 y} - \bar{x} \overline{xy} \\ -\bar{x} \bar{y} + \overline{xy} \end{pmatrix}$$

$$U = \begin{pmatrix} \sigma_{\hat{a}_0}^2 & cov(\hat{a}_0, \hat{a}_1) \\ cov(\hat{a}_0, \hat{a}_1) & \sigma_{\hat{a}_1}^2 \end{pmatrix} = (A^t V^{-1} A)^{-1} = \frac{\sigma^2}{NV[x]} \begin{pmatrix} \overline{x^2} & -\bar{x} \\ -\bar{x} & 1 \end{pmatrix}$$



Mini-exercise: Straight line track-fit

The covariance formula

$$\begin{pmatrix} \sigma_{\hat{a}_0}^2 & cov(\hat{a}_0, \hat{a}_1) \\ cov(\hat{a}_0, \hat{a}_1) & \sigma_{\hat{a}_1}^2 \end{pmatrix} = \frac{\sigma^2}{NV[x]} \begin{pmatrix} \overline{x^2} & -\overline{x} \\ -\overline{x} & 1 \end{pmatrix}$$

is valid for e.g. a straight line track fit in N detectors of resolution σ :

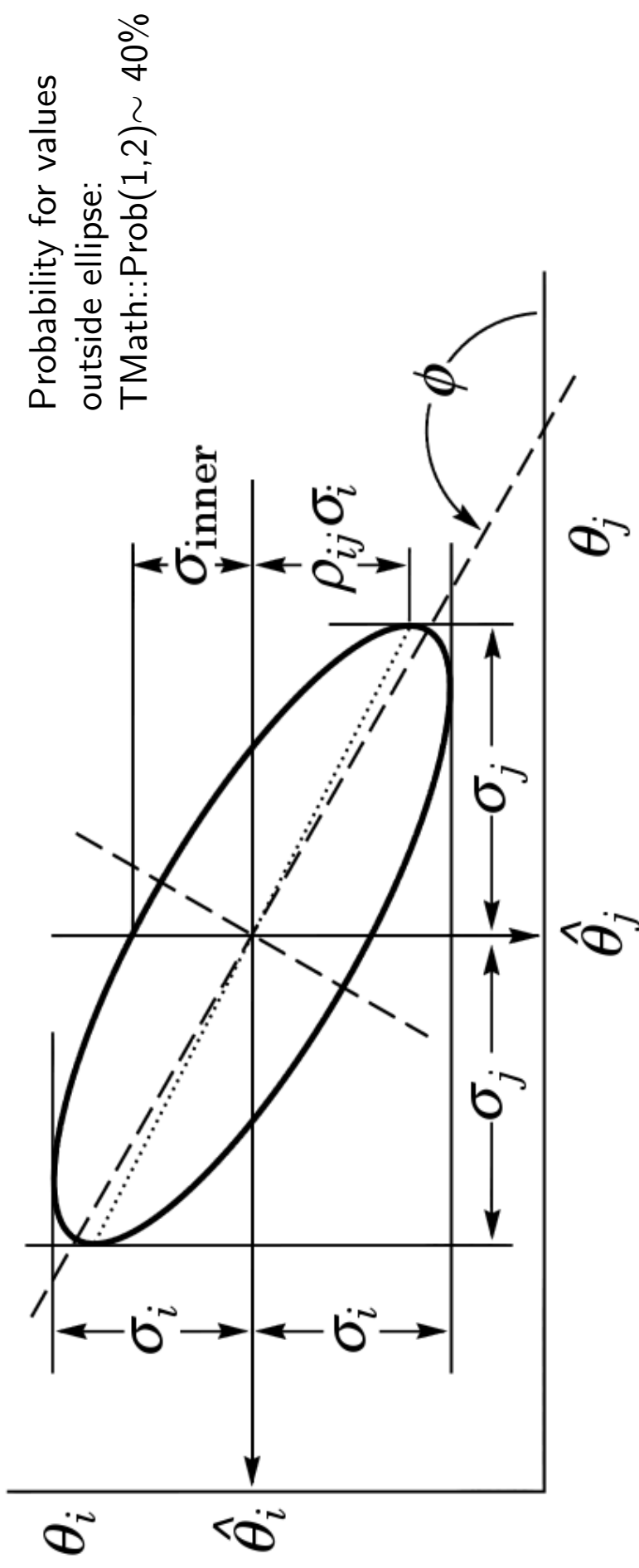
Determine the improvements on the slope error $\sigma_{\hat{a}_1}$ by:

- a) Doubling the number of detector layers N within the same interval in x**
- b) Distributing the detector layers over an interval in x twice as large**
- c) Buying detectors with measurement uncertainties σ reduced by a factor two**

Covariance ellipses

The covariance matrix $V = \begin{pmatrix} \sigma_i^2 & \rho_{ij}\sigma_i\sigma_j \\ \rho_{ij}\sigma_i\sigma_j & \sigma_j^2 \end{pmatrix}$ of two parameters θ_i and θ_j can be represented by error ellipses (see Fig. from PDG below) The role of the correlation coefficient ρ_{ij} :

- If one shifts θ_i to $\hat{\theta}_i + \sigma_i$ one has to shift θ_j to $\hat{\theta}_j + \rho_{ij}\sigma_j$ to keep the χ^2 increase minimal (stay down in the χ^2 valley)
- When fixing θ_j the error on θ_i is reduced to $\sigma_{inner} = \sqrt{1 - \rho^2} \sigma_i$



Computer exercise: Straight line trajectory fit

with Root Macro StraightLineFit.C

Mini summary of what we have learnt

- **Linear least square problems:** $\vec{y} = A\vec{a}$,
→ y is a linear function of the fit parameters \vec{a}
but can be a linear or nonlinear function of
the continuous parameter x .

- **The normal equations are a powerful tool to solve linear least square fit problems**

$$\hat{\vec{a}} = (A^t V^{-1} A)^{-1} A^t V^{-1} \vec{y}, \quad cov(\hat{\vec{a}}) = (A^t V^{-1} A)^{-1}$$

- **Straight line fits are a typical application and there are many others (e.g. parabolas, higher order polynomials, etc.)**

4. Nonlinear least square fits

Think linear but act nonlinear!

Reminder least square method (one parameter)

$$\begin{aligned} \rightarrow & \boxed{\chi^2 = \sum_{i=1}^n \frac{(y_i - f(x_i, a))^2}{\sigma_i^2}} \\ & \leftrightarrow \text{Minimum w.r.t } a \end{aligned}$$

\Rightarrow determine estimator \hat{a} from $\frac{d\chi^2}{da} = 0$

Nonlinear case

Examples: $f(x, a) = \tan(ax)$, $\ln(ax)$, $a \exp(-ax)$

Define $g = \frac{d\chi^2}{da}$ and $G = \frac{d^2\chi^2}{da^2} = g'$

\hookrightarrow Newton steps to find root of g :

$$a_{m+1} = a_m - \frac{g(a_m)}{g'(a_m)} \quad (\text{iteration index } m)$$

For several parameters \vec{a} generalise: $\vec{g} = \frac{d\chi^2}{d\vec{a}}$ and $G = \frac{d^2\chi^2}{d\vec{a}^2}$

\hookrightarrow Newton step: $\delta\vec{a} = -G^{-1}\vec{g}$

Illustration of Newton steps

Fit the curvature κ of a track flying through perpendicular magnetic field

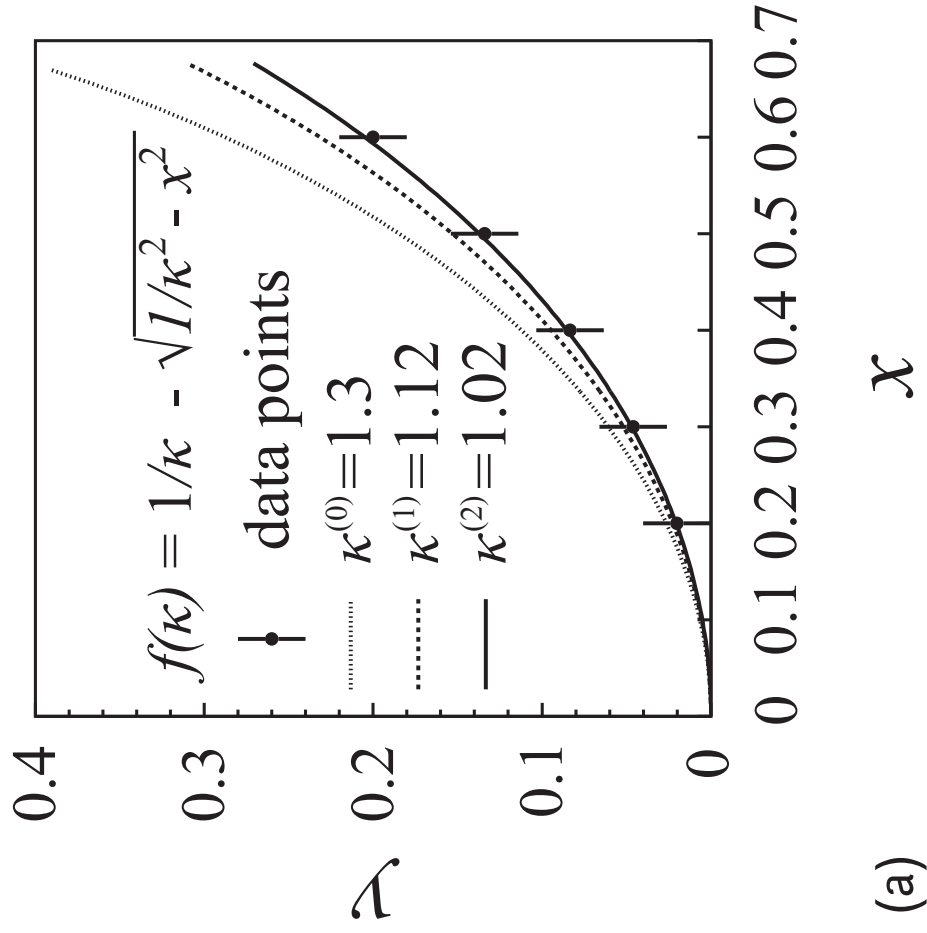
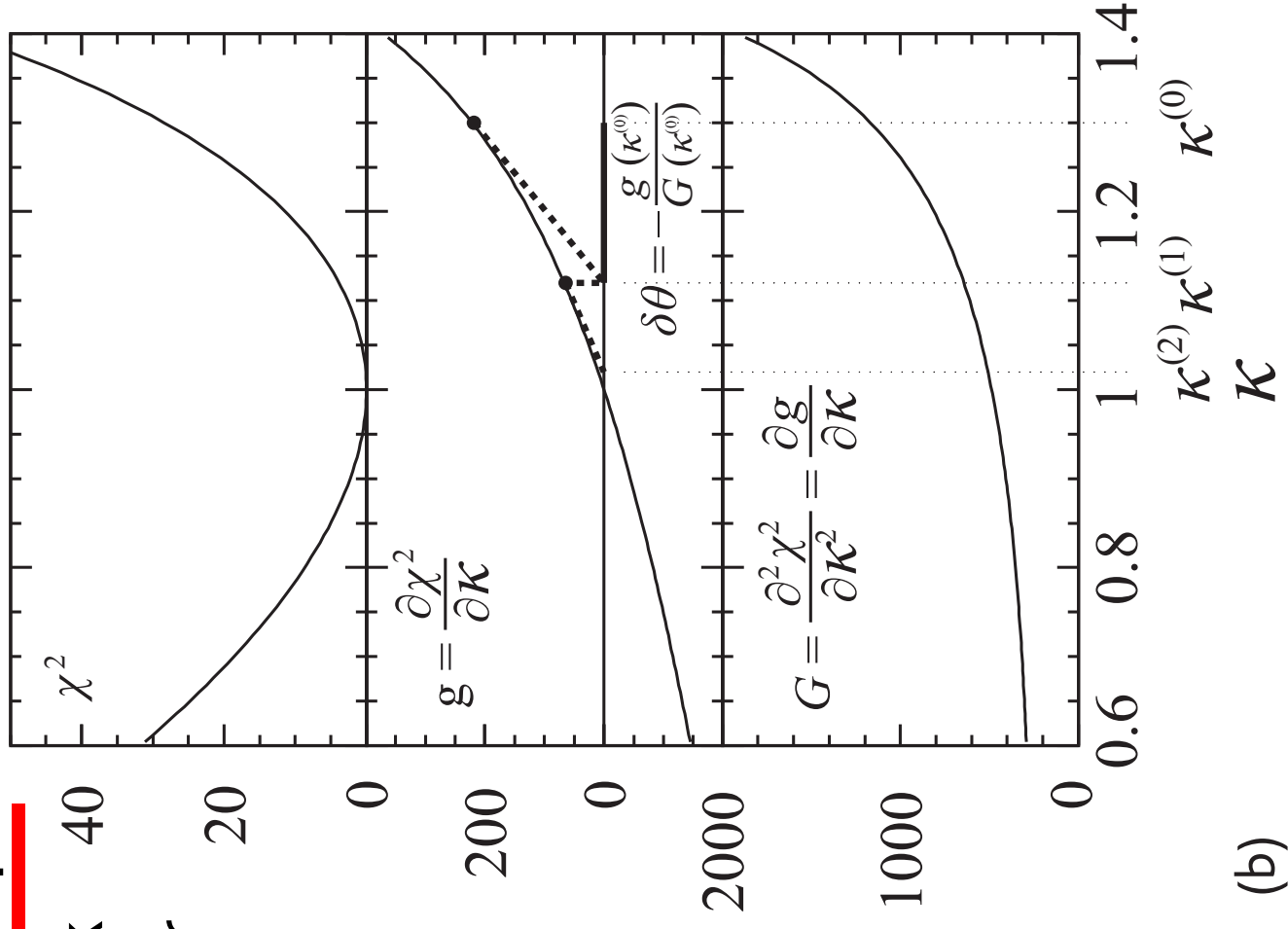


Figure Copyright Wiley-VCH
'Data Analysis in High Energy Physics'



Mini-exercise Nonlinear χ^2 Fit: determine particle mass from signal peak

Paper exercise

Appendix

Content:

- Proof that χ_{min}^2 for averaging two measurements follows χ^2 -distribution with one degree of freedom

χ^2 for two measurements with unknown true value

$$\chi_{min}^2 = \frac{(y_1 - \hat{a})^2}{\sigma_1^2} + \frac{(y_2 - \hat{a})^2}{\sigma_2^2}; \quad \hat{a} = \frac{1}{\frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2}} \cdot \left(\frac{y_1}{\sigma_1^2} + \frac{y_2}{\sigma_2^2} \right) = \frac{G_1 y_1 + G_2 y_2}{G_1 + G_2} \quad (\text{with } G_i := 1/\sigma_i^2)$$

$$\begin{aligned} \Rightarrow \chi_{min}^2 &= G_1 \cdot \left(y_1 - \frac{(G_1 y_1 + G_2 y_2)}{G_1 + G_2} \right)^2 + G_2 \cdot \left(y_2 - \frac{(G_1 y_1 + G_2 y_2)}{G_1 + G_2} \right)^2 \\ &= G_1 \cdot \left(\frac{(G_2 y_1 - G_2 y_2)}{G_1 + G_2} \right)^2 + G_2 \cdot \left(\frac{(G_1 y_2 - G_1 y_1)}{G_1 + G_2} \right)^2 \\ &= \frac{G_1 G_2^2}{(G_1 + G_2)^2} (y_1 - y_2)^2 + \frac{G_2 G_1^2}{(G_1 + G_2)^2} (y_1 - y_2)^2 \\ &= \frac{G_1 G_2 (G_1 + G_2)}{(G_1 + G_2)^2} \cdot (y_1 - y_2)^2 = \frac{G_1 \cdot G_2}{G_1 + G_2} \cdot (y_1 - y_2)^2 \\ &= \frac{1}{1/G_1 + 1/G_2} \cdot (y_1 - y_2)^2 = \frac{1}{\sigma_1^2 + \sigma_2^2} \cdot (y_1 - y_2)^2 \end{aligned}$$

$\Delta = \frac{y_1 - y_2}{\sqrt{\sigma_1^2 + \sigma_2^2}}$ should follow (*errorpropagation!*) gauss distribution $\sim e^{-\frac{\Delta^2}{2}}$

→ $\chi^2 = \Delta^2$ follows 1-dim χ^2 distr.!

→ One degree of freedom “sacrificed” for determination of \hat{a} .

General: n -measurements with one unknown a

→ follows χ^2 distribution with $n - 1$ degrees of freedom