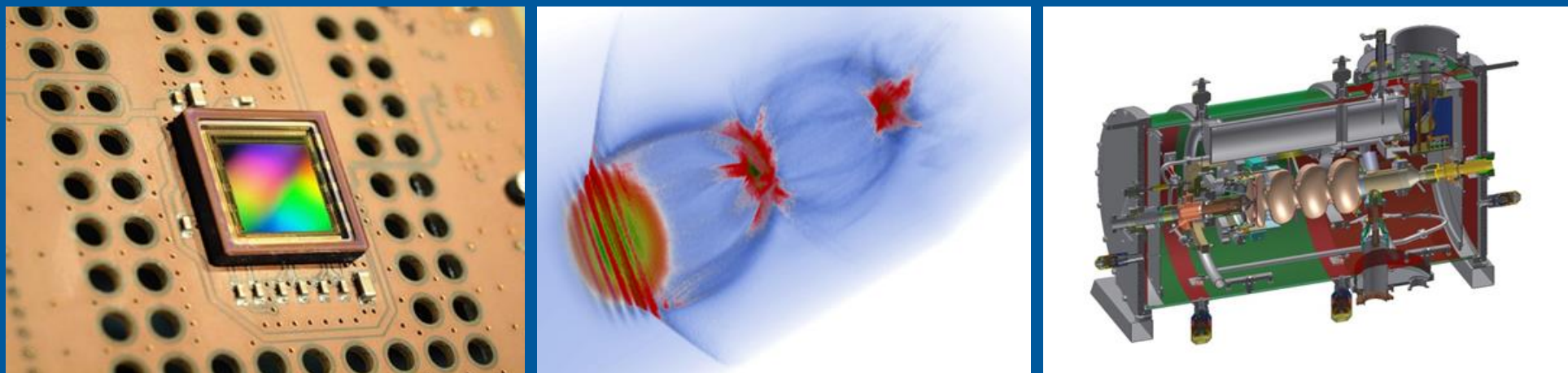


GPU-accelerated algorithms for data analysis

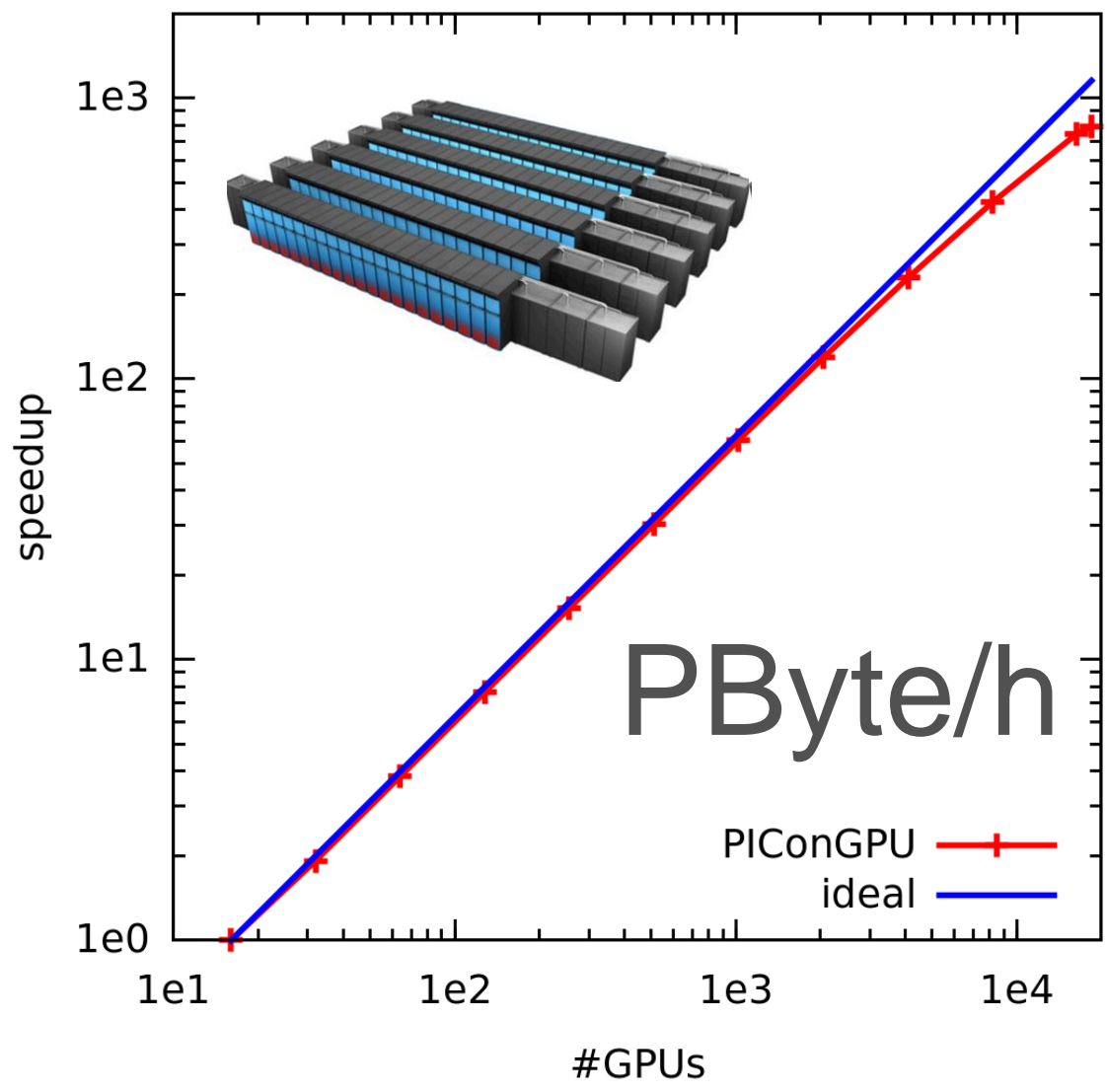


Motivation

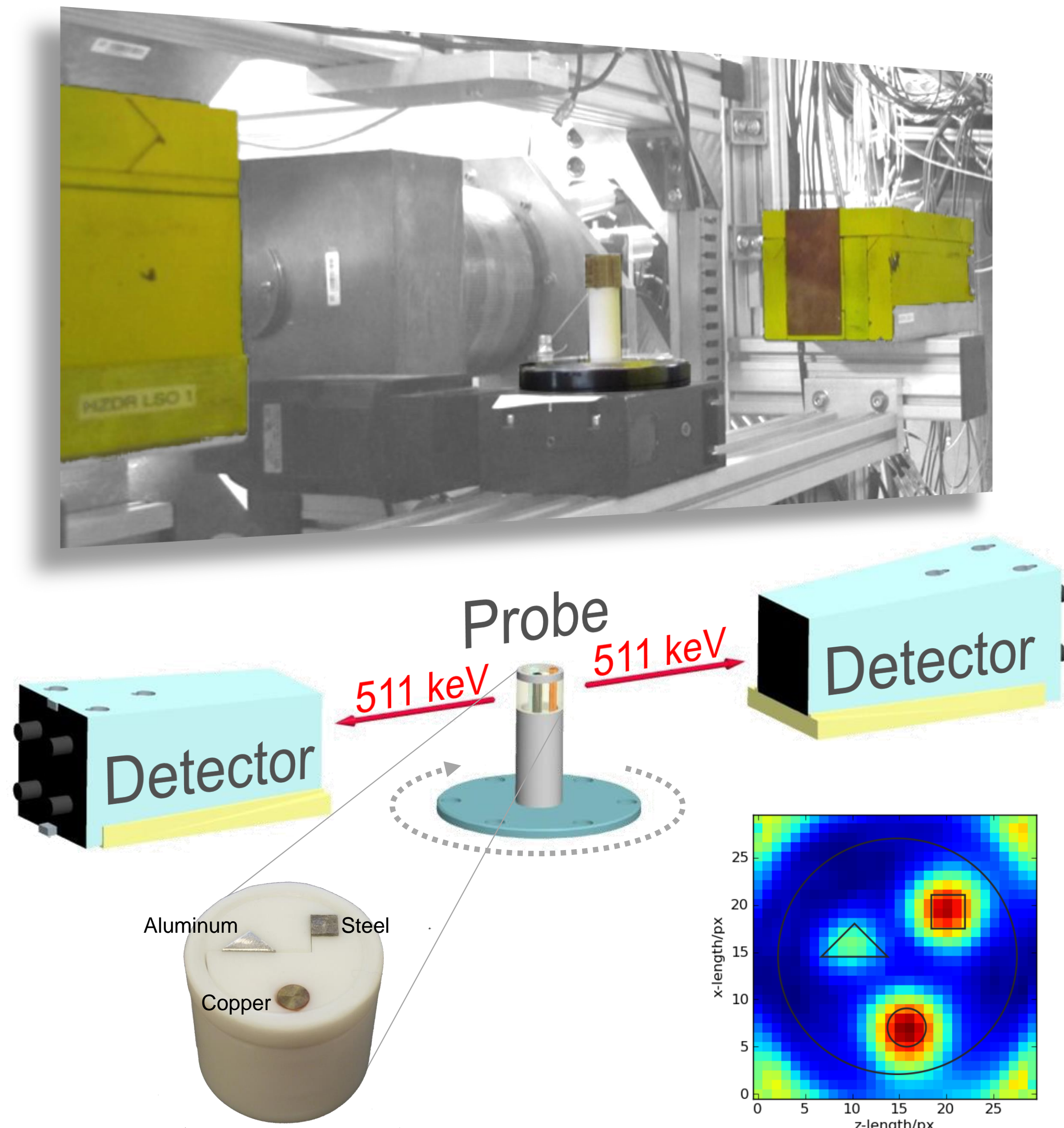
Parallel algorithms allow for **in-situ data analysis** and thus **great reduction** of data rates. Speeding up data analysis enables **real-time feedback**.

Here we show two examples of real-time data analysis that highlight the key requirements on parallel algorithms and data transport.

- Moderate Rate, Complex Signals:** Real-time Image Reconstruction of PET Data
- High Rate, Independent Signals:** Positron Annihilation Spectroscopy Event Analysis



Real-time Image Reconstruction of PET Data



Lines of Response

Activity in Voxels

System Matrix

Number of LoR
 $N \approx 10^6$

Number of Voxels
 $M \approx 10^5$

System Matrix
 $N \times M \approx 10^{11}$

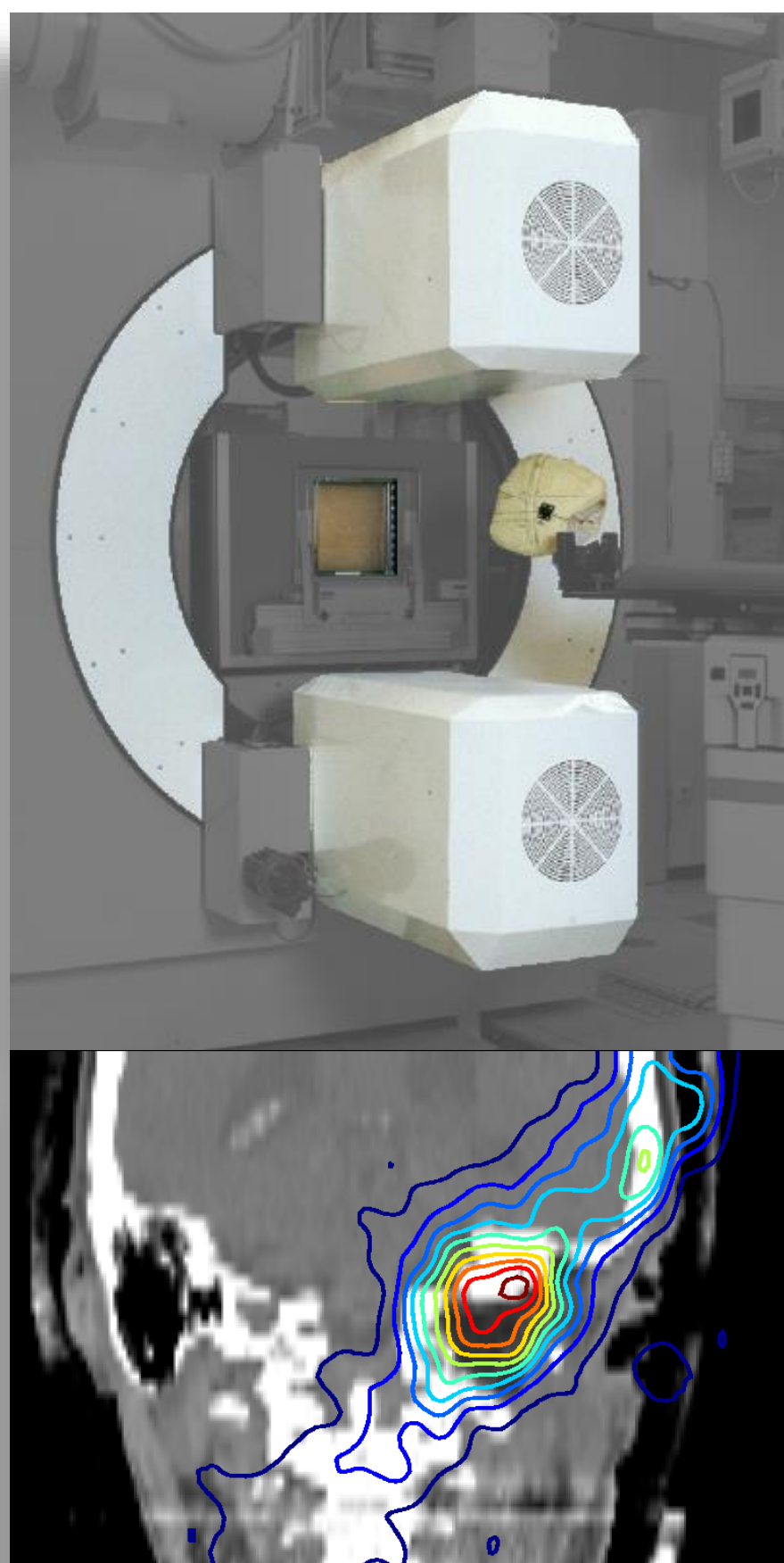
FOR EVERY RECONSTRUCTION STEP

FOR EVERY SYSTEM MATRIX BLOCK

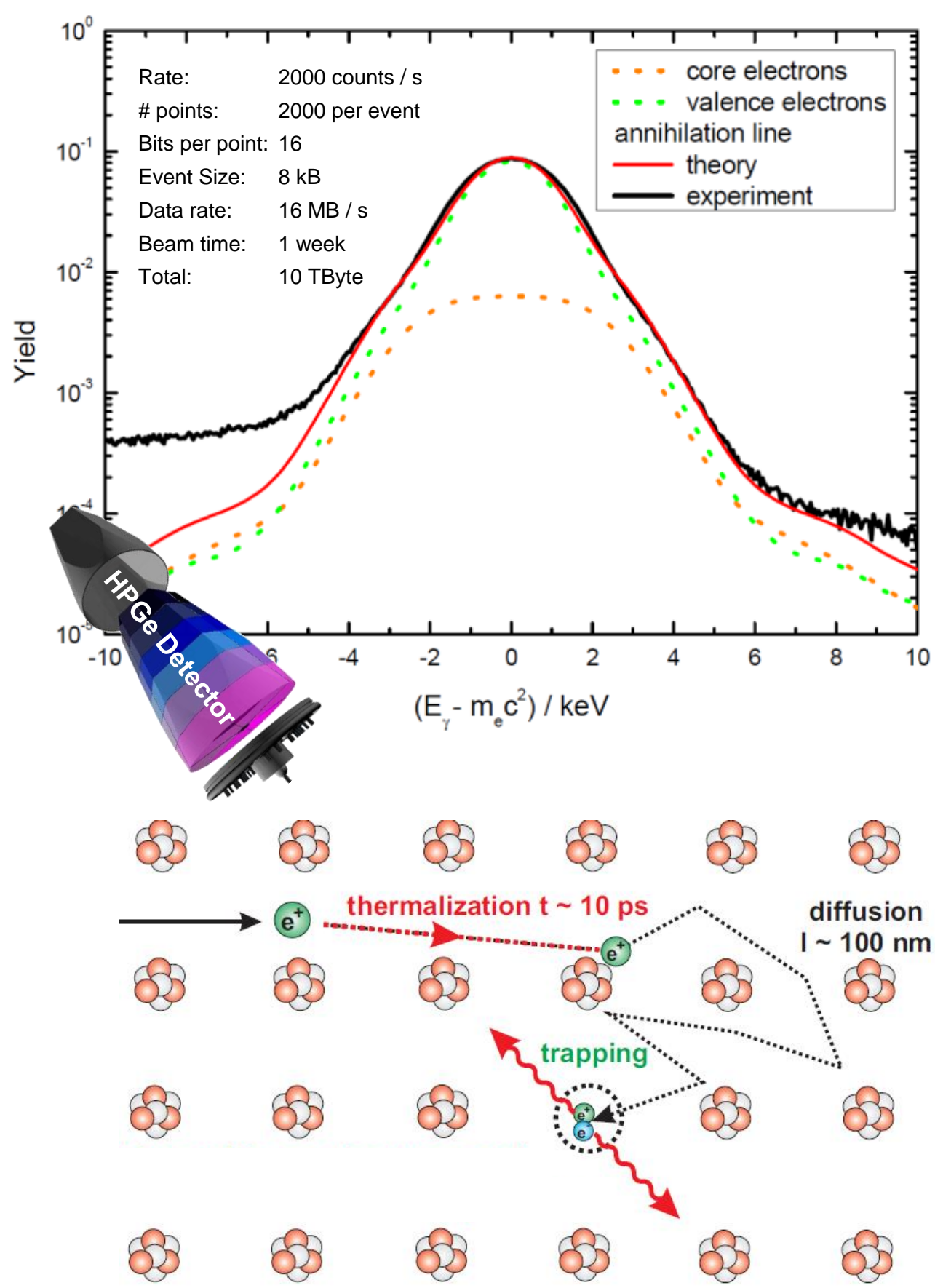
The Algorithm uses a hardware-independent BLAS Interface.

This allows to compare Hardware Performance.

$$\mathbf{x}_j^{(n+1)} = \hat{\mathbf{x}}_j^{(n)} \frac{\sum_{i=1}^N \left(\mathbf{a}_{ij} \frac{y_i}{\sum_{k=1}^M \mathbf{a}_{ik} \hat{x}_k^{(n)}} \right)}{S_j}$$



Positron Annihilation Spectroscopy Event Analysis



TByte / Week

HOST-SYSTEM

Cyclic Buffer

I/O THREAD GPU #1

I/O THREAD GPU #2

I/O THREAD GPU #N

Multi-GPU Support

GPU

H2D Fit D2H

H2D Fit D2H

H2D Fit D2H

H2D Fit D2H

FITTING

Step 1

Step 2

Step 3

Step N

Textures used for fast Access & Interpolation

Concurrency: Blocks, Grids & Streams

