

# High Speed Beam-Based Feedback

**S. Pfeiffer on behalf of the DESY LLRF Team**

2nd ARD ST3 Workshop

HZDR, Dresden

26.02.2014

## 1) Introduction

- Free-Electron Lasers, Beam-Based Feedback

## 2) RF Field Control

- System Modelling and Controller Design for Actuator

## 3) Beam-Based Feedback

- Bunch Arrival Time and Bunch Compression Feedback
  - Feedback Strategies, Results at FLASH

## 4) High Speed Beam-Based Feedback

- Outlook Normal Conducting Cavity, BAM upgrade

## 5) Summary

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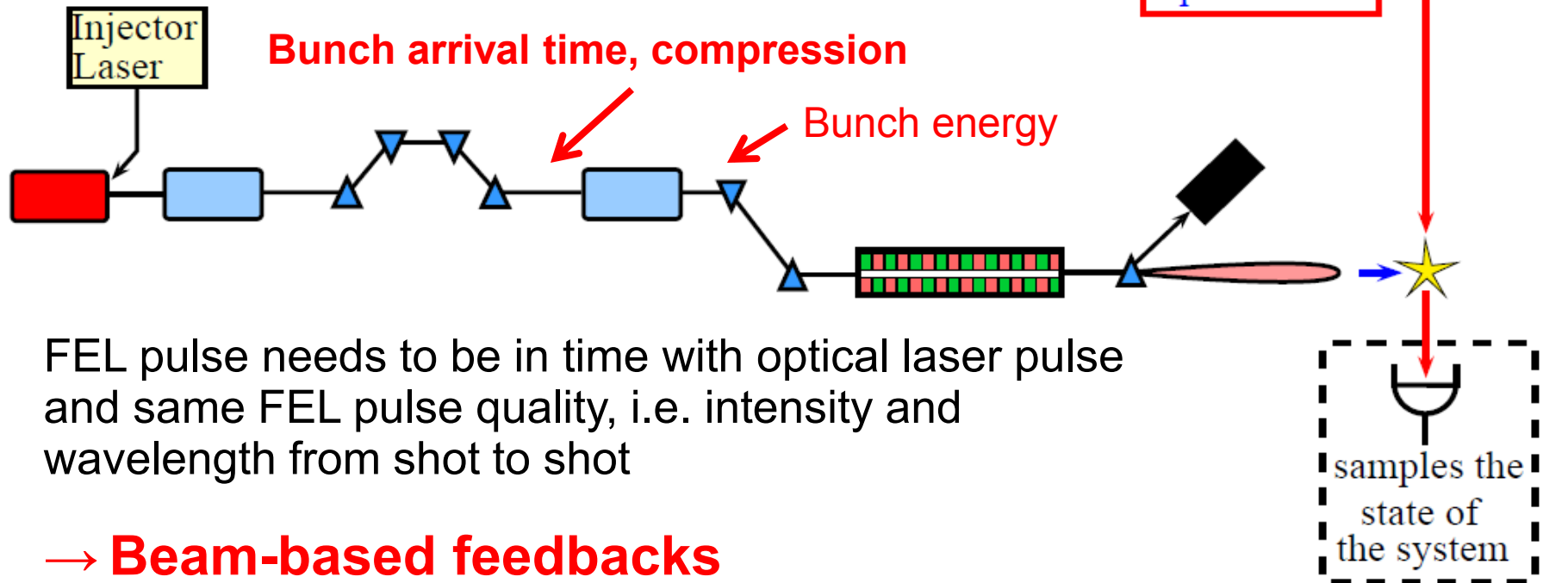
## 5) Summary

# Principle of Free – Electron Laser

## Pump-Probe Experiments

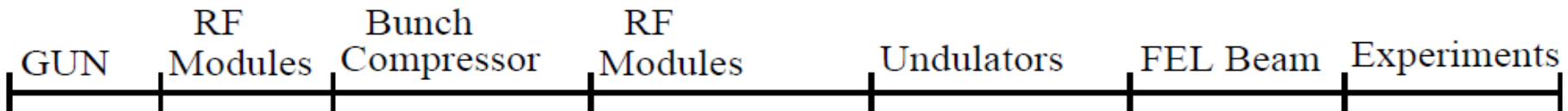
FEL pulse excites the sample

2<sup>nd</sup> laser pulse samples the state of the system



FEL pulse needs to be in time with optical laser pulse and same FEL pulse quality, i.e. intensity and wavelength from shot to shot

→ **Beam-based feedbacks**

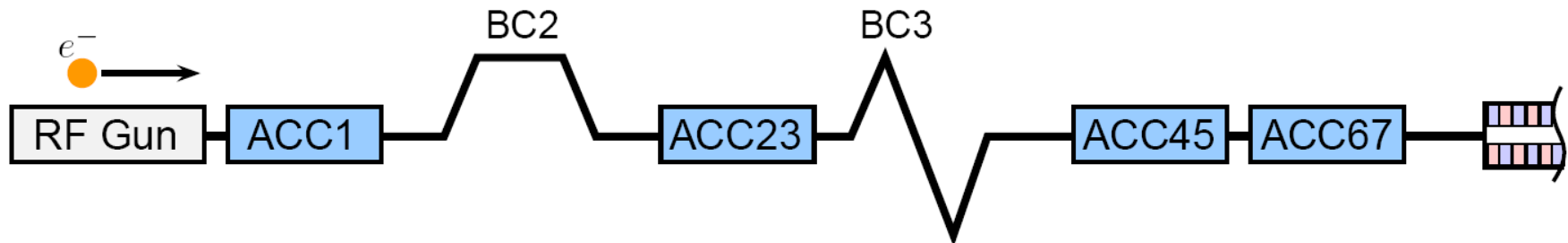


# Linear Accelerators at DESY in Hamburg

## European XFEL – currently under construction



## FLASH – in operation (test bench for XFEL)



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# RF Field Control

## Radio Frequency Field

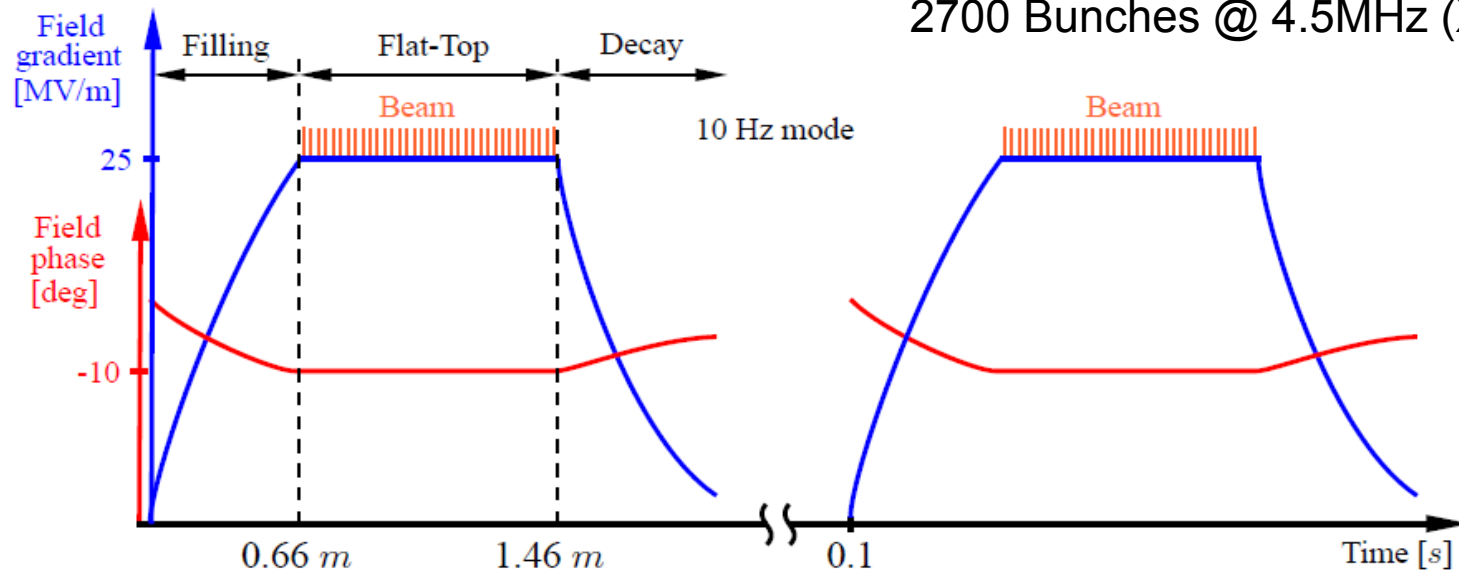


## Control Strategies

**Pulsed operation - 10 Hz**  
2ms pulse length  
(Filling, Flat-top and Decay)

- 1) Adaptation by Learning
- 2) Fast Controller (FPGA)

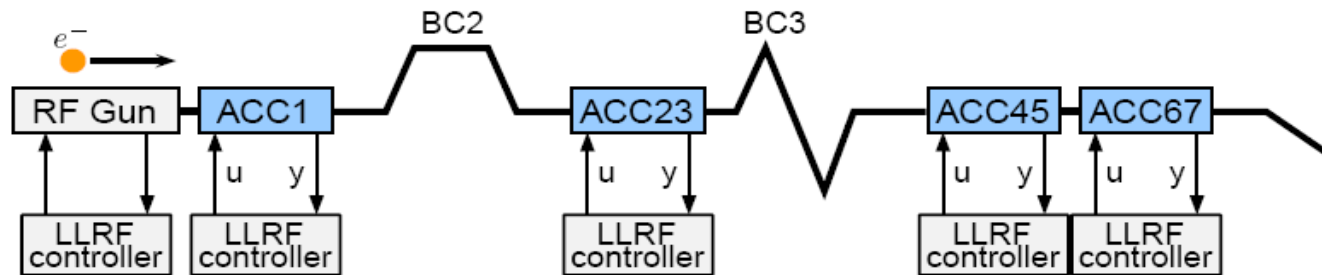
2400 Bunches @ 3MHz (FLASH),  
2700 Bunches @ 4.5MHz (XFEL)



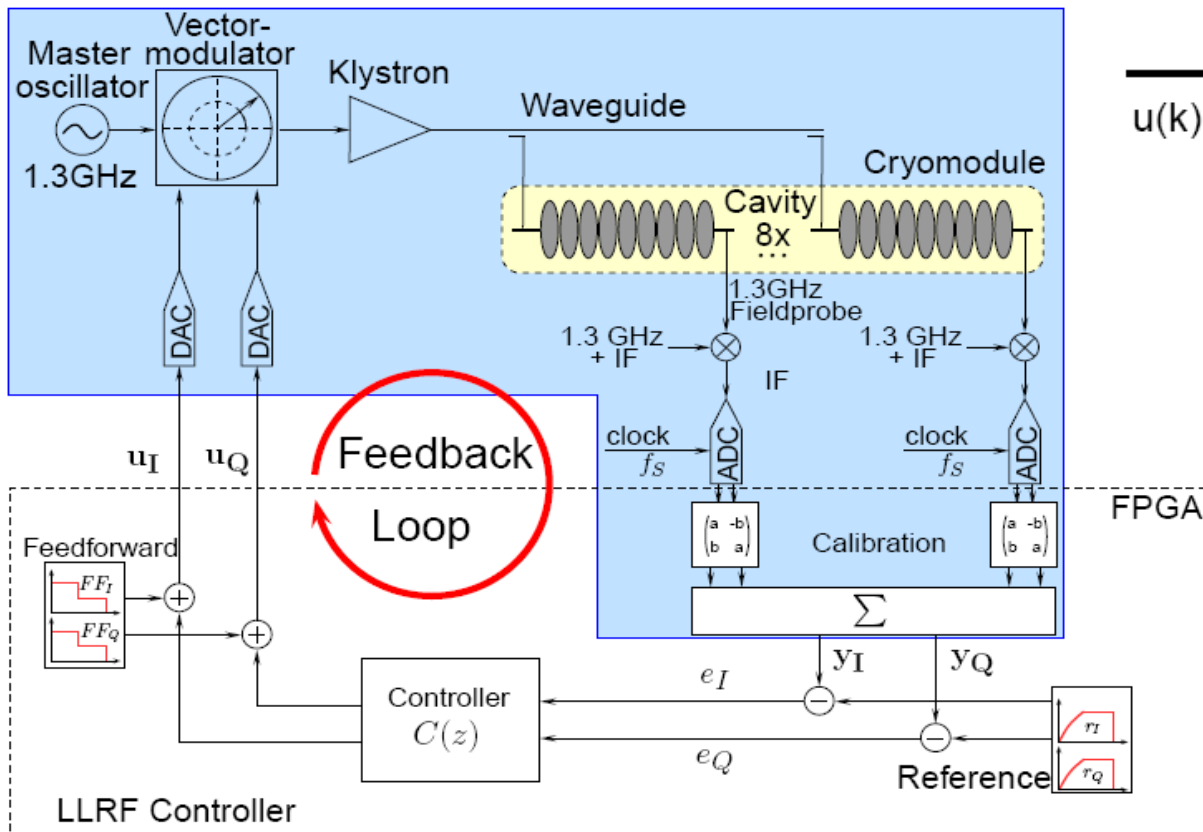
**Model-Based Controller Design**  
to reach  $\Delta A/A < 0.01\%$  and  $\Delta\phi < 0.01$  deg.



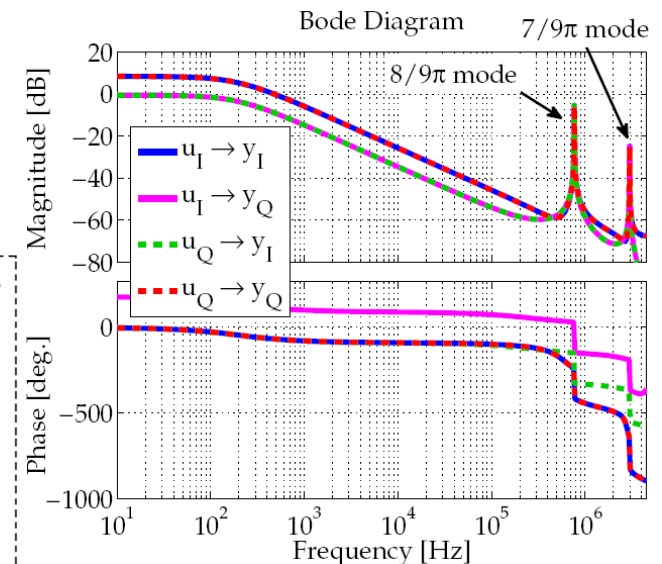
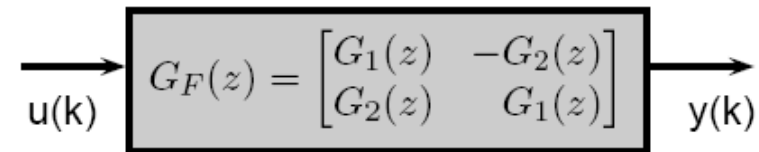
# System Overview (FLASH)



**RF Field  
I/Q control**

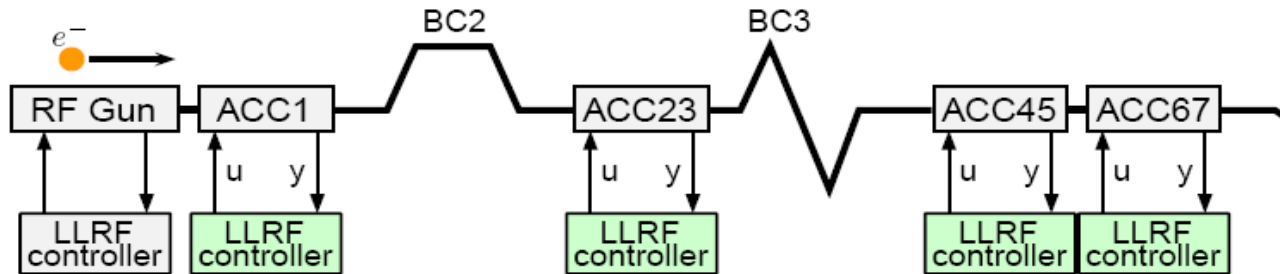


**SO(2) - Grey Box Model**

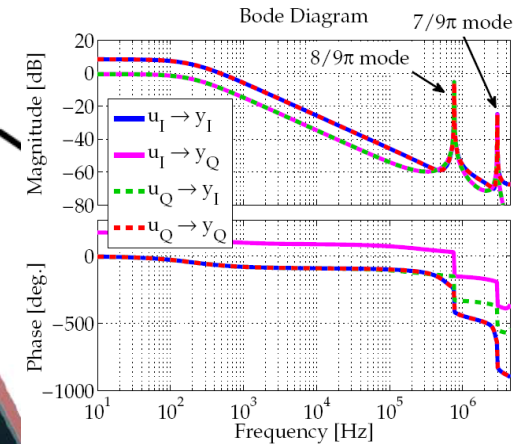




# RF Field Controller



$$C(z) = \begin{bmatrix} C_{II}(z) & C_{IQ}(z) \\ C_{QI}(z) & C_{QQ}(z) \end{bmatrix}$$



2<sup>nd</sup> order IIR →  
only 1 passband  
mode possible

→ 8/9 pi mode by  
*cavity based notch  
filters on SIS8300*

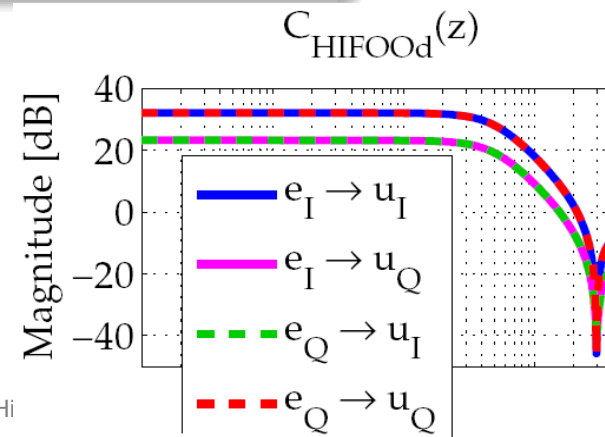
## Controller Implementation on FPGA - 2nd order IIR

$$C_{ij}(z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1 + a_1 z^{-1} + a_2 z^{-2}}$$

20 Parameters to optimize →

Reduced by Factor 2 → 10 Parameters

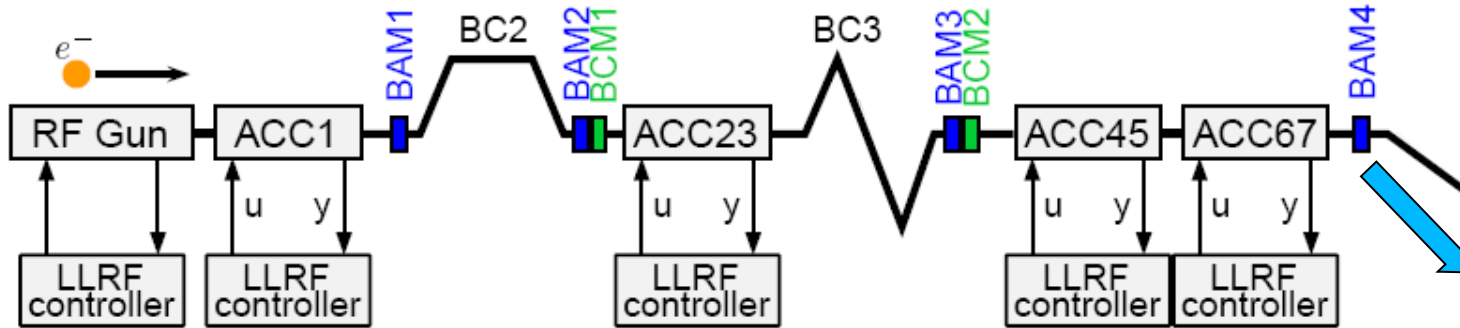
Here:  $\mathcal{H}_\infty$  - Design with HIFOOD



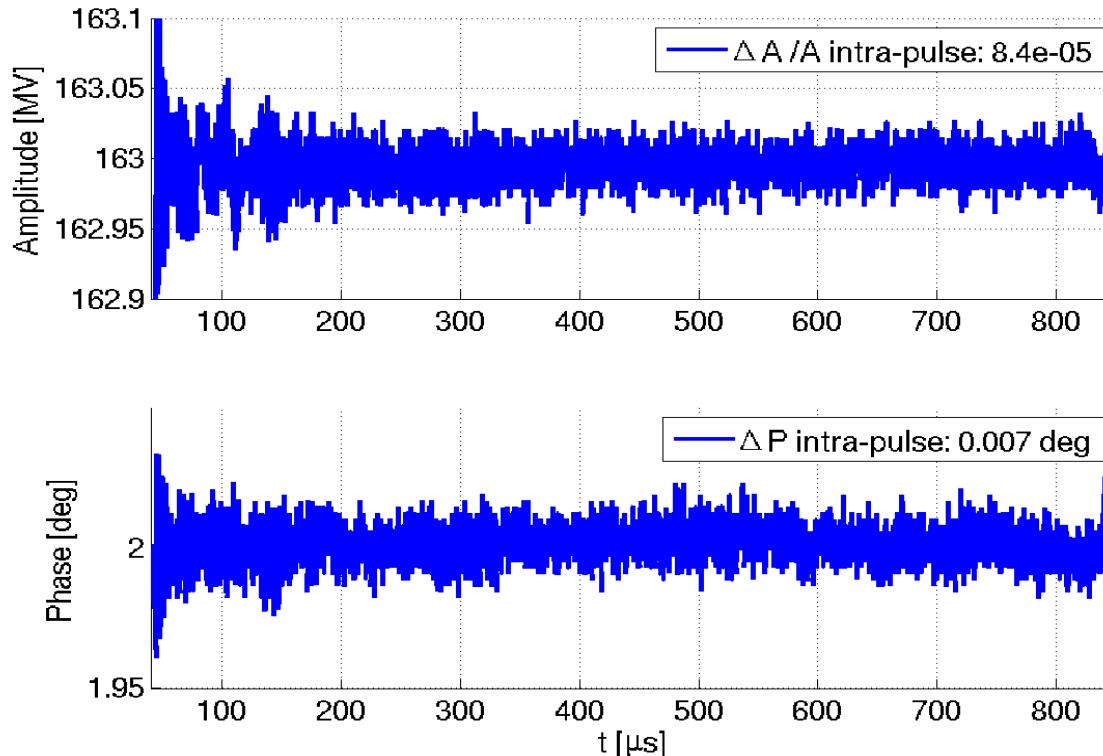
Talk:  
C. Schmidt



# RF Field Controller



ACC1



## Optimal RF Field Control

$$\Delta A/A < 0.008 \%$$
$$\Delta \phi \sim 7 \text{ mdeg.}$$

(MTCA Standard)

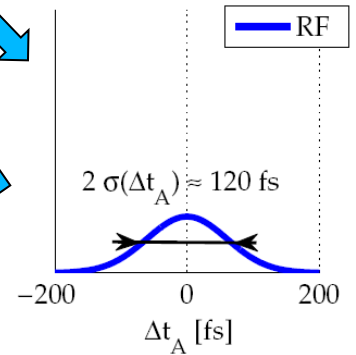
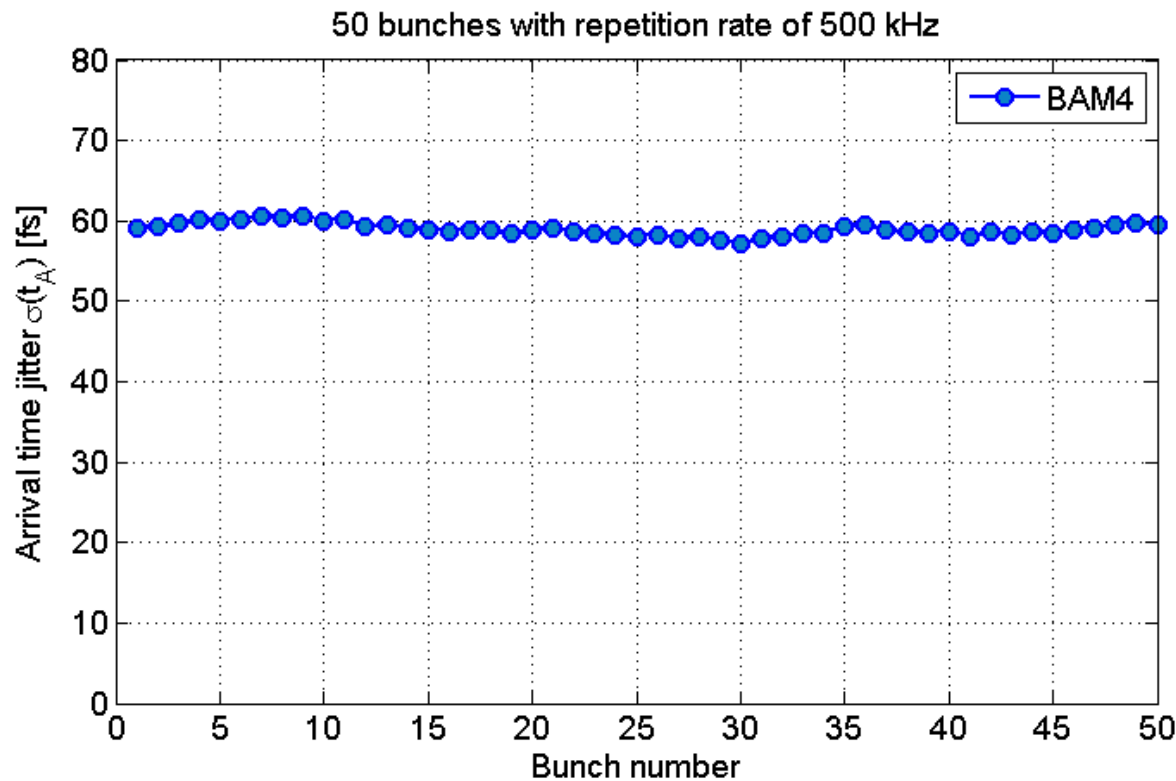
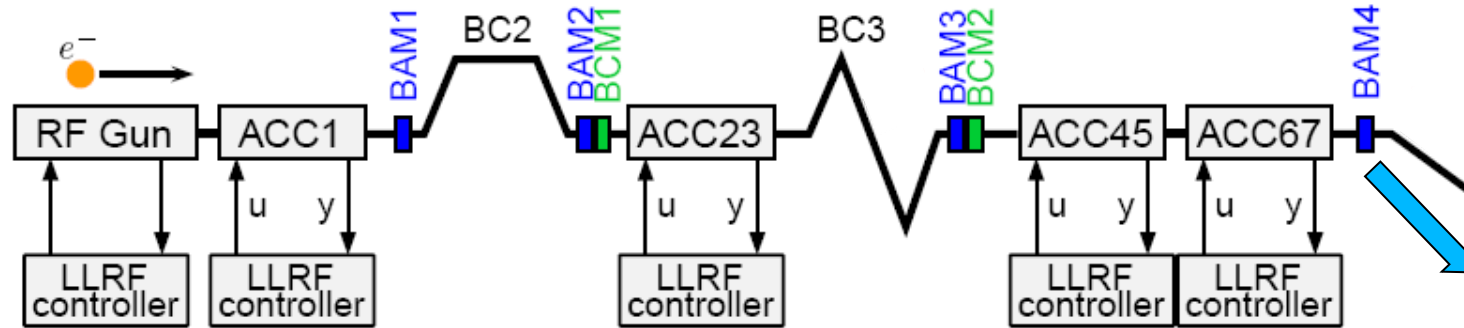


Talk:  
C. Schmidt

Next:  
Beam-based results  
*only for VME*



# RF Field Controller



**Optimal RF Field Control**

$$t_A \approx 60 \text{ fs}$$

**(VME standard)**

**Next: Beam-based FB to improve arr. time jitter**



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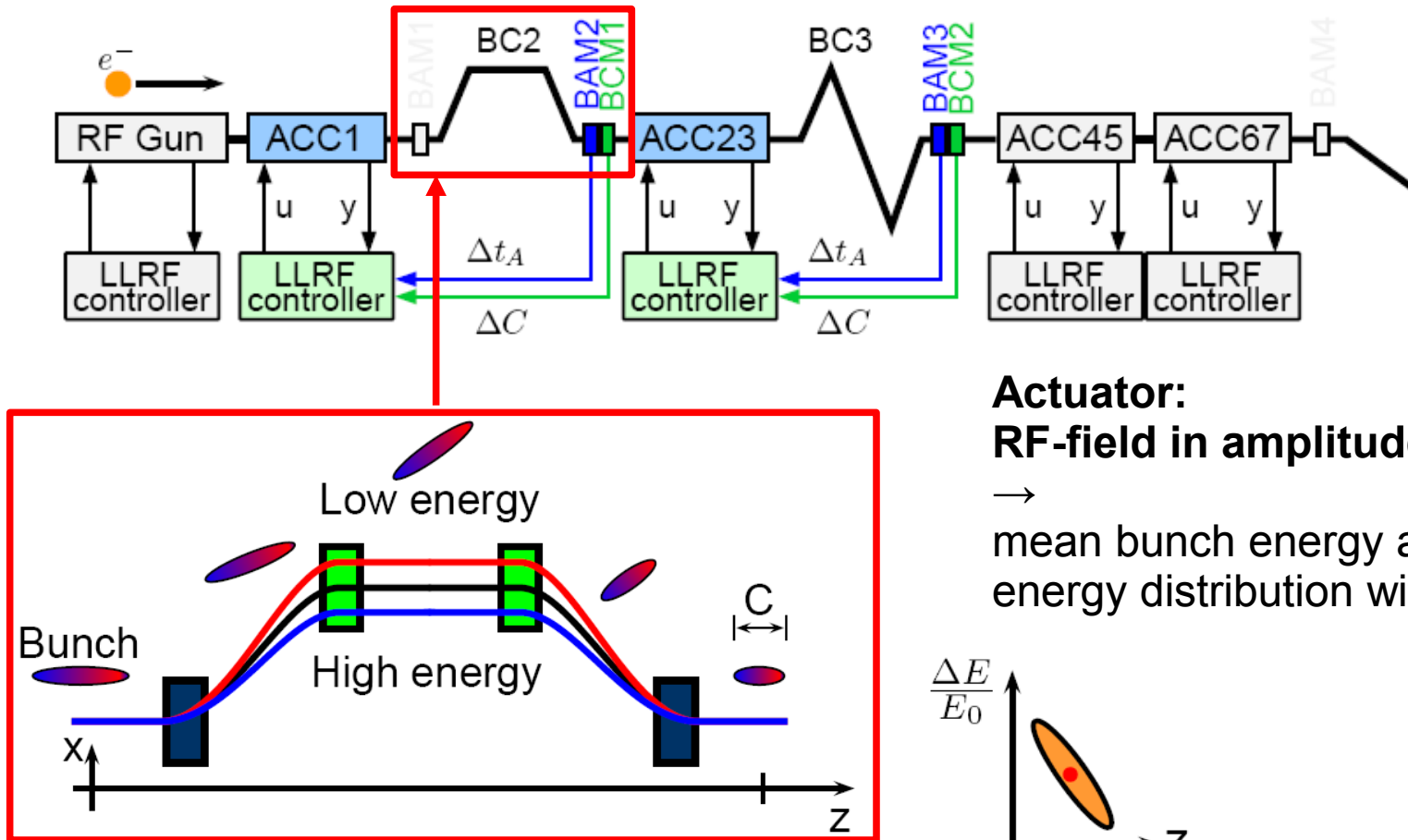
## 4) High Speed Beam-Based Feedback

- Outlook Normal Conducting Cavity, BAM upgrade

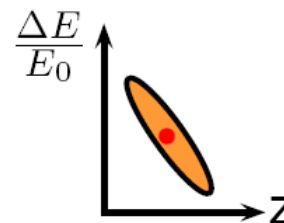
## 5) Summary

# Bunch Arrival Time and Compression Feedback

Bunch energy modulation upstream of BC to control the bunch arrival time and bunch compression

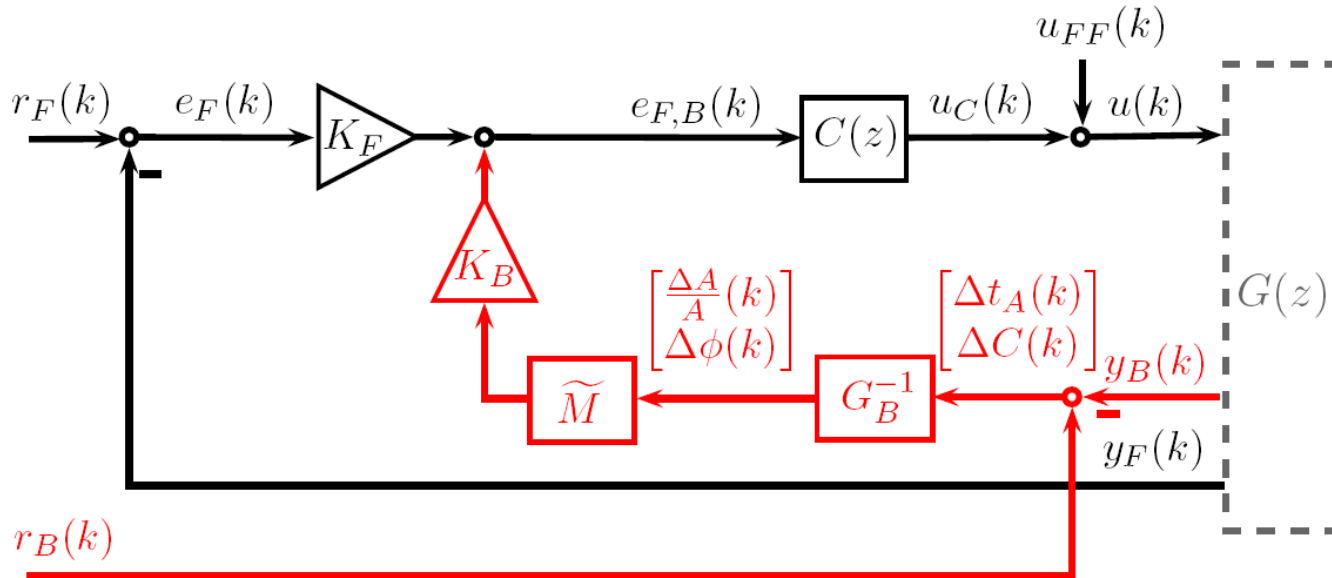


**Actuator:**  
**RF-field in amplitude and phase**  
 →  
 mean bunch energy and  
 energy distribution within a bunch



# Controller Implementation at FLASH

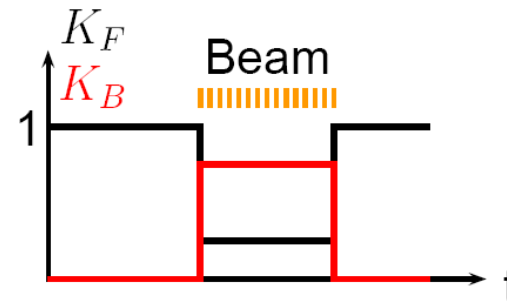
## Bunch arrival time and bunch compression feedback



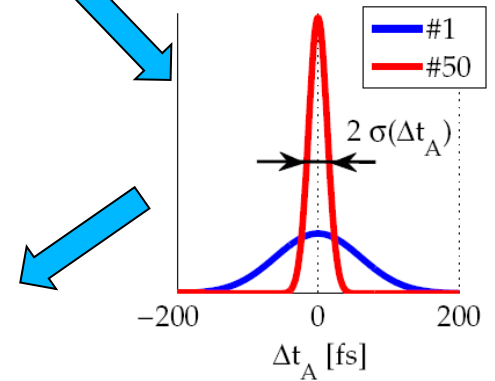
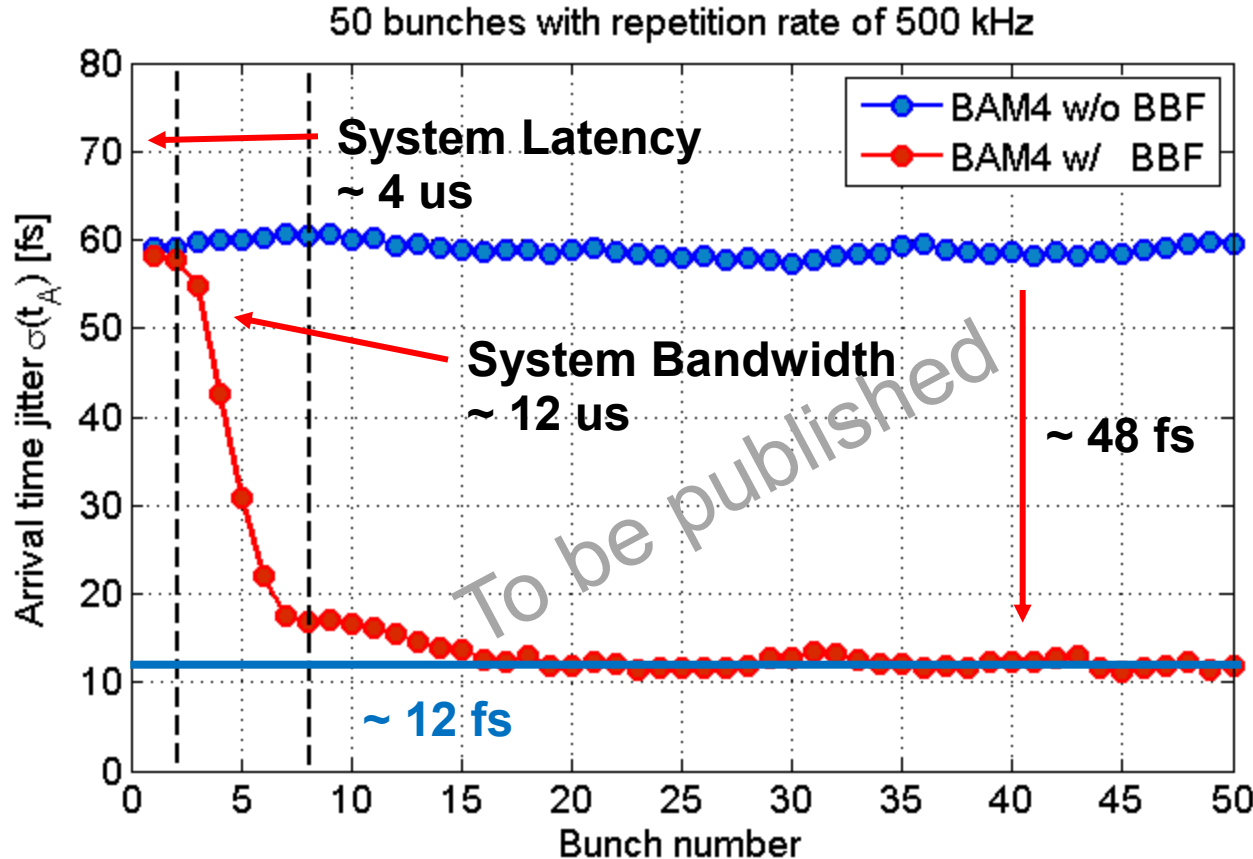
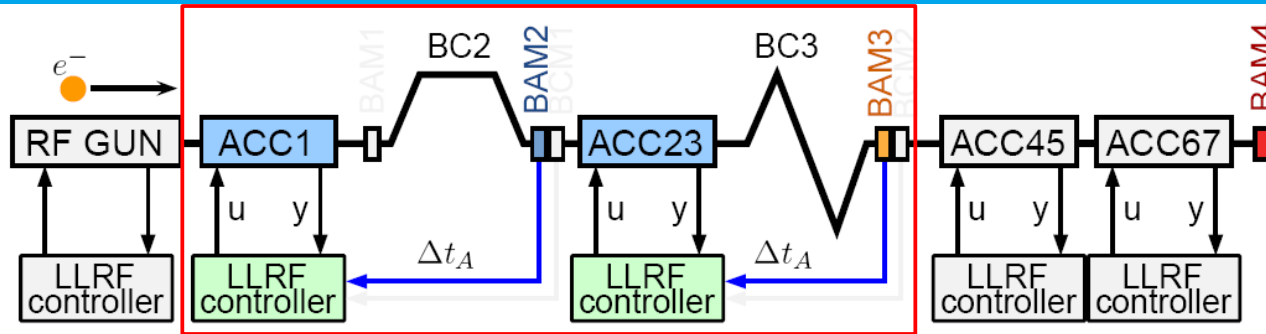
**4 Inputs  
2 Outputs**

Combination of  
RF Field and  
Beam-Based Errors

- $C(z)$  - Controller in I/Q
- $\tilde{M}$  ... Modulation  $\begin{bmatrix} \frac{\Delta A}{A}(k) \\ \Delta\phi(k) \end{bmatrix} \mapsto \begin{bmatrix} e_{B,I} \\ e_{B,Q} \end{bmatrix}$
- $K_F(k)$  and  $K_B(k)$   
→ Adjusted during beam time



# Fast Intratrain Controller at FLASH



- Bunch rep. Rate: 500kHz, 50 Bunche

- BAM4 is an out-of-loop measurement (highest resolution)

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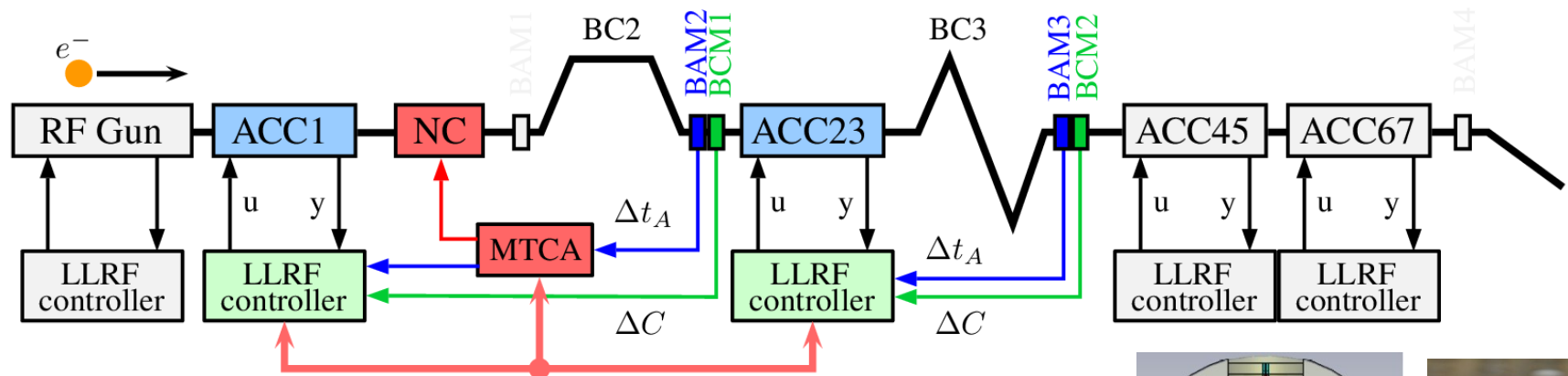
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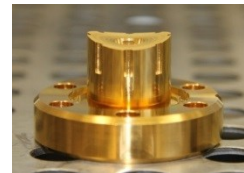
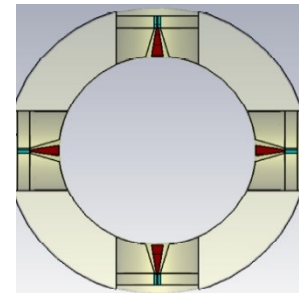
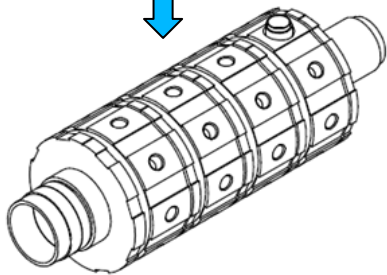


# Outlook: High Speed Beam-Based Feedback

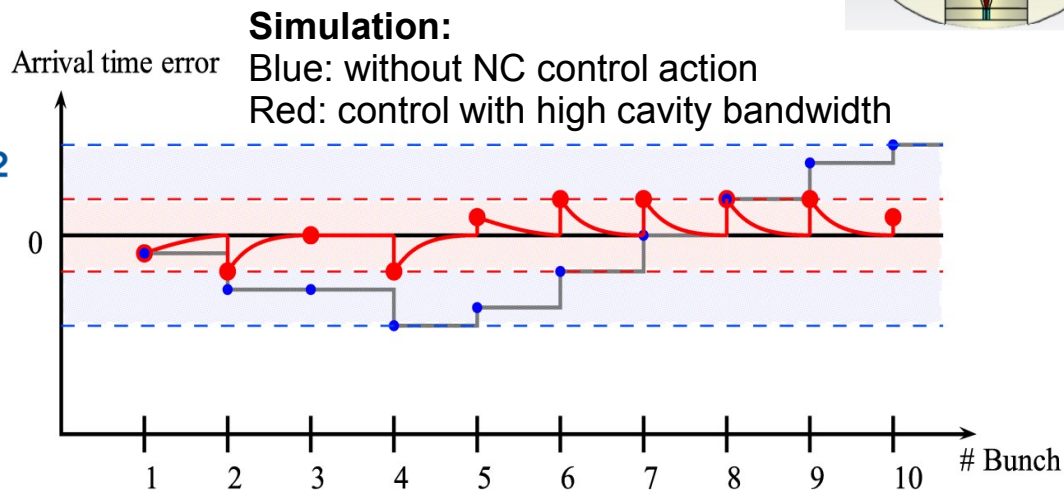
## Normal Conducting (NC) cavity as fast actuator



- Design and Integration of NC cavity
- New BAM pickup design
  - High resolution, Low charge



Courtesy of  
M.K. Czwalińska

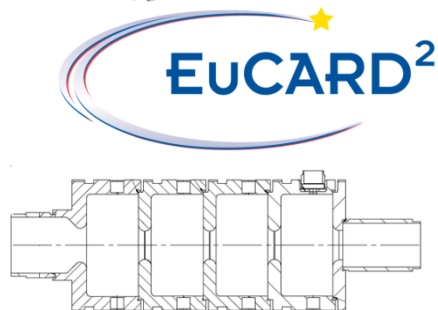


## Design:

Actuator Bandwidth:  
NC (0.5–1.0 MHz)

Latency:  $\sim 0.7 \mu\text{s}$   
BAM Resolution:  $\sim \text{fs}$

**Goal:  $< 5 \text{ fs rms}$**



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# Summary and Outlook

## Summary:

- Beam-based feedback for bunch arrival time and compression
  - Optimization of RF field controller
  - Integration of intra-train beam-based feedback
    - Cascaded control structure for bunch arrival time and compression

***Experience at FLASH shows significant improvements for bunch arrival time and bunch compression***

## Outlook:

- Further improvements using a NC cavity
- Beam-based feedback for MTCA
  - Bunch Arrival Time
  - Bunch Compression
  - Bunch Energy



**Thank you for your attention!**

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