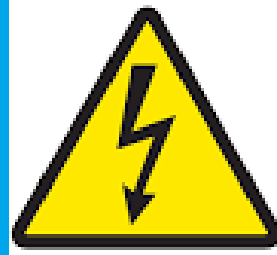


High Voltage Power Module



pluggable to
NAT RTM Power Supply Carrier

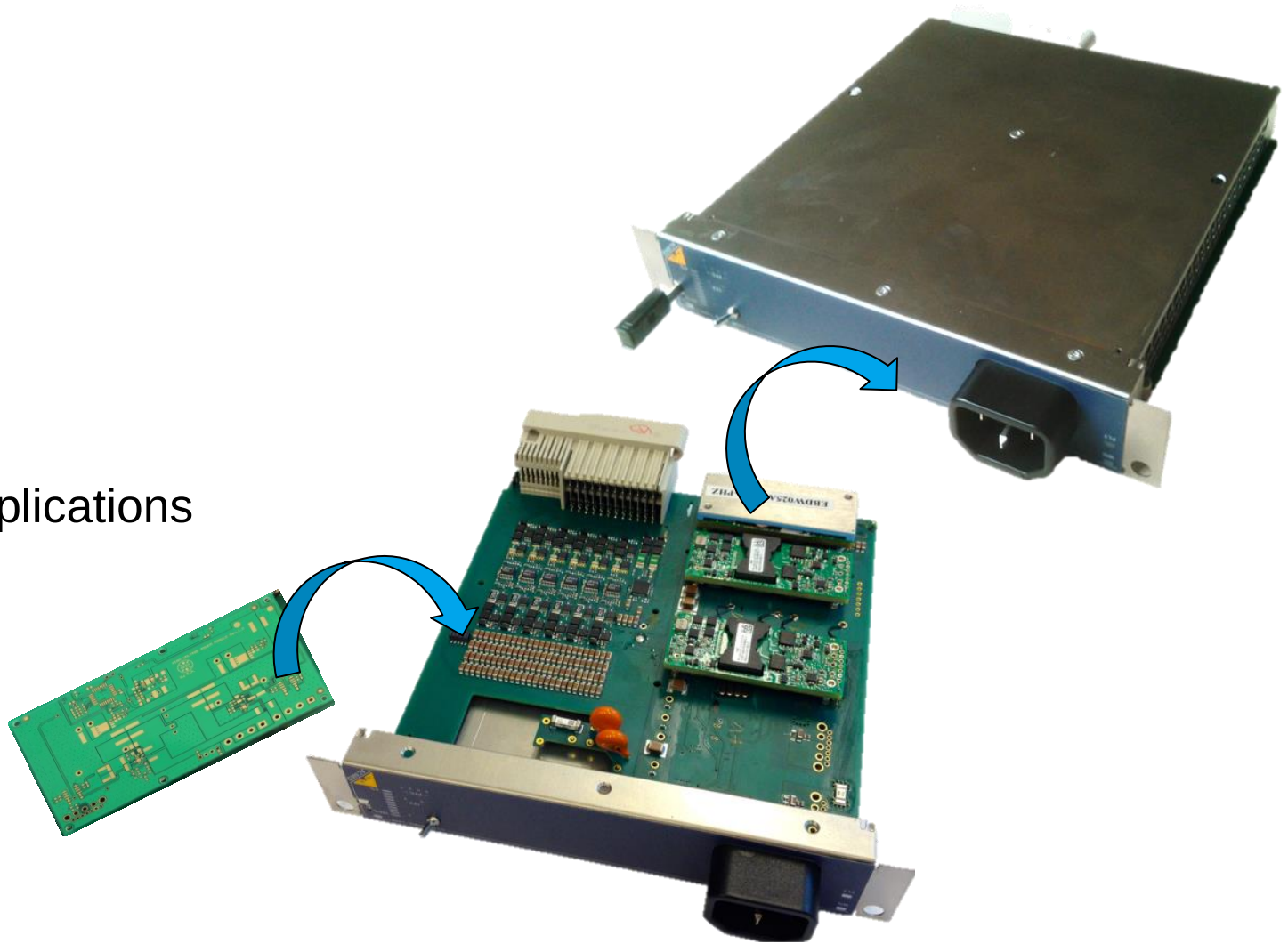
Konrad Przygoda
Michael Fenner,
DESY

Helmut Laftkoetter,
NAT



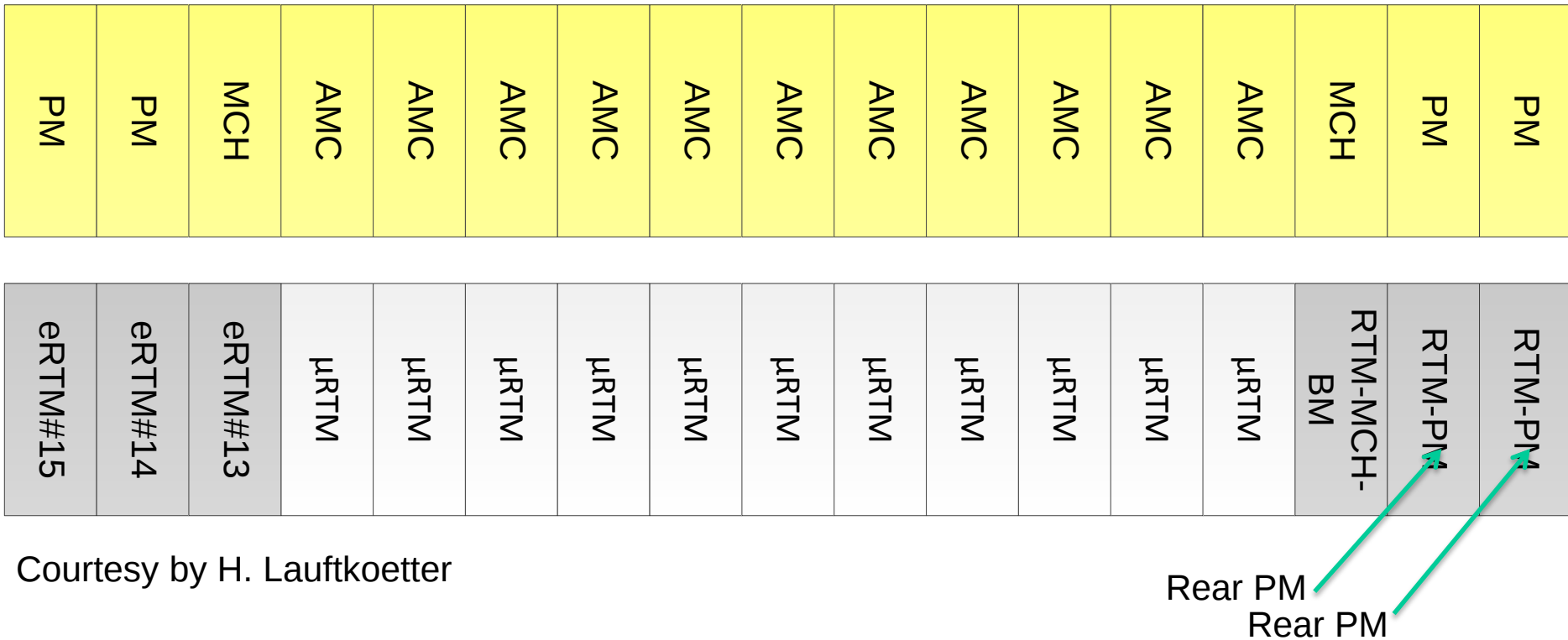
Outline

- Motivation
- Hardware
- Firmware
- Software
- Results
- Possible applications



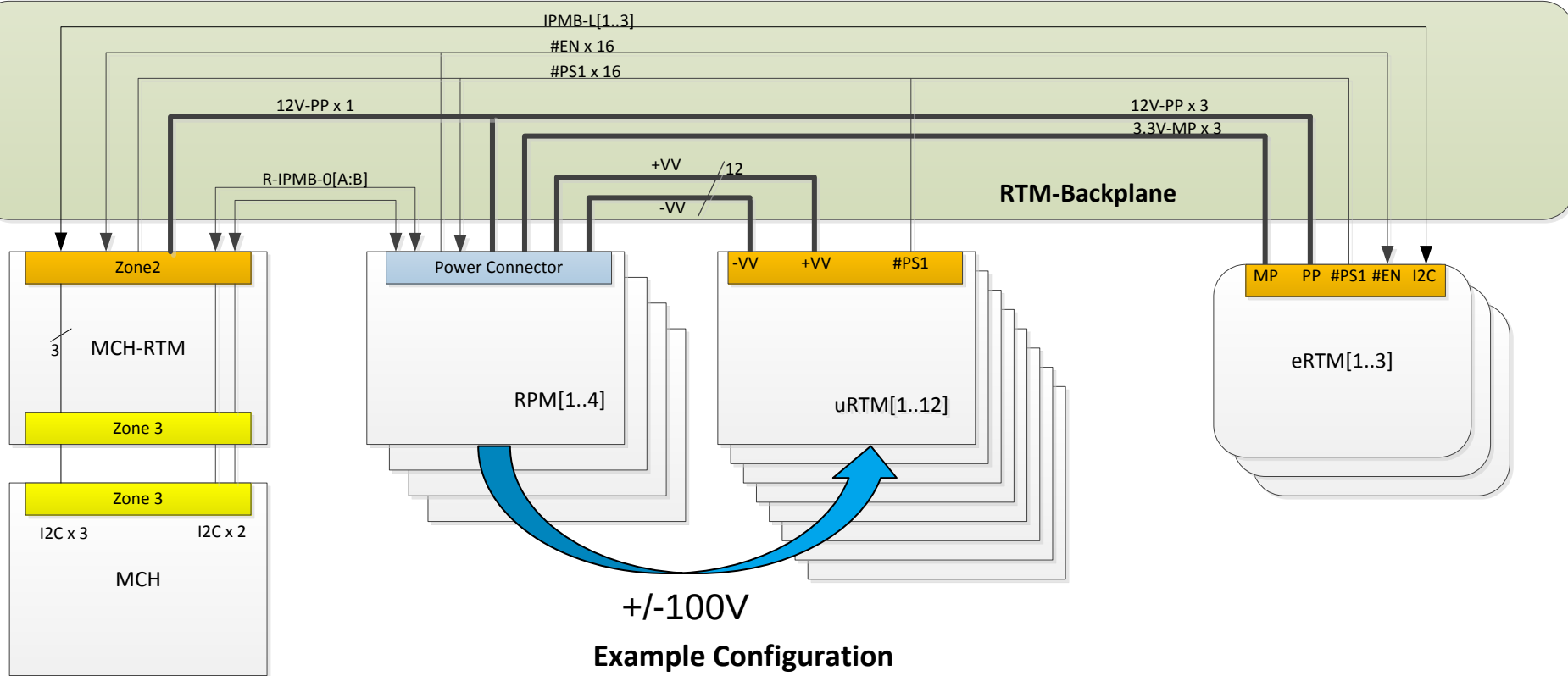
- > DESY introduced an RF-Backplane for MicroTCA.4 Crates
 - The RF-Backplane is located behind the AMC backplane of the MicroTCA.4 Crate.
 - Three types of RTMs used: μ RTMs with only a Zone-3 connection to the front AMCs, μ RTMs with a connector to the RF-Backplane and optionally a Zone-3 connection to the front AMCs and extended RTMs
- > eRTMs are not covered by MicroTCA.4 Specification, a standard Power Modules does not provide power to them
- > μ RTMs used together with the RF-Backplane might be powered from the RF-Backplane instead of corresponding to a given AMC board
- > In many cases sensitive analog signal conditioning elements are installed on RTMs and there is a need to provide clean power supply to these RTMs
- > For specific applications there is a need to deliver high voltage, high current power supply which is not covered by MicroTCA.4 Specification

Hardware (RF-Backplane)



Courtesy by H. Laufkoetter

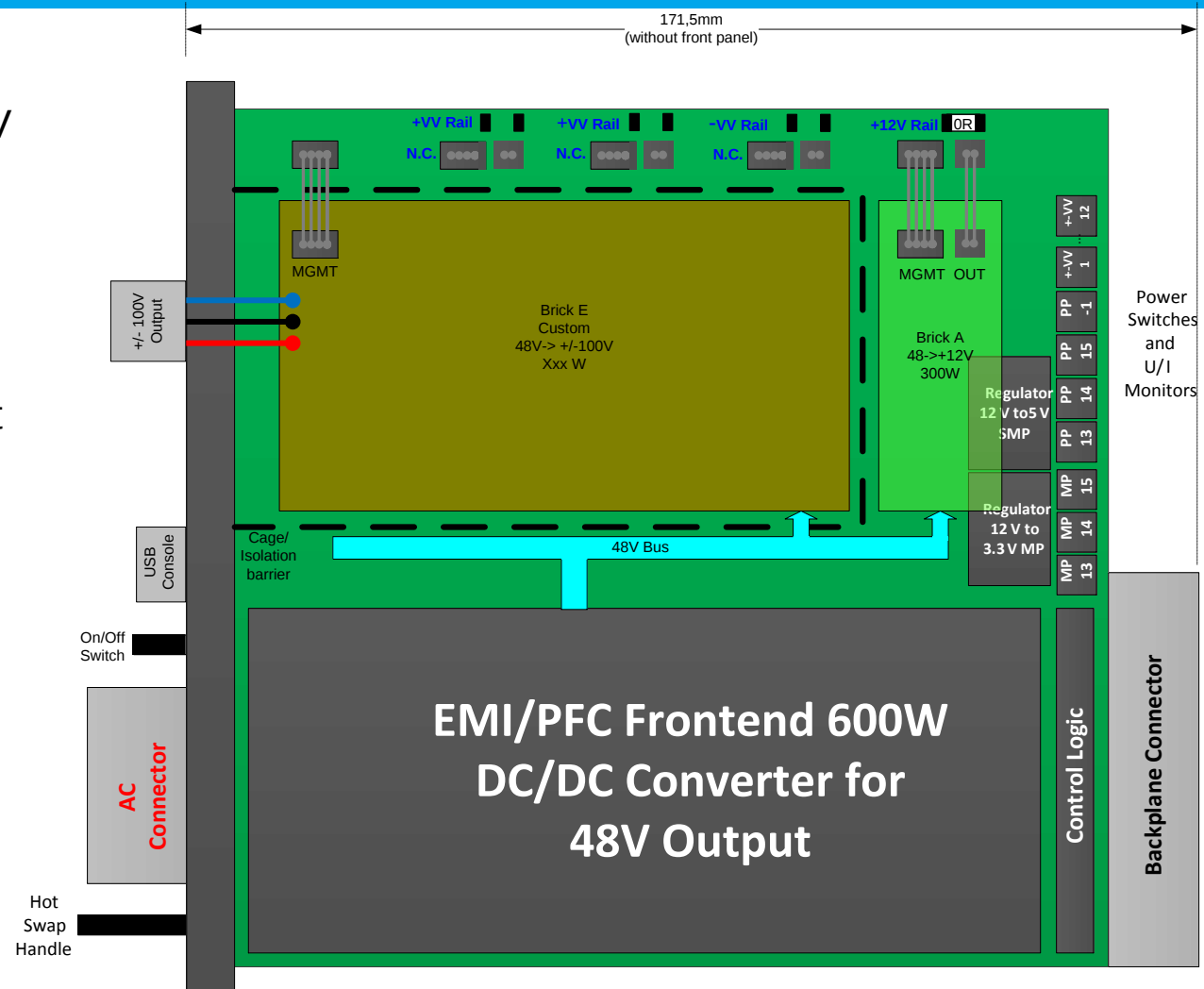
Hardware (Example Setup)



Courtesy by H. Laufkoetter

Hardware (NAT RTM Power Supply Carrier)

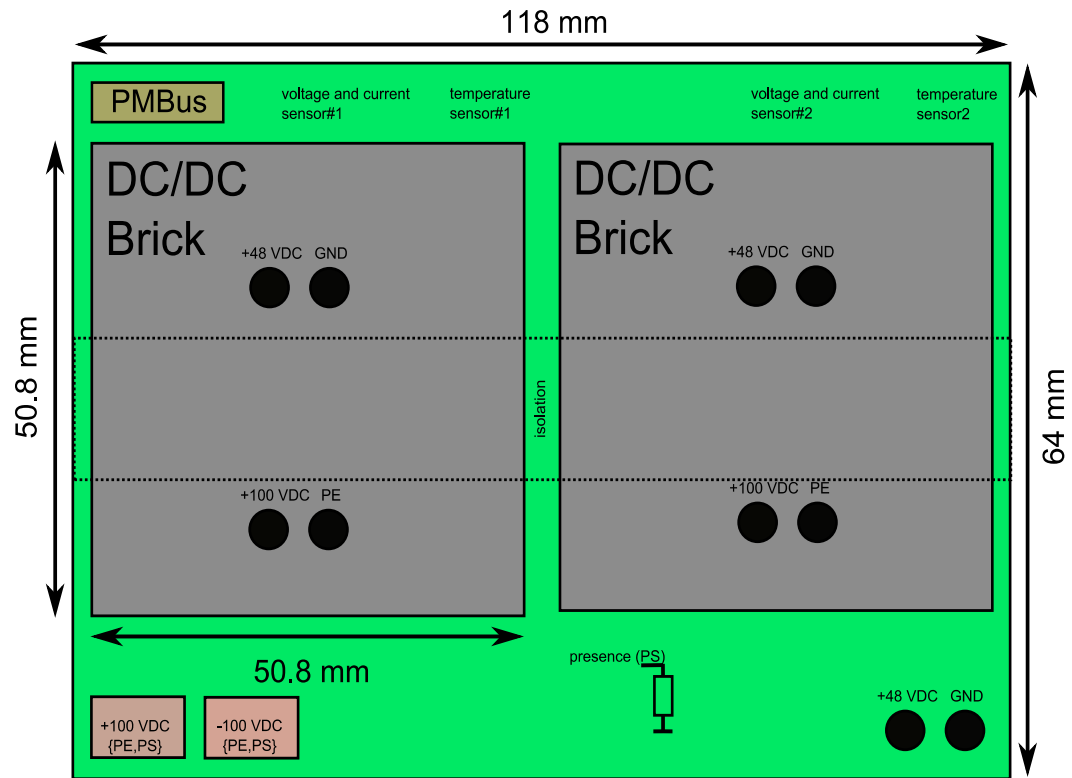
- High quality $\pm VV$ for μ RTMs, adjustable 5-12V
- +12V PP, +3.3V MP for eRTMs
- Contention protection against standard PMs
- Modular design
- Optional $\pm 100V$ output at front panel
- AC frontend



Courtesy by H. Laufkoetter

Hardware (High Voltage Power Module)

- Accept low voltage input (up to +48 VDC) and deliver stable, high voltage (up to ± 100 VDC – bipolar or unipolar) and high current (up to 500 mA) outputs
- PMBus standard communication bus
- Temperature, output voltage, current and power sensors
- Allow supplying up to 4x RTM cards
- High voltage output indicated by front panel LEDs
- Built in: short circuit protection, input filter
- Inputs/outputs isolated with possible line, load regulation
- Closed inside housing (Nickel Plated Copper),
- Cooled using free air convection (no additional heat sink needed)



Firmware (ATXMEGA128A1U)

> hvpm.c

- void HVPM_DriverInit(); void HVPM_ActivateHVPos(); void HVPM_DeactivateHVPos();
- void HVPM_ActivateHVNeg(); void HVPM_DeActivateHVNeg();
- void HVPM_ActivateHVPosNeg(); void HVPM_DeActivateHVPosNeg();
- void HVPM_TemperatureSenseHVPos(); void HVPM_TemperatureSenseHVNeg();
- void HVPM_VoltageSenseHVPos(); void HVPM_CurrentSenseHVPos();
- void HVPM_PowerSenseHVPos(); void HVPM_VoltageSenseHVNeg();
- void HVPM_CurrentSenseHVNeg(); void HVPM_PowerSenseHVNeg();

> hvpm.h

- #define MAX6626A_ADDR (0x48)
- #define MAX6626B_ADDR (0x49)
- #define LTC2945A_ADDR (0xD8>>1)
- #define LTC2945B_ADDR (0xDE>>1)
- ...

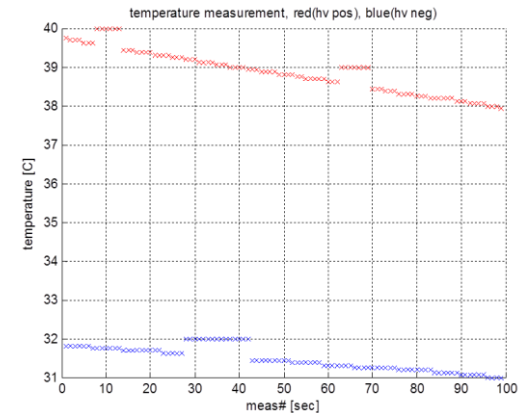


Software

```
VT Tera Term - [disconnected] VT
File Edit Setup Control Window Help
pnbus_init(1): MFR_DEVICE_TYPE failed 0xff
pnbus_setDefaultVolt(0): 120=0xc000
hsc_Init:
CCCCCCCCPM6: pm_startArb, PWR_STATE=0x0040
PM6 is primary !
PM6: ->AUTO !
PM6: pm_startArb done - PWR_STATE=0x0060
PM6 is prim !
pfcState[0,1]=1,1
pfcState[0,1]=1,1
pfcState[0,1]=1,1
---> Bridge ON !
H
HVPM>HVPM ON

HVPM>HVPM OFF

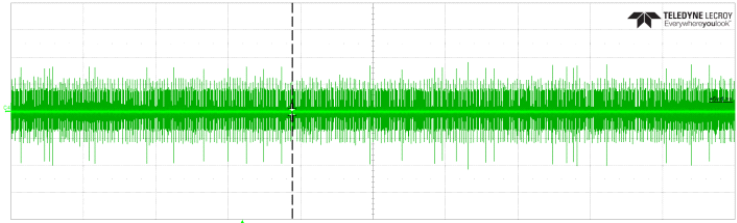
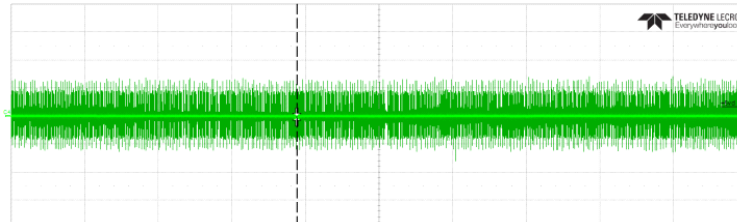
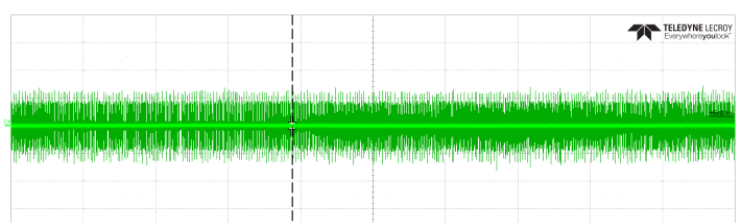
HVPM>HvpmDriverActivateHVM
HVPM>HvpmDriverDeActivateHVM
HVPM>HvpmDriverActivateHV
HVPM>HvpmDriverDeActivateHV
```



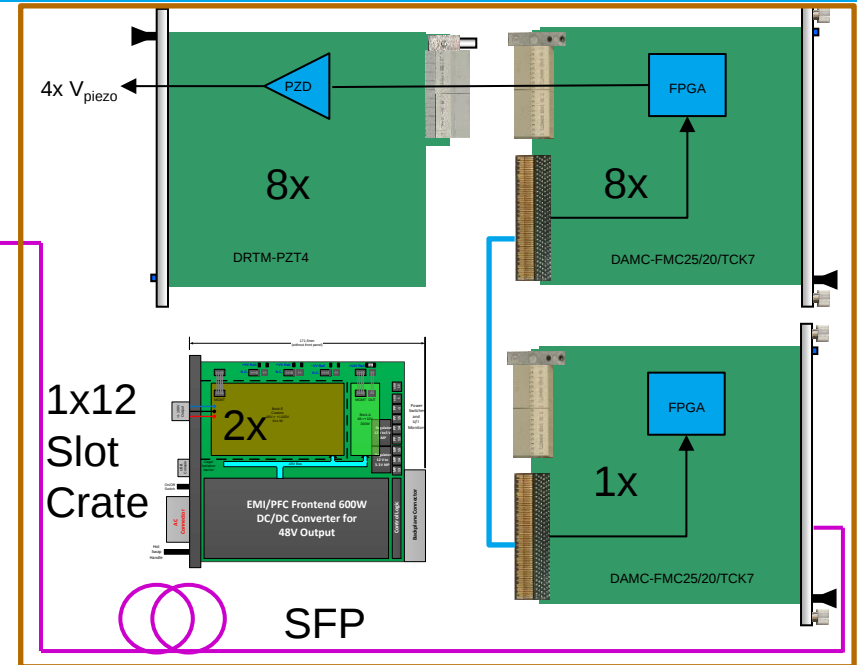
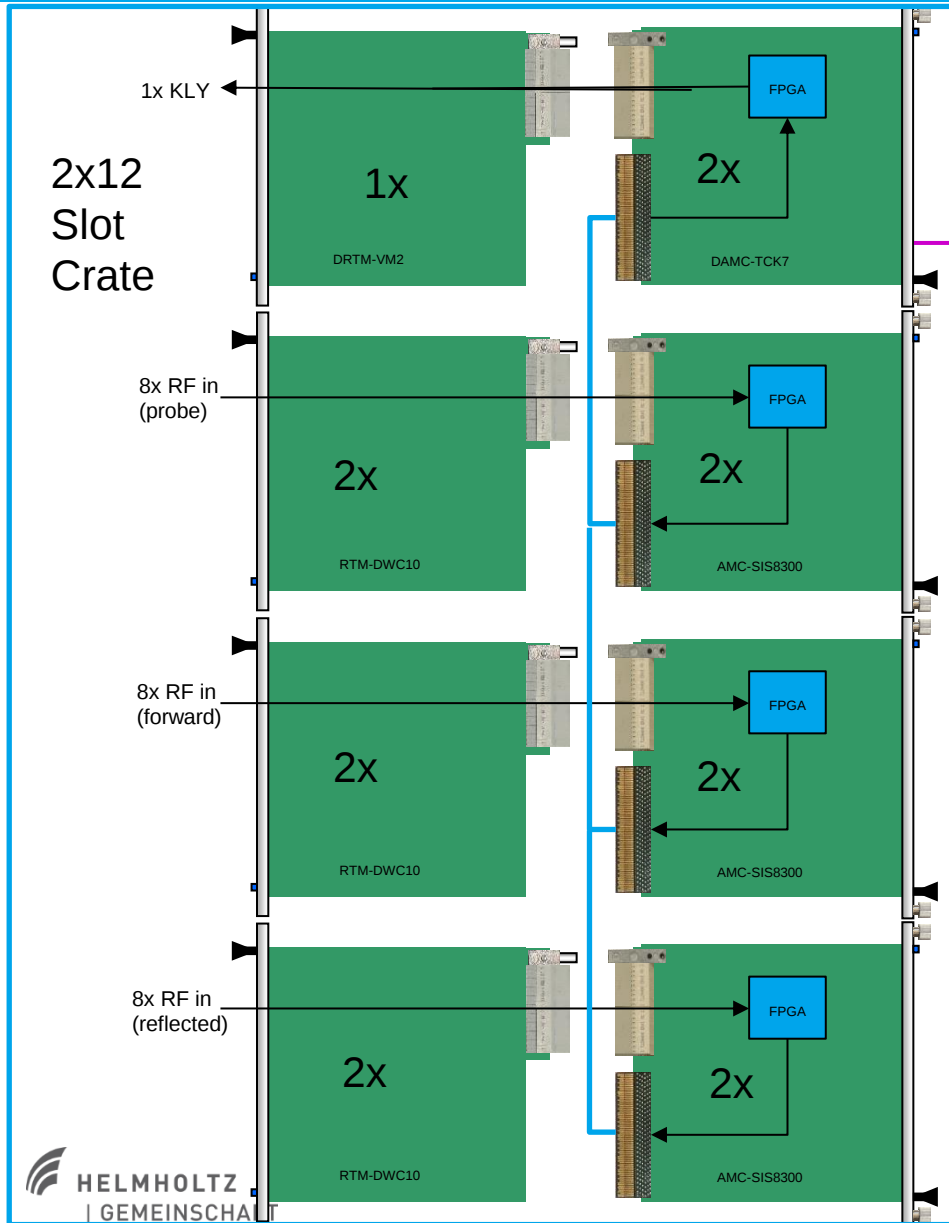
NAT RTM PSC menu

HVPM submenu

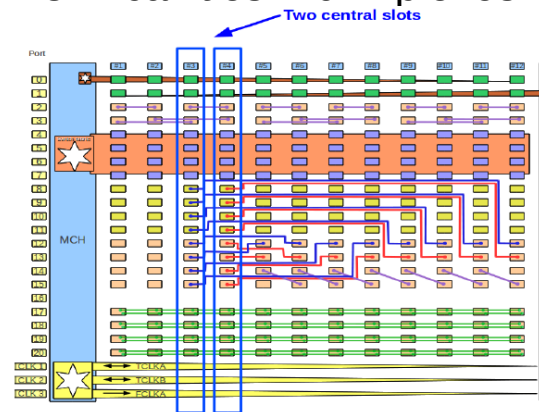
Results

Load	Ripples [Vrms]	Waveform																											
0V@none	0.051	 TELEDYNE LECRODY Everywhere you look Measure <table border="1"> <thead> <tr> <th>Measure</th> <th>value</th> <th>status</th> </tr> </thead> <tbody> <tr> <td>P1: max(C4)</td> <td>908 mV</td> <td>✓</td> </tr> <tr> <td>P2: min(C4)</td> <td>-1.088 V</td> <td>✓</td> </tr> <tr> <td>P3: rms(C4)</td> <td>51.1 mV</td> <td>✓</td> </tr> <tr> <td>P4: sdew(C4)</td> <td>50.5 mV</td> <td>✓</td> </tr> <tr> <td>P5: ...</td> <td></td> <td></td> </tr> <tr> <td>P6: ...</td> <td></td> <td></td> </tr> <tr> <td>P7: ...</td> <td></td> <td></td> </tr> <tr> <td>P8: ...</td> <td></td> <td></td> </tr> </tbody> </table> AC1H 500 mV/div 0.0 mV offset 1: -14.7 mV 2: -14.7 mV 3: 0.0 mV 4: 0.0 mV Time: 1.00 ms Trigger: C2 DC Scale: 1.00 mV/div Auto: 1.00 V X1: 600.00 µs ΔX: 0 ns X2: 600.00 µs 10X+ —	Measure	value	status	P1: max(C4)	908 mV	✓	P2: min(C4)	-1.088 V	✓	P3: rms(C4)	51.1 mV	✓	P4: sdew(C4)	50.5 mV	✓	P5: ...			P6: ...			P7: ...			P8: ...		
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P7: ...																													
P8: ...																													
100V@200 Ohm	0.036	 TELEDYNE LECRODY Everywhere you look Measure <table border="1"> <thead> <tr> <th>Measure</th> <th>value</th> <th>status</th> </tr> </thead> <tbody> <tr> <td>P1: max(C4)</td> <td>702 mV</td> <td>✓</td> </tr> <tr> <td>P2: min(C4)</td> <td>-903 mV</td> <td>✓</td> </tr> <tr> <td>P3: rms(C4)</td> <td>36.2 mV</td> <td>✓</td> </tr> <tr> <td>P4: sdew(C4)</td> <td>36.1 mV</td> <td>✓</td> </tr> <tr> <td>P5: ...</td> <td></td> <td></td> </tr> <tr> <td>P6: ...</td> <td></td> <td></td> </tr> <tr> <td>P7: ...</td> <td></td> <td></td> </tr> <tr> <td>P8: ...</td> <td></td> <td></td> </tr> </tbody> </table> AC1H 500 mV/div 0.0 mV offset 1: -10.8 mV 2: -10.8 mV 3: 0.0 mV 4: 0.0 mV Time: 1.00 ms Trigger: C2 DC Scale: 1.00 mV/div Auto: 1.00 V X1: 600.00 µs ΔX: 0 ns X2: 600.00 µs 10X+ —	Measure	value	status	P1: max(C4)	702 mV	✓	P2: min(C4)	-903 mV	✓	P3: rms(C4)	36.2 mV	✓	P4: sdew(C4)	36.1 mV	✓	P5: ...			P6: ...			P7: ...			P8: ...		
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P6: ...																													
P7: ...																													
P8: ...																													
-100V@200 Ohm	0.043	 TELEDYNE LECRODY Everywhere you look Measure <table border="1"> <thead> <tr> <th>Measure</th> <th>value</th> <th>status</th> </tr> </thead> <tbody> <tr> <td>P1: max(C4)</td> <td>700 mV</td> <td>✓</td> </tr> <tr> <td>P2: min(C4)</td> <td>-815 mV</td> <td>✓</td> </tr> <tr> <td>P3: rms(C4)</td> <td>42.5 mV</td> <td>✓</td> </tr> <tr> <td>P4: sdew(C4)</td> <td>42.3 mV</td> <td>✓</td> </tr> <tr> <td>P5: ...</td> <td></td> <td></td> </tr> <tr> <td>P6: ...</td> <td></td> <td></td> </tr> <tr> <td>P7: ...</td> <td></td> <td></td> </tr> <tr> <td>P8: ...</td> <td></td> <td></td> </tr> </tbody> </table> AC1H 500 mV/div 0.0 mV offset 1: -4.7 mV 2: -4.7 mV 3: 0.0 mV 4: 0.0 mV Time: 1.00 ms Trigger: C2 DC Scale: 1.00 mV/div Auto: 1.00 V X1: 600.00 µs ΔX: 0 ns X2: 600.00 µs 10X+ —	Measure	value	status	P1: max(C4)	700 mV	✓	P2: min(C4)	-815 mV	✓	P3: rms(C4)	42.5 mV	✓	P4: sdew(C4)	42.3 mV	✓	P5: ...			P6: ...			P7: ...			P8: ...		
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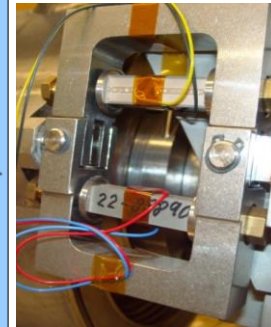
Possible Applications (XFEL RF Station – 32 cavities)



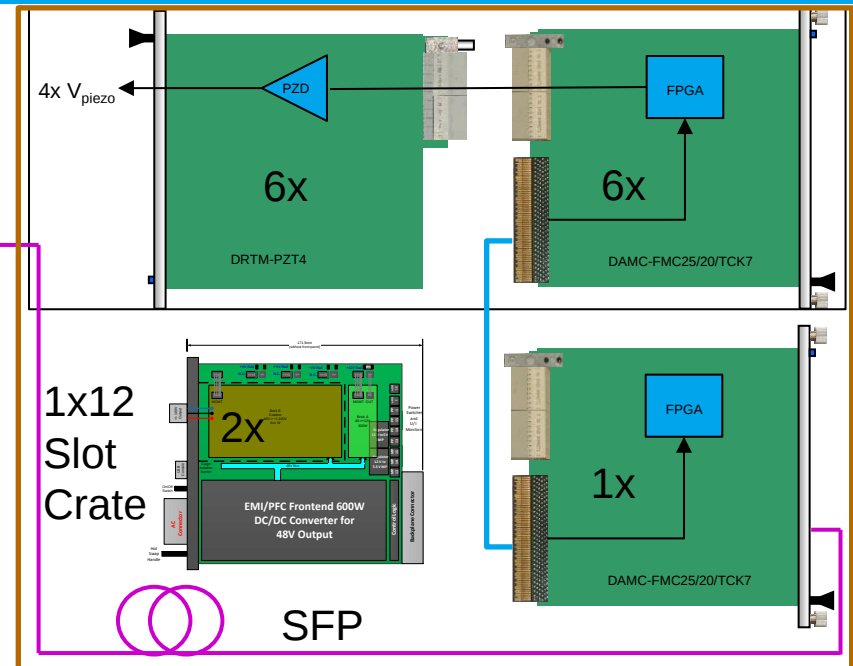
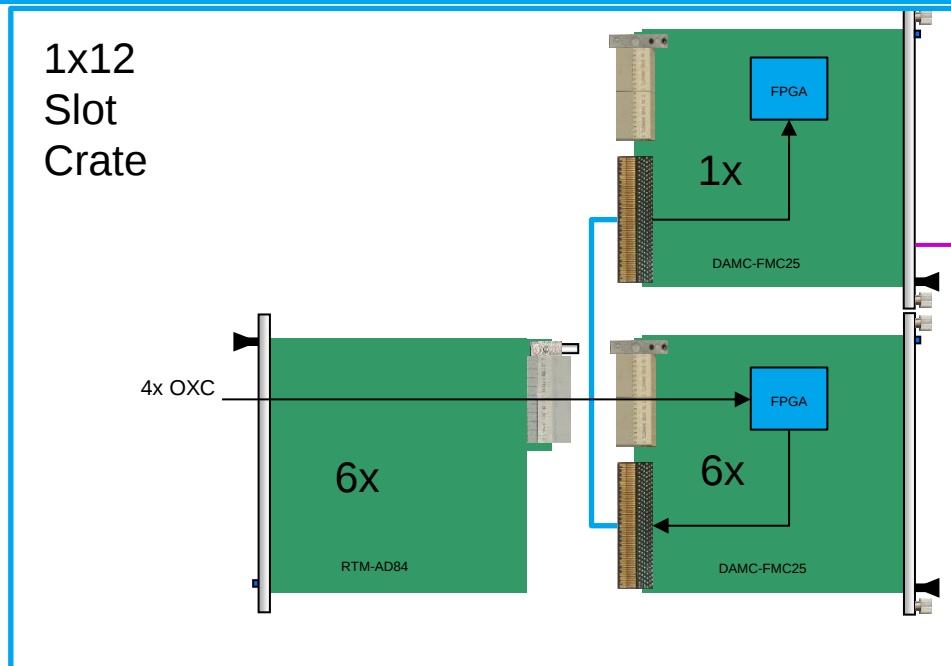
32x cavities = 64x piezos



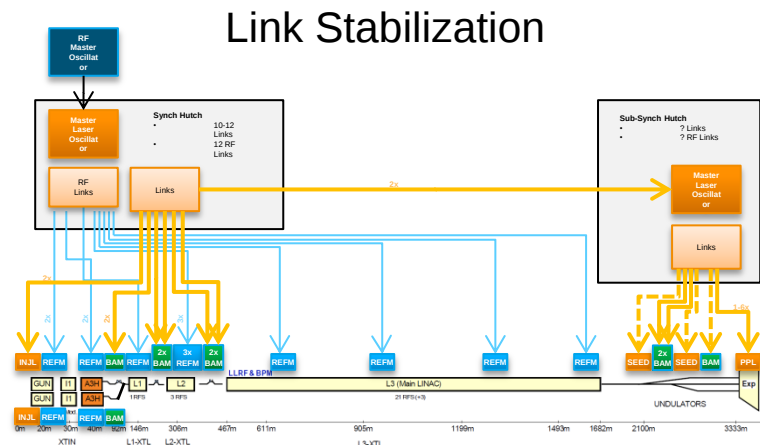
Cavity tuner control – pulse or cw modes



Possible Applications (XFEL link stabilization)

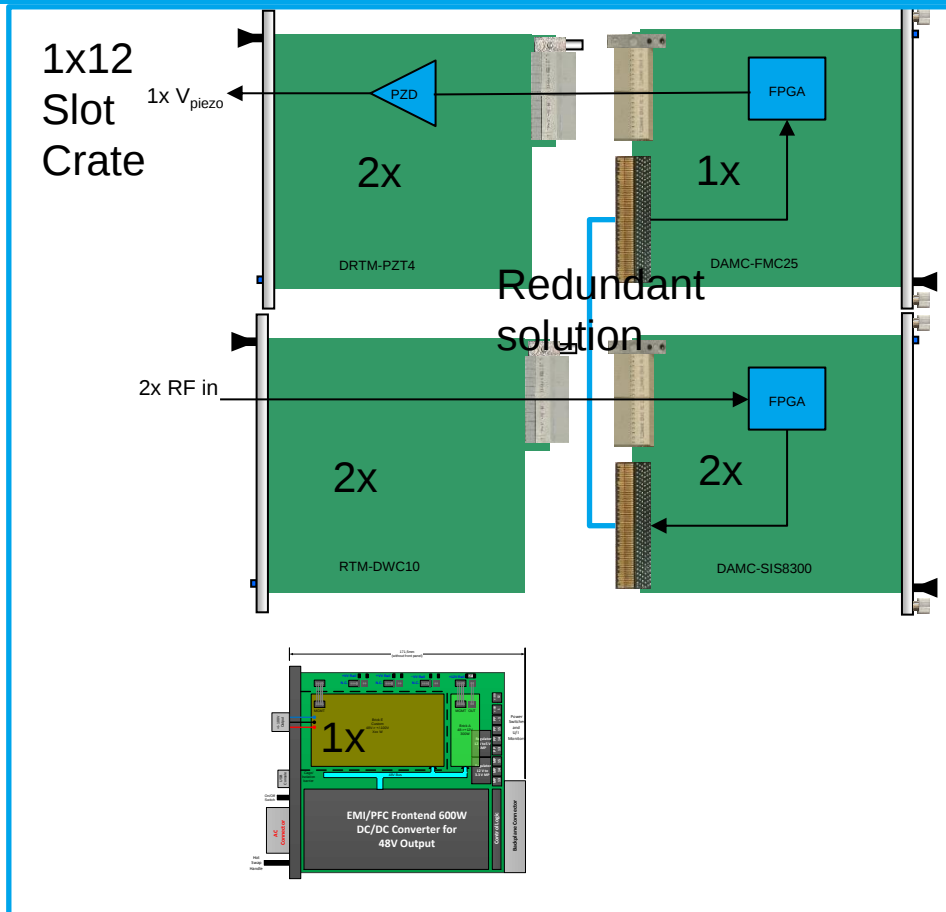


24x links = 24x piezo fiber stretchers

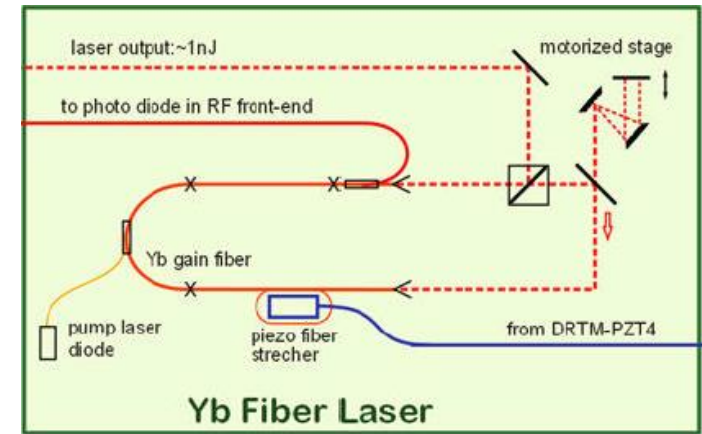


Courtesy by C. Sydlo

Possible Applications (XFEL Master Laser Oscillator Sync)



Laser Synchronization

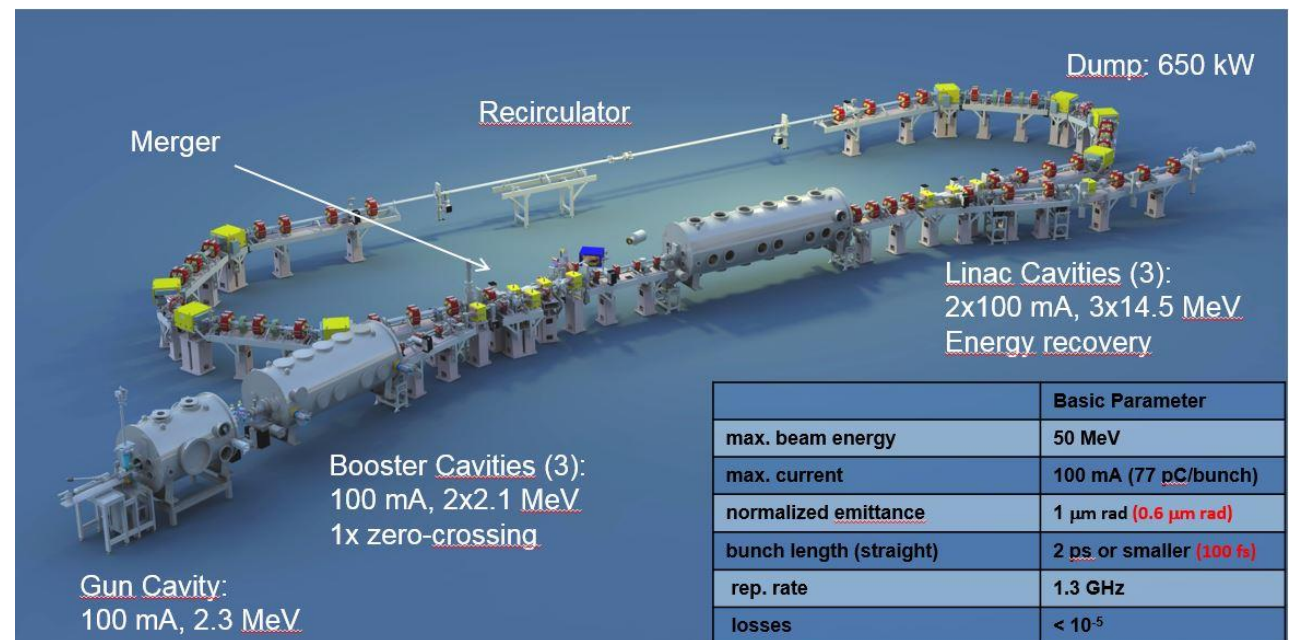


Courtesy by U. Mavric

Before connecting your AMCs with serial links over the AMC backplane study its show_fruinfo 253

Possible Applications (many more)

- bERLinPro at HZB
- TARLA in Ankara
- ESS?



Courtesy by P. Echeverria

Thank You for Attention

