

# MillePede-II short review

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# MP - Introduction

- ★ Millepede is a software package for linear least squares fits with a large number of parameters
- ★ Developed and implemented in FORTRAN77 by Volker Blobel (Univ. Hamburg)
- ★ Used by several experiments for track based alignment and calibration

# MP basics

$$\chi^2(\Delta\mathbf{p}, \Delta\mathbf{q}) = \sum_j^{\text{tracks}} \sum_i^{\text{hits}} \frac{1}{\sigma_{ij}^2} \left( \mathbf{m}_{ij} - \mathbf{f}_{ij}(\mathbf{p}_0, \mathbf{q}_{j0}) - \frac{\partial \mathbf{f}_{ij}}{\partial \mathbf{p}} \Delta\mathbf{p} - \frac{\partial \mathbf{f}_{ij}}{\partial \mathbf{q}_j} \Delta\mathbf{q}_j \right)^2$$

## ★ Track based alignment (and calibration)

### ▶ Minimizing $\chi^2$ sum

- ✦ for large number of global (alignment) parameters  $\Delta\mathbf{p}$
- ✦ from large number of local fits (tracks  $\Delta\mathbf{q}_j$ )
- ✦ with model  $\mathbf{f}$  linearized at initial parameters  $(\mathbf{p}_0, \mathbf{q}_0)$

### ▶ Linear equation system with bordered band matrix

- ✦ Border populated due to global derivatives  $\partial\mathbf{f}/\partial\mathbf{p}$
- ✦ Block diagonal by (independent) local derivatives  $\partial\mathbf{f}/\partial\mathbf{q}_j$

### ▶ Local fits ( $\partial\chi^2/\partial\Delta\mathbf{q}_j=0$ ) done with $\mathbf{p}=\mathbf{p}_0$

- ✦ Size of lin. eqn. system reduced to number of global par.
- ✦ Correlations of global through local parameters maintained

# Millepede basics (II)

## ★ Procedure

### ▶ Local (track) fits

- ✦ For all tracks 'j' solve linear equation system  $A_j \cdot \Delta q_j = b_j$
- ✦ With solution and  $A_j^{-1}$  fill global matrix  $A_g$  and vector  $b_g$

### ▶ Global fit

- ✦ Optionally add constraints ( $C \cdot \Delta p = c$ , e.g. implement hierarchy)
- ✦ Solve linear equation system  $A_g \cdot \Delta p = b_g$
- ✦ Update alignment parameters:  $p = p + \Delta p$

### ▶ Iteration

- ✦ For outlier rejection repeat previous steps
- ✦  $\chi^2$  cut for local fit changed from soft to hard

# Millepede history (I)

## ★ Millepede-I

- ▶ Development started 1996
- ▶ One set of (FORTRAN) subroutines
- ▶ Since 1997 main user has been H1 for calibration and alignment of the central drift chambers
  - ◆ Online calibration: mean drift velocity, Lorentz angle vs  $t$
  - ◆ Offline calibration:  $v_d$ ,  $\alpha_{lor}$  vs  $R$ ,  $\varphi$ ,  $B(Z,R)$ ,  $E$ ,  $P$ , ..
- ▶ Applicable for up to several thousand parameters
  - ◆ Matrix inversion as only solution method, CPU time  $\sim n_{par}^3$

# MillePede history (II)

## ★ MillePede-II

- ▶ Development started 2005 for LHC experiments
  - ✦ Allow for 100 000 parameters
- ▶ Split into two parts
  - ✦ **Mille**: create binary files with measurements, errors and derivatives from user code (C/C++ or FORTRAN)
  - ✦ **Pede**: standalone FORTRAN executable, steering text file and binary files as input
- ▶ Main user is CMS for alignment of the Si tracker
  - ✦ 25k (curved) Si sensors

# MillePede history (III)

## ★ New features with MillePede-II

### ▶ Matrix storage

- ◆ **Sparse:** only nonzero matrix elements  $M_{ij}$  stored

- In alignment typically only 10-30% of  $M_{ij} \neq 0$  ( $i, j$  connected by track(s))

### ▶ Solution method

- ◆ **MINRES:** stepwise minimize  $|\mathbf{A}_g \cdot \Delta \mathbf{p} - \mathbf{b}_g|$  to obtain  $\Delta \mathbf{p}$

- $\mathbf{A}_g^{-1}$  is not calculated  $\rightarrow$  no errors for results

- CPU time dominated by product 'matrix times vector':  $\sim n_{\text{par}}^2 \cdot n_{\text{step}}$

V. Blobel: Track based alignment,  
Nuclear Instruments and Methods A, 566 (2006), pp. 5-13)

# MillePede today

- ★ [MillePedeII@svnsrv.desy.de](mailto:MillePedeII@svnsrv.desy.de)
  - ▶ Maintenance and development by Statistics Tools group of Analysis Center in Helmholtz Terascale Alliance
- ★ Moved to FORTRAN90, 64bit ([doxygen documentation](#))
- ★ Optimization of (Pede) resource usage
  - ▶ Memory: matrix compression
  - ▶ CPU: parallelization with [OpenMP™](#)
  - ▶ Fit 200k parameters from  $10^7$  tracks in 32GB in 10h